SEL-421 Relay SEL-421-1 Relay

Protection Automation Control

User's Guide



Schweitzer Engineering Laboratories 2350 NE Hopkins Court Pullman, WA USA 99163-5603 Tel: (509) 332-1890 FAX: (509) 332-7990 **CAUTION:** Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

CAUTION: There is danger of explosion if the battery is incorrectly replaced. Replace only with Ray-O-Vac® no. BR2335 or equivalent recommended by manufacturer. Dispose of used batteries according to the manufacturer's instructions.

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

DANGER: Contact with instrument terminals can cause electrical shock that can result in injury or death.

WARNING: Use of this equipment in a manner other than specified in this manual can impair operator safety safeguards provided by this equipment.

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

WARNING: This device is shipped with default passwords. Default passwords should be changed to private passwords at installation. Failure to change each default password to a private password may allow unauthorized access. SEL shall not be responsible for any damage resulting from unauthorized access. ATTENTION: Les composants de cet équipement sont sensibles aux décharges électrostatiques (DES). Des dommages permanents non-décelables peuvent résulter de l'absence de précautions contre les DES. Raccordez-vous correctement à la terre, ainsi que la surface de travail et l'appareil avant d'en retirer un panneau. Si vous n'êtes pas équipés pour travailler avec ce type de composants, contacter SEL afin de retourner l'appareil pour un service en usine.

ATTENTION: Il y a un danger d'explosion si la pile électrique n'est pas correctement remplacée. Utiliser exclusivement Ray-O-Vac® No. BR2335 ou un équivalent recommandé par le fabricant. Se débarrasser des piles usagées suivant les instructions du fabricant.

DANGER: Débrancher tous les raccordements externes avant d'ouvrir cet appareil. Tout contact avec des tensions ou courants internes à l'appareil peut causer un choc électrique pouvant entraîner des blessures ou la mort.

DANGER: Tout contact avec les bornes de l'appareil peut causer un choc électrique pouvant entraîner des blessuers ou la mort.

AVERTISSEMENT: L'utilisation de cet appareil suivant des procédures différentes de celles indiquées dans ce manuel peut désarmer les dispositifs de protection d'opérateur normalement actifs sur cet équipement.

AVERTISSEMENT: Seules des personnes qualifiées peuvent travailler sur cet appareil. Si vous n'êtes pas qualifiés pour ce travail, vous pourriez vous blesser avec d'autres personnes ou endommager l'équipement.

AVERTISSEMENT: Cet appareil est expédié avec des mots de passe par défaut. A l'installation, les mots de passe par défaut devront être changés pour des mots de passe confidentiels. Dans le cas contraire, un accés non-autorisé á l'équipement peut être possible. SEL décline toute responsabilité pour tout dommage résultant de cet accés nonautorisé.

Schweitzer Engineering Laboratories, SELOGIC, Connectorized, Job Done, SEL-PROFILE, ACSELERATOR, and **SED** are registered trademarks of Schweitzer Engineering Laboratories. All brand or product names appearing in this document are the trademark or registered trademark of their respective holders.

The software (firmware), schematic drawings, relay commands, and relay messages are copyright protected by the United States Copyright Law and International Treaty provisions. All rights are reserved.

You may not copy, alter, disassemble, or reverse-engineer the software. You may not provide the software to any third party.

The information in this manual is furnished for informational use only and is subject to change without notice.

The English language manual is the only approved SEL manual.

This product is covered by U.S. Patent Numbers: 4,996,624; 5,041,737; 5,317,472; 5,325,061; 5,349,490; 5,365,396; 5,367,426; 5,479,315; 5,515,227; 5,652,688; 5,694,281; 5,703,745; 5,731,943; 5,790,418; 5,793,750; 5,883,578; 5,914,663; 6,028,754; 6,084,755; U.S. and Foreign Patent(s) Pending.

This product is covered by the standard SEL 10-year warranty. For warranty details, visit www.selinc.com or contact your customer service representative.

© 2001, 2002 Schweitzer Engineering Laboratories. All rights reserved.

PM421-01

Table of Contents

List of Tables	ix
List of Figures	xxiii
List of Equations	xxxiii
List of Examples	xxxvii
Manual Change Information	xxxix
Preface	xli

User's Guide

Section 1: Introduction and Specifications	
Features	
Models and Options	
Applications	
Specifications	
Section 2: Installation	
Shared Configuration Attributes	
Plug-In Boards	
Jumpers	
Front-Panel Labels	
Relay Placement	
Connection	
AC/DC Connection Diagrams	U 2 47

Section 3: PC Software

Installing the Computer Software	
Communications Setup	
Settings Database Management and Drivers	
Create and Manage Relay Settings	
Expression Builder	
Analyze Events	
HMI Meter and Control	

Section 4: Basic Relay Operations

Inspecting a New Relay	
Connecting and Applying Power	
Establishing Communication	
Changing the Default Passwords	
Checking Relay Status	
Making Simple Settings Changes	
Examining Metering Quantities	
Reading Oscillograms, Event Reports, and SER	
Operating the Relay Inputs and Outputs	
Configuring High-Accuracy Timekeeping	U.4.66
Readying the Relay for Field Application	

Section 5: Front-Panel Operations

Front-Panel Layout	U.5.2
Front-Panel Menus and Screens	
Front-Panel Automatic Messages	U.5.28
Operation and Target LEDs	
Front-Panel Operator Control Pushbuttons	

Section 6: Testing and Troubleshooting

Testing Philosophy	U.6.2
Testing Features and Tools	U.6.5
Relay Test Connections	U.6.9
Test Methods	U.6.14
Checking Relay Operation	U.6.24
Relay Self-Tests	U.6.37
Relay Troubleshooting	
Factory Assistance	U.6.43

Appendix A: Firmware Versions

Firmware Versions

Application's Handbook

Section 1: Protection Application Examples

Introduction	
230 kV Overhead Transmission Line Example	
500 kV Parallel Transmission	
Lines With Mutual Coupling Example	
345 kV Tapped Overhead Transmission Line Example	
EHV Parallel 230 kV Underground Cables Example	
Out-of-Step Logic Application Examples	
Auto-Reclose Example	
Auto-Reclose and Synchronism Check Example	
Circuit Breaker Failure Application Examples	
Section 2: Monitoring and Metering	
Circuit Breaker Monitor	A 2 2
Station DC Battery System Monitor	
Metering	
Section 3: Analyzing Data	
Data Processing	
Triggering Data Captures and Event Reports	
Duration of Data Captures and Event Reports	A.3.6
Oscillography	A.3.8
Event Reports, Event Summaries, and Event Histories	
SER (Sequential Events Recorder)	
Section 4: Time-Synchronized Measurements	
Relay Configuration for High-Accuracy Timekeeping	A 4 2
Fault Analysis	
Power Flow Analysis	
State Estimation Verification	
Section 5: Substation Automatic Restoration	
230 kV Tapped Transmission Line Application Example	

Section 6: SEL-2030 Applications

SEL Communications Processor	A.6.2
SEL-2030 and SEL-421 Relay Architecture	
SEL-2030 Example	
SEE 2000 Example	

Section 7: Direct Network Communication

Direct Network Communication	A.7.2
Serial Networking	
SEL-2701 Ethernet Processor	
Direct Networking Example	
–	

Reference Manual

Section 1: Protection Functions

Current and Voltage Source Selection	
Frequency Estimation	R.1.10
Fault Location	
Open Phase Detection Logic	R.1.13
Pole Open Logic	
LOP Logic	
FIDS Logic	R.1.20
Ground Directional Element	R.1.21
Phase and Negative-Sequence Directional Elements	
Directionality	
CVT Transient Detection.	
Series-Compensation Line Logic	R.1.38
Load-Encroachment Logic	
OOS Logic	R.1.41
Mho Ground Distance Elements	
Quadrilateral Ground Distance Elements	R.1.51
Mho Phase Distance Elements	R.1.55
Zone Time Delay	R.1.59
Instantaneous Line Overcurrent Elements	R.1.62
Inverse Time-Overcurrent Elements	R.1.69
SOTF Logic	R.1.85
Communications-Assisted Tripping Logic	R.1.88
DCB Scheme	R.1.89
POTT Scheme	
DCUB Scheme Logic	R.1.99
Trip Logic	R.1.103
Circuit Breaker Failure Protection.	R.1.112

Section 2: Auto-Reclose and Synchronism Check

Auto-Reclose	
One-Circuit-Breaker Recloser	
Two-Circuit-Breaker Recloser	
Voltage Checks	
Relay Settings and Relay Word Bits	
Synchronism Check	

Section 3: SELOGIC [®] Control Equation Programming	
SELOGIC Control Equation History	
Separation of Protection and Automation Areas	
SELOGIC Control Equation Programming	
SELOGIC Control Equation Setting Structure	
SELOGIC Control Equation Capacity	
SELOGIC Control Equation Elements	
SELOGIC Control Equation Operators	
Effective Programming	
SEL-311 and SEL-351 Series Users	
Section 4: Communications Interfaces	
Communications Interfaces	
Serial Communication	
Communications Card	
Section 5: SEL Communications Protocols	
Serial Port Hardware Protocol	
Software Protocol Selections	
Protocol Active When Setting PROTO := SEL	
Virtual File Interface	
SEL MIRRORED BITS Communications	
SEL Distributed Port Switch Protocol (LMD)	
Section 6: DNP 3.0 Communications	
Introduction to DNP 3.0	R.6.2
DNP 3.0 in the SEL-421 Relay	
DNP 3.0 Documentation	
Application Example	
Section 7: UCA2 Communications	
Introduction to UCA2	R 7.2
UCA2 in the SEL-421 Relay	
GOOSE Application Example	
Section 8: ASCII Command Reference	
Description of Commands	R 8 2
	70.012
Section 9: Settings	
Global Settings	
Breaker Monitor Settings	
Group Settings	
Protection Free-Form SELOGIC Control Equations	
Automation Free-Form SELOGIC Control Equations	
Output Settings Front-Panel Settings	
Report Settings	
Port Settings	
DNP 3.0 Settings	
Appendix A: Relay Word Bits	DAO
Alphabetic Row List	
	к.А.19
Appendix B: Analog Quantities	
Analog Quantities	

Appendix C: GOMSFE Tables

Introduction	
GOMSFE Tables	
SEL-421 Relay Domains	
SEL-421 Relay Domain-LN0	
SEL-421 Relay Virtual Device Domain	
Special Translation Rules	
Glossary	GL.1
Index	

This page intentionally left blank

List of Tables

User's Guide

Section 1: Intr	oduction and Specifications	
Table 1.1	Application Highlights	U.1.9
Section 2: Inst	tallation	
Table 2.1	I/O Interface Boards Control Inputs	U.2.12
Table 2.2	I/O Interface Boards Control Outputs	
Table 2.3	Main Board Jumpers	
Table 2.4	Main Board Jumpers—JMP1, JMP2, and JMP3	
Table 2.5	I/O Board Jumpers	U.2.25
Table 2.6	Configurable Front-Panel Label Kits	U.2.27
Table 2.7	Options for Configurable Front-Panel Labels	
Table 2.8	Fuse Requirements for the SEL-421 Relay Power Supply	U.2.38
Section 3: PC	Software	
Table 3.1	System Requirements for ACSELERATOR Software	
Table 3.2	ACSELERATOR HMI Tree View Functions	U.3.20
Section 4: Bas	ic Relay Operations	
Table 4.1	Power Supply Voltage Inputs	U.4.4
Table 4.2	General Serial Port Settings	
Table 4.3	SEL-421 Relay Access Levels	U.4.8
Table 4.4	Access Level Commands and Passwords	U.4.9
Table 4.5	Settings Classes and Instances	
Table 4.6	Actions at Settings Prompts	
Table 4.7	Actions at Text-Edit Mode Prompts	
Table 4.8	Time Source Automatic Switching Enable Settings	
Table 4.9	Date/Time Last Update Sources	
Table 4.10	Communications Port Commands That Clear Relay Buffers	U.4.73
Section 5: Fro	nt-Panel Operations	
Table 5.1	Front-Panel Inactivity Time-Out Setting	
Table 5.2	Metering Screens Enable Settings	
Table 5.3	Display Point Settings	
Table 5.4	Local Bit Control Settings	
Table 5.5	Settings Available From the Front Panel.	
Table 5.6	TIME Target LED Trigger Elements–Factory Defaults	
Table 5.7	Operator Control Pushbuttons and LEDs—Factory Defaults	U.5.34
	ting and Troubleshooting	
Table 6.1	Acceptance Testing	U.6.2
Table 6.2	Commissioning Testing	
Table 6.3	Maintenance Testing	
Table 6.4	UUT Database Entries for SEL-5401 Relay Test System Software—5 A Relay	
Table 6.5	UUT Database Entries for SEL-5401 Relay Test System Software—1 A Relay	
Table 6.6	Phase Instantaneous Overcurrent Pickup	
Table 6.7	Selectable Operating Quantity Time-Overcurrent Element (51S1) Default Settings	
Table 6.8 Table 6.9	Negative-Sequence Directional Element Settings AUTO Calculations Troubleshooting Procedures	
Appendix A: F	irmware Versions	

Table A.1	Firmware Versions	. U.A	. 1

Applications Handbook

Section 1: Protection Application Examples

Table 1.1	System Data—230 kV Overhead Transmission Line	A.1.3
Table 1.2	Secondary Impedances	
Table 1.3	LOP Enable Options	
Table 1.4	Options for Enabling Pole-Open Logic	A.1.13
Table 1.5	Setting TULO Unlatch Trip Options	A.1.14
Table 1.6	SEL-421 Relay Settings	A.1.16
Table 1.7	System Data—500 kV Parallel Overhead Transmission Lines	A.1.21
Table 1.8	Secondary Impedances	A.1.21
Table 1.9	LOP Enable Options	A.1.26
Table 1.10	Tilt Resulting From Nonhomogeneity	
Table 1.11	Options for Enabling Pole-Open Logic	A.1.37
Table 1.12	Trip Unlatch Options	A.1.41
Table 1.13	General Global Settings	A.1.46
Table 1.14	System Data-345 kV Tapped Overhead Transmission Line	A.1.54
Table 1.15	Secondary Impedances	A.1.55
Table 1.16	LOP Enable Options	
Table 1.17	Local Zone 2 Fault Impedance Measurements	
Table 1.18	Apparent Impedance Measurement for Remote Faults	
Table 1.19	Options for Enabling Pole-Open Logic	
Table 1.20	Setting TULO Unlatch Trip Options	
Table 1.21	SEL-421 Relay Settings	A.1.81
Table 1.22	System Data—230 kV Parallel Underground Cables	A.1.87
Table 1.23	Secondary Impedances	
Table 1.24	LOP Enable Options	A.1.92
Table 1.25	Tilt Resulting From Nonhomogeneity	A.1.96
Table 1.26	XAG Measurement for Remote AG Fault	
	$(k01 = 0.374 - 39.2^\circ)$, sheath and ground return path)	A.1.98
Table 1.27	XAG Measurement for Remote AG Fault ($k01 = 0.385 - 46.7^\circ$, sheath return pa	ath)A.1.99
Table 1.28	XAG Measurement for Remote AG Fault ($k0 = 6.105 - 44.5^\circ$, ground return path)) A.1.99
Table 1.29	Options for Enabling Pole-Open Logic	A.1.108
Table 1.30	Setting TULO Unlatch Trip Options	A.1.111
Table 1.31	General Global Settings	A.1.113
Table 1.32	Positive-Sequence Impedances (Secondary)	A.1.118
Table 1.33	Automatically Calculated/Hidden Settings	A.1.127
Table 1.34	Relay Configuration (Group)	
Table 1.35	Out-of-Step Tripping/Blocking	
Table 1.36	Automatically Calculated/Hidden Settings	A.1.134
Table 1.37	Relay Configuration (Group)	A.1.134
Table 1.38	Out-of-Step Tripping/Blocking	
Table 1.39	SEL-421 Relay Settings	A.1.139
Table 1.40	SEL-421 Relay Settings	A.1.148
Table 1.41	Secondary Quantities	A.1.155
Table 1.42	Relay Configuration (Group)	
Table 1.43	Secondary Quantities	
Table 1.44	Relay Configuration (Group)	A.1.168

Section 2: Monitoring and Metering

Table 2.1	Circuit Breaker Monitor Configuration	A.2.3
Table 2.2	Circuit Breaker Maintenance Information—Example	
Table 2.3	Contact Wear Monitor Settings—Circuit Breaker 1	A.2.5
Table 2.4	Circuit Breaker Monitor Initiate SELOGIC Control Equations	A.2.7
Table 2.5	Circuit Breaker Monitor Close SELOGIC Control Equations	
Table 2.6	BRE Command	A.2.18
Table 2.7	DC Monitor Settings and Relay Word Bit Alarms	A.2.23
Table 2.8	Example DC Battery Voltage Conditions	

Table 2.9	Example DC Battery Monitor Settings—125 Vdc for Vdc1 and 48 Vdc for Vdc2	
Table 2.10	Example DC Battery Monitor Settings—AC Ripple Voltages	
Table 2.11	Example DC Battery Monitor Settings—Ground Detection Factor (EGADVS := Y)	A.2.26
Table 2.12	MET Command—Metering Only	
Table 2.13	Instantaneous Metering Quantities-Voltages, Currents, Frequency	A.2.30
Table 2.14	Instantaneous Metering Quantities—Powers	
Table 2.15	Instantaneous Metering Accuracy-Voltages, Currents, and Frequency	
Table 2.16	Instantaneous Metering Accuracy—Power	
Table 2.17	Maximum/Minimum Metering Quantities—	
	Voltages, Currents, Frequency, and Powers	A 2 34
Table 2.18	Demand and Peak Demand Metering Quantities—(LINE)	
Table 2.19	Rolling Demand Calculations	
Table 2.20	Demand Metering Settings.	
Table 2.20	Energy Metering Quantities—(LINE)	
Table 2.21	Synchrophasor Port Settings	
14010 2.22	Synchrophasor Fort Settings	A.2.42
Section 3: Analy	vzing Data	
Table 3.1	Report Settings	136
Table 3.2	Event Report Nonvolatile Storage Capability	
Table 3.3	EVE Command	
Table 3.4	EVE Command Examples	
Table 3.5	Event Report Metered Analog Quantities	
Table 3.6	Event Types	
Table 3.7	SUM Command	
Table 3.8	HIS Command	
Table 3.9	SEP Commanda	A 3 35
14010 5.9	SER Commands	
Section 4: Time	-Synchronized Measurements	
Section 4: Time Table 4.1	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	
Section 4: Time Table 4.1 Section 5: Subs	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration	A.4.8
Section 4: Time Table 4.1 Section 5: Subs Table 5.1	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings	A.4.8 A.5.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7 A.5.9
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces	A.4.8 A.5.6 A.5.7 A.5.7 A.5.12 A.5.12 A.6.3
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2	 Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings 	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages	A.4.8 A.5.6 A.5.7 A.5.7 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.7
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4 Table 6.5	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 Port 1 Region Map	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.8
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4 Table 6.5 Table 6.6 Table 6.7	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs. Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 Port 1 Region Map SEL-2030 TARGET Region	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.8
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4 Table 6.5 Table 6.6 Table 6.7 Section 7: Direct	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 METER Region Map SEL-2030 TARGET Region St Network Communications	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.7 A.6.8 A.6.9
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4 Table 6.5 Table 6.6 Table 6.7 Section 7: Direct Table 7.1	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 METER Region Map SEL-2030 TARGET Region Xt Network Communication DNP 3.0 Feature Summary	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.8 A.6.9 A.7.3
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.3 Table 6.4 Table 6.5 Table 6.7 Section 7: Direct Table 7.1 Table 7.2	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 METER Region Map SEL-2030 TARGET Region SEL-2030 TARGET Region DNP 3.0 Feature Summary Ethernet Connection Options	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.8 A.6.8 A.6.9
Section 4: Time Table 4.1 Section 5: Subs Table 5.1 Table 5.2 Table 5.3 Table 5.4 Table 5.5 Table 5.6 Section 6: SEL-2 Table 6.1 Table 6.2 Table 6.3 Table 6.4 Table 6.5 Table 6.6 Table 6.7 Section 7: Direct Table 7.1	-Synchronized Measurements SEL-421 Relay Voltage and Current Measurement tation Automatic Restoration Global Settings Breaker Monitor Settings Group Settings Protection Free-Form SELOGIC Control Equations Control Inputs Control Outputs (SELOGIC Control Equations) 2030 Applications SEL-2020 and SEL-2030 Communications Processor Protocol Interfaces SEL-2030 Port 1 Settings SEL-2030 Data Collection Automessages SEL-2030 Port 1 Automatic Messaging Settings SEL-2030 METER Region Map SEL-2030 TARGET Region Xt Network Communication DNP 3.0 Feature Summary	A.4.8 A.5.6 A.5.7 A.5.9 A.5.12 A.5.12 A.5.12 A.6.3 A.6.6 A.6.6 A.6.7 A.6.8 A.6.8 A.6.9

Reference Manual

Section 1: Protection Functions

Table 1.1	ESS := N, Current and Voltage Source Selection	R.	1.	2
Table 1.2	ESS := 1, Current and Voltage Source Selection	R.	1.	3
Table 1.3	ESS := 2, Current and Voltage Source Selection	R.	1.	4
Table 1.4	ESS := 3, Current and Voltage Source Selection	R.	1.	5
Table 1.5	ESS := 4, Current and Voltage Source Selection	R.	1.	6
Table 1.6	ESS := Y, Tapped Line			
Table 1.7	ESS := Y, Current Polarizing Source	R.	1.	8
Table 1.8	Frequency Estimation			
Table 1.9	Frequency Estimation Analog Quantity			
Table 1.10	Fault Location Triggering Elements			
Table 1.11	Fault Type			
Table 1.12	Fault Location Settings			
Table 1.13	Fault Location Relay Word Bit	R .1	.1	2
Table 1.14	Open Phase Detection Relay Word Bits			
Table 1.15	Pole Open Logic Settings			
Table 1.16	EPO Setting Selections			
Table 1.17	Pole Open Logic Relay Word Bits			
Table 1.18	LOP Logic Setting			
Table 1.19	LOP Logic Relay Word Bits			
Table 1.20	FIDS Relay Word Bits			
Table 1.21	Directional Elements Supervising Ground Distance Elements			
Table 1.22	Ground Directional Element Settings			
Table 1.23	Ground Directional Element Settings AUTO Calculations			
Table 1.24	Ground Directional Element Enables			
Table 1.25	Ground Directional Element Relay Word Bits			
Table 1.26	Reference Table for <i>Figure 1.15</i> , <i>Figure 1.16</i> , and <i>Figure 1.17</i>			
Table 1.27	Phase and Negative-Sequence Directional Elements Relay Word Bits			
Table 1.28	Zone Directional Settings			
Table 1.29	CVT Transient Detection Logic Setting			
Table 1.30	CVT Transient Detection Logic Relay Word Bit			
Table 1.31	Series-Compensation Line Logic Relay Settings			
Table 1.32	Load-Encroachment Logic Relay Settings			
Table 1.33	Load-Encroachment Logic Relay Word Bits			
Table 1.34	OOS Logic Relay Settings			
Table 1.35	OOS Logic Relay Word Bits			
Table 1.36	Mho Ground Distance Element Settings			
Table 1.37	Mho Ground Distance Elements Relay Word Bits			
Table 1.38	Quadrilateral Ground Distance Element Settings			
Table 1.39	Quadrilateral Ground Distance Elements Relay Word Bits			
Table 1.40	Mho Phase Distance Element Settings			
Table 1.41	Mho Phase Distance Elements Relay Word Bits			
Table 1.42	Zone Delay Settings			
Table 1.43	Zone Time Delay Relay Word Bits			
Table 1.44	Phase Overcurrent Element Settings			
Table 1.45	Negative-Sequence Overcurrent Element Settings			
Table 1.46	Residual Ground Overcurrent Element Settings			
Table 1.47	Phase Instantaneous and Definite-Time Line Overcurrent Relay Word Bits			
Table 1.48	Negative-Sequence Instantaneous	11	.0	1
	and Definite-Time Line Overcurrent Relay Word Bits	R 1	6	4
Table 1.49	Residual Ground Instantaneous and Definite-Time Line Overcurrent Relay Word Bits .			
Table 1.50	Selectable Current Quantities			
Table 1.50	Selectable Inverse Time-Overcurrent Settings			
Table 1.52	Selectable Inverse-Time Overcurrent Relay Word Bits			
Table 1.52	SOTF Settings			
Table 1.54	SOTF Relay Word Bits			
and the second s				-

Table 1.55	ECOMM Setting	R.1.88
Table 1.56	DCB Settings	
Table 1.57	DCB Relay Word Bits	
Table 1.58	POTT Settings	
Table 1.59	POTT Relay Word Bits	
Table 1.60	DCUB Settings	
Table 1.61	DCUB Relay Word Bits	
Table 1.62	Trip Logic Settings	
Table 1.63	Setting TULO Unlatch Trip Options	
Table 1.64	Trip Logic Settings	
Table 1.65	Trip Logic Relay Word Bits	
Table 1.66	Circuit Breaker Failure Protection Logic Settings	R.1.118
Table 1.67	Circuit Breaker Failure Relay Word Bits	
Section 2: Auto	o-Reclose and Synchronism Check	
Table 2.1	Auto-Reclose Logical States for Circuit Breaker 1	R 2 4
Table 2.2	One-Circuit-Breaker Three-Pole Reclosing Initial Settings	
Table 2.3	One-Circuit-Breaker Single-Pole Reclose Initial Settings	
Table 2.4	One Circuit Breaker Modes of Operation	
Table 2.5	Dynamic Leader/Follower Settings	
Table 2.6	Leader/Follower Selection	
Table 2.7	Example One: Reset and 79CY3 States	
Table 2.8	Example One: Lockout State	
Table 2.9	Example One: Reset State After Reclaim Time	
Table 2.10	Leader/Follower Selection	
Table 2.11	Example Two: Initial Reset State	
Table 2.12	Example Two: Final Reset State	
Table 2.13	Leader/Follower Selection	
Table 2.14	Example Three: Reset State	R.2.21
Table 2.15	Example Three: Three-Pole Cycle State	
Table 2.16	Example Three: Lockout State, BK1	
Table 2.17	Leader/Follower Selection	R.2.22
Table 2.18	Two Circuit Breakers: Circuit Breaker BK1 Out of Service	R.2.23
Table 2.19	Two-Circuit-Breaker Three-Pole Reclose Initial Settings	R.2.23
Table 2.20	Two-Circuit-Breaker Single-Pole Reclose Initial Settings	R.2.24
Table 2.21	Circuit Breaker BK1 Modes of Operation	
Table 2.22	Circuit Breaker BK2 Modes of Operation	
Table 2.23	Trip Logic Enable Options	
Table 2.24	Auto-Reclose Logic Settings	
Table 2.25	Auto-Reclose Logic Relay Word Bits	
Table 2.26	Synchronism-Check Relay Word Bits	R.2.45
Section 3: SEL	OGIC [®] Control Equation Programming	
Table 3.1	Advanced SEL-421 Relay SELOGIC Control Equation Features	
Table 3.2	SEL-421 Relay SELOGIC Control Equation Programming Summary	R.3.2
Table 3.3	Summary of SELOGIC Control Equation Elements	
Table 3.4	First Execution Bit Operation on Power-Up	
Table 3.5	First Execution Bit Operation on Automation Settings Change	R.3.12
Table 3.6	First Execution Bit Operation on	D 2 12
T-1-1 2.7	Protection Settings Change, Group Switch, and Source Selection	
Table 3.7	SELOGIC Control Equation Variable Quantities	
Table 3.8	SELOGIC Control Equation Math Variable Quantities	
Table 3.9	Latch Bit Quantities	
Table 3.10	Latch Bit Parameters	
Table 3.11	Conditioning Timer Quantities	
Table 3.12 Table 3.13	Conditioning Timer Parameters	
Table 3.13	Sequencing Timer Quantities	
10010 3.14	Sequencing Timer Parameters	K.3.20

T 11 0 15		D 2 22
Table 3.15	Counter Quantities	
Table 3.16	Counter Parameters	
Table 3.17	Operator Precedence from Highest to Lowest	
Table 3.18 Table 3.19	Boolean Operator Summary Parentheses Operation in Boolean Equation	
Table 3.20	NOT Operator Truth Table	
Table 3.20 Table 3.21	AND Operator Truth Table	
Table 3.21 Table 3.22	OR Operator Truth Table	
Table 3.22	Comparison Operations	
Table 3.24	Math Operator Summary	
Table 3.24 Table 3.25	Math Operator Summary	
Table 3.26	SEL-311 Series Relays and	R.3.30
14010 5.20	SEL-421 Relay SELOGIC Control Equation Programming Features	P 3 36
Table 3.27	SEL-421 Keray SELCORE Control Equation Programming Features	K.J.J0
10010 5.27	SEL-421 Relay SELOGIC Control Equation Boolean Operators	R.3.36
Section 4: Cor	nmunications Interfaces	
Table 4.1	SEL-421 Relay Communications Protocols	R 4 2
Table 4.2	EIA-232 Pin Assignments	
Table 4.3	Communications Card Database Regions	
	Communications Protocols	D 5 0
Table 5.1	Hardware Handshaking	
Table 5.2	Supported Serial Command Sets	
Table 5.3	Selected ASCII Control Characters	
Table 5.4	Compressed ASCII Commands	
Table 5.5	Fast Commands and Response Descriptions	
Table 5.6	Fast Operate Command Types	R.5.10
Table 5.7	Fast Message Command Function Codes	D 5 11
T-1-1- 7-0	Used With Fast SER (A546 Message) and Relay Response Descriptions	
Table 5.8	Analog Quantities Included in the Synchrophasor Fast Message	
Table 5.9	Fast Message Command Function Codes for Synchrophasor Fast Write Commands in Recommended Sequence for Automatic Configuration	
Table 5.10 Table 5.11	Virtual File Structure	
Table 5.11 Table 5.12	Settings Directory Files	
Table 5.12		
Table 5.13 Table 5.14	REPORTS Directory Files EVENTS Directory Files (for event 10001)	
Table 5.14	MIRRORED BITS Communications Features	
Table 5.16	General Port Settings Used With MIRRORED BITS Communications	
Table 5.17	MIRRORED BITS Communications Protocol Settings	
Table 5.17	MIRRORED BITS Communications Protocol Settings	
Table 5.19	MIRRORED BITS Communications IN Settings for Three-Terminal Application	
Table 5.20	SEL-2885 Initialization String [MODE PREFIX ADDR:SPEED]	
Section 6. DNI	P 3.0 Communications	
Table 6.1	DNP 3.0 Implementation Levels	P 6 2
Table 6.2	Selected DNP 3.0 Function Codes	
Table 6.3	DNP Access Methods	
Table 6.4	DNI Access Methods	
Table 6.5	SEL-421 Relay Event Buffer Capacity	
Table 6.6	SEL-421 Relay Port DNP Protocol Settings	R 6 9
Table 6.7	SEL-421 Relay DNP Map Settings	
Table 6.8	SEL-421 Relay DNP 3.0 Device Profile	
Table 6.9	SEL-421 Relay DNP Object List	
Table 6.10	SEL-421 Relay DNP 3.0 Default Data Map	
Table 6.11	SEL-421 Relay Object 1, 2 Relay Word Bit Mapping	
Table 6.12	Object 1, 2 Indices 1600—1615 Front-Panel Targets	
Table 6.12	Object 30, Index 176 Upper Byte—Event Cause	
14010 0.15	cojector, maan 170 opper Djue - Drent Outbe	

Table 6.14	Object 30, Index 176 Lower Byte—Fault Type	
Table 6.15	SEL-421 Relay Object 12 Trip/Close Pair Operation	R.6.27
Table 6.16	SEL-421 Relay Object 12 Code Selection Operation	R.6.28
Table 6.17	DNP 3.0 Application Example Data Map	R.6.29
Table 6.18	SEL-421 Relay Class D Example Settings	
Table 6.19	SEL-421 Relay Port 3 Example Settings	
Section 7: UC	A2 Communications	
Table 7.1	UCA2 Layers	R.7.2
Table 7.2	GOMSFE Components	
Table 7.3	Components of MMXU\$MX\$A\$PhsAf	
Table 7.4	GOOSE Bit Pairs	
Table 7.5	SEL-421 Relay GOMSFE Domains	R.7.5
Table 7.6	SEL-421 Relay Virtual Device Domain Models	
Table 7.7	SEL-421 LN0 Domain Models	R.7.6
Table 7.8	Protection Free-Form Settings	R.7.7
Table 7.9	SEL-421 Relay Port 5 Incoming GOOSE Example Settings	R.7.8
Table 7.10	SEL-421 Relay Outgoing GOOSE Example Output Settings	R.7.8
Table 7.11	SEL-421 Relay Port 5 Outgoing GOOSE Example Settings	R.7.8
Section 8: ASC	CII Command Reference	
Table 8.1	2AC Command	R.8.2
Table 8.2	AAC Command	R.8.2
Table 8.3	ACC Command	R.8.2
Table 8.4	BAC Command	R.8.2
Table 8.5	BNA Command	R.8.2

Table 8.4	BAC Command	R.8.2
Table 8.5	BNA Command	R.8.2
Table 8.6	BRE n Command	R.8.3
Table 8.7	BRE n C and BRE n R Commands	R.8.3
Table 8.8	BRE C A and BRE R A Commands	R.8.3
Table 8.9	BRE n H Command	R.8.3
Table 8.10	BRE n P Command	R.8.4
Table 8.11	CAS Command	R.8.4
Table 8.12	CBR Command	R.8.4
Table 8.13	CBR TERSE Command	R.8.5
Table 8.14	CEV Command	R.8.5
Table 8.15	CEV ACK Command	R.8.5
Table 8.16	CEV C Command	R.8.6
Table 8.17	CEV L Command	R.8.6
Table 8.18	CEV Lyyy Command	R.8.6
Table 8.19	CEV N Command	R.8.7
Table 8.20	CEV NSET Command	R.8.7
Table 8.21	CEV NSUM Command	R.8.7
Table 8.22	CEV Sx Command	R.8.8
Table 8.23	CEV TERSE Command	
Table 8.24	CEV Command Option Groups	R.8.8
Table 8.25	CHI Command	R.8.9
Table 8.26	CHI TERSE Command	R.8.9
Table 8.27	CLOSE n Command	
Table 8.28	COM c Command	
Table 8.29	COM c C and COM c R Command	R.8.11
Table 8.30	COM c L Command	
Table 8.31	CON nn Command	R.8.12
Table 8.32	COPY Command	R.8.13
Table 8.33	CSE Command	R.8.14
Table 8.34	CSE TERSE Command	R.8.15
Table 8.35	CST Command	
Table 8.36	CSU Command	R.8.16
Table 8.37	CEV ACK Command	R.8.16

Table 8.38	CSU MB Command			
Table 8.39	CSU N Command			
Table 8.40	CSU TERSE Command	R	8.	17
Table 8.41	DATE Command	R	8.	17
Table 8.42	DNA Command	R	8.	17
Table 8.43	DNP Command	R	8.	18
Table 8.44	EVE Command	R	8.	18
Table 8.45	EVE A Command	R	8.	18
Table 8.46	EVE ACK Command	R	8.	19
Table 8.47	EVE C Command			
Table 8.48	EVE D Command			
Table 8.49	EVE L Command			
Table 8.50	EVE Lyyy Command			
Table 8.51	EVE N Command			
Table 8.52	EVE NSET Command			
Table 8.53	EVE NSUM Command			
Table 8.54	EVE Sx Command			
Table 8.55	EVE Command Option Groups			
Table 8.56	EVE Command Examples			
Table 8.57	FILE Command			
Table 8.58	GROUP Command			
Table 8.59	HELP Command.			
Table 8.60	HIS Command			
Table 8.61	HIS C and HIS R Commands			
Table 8.62	HIS CA and HIS RA Commands			
Table 8.63	ID Command			
Table 8.64	IRIG Command			
Table 8.65	LOOP Command			
Table 8.66	LOOP DATA Command			
Table 8.67	LOOP R Command			
Table 8.68	MAP 1 Command			
Table 8.69	MAP 1 Region Command			
Table 8.70	MET Command	R	8	28
Table 8.71	MET AMV Command			
Table 8.72	MET ANA Command			
Table 8.73	MET BAT Command			
Table 8.74	MET D Command			
Table 8.75	MET E Command			
Table 8.76	MET M Command			
Table 8.77	MET PM Command	R	8	31
Table 8.78	MET PMV Command			
Table 8.79	MET RMS Command			
Table 8.80	MET SYN Command			
Table 8.81	OAC Command			
Table 8.82	OPEN n Command			
Table 8.83	PAC Command			
Table 8.84	PAS Command			
Table 8.85	PAS level new password Command			
Table 8.86	PAS level DISABLE Command			
Table 8.87	PORT P Command			
Table 8.88	PORT Kill n Command			
Table 8.89	PUL OUTnnn Command			
Table 8.90	QUIT Command			
Table 8.91	SER Command			
Table 8.92	SER C and SER R Commands			
Table 8.93	SER CA Commands			
Table 8.94	SER D Command			
Table 8.95	SET Command Overview			
			· • •	

Table 8.96	SET A Command	
Table 8.97	SET D Command	.R.8.39
Table 8.98	SET F Command	.R.8.40
Table 8.99	SET G Command	.R.8.40
Table 8.100	SET L Command	.R.8.40
Table 8.101	SET M Command	. R .8.41
Table 8.102	SET O Command	. R .8.41
Table 8.103	SET P Command	. R.8.4 1
Table 8.104	SET R Command	
Table 8.105	SET TERSE Command Examples	
Table 8.106	SHOW Command Overview	
Table 8.107	SHOW A Command	
Table 8.108	SHOW D Command	.R.8.43
Table 8.109	SHOW F Command	
Table 8.110	SHOW G Command	
Table 8.111	SHOW L Command	
Table 8.112	SHOW M Command	
Table 8.113	SHOW O Command	
Table 8.114	SHOW P Command	
Table 8.115	SHOW R Command	
Table 8.116	SNS Command	
Table 8.117	STA Command	
Table 8.118	STA A Command	
Table 8.119	STA C and STA R Command	
Table 8.120	STA S Command	
Table 8.121	STA SC and STA SR Command	
Table 8.122	SUM Command	
Table 8.123	SUM ACK Command	
Table 8.124	SUM N Command	
Table 8.125	TAR Command	
Table 8.126	TAR ALL Command	
Table 8.127	TAR R Command	
Table 8.128	TAR X Command	
Table 8.129	TEST DB Command	
Table 8.130	TEST DB OFF Command	
Table 8.131	TEST DNP Command	
Table 8.132	TEST DNP Command.	
Table 8.133	TEST FM Command	
Table 8.134	TEST FM DEM Command	
Table 8.135	TEST FM OFF Command	
Table 8.136	TEST FM PEAK Command	
Table 8.137	TIME Command	
Table 8.138	TIME Q Command.	
Table 8.139	TRI Command	
Table 8.140	VER Command	
Table 8.141	VIEW 1 Commands-Region.	
Table 8.142 Table 8.143	VIEW 1 Commands–Register Item VIEW 1 Commands–Bit	
12010 0.145	VIEW I Commanus-Dit	
Section 9: Setti	ings	
Table 9.1	Global Settings Categories	R.9.3
Table 9.2	General Global Settings	
Table 9.3	Global Enables	
Table 9.4	Station DC1 Monitor (and Station DC2 Monitor).	
Table 9.5	Control Inputs (Global)	
Table 9.6	Main Board Control Inputs	
Table 9.7	Interface Board #1 Control Inputs	
Table 9.8	Interface Board #2 Control Inputs	

Table 9.9	Settings Group Selection	R.9.5
Table 9.10	Data Reset Control	
Table 9.11	Frequency Estimation	R.9.6
Table 9.12	Time and Date Management	
Table 9.13	Current and Voltage Source Selection	
Table 9.14	Breaker Monitor Settings Categories	
Table 9.15	Breaker Configuration	
Table 9.16	Breaker 1 Inputs	
Table 9.18	Breaker 1 Monitor (and Breaker 2 Monitor)	
Table 9.19	Breaker 1 Contact Wear (and Breaker 2 Contact Wear)	
Table 9.17	Breaker 2 Inputs	
Table 9.20	Breaker 1 Electrical Operating Time (and Breaker 2 Electrical Operating Time)	R 9.10
Table 9.21	Breaker 1 Mechanical Operating Time (and Breaker 2 Mechanical Operating Time)	
Table 9.22	Breaker 1 Pole Scatter and Pole Discrepancy	
	(and Breaker 2 Pole Scatter and Pole Discrepancy)	R.9.10
Table 9.23	Breaker 1 Inactivity Time Elapsed (and Breaker 2 Inactivity Time Elapsed)	
Table 9.24	Breaker 1 Motor Running Time (and Breaker 2Motor Running Time)	
Table 9.25	Breaker 1 Current Interrupted (and Breaker 2 Current Interrupted)	
Table 9.26	Group Settings Categories	
Table 9.27	Line Configuration	
Table 9.28	Relay Configuration	
Table 9.29	Mho Phase Distance Element Reach	
Table 9.30	Series Compensation	
Table 9.31	Mho Phase Distance Element Time Delay	
Table 9.32	Mho Ground Distance Element Reach	
Table 9.32	Quad Ground Distance Element Reach	
Table 9.34	Zero-Sequence Compensation Factor	
Table 9.35	Ground Distance Element Time Delay	
Table 9.36	Distance Element Common Time Delay	
Table 9.37	Switch-Onto-Fault Scheme.	
Table 9.38	Out-of-Step Tripping/Blocking.	
Table 9.39	Load Encroachment	
Table 9.40	Phase Instantaneous Overcurrent Pickup	
Table 9.41	Phase Definite-Time Overcurrent Time Delay	
Table 9.42	Phase Instantaneous Definite-Time Overcurrent Torque Control	
Table 9.43	Residual Ground Instantaneous Overcurrent Pickup.	
Table 9.44	Residual Ground Definite-Time Overcurrent Time Delay	
Table 9.44	Residual Ground Definite-Time Overcurrent Time Delay	
Table 9.46	Negative-Sequence Instantaneous Overcurrent Pickup	
Table 9.40	Negative-Sequence Definite-Time Overcurrent Time Delay	
Table 9.48	Negative-Sequence Instantaneous Definite-Time Overcurrent Torque Control	
Table 9.49	Selectable Operating Quantity Inverse Time Overcurrent Element 1	
Table 9.50	Selectable Operating Quantity Inverse Time Overcurrent Element 2	
Table 9.50	Selectable Operating Quantity Inverse Time Overcurrent Element 3	
Table 9.51	Zone/Level Direction	
Table 9.52	Directional Control Element	
Table 9.55	Pole Open Detection	
Table 9.55	POTT Trip Scheme	
Table 9.55	DCUB Trip Scheme	
Table 9.50	DCB Trip Scheme	
Table 9.57	Breaker 1 Failure Logic (and Breaker 2 Failure Logic)	
Table 9.58	Synchronism Check Element Reference	
Table 9.60	Breaker 1 Synchronism Check	
Table 9.60 Table 9.61	Breaker 2 Synchronism Check	
Table 9.61 Table 9.62	Recloser and Manual Closing	
Table 9.62	Single-Pole Reclose Settings	
Table 9.63 Table 9.64	Three-Pole Reclose Settings	
Table 9.65	Voltage Elements	
14010 7.05		11. / .4/

Table 9.66	Demand Metering	R 9 27
Table 9.67	Trip Logic	
Table 9.68	Protection Free-Form SELOGIC Control Equations	
Table 9.69	Output Settings Categories	
Table 9.70	Main Board.	
Table 9.71	Interface Board #1	
Table 9.72	Interface Board #2	
Table 9.72	Communications Card Outputs	
Table 9.74	MIRRORED BITS Transmit Equations	
Table 9.75	Front-Panel Settings Categories	
Table 9.76	Front Panel Settings	
Table 9.77	Selectable Screens for the Front Panel	
Table 9.78	Display Points and Aliases	
Table 9.79	Local Control and Aliases	
Table 9.80	Report Settings Categories	
Table 9.81	SER Chatter Criteria	
Table 9.82	SER Points and Aliases	
Table 9.82	Event Reporting	
Table 9.84	Event Reporting Digital Elements	
Table 9.85	Port Settings Categories	
Table 9.86	Protocol Selection	
Table 9.87	Communications Settings	
Table 9.88	SEL Protocol Settings	
Table 9.89	Synchronized Phasor Measurement Settings	
Table 9.90	DNP 3.0 Protocol Settings	
Table 9.90	MIRRORED BITS Protocol Settings	
Table 9.92	Ethernet Settings	
Table 9.92	FTP Settings	
Table 9.93	Telnet Settings	
Table 9.94	Network Host Name	
Table 9.95	UCA Settings	
Table 9.90	DNP 3.0 Settings Categories	
Table 9.98	DNP 3.0 Object Default Map Enables	
Table 9.99	Binary Input Map	
Table 9.100		
Table 9.100	Binary Output Map Counter Map	
Table 9.101 Table 9.102	Analog Input Map	
Table 9.102	Analog Output Map	
Appendix A: Re		
Table A.1	Alphabetic List of Relay Word Bits	
Table A.2	Relay Word Bits: Enable and Tripping	
Table A.3	Relay Word Bits: Distance Elements	
Table A.4	Relay Word Bits: Series Compensated Line Logic	
Table A.5	Relay Word Bits: Out-of-Step Elements	
Table A.6	Relay Word Bits: Directional Elements	
Table A.7	Relay Word Bits: Overcurrent Elements	
Table A.8	Relay Word Bits: Synchronism-Check Elements	
Table A.9	Relay Word Bits: Reclosing Elements	
Table A.10	Relay Word Bits: Miscellaneous Elements	
Table A.11	Relay Word Bits: Trip Logic Elements	
Table A.12	Relay Word Bits: Pilot Tripping Elements	
Table A.13	Relay Word Bits: Circuit Breaker 1 Failure	
Table A.14	Relay Word Bits: Circuit Breaker 2 Failure Elements	
Table A.15	Relay Word Bits: Circuit Breaker Status and Open Phase Detector	
Table A.16	Relay Word Bits: Reserved Category Elements	
Table A.17	Relay Word Bits: Circuit Breaker Monitor	
Table A.18	Relay Word Bits: Reserved Category	R.A.36

Table A.19	Relay Word Bits: DC Supply Monitor	R.A.37
Table A.20	Relay Word Bits: Metering Elements	
Table A.21	Relay Word Bits: Open and Close Command	R.A.37
Table A.22	Relay Word Bits: Local Bits	R.A.38
Table A.23	Relay Word Bits: Remote Bits	R.A.38
Table A.24	Relay Word Bits: Active Protection Settings Group	R.A.39
Table A.25	Relay Word Bits: Input Elements	R.A.40
Table A.26	Relay Word Bits: Protection Variables	R.A.41
Table A.27	Relay Word Bits: Protection Latches	R.A.43
Table A.28	Relay Word Bits: Protection Conditioning Timers	R.A.44
Table A.29	Relay Word Bits: Protection Sequencing Timers	R.A.44
Table A.30	Relay Word Bits: Protection Counters	R.A.46
Table A.31	Relay Word Bits: Automation Variables	R.A.47
Table A.32	Relay Word Bits: Automation Latches	R.A.54
Table A.33	Relay Word Bits: Automation Sequencing Timers	R.A.55
Table A.34	Relay Word Bits: Automation Counters	R.A.57
Table A.35	Relay Word Bits: SELOGIC Control Equation Error and Status	R.A.58
Table A.36	Relay Word Bits: Relay Alarms	R.A.59
Table A.37	Relay Word Bits: Reserved Category	R.A.60
Table A.38	Relay Word Bits: Time and Date Elements	R.A.63
Table A.39	Relay Word Bits: Output Elements	R.A.64
Table A.40	Relay Word Bits: Pushbutton Elements	R.A.65
Table A.41	Relay Word Bits: Data Reset Bits	R.A.66
Table A.42	Relay Word Bits: Target Logic Bits	R.A.66
Table A.43	Relay Word Bits: MIRRORED BITS	R.A.67
Table A.44	Relay Word Bits: Test Bits	
Table A.45	Relay Word Bits: Communications Card Input Points	R.A.69
Table A.46	Relay Word Bits: Communications Card Output Points	R.A.70
Table A.47	Relay Word Bits: Communications Card Status Points	R.A.71
Table A.48	Relay Word Bits: Fast SER Enable Bits	R.A.72
Table A.49	Relay Word Bits: Source Selection Elements	R.A.72
Annendix B. An	alog Quantities	
Table B.1		D D 2
Table B.2	Analog Quantities Sorted By Function Analog Quantities Sorted Alphabetically	
		K.D . /
Appendix C: GO	MSFE Tables	
Table C.1	GOMSFE Model Table Column Definitions	R.C.2
Table C.2	SEL-421 Relay Domains	
Table C.3	Models in LN0 Domain	R.C.4
Table C.4	Device ID Model (DI)—LN0 Domain	R.C.4
Table C.5	GCTL Model (GCTL)—LN0 Domain	
Table C.6	Globe Model (GLOBE)—LN0 Domain	R.C.5
Table C.7	Models in Virtual Device Domain for SEL-421 Relays	R.C.9
Table C.8	Device ID Model (DI)—SEL-421 Relay Domain	R.C.9
Table C.9	Fault Identification Model (FAULT1-FAULT20)-SEL-421 Relay Domain	R.C.10
Table C.10	GCTL Model (GCTL)—SEL-421 Relay Domain	
Table C.11	Globe Model (GLOBE)—SEL-421 Relay Domain	R.C.11
Table C.12	Polyphase Meter Unit Model (MMTR)—SEL-421 Relay Domain	R.C.15
Table C.13	Polyphase Measurement Unit Model (MMXU)-SEL-421 Relay Domain	R.C.15
Table C.14	Circuit Breaker Control and Status Model	
	(XCBR1—XCBR2)—SEL-421 Relay Domain	
Table C.15	Special Translation Rules	
Table C.16	SEL-421 Relay Target Bit Mapping	
Table C.17	Event Types	
Table C.18	Common Fault Types	R.C.19

List of Figures

User's Guide

Section 1: Intro	duction and Specifications	
Figure 1.1	SEL-421 Relay Functional Overview.	. U.1.2
Figure 1.2	Protecting a Line Segment With MIRRORED BITS Communications on a Fiber Channel.	
Figure 1.3	Single Circuit Breaker Configuration (ESS := 1)	. U.1.6
Figure 1.4	Single Circuit Breaker Configuration With Line and Breaker CTs (ESS := 2)	
Figure 1.5	Double Circuit Breaker Configuration (ESS := 3).	
Figure 1.6	Double Circuit Breaker Configuration With Bus Protection (ESS := 4).	. U.1.8
Figure 1.7	Tapped Line (ESS := Y).	. U.1.8
Section 2: Insta	allation	
Figure 2.1	Horizontal Front-Panel Template.	. U.2.4
Figure 2.2	Vertical Front-Panel Template.	. U.2.4
Figure 2.3	Rear 3U Template, Fixed Terminal Block Analog Inputs	. U.2.5
Figure 2.4	Rear 3U Template, Connectorized Analog Inputs.	. U.2.5
Figure 2.5	Standard Control Output Connection.	
Figure 2.6	Hybrid Control Output Connection.	. U.2.8
Figure 2.7	Fast Hybrid Control Output Connection.	. U.2.8
Figure 2.8	Fast Hybrid Control Output Typical Terminals	. U.2.9
Figure 2.9	Precharging Internal Capacitance of Fast Hybrid Output Contacts.	. U.2.9
Figure 2.10	INT1 or INT6 I/O Interface Board.	U.2.12
Figure 2.11	INT5 I/O Interface Board.	U.2.12
Figure 2.12	Chassis Key Positions for I/O Interface Boards.	U.2.14
Figure 2.13	Major Component Locations on the SEL-421 Relay Main Board	U.2.18
Figure 2.14	J18 Header—Password and Breaker Jumpers	U.2.19
Figure 2.15	Major Component Locations on the SEL-421 Relay INT1 I/O Board.	U.2.22
Figure 2.16	Major Component Locations on the SEL-421 Relay INT5 I/O Board.	U.2.23
Figure 2.17	Major Component Locations on the SEL-421 Relay INT6 I/O Board.	
Figure 2.18	Blank Slide-In Label Set and Label Removal Tool	
Figure 2.19	SEL-421 Relay Chassis Dimensions.	U.2.32
Figure 2.20	3U Rear Panel, SEL-421 Relay.	U.2.33
Figure 2.21	3U Rear Panel, Connectorized SEL-421 Relay	
Figure 2.22	4U Rear Panel, Without Optional I/O, SEL-421 Relay	
Figure 2.23	4U Rear Panel, INT5 I/O Interface Board, SEL-421 Relay.	
Figure 2.24	5U Rear Panel, INT5 and INT1/INT6 I/O Interface Board, SEL-421 Relay	
Figure 2.25	Rear-Panel Symbols.	
Figure 2.26	Screw Terminal Connector Keying.	
Figure 2.27	Rear-Panel Receptacle Keying, SEL-421 Relay.	
Figure 2.28	PS30 Power Supply Fuse Location.	
Figure 2.29	Control Output OUT108.	
Figure 2.30	SEL-421 Relay to Computer—D-Subminiature 9-Pin Connector.	
Figure 2.31	Typical External AC/DC Connections—Single Circuit Breaker.	
Figure 2.32	Typical External AC/DC Connections—Dual Circuit Breaker	U.2.49
0 11 0 D0 0		

Section 3: PC Software

Figure 3.1	SEL Software License Agreement.	U.3.3
Figure 3.2	Windows Run Command Line to Load the ACSELERATOR Software	U.3.3
Figure 3.3	ACSELERATOR Communication Parameters Dialog Box.	U.3.4
Figure 3.4	ACSELERATOR Network Parameters Dialog Box: FTP	U.3.5
Figure 3.5	ACSELERATOR Network Parameters Dialog Box: Telnet.	U.3.5
Figure 3.6	Database Manager Relay Database in the ACSELERATOR Software.	U.3.6

Figure 3.7	Database Manager Copy/Move in the ACSELERATOR Software	U.3.7
Figure 3.8	ACSELERATOR Software Driver Information in the FID String	U.3.8
Figure 3.9	HMI Driver Version Number in the HMI Window.	
Figure 3.10	Sample Settings in the ACSELERATOR Software	U.3.9
Figure 3.11	Selecting a Settings Driver in the ACSELERATOR Software.	U.3.10
Figure 3.12	Opening Relay Settings in the ACSELERATOR Software.	U.3.10
Figure 3.13	Reading Relay Settings in the ACSELERATOR Software	U.3.11
Figure 3.14	ACSELERATOR Software Relay Editor.	
Figure 3.15	Retrieving the Relay Part Number.	
Figure 3.16	Setting the Relay Part Number in the ACSELERATOR Software.	
Figure 3.17	Location of EB Option Button	U.3.13
Figure 3.18	The ACSELERATOR Expression Builder.	
Figure 3.19	Retrieving Relay Event History.	
Figure 3.20	ACSELERATOR Event Waveform Window.	
Figure 3.21	Sample Event Oscillogram.	
Figure 3.22	Retrieving Event Report Waveforms.	U.3.16
Figure 3.23	Sample Phasors Event Waveform Screen	U.3.17
Figure 3.24	Sample Harmonic Analysis Event Waveform Screen.	
Figure 3.25	Sample Event Report Summary Screen	
Figure 3.26	Sample Event Waveform Settings Screen.	
Figure 3.27	ACSELERATOR HMI Features	

Section 4: Basic Relay Operations

Figure 4.1	SEL-421 Relay Serial Number Label.	U.4.2
Figure 4.2	Power Connection Area of the Rear Panel.	
Figure 4.3	PORT F, LCD Display, and Navigation Pushbuttons.	U.4.5
Figure 4.4	Report Header.	U.4.6
Figure 4.5	Access Level Structure.	
Figure 4.6	Default Passwords.	U.4.11
Figure 4.7	Relay Status.	U.4.12
Figure 4.8	ACSELERATOR Software Port Parameters and Password Entry.	
Figure 4.9	Retrieving Relay Status: ACSELERATOR Software.	U.4.13
Figure 4.10	Checking Relay Status: Front-Panel LCD.	U.4.14
Figure 4.11	Relay Settings Structure Overview.	U.4.16
Figure 4.12	Components of SET Commands.	
Figure 4.13	Initial Global Settings.	U.4.20
Figure 4.14	Using Text-Edit Mode Line Editing to Set Display Points	U.4.23
Figure 4.15	Using Text-Edit Mode Line Editing to Delete a Display Point.	
Figure 4.16	Selecting Global Settings in the ACSELERATOR Software.	U.4.26
Figure 4.17	The ACSELERATOR Software Global Settings Window.	
Figure 4.18	Uploading Global Settings to the SEL-421 Relay.	
Figure 4.19	DATE and TIME Settings: Front-Panel LCD.	
Figure 4.20	SETTINGS Menus.	
Figure 4.21	Setting ESS: Terminal	U.4.31
Figure 4.22	Setting CTRW and PTRY: Terminal.	U.4.32
Figure 4.23	Test Connections Using Three Voltage Sources/Three Current Sources	U.4.32
Figure 4.24	Test Connections Using Two	
	Current Sources for Three-Phase Faults and METER Test.	U.4.33
Figure 4.25	Terminal Screen MET Metering Quantities.	U.4.34
Figure 4.26	Global Alternate Source Selection Settings in the ACSELERATOR Software	U.4.35
Figure 4.27	Group 1 Terminal Configuration Settings: ACSELERATOR Software.	U.4.36
Figure 4.28	HMI Tree View: ACSELERATOR Software.	U.4.36
Figure 4.29	Phasor Metering Quantities: ACSELERATOR HMI.	U.4.37
Figure 4.30	Front-Panel Screens for METER.	U.4.38
Figure 4.31	ACSELERATOR HMI Tree View.	U.4.40
Figure 4.32	ACSELERATOR HMI Control Window	U.4.40
Figure 4.33	Event Trigger Prompt: ACSELERATOR Software.	U.4.41
Figure 4.34	Relay Event History Dialog Box	U.4.42

Figure 4.35	Sample HIS Command Output: Terminal.	
Figure 4.36	EVENTS Folder Files.	
Figure 4.37	Relay Event History Dialog Box in the ACSELERATOR Software	
Figure 4.38	ACSELERATOR Event Waveform Window.	
Figure 4.39	Sample Event Oscillogram	
Figure 4.40	Selecting SER Points and Aliases Settings: ACSELERATOR Software	
Figure 4.41	SER Points and Aliases Settings: ACSELERATOR Software.	
Figure 4.42	Uploading Report Settings to the SEL-421 Relay	
Figure 4.43	Retrieving SER Records With the ACSELERATOR Software.	
Figure 4.44	SER Records in the ACSELERATOR HMI.	
Figure 4.45	Setting an SER Element: Terminal.	
Figure 4.46	Reports File Structure	U.4.51
Figure 4.47	Terminal Display for PULSE Command.	
Figure 4.48	Front-Panel Menus for Pulsing OUT104.	
Figure 4.49	Password Entry Screen	
Figure 4.50	Using Text-Edit Mode Line Editing to Set Local Bit 3	
Figure 4.51	Setting Control Output OUT105: Terminal.	U.4.56
Figure 4.52	Front-Panel LOCAL CONTROL Screens.	
Figure 4.53	Assigning an Additional Close Output: ACSELERATOR Software	U.4.58
Figure 4.54	Uploading Output Settings to the SEL-421 Relay.	
Figure 4.55	Setting 52AA1: Terminal.	
Figure 4.56	Accessing Global Enable Settings in the ACSELERATOR Software	U.4.63
Figure 4.57	Control Input Settings in the ACSELERATOR Software	
Figure 4.58	Setting BK1TYP in the ACSELERATOR Software.	
Figure 4.59	Setting 52AA1 in the ACSELERATOR Software.	U.4.64
Figure 4.60	Uploading Global and Breaker Monitor Settings to the SEL-421 Relay	U.4.65
Figure 4.61	TIME BNC Jacks.	U.4.67
Figure 4.62	Confirming the High-Accuracy Timekeeping Enable Settings	U.4.68
Figure 4.63	Results of the TIME Q Command	
Figure 4.64	Programming a PSV in the ACSELERATOR Software.	
Figure 4.65	Setting OUT108 in the ACSELERATOR Software	U.4.71
Figure 4.66	Uploading Group 1 and Breaker Monitor Settings to the SEL-421 Relay	U.4.71

Section 5: Front-Panel Operations

Figure 5.1	SEL-421 Relay Front Panel	U.5.2
Figure 5.2	LCD Display and Navigation Pushbuttons.	
Figure 5.3	RELAY ELEMENTS Highlighted in MAIN MENU.	
Figure 5.4	Sample ROTATING DISPLAY.	
Figure 5.5	Sample Display Points Screen	U.5.6
Figure 5.6	Fast Meter Display Points Sample Screen.	U.5.8
Figure 5.7	Contrast Adjustment.	U.5.9
Figure 5.8	Enter Password Screen.	U.5.10
Figure 5.9	Invalid Password Screen.	U.5.10
Figure 5.10	MAIN MENU	U.5.11
Figure 5.11	METER MENU Screens.	U.5.11
Figure 5.12	METER SUBMENU.	U.5.12
Figure 5.13	RMS, FUND, and DEMAND Metering Screens.	U.5.13
Figure 5.14	ENERGY, MAX/MIN, and SYNCH CHECK Metering Screens.	U.5.14
Figure 5.15	EVENT SUMMARY Screens.	U.5.15
Figure 5.16	BREAKER MONITOR Report Screens.	U.5.15
Figure 5.17	RELAY ELEMENTS Screen.	U.5.16
Figure 5.18	ELEMENT SEARCH Screen	U.5.16
Figure 5.19	LOCAL CONTROL Initial Menu.	U.5.17
Figure 5.20	BREAKER CONTROL Screens.	U.5.18
Figure 5.21	LOCAL CONTROL Example Menus	U.5.19
Figure 5.22	OUTPUT TESTING Screen	U.5.21
Figure 5.23	SET/SHOW Screens.	U.5.22
Figure 5.24	Sample Settings Input Screens.	U.5.23

Figure 5.25	Changing the ACTIVE GROUP.	
Figure 5.26	DATE/TIME Screen.	
Figure 5.27	Edit DATE and Edit TIME Screens.	
Figure 5.28	Relay STATUS Screens.	
Figure 5.29	VIEW CONFIGURATION Sample Screens.	
Figure 5.30	DISPLAY TEST Screens.	
Figure 5.31	RESET ACCESS LEVEL Screen.	
Figure 5.32	Sample Status Warning and Trip EVENT SUMMARY Screens.	
Figure 5.33	Sample Status Warning in the LCD Message Area.	
Figure 5.34	Factory Default Front-Panel Target Areas.	
Figure 5.35	Operator Control Pushbuttons and LEDs.	
Figure 5.36	Factory Default Operator Control Pushbuttons—Left Side.	
Figure 5.37	Factory Default Operator Control Pushbuttons—Right Side.	
Section 6: Test	ting and Troubleshooting	
Figure 6.1	Low-Level Test Interface.	U.6.7
Figure 6.2	Test Connections Using Three Voltage and Three Current Sources	U.6.9
Figure 6.3	Test Connections Using Two Current Sources for	
	Phase-to-Phase, Phase-to-Ground, and Two-Phase-to-Ground Faults	U.6.10
Figure 6.4	Test Connections Using Two Current Sources for Three-Phase Faults	U.6.11
Figure 6.5	Test Connections Using a Single Current Source for a Phase-to-Ground Fault	U.6.12
Figure 6.6	Test Connections Using a Single Current Source for a Phase-to-Phase Fault	U.6.13
Figure 6.7	Sample Targets Display on a Serial Terminal.	
Figure 6.8	Viewing Relay Word Bits From the Front-Panel LCD.	U.6.16
Figure 6.9	Setting Pushbutton LED Response: ACSELERATOR Software.	U.6.17
Figure 6.10	Uploading Front-Panel Settings to the SEL-421 Relay.	U.6.18
Figure 6.11	Setting Main Board Outputs: ACSELERATOR Software.	U.6.19
Figure 6.12	Uploading Output Settings to the SEL-421 Relay.	U.6.19
Figure 6.13	Checking the 51S1 Overcurrent Element: ACSELERATOR Software.	U.6.21
Figure 6.14	Setting SER Points and Aliases: ACSELERATOR Software.	U.6.22
Figure 6.15	Uploading Group 1 and Report Settings to SEL-421 Relay.	
Figure 6.16	HMI Tree View: ACSELERATOR Software.	U.6.23
Figure 6.17	SER Report: ACSELERATOR HMI.	
Figure 6.18	Group 1 Relay Configuration Settings: ACSELERATOR Software.	U.6.26
Figure 6.19	Negative-Sequence Instantaneous	
	Overcurrent Element Settings: ACSELERATOR Software.U.6.26	
Figure 6.20	Uploading Group 1 Settings to the SEL-421 Relay	
Figure 6.21	ELEMENT SEARCH Screen.	
Figure 6.22	RELAY ELEMENTS Screen Containing Element 50Q1	
Figure 6.23	Group 1 Relay Configuration Settings: ACSELERATOR Software	
Figure 6.24	Breaker 1 Breaker Monitor Settings: ACSELERATOR Software	
Figure 6.25	Group 1 Line Configuration Settings: ACSELERATOR Software.	
Figure 6.26	Directional Settings: ACSELERATOR Software.	U.6.31
Figure 6.27	Uploading Group 1 and	
	Breaker Monitor Settings to the SEL-421 Relay.U.6.31	
Figure 6.28	RELAY ELEMENTS LCD	
	Screen Containing Elements F32Q and R32Q.U.6.32	
Figure 6.29	Finding Phase-to-Phase Test Quantities.	
Figure 6.30	Phase Distance Elements Settings: ACSELERATOR Software.	
Figure 6.31	RELAY ELEMENTS LCD Screen Containing Element MBC2	
Figure 6.32	Relay Status: ACSELERATOR HMI.	
Figure 6.33	Relay Status From a STATUS A Command on a Terminal	
Figure 6.34	Compressed ASCII CST Command on a Terminal.	U.6.39

Appendix A: Firmware Versions

Applications Handbook

Section 1: Protection Application Examples

Figure 1.1	230 kV Overhead Transmission Line.	A.1.3
Figure 1.2	Circuit Breaker Arrangement at Station S	
Figure 1.3	500 kV Parallel Overhead Transmission Lines.	
Figure 1.4	Circuit Breaker-and-a-Half Arrangement: Station S, Line 1.	
Figure 1.5	Quadrilateral Ground Distance Element Reactive Reach Setting	
Figure 1.6	Definition of Homogeneous Network	
Figure 1.7	Tilt in Apparent Fault Impedance Resulting From Nonhomogeneity	
Figure 1.8	Nonhomogeneous Angle Setting.	
Figure 1.9	Current Distribution During Cross-Country Fault.	
Figure 1.10	Simplified POTT Scheme KEY1/KEY3 Logic.	
Figure 1.11	345 kV Tapped Overhead Transmission Line.	
Figure 1.12	Circuit Breaker Arrangement at Station S	
Figure 1.12	Reverse Zone 3 Coordination.	
Figure 1.14	Impedance Diagram.	
Figure 1.15	Load-Encroachment Function.	
Figure 1.16	345 kV Tapped Line Negative-Sequence Network.	
Figure 1.17	345 kV Tapped Line Zero-Sequence Network	
Figure 1.17	DC Schematic for DCB Trip Scheme.	
-		
Figure 1.19	230 kV Parallel Underground Cables	
Figure 1.20	Circuit Breaker Arrangement at Station S, Cable 1.	
Figure 1.21	Quadrilateral Ground Distance Element Reactive Reach Setting	
Figure 1.22	Circuit to Determine Network Homogeneity.	
Figure 1.23	Apparent Fault Impedance Resulting From Nonhomogeneity	
Figure 1.24	Nonhomogeneous Angle Setting.	
Figure 1.25	External Ground Fault.	
Figure 1.26	Negative-Sequence Fault Current Distribution—External Ground Fault	
Figure 1.27	Reverse Unbalanced Fault on Cable Circuit (Shunt Admittance)	
Figure 1.28	500 kV Power System.	
Figure 1.29	OOS Characteristic Settings Parameters.	
Figure 1.30	Calculating Setting R1R7.	
Figure 1.31	Swing Trajectory to Determine the OSBD Setting.	
Figure 1.32	Inner Blinders.	
Figure 1.33	OST Characteristics	
Figure 1.34	230 kV Example Power System.	
Figure 1.35	Circuit Breaker Arrangement at Station S	
Figure 1.36	Potential Sources.	
Figure 1.37	500 kV Power System.	
Figure 1.38	Partial Circuit Breaker-and-a-Half Arrangement at Station S, Line 1	
Figure 1.39	Potential Sources.	
Figure 1.40	Scheme 1 All Faults and Scheme 2 Multiphase Fault Timing Diagram	
Figure 1.41	Scheme 2 Single-Phase Fault Timing Diagram.	
Figure 1.42	230 kV Power System for Circuit Breaker Failure Scheme 1	
Figure 1.43	Timing Diagram for Setting BFPU1—Scheme 1	
Figure 1.44	Circuit Breaker Failure Trip and Circuit Breaker Trip DC Connections	
Figure 1.45	500 kV Power System for Circuit Breaker Failure Scheme 2	
Figure 1.46	Fault Current Distribution Through Faulted Line at Station S	
Figure 1.47	Timing Diagram for Setting BFPU1—Scheme 2	A.1.163
Figure 1.48	Timing Sequences for Circuit Breaker Failure Protection Scheme 2	A.1.164
Figure 1.49	Circuit Breaker BK1 DC Connections (Two Trip Coils).	
Section 2: Moni	itoring and Metering	
	SEL-421 Relay Intelligent Circuit Breaker Monitor	A.2.2

Figure 2.1	SEL-421 Relay Intelligent Circuit Breaker Monitor.	
Figure 2.2	Circuit Breaker Maintenance Curve (Manufacturer's Data)	
Figure 2.3	Circuit Breaker Contact Wear Curve With SEL-421 Relay Settings	
Figure 2.4	Trip Bus Sensing With Relay Input IN106.	

Figure 2.5	Mechanical Operating Time for Circuit Breaker 1 A-Phase.	
Figure 2.6	Electrical Operating Time for Circuit Breaker 1 A-Phase	
Figure 2.7	Timing Illustration for Pole Scatter at Trip	
Figure 2.8	Pole Discrepancy Measurement.	
Figure 2.9	Breaker Report	
Figure 2.10	Breaker History Report	
Figure 2.11	Circuit Breaker Preload Data	
Figure 2.12	Typical Station DC Battery System.	
Figure 2.13	Ground Detection Factor Areas.	
Figure 2.14	Battery Metering: Terminal.	
Figure 2.15	Complex Power (P/Q) Plane	
Figure 2.16	Typical Current Measuring Accuracy.	
Figure 2.17	Thermal Demand Metering.	
Figure 2.18	Rolling Demand Metering.	
Figure 2.19	Demand Current Logic Outputs.	A.2.39
Section 3: Ana	alyzing Data	
Figure 3.1	SEL-421 Relay Input Processing	A.3.2
Figure 3.2	Data Capture/Event Report Times.	
Figure 3.3	Sample SEL-421 Relay Oscillogram.	
Figure 3.4	Sample COMTRADE .HDR Header File	
Figure 3.5	COMTRADE .CFG Configuration File Data.	A.3.10
Figure 3.6	Analog Section of the Event Report.	
Figure 3.7	Event Report Current Column Data and RMS Current Magnitude	
Figure 3.8	Event Report Current Column Data and RMS Current Angle.	
Figure 3.9	Digital Section of the Event Report.	A.3.20
Figure 3.10	Sample Digital Portion of the Event Report.	
Figure 3.11	Summary Section of the Event Report.	
Figure 3.12	Settings Section of the Event Report.	
Figure 3.13	Sample Compressed ASCII Event Report.	A.3.27
Figure 3.14	Sample Event Summary Report.	A.3.28
Figure 3.15	Sample Compressed ASCII Summary	A.3.31
Figure 3.16	Sample Event History.	
Figure 3.17	Sample Compressed ASCII History Report.	A.3.33
Figure 3.18	Sample SER Report.	A.3.34
Figure 3.19	Sample Compressed ASCII SER Report.	A.3.36
Section 4: Tim	e-Synchronized Measurements	
Figure 4.1	Very High-Accuracy Timekeeping Connections.	A.4.2
Figure 4.2	Selecting Protection Logic 1 Settings in the ACSELERATOR Software	
Figure 4.3	Setting PMV64 with the Expression Builder Dialog Box.	
Figure 4.4	Selecting Trip Logic and ER Trigger Settings in the ACSELERATOR Software	
E' 4.5		× 4 7

Figure 4.5	Uploading Group Settings to the SEL-421 Relay	A.4.5
Figure 4.6	230 kV Transmission Line System.	
Figure 4.7	500 kV Three Bus Power System.	
Figure 4.8	Power Flow Solution.	

Section 5: Substation Automatic Restoration

Figure 5.1	230 kV Tapped Overhead Transmission Line.	A.5.2
Figure 5.2	Automatic Restoration Timing Diagram.	
Figure 5.3	SEL-421 Relay Inputs.	A.5.5
Figure 5.4	Protection Free-Form SELOGIC Control Equations	A.5.11
Figure 5.5	Protection Free-Form SELOGIC Control Equations.	A.5.13
Figure 5.6	Ladder Logic Representation, Protection Free-Form SELOGIC Control Equations	A.5.15

Section 6: SEL-2030 Applications

Figure 6.1	SEL-2030 Star Integration Network.	
Figure 6.2	Multitiered SEL-2030 Architecture.	
Figure 6.3	Enhancing Multidrop Networks With the SEL-2030.	A.6.5
Figure 6.4	Example SEL-421 Relay and SEL-2030 Configuration.	

Section 7: Direct Network Communication

Figure 7.1	DNP Multidrop Network Topology	A.7.3
Figure 7.2	DNP Star Network Topology.	
Figure 7.3	DNP Network with Communications Processor.	
Figure 7.4	Example Direct Networking Topology	A.7.7
Figure 7.5	Telnet Connection Dialog Box.	
Figure 7.6	Example FTP Session	
Figure 7.7	Partial Contents of SET P5.TXT.	
Figure 7.8	Example Telnet Session.	A.7.12
-		

Reference Manual

Section 1: Protection Functions

Figure 1.1	ESS := 1; Single Circuit Breaker Configuration.	R 1 3
Figure 1.2	ESS := 2; Single Circuit Breaker Configuration.	
Figure 1.3	ESS := 3; Double Circuit Breaker Configuration	
Figure 1.4	ESS := 4; Double Circuit Breaker Configuration	
Figure 1.5	Tapped EHV Overhead Transmission Line	
Figure 1.6	ESS := Y; Tapped Line.	
Figure 1.7	ESS := Y; Single Circuit Breaker	
	With Current Polarizing Source Tapped Power Transformer.	
Figure 1.8	Frequency Estimation.	
Figure 1.9	Pole Open Logic Diagram	R.1.15
Figure 1.10	LOP Logic Process Overview	
Figure 1.11	LOP Logic.	
Figure 1.12	32Q and 32QG Enable Logic Diagram.	R.1.25
Figure 1.13	32V and 32I Enable Logic Diagram.	
Figure 1.14	Best Choice Ground Directional Logic.	R.1.27
Figure 1.15	Negative-Sequence Voltage-Polarized Directional Element Logic	
Figure 1.16	Zero-Sequence Voltage-Polarized Directional Element Logic.	
Figure 1.17	Zero-Sequence Current-Polarized Directional Element Logic.	
Figure 1.18	Ground Directional Element Output Logic Diagram.	R.1.29
Figure 1.19	32P, Phase Directional Element Logic Diagram.	
Figure 1.20	32Q, Negative-Sequence Directional Element Logic Diagram.	
Figure 1.21	CVT Transient Detection Logic.	
Figure 1.22	Load-Encroachment Logic Diagram.	R.1.39
Figure 1.23	Load-Encroachment Characteristics.	R.1.39
Figure 1.24	OOS Characteristics.	R.1.41
Figure 1.25	OOS Positive-Sequence Measurements.	R.1.44
Figure 1.26	OOS Override Logic.	R.1.44
Figure 1.27	OOS Logic Diagram	R.1.45
Figure 1.28	Zone 1 Mho Ground Distance Element Logic Diagram.	R.1.48
Figure 1.29	Zone 2 Mho Ground Distance Element Logic Diagram.	R.1.49
Figure 1.30	Zones 3, 4, and 5 Mho Ground Distance Element Logic Diagram	R.1.50
Figure 1.31	Zone 1 Quadrilateral Ground Distance Element Logic Diagram	R.1.53
Figure 1.32	Zone 2 Quadrilateral Distance Element Logic Diagram	
Figure 1.33	Zones 3, 4, and 5 Quadrilateral Ground Distance Element Logic.	
Figure 1.34	Zone 1 Mho Phase Distance Element Logic Diagram.	
Figure 1.35	Zone 2 Mho Phase Distance Element Logic Diagram.	
Figure 1.36	Zones 3, 4, and 5 Mho Phase Distance Element Logic Diagram	
Figure 1.37	Zone Timers.	

Figure 1.38	Phase Instantaneous and Directional Overcurrent.	R.1.66
Figure 1.39	Residual Ground Instantaneous and Directional Overcurrent.	R.1.67
Figure 1.40	Negative-Sequence Instantaneous and Directional Overcurrent.	R.1.68
Figure 1.41	US Moderately Inverse—U1.	R.1.74
Figure 1.42	US Inverse—U2.	R.1.75
Figure 1.43	US Very Inverse—U3.	R.1.76
Figure 1.44	US Extremely Inverse—U4.	
Figure 1.45	US Short-Time Inverse—U5.	R.1.78
Figure 1.46	IEC Standard Inverse—C1.	R.1.79
Figure 1.47	IEC Very Inverse—C2.	
Figure 1.48	IEC Extremely Inverse—C3	
Figure 1.49	IEC Long-Time Inverse—C4.	
Figure 1.50	IEC Short-Time Inverse—C5.	
Figure 1.51	Selectable Time-Overcurrent Element Logic Diagram.	R.1.84
Figure 1.52	SOTF Logic Diagram.	
Figure 1.53	Required Zone Directional Settings.	
Figure 1.54	DCB Logic Diagram	
Figure 1.55	Permissive Trip Receiver Logic Diagram.	
Figure 1.56	POTT Logic Diagram.	
Figure 1.57	POTT Cross-Country Logic Diagram.	
Figure 1.58	Permissive Trip Receiver Logic Diagram.	
Figure 1.59	DCUB Logic Diagram.	
Figure 1.60	Trip Logic Diagram.	
Figure 1.61	Two Circuit Breakers Trip Logic Diagram.	
Figure 1.62	Trip A Unlatch Logic	
Figure 1.63	Trip During Pole Open.	
Figure 1.64	Scheme 1 Logic Diagram.	
Figure 1.65	Scheme 2 Three-Pole Circuit Breaker Failure Protection Logic.	
Figure 1.66	Scheme 2 Single-Pole Circuit Breaker Failure Protection Logic.	
Figure 1.67	Current-Supervised Three-Pole Retrip Logic.	
Figure 1.68	Current-Supervised Single-Pole Retrip Logic No Current/Residual Current Circuit Breaker Failure Protection Logic Diagram	
Figure 1.69	Circuit Breaker Failure Seal-In Logic Diagram.	
Figure 1.70 Figure 1.71	Failure to Interrupt Load Current Logic Diagram.	
Figure 1.72	Flashover Protection Logic Diagram.	
Figure 1.72	Circuit Breaker Failure Trip Logic Diagram.	
-		
Section 2: Auto	o-Reclose and Synchronism Check	
Figure 2.1	Auto-Reclose State Diagram for Circuit Breaker 1	
Figure 2.2	Multiple Circuit Breaker Arrangement.	R.2.15
Figure 2.3	Multiple Circuit Breaker Arrangement.	R.2.18
Figure 2.4	Leader/Follower Selection by Relay Input.	R.2.22
Figure 2.5	Voltage Sources for Circuit Breaker-and-a-Half Arrangement.	R.2.27
Figure 2.6	Voltage Sources for Single Circuit Breaker Arrangement.	R.2.27
Figure 2.7	Voltage Sources for Single Circuit Breaker Arrangement.	R.2.28
Figure 2.8	Circuit Breaker Pole-Open Logic Diagram.	
Figure 2.9	Line-Open Logic Diagram	R.2.32
Figure 2.10	Single-Pole Reclose Enable	
Figure 2.11	Three-Pole Reclose Enable	
Figure 2.12	Voltage Check Elements.	
Figure 2.13	One Circuit Breaker Single-Pole Cycle State (79CY1)	
Figure 2.14	One Circuit Breaker Three-Pole Cycle State (79CY3)	
Figure 2.15	Two Circuit Breakers Single-Pole Cycle State (79CY1).	
Figure 2.16	Two Circuit Breakers Three-Pole Cycle State (79CY3)	
Figure 2.17	Partial Breaker-and-a-Half or Partial Ring-Bus Breaker Arrangement.	
Figure 2.18	Voltage Angle Difference in a Paralleled System.	
Figure 2.19	Synchronism-Check Voltages for Two Circuit Breakers.	
Figure 2.20	Synchronism-Check Settings.	К .2.44

Figure 2.21	Synchronism-Check Relay Word Bits	R.2.44
Figure 2.22	Synchronism-Check Voltage Connections to SEL-421 Relay.	R.2.46
Figure 2.23	Synchronism-Check Voltage Reference.	R.2.47
Figure 2.24	Normalized Synchronism-Check Voltage Sources VS1 and VS2	R.2.48
Figure 2.25	Healthy Voltage Window and Indication.	R.2.49
Figure 2.26	Synchronism-Check Enable Logic	R.2.49
Figure 2.27	"No Slip" System Synchronism-Check Element Output Response	R.2.51
Figure 2.28	"Slip-No Compensation" Synchronism-Check Element Output Response	R.2.52
Figure 2.29	"Slip-With Compensation" Synchronism-Check Element Output Response	R.2.54
Figure 2.30	Alternative Synchronism-Check Source 2 Example and Settings.	R.2.57

Section 3: SELogic[®] Control Equation Programming

Figure 3.1	Protection and Automation Separation.	R.3.3
Figure 3.2	SELOGIC Control Equation Programming Areas.	
Figure 3.3	Conditioning Timer With Pickup and No Dropout Timing Diagram	R.3.17
Figure 3.4	Conditioning Timer With Pickup Not Satisfied Timing Diagram	R.3.17
Figure 3.5	Conditioning Timer With Dropout and No Pickup Timing Diagram	R.3.18
Figure 3.6	Conditioning Timer With Pickup and Dropout Timing Diagram.	R.3.18
Figure 3.7	Conditioning Timer Timing Diagram for <i>Example 3.7</i>	R.3.19
Figure 3.8	Conditioning Timer Timing Diagram.	R.3.20
Figure 3.9	R_TRIG Timing Diagram.	R.3.27
Figure 3.10	F_TRIG Timing Diagram	R.3.28

Section 4: Communications Interfaces

Figure 4.1	SEL-421 Relay 3U Chassis Front-Panel Layout.	R.4.3
Figure 4.2		
Figure 4.3		R.4.3
Figure 4.4	MAP 1:METER Command Example	R.4.7

Section 5: SEL Communications Protocols

	3.0 Communications DNP Application Network Diagram.	R.6.29
Section 7: UCA	2 Communications GOOSE Application Example Network.	
Section 8: ASC	II Command Reference	
	Sample ID Command Response Sample VER Command Response	
Section 9: Set	L L	

Appendix A: Relay Word Bits

Appendix B: Analog Quantities

Appendix C: GOMSFE Tables

This page intentionally left blank

List of Equations

User's Guide

Section 1: Introduction and Specifications

Section 2: Installation

Section 3: PC Software

Section 4: Basic Relay Operations

Section 5: Front-Panel Operations

Section 6: Testing and Troubleshooting

Equation 6.1		U.6.20
Equation 6.2		U.6.21
Equation 6.3		U.6.28
Equation 6.4		U.6.28
Equation 6.5		U.6.28
Equation 6.6		U.6.28
Equation 6.7		U.6.28
Equation 6.8		
Equation 6.9		U.6.33
Equation 6.10	0	U.6.33
Equation 6.11	1	U.6.33
Equation 6.12	2	U.6.33
Equation 6.13	3	U.6.34
Equation 6.14	4	U.6.34

Appendix A: Firmware Versions

Applications Handbook

Section 1: Protection Application Examples

Equation 1.1	A.1.3
Equation 1.2	A.1.3
Equation 1.3	
Equation 1.4	A.1.9
Equation 1.5	A.1.11
Equation 1.6	A.1.21
Equation 1.7	A.1.21
Equation 1.8	A 1.25
Equation 1.9	A 1.29
Equation 1.10	A.1.29
Equation 1.11	
Equation 1.12	
Equation 1.13	
Equation 1.14	
Equation 1.15	
Equation 1.16	
Equation 1.17	
Equation 1.18	
Equation 1.19	

xxxiv	List of Equations

Equation 1	1.20		A.1		
Equation					
Equation 1					
Equation 1	1.23				
Equation 1	1.24				
Equation 1	1.25		A.1	.6	1
Equation 1	1.26		A.1	.6	1
Equation	1.27		A.1	.6	1
Equation			A.1	.6	53
Equation	1.29				
Equation 1	1.30				
Equation	1.31		A.1	.6	64
Equation	1.32		A.1	.6	57
Equation 1	1.33				
Equation	1.34		A.1	.6	9
Equation	1.35		A.1	.6	9
Equation 1	1.36		A.1	1.7	$^{\prime}1$
Equation	1.37		A.1	1.7	$^{\prime}1$
Equation 1					
Equation 1					
Equation					
Equation	1.41				
Equation 1					
Equation	1.43		A.1	1.7	'3
Equation 1					
Equation 1	1.45		A.1	1.7	'3
Equation					
Equation	1.47				
Equation 1					
Equation			A.1	1.7	'5
Equation	1.50		A.1	1.7	'5
Equation 1	1.51				
Equation					
Equation	1.53				
Equation 1					
Equation					
Equation 1					
Equation 1			A.1		
Equation 1	1.58		A.1	1.9	15
Equation 1	1.59		A.1		
Equation 1			A.1	.9	17
Equation	1.61				
Equation 1			A.1	1.9	18
Equation 1	1.63		A.1	1.9	18
Equation 1		A	1.	10	13
Equation 1		A	1.	10)5
Equation 1	1.66	A	1.	10)6
Equation 1			1.		
Equation			.1.		
Equation		A			
Equation					
Equation 1		A			
Equation		A			
Equation					
Equation		A			
Equation					
Equation		A			
Equation		A	.1.	12	:4

Equation 1.78	 A.1.124
Equation 1.79	 A.1.130
Equation 1.80	 A.1.131
Equation 1.81	 A.1.132
Equation 1.82	 A.1.132
Equation 1.83	 A.1.132
Equation 1.84	 A.1.133
Equation 1.85	 A.1.133
Equation 1.86	1 1 1 2 2
Equation 1.87	 A.1.156
Equation 1.88	 A.1.157
Equation 1.89	 A.1.162
Equation 1.90	 A.1.162
Equation 1.91	 A.1.163
Equation 1.92	 A.1.163

Section 2: Monitoring and Metering

Equation 2.1	 A.2.7
Equation 2.2	A.2.7
Equation 2.3	A.2.7
Equation 2.4	A.2.15
Equation 2.5	A.2.25
Equation 2.6	A.2.25
Equation 2.7	A.2.33

Section 3: Analyzing Data

Equation 3.1	
Equation 3.2	A.3.18
Equation 3.3	A.3.19
Equation 3.4	A 3.19
Equation 3.5	

Section 4: Time-Synchronized Measurements

Section 5: Substation Automatic Restoration

Section 6: SEL-2030 Applications

Section 7: Direct Network Communication

Reference Manual

Section 1: Protection Functions

Equation 1.1	 R.1.30
Equation 1.2	 R.1.30
Equation 1.3	 R.1.30
Equation 1.4	 R.1.30
Equation 1.5	 R.1.31
Equation 1.6	 R.1.31
Equation 1.7	R.1.31
Equation 1.8	R.1.31
Equation 1.9	R.1.31
Equation 1.10	R.1.31
Equation 1.11	R 1 31
Equation 1.12	R 1 31
Equation 1.13	R 1 32
Equation 1.14	R 1 46
Equation 1.11	

Equation 1.15		R.1.71
Equation 1.16		
Equation 1.17		R.1.71
Equation 1.18		R.1.71
Equation 1.19		R.1.71
Equation 1.20		R.1.71
Equation 1.21		
Equation 1.22		
Equation 1.23		R.1.72
Equation 1.24		R.1.72
Equation 1.25		R.1.72
Equation 1.26		R.1.72
Equation 1.27		R.1.72
Equation 1.28		R.1.72
Equation 1.29		
Equation 1.30		
Equation 1.31		
Equation 1.32		
Equation 1.33		
Equation 1.34		
Equation 1.35		
Section 2: Auto	-Reclose and Synchronism Check	
		R 2 / 2
Equation 2.1 Equation 2.2		
Equation 2.2 Equation 2.3		
_		
Section 3: SEL0	GIC [®] Control Equation Programming	
Section 4: Com	munications Interfaces	
Section 5: SEL (Communications Protocols	
Section 6: DNP	3.0 Communications	
Section 7: UCA2	2 Communications	
Section 8: ASCI	I Command Reference	
Section 9: Setti	ings	
Appendix A: Rel	lay Word Bits	
Annual Con De Ann	alan Overtitian	

Appendix B: Analog Quantities

Appendix C: GOMSFE Tables

List of Examples

User's Guide

- Section 1: Introduction and Specifications
- Section 2: Installation
- Section 3: PC Software
- Section 4: Basic Relay Operations

Section 5: Front-Panel Operations

Example 5.1	Creating a Display Point	U.5.7
	Monitoring Test Modes With Display Points	
	Enabling Local Bit Control	

Section 6: Testing and Troubleshooting

Appendix A: Firmware Versions

Applications Handbook

Section 1: Protection Application Examples

Section 2: Monitoring and Metering

Example 2.1	Creating the Circuit Breaker Contact Wear Curve	
Example 2.2	I ² t Criteria Application	
	Circuit Breaker Monitor External Trip Initiation	
Example 2.4	Using a Control Input to Capture External and Internal Trip Commands	A.2.8
Example 2.5	Mechanical Operating Time Settings	A.2.10
Example 2.6	Electrical Operating Time Settings	
Example 2.7	Pole Scatter Settings	A.2.13
Example 2.8	Pole Discrepancy Alarm for	
	Circuit Breaker 1-No Other Circuit Breaker Monitor Functions	
Example 2.9	Inactivity Time Settings	
Example 2.10	Motor Running Time Settings	A.2.17

Section 3: Analyzing Data

Example 3.1	Triggering Event Report/Data Capture Using the ER SELOGIC Control Equation	. A.3.4
Example 3.2	Including PUL Command Triggering in the ER SELOGIC Control Equation	. A.3.5
Example 3.3	Reading the Digital Portion of the Event Report	A.3.21

Section 4: Time-Synchronized Measurements

Section 5: Substation Automatic Restoration

Section 6: SEL-2030 Applications

Section 7: Direct Network Communication

Reference Manual

Section 1: Protection Functions

Section 2: Auto-Reclose and Synchronism Check

Example 2.1	Conditional Three-Pole Tripping for Circuit Breaker BK2R	R.2.25
Example 2.2	Setting Alternative Synchronism-Check Source 2	2.2.56

Section 3: SELOGIC[®] CONTROL EQUATION PROGRAMMING

Example 3.1	Fixed SELOGIC Control Equations	
Example 3.2	Free-Form SELOGIC Control Equations	
Example 3.3	Boolean and Math SELOGIC Control Equations	
Example 3.4	SELOGIC Control Equation Variables	
Example 3.5	SELOGIC Control Equation Math Variables	
Example 3.6	Protection Latch Bits	
Example 3.7	Conditioning Timer Programming and Operation	
Example 3.8	Automation Sequencing Timer Programming	
Example 3.9	Counter Programming	
Example 3.10	R_TRIG Operation	
Example 3.11	F TRIG Operation	
Example 3.12	Using Parentheses in Math Equations	
Example 3.13	Using Arithmetic Operations	
Example 3.14	Using the SQRT Operator	
Example 3.15	Using the LN, EXP, and LOG Operators	R.3.31
Example 3.16	Using the SIN and COS Operators	
Example 3.17	Using the ASIN and ACOS Operators	
	Using the ABS Operator	
Example 3.19	Using the CEIL Operator	
Example 3.20	Using the FLOOR Operator	
	Using the Negation Operator	
Example 3.22	Comments in Free-Form SELOGIC Control Equation Programming	
Example 3.23	Converting SEL-311 Series Relay SELOGIC Control Equation Variables .	
Example 3.24	Converting SEL-311 Series Relay SELOGIC Control Equation Timers	
Example 3.25	Converting SEL-311 Series Relay Latch Bits	

Section 4: Communications Interfaces

Section 5: SEL Communications Protocols

Section 6: DNP 3.0 Communications

Section 7: UCA2 Communications

Section 8: ASCII Command Reference

Section 9: Settings

Appendix A: Relay Word Bits

Appendix B: Analog Quantities

Appendix C: GOMSFE Tables

Manual Change Information

The date code at the bottom of each page of this manual reflects the creation or revision date.

Changes in this manual are summarized below (most recent revisions listed at top).

Release Date	Summary of Changes in this Release (Sheet 1 of 2)	
This Manual Cha	inge Information section is provided as a record of all changes made to this manual since the initial release.	
20020501	Reference Manual Section 6: DNP 3.0 Communications Updated Table 6.17 on page R6.29. Reference Manual Appendix C: GOMSFE Tables All UCA2 control points were made readable. Default data was set for the UCA2 FAULT model.	
20020417	User's Guide Appendix A: Firmware Versions Firmware updated. Spurious Quart interrupts caused by varying character spacing will cause the relay to dis- able. This condition occurs when a communications processor is automatically retrieving data from the relay simultaneously with a serial port terminal session.	
20020403	Initial Release with Synchrophasor Measurement capability to SEL-421. Added VAZ, VBZ, VCZ settings options to SYNCP. Added VAY, VBY, VCY settings options to SYNCS1, SYNCS2 and ASYNCS2. Added ACOS, ASIN, CEIL, FLOOR and LOG math functions to SELOGIC control equations. Added new analog quantities for use in SELOGIC control equations: Terminal W and X current magnitudes Terminal Y and Z voltage magnitudes Instantaneous sequence quantities Contact inputs Modified CHI output for SEL-2030 compatibility.	
20020108	 SEL-421-1 Relay introduction. Configurable front-panel labels. I and V Source Selection settings clarifications. Preface Added Notes explanation. User's Guide Section 1: Introduction and Specifications Added description of SEL-421-1 Relay. Added description of SEL-421-1 Relay. Added Notes to flag the differences in the SEL-421-1 Relay. Added Humidity to <i>Specifications</i>. Added Humidity to <i>Specifications</i>. Added SEL-421-1 Relay Maximum Operating Time to <i>Specifications</i>. Revised Power and Energy in <i>Specifications</i>. User's Guide Section 2: Installation Added subsection 3: PC Software Added description of SEL-5030 ACSELERATOR® Software Analysis function keys F2, F3, and F4. Revised Relay Editor settings tree view operation. User's Guide Section 4: Basic Relay Operations Included front-panel label kit in shipped items list. Added Notes to flag the differences in the SEL-421-1 Relay. Fixed <i>Figure 4.45 on page U4.50</i> and setting SER example procedure. Fixed <i>Figure 4.45 on page U4.61</i> and setting control input/52A example procedure. User's Guide Section 5: Front-Panel Operations Added descriptions of configurable front-panel labels. 	

Release Date	Summary of Changes in this Release (Sheet 2 of 2)		
	Applications Handbook Section 1: Protection Application Examples Added Notes to flag the differences in the SEL-421-1 Relay.		
	Corrected control inputs in Auto-Reclose Examples.		
	Added explanation for missing setting 3PMRCD (Manual Close Reclaim Time Delay) in <i>Recloser Closing on</i> page A1.137.		
	Applications Handbook Section 2: Monitoring and MeteringCorrected communications equipment battery voltage to 48 Vdc in Figure 2.12 on page A2.22.Revised text and Table 2.16 on page A2.32 for power and energy specifications.		
	Applications Handbook Section 3: Analyzing Data Corrected compressed ASCII command example in Event File Download procedure.		
	 Reference Manual Section 1: Protection Functions Added Notes to flag the differences in the SEL-421-1 Relay. Included more explanation for settings ALTI and ALTV in <i>Current and Voltage Source Selection on page R1.2</i>. 		
	Corrected setting ORDER text in ORDER on page R1.24. Supplemented Series-Compensation Line Logic on page R1.38 material.		
	Reference Manual Section 3: SELOGIC[®] Control Equation Programming Added Notes to flag the differences in the SEL-421-1 Relay.		
	Reference Manual Section 6: DNP 3.0 Communications Updated setting TIMERQ to reflect correct prompt and default (no change in the relay).		
	Reference Manual Section 9: Settings Added Notes to flag the differences in the SEL-421-1 Relay.		
	Reference Manual Appendix A: Relay Word Bits Added Notes to flag the differences in the SEL-421-1 Relay.		
	Index Added index entries for configurable front-panel labels, SEL-421-1 Relay, and series-compensated line.		
20010703	Initial Release.		

Preface

This manual provides information and instructions for installing and operating the SEL-421 Relay. The three volumes that comprise this manual are for use by power engineers and others experienced in protective relaying applications. Included are detailed technical descriptions of the relay and application examples. While this manual gives reasonable examples and illustrations of relay uses, you must exercise sound judgment at all times when applying the SEL-421 Relay in a power system.

Use this manual for both the SEL-421 Relay and the SEL-421-1 Relay. Margin notes next to the text specify differences between the two relay models when these differences affect relay functions or operations.

Manual Overview

	The SEL-421 Relay Manual consists of three volumes:
	► User's Guide
	 Applications Handbook
	 Reference Manual
	In addition, the SEL-421 Relay Manual contains a comprehensive Index that encompasses the entire manual. The Index appears at the end of each printed volume. In the electronic version of the manual, the Index appears once; hyperlinks take you to material referenced in the Index. Also included is a Glossary that lists and defines technical terms used throughout the manual.
	The SEL-421 Relay Manual is a comprehensive work covering all aspects of relay application and use. Read the sections that pertain to your application to gain valuable information about using the SEL-421 Relay. For example, to learn about relay protection functions, read the protection sections of this manual and skim the automation sections. You can concentrate on the operation sections or on the automation sections of this manual as your job needs and responsibilities dictate. An overview of each manual section and section topics follows.
User's Guide	Preface. describes manual organization and conventions used to present information (appears once in the electronic form of the manual; repeated in each printed volume).
	Section 1: Introduction and Specifications. introduces SEL-421 Relay features; summarizes relay functions and applications; lists relay specifications, type tests, and ratings.
	Section 2: Installation. discusses the ordering configurations and interface features (control inputs, control outputs, and analog inputs, for example); provides information about how to design a new physical installation and secure the relay in a panel or rack; details how to set relay board jumpers and make proper rear-panel connections (including wiring to CTs, PTs, and a GPS receiver); explains basic connections for the relay communications ports and how to install optional communications cards (such as the SEL-2701 Ethernet Processor).
	Section 3: PC Software. explains how to use the SEL-5030 ACSELERATOR [®] Software Program.
	Section 4: Basic Relay Operations. describes how to perform fundamental operations such as applying power and communicating with the relay, setting and viewing passwords, checking relay status, viewing metering data, reading event reports and SER (Sequential Events Recorder) records, operating relay control outputs and control inputs, and using relay features to make relay commissioning easier.
	Section 5: Front-Panel Operations. describes the LCD display messages and menu screens; shows you how to use front-panel pushbuttons and read targets; provides information about local substation control and how to make relay settings via the front panel.
	Section 6: Testing and Troubleshooting. describes techniques for testing, troubleshooting, and maintaining the SEL-421 Relay; includes the list of status notification messages and a troubleshooting chart.

Appendix A: Firmware Versions. lists the current firmware versions and details differences between the current and previous versions.

Applications Handbook

Section 1: Protection Application Examples. provides the following protection schemes with explanations and settings:

- Overhead single 230 kV transmission line
- Overhead parallel 500 kV transmission lines with zerosequence mutual coupling
- ► Overhead tapped 345 kV transmission line
- Parallel submarine 230 kV underground cables

This section also provides separate application examples for out-ofstep blocking and tripping, circuit breaker failure protection, and automatic reclose and synchronism checking.

Section 2: Monitoring and Metering. describes how to use the circuit breaker monitors and the substation dc battery monitors; provides information on viewing fundamental and rms metering quantities for voltages and currents, as well as power and energy metering data.

Section 3: Analyzing Data. explains how to obtain and interpret highresolution raw data oscillograms, filtered event reports, event summaries, history reports, and SER reports; discusses how to enter SER trigger and alias settings.

Section 4: Time-Synchronized Measurements. explains synchronized phasor measurements and estimation of power system states using the SEL-421 Relay high-accuracy time-stamping capability; presents real-time load flow/power flow application ideas.

Section 5: Substation Automatic Restoration. describes an example of automatic substation restoration; gives a real-world example of the programming ease and flexibility of free-form expanded SELOGIC[®] control equations.

Section 6: SEL-2030 Applications. provides examples of how to use the SEL-421 Relay with the SEL-2020 and SEL-2030 Communications Processors for total substation automation solutions.

Section 7: Direct Network Communication. explains how to use DNP 3.0 and the Ethernet protocols such as Telnet, FTP, and UCA2.

Section 1: Protection Functions. describes the function of various relay protection elements; describes how the relay processes these elements; gives detailed specifics on protection scheme logic for POTT, DCB, DCUB, and DTT; provides trip logic diagrams, and current and voltage source selection details.

Section 2: Auto-Reclose and Synchronism Check. explains how to operate the SEL-421 Relay two-circuit breaker multi-shot recloser; describes how to set the SEL-421 Relay for single-pole reclosing, three-pole reclosing, or both; shows selection of the lead and follow circuit breakers; explains how to set and apply synchronism-check elements for automatic and manual closing.

Section 3: SELOGIC[®] Control Equation Programming. describes SELOGIC control equations and how to apply these equations; discusses expanded SELOGIC control equation features such as PLC-style commands, math functions, counters, and conditioning timers; provides a tutorial for converting older format SELOGIC control equations to new free-form equations.

Reference Manual

	Section 4: Communications Interfaces - autoing the relational connection
	Section 4: Communications Interfaces. explains the physical connection of the SEL-421 Relay to various communications network topologies.
	Section 5: SEL Communications Protocols. describes the various SEL software protocols and how to apply these protocols to substation integration and automation; includes details about SEL ASCII, SEL Compressed ASCII, SEL Fast Meter, SEL Fast Operate, SEL Fast SER, and enhanced MIRRORED BITS [™] communications.
	Section 6: DNP 3.0 Communications. describes the DNP 3.0 communications protocol and how to apply this protocol to substation integration and automation; provides a Job Done [®] example for implementing DNP 3.0 in a substation.
	Section 7: UCA2 Communications. describes the UCA2 communications protocol and how to apply this protocol to substation integration and automation; presents a Job Done example for using UCA2 to operate and control a substation.
	Section 8: ASCII Command Reference. provides an alphabetical listing of all ASCII commands with examples for each ASCII command option.
	Section 9: Settings . provides a list of all SEL-421 Relay settings and defaults. The organization of the settings is the same as for the settings organization in the relay and in the ACSELERATOR software.
	Appendix A: Relay Word Bits. contains a summary of Relay Word bits.
	Appendix B: Analog Quantities. contains a summary of analog quantities.
	Appendix C: GOMSFE Tables. contains a UCA2 GOMSFE model.
CD-ROM	The CD-ROM contains the SEL-421 Relay Manual in an electronic form that you can search easily.
Page Numbering	This manual shows page identifiers at the top of each page; see the figure below.



Page Number Format.

The page number appears at the outside edge of each page; a vertical bar separates the page number from the page title block. The three volumes of the SEL-421 Relay Manual are represented by the first letter in the page number character string: U is for User's Guide, A is for Applications Handbook, and R is for the Reference Manual. The next character in the page number is the section number; the last digit is the actual page number in the particular section.

The section title is at the top of the page title block, with the main subsection reference in bold type underneath the section title. This number and title arrangement makes navigating the printed manual and the CD-ROM manual easy and efficient.

Conventions

The SEL-421 Relay Manual uses certain conventions that identify particular terms and help you find information. To benefit fully from reading this manual, take a moment to familiarize yourself with these conventions.

Typographic Conventions

The SEL-421 Relay Manual shows certain information with specific font and formatting attributes. The following table lists the typographic conventions used in this documentation.

Example	Description
STATUS	ASCII and Compressed ASCII commands.
TAR 23 <enter></enter>	Commands/input that you type.
{CLOSE}	Relay front-panel pushbuttons.
<enter></enter>	Single keystroke command.
<ctrl+d></ctrl+d>	Multiple keystroke command to bring up a control win- dow or activate a control function.
RELAY ELEMENTS	Front-panel LCD menu items.
Analysis > Read History	Choosing the Read History submenu in the Analysis menu of the ACSELERATOR software. Depiction of the navigation to other submenus is similar.
Are you sure (Y,N)?	Communications terminal screen response style.
www.selinc.com	Web site reference. The prefix http:// is understood.
SELOGIC control equations	SEL Trademarks and registered trademarks contain the appropriate symbol on first reference in a section. In the SEL-421 Relay Manual, certain SEL trademarks appear in small caps. These include SELOGIC control equations, MIRRORED BITS communications, and SEL-5030 ACSELERATOR Software Program.
Best Choice Ground Directional Element [™]	Other SEL trademarks and registered trademarks contain the appropriate symbol on first reference in a section, but these trademarks do not appear in small caps.
Modbus®	Registered trademarks of other companies include the registered trademark symbol with the first occurrence of the term in a section.
U.3.1 A.3.1 R.3.1	Page numbers include a reference to the volume, section and page number. U stands for User's Guide, A stands for Applications Handbook, and R stands for Reference Manual.

Cross-References

Cross-references are formatted as described below in both the hard copy and electronic documentation for the SEL-421 Relay. In the electronic documentation, clicking with the mouse on cross-references takes you to the referenced location.

- Reference to information on the same page includes only the reference item
 - \succ Table 3.1
 - > Oscillography

- Reference to information on another page in the same section includes the reference item and the page number
 - \succ Table 3.1 on page 3.2
 - > Oscillography on page 3.8
- Reference to information in another section in the same volume includes the reference item, page number (if appropriate), and the volume name
 - > Table 3.1 on page A.3.2 in the Applications Handbook
 - Oscillography on page A.1.5 in the Applications Handbook
- Reference to information in another volume includes the reference item, page number (if appropriate), and volume name
 - > Access Levels on page U.4.8 in the User's Guide
 - > Section 4: Basic Relay Operations in the User's Guide

Alerts

DANGER

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death. DANGER statements indicate an imminently hazardous situation that, if not avoided, will result in death or serious injury. The text to the left is an example of a DANGER statement.

WARNING

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage. WARNING statements indicate a potentially hazardous situation that, if not avoided, can result in death or serious injury. WARNING and DANGER tags do not apply to property damage hazards unless these hazards also involve personal injury risk appropriate to these levels. The text to the left is an example of a WARNING statement.

CAUTION

CAUTION statements are in two different forms:

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

CAUTION: Equipment damage can result from connecting ac circuits to Hybrid (high-current-interrupting) control outputs. Do not connect a circuit to Hybrid control outputs. Use only dc circuit with Hybrid control outputs.

- A CAUTION statement indicates a potentially hazardous situation that, if not avoided, can possibly result in minor or moderate injury. The text to the left is an example of this kind of CAUTION statement.
- A CAUTION statement alerts you about unsafe practices that can possibly cause property damage. The text to the left is an example of this kind of CAUTION statement.

Notes	Margin notes serve two purposes in the SEL-421 Relay Manual. Notes present valuable or important points about relay features or functions. Use these notes as tips to easier and more efficient operation of the relay. Also in this manual, Notes specify differences between the SEL-421 Relay and the SEL-421-1 Relay models when these differences affect relay functions or operations.	
Step-by-Step Procedures	The SEL-421 Relay Manual contains many step-by-step procedures. These procedures lead you easily and efficiently through complex tasks. Each procedure lists required equipment, as well as the basic knowledge you need to perform the steps in the procedure. Throughout the procedure, the documentation references other SEL-421 Relay Manual sections where you can find more information.	
	Read the entire procedure before performing the listed steps. Read each step again before you perform it. The format of a single step is the following:	
	 Synopsis of the step 	
	► Tasks to perform the step	
	The following text shows sample steps. Steps include explanations, text references, table references, and figure references to further illustrate the steps.	
	Synopsis	
	Step 1. Establish communication. Press <ctrl+t></ctrl+t> to use the serial Tasks communications terminal in the ACSELERATOR software. Press <enter></enter> to see if the communications link is active between the software and the relay. You should see the = action prompt in the terminal window.	
	Step 2. Confirm that you have loaded the correct passwords in the ACSELERATOR software. Open the Communication menu and click Port Parameters. Confirm that you have entered the correct passwords in the Level One Password dialog box and the Level Two Password dialog box.	
	Step 3. Read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all configuration and settings data to the ACSELERATOR software.	
	Step 4. Select settings. Click the + mark next to the Group you want to program on the Settings tree view. This example uses Group 1, as shown in <i>Figure 1.2</i> .	
	Figure Reference	
	Sample Step-By-Step Instructions.	
Numbers	This manual displays numbers as decimal values. Hexadecimal numbers include the letter "h" appended to the number. Alternatively, the prefix 0X can also indicate a hexadecimal number. For instance, 11 is the decimal number aleven, but 11b and 0X11 are hexadecimal representations of the decimal	

value seventeen.

eleven, but 11h and 0X11 are hexadecimal representations of the decimal

Logic Diagrams

Logic diagrams in this manual follow the conventions and definitions shown below.

NAME	SYMBOL	FUNCTION
COMPARATOR	A c	Input A is compared to input B. Output C asserts if A is greater than B.
INPUT FLAG	A ►	Input A comes from other logic.
OR	A C	Either input A or input B asserted cause output C to assert.
EXCLUSIVE OR	A C	If either A or B is asserted, output C is asserted. If A and B are of the same state, C is deasserted.
NOR	A C	If neither A nor B asserts, output C asserts.
AND	A C	Input A and input B must assert to assert output C.
AND W/ INVERTED INPUT	A C C	If input A is asserted and input B is deasserted, output C asserts. Inverter "O" inverts any input or output on any gate.
NAND	A C	If A and/or B are deasserted, output C is asserted.
TIME DELAYED PICK UP AND/OR TIME DELAYED DROP OUT	A X B	X is a time-delay-pickup value; Y is a time-delay-dropout value. B asserts time X after input A asserts; B will not assert if A does not remain asserted for time X. If X is zero, B will assert when A asserts. If Y is zero, B will deassert when A deasserts.
EDGE TRIGGER TIMER	A Y B	Rising edge of A starts timers. Output B will assert time X after the rising edge of A. B will remain asserted for time Y. If Y is zero, B will assert for a single proccessing interval. Input A is ignored while the timers are running.
SET RESET FLIP FLOP	S 0	Input S asserts output Q until input R asserts. Output Q deasserts or resets when R asserts.
FALLING EDGE	АДВ	B asserts at the falling edge of input A.

Logic Diagram Symbols.

Section 1

Introduction and Specifications

The SEL-421 Relay is a high-speed transmission line protection relay featuring single-pole and three-pole tripping and reclosing with synchronism check, circuit breaker monitoring, circuit breaker failure protection, and series-compensated line protection logic. The SEL-421-1 Relay contains all of the protection functions of the SEL-421 Relay except high-speed distance elements and series-compensated line protection logic. Both relays feature extensive metering and data recording including high-resolution data capture and reporting.

The relays feature expanded SELOGIC[®] control equation programming for easy and flexible implementation of custom protection and control schemes. The SEL-421 Relay has separate protection and automation SELOGIC control equation programming areas with extensive protection programming capability and 1000 lines of automation programming capability. You can organize automation SELOGIC control equation programming into 10 blocks of 100 program lines each. The SEL-421-1 Relay has the same protection programming capability but has only 1 block of 100 lines of automation programming capability.

Both the SEL-421 Relay and the SEL-421-1 Relay provide extensive communications interfaces from standard SEL ASCII and enhanced MIRRORED BITS[™] communications protocols to Ethernet connectivity with the optional SEL-2701 Ethernet Processor. Using the SEL-421 Relay, you can employ the latest industry communications tools including UCA2, FTP, and DNP 3.0 protocols.

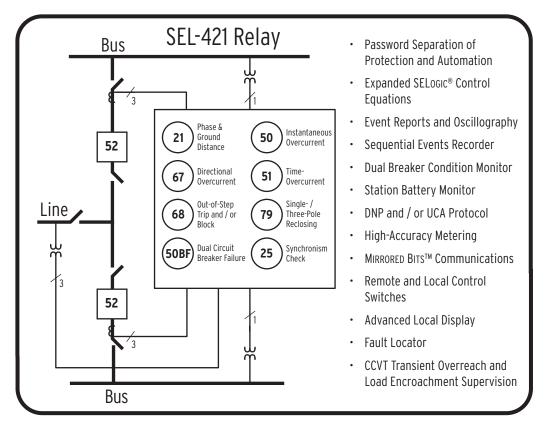
Included with the SEL-421 Relay and the SEL-421-1 Relay is the SEL-5030 ACSELERATOR[®] Software Program. The ACSELERATOR software assists you in setting, controlling, and acquiring data from the relays both locally and remotely.

A simple and robust hardware design features efficient digital signal processing. Combined with extensive self-testing, these features provide relay reliability and enhance relay availability.

This section introduces the SEL-421 Relay and the SEL-421-1 Relay and provides information on the following topics:

- ► Features
- ► Models and options
- ► Applications
- Specifications

Features



The SEL-421 Relay contains many protection, automation, and control features. *Figure 1.1* presents a simplified functional overview of the relay.

Figure 1.1 SEL-421 Relay Functional Overview.

NOTE: The SEL-421-1 Relay does not provide series-compensated line protection logic.

NOTE: The SEL-4211 Relay does not provide high-speed directional elements and high-speed distance elements.

- SEL-421 Relay features include the following:
 - Superior Protection. Combine five zones of phase distance and ground distance elements with directional overcurrent elements. Patented Coupling Capacitor Voltage Transformer (CCVT) transient overreach logic enhances Zone 1 distance element security. The Best Choice Ground Directional Element[™] optimizes directional element performance and eliminates many settings. Additional logic prevents Zone 1 overreach on series-compensated lines.
 - High-Speed Tripping. The SEL-421 Relay uses the HSDPS (High-Speed Directional and Phase Selection) element and high-speed distance elements for subcycle detection of power system faults.
 - Reclosing Control. Incorporate programmable single-pole and three-pole tripping and reclosing of one and two circuit breakers into an integrated substation control system. Synchronism and voltage checks from multiple sources provide complete bay control.
 - Breaker Failure. The SEL-421 Relay incorporates CT subsidence detection to produce element dropout in 5/8 cycle. Included is the necessary logic for single-pole and three-pole breaker failure retrip and initiation of transfer tripping.

- Out-of-Step Blocking and Tripping. Select out-of-step blocking of distance elements or out-of-step tripping during power swings. The SEL-421 Relay includes multizone elements and logic for detection of an outof-step condition.
- Switch-Onto-Fault. Relay switch-onto-fault (SOTF) logic permits specific protection elements to quickly trip after the circuit breaker closes, protecting maintenance personnel and substation equipment.
- Fault Locator. Efficiently dispatch line crews to quickly repair line problems.
- Primary Potential Redundancy. Multiple voltage inputs to the SEL-421 Relay provide primary input redundancy. At loss-of-potential (LOP) detection, configure the relay to use inputs from an electrically equivalent source. Protection remains in service without compromising security.
- Dual CT Input. Connect separate CTs to the relay inputs and combine these currents inside the relay for protection functions, but keep these CT currents separately available for protection, monitoring, and station integration applications.

Expanded SELOGIC Control Equations. Modify and set custom relay applications with PLC-style (programmable logic controller, IEC 61131-3 ST compatible) SELOGIC control equation programming that includes math and comparison functions. Use counters and multifunction timers for greater application flexibility. Perform advanced PLC functions within the relay. The SEL-421 Relay has separate protection and automation SELOGIC control equation programming areas. These programming areas provide you with ample protection programming capability and 10 blocks of 100-line automation programming capability (1000 lines).

- Monitoring. Schedule breaker maintenance when accumulated breaker duty (independently monitored for each pole of two circuit breakers) indicates excessive contact wear. The SEL-421 Relay records electrical and mechanical operation times for the last operation and for the average of operations since the monitor function reset. In addition, the relay alarms for out-of-tolerance conditions that you specify. Use the two independent battery monitors to detect substation battery voltage problems even if battery voltage is low only during a trip or close operation.
- Metering. View metering information for Line, Circuit Breaker 1, and Circuit Breaker 2. SEL-421 Relay metering includes fundamental and rms metering, as well as energy import/export, demand, and peak demand metering data.
- Oscillography and Event Reporting. Record raw voltages and currents at a sampling rate as great as 8 kHz (8000 samples/second). Investigate relay internal logic points and power system performance with event report phasor and harmonic analysis.
- Sequential Events Recorder (SER). Record 1000 system entries, including settings changes, power-ups, and Relay Word bit elements that you select. Set element names to easily understood aliases.
- High-Accuracy Time Stamping. Time-tag event reports with real-time accuracy of $10 \ \mu$ s. You can coordinate time-stamped data to determine system states at an accuracy of 0.25 electrical degree.

NOTE: The SEL-421-1 Relay has only one 100-line automation programming block.

- Digital Relay-to-Relay Communication. Use MIRRORED BITS communications to monitor internal element conditions between relays within a substation and between substations using communication channels (SEL fiber-optic transceivers, for example).
- Ethernet Communications Capability. Add the optional plug-in SEL-2701 Ethernet Processor to implement control and data gathering capabilities via substation local-area-networks (LANs) and company wide-area-networks (WANs). Employ UCA and FTP protocols for system data acquisition and control.
- Increased Security. The SEL-421 Relay divides control and settings into seven relay access levels; the relay has separate breaker, protection, automation, and output access levels, among others. Set unique passwords for each access level.
- Computer Software. Use the rules-based settings editor, the ACSELERATOR software, to develop settings off-line. View a graphical human machine interface (HMI) for metering and control.
- Settings Reduction. Internal relay programming shows only the settings for the functions and elements you have enabled.

Models and Options

The SEL-421 Relay and the SEL-421-1 Relay have many common features. Consider the following options when ordering and configuring these relays.

- ➤ Chassis size
 - ➤ 3U, 4U, and 5U
 - (U is one rack unit–1.75 inches or 44.45 mm)
- ► Additional I/O boards (for 4U and 5U chassis)
 - INT1: 8 independent inputs; 13 Standard form A outputs; 2 Standard form C outputs
 - INT5: 8 independent inputs; 8 Fast High-Current-Interrupting form A outputs
 - INT6: 8 independent inputs; 13 High-Current Interrupting form A outputs, 2 Standard form C outputs
- ► Chassis orientation and type
 - Horizontal rack mount
 - > Horizontal panel mount
 - > Vertical rack mount
 - > Vertical panel mount
- ► Power supply
 - ≻ 24/48 Vdc
 - ➤ 48/125 Vdc or 120 Vac
 - ➤ 125/250 Vdc or 120/230 Vac
- ► Secondary inputs
 - 1 A nominal or 5 A nominal CT inputs.
 300 V phase-to-neutral wye configuration PT inputs
- Communications card options
 - SEL-2701 Ethernet Processor with combinations of 10 MHz and 100 MHz copper and fiber jacks on each of two ports
- ► Communications protocols
 - Complete group of SEL protocols (SEL ASCII, SEL Compressed ASCII, SEL Settings File Transfer, SEL Fast Meter, SEL Fast Operate, SEL Fast SER, Enhanced MIRRORED BITS Communications)
 - > Complete group of SEL protocols plus DNP 3.0
- ► Connector type
 - > Fixed PT and CT terminal block inputs
 - Plug-in/plug-out PT and shorting CT Connectorized[®] versions

Contact the SEL factory or your local Technical Service Center for particular part number and ordering information (see *Factory Assistance on page U.6.43 in the User's Guide*). You can also view the latest part number and ordering information on the SEL website at www.selinc.com.

Applications

Use the SEL-421 Relay in a variety of transmission line protection applications. For information on connecting the relay, see *Section 2: Installation in the User's Guide*. See *Applications Handbook* for thorough discussions of protection and automation applications using the SEL-421 Relay.

The figures in this subsection illustrate common relay application configurations. *Figure 1.3, Figure 1.4 on page 1.7, Figure 1.5 on page 1.7, Figure 1.6 on page 1.8*, and *Figure 1.7 on page 1.8* demonstrate relay versatility with Global setting ESS (Current and Voltage Source Selection). These figures show the power and simplicity of the four preprogrammed ESS options. For more information on setting ESS, see *Current and Voltage Source Selection on page R.1.2 in the Reference Manual*.

The SEL-421 Relay has two sets of three phase analog current inputs, IW and IX, and two sets of three-phase analog voltage inputs, VY and VZ. The drawings that follow use a two-letter acronym to represent all three phases of a relay analog input. For example, IW represents IAW, IBW, and ICW for A-, B-, and C-phase current inputs on terminal W, respectively. The drawings list a separate phase designator if you need only one or two phases of the analog input set (VAZ for the A-phase voltage of the VZ input set, for example).

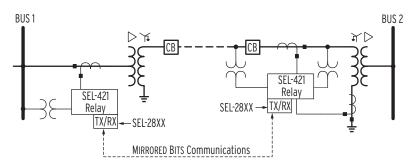


Figure 1.2 Protecting a Line Segment With MIRRORED BITS Communications on a Fiber Channel.

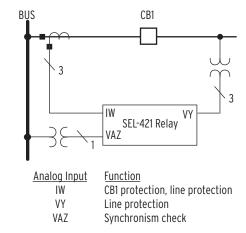
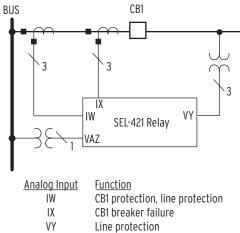
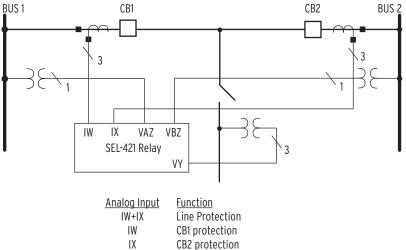


Figure 1.3 Single Circuit Breaker Configuration (ESS := 1).



VAZ Synchronism check

Figure 1.4 Single Circuit Breaker Configuration With Line and Breaker CTs (ESS := 2).



- VY Line protection
- VAZ Synchronism check Circuit Breaker 1
- VBZ Synchronism check Circuit Breaker 2

Figure 1.5 Double Circuit Breaker Configuration (ESS := 3).

U.1.8 | Introduction and Specifications | Applications

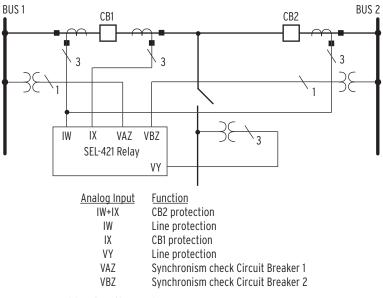


Figure 1.6 Double Circuit Breaker Configuration With Bus Protection (ESS := 4).

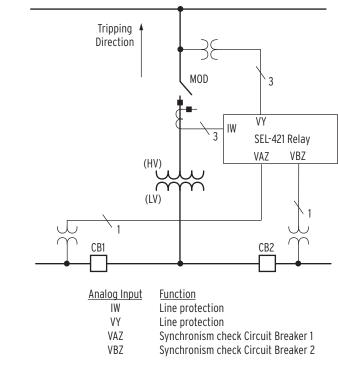


Figure 1.7 Tapped Line (ESS := Y).

Application Highlights

	Application	Key Features
NOTE: The SEL-421-1 Relay does not provide high-speed directional elements and high-speed distance elements.	Single-pole and three-pole tripping	High-speed distance elements Best Choice Ground Directional element Secure protection during open-pole interval Pole-discordance logic trips three-pole for excessive single-pole-open conditions
	Multiple-breaker tripping	SPT one; 3PT other SPT both; 3PT both Breaker failure protection
	Reclosing and synchronism check	2 shots SPT; 4 shots 3PT Leader/follower breaker arrangements Two-circuit-breaker universal synchronism check
	Coupling-Capacitor Voltage Transformer (CCVT) transient detection logic	Detect CCVT transients to provide correct operation of the direct tripping (Zone 1) distance elements
	Long lines	Load-encroachment elements prevent unwanted trips on load Voltage elements detect local bus overvoltages Sensitive negative-sequence and residual overcurrent elements provide sensitive backup protection
	Tapped and three-terminal lines	Five zones Three zero-sequence compensation factors for more accurate ground-distance reach on either side of tap Independent reach settings for phase, ground mho, and ground quadrilateral elements Multiple settings groups cover any switching configurations
	Bus-tie or transfer circuit breakers	Multiple setting groups Match relay settings group to each line substitution Eliminate current reversing switches Local or remote operator switches the setting groups
	Subtransmission lines	Time-step distance protection Ground directional overcurrent protection Torque-controlled time-overcurrent elements
NOTE: The SEL-421-1 Relay does not provide series-compensated line	Lines with capacitors	Series-compensated line logic
protection logic.	Lines with transformers	Negative-sequence overcurrent protection
	Short transmission lines	Directional overcurrent elements and communications- assisted tripping schemes
	Permissive Overreach- ing Transfer Tripping (POTT) schemes	Current reversal guard logic Open breaker echo keying logic Weak-infeed and zero-infeed logic Time-step distance backup protection
	Directional Comparison Unblocking Tripping (DCUB) schemes	Includes all POTT logic All loss-of-channel logic is inside the relay Time-step distance backup protection
	Permissive Under- reaching Transfer Tripping (PUTT) schemes	Supported by POTT logic Time-step distance backup protection

Apply the SEL-421 Relay in power system protection and control situations. *Table 1.1* lists applications and key features of the relay.

 Table 1.1
 Application Highlights (Sheet 1 of 2)

NOTE: Synchrophasor capability is not available in the SEL-421-1 Relay.

Application	Key Features
Directional Comparison Blocking Trip (DCB) schemes	Current reversal guard logic Carrier coordinating timers Carrier send and receive extend logic Zone 3 latch eliminates the need for offset three-phase distance elements Time-step distance backup protection
Direct Transfer Trip- ping (DTT) schemes	SELOGIC control equations program the elements that key direct tripping
SCADA applications	Analog and digital data acquisition for station wide functions
Communications capability	SEL ASCII MIRRORED BITS communications SEL Fast Meter, SEL Fast Operate, SEL Fast SER SEL Compressed ASCII Optional protocols: Ethernet, UCA2, FTP, Telnet Optional DNP 3.0
Customized protection and automation schemes	Separate protection and automation SELOGIC control equation programming areas Use timers and counters in expanded SELOGIC control equations for complete flexibility
Synchronized phasor measurement	Phase and positive-sequence voltage measurements synchro- nized within 0.25 degrees, sampled at 20 times per second

 Table 1.1
 Application Highlights (Sheet 2 of 2)

Specifications

General Specifications

General Specifications	
AC Current Inputs (Seconda 5 A nominal	ary Circuits) 15 A continuous,
5 / Homman	linear to 100 A symmetrical
	500 A for 1 second, 1250 A for 1 cycle
	Burden: 0.27 VA @ 5 A
	2.51 VA @ 15 A
1 A nominal	3 A continuous, linear to 20 A symmetrical
	100 A for 1 second,
	250 A for 1 cycle Burden: 0.13 VA @ 1 A;
	1.31 VA @ 3 A
AC Voltage Inputs	
300 V _{L-N} continuous (conn 600 Vac for 10 seconds	ect any voltage up to 300 Vac)
Burden:	0.03 VA @ 67 V
	0.06 VA @ 120 V
	0.8 VA @ 300 V
Power Supply 125/250 Vdc or 120/230 Va	
Range:	85–300 Vdc <35 W or 85–264 Vac
Burden:	(30 Hz–120 Hz) <120 VA
48/125 Vdc or 120 Vac	<120 VA
Range:	38–140 Vdc <35W or 85–140 Vac (30 Hz–120 Hz)
Burden:	<120 VA
24/48 Vdc Range:	18–60 Vdc
Burden:	<35 W
Control Outputs	
Standard:	20.4
Make: Carry:	30 A 6 A continuous carry at 70°C
-	4 A continuous carry at 85°C
1s Rating: MOV Protection	50 A
(maximum voltage): Pickup/Dropout Time:	250 Vac/330 Vdc 6 ms, resistive load
Update Rate:	1/8 cycle
Break Capacity (10000 oper 48 Vdc 0.50 A	rations): L/R = 40 ms
125 Vdc 0.30 A	L/R = 40 ms
250 Vdc 0.20 A Cyclic Capacity (2.5 cycle/s	L/R = 40 ms
48 Vdc 0.50 A	L/R = 40 ms
125 Vdc 0.30 A 250 Vdc 0.20 A	
Hybrid (high current interru	
Make: Carry:	30 A 6 A continuous carry at 70°C
Carry.	4 A continuous carry at 85°C
1s Rating: MOV Protection	50 A
(maximum voltage):	330 Vdc
Pickup/Dropout Time: Update Rate:	6 ms, resistive load 1/8 cycle
Break Capacity (10000 oper	rations):
48 Vdc 10.0 A 125 Vdc 10.0 A	L/R = 40 ms L/R = 40 ms
250 Vdc 10.0 A	L/R = 20 ms
Cyclic Capacity (4 cycles in thermal dissipation)	1 second, followed by 2 minutes idle for
48 Vdc 10.0 A	L/R = 40 ms
125 Vdc 10.0 A 250 Vdc 10.0 A	L/R = 40 ms L/R = 20 ms
Note: Do not use hybrid con	ntrol outputs to switch ac control signals.
These outputs are polarity Fast Hybrid (high-speed high	dependent.
Make:	30 A
Carry:	6 A continuous carry at 70°C 4 A continuous carry at 85°C

1 s Rating: 50 A MOV Protection 250 Vac/330 Vdc (maximum voltage): 10 µs, resistive load Pickup Time: Dropout Time: 8 ms, resistive load Update Rate: 1/8 cycle Break Capacity (10000 operations): L/R = 40 ms10.0 A 48 Vdc 125 Vdc 10.0 A L/R = 40 ms250 Vdc 10.0 A L/R = 20 msCyclic Capacity (4 cycles in 1 second, followed by 2 minutes idle for thermal dissipation) 10.0 A 48 Vdc L/R = 40 ms125 Vdc L/R = 40 ms10.0 A 250 Vdc 10.0 A L/R = 20 msNote: Per IEC 60255-23 (1994), using the simplified method of assessment. Note: Make rating per IEEE C37.90-1989. **Control Inputs** Range: 15-265 Vdc Accuracy $\pm 5\%$ plus ± 3 Vdc Maximum Voltage: 300 Vdc Sampling Rate: 1/16 cycle Typical Burden: 0.24 W @ 125 Vdc Frequency and Rotation System Frequency: 50/60 Hz Phase Rotation: ABC or ACB Frequency tracking range: 40-65 Hz **Communications Ports** EIA-232: 1 Front & 3 Rear 300-57600 bps Serial Data Speed: Communications Card Slot for optional SEL-2701 Ethernet Processor **Time Inputs** IRIG Input Demodulated IRIG-B time code Input: Nominal Voltage: 5 Vdc +10% Maximum Voltage: 8 Vdc Input Impedance: 333 Ohms Isolation: 500 Vdc 1k PPS Input Input: Demodulated IRIG-B and 1k PPS Nominal Voltage: 5 Vdc +10% Maximum Voltage: 8 Vdc 500 Ohms Input Impedance: Operating Temperature -40° to +85°C (-40° to +185°F) Note: LCD contrast impaired for temperatures below -20° and above +70°C Humidity 5% to 95% without condensation Weight (Maximum) 3U Rack Unit: 17.5 lbs (8.0 kg) 21.5 lbs (9.8 kg) 4U Rack Unit: 5U Rack Unit: 25.5 lbs (11.6 kg) Type Tests Electromagnetic Compatibility (EMC) Electromagnetic Emissions: EN 50263: 1999 IEC 60255-25 (2000) Emissions: **Electromagnetic Compatibility Immunity** Conducted RF Immunity: ENV 50141: 1993, 10 V rms Digital Radio ENV 50204: 1995, 10 V/m at 900 MHz Telephone RF: and 1.89 GHz IEC 60255-22-2 (1996), Electrostatic Discharge:

Levels 1, 2, 3, 4

	IEC 61000-4-2 (1995),
	Levels 1, 2, 3, 4
Fast Transient Disturbance:	IEC 61000-4-4 (1995),
	IEC 60255-22-4 (1992),
Magnetic Field	4 kV at 2.5 and 5 kHz
Immunity:	IEC 61000-4-8 (1993)
	850 A/m for 3 seconds IEC 61000-4-9 (1993)
	850 A/m
Power Supply Immunity:	IEC 61000-4-11 (1994),
,	5 cycles
Radiated Radio	IEC 60255-11 (1979)
Frequency:	ENV 50140: 1993,
	IEC 60255-22-3 (1989) IEC 61000-4-3 (1998)
	10 V/m
	IEEE C37.90.2-1995, 35 V/m
	Exceptions: DC Battery System
	Monitor, 10 V/m (±10%); SEL-2701 Installed, 10 V/m
Surge Withstand:	IEC 60255-22-1(1988),
	2.5 kV peak common mode,2.5 kV peak differential mode
	IEEE C37.90.1-1989,
	3.0 kV oscillatory, 5.0 kV fast transient
Environmental	
Cold:	IEC 60068-2-1 (1990)
	[EN 60068-2-1: 1993], Test Ad: 16 hours at –40°C
Dry Heat:	IEC 60068-2-2 (1974)
	[EN 60068-2-2: 1993], Test Bd: Dry heat,
	16 hours at +85°C
Damp Heat, Cyclic:	IEC 60068-2-30 (1980), Test Db: 55°C, 6 cycles,
	95% humidity
Object Penetration:	IEC 60529 (1989), IP30
Vibration:	IEC 60255-21-1 (1988),
	Class 1 IEC 60255-21-2 (1988),
	Class 1
	IEC 60255-21-3 (1993), Class 2
Safety	
Dielectric Strength:	IEC 60255-5 (1977),
	IEEE C37.90-1989, 2500 Vac on control inputs,
	control outputs, and analog inputs;
Impulse:	3100 Vdc on power supply IEC 60255-5 (1977),
-	0.5 J. 5 kV
Insulation Resistance:	IEC 60255-5 (1977), Resistance @ 500 V >1 minute.
	Resistance 10 M Ω -100 M Ω
Laser Safety (optional SEL-2701	
(optional SEL-2701 Ethernet Processor):	21 CFR 1040.10, FDA,
	IEC 60825-1 (1993), ANSI Z136.1-1993,
	Class 1
	ANSI Z136.2-1988, Service Group 1
	a contraction of the second se
Certifications	
ISO:	Relay is designed and manufactured using ISO-9001 certified quality
	program.
Product Safety:	IEC 60255-6 (1988) [EN 60255-6: 1994]

Reporting Functions High-Resolution Data Rate: 8000 samples/second 4000 samples/second 2000 samples/second 1000 samples/second Output Format: Binary COMTRADE Note: Per IEEE Standard Common Format for Transient Data Exchange (COMTRADE) for Power Systems, IEEE C37.111-1999 **Event Reports** Storage: 35 quarter-second events or 24 half-second events Maximum Duration: Record events as long as 5 seconds Resolution: 8- or 4-samples/cycle Event Summary Storage 100 summaries **Breaker History** 128 histories Storage Sequential Events Recorder Storage: 1000 entries Trigger elements: 250 relay elements **Processing Specifications** AC Voltage and Current Inputs 8000 samples per second, 3 dB low-pass analog filter cut-off frequency of 3000 Hz. **Digital Filtering** Full-cycle cosine and half-cycle Fourier filters after low-pass analog and digital filtering. Protection and Control Processing 8 times per power system cycle **Control Points** 32 remote bits 32 local control bits 32 latch bits in protection logic 32 latch bits in automation logic Relay Element Pickup Ranges and Accuracies Mho Phase Distance Elements Zones 1-5 Impedance Reach Setting Range: 5 A Model OFF, 0.05 to 64 Ω secondary, 0.01 Ω steps 1 A Model: OFF, 0.25 to 320 Ω secondary, 0.01 Ω steps Sensitivity: 5 A Model: 0.5 A_{P-P} secondary 1 A Model: 0.1 Ap-p secondary (Minimum sensitivity is controlled by the pickup of the supervising phase-to-phase overcurrent elements for each zone.) Accuracy (Steady State): \pm 3% of setting at line angle for SIR (source-to-line impedance ratio) < 30 \pm 5% of setting at line angle for $30 \le SIR \le 60$ Zone 1 Transient Overreach: < 5% of setting plus steady state accuracy SEL-421 Maximum Operating Time: SEL-421-1 Maximum 0.8 cycle at 70% of reach and SIR = 1 1.5 cycle at 70% of reach and SIR = 1 Operating Time: Mho Ground Distance Elements Zones 1-5 Impedance Reach Mho Element Reach: 5 A Model:

OFF, 0.05 to 64 \Omega secondary, 0.01 Ωsteps OFF, 0.25 to 320 Ω secondary, 0.01Ω steps

0.5 A secondary 0.1 A secondary

1 A Model:

1 A Model:

Sensitivity: 5 A Model:

	(Minimum sensitivity is controlled by the pickup of the supervising phase and residual overcurrent elements for	Su p
Accuracy (Steady State):	5	
	$\pm 3\%$ of setting at line angle for SIR < 30 $\pm 5\%$ of setting at line angle for $30 \le SIR \le 60$	
Zone 1 Transient		Und
Overreach:	< 5% of setting <i>plus</i>	Pi
SEL-421 Maximum	steady state accuracy	Ph
Operating Time: SEL-421-1 Maximum	0.8 cycle at 70% of reach and SIR = 1	Ac
Operating Time:	1.5 cycle at 70% of reach and SIR = 1	Dro
Quadrilateral Ground Dista	ince Elements	Brea Se
Zones 1–5 Impedance Rea	ch	5
Quadrilateral Reactance Reach:		1
5 A Model:	OFF, 0.05 to 64 Ω secondary, 0.01 Ω steps	A0 5
1 A Model:	OFF, 0.25 to 320 Ω secondary,	1
	0.01 Ω steps	Tr
Quadrilateral Resistance Reach:		М
5 A Model:	OFF, 0.05 to 50 Ω secondary, 0.01 Ω steps	M
1 A Model:	OFF, 0.25 to 250 Ω secondary,	Ti
	0.01 Ω steps	
Sensitivity:		
5 A Model: 1 A Model:	0.5 A secondary	Ti
I A Woder.	0.1 A secondary (Minimum sensitivity is controlled by	Syn
	the pickup of the supervising phase and	SI
	residual overcurrent elements for each	P
	zone.)	SI
Accuracy (Steady State):	$\pm 3\%$ of setting at line angle for SIR < 30 $\pm 5\%$ of setting at line angle for	P Cl
	$\pm 5\%$ of setting at the angle for $30 \le SIR \le 60$	Cl
Transient Overreach:	< 5% of setting plus steady state accuracy	
Instantaneous/Definite-Tin	ne Overcurrent Flements	Loa Se
Phase, Residual Ground, and		5
Pickup Range:	-	1
5 A Model:	OFF, 0.25–100.00 A secondary,	F
1 A Model:	0.01 A steps OFF, 0.05–20.00 A secondary,	R Ad
I A Wodel.	0.01 A steps	I
Accuracy (Steady State):	1	Α
5 A Model:	± 0.05 A plus $\pm 3\%$ of setting	Out
1 A Model: Transient Overreach:	±0.01 A plus ±3% of setting < 5% of pickup	Bl
Time Delay:	0.00–16000.00 cycles, 0.125 cycle steps	5
Timer Accuracy:	± 0.125 cycle plus $\pm 0.1\%$ of setting	1
Maximum	1.5	1
Operating Time: Note: See pickup and reset	1.5 cycles time curves in the <i>Inverse Time-Overcurrent</i>	Bl
	in the Reference Manual.	5
Time-Overcurrent Element	S	1
Pickup Range:		
5 A Model:	0.50–16.00 A secondary, 0.01 A steps	A0 5
1 A Model: Accuracy (Steady State):	0.10-3.20 A secondary, 0.01 A steps	3
5 A Model:	± 0.05 A plus $\pm 3\%$ of setting	
1 A Model:	± 0.01 A plus $\pm 3\%$ of setting	1
Time Dial Range:		1
US: IEC:	0.50-15.00, 0.01 steps	
Curve Timing Accuracy:	0.05-1.00, 0.01 steps ± 1.50 cycles plus $\pm 4\%$ of curve time	_
Curve Timing Recuracy.	(for current between 2 and 30	Tr
	multiples of pickup)	Pc
Reset:	1 power cycle or Electromechanical	Se
	Reset Emulation time	5
Ground Directional Elemen	its	1
NegSeq. directional		A0 5
impedance threshold (Z2I		1
5 A Model: 1 A Model:	-64 to 64 Ω -320 to 320 Ω	Tr
Zero-Seq. directional		
impedance threshold (Z01		
5 A Model:	$-64 \text{ to } 64 \Omega$	
1 A Model:	-320 to 320 Ω	

Supervisory overcurrent pickup 50FP, 50RP: 5 A Model:	0.25 to 5.00 A 310 secondary
1 A Model:	0.25 to 5.00 A 312 secondary 0.05 to 1.00 A 310 secondary 0.05 to 1.00 A 312 secondary
Indervoltage and Overvolt Pickup Ranges:	Phase elements: 1-200 V secondary,
Phase-to-phase elements: Accuracy (Steady State): Transient Overreach:	1 V steps 1.0–300.0 V secondary, 0.1 V steps ±1 V plus ±5% of setting < 5% of pickup
Breaker Failure Instantane Setting Range:	ous Overcurrent
5 A Model: 1 A Model: Accuracy:	0.50-50.0 A, 0.01 A steps 0.10-10.0 A, 0.01 A steps
5 A Model: 1 A Model: Transient Overreach:	±0.05 A plus ±3% of setting ±0.01 A plus ±3% of setting < 5% of setting
Maximum Pickup Time: Maximum Reset Time: Timers Setting Range:	1.5 cycles 1 cycle 0-6000 cycles, 0.125 cycle steps (All by DEIDOR, DEISDE)
Time Delay Accuracy:	(All but BFIDOn, BFISPn) 0–1000 cycles, 0.125 cycle steps (BFIDOn, BFISPn) 0.125 cycle plus ±0.1% of setting
Time Delay Accuracy:	
Slip Frequency Pickup Range:	
Slip Frequency Pickup Accuracy:	0.005–0.500 Hz, 0.001 Hz steps ±0.0025 Hz plus ±2% of setting
Close Angle Range: Close Angle Accuracy:	3-80°, 1° steps + 3°
oad-Encroachment Detect	
5 A Model: 1 A Model: Forward Load Angle: Reverse Load Angle:	0.05-64 Ω secondary, 0.01 Ωsteps 0.25-320 Ω secondary, 0.01 Ωsteps -90° to +90° +90° to +270°
Accuracy: Impedance measurement: Angle measurement:	±3% ±2°
Out-of-Step Elements Blinders (R1) parallel to the	e line angle:
5 A Model:	0.05 to 70 Ω secondary -0.05 to -70 Ω secondary
1 A Model:	0.25 to 350 Ω secondary -0.25 to -350 Ω secondary
Blinders (X1) perpendicula 5 A Model:	r to the line angle: 0.05 to 96 Ω secondary
1 A Model:	-0.05 to -96Ω secondary 0.25 to 480 Ω secondary
Accuracy (Steady State):	-0.25 to -480Ω secondary
5 A Model:	\pm 5% of setting plus \pm 0.01 A for SIR (source to line impedance ratio) < 30 \pm 10% of setting plus \pm 0.01 A for
1 A Model:	$30 \le SIR \le 60$ ±5% of setting plus ±0.05 A for SIR
	(source to line impedance ratio) < 30 $\pm 10\%$ of setting plus ± 0.05 A for $30 \le SIR \le 60$
Transient Overreach:	< 5% of setting <i>plus</i> steady state accuracy
Positive-Sequence Overcur Setting Range:	rent Supervision:
5 A Model:	1.0–100.0 A, 0.01 A steps
1 A Model: Accuracy:	0.2–20.0 A, 0.01 A steps
5 A Model:	$\pm 3\%$ of setting plus ± 0.05 A
1 A Model: Transient Overreach:	±3% of setting plus ±0.01 A < 5% of setting

Timer Specifications Setting Ranges Breaker Failure:	0–6000 cycles, 0.125 cycle steps (All but BFIDOn, BFISPn)	Sequence Currents Magnitude 5 A Model Input > 0.5 A: ± 0.3 1 A Model Input > 0.1 A: ± 0.3 Sequence Current Angle: ± 0.3
Communications-	0–1000 cycles, 0.125 cycle steps (BFIDOn, BFISPn)	Voltages Phase and Phase-to-Phase Volta Input > 33.5 volts: ±0.1
Assisted Tripping Schemes: Out-of-Step Timers:	0.000–16000 cycles, 0.125 cycle steps	Phase and Phase-to-Phase Angle: ±0.0 Sequence Voltage Magnitude:
OSBD, OSTD: UBD:	0.500–8000 cycles, 0.125 cycle steps 0.500–120 cycles, 0.125 cycle steps	Input > 33.5 volts: ± 0.1 Sequence Voltage Angle: ± 0.1
Pole Open Timer: Recloser: Switch-Onto-Fault:	0.000–60 cycles, 0.125 cycle steps 1–99999 cycles, 1 cycle steps	Frequency (Input 40-65 Hz) Accuracy: ±0.0
CLOEND, 52AEND:	OFF, 0.000–16000 cycles, 0.125 cycle steps	Power and Energy Real Power, P (MW), Three Pha At 0.1 • I _{nom}
SOTFD: Synchronism	0.50-16000 cycles, 0.125 cycle steps	Power factor unity ± 0.4 Power factor
Check Timers: TCLSBK1,		0.5 lag, 0.5 lead ± 0.7 At 1.0 • I _{nom}
TCLSBK2: Zone Time Delay:	1.00–30.00 cycles, 0.25 cycle steps 0.000–16000 cycles, 0.125 cycle steps	Power factor unity ± 0.4 Power factor
-		$0.5 \text{ lag}, 0.5 \text{ lead} \pm 0.4$ Reactive Power, Q (MVAR), Th
Station DC Dattery Sy	stem Monitor Specifications	At 0.1 • I

Operating Range: Input Sampling Rate: Processing Rate: Maximum Operating Time: Setting Range: DC settings: AC ripple setting: Accuracy: Pickup Accuracy: 0–350 Vdc 2 kHz 1/8 cycle ≤ 1.5 cycles 15–300 Vdc, 1 Vdc steps 1–300 Vac, 1 Vac steps

±3% plus ±2 Vdc (all elements but DC1RP and DC2RP) ±10% plus ±2 Vac (DC1RP and DC2RP)

Metering Accuracy

All metering accuracy is at 0.1 \cdot $I_{nom},$ 20°C, and nominal frequency unless otherwise noted.

Currents

Phase Current Magnitude5 A Model Input \geq 0.5 A:1 A Model Input \geq 0.1 A: \pm 0.2'Phase Current Angle: \pm 0.2'

±0.2% plus ±4 mA ±0.2% plus ±0.8 mA ±0.2°

 $nput > 0.5 \text{ A}: \pm 0.3\% \text{ plus } \pm 4 \text{ mA}$ nput $\ge 0.1 \text{ A}$: $\pm 0.3\%$ plus $\pm 0.8 \text{ mA}$ irrent Angle: ±0.3 degree hase-to-Phase Voltage Magnitude: volts: ±0.1% nase Angle: ±0.05 degree ltage Magnitude: ±0.15% volts: oltage Angle: ±0.1 degree put 40-65 Hz) ±0.01 Hz ergy P (MW), Three Phase tor unity $\pm 0.4\%$ tor 0.5 lead ±0.7% ±0.4% tor unity tor 0.5 lead ±0.4% wer, Q (MVAR), Three Phase At 0.1 • I_{nom} Power factor $\pm 0.5\%$ 0.5 lag, 0.5 lead At 1.0 • I_{nom} Power factor 0.5 lag, 0.5 lead ±0.4% Energy (MWh), Three Phase At 0.1 • I_{nom} Power factor unity ±0.5% Power factor 0.5 lag, 0.5 lead ±0.7% At 1.0 • I_{nom} Power factor unity ±0.4% Power factor 0.5 lag, 0.5 lead $\pm 0.4\%$

Synchronized Phasor Measurements*

Sampling Rate:	20 sps
Voltage	
Magnitude Accuracy:	±0.1%
Voltage Angle Accuracy:	±0.125°
Voltage Range:	30–150 V

* Synchrophasor capability is not available in the SEL-421-1 Relay.

Section 2 Installation

The first steps in applying the SEL-421 Relay are installing and connecting the relay. This section describes common installation features and particular installation requirements for the many physical configurations of the SEL-421 Relay. You can order the relay in horizontal and vertical orientations, and in panel-mount and rack-mount versions. SEL also provides various expansion I/O (input/output) interface boards to tailor the relay to your specific needs.

To install and connect the relay safely and effectively, you must be familiar with relay configuration features and options and relay jumper configuration. You should carefully plan relay placement, cable connection, and relay communication. Consider the following when installing the SEL-421 Relay:

- ► Shared relay configuration attributes
- ► Plug-in boards
 - > I/O interface board(s) (if applicable)
 - > Communications card (if applicable)
- ► Jumpers
- ► Placement
 - > Physical location
 - Cutting and drilling the mounting panel (if the relay is a panel-mount configuration)
 - > Mounting the relay to a panel or into a rack
- ► Connection
 - ➤ Grounding
 - > Power
 - > DC battery monitor
 - Secondary circuits
 - Control circuits
 - ≻ IRIG-B
 - Ik PPS [from a GPS (Global Positioning System) receiver]
 - > Communications circuits

This section contains drawings of typical ac and dc connections to the SEL-421 Relay (*AC/DC Connection Diagrams on page 2.47*). Use these drawings as a starting point for planning your particular relay application.

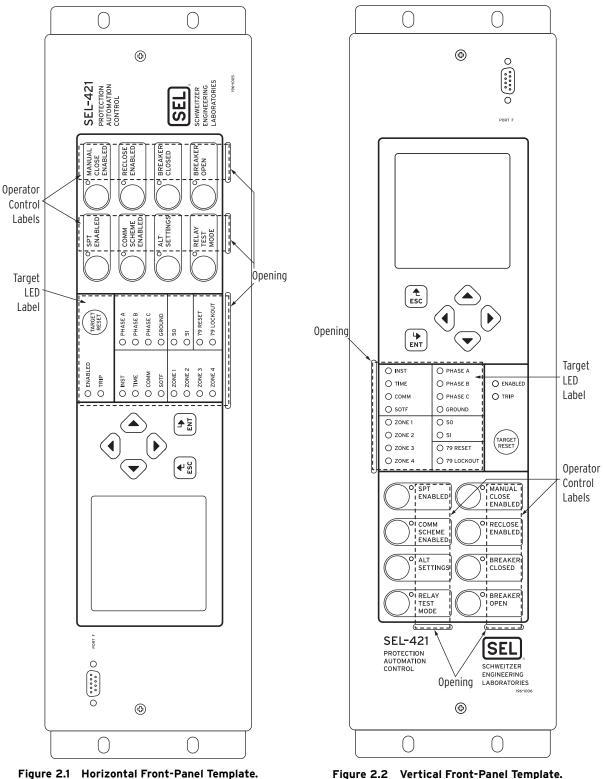
It is also very important to limit access to the SEL-421 Relay settings and control functions by using passwords. For information on relay access levels and passwords, see *Changing the Default Passwords: Terminal on page U.4.10 in the User's Guide*.

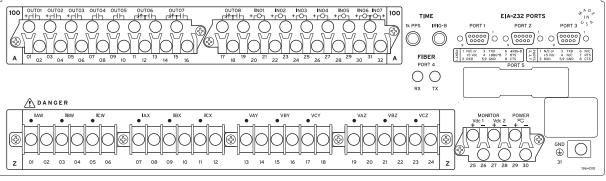
Shared Configuration Attributes

	There are common or shared attributes among the many possible configurations of SEL-421 Relays. This section discusses the main shared features of the relay.
Relay Sizes	SEL produces the SEL-421 Relay in horizontal and vertical rack-mount versions and horizontal and vertical panel-mount versions. Relay sizes correspond to height in rack units, U, where U is approximately 1.75 inches or 44.45 mm. The SEL-421 Relay is available in 3U, 4U, and 5U sizes.
Front-Panel Templates	The horizontal front-panel template shown in <i>Figure 2.1 on page 2.4</i> is the same for all 3U, 4U, and 5U horizontal versions of the relay. The vertical front-panel template (shown in <i>Figure 2.2 on page 2.4</i>) is the same for all 3U, 4U, and 5U vertical versions of the relay.
	The SEL-421 Relay front panel has three pockets for slide-in labels: one pocket for the Target LED label, and two pockets for the Operator Control labels. <i>Figure 2.1 on page 2.4</i> shows the front-panel pocket areas and openings for typical horizontal and vertical relay orientations; dashed lines denote the pocket areas. See <i>Changing Configurable Front-Panel Labels on page 2.27</i> for information on reconfiguring front-panel LED and pushbutton labels.
Rear Panels	Rear panels are identical for the horizontal and the vertical configurations of the relay. <i>Figure 2.3 on page 2.5</i> is an example of a rear panel for a 3U relay with fixed terminal block analog inputs. <i>Figure 2.4 on page 2.5</i> shows a rear panel for a 3U relay with Connectorized [®] analog inputs. See <i>Rear-Panel Layout on page 2.33</i> for representative 3U, 4U, and 5U relay rear panels (large drawings are in <i>Figure 2.21 on page 2.34</i> , <i>Figure 2.22 on page 2.34</i> , <i>Figure 2.23 on page 2.34</i> , and <i>Figure 2.24 on page 2.35</i>).
Connector Types	
	Screw Terminal Connectors-I/O and Monitor/Power
	Connect to the relay I/O and Monitor/Power terminals on the rear panel through screw terminal connectors. You can remove the entire screw terminal connector from the back of the relay to disconnect relay I/O, DC Battery Monitor, and Power without removing each wire connection. The screw terminal connectors are keyed (see <i>Figure 2.26 on page 2.36</i>), so you can replace the screw terminal connector on the rear panel only at the location from which you removed the screw terminal connector. In addition, the receptacle key prevents you from inverting the screw terminal connector. This feature makes relay removal and replacement easier.
	Secondary Circuit Connectors
	Fixed Terminal Blocks
	Connect PT and CT inputs to the fixed terminal blocks in the bottom row of the relay rear panel. You cannot remove these terminal blocks from the relay rear panel. These terminals offer a secure high-reliability connection for PT and CT secondaries.

Connectorized

The Connectorized SEL-421 Relay features receptacles that accept plugin/plug-out connectors for terminating PT and CT inputs; you must order a wiring harness (SEL-WA0421) with mating plugs and wire leads. *Figure 2.4 on page 2.5* shows the relay 3U chassis with Connectorized CT and PT analog inputs. See *Connectorized on page 2.40* for more information.





i3359a

Figure 2.3 Rear 3U Template, Fixed Terminal Block Analog Inputs.

(When using a vertical-mount relay, the right rear side is at the top.)

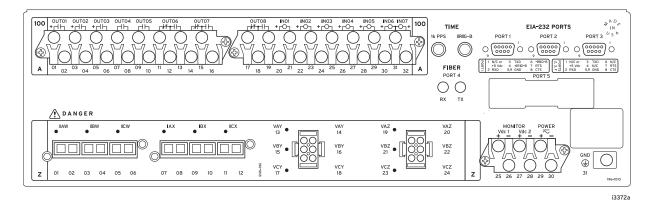


Figure 2.4 Rear 3U Template, Connectorized Analog Inputs.

(When using a vertical-mount relay, the right rear side is at the top.)

Secondary Circuits

The SEL-421 Relay is a very low burden load on the CT secondaries and PT secondaries. For both the CT and PT inputs, the frequency range is 40–65 Hz.

The relay accepts two sets of three-phase currents from power system CT inputs:

- ► IAW, IBW, and ICW
- ► IAX, IBX, and ICX

For 5 A relays, the rated nominal input current, I_{nom} , is 5 A. For 1 A relays, the rated nominal input current, I_{nom} , is 1 A. Input current for both relay types can range to 20 • I_{nom} . The CT burden is 0.27 VA @ 5A and 2.51 VA @ 15 A for the 5 A relay. The CT burden for the 1 A relay is 0.13 VA @ 1 A and 1.31 VA @ 3A. See the *AC Current Inputs (Secondary Circuits) on page U.1.11 in the User's Guide* for complete CT input specifications.

The relay also accepts two sets of three-phase, four-wire (wye) potentials from power system PT or CCVT (coupling-capacitor voltage transformer) secondaries:

- ► VAY, VBY, and VCY
- ► VAZ, VBZ, and VCZ

The nominal line-to-neutral input voltage for the PT inputs is 67 volts with a range of 0–300 volts. The PT burden is less than 0.5 VA at 67 volts, L-N. See *AC Voltage Inputs on page U.1.11 in the User's Guide* for complete PT input specifications.

Some applications do not use all three phases of a source; for example, voltage synchronization sources can be single phase. See *Section 1: Protection Application Examples in the Applications Handbook* for examples of connections to the potential inputs.

See *Secondary Circuit Connections on page 2.40* for information on connecting power system secondary circuits to these inputs.

I/O inputs into the relay are direct-coupled, high-impedance control inputs. Use these inputs for monitoring on/off and logical change-of-state conditions of power system equipment. These high-isolation control inputs are polarity-sensitive, ground-isolated circuits. You cannot damage these inputs with a reverse polarity connection, although the relay will not detect input changes with a reverse-polarity input. For more information on control input specifications, see *Control Inputs on page U.1.11 in the User's Guide*.

Inputs can be independent or common. Independent inputs have two separate ground-isolated connections to a high-isolation ADC (analog to digital converter). There are no internal connections among independent inputs. Common inputs share one input leg in common; all input legs of common inputs are ground-isolated. Each pair of common inputs is isolated from all other pairs.

Nominal current draw for these inputs is very low (4 mA or less) with an input voltage range of 15 Vdc to 265 Vdc. You can adjust the level at which these inputs assert; use the **SET G** (Global) command for control input pickup settings, GINP, and advanced settings, IN*nnn*P, where *n* represents the input number. You can also debounce the control inputs by using the **SET G** command for control input debounce settings, GIND, and advanced settings, IN*nnnD*. You can also set a global dropout factor, GINDF. See *Global Settings on page R.9.3 in the Reference Manual* for the default settings and more information. The control input accuracy is ± 5 percent of the applied signal plus ± 3 Vdc. The maximum voltage input is 300 Vdc, and the relay samples the control inputs 16 times per cycle.

I/O control outputs from the relay include Standard outputs, Hybrid (highcurrent-interrupting) outputs, and Fast Hybrid (fast high-current-interrupting) outputs. Fast Hybrid outputs are available only on the optional I/O interface board INT5. An MOV (metal-oxide varistor) protects against excess voltage transients for each contact. Each output is individually isolated except Form C outputs, which share a common connection between the NC (normally closed) and NO (normally open) contacts.

The relay updates control outputs eight times per cycle. Updating of relay control outputs does not occur when the relay is disabled. When the relay is reenabled, the control outputs assume the state that reflects the present protection processing.

Control Inputs

NOTE: The SEL-421 Relay has polarity-sensitive inputs. Observe the polarity marks when connecting external wiring.

Control Outputs

Standard Control Outputs

NOTE: You can use ac or dc circuits with Standard control outputs.

The Standard control outputs are "dry" Form A contacts rated for tripping duty. Ratings for Standard outputs are 30 A make, 6 A continuous, and 0.5 A or less break (depending on circuit voltage). Standard contact outputs have a maximum voltage rating of 250 Vac/330 Vdc. Maximum break time is 6 ms (milliseconds) with a resistive load. The maximum pickup time for the Standard control outputs is 6 ms. *Figure 2.5 on page 2.7* shows a representative connection for a Form A Standard control output on the main board I/O terminals.

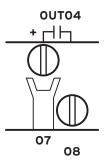


Figure 2.5 Standard Control Output Connection.

See *Control Outputs on page U.1.11 in the User's Guide* for complete standard control output specifications.

Hybrid (High-Current-Interrupting) Control Outputs

The Hybrid (high-current-interrupting) control outputs are polarity dependent and are capable of interrupting high-current, inductive loads. Hybrid control outputs use an IGBT (Insulated Gate Bipolar Junction Transistor) in parallel with a mechanical contact to interrupt (break) highly inductive dc currents. The contacts can carry continuous current, while eliminating the need for heat sinking and providing security against voltage transients.

With any hybrid output, break time varies according to the L/R (circuit inductive/resistive) ratio. As the L/R ratio increases, the time needed to interrupt the circuit fully increases also. The reason for this increased interruption delay is that circuit current continues to flow through the output MOV after the output deasserts, until all of the inductive energy dissipates. Maximum dropout (break) time is 6 ms with a resistive load, the same as for the Standard control outputs. The other ratings of these control outputs are similar to the Standard control outputs, except that the Hybrid outputs can break current as great as 10 A. Hybrid contact outputs have a maximum voltage rating of 330 Vdc.

The maximum pickup time for the Hybrid control outputs is 6 ms. *Figure 2.6* shows a representative connection for a Form A Hybrid control output on the main board I/O terminals.

CAUTION: Equipment damage can result from connecting ac circuits to Hybrid (high-current-interrupting) control outputs. Do not connect ac circuits to Hybrid control outputs. Use only dc circuits with Hybrid control outputs.

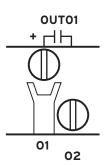


Figure 2.6 Hybrid Control Output Connection.

See *Section 1: Introduction and Specifications in the User's Guide*, for complete Hybrid control output specifications.

Fast Hybrid (Fast High-Current-Interrupting) Control Outputs

In addition to the Standard control outputs and the Hybrid control outputs, I/O interface board INT5 offers Fast Hybrid (fast high-current-interrupting) control outputs. These control outputs have a resistive load pickup time of 10 µs (microseconds), which is much faster than the 6 ms pickup time of the Standard and Hybrid control outputs. The Fast Hybrid control outputs drop out at a maximum time of 8 ms. The maximum voltage rating is 250 Vac/330 Vdc. See *Control Outputs on page U.1.11 in the User's Guide*, for complete Fast Hybrid control output specifications. *Figure 2.7* shows a representative connection for a Form A Fast Hybrid control output on the INT5 I/O interface terminals.

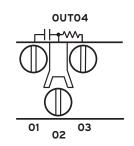


Figure 2.7 Fast Hybrid Control Output Connection.

Short transient inrush current can flow at the closing of an external switch in series with open Fast Hybrid contacts. This transient will not energize the circuits in typical relay-coil control applications (trip coils and close coils), and standard auxiliary relays will not pick up. However, an extremely sensitive digital input or light-duty, high-speed auxiliary relay can pick up for this condition. This false pick-up transient occurs when the capacitance of the Fast Hybrid output circuitry charges (creating a momentary short circuit that a fast, sensitive device sees as a contact closure). A third terminal (03 in *Figure 2.8*) provides an internal path for precharging the Fast Hybrid output circuit is open.

NOTE: You can use ac or dc circuits with Fast Hybrid (fast high-currentinterrupting) outputs.

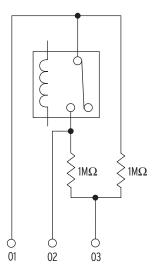


Figure 2.8 Fast Hybrid Control Output Typical Terminals.

Figure 2.9 on page 2.9 shows some possible connections for this third terminal that will eliminate the false pick-up transients when closing an external switch. In general, you must connect the third terminal to the dc rail (positive or negative) that is on the same side as the open external switch condition. If an open switch exists on either side of the output contact, then you can accommodate only one condition because two open switches (one on each side of the contact) defeat the precharge circuit.

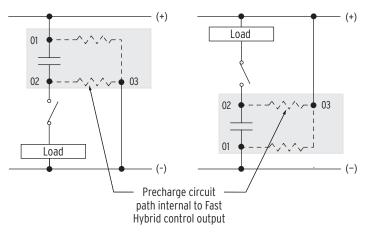


Figure 2.9 Precharging Internal Capacitance of Fast Hybrid Output Contacts.

The SEL-421 Relay base model is a 3U chassis with I/O interface on the main board (the top board). See *Figure 2.20 on page 2.33* and *Figure 2.21 on page 2.34* for representative rear-panel views of the 3U chassis rear panel. Every SEL-421 Relay configuration includes the main board I/O and features these connections:

- ➤ Three Hybrid (high-current-interrupting) Form A outputs
- ► Two Standard Form A outputs
- ► Three Standard Form C outputs
- Seven high-isolation control inputs (five independent and two with a common leg)

Main Board I/O

TIME Inputs

The SEL-421 Relay has high-accuracy time-keeping modes IRIG and PPS. You can provide IRIG-B time code format signals to the relay from many sources (SEL-2030 Communications Processor, GPS receiver, etc.). For even greater accuracy, use GPS satellite-locked 1000 PPS (pulse-per-second) time code signals for extremely accurate time stamping of power system events. This is very valuable for analyzing event data and developing a look at instantaneous power system states (state estimation). See *Section 3: Analyzing Data in the Applications Handbook* and *Section 4: Time-Synchronized Measurements in the Applications Handbook* for more information on the use and benefits of high-accuracy time keeping.

IRIG-B

The IRIG-B serial data format consists of a 1-second frame containing 100 pulses divided into fields. The relay decodes the second, minute, hour, and day fields and sets the internal time clock upon detecting valid time data in the IRIG time mode. Timing accuracy for IRIG-only time mode is as close as 150 μ s for a highly stable and accurate IRIG-B source. See *IRIG-B on page U.4.66 in the User's Guide* for information on enabling IRIG-B time keeping.

1k PPS

	The 1000 PPS (1k PPS) pulse train output of a GPS receiver provides a high- accuracy time source. The GPS receiver generates this pulse train from the 1k PPS satellite-transmitted time signal. High-accuracy GPS-based time and frequency receivers from various manufacturers provide the 1k PPS signal as an ordering option. In PPS time mode, use both an IRIG-B and a 1000 PPS time code signal for extremely accurate time stamping of power system events. Timing accuracy for PPS mode is \pm 10 µs. See <i>1k PPS on page U.4.66</i> <i>in the User's Guide</i> , for information on enabling PPS time keeping.
Battery-Backed Clock	If relay input power is lost or removed, a lithium battery powers the relay clock providing date and time backup. The battery is a 3 V lithium coin cell, Ray-O-Vac [®] No. BR2335 or equivalent. If power is lost or disconnected, the battery discharges to power the clock. At room temperature (25° C), the battery will operate for approximately 10 years at rated load.
	When the SEL-421 Relay is operating with power from an external source, the self-discharge rate of the battery only is very small. Thus, battery life can extend well beyond the nominal 10-year period because the battery rarely discharges after the relay is installed. The battery cannot be recharged. <i>Figure 2.13 on page 2.18</i> shows the clock battery location (at the front of the main board).
	If the relay does not maintain the date and time after power loss, replace the battery. See <i>Replacing the Lithium Battery on page 2.44</i> .
Communications Interfaces	The SEL-421 Relay has several communications interfaces you can use to communicate with other IEDs (intelligent electronic devices) via EIA-232 ports: PORT 1, PORT 2, PORT 3, and PORT F. See <i>Section 4: Communications Interfaces in the Reference Manual</i> for more information and options for connecting your relay to the communications interfaces.
	You can install an optional communications card to obtain Ethernet capability for the SEL-421 Relay. A communications card, such as the SEL-2701 Ethernet Processor, gives the relay access to popular Ethernet networking

standards including TCP/IP, FTP, Telnet, and UCA2 over local area networks and wide area networks. For more information on UCA2 applications, see *Section 7: UCA2 Communications in the Reference Manual*.

All versions of the SEL-421 Relay also feature ground, power, and battery monitor connections, communications ports, and fiber ports. See *Connection on page 2.33* for information on these relay interface features.

Other Shared Configuration Attributes

Plug-In Boards

NOTE: Ordering the 4U and 5U relay with partial or no extra I/O allows for future system expansion and future use of additional relay features.

I/O Interface Boards

The SEL-421 Relay is available in many input/output configuration options. The relay base model is a 3U chassis with Standard I/O and screw terminal connector connections (see *Figure 2.3 on page 2.5*). Other ordering options include versions of the relay in larger enclosures (4U or 5U) with all, partial, or no extra I/O boards installed.

Also available for the SEL-421 Relay is a plug-in communications card. The optional SEL-2701 Ethernet Processor communications card allows you to use TCP/IP, FTP, Telnet, and UCA2 applications on an Ethernet network.

You can choose among three input/output interface boards for the I/O slots of the 4U and 5U chassis. These I/O interface boards are in addition to the main board I/O described in *Shared Configuration Attributes on page 2.2*. The I/O interface boards are INT1, INT5, and INT6. *Figure 2.10* and *Figure 2.11* show the rear screw terminal connectors associated with these interface boards.

200	outo1 outo2 outo3 outo4 outo5 outo6 outo7 outo8	outos outro outri outris outris outris outris	1001 1002 1003 1004 1005 1006 1007 1008 200
6			
в	01 02 03 04 05 06 07 08 09 10 11 12 13 14 15 16	17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32	³³ ³⁵ ³⁶ ³⁷ ³⁸ ³⁹ ⁴⁰ ⁴¹ ⁴² ⁴³ ⁴⁴ ⁴⁵ ⁴⁶ ⁴⁷ ⁴⁸ B

Figure 2.10 INT1 or INT6 I/O Interface Board.

200								outos	1N01 + r 0-1	1N02	1N03		1N06 I +rO1 *r	N07 IN08	200
1/	OO	00	00		NOD	00	ЮQ		<u>a/IO</u>	Q	OIC	00	ЮС		J@I
Ø	i O C	ÖÖC) O C		£0() O C	000		7&	ĎС	Ĵ Ő	<u> </u>	ŬŐ	<u> </u>	5/1
В	01 03 03 04	05 07 07	09 11 1	13 15 16	17 10 19	21 23 23 2	25 . 27	29 30 31 33	33 34	35	37 20 3	19 40 41 43	43 45	47 48	ТвІ

Figure 2.11 INT5 I/O Interface Board.

The I/O interface boards carry jumpers that identify the board location. See *Jumpers on page 2.17* for more information on I/O board jumpers.

I/O Interface Board Inputs

All optional I/O interface boards have eight independent control inputs. All independent inputs are isolated from other inputs. These high-isolation control inputs are polarity-sensitive, ground-isolated circuits. You cannot damage these inputs with a reverse polarity connection; though, the relay will not detect input changes with a reverse-polarity input.

Table 2.1 is a comparison of the I/O board input capacities; the table also shows the I/O inputs on the main board. See *Control Inputs on page U.1.11 in the User's Guide* for complete control input specifications.

Table 2.1	I/O Interface	Boards	Control Inputs
-----------	---------------	--------	-----------------------

Board Number	Independent Contact Pairs	Common Contact Pairs
INT1	8	
INT5	8	
INT6	8	
Main Board	5	2

I/O Interface Board Outputs

The I/O interface boards vary by the type and amount of output capabilities. *Table 2.2* lists the outputs of the additional I/O interface boards; the table also shows the I/O outputs on the main board. Information about the Standard and Hybrid (high-current interrupting) control outputs is in *Control Outputs on page 2.6*.

	Standard		Fast Hybrid ^a	Hybrid ^b	
Board Number	Form A	Form C	Form A	Form A	Form C
INT1	13	2			
INT5			8		
INT6				13	2
Main Board	2	3		3	

Table 2.2 I/O Interface Boards Control Outputs

^a High-Speed/High-Current Interrupting

^b High-Current Interrupting

Installing Optional I/O Interface Boards

When expanding the capability of the SEL-421 Relay with additional I/O interface boards, perform the following steps:

- Step 1. Remove the relay from service. Follow your company standard for removing a relay from service. Disconnect power from the SEL-421 Relay. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect all cables from the main board (the top board).
- Step 4. Confirm proper installation of address jumpers on the interface board. See *Jumpers on page 2.17*.
- Step 5. Confirm drawout tray keying. The relay chassis and the drawout trays for the 200-addresses slot and the 300-addresses slot are keyed (see *Figure 2.12*). The keys are two round plug-in/plug-out discs on the bottom of the drawout tray. The 200-addresses slot keys go to the left, and the 300-addresses slot keys go to the right (when viewed from the top and front of the drawout tray). Move a key on the bottom of the drawout tray to the correct position by prying the key from the tray and reinserting the key in the proper position. Do this for both keys.

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

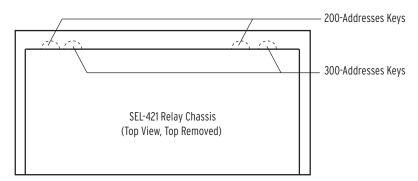


Figure 2.12 Chassis Key Positions for I/O Interface Boards.

- Step 6. Install the drawout tray with I/O interface board. Use the following precautions when installing the I/O interface board:
 - Position the drawout tray edges into the left-side and right-side internally mounted slots.
 - Slide the I/O interface board into the SEL-421 Relay by pushing the front edge of the board drawout tray.
 - ► Apply firm pressure to fully seat the I/O interface board.
 - If you encounter resistance, stop, and withdraw the board. Inspect the drawout tray edge guide slots for damage. If you see no damage, take all of the precautions outlined above and try again to insert the board.
- Step 7. If this is a new I/O interface board installation, remove the INTERFACE BOARD EXPANSION SLOT self-sticking label from the rear panel. Do this by lifting a corner of the label with a sharp tool and peeling away the label from the rear panel.
- Step 8. Confirm screw terminal connector keying. SEL supplies three new screw terminal connectors with new I/O interface boards. Inspect the screw terminal connector receptacles on the rear of the I/O interface board. Refer to *Figure 2.27 on page 2.37* for the corresponding key positions inside the receptacle. If the keys inside the I/O Interface board receptacles are not in these positions, grasp the key edge with long-nosed pliers to remove the key and reinsert the key in the correct position. Break the webs of the screw terminal connectors in the position that matches the receptacle key (see *Figure 2.26 on page 2.36*).
- Step 9. Attach the screw terminal connector. Mount the screw terminal connectors to the rear panel of the SEL-421 Relay. Refer to *Figure 2.10 on page 2.12* and *Figure 2.11 on page 2.12* for screw terminal connector placement. Tighten the screw terminal connector mounting screws to between 7 in-lb. and 12 in-lb. (0.8 Nm to 1.4 Nm).
- Step 10. Connect the interface cable(s) from the I/O board(s) to the main board.
- Step 11. Reconnect the internal power and analog cables.
- Step 12. Reattach the front panel.

- Step 13. Apply power. Enter Access Level 2 (Making Simple Settings Changes on page U.4.15 in the User's Guide). Issue the STA command and answer Y<Enter> to accept the new hardware configuration (see STATUS on page R.8.45 in the Reference Manual).
- Step 14. Inspect the relay targets to confirm that the relay reads the added I/O interface board(s). You can see the new control inputs in the target listings by using a terminal, the SEL-5030 ACSELERATOR[®] Software Program, and the front panel. Use a communications terminal to issue the commands TAR OUT201<Enter> (for the 200-addresses slot) or TAR OUT301<Enter> (for the 300-addresses slot). Alternatively, from the front panel MAIN MENU, select RELAY ELEMENTS, press the down pushbutton to go to ROW 94 (for the 200-addresses slot) or ROW 97 (for the 300-addresses slot).
- Step 15. Follow your company standard procedure to return the relay to service.

You can add other communications protocols to the SEL-421 Relay by inserting a communications card in the rear-panel PORT 5 slot. Ethernet communication is possible by adding the SEL-2701 Ethernet Communications Processor card. The SEL-2701 is an Ethernet device for industrial installations that handles data traffic between the SEL-421 Relay and a LAN (local area network).

Installing the Communications Card

To install a communications card in an SEL-421 Relay, perform the following steps. If your communications card is already installed, skip the following steps and perform the Initial Checkout procedures for your communications card.

- Step 1. Remove the relay from service. Follow your company standard for removing a relay from service. Disconnect power from the SEL-421 Relay. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect the power, interface board cable(s), and input board analog cable from the main board (the top board).
- Step 4. Remove the cover from the PORT 5 slot.
- Step 5. Remove the screw terminal connectors. Loosen the attachment screws at each end of the 100-addresses screw terminal connectors. Pull straight back to remove.
- Step 6. Remove rear-panel EIA-232 Ports mating connectors. Unscrew the keeper screws and disconnect any serial cables connected to the Port 1, Port 2, and Port 3 rear-panel receptacles.
- Step 7. Pull out the drawout tray containing the main board.
- Step 8. Insert the communications card 80-pin connector into the 80pin receptacle on the underside of the host main board, taking the following precautions:
 - Ensure the connector pins line up with the guide holes on the host main board.

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

Communications

Card

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

- Apply firm pressure while inserting the connector pins into the host receptacle, but do not force the connection. Forcing the connection can cause damage to the pins or guide holes. Rocking the communications card slightly from side to side can help align the connector pins.
- If you encounter resistance or all the pins do not protrude evenly on the upper side of the main board, stop, and withdraw the card. Inspect the pins and guide holes for damage. If pins and receptacle are undamaged, take all the precautions outlined above, and try again to insert the card.
- Step 9. Use the four screws included with the communications card to attach the cart to standoffs on the host main board. Tighten the screws to 8.0 in-lbs (0.9 Nm) to prevent stripping the threads in the nylon standoffs.
- Step 10. Reinstall the SEL-421 Relay main board, and reconnect power, interface board cables, and the input board analog cable.
- Step 11. Reattach rear-panel connections. Affix the screw terminal connectors to the appropriate 100-addresses locations on the rear panel. Reconnect any serial cables that you removed in the disassembly process to the EIA-232 Ports.
- Step 12. Reattach the front panel.
- Step 13. Follow your company standard procedure to return the relay to service.
- Step 14. Proceed with the Initial Checkout procedures for your communications card.

The SEL-421 Relay contains jumpers that configure the relay for certain operating modes. The jumpers are located on the main board (the top board) and the I/O interface boards (one or two boards located immediately below the main board).

Main Board Jumpers

The jumpers on the main board of the SEL-421 Relay perform these functions:

- ► Temporary/emergency password disable
- ► Circuit breaker control enable
- ► Rear serial port +5 Vdc source enable

Figure 2.13 on page 2.18 shows the positions of the main board jumpers. The main board jumpers are in two locations. The password disable jumper and circuit breaker control jumper are at the front of the main board. The serial port jumpers are near the rear-panel serial ports; each serial port jumper is directly in front of the serial port that it controls.

Password and Circuit Breaker Jumpers

You can access the password disable jumper and circuit breaker control jumper without removing the main board from the relay cabinet. Remove the SEL-421 Relay front cover to view these jumpers (use appropriate ESD precautions). The password and circuit breaker jumpers are on jumper header J18 on the front of the main board, located immediately left of Power connector J17 (see *Figure 2.13*).

The J18 header is denoted A, B, C, and D from right to left (position A is on the right). Position B is the password disable jumper; position C is the circuit breaker control enable jumper. Positions A and D are not used. *Figure 2.14 on page 2.19* shows the jumper header with the circuit breaker/control jumper in the ON position and the password jumper in the OFF position; these are the normal jumper positions for an in-service relay. *Table 2.3 on page 2.19* lists the J18 jumper positions and functions.

CAUTION: Do not install a jumper on positions A or D of the main board J18 header. Relay misoperation can result if you install jumpers on positions J18A and J18D.

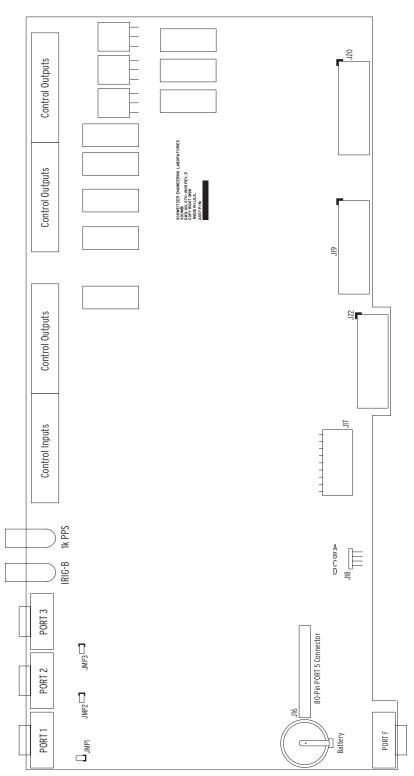


Figure 2.13 Major Component Locations on the SEL-421 Relay Main Board.

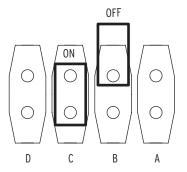


Figure 2.14 J18 Header–Password and Breaker Jumpers.

Table 2.3 Main Board Jumpers^a

Jumper	Jumper Location	Jumper Position	Function
J18A	Front	OFF	For SEL use only
J18B	Front	OFF	Enable password protection (normal and shipped position)
		ON	Disable password protection (temporary or emergency only)
J18C	Front	OFF	Disable control outputs (shipped position)
		ON	Enable control outputs, including circuit breaker CLOSE and OPEN (normal position)
J18D	Front	OFF	For SEL use only

^a ON is the jumper shorting both pins of the jumper. Place the jumper over one pin only for OFF.

The password disable jumper, J18B, is for temporary or emergency suspension of the relay password protection mechanisms. Under no circumstance should you install J18B on a long-term basis. The SEL-421 Relay ships with password disable jumper J18B OFF (passwords enabled). For temporary unprotected access to a particular access level, use the **PAS** *n* **DISABLE** command (*n* is the access level: n = 1, B, P, A, O, 2). For more information on this command and setting passwords, see *Passwords on page U.4.10 in the User's Guide*.

The circuit breaker control enable jumper, Jumper J18C, supervises the *CLOSE n* command, the *OPEN n* command, the *PULSE OUTnnn* command, and front-panel local bit control. To use these functions you must install jumper J18C. The relay checks the status of the circuit breaker control jumper when you issue **CLOSE n**, **OPEN n**, **PULSE OUTnnn**, and when you use the front panel to close or open circuit breakers, control a local bit, or pulse an output. Jumper J18C is usually installed on a long-term basis after you have completed relay commissioning and installation tests. The SEL-421 Relay ships with circuit breaker jumper J18C to ON for proper control output operation.

Serial Port Jumpers

Place jumpers on the main board to connect +5 Vdc to Pin 1 of each of the three rear-panel EIA-232 serial ports. The maximum current available from this Pin 1 source is 0.5 A. The Pin 1 source is useful for powering an external modem. *Table 2.4 on page 2.20* describes the JMP1, JMP2, and JMP3

positions. Refer to *Figure 2.13 on page 2.18* for the locations of these jumpers. The SEL-421 Relay ships with JMP1, JMP2, and JMP3 OFF (no +5 Vdc on Pin 1).

Table 2.4 Main Board Jumpers–JMP1, JMP2, and JMP3^a

Jumper	Jumper Location	Jumper Position	Function
JMP1	Rear	OFF	Serial Port 1, Pin 1 = not connected
		ON	Serial Port 1, Pin $1 = +5$ Vdc
JMP2	Rear	OFF	Serial Port 2, Pin 1 = not connected
		ON	Serial Port 2, Pin $1 = +5$ Vdc
JMP3	Rear	OFF	Serial Port 3, Pin 1 = not connected
		ON	Serial Port 3, Pin $1 = +5$ Vdc

^a ON is the jumper shorting both pins of the jumper. Place the jumper over one pin only for OFF.

Changing Serial Port Jumpers

You must remove the main board to access the serial port jumpers. To change the JMP1, JMP2, and JMP3 jumpers in an SEL-421 Relay, perform the following steps:

- Step 1. Remove the relay from service. Follow your company standard for removing a relay from service. Disconnect power from the SEL-421 Relay. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect the power cable, interface board cable(s), and input board analog cable from the main board (the top board).
- Step 4. Remove the screw terminal connectors. Loosen the attachment screws at each end of the 100-addresses screw terminal connectors. Pull straight back to remove.
- Step 5. Remove rear-panel EIA-232 Ports mating connectors. Unscrew the keeper screws and disconnect any serial cables connected to the Port 1, Port 2, and Port 3 rear-panel receptacles.
- Step 6. Carefully pull out the drawout assembly containing the main board.
- Step 7. Locate the jumper you want to change. Jumpers JMP1, JMP2, and JMP3 are located at the rear of the main board, directly in front of Port 1, Port 2, and Port 3, respectively (see *Figure 2.13* on page 2.18).
- Step 8. Install or remove the jumper as needed. See *Table 2.4* for jumper position descriptions.
- Step 9. Reinstall the SEL-421 Relay main board, and reconnect power, interface board cable(s) and the input board analog cable.
- Step 10. Reattach rear-panel connections. Affix the screw terminal connectors to the appropriate 100-addresses locations on the rear panel. Reconnect any serial cables that you removed in the disassembly process to the EIA-232 Ports.
- Step 11. Reattach the front panel.

DANGER: Contact with instrument terminals can cause electrical shock that can result in injury or death.

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service. Step 12. Follow your company standard procedure to return the relay to service.

I/O Interface Board Jumpers

Jumpers on the I/O interface boards identify the particular I/O board configuration and I/O board control address. Three I/O interface boards are available: INT1, INT5, and INT6 (see *I/O Interface Boards on page 2.12* for more information on these boards). The jumpers on these I/O interface boards are at the front of each board, as shown in *Figure 2.15 on page 2.22*, *Figure 2.16 on page 2.23*, and *Figure 2.17 on page 2.24*.

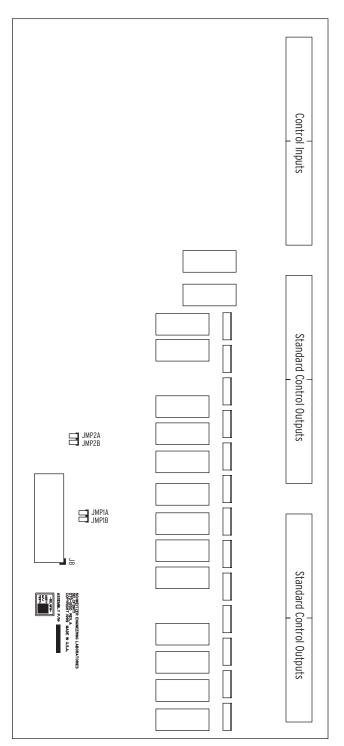


Figure 2.15 Major Component Locations on the SEL-421 Relay INT1 I/O Board.

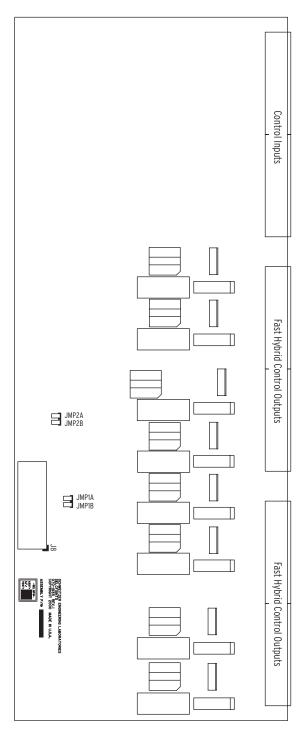


Figure 2.16 Major Component Locations on the SEL-421 Relay INT5 I/O Board.

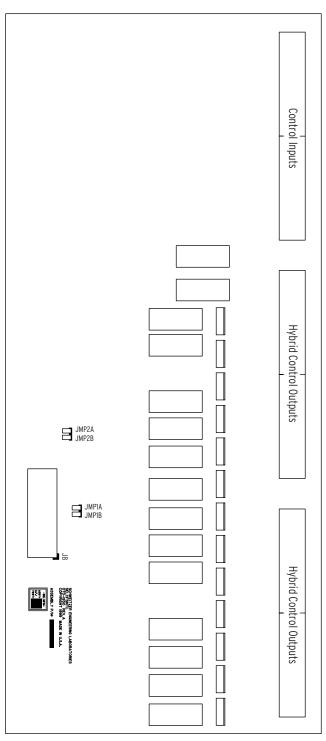


Figure 2.17 Major Component Locations on the SEL-421 Relay INT6 I/O Board.

To confirm the positions of your I/O board jumpers, you can remove the front panel and inspect the jumper placements visually. *Table 2.5 on page 2.25* lists the four jumper positions for I/O interface boards. Refer to *Figure 2.15 on page 2.22*, *Figure 2.16 on page 2.23*, and *Figure 2.17 on page 2.24* for the locations of these jumpers.

The I/O board control address has a hundreds-series prefix attached to the control inputs and control outputs for that particular I/O board chassis slot. A 4U chassis has a 200-addresses slot for inputs IN201, IN202, etc., and outputs OUT201, OUT202, etc. A 5U chassis has a 200-addresses slot and a 300-addresses slot. The drawout tray on which each I/O board is mounted is keyed. See *Installing Optional I/O Interface Boards on page 2.13* for information on the key positions for the 200-addresses slot trays and the 300-addresses slot trays.

Table 2.5	I/O Board	Jumpers
-----------	-----------	---------

I/O Board Control Address	JMP1A	JMP1B	JMP2A	JMP2B
2XX	OFF	OFF	OFF	OFF
3XX	ON	OFF	ON	OFF

Changing I/O Interface Board Jumpers

Change the I/O interface board jumpers only when you move the slot position of an I/O board. You must remove the I/O interface boards to access the jumpers. To change JMP1A, JMP1B, JMP2A, and JMP2B on an SEL-421 Relay I/O interface board, perform the following steps:

- Step 1. Remove the relay from service. Follow your company standard for SEL-421 for removing a relay from service. Disconnect power from the SEL-421 Relay. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect the interface board cable from the main board (the top board).
- Step 4. Pull out the drawout assembly containing the I/O interface board.
- Step 5. Locate the jumper you want to change. Jumpers JMP1A, JMP1B, JMP2A, and JMP2B are located at the front of the I/O board to the left and right of the interface board connector (see *Figure 2.15 on page 2.22, Figure 2.16 on page 2.23*, and *Figure 2.17 on page 2.24*).
- Step 6. Install or remove the jumper as needed. See *Table 2.5* for jumper position descriptions.
- Step 7. Reinstall the SEL-421 Relay I/O interface board, and reconnect the interface board cable.
- Step 8. Reattach the front panel.
- Step 9. Follow your company standard procedure to return the relay to service.
- Step 10. At relay power-up, confirm that the relay does not display a Status Warning about I/O board addresses. For information on this Status Warning, see *Relay Self-Tests on page U.6.37 in the User's Guide*.

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

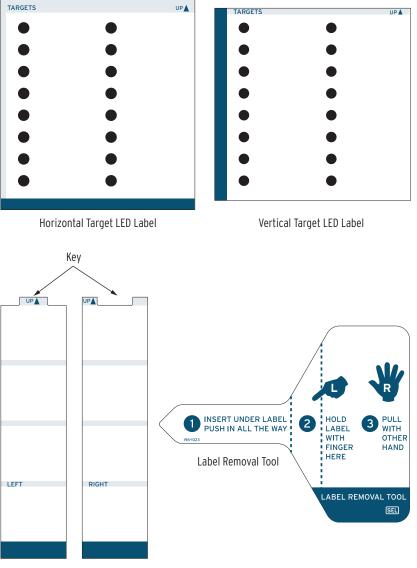
WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

Front-Panel Labels

The SEL-421 Relay features a versatile front panel that you can customize for your needs. Use SELOGIC control equations and slide-in configurable front-panel labels to change the function and identification of target LEDs and operator control pushbuttons and LEDs. Horizontal and vertical relay configurations have slide-in labels as shown in *Figure 2.1 on page 2.4* and *Figure 2.2 on page 2.4*.

The blank slide-in label set, shown in *Figure 2.18*, is included with the SEL-421 Relay. The Operator Control Labels and front-panel pockets are keyed for left and right placement corresponding to the left and right operator control pushbuttons and LEDs.



Operator Control Labels

Figure 2.18 Blank Slide-In Label Set and Label Removal Tool.

If you need additional configurable front-panel label supplies, order the horizontal labels kit or the vertical labels kit in *Table 2.6*. The table lists the part numbers of each kit component as an aid for determining which Part

Number 926000x kit to order. Contact your Technical Service Center or the SEL factory to obtain these kits (see *Factory Assistance on page 6.43 in Section 6: Testing and Troubleshooting*).

Content Descriptions	Quantity	Part Number
SEL-421 Relay Labels Kit—Horizontal	One	9260004
Blank Customer Label Templates on perforated paper for laser printing; horizontal	Five	196-1009
Blank slide-in label sets for labeling by hand (use only a fine point permanent marker); horizontal	Two sets—three labels for each set	196-1008
Label Removal Tool	One	196-1023
SEL-421 Relay Labels Kit—Vertical	One	9260005
Blank Customer Label Templates on perforated paper for laser printing; vertical	Five	196-1022
Blank slide-in label sets for labeling by hand (use only a fine point permanent marker); vertical	Two sets—three labels for each set	196-1021
Label Removal Tool	One	196-1023

Table 2.6 Configurable Front-Panel Label Kits

Included with the relay is the Label Removal Tool, also shown in *Figure 2.18* on page 2.26. Use this tool to remove labels from the front-panel pockets. Use the procedure in the following steps to remove a slide-in front-panel label:

- Step 1. Push the existing label all the way inside the label pocket.
- Step 2. Slide the tip of the tool under the label at the label pocket opening (see *Figure 2.1 on page 2.4* for opening locations).
- Step 3. Push the exposed, bottom edge of the label against the Label Removal Tool while pulling out the combined label and Label Removal Tool to extract the label. For the Target LED Label, slide the Label Removal Tool from side to side to extract the label.

There are four options for producing custom labels for the SEL-421 Relay front panel:

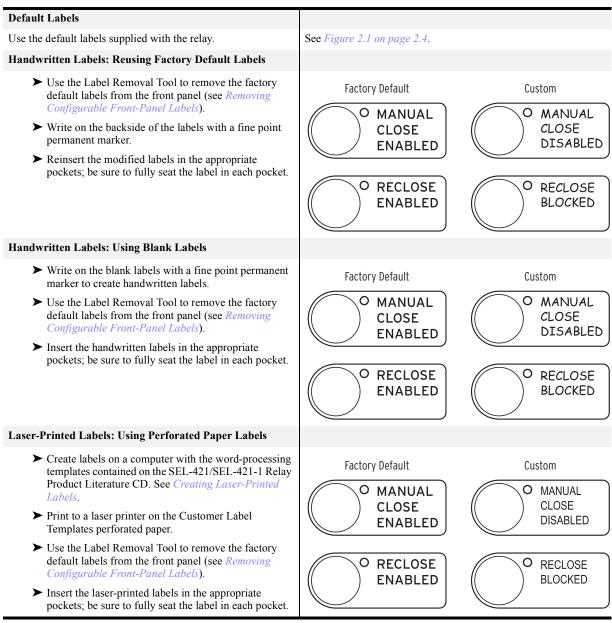
- ► Use factory default labels
- Use handwritten labels on factory default labels
- Use handwritten labels on blank labels
- ► Use laser-printed labels on perforated paper labels

Table 2.7 on page 2.28 illustrates each option. The Operator Control Label examples in *Table 2.7 on page 2.28* show a common application for configurable front-panel labels: changing from factory default "enabled" functions to custom "disabled/blocked" functions. *Table 2.7 on page 2.28* shows just one possibility; you can program front-panel pushbutton/LED functions to any relay-supported control or monitoring function. Check any label change against relay programming to confirm that the new label and relay functioning match.

Removing Configurable Front-Panel Labels

Changing Configurable Front-Panel Labels

NOTE: The SEL-421 Relay ships with factory default labels and settings. To change the front-panel factory default labels, you must examine and perhaps modify relay settings. Verify that any customized Target LED and Operator Control Label matches relay programming.



Creating Laser-Printed Labels

NOTE: The template is a Word 2000 file. The default template font is Arial Narrow. You can use this font or choose a different font that is available on your computer system.

The purpose of this procedure is to create laser-printed configurable front-panel labels on blank Customer Label Templates (supplied). These steps are for both the horizontal and the vertical versions of the relay.

The source for label template files and test sheet files is the SEL-421/SEL-421-1 Relay Product Literature CD. In addition, you can find these files on the SEL website; visit www.selinc.com.

Step 1. Open Microsoft[®] Windows[®] Explorer and find the Microsoft Word label template files (421_Horizontal.dot and 421_Vertical.dot) in the Customer Label Template folder on the SEL-421/SEL-421-1 Relay Product Literature CD. In the Word program, use the Tools > Options > File Locations menu to locate the "User templates" folder on your computer; note the directory path to this folder. Open another Windows Explorer window and navigate to the Templates folder noted earlier. Copy the template files from the SEL-421/SEL-421-1 Relay Product Literature CD (in the first Explorer window) to the Templates folder on your computer (in the second Explorer window).

- Step 2. In Microsoft Word use the File > New menu to access the 421_Horizontal.dot or 421_Vertical.dot files from your storage drive. Choose the template file that matches the layout you want to use (see *Figure 2.18 on page 2.26*). Double-click on the template file you have chosen to open a copy of that file. Make sure you can see table gridlines. Toggle the Table > Hide Gridlines menu item to see the template gridlines.
- Step 3. Save the document with a new file name.
- Step 4. Edit the template document placing LED and pushbutton labels in appropriate positions on the blank Customer Label Template. Fill in the fields (use the tab and arrow keys, or the mouse to move from field to field). Field space is limited; only text displayed on the screen prints on the label. Save the file often to preserve your work in progress.

Use the identification fields at the top of the Target LED Label and in four positions between pushbutton labels to mark the relay that corresponds with the label set.

- Step 5. Complete all necessary entries and save the file.
- Step 6. Create test sheets for a test print. Print test sheets from Adobe[®] Acrobat[®] or Acrobat Reader[®] (the Reader is included on the SEL-421/SEL-421-1 Relay Product Literature CD).

Use the Acrobat File > Open menu to access the Customer Label Template folder on the SEL-421/SEL-421-1 Relay Product Literature CD. Open the test sheet file that corresponds to your relay (either 421_Horizontal_TestSheet.pdf or 421_Vertical_TestSheet.pdf). When printing, be sure that "Fit to Page" is not checked.

- Step 7. Print on the test sheet. Position the test sheet properly in the printer. Print the labels from Microsoft Word to the printer.
- Step 8. Examine the printed test sheet (the identification fields are good indicators of printed text alignment on the test sheet). Printer drivers differ greatly resulting in label position discrepancies from the positioning shown on your screen. Make minor adjustments as necessary to print in the proper location on the test sheet. To make these adjustments, change margin settings as follows:
 - Use the Tools > Unprotect Document to unlock/unprotect the document
 - Use the File > Page Setup menu to adjust the top or left margins as needed to correct the alignment
 - ► Do a test print on the test sheets
 - ► Examine the label position

When the printed label alignment is correct, save the document.

NOTE: If you want to adjust the font size, use the procedure in Step 8 to Unprotect the document.

NOTE: If your printer has duplex capability, be sure to set the printer to print single sided.

NOTE: DO NOT "Protect" the document afterwards, because the Protect function automatically deletes your labels contained in field data. Step 9. When the labels print correctly on the test sheets, print the labels on the perforated stock sheets.

If the labels are incorrect, repeat this procedure beginning with *Step 4 on page 2.29*.

- Step 10. Fold and tear the perforated edges of the stock paper to remove the labels from the sheet.
- Step 11. Use the Label Removal Tool to remove existing labels from front-panel label pockets and insert the created labels in the appropriate pockets on the relay front panel. (*Figure 2.18 on page 2.26* shows the Label Removal Tool.)
- Step 12. To change the labeling again, remove existing labels and repeat the above procedure.

Relay Placement

	Proper placement of the SEL-421 Relay helps make certain that you receive years of trouble-free power system protection. Use the following guidelines for proper physical installation of the SEL-421 Relay.
Physical Location	You can mount the SEL-421 Relay in a sheltered indoor environment (a building or an enclosed cabinet) that does not exceed the temperature and humidity ratings for the relay. The relay is IEC EN61010-1 rated at Installation/Overvoltage Category II and Pollution Degree 2. This rating allows mounting the relay indoors or in an outdoor (extended) enclosure where the relay is protected against exposure to direct sunlight, precipitation, and full wind pressure, but neither temperature nor humidity are controlled.
	You can place the relay in extreme temperature and humidity locations. The temperature range over which the relay operates is -40° to $+185^{\circ}$ F (-40° to $+85^{\circ}$ C, see <i>Operating Temperature on page U.1.11 in the User's Guide</i>). The relay operates in a humidity range from 5 percent to 95 percent, no condensation. For EN61010 certification, the SEL-421 Relay rating is 2000 m (6560 feet) above mean sea level.
Rack Mounting	When mounting in a rack, use the reversible front flanges to either semiflush- mount or projection mount the relay. The semiflush mount gives a small panel protrusion from the relay rack rails of approximately 1.1 in. or 27.9 mm. The projection mount places the front panel approximately 3.5 in. or 88.9 mm in front of the relay rack rails. See <i>Figure 2.19 on page 2.32</i> for exact mounting dimensions for both the horizontal and vertical rack-mount relays. Use four screws of the appropriate size for your rack.

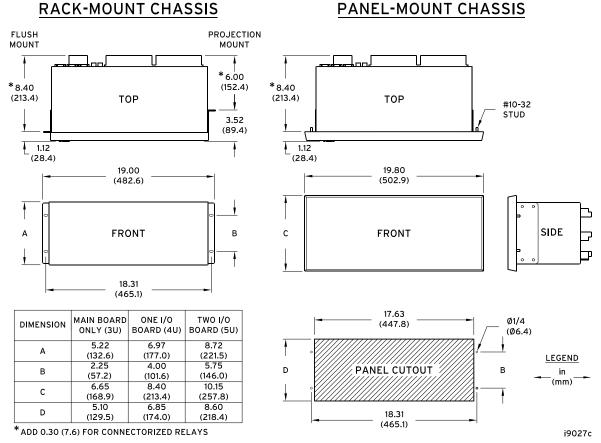


Figure 2.19 SEL-421 Relay Chassis Dimensions.

Panel Mounting

Place the panel-mount versions of the SEL-421 Relay in a switchboard panel. See the drawings in *Figure 2.19* for panel cut and drill dimensions (these dimensions apply to both the horizontal and vertical panel-mount relay versions). Use the supplied mounting hardware to attach the relay.

Connection

CAUTION: Insufficiently rated insulation can deteriorate under abnormal operating conditions and cause equipment damage. For external circuits, use wiring of sufficiently rated insulation that will not break down under abnormal operating conditions. The SEL-421 Relay is available in many different configurations depending on the number and type of control inputs, control outputs, and analog input termination you specified at ordering. This subsection presents a representative sample of relay rear-panel configurations and the connections to these rear panels. Only horizontal chassis are shown; rear panels of vertical chassis are identical to horizontal chassis rear panels for each of the 3U, 4U, and 5U sizes.

When connecting the SEL-421 Relay, refer to your company plan for wire routing and wire management. Be sure to use wire that is appropriate for your installation with an insulation rating of at least 90°C.

Rear-Panel Layout

Figure 2.20 on page 2.33, Figure 2.21, Figure 2.22, and Figure 2.23 on page 2.34, and Figure 2.24 on page 2.35 show some of the available SEL-421 Relay rear panels. All relay versions have screw terminal connectors for I/O, power, and battery monitor. You can order the relay with fixed terminal blocks for the CT and PT connections, or you can order SEL Connectorized rearpanel configurations that feature plug-in/plug-out PT connectors and shorting CT connectors for relay analog inputs. *Figure 2.21 on page 2.34* shows the Connectorized 3U horizontal configuration of the SEL-421 Relay. For clarity, the figures do not show a communications card installed in PORT 5.

The screw terminal connections for the INT1 and the INT6 I/O interface boards are the same. The INT5 I/O interface board has control output terminals grouped in threes, with the fourth terminal as a blank additional separator (terminals 4, 8, 12, 16, 20, 24, 28, and 32). For more information on the main board control inputs and control outputs, see *Main Board I/O on page 2.9*. For more information on the I/O interface board control inputs and control outputs, see *I/O Interface Board Jumpers on page 2.21*.

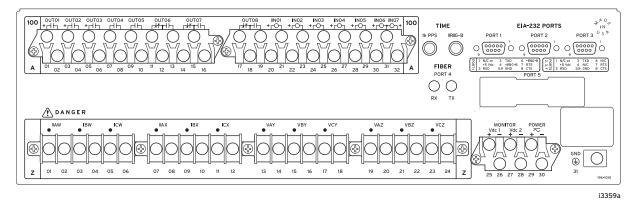


Figure 2.20 3U Rear Panel, SEL-421 Relay.

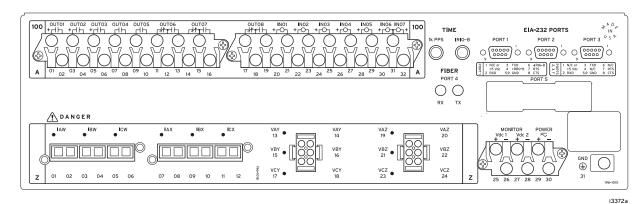


Figure 2.21 3U Rear Panel, Connectorized SEL-421 Relay.

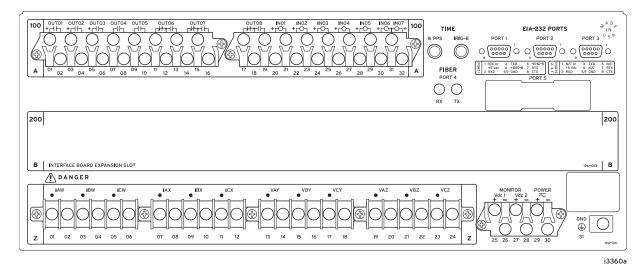


Figure 2.22 4U Rear Panel, Without Optional I/O, SEL-421 Relay.

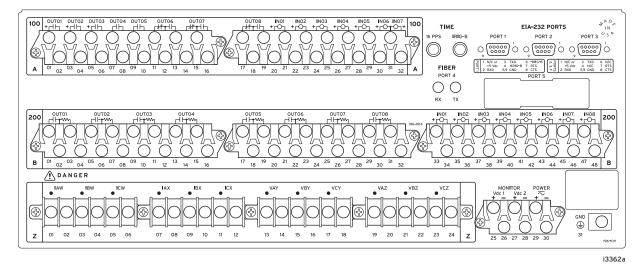


Figure 2.23 4U Rear Panel, INT5 I/O Interface Board, SEL-421 Relay.

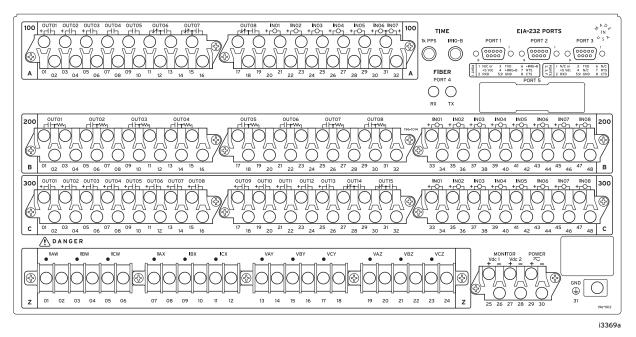


Figure 2.24 5U Rear Panel, INT5 and INT1/INT6 I/O Interface Board, SEL-421 Relay. (The INT5 board is the 200-addresses slot; the INT1/INT6 board is the 300-addresses slot.)

Rear-Panel Symbols

There are important safety symbols on the rear of the SEL-421 Relay (see *Figure 2.25*). Observe proper safety precautions when you connect the relay at terminals marked by these symbols. In particular, the danger symbol located on the rear panel corresponds to the following: *Contact with instrument terminals can cause electrical shock that can result in injury or death*. Be careful to limit access to these terminals.

Grounding Terminal

Symbol

GND

DC Input Symbol

Figure 2.25 Rear-Panel Symbols.

Danger Symbol

Terminate connections to the SEL-421 Relay screw terminal connectors with ring-type crimp lugs. Use a #8 ring lug with a maximum width of 0.360 in. (9.1 mm). The screws in the rear-panel screw terminal connectors are #8-32 binding head, slotted, nickel-plated brass screws. Tightening torque for the terminal connector screws is 9 in-lb. to 18 in-lb. (1.0 Nm to 2.0 Nm).

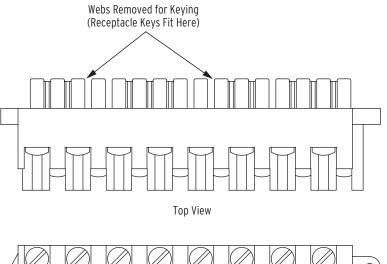
You can remove the screw terminal connectors from the rear of the SEL-421 Relay by unscrewing the screws at each end of the connector block. Remove the connector by pulling the connector block straight out. Note that the receptacle on the relay circuit board is keyed; you can insert each screw terminal connector in only one location on the rear panel. To replace the screw terminal connector, confirm that you have the correct connector, push the connector firmly onto the circuit board receptacle, and reattach the two screws at each end of the block.

Screw Terminal Connectors

Changing Screw Terminal Connector Keying

You can rotate a screw terminal connector so that the connector wire dress position is the reverse of the factory-installed position (for example, wires entering the relay panel from below instead of from above). In addition, you can move similar function screw terminal connectors to other locations on the rear panel. To move these connectors to other locations, you must change the screw terminal connector keying.

Inserts in the circuit board receptacles key the receptacles for only one screw terminal connector in one orientation. Each screw terminal connector has a missing web into which the key fits (see *Figure 2.26*). If you want to move a screw terminal connector to another circuit board receptacle or reverse the connector orientation, you must rearrange the receptacle keys to match the screw terminal connector block. Use long-nosed pliers to move the keys. *Figure 2.27 on page 2.37* shows the factory default key positions.





Front View

Figure 2.26 Screw Terminal Connector Keying.

Grounding

You must connect the grounding terminal (#Z31) labeled "GND" on the rear panel to a rack frame ground or main station ground for proper safety and performance. This protective earthing terminal is in the lower right side of the relay panel (see *Figure 2.20*, *Figure 2.21*, *Figure 2.22*, and *Figure 2.23 on page 2.34*, and *Figure 2.24 on page 2.35*). The symbol that indicates the grounding terminal is shown in *Figure 2.25 on page 2.35*. Use 12 AWG (4 mm²) or heavier wire less than 6.6 feet (2 m) in length for this connection. This terminal connects directly to the internal chassis ground of the SEL-421 Relay.

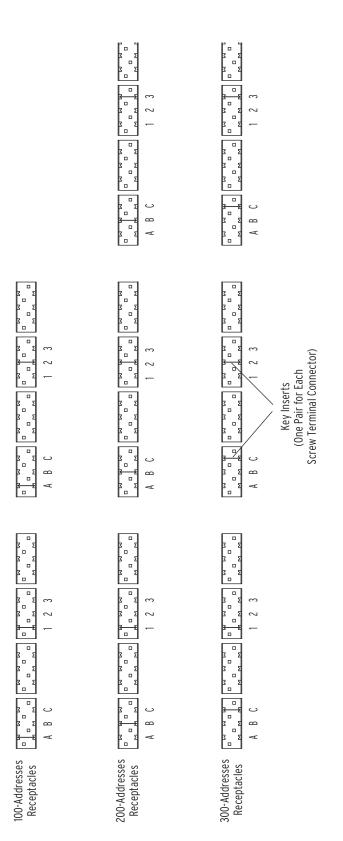


Figure 2.27 Rear-Panel Receptacle Keying, SEL-421 Relay.

Power Connections

NOTE: The combined voltages applied to the POWER and MONITOR terminals must not exceed 600 V (rms or dc). The terminals labeled POWER on the rear panel (#Z29 and #Z30) must connect to a power source that matches the power supply characteristics that your SEL-421 Relay specifies on the rear-panel serial number label. (See *Power Supply on page U.1.11 in the User's Guide*, for complete power input specifications.) For the relay models that accept dc input, the serial number label specifies dc with the symbol shown in *Figure 2.25 on page 2.35*.

The POWER terminals are isolated from chassis ground. Use 16 AWG (1.5 mm²) size or heavier wire to connect to the POWER terminals. Connection to external power must comply with IEC 947-1 and IEC 947-3.

Place an external switch, circuit breaker, or overcurrent device in the POWER leads for the SEL-421 Relay; this device must interrupt both the hot (H) and neutral (N) power leads. The maximum current rating for the power disconnect circuit breaker or overcurrent device (fuse) must be 20 A. Be sure to locate this device within 9.8 feet (3.0 m) of the relay.

Operational power is internally fused by power supply fuse F1. *Table 2.8* lists the SEL-421 Relay power supply fuse requirements. Be sure to use fuses that comply with IEC 127-2.

You can order the SEL-421 Relay with one of three operational power input ranges listed in *Table 2.8*. Each of the three supply voltage ranges represents a power supply ordering option. As noted in *Table 2.8*, model numbers for the relay with these power supplies begin 04210*n*, where *n* is 2, 4, or 6, to indicate low, middle, and high voltage input power supplies, respectively. Note that each power supply range covers two widely used nominal input voltages. The SEL-421 Relay power supply operates from 30 Hz to 120 Hz when ac power is used for the POWER input.

Nominal Power Supply Voltage Rating	Power Supply Voltage Range	Fuse F1	Fuse Description	Model Number
24/48 V	18-60 Vdc	T6.3A H250V	5x20 mm, time-lag, 6.3 A, high break capacity, 250 V	042102
48/125 V	38–140 Vdc or 85–140 Vac (30–120 Hz)	T3.15A H250V	5x20 mm, time-lag, 3.15 A, high break capacity, 250 V	042104
125/250 V	85–300 Vdc or 85–264 Vac (30–120 Hz)	T3.15A H250V	5x20 mm, time-lag, 3.15 A, high break capacity, 250 V	042106

 Table 2.8
 Fuse Requirements for the SEL-421 Relay Power Supply

The SEL-421 Relay accepts dc power input for all three power supply models. The 48/125 Vdc supply also accepts 120 Vac; the 125/250 Vdc supply also accepts 120/240 Vac. When connecting a dc power source, you must connect the source with the proper polarity, as indicated by the + (terminal #Z29) and – (terminal #Z30) symbols on the power terminals. When connecting an ac power source, the + terminal #Z29 is hot (H), and the – terminal #Z30 is neutral (N).

Each model of the SEL-421 Relay internal power supply exhibits low power consumption and a wide input voltage tolerance. For more information on the power supplies, see *Power Supply on page U.1.11 in the User's Guide*.

Power Supply Fuse Replacement

You can replace a bad fuse in an SEL-421 Relay power supply, or you can return the SEL-421 Relay to SEL for fuse replacement. If you decide to replace the fuse, perform the following steps to replace the power supply fuse:

- Remove the relay from service. Follow your company standard for removing a relay from service. Disconnect power from the SEL-421 Relay. Remove the relay from the rack or panel. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect the interface board cable(s) from the main board (the top board) and the I/O interface board(s).
- Step 4. Disconnect the power, input board analog cable, and interface board cable(s) from the main board.
- Step 5. Remove the screw terminal connectors. Loosen the attachment screws at each end of the 100-addresses, 200-addresses, and 300-addresses screw terminal connectors. Pull straight back to remove.
- Step 6. Remove rear-panel EIA-232 Ports mating connectors. Unscrew the keeper screws and disconnect any serial cables connected to the Port 1, Port 2, and Port 3 rear-panel receptacles.
- Step 7. Pull out the drawout tray containing the I/O interface board(s).
- Step 8. Pull out the drawout tray containing the main board.
- Step 9. Remove the top chassis plate by unscrewing seven screws from the chassis.
- Step 10. Locate the power supply. Fuse F1 is at the rear of the power supply circuit board. See *Figure 2.28 on page 2.40*. Examine the power supply for blackened parts or other damage. If you can see obvious damage, reinstall all boards and contact SEL to arrange return of the relay for repair.
- Step 11. Remove the spent fuse from the fuse clips. Replace the fuse with an exact replacement. See *Table 2.8 on page 2.38* for the proper fuse for your power supply.
- Step 12. Replace the chassis top on the relay and secure it with seven screws.
- Step 13. Reinstall the SEL-421 Relay main board, and the I/O interface board(s).
- Step 14. Reattach the power cable, the interface board cable(s), and the input board analog cable.
- Step 15. Reattach rear-panel connections. Affix the screw terminal connectors to the appropriate 100-addresses, 200-addresses, and 300-addresses locations on the rear panel. Reconnect any serial cables that you removed in the disassembly process to the EIA-232 Ports.
- Step 16. Reattach the front panel.
- Step 17. Follow your company standard procedure to return the relay to service.

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

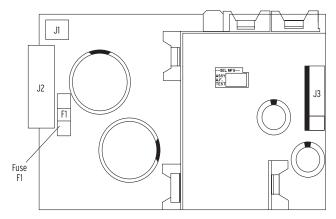


Figure 2.28 PS30 Power Supply Fuse Location.

The SEL-421 Relay monitors two dc battery systems. For information on the battery monitoring function, see *Station DC Battery System Monitor on page A.2.22 in the Applications Handbook*. Connect the positive lead of Battery System 1 to Terminal #Z25 and the negative lead of Battery System 1 to Terminal #Z26. (Usually Battery System 1 is also connected to the rearpanel POWER input terminals.) For Battery System 2, connect the positive lead to Terminal #Z27, and the negative lead to Terminal #Z28.

The SEL-421 Relay has two sets of three-phase current inputs and two sets of three-phase voltage inputs. *Shared Configuration Attributes on page 2.2* describes these inputs in detail. The alert symbol and the word DANGER on the rear panel indicate that you should use all safety precautions when connecting secondary circuits to these terminals.

To verify these connections, use SEL-421 Relay metering (See *Examining Metering Quantities on page U.4.31 in the User's Guide*). You can also review metering data in an event report that results when you issue the **TRIGGER** command (see *Triggering Data Captures and Event Reports on page A.3.4 in the Applications Handbook*).

Fixed Terminal Blocks

Connect the secondary circuits to the Z terminal blocks on the relay rear panel. Note the polarity dots above the odd-numbered terminals #Z01, #Z03, #Z05, #Z07, #Z09, and #Z11 for CT inputs. Similar polarity dots are above the odd-numbered terminals #Z13, #Z15, #Z17, #Z19, #Z21, and #Z23 for PT inputs.

Connectorized

For the Connectorized SEL-421 Relay, you must order the wiring harness kit, SEL-WA0421. The wiring harness contains four prewired connectors for the relay current and voltage inputs. You can order the wiring harness with various wire sizes and lengths. Contact your local Technical Service Center or the SEL factory for ordering information.

Plug the CT shorting connectors into terminals #Z01 through #Z06 for the IW inputs, and #Z07 through #Z12 for the IX inputs, as appropriate. Odd-numbered terminals are the polarity terminals. Secure the connector to the relay chassis with the two screws located on each end of the connector. When you remove the CT shorting connector, pull straight away from the relay rear

Monitor Connections (DC Battery)

NOTE: The combined voltages applied to the POWER and MONITOR terminals must not exceed 600 V (rms or dc).

Secondary Circuit Connections

DANGER: Contact with instrument terminals can cause electrical shock that can result in injury or death.

CAUTION: Relay misoperation can result from applying other than specified secondary voltages and currents. Before making any secondary circuit connections, check the nominal voltage and nominal current specified on the rear-panel nameplate. panel. As you remove the connector, internal mechanisms within the connector separately short each power system current transformer. You can install these connectors in only one orientation.

Plug the PT voltage connectors into terminals #Z13 to #Z18 for the VY inputs, and #Z19 to #Z24 for the VZ inputs, as appropriate. Odd numbered terminals are the polarity terminals. You can install these connectors in only one orientation.

You can configure the SEL-421 Relay with many combinations of control inputs and control outputs. See *Main Board I/O on page 2.9* and *I/O Interface Boards on page 2.12* for information about I/O configurations. This subsection provides details about connecting these control inputs and outputs. Refer to *Figure 2.3 on page 2.5, Figure 2.10 on page 2.12*, and *Figure 2.11 on page 2.12* for representative rear-panel screw terminal connector locations.

Control Inputs

NOTE: The combined voltages applied to the INnnn and OUTnnn terminals must not exceed 600 V (rms or dc).

Control Circuit

Connections

The control input connections on the rear-panel I/O screw terminal connectors are polarity sensitive. A + indication appears over each pair of control inputs. Connect the positive sense of the control input to the + terminal. Although you cannot damage these inputs with a reverse polarity connection, a reverse polarity connection will cause the relay internal A/D converter to measure the input voltage incorrectly and the relay will no longer detect input changes. See *Control Inputs on page 2.6* for more information.

Note that the main board I/O control inputs have one set of two inputs that share a common input leg. These inputs are IN106 and IN107 found on terminals #A30, #A31, and #A32.

To assign the functions of the control inputs, see *Operating the Relay Inputs* and *Outputs on page U.4.52 in the User's Guide*, or the **SET G** command in *SET on page R.8.38 in the Reference Manual* for more details. You can also use the ACSELERATOR Software to set and verify operation of the inputs.

Control Outputs

The SEL-421 Relay has three types of outputs:

- ► Standard outputs (example: main board OUT104)
- Hybrid (high-current-interrupting) outputs (example: main board OUT101)
- ► Fast Hybrid (fast high-current-interrupting) outputs (example: INT5 board OUT201, or OUT301)

See Control Outputs on page 2.6 for more information.

You can connect the Standard outputs and the Fast Hybrid (fast high-currentinterrupting) outputs in either ac or dc circuits. Connect the Hybrid (highcurrent-interrupting) outputs to dc circuits only. The screw terminal connector legends alert you about this requirement by showing polarity marks on the Hybrid (high-current-interrupting) contacts.

Form A (SPST NO) contacts comprise the majority of the control outputs. Two pairs of Form C (DPST CO) contacts are on the main board, the INT1 I/O interface board, and the INT6 I/O interface board. The INT5 I/O interface board features high-speed operation capability using Fast Hybrid control outputs. To limit the false pickup indications with digital inputs and light duty high-speed auxiliary relays, precharging resistors are available on the screw terminal connector for each pair of control output contacts. See *Fast Hybrid (Fast High-Current-Interrupting) Control Outputs on page 2.8* for further information, and *Figure 2.8 on page 2.9* and *Figure 2.9 on page 2.9* for resistor connection details.

Alarm Output

The SEL-421 Relay monitors internal processes and hardware in continual self-tests. If the relay senses an out-of-tolerance condition, the relay declares a Status Warning or a Status Failure. The relay signals a Status Warning by pulsing the HALARM Relay Word bit (hardware alarm) to a logical 1 for five seconds. For a Status Failure, the relay latches the HALARM Relay Word bit at logical 1.

To provide remote alarm status indication, connect the 'b' contact of OUT108 to your control system remote alarm input. *Figure 2.29* shows the configuration of the 'a' and 'b' contacts of control output OUT108.

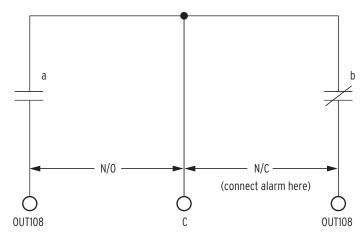


Figure 2.29 Control Output OUT108.

Program OUT108 to respond to NOT HALARM by entering the following SELOGIC[®] control equation with a communications terminal, with the ACSELERATOR software, or by using the front-panel LCD and navigation pushbuttons:

OUT108 := NOT HALARM

When the relay is operating normally, the NOT HALARM signal is at logical 1 and the 'b' contacts of control output OUT108 are open. When a Status Warning condition occurs, the relay pulses the NOT HALARM signal to logical 0 and the 'b' contacts of OUT108 close momentarily to indicate an alarm condition. For a Status Failure, the relay disables all control outputs and the OUT108 'b' contacts close to trigger an alarm. Also, when relay power is off, the OUT108 'b' contacts close to generate a power-off alarm. See *Relay Self-Tests on page U.6.37 in the User's Guide* for information on relay self-tests.

The relay pulses the SALARM Relay Word bit for software programmed conditions; these include settings changes, access level changes, and alarming after three unsuccessful password entry attempts. You can add the software alarm SALARM to the alarm output by entering the following SELOGIC control equation:

OUT108 := NOT (HALARM OR SALARM)

Tripping and Closing Outputs

To assign the control outputs for tripping and closing, see *Setting Outputs for Tripping and Closing on page U.4.57 in the User's Guide*. In addition, you can use the **SET O** command; see *SET on page R.8.38 in the Reference Manual*, for more details. You can also use the front panel to set and verify operation of the outputs. See *SET/SHOW on page U.5.21 in the User's Guide*.

TIME Input Connections

IRIG-B Input Connection

The SEL-421 Relay accepts a demodulated IRIG-B signal through two types of rear-panel connectors. These IRIG-B inputs are through the BNC connector labeled TIME IRIG-B or through Pin 4 (+) and Pin 6 (-) of the rear-panel 9-pin D-subminiature connector PORT 1. See *Communications Ports Connections on page 2.44* for other DE-9 connector pinouts and additional details. These inputs accept the dc shift time code generator output (demodulated) IRIG-B signal with positive edge on the time mark. For more information on IRIG-B and the SEL-421 Relay, see *TIME Inputs on page 2.10*.

The BNC IRIG-B input and the PORT 1 IRIG-B input circuit connect to a 330 Ω resistor in series with an optocoupler input diode. The optocoupler input diode forward voltage drop is about 1.5 V. Driver circuits should source approximately 10 mA through the circuit for the ON state. When using the PORT 1 input, ensure that you connect Pins 4 and 6 with the proper polarity.

For ease of connection or for long runs from the IRIG-B generator to the SEL-421 Relay, use the BNC IRIG-B input. Connect a 50 Ω coaxial cable assembly with a male BNC connector to the IRIG-B input of the SEL-421 Relay and the other end of the coaxial cable to the GPS receiver or other IRIG-B generation equipment.

Where distance between the SEL-421 Relay and the IRIG-B sending device exceeds the cable length recommended for conventional EIA-232 metallic conductor cables, you can use transceivers to provide isolation and to establish communication to remote locations. Conventional fiber-optic and telephone modems do not support IRIG-B signal transmission. Use the SEL-2810 transceiver to provide long distance delivery of the IRIG-B signal to the SEL-421 Relay. The SEL-2810 includes a channel for the IRIG-B time code. These transceivers enable you to synchronize time precisely from IRIG-B time code generators (such as the SEL-2020 Communications Processor) over a fiber-optic communications link.

Replacing the Lithium Battery

DANGER: Disconnect or de-energize all external connections before opening this device. Contact with hazardous voltages and currents inside this device can cause electrical shock resulting in injury or death.

WARNING: Have only qualified personnel service this equipment. If you are not qualified to service this equipment, you can injure yourself or others, or cause equipment damage.

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipment. If your facility is not equipment. If your facility is not equipment to work with these components, contact SEL about returning this device and related SEL equipment for service.

CAUTION: There is danger of explosion if the battery is incorrectly replaced. Replace only with Ray-O-Vac® no. BR2335 or equivalent recommended by manufacturer. Dispose of used batteries according to the manufacturer's instructions.

Communications Ports Connections

1k PPS Input Connection

The SEL-421 Relay accepts a 1k PPS (or 1000 PPS) input from a GPS receiver/time source through the rear-panel BNC jack labeled 1k PPS. (For PPS mode, you must also supply a locked IRIG-B input.) For more information on 1k PPS and the SEL-421 Relay, see *TIME Inputs on page 2.10*.

The 1k PPS port input impedance is 50 Ω . Use a BNC cable assembly to connect the 1k PPS signal from the GPS receiver/time source to the rear-panel BNC jack labeled 1k PPS. Typical input levels are approximately 2.5 Vdc into 50 Ω (open circuit 0–5 Vdc). See *Time Inputs on page U.1.11 in the User's Guide* for complete 1k PPS input specifications. For high-accuracy timing applications, be sure to match the lengths and propagation delays of the coaxial cables carrying the IRIG-B and 1k PPS signals to the SEL-421 Relay inputs.

You can replace a bad lithium battery in the SEL-421 Relay. Perform the following steps to replace the lithium battery.

- Remove the relay from service. Follow your company standard procedure for removing a relay from service. Disconnect power from the SEL-421 Relay. Remove the relay from the rack or panel. Retain the GND connection, if possible, and ground the equipment to an ESD mat.
- Step 2. Remove the front panel from the SEL-421 Relay.
- Step 3. Disconnect power, interface board cable(s), and input board analog cable from the main board.
- Step 4. Pull out the drawout tray containing the main board.
- Step 5. Locate the lithium battery. The lithium battery is at the front of the main board. See *Figure 2.13 on page 2.18*.
- Step 6. Remove the spent battery from beneath the clip of the battery holder. Replace the battery with an exact replacement. Use a 3 V lithium coin cell, Ray-O-Vac[®] No. BR2335 or equivalent. The positive side (+) of the battery faces up.
- Step 7. Reinstall the SEL-421 Relay main board drawout tray.
- Step 8. Reattach the power cable, interface board cable(s), and input board analog cable.
- Step 9. Reattach the front panel
- Step 10. Set the relay date and time via the communications ports or front panel (See *Making Simple Settings Changes on page U.4.15 in the User's Guide*).
- Step 11. Follow your company standard procedure to return the relay to service.

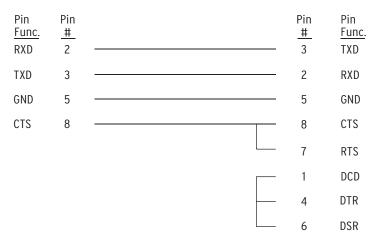
The SEL-421 Relay has three rear-panel EIA-232 serial communications ports labeled PORT 1, PORT 2, and PORT 3 and one front-panel port, PORT F. For information on serial communications, see *Establishing Communication on page U.4.5 in the User's Guide, Serial Communication on page R.4.3 in the Reference Manual*, and *Serial Port Hardware Protocol on page R.5.2 in the Reference Manual*.

In addition, the rear panel features a PORT 5 for an optional communications card. For additional information about communications topologies and standard protocols that are available in the SEL-421 Relay, see Section 6: SEL-2030 Applications in the Applications Handbook, Section 7: Direct Network Communication in the Application Handbook, the Section 6: DNP 3.0 Communications in the Reference Manual, and the Section 7: UCA2 Communications in the Reference Manual.

Serial Ports

The SEL-421 Relay serial communications ports use EIA-232 standard signal levels in a D-subminiature 9-pin connector. To establish communication between the relay and a DTE device (a computer terminal, for example) with a D-subminiature 9-pin connector, use an SEL Cable C234A. See *Section 4: Basic Relay Operations in the User's Guide*.

Figure 2.30 shows the configuration of SEL Cable C234A that you can use for basic ASCII and binary communication with the relay. A properly configured ASCII terminal, terminal emulation program, or the ACSELERATOR software along with the C234A cable provide communication with the relay in most cases. See *Section 4: Communications Interfaces in the Reference Manual* for a list of hardware interfaces to the SEL-421 Relay.



*DTE = Data Terminal Equipment (Computer, Terminal, etc.)



Serial Cables

CAUTION: Severe power and ground problems can occur on the communications ports of this equipment as a result of using non-SEL cables. Never use Standard nullmodem cables with this equipment.

Using an improper cable can cause numerous problems or failure to operate, so you must be sure to specify the proper cable for application of your SEL-421 Relay. Several standard SEL communications cables are available for use with the relay. See *EIA-232 Communications Cables on page R.4.4 in the Reference Manual* for information on recommended serial cables.

The following list provides additional rules and practices you should follow for successful communication using EIA-232 serial communications devices and cables:

Route communications cables well away from power and control circuits. Switching spikes and surges in power and control circuits can cause noise in the communications circuits if power and control circuits are not adequately separated from communications cables.

- You should keep the length of the communications cables as short as possible to minimize communications circuit interference and also to minimize the magnitude of hazardous ground potential differences that can develop during abnormal power system conditions.
- ► EIA-232 communications cable lengths should never exceed 50 feet, and you should always use shielded cables for communications circuit lengths greater than 10 feet.
- Modems provide communication over long distances and give isolation from ground potential differences that are present between device locations. (Examples are the SEL-28XX-series transceivers.)
- Lower data speed communication is less susceptible to interference and will transmit greater distances over the same medium than higher data speeds. You should use the lowest data speed that provides an adequate data transfer rate.

AC/DC Connection Diagrams

You can apply the SEL-421 Relay in many power system protection schemes. *Figure 2.31 on page 2.48* shows one particular application scheme with connections that represent typical interfaces to the relay for a single circuit breaker connection. *Figure 2.32 on page 2.49* depicts typical connections for a dual circuit breaker protection scheme.

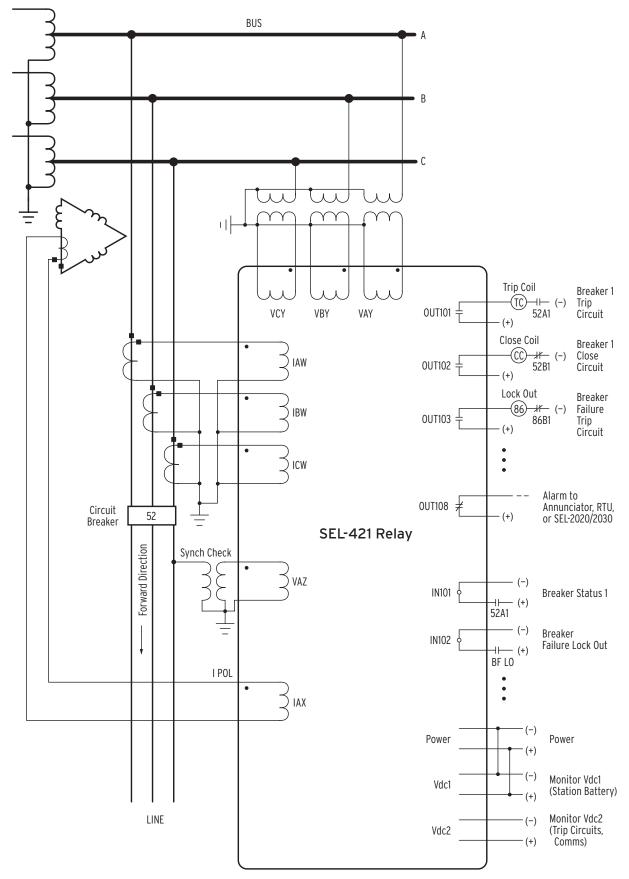


Figure 2.31 Typical External AC/DC Connections-Single Circuit Breaker.

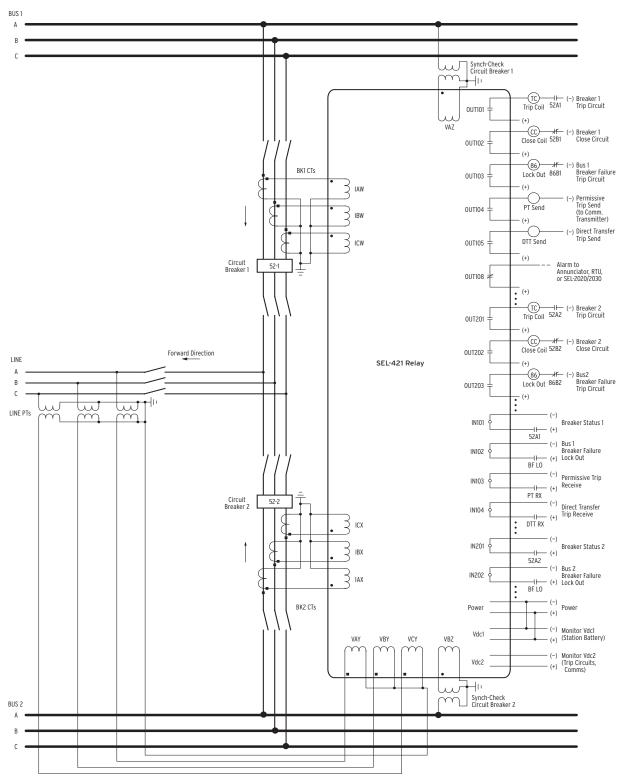


Figure 2.32 Typical External AC/DC Connections-Dual Circuit Breaker.

This page intentionally left blank

Section 3 PC Software

The SEL-421 Relay includes a powerful relay settings, analysis, and measurement tool to aid you in applying and using the relay; this tool is the SEL-5030 ACSELERATOR[®] Software Program. The ACSELERATOR software reduces engineering costs for relay settings, logic programming, and system analysis. The ACSELERATOR software makes it easier for you to do the following:

- Create and manage relay settings
 - ➤ Create settings for one or more SEL-421 Relays
 - Store and retrieve settings with an IBM-compatible PC (personal computer)
 - Upload and download relay settings files to and from SEL-421 Relays
- ► Analyze events
 - Use the integrated waveform and harmonic analysis tools
- ► Monitor real-time and relay-stored power system data
 - Use the HMI (human machine interface) to view metering, Relay Word bits, and circuit breaker monitor data
- ► Control the relay
 - Command relay operation through use of a GUI (graphical user interface) environment
 - > Execute relay serial port commands in terminal mode
- ► Configure the serial port and passwords

SEL provides the ACSELERATOR software for easier, more efficient configuration of relay settings, metering, and control. However, you do not have to use the ACSELERATOR software to configure the SEL-421 Relay; you can continue to use an ASCII terminal or a computer running terminal emulation software to access all relay settings and metering. The ACSELERATOR software gives you the advantages of rules-based settings checks, SELOGIC[®] control equation Expression Builder, operator control and metering HMI, and event analysis.

Installing the Computer Software

Load the ACSELERATOR software on an IBM-compatible PC. If you encounter any difficulties installing the ACSELERATOR software, contact your Technical Service Center or the SEL factory for assistance. See *Factory Assistance on page U.6.43 in the User's Guide* for contact information.

System Requirements

To successfully install and use the ACSELERATOR software, your computer must have the minimum resources listed in *Table 3.1*.

Item	Description
Processor	Pentium [®] class, \geq 90 MHz
Operating System / RAM	Microsoft [®] Windows [®] 95/98/ME–64 MB RAM Microsoft Windows 2000–64 MB RAM Microsoft Windows NT [®] –32 MB RAM (64 MB recom- mended)
Hard drive	At least 25 MB available storage space
Communications Port	One EIA-232 serial port or one Ethernet port (SEL-2701 Ethernet Processor installed in the relay)
Drives	CD-ROM for software installation
Monitor	SVGA 800 x 600 pixel resolution or greater (1024 x 768 pixel resolution recommended)
Pointing Device	Mouse or other pointing device

Table 3.1 System Requirements for ACSELERATOR Software

Installation

You can load the ACSELERATOR software automatically if your computer autorun feature is enabled; this is Method A. If autorun is not enabled on your computer, use the Windows Run command to load the ACSELERATOR software; this is Method B.

Perform the following steps to install the ACSELERATOR software:

- Step 1. Load the ACSELERATOR software using one of the following methods:
 - Method A. Load the ACSELERATOR software automatically. To load the software automatically, turn on your PC and run the Windows operating environment. Close all other applications on your PC. Place the ACSELERATOR CD-ROM in the PC CD-ROM drive. The setup software should run automatically and the SEL Software License Agreement will appear as in *Figure 3.1*.



Figure 3.1 SEL Software License Agreement.

Method B. Use the Windows Run command to load the ACSELERATOR software. If the Setup program does not start automatically, use the Microsoft Windows Run function (in the Start menu) to load the ACSELERATOR software. Type the command shown in *Figure 3.2*, being certain to use the correct drive letter for the CD-ROM drive in your PC (the CD-ROM drive in the *Figure 3.2* example is drive D). You should see the SEL Software License Agreement (*Figure 3.1*).

Run	? X
	Type the name of a program, folder, or document, and Windows will open it for you.
<u>O</u> pen:	D:\SETUP.EXE
	Run in Separate Memory Space
	OK Cancel <u>B</u> rowse

Figure 3.2 Windows Run Command Line to Load the ACSELERATOR Software.

Step 2. Complete the software loading process. Read the Software License Agreement and follow the loading instructions as these instructions appear on the PC screen.

You can use the Windows Start menu to open the ACSELERATOR software. If you installed the ACSELERATOR software to the Program Manager group, click the Start button and point to Programs. Point to SEL Applications and click ACSELERATOR. If you used a custom program group, click the Start button and click ACSELERATOR in the custom group.

You can also create a shortcut on the Windows Desktop. See your Windows documentation for instructions on creating a shortcut. Double-click the shortcut icon to start the ACSELERATOR software from the shortcut.

Starting the ACSELERATOR Software

Communications Setup

The ACSELERATOR software uses the relay communications ports to communicate with the SEL-421 Relay. Configure the ACSELERATOR Communication menu Parameters settings to communicate effectively with the relay. You can also use a basic terminal emulation any time you run the ACSELERATOR software. Use the Communication menu to view and clear a Connection Log. For a step-by-step procedure using the ACSELERATOR software to communicate with the relay, see *Checking Relay Status:* ACSELERATOR Software on page U.4.12 in the User's Guide.

Communication Parameters

Use the Communication Parameters dialog box to configure relay communications settings. Select the Communication menu on the top ACSELERATOR toolbar and click Parameters to open this dialog box. *Figure 3.3* shows the ACSELERATOR Communication Parameters dialog box.

Communication Parameters			×
Device Direct to COM1 Phone Number	Data Speed O 300 O 1200 O 2400	 ○ 4800 ○ 9600 ○ 19200 	© 38400 © 57600
Level One Password (Serial & Telnet) xxxxxx Level Two Password (Serial & Telnet) xxxxx	Data Bits © 8 © 7	Stop Bits C 2 C 1	Parity None Odd Even
Use Network Network Perame	sters		
	<u>0</u> K	<u>C</u> ancel	<u>H</u> elp

Figure 3.3 ACSELERATOR Communication Parameters Dialog Box.

Serial Setup

You can use serial communication via relay Ports 1, 2, 3, and F (front panel). *Figure 3.3* shows the default serial port parameters (9600, 8, N, 1). Enter your relay Access Level One and Access Level Two passwords in the respective text boxes. (For complete information on passwords, see *Changing the Default Passwords: Terminal on page U.4.10 in the User's Guide.*) If you choose a device from the Device text box that is a telephone modem, enter the dial-up telephone number in the Phone Number text box.

FTP Setup

Click the Use Network check box to access the Network Parameters. *Figure 3.4* shows the Network Parameters dialog box. For FTP (File Transfer Protocol) use Telnet Port number 23.

When you connect to a relay to use FTP, you must specify the access level and password. Provide the access level command (ACC, 2AC, for example) in the User ID text box and the corresponding access level password in the Password text box to control the relay at a specific access level. See *Changing the Default Passwords: Terminal on page U.4.10 in the User's Guide.*

Connection Name Pullman Substation		
Host IP Address	User ID	File Transfer Options
172.16.112.123	2AC	
Telnet Port Number 23	Password ****	C Telnet
Save to Address Book	<u>A</u> ddress Boo	k

Figure 3.4 ACSELERATOR Network Parameters Dialog Box: FTP.

Telnet Setup

Click the Telnet option button in the Network Parameters dialog box (see *Figure 3.5*) to connect to a relay for a Telnet session. The Telnet session uses the relay passwords on the Communication Parameters dialog box (*Figure 3.3*). The default Telnet Port Number for accessing the relay is T1PNUM := 23. The default Telnet Port Number for communicating directly with the SEL-2701 Ethernet Processor is T2PNUM := 1024. See Section 7: Direct Network Communication in the Application Handbook for information on changing the Telnet Port Number.

Pullman Substation		-
Host IP Address	User ID	File Transfer Options
172.16.112.123	2AC	O FTP
Felnet Port Number	Password	 Telnet
23	*****	
Save to Address Boo	ok Address Bool	k

Figure 3.5 ACSELERATOR Network Parameters Dialog Box: Telnet.

Terminal ModeThe terminal window is an ASCII interface between you and the relay. This is
a basic terminal emulation with no file transfer capabilities. Many third-party
terminal emulation programs are available with file transfer encoding
schemes.Click the Communication menu and then click Terminal to start the terminal

Terminal Logging When you check t

When you check the Terminal Logging item in the Communication menu, the ACSELERATOR software records communications events and errors in a log. Click Communication > Connection Log to view the log. Clear the log by selecting Communication > Clear Connection Log.

window. Another convenient method to start the terminal is to type <Ctrl+T>.

Settings Database Management and Drivers

Database Manager

The ACSELERATOR software uses a relay database to save relay settings. The ACSELERATOR software contains sets of all settings files for each relay that you specify in the Database Manager. See *Virtual File Interface on page R.5.14 in the Reference Manual* for a list of the settings file in the SEL-421 Relay. Choose appropriate storage backup methods and a secure location for storing your relay database files. Use the File > Active Database menu to retrieve a relay database from computer memory.

Relay Database

The default relay database file already configured in the ACSELERATOR software is Relay.rdb. This database contains example settings files for the SEL products with which you can use the ACSELERATOR software. Open the Database Manager to access the database. Click on File in the ACSELERATOR top toolbar, then select and click the Database Manager menu item. You will see the dialog box similar to *Figure 3.6*. You can enter descriptions for the database and for each relay in the database in the Database Description and Relay Description dialog boxes. Type in the Relay Description dialog box special operating characteristics that describe the relay settings. These can include the protection scheme settings and communications settings.

Open	<u>O</u> pen	Database Description
C:\\Relay.rdb Relays in Database	,	Relay.rdbCompany source database
Example SEL-351 Example SEL-351 Example SEL-351 Example SEL-351 Example SEL-351 Pullman Substatio	A 003 5 002 5 003	, Relay Description Pullman Substation SEL-421 Relay. POTT with Step Distance Backup, Load Encroachment, OOS, and CBF.
		Relay Operations
		Rename Copy Delete
		Relay Text Files
		Import Export

Figure 3.6 Database Manager Relay Database in the ACSELERATOR Software.

Highlight one of the relays listed in Relays in Database and select the Copy option button to create a new collection of relay settings. The ACSELERATOR software prompts you to provide a new name. Be sure to enter a new description in Relay Description.

Copy/Move Relays Between Databases

You can create multiple relay databases with the Database Manager; these databases are useful for grouping similar protection schemes or geographic areas. Select the Copy/Move Relays Between Databases tab to access the dialog box shown in *Figure 3.7*. Click the Open B option button to open a relay database. Type a filename and click open; for example, Relay2.rdb is the B relay database in *Figure 3.7*.

Highlight a relay in the A database, select Copy or Move, and click the > button to create a new relay in the B database. Reverse this process to take relays from the B database to the A database. Copy creates an identical relay that appears in both databases. Move removes the relay from one database and places the relay in another database.

A Open C:\\Relay.rdb Relays in Datab			B Open C:\\Relay2.rdb Relays in Databa	
Example SEL: Example SEL: Example SEL: Example SEL: Example SEL: Pullman Subst	351A 003 351S 002 351S 003 421	∠ ≤ Copy C Moye	Pullman Substat	ion

Figure 3.7 Database Manager Copy/Move in the ACSELERATOR Software.

Create a New Database

To create and copy an existing database of relays to a new database, select the File > Database Manager menu and select the Copy / Move Relays Between Databases Tab on the Database Manager dialog box. The ACSELERATOR software opens the last active database and assigns it as Database A (see *Figure 3.7*). Click on the Open B button; the ACSELERATOR software prompts you for a file location. Type a new database name, click on the Open button, and answer Yes; the program creates a new empty database. Load relays into the new database as in Copy/Move Relays Between Databases. Drivers Relay settings folders in the ACSELERATOR software are closely associated with the ACSELERATOR software relay driver that you used to create the settings. The relay settings and the ACSELERATOR software drivers must match. Use the STATUS command to query the relay for the FID (firmware identification number) to determine the active ACSELERATOR drivers. Click the Status button in the HMI tree view to see the relay FID information. See Checking Relay Status on page U.4.12 in the User's Guide for information on viewing relay status. At a terminal (<Ctrl+T> from the ACSELERATOR software), you can type **ID**<**Enter**> to view the FID. Use the "Z-number" to determine the proper ACSELERATOR software relay settings driver version when creating or editing relay settings files. View the ACSELERATOR software settings driver information at the bottom of the Relay Editor window (see *Figure 3.14 on page 3.11*). The first portion of the Znumber is the ACSELERATOR software settings driver version number (see *Figure 3.8*). Compare the ACSELERATOR driver number and the relay FID number. This ACSELERATOR software driver Z-number and the corresponding part of the relay FID must match.

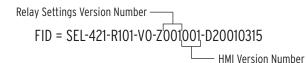


Figure 3.8 ACSELERATOR Software Driver Information in the FID String.

The ACSELERATOR software reads the latter portion of the Z-number (ZXXX001, for example) to determine the correct HMI to display when you select the HMI > Meter and Control menu. View the bottom of the HMI window to check the HMI driver number (see *Figure 3.9*).



Help /		
Device Overview Phasors Instantaneous	Status	
🗆 🔍 Demand/Peak	Relay 1	Date: O
Maximum/Minimum Energy	Station A	Serial
Targets . Status	FID=SEL-421-R101-V0-Z001001-D20010106	CID=0xe
SER	Failures	
Breaker 1 Monitor Data Breaker 2 Monitor Data Control Window	No Failures	
	Warnings	
	No Warnings	
	SELogic Relay Programming Environment Err No Errors	ors
	Relay Enabled	
	-	
Disable Update		

HMI Driver Version Number

Figure 3.9 HMI Driver Version Number in the HMI Window.

As SEL develops new drivers, you can update your existing ACSELERATOR software with specific relay drivers for each SEL product that uses the ACSELERATOR software. Contact your local Technical Service Center or the SEL factory for the latest ACSELERATOR software drivers.

Create and Manage Relay Settings

The ACSELERATOR software gives you the ability to create settings for one or more SEL-421 Relays. You can store existing relay settings downloaded from SEL-421 Relays with the ACSELERATOR software, creating a library of relay settings (see *Database Manager on page 3.6*). You can then modify and upload these settings from your settings library to an SEL-421 Relay.

The ACSELERATOR software makes setting the relay easy and efficient. For an example of setting the SEL-421 Relay with the ACSELERATOR software, see *Making Initial Global Settings: ACSELERATOR Software on page U.4.25 in the User's Guide.*

Collected Settings The ACSELERATOR software arranges relay settings in easy-to-understand categories (for an explanation of settings organization, see *Making Simple Settings Changes on page U.4.15 in the User's Guide*). These categories of collected settings help you quickly set the relay. *Figure 3.10* is an example of relay settings categories in the Relay Editor Settings tree view. (Use the procedures described in Settings Menu to view the tree views in *Figure 3.10*.)

The ACSELERATOR software shows all of the settings categories in the settings tree view. When you enable and disable settings categories, the tree view remains constant, but when you click on the tree view to access the settings in a disabled category, the disabled settings are dimmed. For example, select the Group $1 > \text{Set } 1 > \text{Relay Configuration branch of the Settings tree view and choose N for E50Q. Click on the Negative-Sequence O/C branch and observe that the Negative-Sequence Overcurrent Elements settings are dim. If you select 1 for E50Q, then only the level 1 overcurrent element settings are active and the remainder of the Negative-Sequence Overcurrent Element settings are dim.$ *Figure 3.10*illustrates this feature of the ACSELERATOR software.

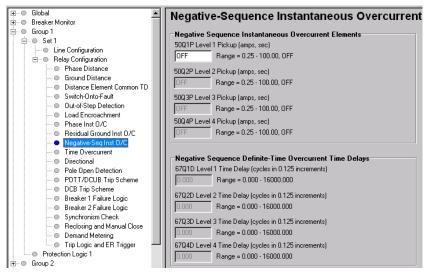


Figure 3.10 Sample Settings in the ACSELERATOR Software.

Settings Menu

The Settings menu on the top ACSELERATOR toolbar is the starting point for all settings entries. The menu items in the Settings menu are New, Open, and Read. All of these menu items open the Relay Editor (see *Relay Editor on page 3.11*).

New

Selecting the New menu item creates new relay settings files. The ACSELERATOR software makes the new settings files from the relay drivers that you specify in the Relay Editor Selection dialog box (see *Figure 3.11*). The ACSELERATOR software uses the Z-number in the relay FID string to create a particular version of relay settings (see *Drivers on page 3.7*).

elay Editor Selection	First 3 digits of Z number in FID String
SEL-351-6 SEL-351-7 SEL-351A SEL-351S-5 SEL-351S-6 SEL-351S-7 SEL-421	001
Relay Editor Information	
Name: SEL-421 001 Setting Version: 1.0.0.38	s Driver
Date: 3/12/01 2:45:20 PM	
Example FID String	OK Cancel

Figure 3.11 Selecting a Settings Driver in the ACSELERATOR Software.

After selecting the relay model and settings driver, the ACSELERATOR software presents the Relay Part Number dialog box. Use this dialog box to configure the Relay Editor to produce settings for a relay with options determined by the part number. See *Relay Part Number on page 3.11*.

Open

The Open menu item opens an existing relay from the active database folder (see *Figure 3.12*). The ACSELERATOR software prompts you for a folder containing relay settings to load into the Relay Editor.

Open Relay	×
Relays	
Example SEL-351-5-6-7 Example SEL-351A 003 Example SEL-351S 002 Example SEL-351S 003 Example SEL-421 Pullman Substation	
	OK
	Cancel

Figure 3.12 Opening Relay Settings in the ACSELERATOR Software.

Read

When you select the Read menu item, the ACSELERATOR software reads the relay settings from a connected relay. As the ACSELERATOR software reads the relay, you will see a dialog box similar to *Figure 3.13*. The ACSELERATOR software uses serial protocols at a serial port or FTP from an Ethernet port to read settings from SEL devices.

Transfer Status	
Reading 18 of 32	
Reading File: SETTINGS\SET_P1.TXT	
Reading	Cancel

Figure 3.13 Reading Relay Settings in the ACSELERATOR Software.

Relay Editor

Use the Relay Editor to enter relay settings. *Figure 3.14* illustrates the important features of the editor. These features include the ACSELERATOR software settings driver version number (the first three digits of the Z-number) in the lower left corner of the Relay Editor.

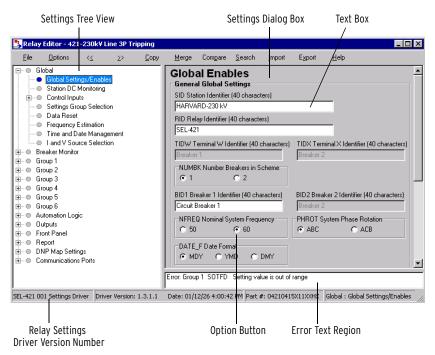


Figure 3.14 ACSELERATOR Software Relay Editor.

Entering Settings

	Click the + marks and the buttons in the Settings Tree View to expand and select the settings class, instance, and category that you want to change. Use Tab or click in a dialog box to edit a setting. The right-click mouse button performs two special functions when you are editing settings: Previous Value and Default Value. To restore the previous value for a setting, right click the mouse over the setting and select Previous Value. Right click in the setting dialog box and select Default Value if you want to restore the factory default setting value.
	If you enter a setting that is out of range or has an error, the ACSELERATOR software shows the error at the bottom of the Relay Editor. Double-click on the error listing to go to the setting to enter a valid input.
Relay Part Number	The relay part number determines the settings that the ACSELERATOR software displays and the functions that the software controls. When configuring the ACSELERATOR software to control a particular relay, you should confirm that the ACSELERATOR software part number matches the relay part number so that you can access all of the settings you need for your relay.

Configuring the Part Number

Select the Settings Menu on the ACSELERATOR top toolbar and click New, Open, or Read to start the Relay Editor; see *Settings Menu on page 3.9*. Once in the Relay Editor, click the Options menu on the Relay Editor toolbar (see *Figure 3.15*). Point to Part Number and click this option.



Figure 3.15 Retrieving the Relay Part Number.

You will see the Relay Part Number dialog box, as shown in *Figure 3.16*. Use the arrows inside the text boxes to match corresponding portions of the Relay Part Number dialog box to your relay.

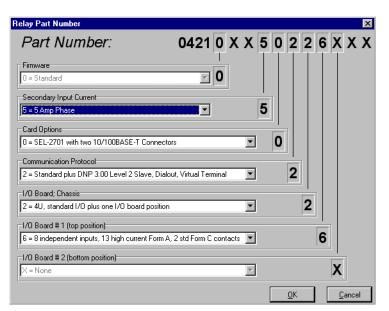


Figure 3.16 Setting the Relay Part Number in the ACSELERATOR Software.

Expression Builder

SELOGIC control equations are a powerful means for customizing relay performance. Creating these equations can be difficult, because of the large number of relay elements (Relay Word bits) and analog quantities in the relay. The ACSELERATOR software simplifies this process with the Expression Builder, a rules-based editor for programming SELOGIC control equations. The Expression Builder organizes relay elements, analog quantities, and SELOGIC control equation variables and focuses your equation decisionmaking. The Expression Builder checks basic rules and flags mistakes in SELOGIC control equation settings.

Settings dialog boxes in the Relay Editor window show an "EB" option button (see *Figure 3.17*). Click the EB option button to use the Expression Builder.

Global Global Global Global	Trip Logic and ER Trigger	
i≕ ● Group 1 i= ··· ● Set 1 i= ··· ● Line Configuration	TR Trip (SELOGIC) M1P OR Z1G OR M2PT OR Z2GT	EB
Relay Configuration Phase Distance Ground Distance	TRCOMM Communicaton Aided Trip (SELOGIC) [M2P OR Z2G) AND PLT02	EB
Switch-Onto-Fault	TRSOTF Switch-Onto-Fault Trip (SELOGIC) [50P1 OR M2P OR Z2G	EB
Phase Inst O/C Time Overcurrent Directional	DTA Direct Transfer Trip A-Phase (SELOGIC)	EB
Pole Open Detection POTT/DCUB Trip Scheme Reclosing and Manual Close	DTB Direct Transfer Trip B-Phase (SELOGIC) NA DTC Direct Transfer Trip C-Phase (SELOGIC)	EB
Trip Logic and ER Trigger Protection Logic 1		EB

Figure 3.17 Location of EB Option Button.

Expression The representation SELC

The Expression Builder dialog box is organized into two main parts representing the left side (LVALUE) and right side (RVALUE) of the SELOGIC control equation. (The LVALUE is fixed for all settings except Protection Free-Form SELOGIC and Automation Free Form SELOGIC settings; see *Fixed SELOGIC Control Equations on page R.3.5 in the Reference Manual.*) *Figure 3.18* shows the two sides of the Expression Builder, with the SELOGIC control equation that you are constructing at the top of the dialog box. Note the dark vertical line and the equals sign (:=) separating the equation left and right sides.

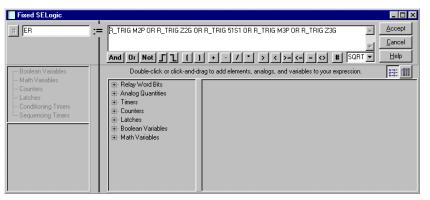


Figure 3.18 The ACSELERATOR Expression Builder.

Access the Expression Builder

Using the Expression Builder

For Protection Free-Form SELOGIC and Automation Free Form SELOGIC, select the type of result (LVALUE) for the SELOGIC control equation to use the Expression Builder. The ACSELERATOR software shows these possibilities in the file box directly underneath the left side of the equation. The program shows the relay elements for each type of SELOGIC control equation (Boolean Variables, Math Variables, etc.).

On the right side of the equation (RVALUE), you can select broad categories of relay elements, analog quantities, counters, timers, latches, Boolean variables, and math variables. Select a category in the RVALUE tree view, and the Expression Builder displays all elements for that category in the list box at the bottom right side.

Directly underneath the right side of the equation, you can choose operations to include in the RVALUE. These operations include basic logic functions, rising and falling edge triggers, expression compares, and math functions.

For more information on programming SELOGIC control equations, see *Section 3: SELOGIC[®] Control Equation Programming in the Reference Manual.*

Analyze Events

The ACSELERATOR software has integrated analysis tools that help you retrieve information about protection system operations quickly and easily. Use the protection system event information that the SEL-421 Relay stores to evaluate the performance of a protection system.

Event Waveforms

The SEL-421 Relay records power system events for all trip situations and for other operating conditions that you program with SELOGIC control equations (see *SELOGIC Control Equation ER on page A.3.4 in the Applications Handbook*). The relay provides two types of event data captures: high-resolution oscillography that uses raw sample per second data and event report oscillography that uses filtered sample per cycle data. See *Triggering Data Captures and Event Reports on page A.3.4 in the Applications Handbook* and *Generating an Event on page U.4.39 in the User's Guide* for information on recording events. Use the ACSELERATOR software to view high resolution and event report oscillograms, phasor diagrams, harmonic analyses, and settings.

Read History

You can retrieve event files stored in the relay and transfer these files to your computer. For information on the types of event files and data capture, see *Triggering Data Captures and Event Reports on page A.3.4 in the Applications Handbook.*

To download event files from the relay, open the ACSELERATOR software Analysis menu at the top ACSELERATOR toolbar and click Read History. The Relay Event History dialog box will appear (*Figure 3.19* is similar).

😫 Relay Event History	
Event History for SEL-421-R101-V0-Z001001-D20010315	
10002 03/29/2001 13:4023 186 600 _49:83 8:66 T 10001 03/15/2001 17:40:14.082.400 \$\$\$\$.\$\$ ER 10000 03/15/2001 13:37:17.173.000 \$\$\$\$.\$\$ TRIG	Event Options Event type CEV 4 samples/cyc Event length (cycles) 15 Get Event Irigger Eefresh Close
	<u>R</u> efresh

Figure 3.19 Retrieving Relay Event History.

Get Event

Highlight the event you want to view and click the Get Event button. The Event Type dialog box lists high resolution data files as Binary COMTRADE, and event report files (from Compressed ASCII format) as CEV 4 samples/ cyc or CEV 8 samples/cyc. When downloading is complete, the ACSELERATOR software prompts whether you want to save the file on your computer. (You can save the file for later analysis.) The ACSELERATOR software displays the Event Waveform dialog box and the event oscillogram (see *Figure 3.20* and *Figure 3.21*).

When viewing the event oscillogram, use keyboard function keys to measure the time of oscillogram occurrences. These function keys and related functions help in event analysis

- <**F2**>: go to trigger <**F3**>: Cursor 1
- <**F4**>: Cursor 2

The display shows the time difference between the **<F3>** and **<F4>** cursors.

You can see high-accuracy time-stamp information on the event oscillogram. Click the Pref button at the bottom of the oscillogram and select Time (under Time Units, Starting/Ending Row); click OK. Click on any point in a graph to observe the Event Time in microseconds of that data point at the bottom of the oscillogram.



Figure 3.20 ACSELERATOR Event Waveform Window.

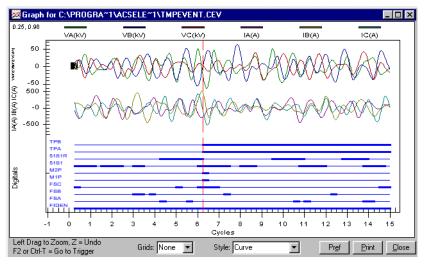


Figure 3.21 Sample Event Oscillogram.

You can also view other event displays. From the Event Waveform dialog box, select the View menu and click Phasors, as shown in *Figure 3.22*, to view a sample-by-sample phasor display. You should see a phasor display similar to *Figure 3.23*.

🖂 E	vent Waveform	×
Eile	View Botation	
	<u>S</u> ummary Data <u>G</u> raph Graph P <u>r</u> eferences	01-D20010223 49.26
Read	<u>P</u> hasors <u>E</u> vent Report Text <u>H</u> armonic Analysis	2:59 PM
	Settings	

Figure 3.22 Retrieving Event Report Waveforms.

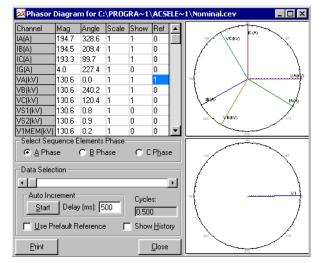


Figure 3.23 Sample Phasors Event Waveform Screen.

The ACSELERATOR software also presents a harmonic analysis of power system data for raw data binary COMTRADE event captures. From the Event Waveform View menu, click Harmonic Analysis. You will see a window similar to *Figure 3.24*. On the left side of the Harmonic Analysis screen, choose the relay voltage and current channels to monitor for harmonic content. You can view both a spectral analysis plot and a harmonic analysis bar chart. Click the arrows of the Data Scroll box or the # Cycles box to change the data analysis range.

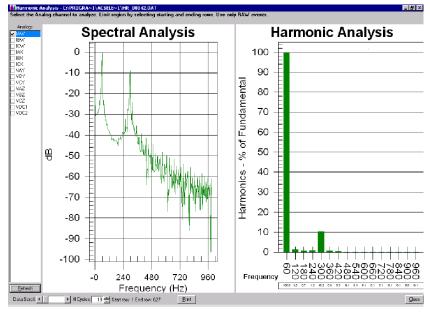


Figure 3.24 Sample Harmonic Analysis Event Waveform Screen.

Click Summary Data on the Event Waveform View menu to see event summary information and to confirm that you are viewing the correct event. *Figure 3.25* shows a sample ACSELERATOR software Event Report Summary screen.

iummary Data				
	Event Report	Summary		
Event Report File:	C:\PROGRA~1\ACSELE~1\	TmpEvent.cev		
Relay FID:	FID=SEL-421-R101-V0-Z001	001-D20010315		
Frequency:	60 # Cycles:	15	Samples/Cycle:	4
Event Date/Time:	Thursday, March 15, 2001	23:30:49.026		
Miscellaneous:	EVENT_NUM	10007		
	EVENT	BCG T		
	LOCATION	48.17		
	NFREQ	60		
	SER_NUM	20010012	234	
	PRIM_VAL	YES		
	CTR_IA	1.0		
	CTR_IB	1.0		-
		1		
			<u>P</u> rint	<u>C</u> lose

Figure 3.25 Sample Event Report Summary Screen.

Click Settings on the Event Waveform View menu to view the relay settings that were active at the time of the event. *Figure 3.26* shows a sample CEV-type event Settings screen.

🔀 Settin	gs from C:\PR	OGRAM FI	LESVACSELEI	RATOR\tmp	orpt.txt			'×
Group 1	L							
Line Co	onfiguration							
CTRW	:= 400	CTRX	:= 400	PTRY	:= 3636	VNOMY	:= 115	
PTRZ	:= 3636	VNOMZ	:= 115	ZIMAG	:= 4.72	ZIANG	:= 82.60	
ZOMAG	:= 14.50	ZOANG	:= 75.70	EFLOC	:= Y	LL	:= 100.00	
Relay (Configuratio	n						
E21P	:= 3	E21MG	:= 3	E21XG	:= N	ECVT	:= N	
ESERCME	? := N	ECDTD	:= N	ESOTF	:= N	EOOS	:= N	
ELOAD	:= N	E50P	:= N	E50G	:= N	E50Q	:= N	
E51S	:= N	E32	:= AUTO	ECOMM	:= N	EBFL1	:= N	
EBFL2	:= N	E25BK1	:= N	E25BK2	:= N	E79	:= N	
EMANCL	:= N	ELOP	:= N	EDEM	:= N	EADVS	:= N	
Mho Pha	ase Distance	Element	Reach					
Z1P	:= 3.78	Z2P	:= 5.78	Z3P	:= 1.87			

Figure 3.26 Sample Event Waveform Settings Screen.

Open File

Computer-stored data captures are available as COMTRADE files (*.DAT) or compressed event report files (*.CEV). Open the ACSELERATOR software Analysis menu and click Open File to view the waveforms in an event file stored on your computer. You should see the Event Waveform dialog box similar to *Figure 3.20 on page 3.16* and an oscillographic event screen similar to *Figure 3.21 on page 3.16*.

At the Event Waveform dialog box, you can select the Phasors display, the Harmonic Analysis display, the Summary Data display, and the Settings display from the Event Waveform window (see *Read History on page 3.15*).

HMI Meter and Control

Use the ACSELERATOR HMI feature to view real-time relay information in a graphical format. Use the virtual relay front panel to read metering and targets and to operate the relay.

Open the ACSELERATOR HMI

ACSELERATOR HMI Features On the HMI menu, click Meter and Control. The ACSELERATOR software opens the HMI window and downloads the interface data. See the detailed examples in *View Metering: ACSELERATOR Software on page U.4.34 in the User's Guide* for step-by-step instructions.

You can use the ACSELERATOR software to access many types of relay information and relay controls. Click the HMI menu at the top ACSELERATOR toolbar and then click Meter and Control to access the ACSELERATOR HMI. *Figure 3.27* shows the HMI tree view; *Table 3.2* lists the functions in the HMI tree view and a brief explanation of each function.

In the ACSELERATOR HMI, an LED representation shows that a color is asserted or "on." The flashing LED representation in the lower left of each HMI screen indicates an active data update via the communications channel. Click the button marked "Disable Update" to suspend HMI use of the communications channel.



Figure 3.27 ACSELERATOR HMI Features.

Function	Description
Device Overview	View general metering, selected targets, control input, control outputs, and the virtual front panel.
Phasors	A graphical and textual representation of phase and sequence voltage and current phasors.
Instantaneous	A table of instantaneous voltages, currents, powers, frequency, and dc monitor voltages.
Demand/Peak	A table showing demand and peak demand values. Reset but- tons are in this display.
Max/Min	A table showing maximum/minimum metering quantities. A reset button is in this display.
Energy	A table showing energy import/export. A reset button is in this display.
Targets	View selected Relay Word bits in a row/column format.
Status	A list of relay status conditions.
SER	Sequential Events Recorder data listed oldest to newest, top to bottom. Set the range of SER records with the dialog boxes at the bottom of the display.
Breaker Monitor Data	A table showing the latest circuit breaker monitor data.
Control Window	Metering and records reset buttons, trip and close control, out- put pulsing, target reset, time and date set, group switch, and remote bit control.

Table 3.2 ACSELERATOR HMI Tree View Functions

Section 4 Basic Relay Operations

The SEL-421 Relay is a powerful tool for power system protection and control. Understanding basic relay operation principles and methods will help you use the relay effectively. This section presents the fundamental knowledge you need to operate the SEL-421 Relay organized by task. These tasks help you become familiar with the relay and include the following:

- ► Inspecting a new relay
- ► Connecting and applying power
- ► Establishing communication
- ► Changing the default passwords
- ► Checking relay status
- ► Making simple settings changes
- ► Examining metering quantities
- Reading oscillograms, event reports, and the SER (Sequential Events Recorder)
- ► Operating the relay inputs and outputs
- ► Configuring high-accuracy timekeeping
- ► Readying the relay for field application

Perform these tasks to gain a good understanding of relay operation, be able to confirm that the relay is properly connected, and be more effective when using the relay.

Inspecting a New Relay

CAUTION: Do not connect power to the relay until you have completed these procedures and receive instruction to apply power. Otherwise, equipment damage can result.

The following items are included in your shipment from SEL:

- ► SEL-421 Relay
- ▶ Printed volume of the entire SEL-421 Relay User's Guide
- CD-ROM containing the electronic version of the entire SEL-421 Relay Manual and the Customer Label Templates
- CD-ROM containing the SEL-5030 ACSELERATOR[®] Software Program
- ► SEL Contact Card
- ► Configurable Front-Panel Label Kit

If any item is missing or damaged, please contact your distributor or SEL immediately.

Remove the protective wrapping from the SEL-421 Relay. Observe the outside of the front cover and the rear panel. Check that no significant scratches or dents are evident on any outer surface. Confirm that all terminal strips on the rear panel are secure.

Cleaning

Use care when cleaning the SEL-421 Relay. Use a mild soap or detergent solution and a damp cloth to clean the relay chassis. Allow the relay to air dry, or wipe dry with a soft dry cloth. Do not use abrasive materials or polishing compounds on any relay surface. Be careful cleaning the front and rear panels because a permanent plastic sheet covers each panel; do not use harsh chemical solvents such as xylene or acetone on these surfaces.

Verify Relay Configuration

Initial Inspection

When you first inspect the relay, confirm that the relay power supply voltage and nominal ac signal magnitudes are appropriate for your application. Examine the serial number label on the relay rear panel; *Figure 4.1* shows a sample rear-panel serial number label.

P/N 04210615012 S/N 2001001234			- Part Number - Serial Number
POWER SUPPLY Ratings: 125/250 120/230V 50/6 Ranges: 85-300V 85-264V 30-120	0Hz <120VA		Power Supply Input Specifications
VOLTS AC 300V Wye	AMPS AC 5/PH	J	
		— Secondar	y Current Input
		— Secondar	y Voltage Input

Figure 4.1 SEL-421 Relay Serial Number Label.

Figure 4.1 shows a serial number label for an SEL-421 Relay with standard I/O in a 3U horizontal chassis. This example serial number label is for a 5 A-per-phase secondary current transformer input relay. For information on CT and PT inputs, see *Secondary Circuits on page U.2.5 in the User's Guide*.

The power supply specification in *Figure 4.1* indicates that this relay is equipped with a power supply that accepts a nominal 125/250 Vdc input. This power supply also accepts a 120/230 Vac input. Other power supply options include nominal 24/48 Vdc, and 48/125 Vdc power supplies. The 48/125 Vdc power supply also accepts a 120 Vac input. Refer to the serial number label affixed to the back of your relay to determine the power supply voltage you should apply to the relay power supply input terminals. As this label indicates, the voltage source should be capable of providing at least 35 W for dc inputs and 120 VA for ac inputs. See *Power Supply on page U.1.11 in the User's Guide* for more information on power supply specifications.

The serial number label does not call out power system phase rotation and frequency ratings, because you can use relay settings to configure these parameters. The factory defaults are ABC phase rotation and 60 Hz nominal frequency. See *Making Settings Changes: Initial Global Settings on page 4.19* for details on setting these parameters.

The serial number label does not list a control input (logic input) level because the SEL-421 Relay uses an advanced A/D input converter circuit that accepts inputs over a wide range. For more information on control inputs, see *Control Inputs on page U.2.6 in the User's Guide*.

Connecting and Applying Power

Connect external power to the SEL-421 Relay to perform the initial checkout and familiarization procedures in this section. For complete information on power connections, see *Power Connections on page U.2.38 in the User's Guide. Figure 4.2* shows the portion of the relay rear panel where you connect the power input.

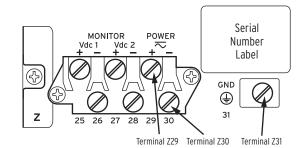


Figure 4.2 Power Connection Area of the Rear Panel.

Always attach a safety ground as the first connection you make to the SEL-421 Relay. You must connect the grounding terminal (#Z31) labeled "GND" on the rear panel to a rack frame ground or main station ground for proper safety and performance.

You can order the SEL-421 Relay with one of three power supplies with nominal operating voltages: 24/48 Vdc, 48/125 Vdc, and 125/250 Vdc. The two higher voltage supplies, 48/125 Vdc and 125/250 Vdc use ac input and dc input. The relay serial number label on the back of the relay lists voltage ranges that encompass the nominal voltages. *Table 4.1* shows the nominal voltage inputs and power supply voltage ranges for dc input, and ac inputs if applicable.

Table 4.1	Power	Supply	Voltage	Inputs
-----------	-------	--------	---------	--------

Nominal DC Voltage Input	DC Input Range	AC Input Range (30-120 Hz)
24/48 Vdc	18–60 Vdc <35 W	N/A
48/125 Vdc	38–140 Vdc <35 W	120 Vac <120 VA
125/250 Vdc	85–300 Vdc <35 W	120/230 Vac <120 VA

Use 16 AWG (1.5 mm²) wire (or heavier) to connect to the POWER terminals. When you use a dc power source, you must connect the source with the proper polarity, as indicated by the + (Terminal #Z29) and – (Terminal #Z30) symbols on the power terminals. You can use ac input for the 48/125 Vdc power supply and the 125/250 Vdc power supply. The relay operates from 30 to 120 Hz (nominal 50/60 Hz) when alternating current supplies the POWER input.

Upon connecting power, you will see information on the front-panel LCD (liquid crystal display) and the ENABLED LED (light-emitting diode) will light. For complete information on the SEL-421 Relay front panel, see *Section 5: Front-Panel Operations in the User's Guide*.

DANGER: Contact with instrument terminals can cause electrical shock that can result in injury or death.

Establishing Communication

Once you have applied the correct power input successfully, you are ready to operate the relay. Use the relay front panel and the communications ports to communicate with the relay.

Front-panel control of relay functions involves use of a menu system that you access through the LCD and the six navigational pushbuttons shown in *Figure 4.3*. For complete instructions on using the front-panel menu system, see *Navigating the Menus on page U.5.3 in the User's Guide*.

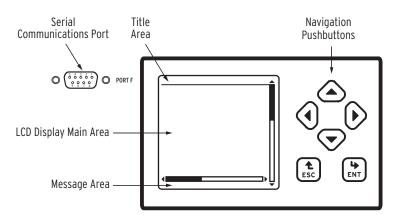


Figure 4.3 PORT F, LCD Display, and Navigation Pushbuttons.

Fast and efficient communication with the relay is available through communications ports such as PORT F, also shown in *Figure 4.3*. A design philosophy for all SEL relays is that an ASCII or open terminal is all that you need to communicate with the relay. Many "off-the-shelf" computer programs provide terminal emulation. These programs are inexpensive and widely available. Use the cable connections appropriate for your terminal configuration. See *Section 4: Communications Interfaces in the Reference Manual* for more information on communications ports.

All ASCII commands you send to the relay must terminate with a carriage return or carriage return/line feed; the terminal emulation program appends the necessary carriage return when you press Enter → on the computer keyboard. You can truncate commands to the first three characters: **EVENT 1** <**Enter>** becomes **EVE 1** <**Enter>**. Use upper- and lower-case characters without distinction, except in passwords, which are case sensitive. For a list of ASCII commands see *Section 8: ASCII Command Reference in the Reference Manual*.

When you are using a terminal, you can access built-in relay help for each ASCII command. Relay help is access-level sensitive; you see only the ASCII commands for the present access level when you type **HELP**<**Enter**>. For indepth information on a particular ASCII command, enter the command name after typing HELP. For example, for help on the **EVENT** ASCII command, type **HELP EVE**<**Enter**>.

When you are using the ACSELERATOR software, press the <F1> key to get help, or select the Help menu from the ACSELERATOR toolbars. The help information in the ACSELERATOR software gives detailed information and sample screens in a GUI format.

Help

Making an EIA-232 Serial Port Connection

The following steps use any popular computer terminal emulation software and SEL serial cables to connect to the SEL-421 Relay. Use an SEL Cable C234A cable to connect a 9-pin computer serial port to the SEL-421 Relay. Use an SEL Cable C227A cable to connect a 25-pin computer serial port to the relay. See *Section 4: Communications Interfaces in the Reference Manual* for further information on serial communications connections. These and other cables are available from SEL. Contact the factory or your local distributor for more information.

- Step 1. Connect the computer and the SEL-421 Relay using the serial communications cable. Use the 9-pin serial port labeled PORT F on the relay front panel.
- Step 2. Apply power to both the computer and to the relay.
- Step 3. Start the computer terminal emulation program.
- Step 4. Set your computer terminal emulation program serial communications parameters. The default SEL-421 Relay communications port settings are listed in *Table 4.2*. Set your computer terminal emulation program to the parameters in the Default column. Also set the terminal program to emulate either VT100 or VT52 terminals. These terminal emulations work best with SEL relays.

Table 4.2	General	Serial	Port	Settinas
		•••••		

Name	Description	Default
PROTO	Protocol (SEL, DNPa, MBA, MBB)	SEL
SPEED	Data speed (300 to 57600, SYNC)	9600
DATABIT	Data bits (7, 8 bits)	8
PARITY	Parity (Odd, Even, None)	Ν
STOPBIT	Stop bits (1, 2, bits)	1
RTSCTS	Enable Hardware Handshaking (Y, N)	Ν

^a DNP protocol is an ordering option.

Step 5.	computer keyboard to confirm that you can communicate with the relay. You will see the "=" action prompt at the left side of your computer screen (column 1). If you do not see the prompt, check the cable connections and confirm the settings for the
	default communications parameters of <i>Table 4.2</i> in your terminal emulation program.
Step 6.	View the relay report header. Type OUIT<enter></enter> . You will

see a computer screen display similar to *Figure 4.4*. (Text that you type is emphasized in bold letters.) If you see jumbled characters, change the terminal emulation type in the computer terminal program.

=QUIT <enter></enter>	
Relay 1	Date: 03/15/2001 Time: 00:01:05.209
Station A	Serial Number: 2001001234
=	



When you communicate with the relay at the "=" prompt, you are in security Access Level 0. You cannot control relay functions at this level. Higher access levels are password protected and allow increased control over relay operation. For more information on access levels and password protection, see *Changing the Default Passwords: Terminal on page 4.10.*

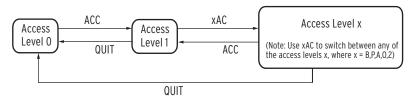
Changing the Default Passwords

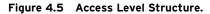
NOTE: Perform the passwordchange steps described in Changing the Default Passwords-Terminal at the end of this subsection.

Access Levels

It is extremely important that you change the factory default passwords programmed in the SEL-421 Relay. Setting unique passwords for the relay access levels increases the security of your substation and the power system. This subsection begins with information on the access level/password system in the SEL-421 Relay and includes an example of changing the default passwords.

Access levels control whether you can perform different operations within the SEL-421 relay. These security levels are labeled 0, 1, B, P, A, O, and 2. *Figure 4.5* presents an overview of the general access level structure in the relay.





Access Level 0 is the least secure and most limited access level, and Access Level 2 is the most secure level at which you have total relay functionality. For example, from Access Level 1, you can view settings; you cannot change settings unless you are at a higher access level. *Table 4.3* lists access levels and operator functions for the SEL-421 Relay.

Table 4.3 SEL-421 Relay Access Levels

Access Level	Prompt	Allowed Operations
0	=	Log in to Access Level 1; some test diagnostics.
1	=>	View data and status information.
В	==>	Access Level 1 functions plus breaker control and data.
Р	P=>	Access Level B functions plus protection settings.
А	A=>	Access Level B functions plus automation settings.
0	O=>	Access Level B functions plus output settings.
2	=>>	Perform all relay access level functions.

The SEL-421 Relay performs command interpretation and execution according to your validated access level. Each access level has a password that the relay must verify before you can control the relay at that level. *Table 4.4 on page 4.9* lists the access level commands with corresponding passwords.

Access Level	Command	Factory Default Password	
0	QUIT	(None)	
1	ACCESS	OTTER	
В	BACCESS	EDITH	
Р	PACCESS	AMPERE	
А	AACCESS	VOLTA	
0	OACCESS	WATT	
2	2ACCESS	TAIL	

Table 4.4 Access Level Commands and Passwords

Communications Ports Access Levels

Entrance to the higher security levels is sequential. You must first enter a correct password to move from Access Level 0 to Access Level 1. To enter Access Levels B, P, A, O, and 2, you must enter a correct password from Access Level 1. For example, to go to the O (Output) Access Level from Access Level 1, type **OAC**<**Enter**>; at the "Password: ?" prompt, type your Access Level O password.

Use the relay **QUIT** command from any access level to return the relay to Access Level 0. To reestablish control at a previous access level from Access Level 1, you must use the access level commands and passwords to log in to that previous access level.

When a connection with the SEL-421 Relay times out, the relay reduces the access level to Access Level 0 for that communications port connection.

Front-Panel Access Levels

The lowest access level for the front panel is Access Level 1. To enter Access Levels B, P, A, O, and 2, you must enter a correct password from Access Level 1. The front-panel LCD displays a password prompt when you attempt to control the relay at any access level higher than Access Level 1. (For more information on entering passwords from the front panel, see *Password on page U.5.10 in the User's Guide.*) The front-panel MAIN MENU item RESET ACCESS LEVEL returns the relay to Access Level 1. In addition, when the front-panel inactivity timer times out (indicated by the ROTATING DISPLAY on the front-panel LCD), the relay returns the front-panel access level to Access Level 1.

ACCESS Command

NOTE: You can shorten relay commands to the first three letters of the full command. See Section 8: ASCII Command Reference in the Reference Manual for more information. Use the ACCESS (ACC) command to change to Access Level 1. Passwords are case sensitive; you must enter a password exactly as set. If you enter the password correctly, the SEL-421 Relay moves you to Access Level 1 from Access Level 0. The Access Level 1 action prompt (=>) appears. If you are at a higher access level (B, P, A, O, and 2), you can reduce the access level to Access Level 1 by entering the ACC command; the relay performs no password validation to reduce the present access level.

Higher Access Level Commands

Use the commands in *Table 4.4 on page 4.9* to enter access levels above Access Level 1. For example, use the **2ACCESS (2AC)** command to change to Access Level 2. If you are presently at Access Level 1, B, P, A, or O, typing **2AC <Enter>** causes the SEL-421 Relay to prompt you to type the Access Level 2 password. If the present level is Access Level 0, the SEL-421 Relay responds with "Invalid Access Level." The relay asserts alarm Relay Word bit SALARM when entering Access Level B, P, A, O, and 2 from a lower access level.

If you are unable to enter the correct password after the third failed attempt, the SEL-421 Relay asserts the SALARM Relay Word bit and displays on a communications terminal screen the error message "WARNING: ACCESS BY UNAUTHORIZED PERSONS STRICTLY PROHIBITED." In addition, you cannot make further access level entry attempts for 30 seconds. The relay terminates the communications connection after the third failed attempt when you use Ethernet via an SEL-2701 Ethernet Processor, DNP (Distributed Network Protocol), and MIRRORED BITS[™] communications virtual terminal mode. For more information on these protocols, see *Section 6: DNP 3.0 Communications in the Reference Manual* and *Section 5: SEL Communications Protocols in the Reference Manual*.

If your connection to the SEL-421 Relay has an inactivity time-out (in the **SET P** port settings), the SEL-421 Relay automatically closes the communications connection and changes to Access Level 0 when the time-out occurs.

Valid passwords are character sequences of as many as six characters. Valid password characters are numbers, upper- and lower-case alphabetic characters, "." (period), and "-" (hyphen). Passwords are case-sensitive. Use strong passwords. These contain a mix of the valid password characters in a combination that does not spell common words in any portion of the password.

Changing the Default Passwords: Terminal

- Step 1. Confirm that the relay is operating. See *Connecting and Applying Power on page 4.4*.
- Step 2. Establish communication with the SEL-421 Relay. See *Making* an *EIA-232 Serial Port Connection on page 4.6* to learn how to use a terminal to communicate with the relay.
- Step 3. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password OTTER and press <Enter>. You will see the => action prompt. Type 2AC<Enter>. At the password prompt, type TAIL<Enter>. You will see the =>> action prompt.
- Step 4. View the list of access levels and passwords. Type
 PAS<Enter>. For a new relay, you will see a terminal screen similar to *Figure 4.6*. (Text that you type is emphasized in bold letters.)

WARNING: This device is shipped with default passwords. Default passwords should be changed to private passwords at installation. Failure to change each default password to a private password may allow unauthorized access. SEL shall not be responsible for any damage resulting from

unauthorized access.

Passwords

NOTE: Passwords are case sensitive; you must enter passwords exactly as set.

=>>PAS <enter></enter>
1:OTTER
B:EDITH
P:AMPERE
A:VOLTA
O:WATT
2:TAIL
=>>

Figure 4.6 Default Passwords.

- Step 5. Set a new password for Access Level 2. Type **PAS 2 nE2Pw**-**<Enter>**. (nE2Pw- becomes the new strong password). The relay will return the word "Set" and the Access Level 2 prompt =>>.
- Step 6. Set new passwords for each access level. In a similar manner as the previous step, create new strong passwords for each access level. Work through the passwords list presented in *Figure 4.6*.
- Step 7. Confirm that you have changed all the default passwords. Type PAS<Enter>. You will see the list of *Figure 4.6* with your new passwords at each access level. Commit these passwords to memory, permanently record your new passwords, and store this permanent record in a secure location.

Eliminate password verification for an access level by entering DISABLE in place of the new password. This action will disable the password of that level; therefore, the relay does not check for a password upon entering that access level. Using DISABLE is not recommended. Always set a unique, strong password in the relay for each access level. Failure to do this can severely jeopardize the security of your substation and the power system.

After you enter a new password, the relay pulses the Relay Word bit SALARM for one second and responds "Set." The relay responds with the message "Password Disabled," if you used the DISABLE parameter.

If you forget a password, or encounter difficulty changing the default passwords in *Changing the Default Passwords: Terminal on page 4.10*, you can temporarily disable password verification. See *Jumpers on page U.2.17 in the User's Guide* for information on the password disable jumper J18B.

Checking Relay Status

	With continual self-testing, the SEL-421 Relay monitors the internal operation of all circuits to verify optimal performance of relay functions. If an intern circuit, protection algorithm, or automation algorithm enters an out-of-tolerance operating range, the relay reports a status warning. In the unlike event that an internal failure occurs, the relay reports a status failure. For m information on relay status, see <i>Relay Self-Tests on page U.6.37 in the Use Guide</i> .	nal ly nore	
	You can check relay status through a communications port by using a terminal, terminal emulation computer program, or the ACSELERATOR software. In addition, you can use the relay front panel to view status information.		
Checking Relay Status: Terminal	The procedure in the following steps assumes that you have successfully established communication with the relay; see <i>Making an EIA-232 Serial F Connection on page 4.6</i> for a step-by-step procedure. In addition, you must familiar with relay access levels and passwords. See <i>Changing the Default Passwords: Terminal on page 4.10</i> to change the default access level passwords.		
	Step 1. Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC <enter>. Type the Acc Level 1 password and press <enter>. You will see the => action prompt.</enter></enter>	cess	
	Step 2. Type STA<enter></enter> . The relay returns a status terminal screasinilar to that in <i>Figure 4.7</i> .	een	
	=>STA <enter></enter>		
	Relay 1 Date: 03/15/2001 Time:07:02:50. Station A Serial Number: 000101234	776	
	FID=SEL-421-R101-V0-Z001001-D20010315 CID=0x9aed		
	Failures No Failures		
	Warnings No Warnings		
	SELogic Relay Programming Environment Errors No Errors		
	Relay Enabled =>		
	Figure 4.7 Relay Status.		
	To view all relay status entries, use the STA A command. For more		

information on relay status report items, see *STATUS on page R.8.45 in the Reference Manual.*

You can use the SEL-5030 ACSELERATOR Software Program to check relay status. Use the HMI > Meter Control menu to view status conditions.

The procedure in the following steps assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default*

SEL-421/SEL-421-1 Relay

Checking Relay

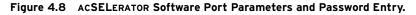
Software

Status: ACSELERATOR

Passwords: Terminal on page 4.10 to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Communication Parameters. You will see the Communication Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters and connect to the relay. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm that you have loaded the correct passwords in the ACSELERATOR software. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.

Communication Parameters				×
Device Direct to COM1 Phone Number	Data Speed C 300 C 1200 C 2400	 4800 9600 19200 	 38400 57600 	
Level One Password (Serial & Telnet) server Level Two Password (Serial & Telnet) server	Data Bits © 8 © 7	Stop Bits C 2 C 1	Parity None O Odd O Even	
Use Network	iers			
	<u>0</u> K	<u>C</u> ancel	<u>H</u> elp]



- Step 3. Start the ACSELERATOR software operator interface. In the top toolbar HMI menu, click Meter and Control.
- Step 4. Select ACSELERATOR status information. Click the Status button of the HMI tree view. See *Figure 4.9*.
- Step 5. View relay status. The ACSELERATOR software displays relay status with a display similar to that in *Figure 4.7*.

	Device Overview
•	Phasors
	Instantaneous
•	Demand/Peak
	Maximum/Minimum
	Energy
	Targets
	Status
	SER
	Breaker Monitor Data
	Control Window

Figure 4.9 Retrieving Relay Status: ACSELERATOR Software.

Checking Relay Status: Front Panel

Use the front-panel display and navigation pushbuttons to check SEL-421 Relay status. See *Section 5: Front-Panel Operations in the User's Guide* for information on using the relay front panel.

- Step 1. Prepare to use the front panel. Apply power to the relay, and note that the LCD shows a sequence of screens called the ROTATING DISPLAY. (Also, if you do not operate the front panel for a certain period, the relay will enter front-panel timeout mode and you will see the sequential screens of the ROTATING DISPLAY.)
- Step 2. View the MAIN MENU. Press the **{ENT}** pushbutton to display the MAIN MENU of *Figure 4.10*.

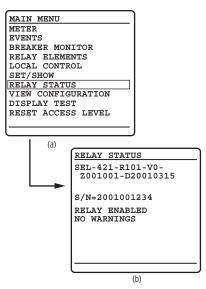


Figure 4.10 Checking Relay Status: Front-Panel LCD.

- Step 3. View relay status. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the RELAY STATUS action item (See *Figure 4.10*). Press the {ENT} pushbutton. You will see the RELAY STATUS screen (the second screen of *Figure 4.10*).
- Step 4. Normalize the front-panel display. To return to the MAIN MENU, press the **{ESC}** key. To return to the ROTATING DISPLAY, press **{ESC}** again.

For more information on the front-panel screen presentations and the items in the STATUS screens, see *RELAY STATUS on page U.5.24 in the User's Guide*.

Making Simple Settings Changes

The SEL-421 Relay settings structure makes setting the relay easy and efficient. Settings are grouped logically, and you do not see relay elements that are not used in your selected protection scheme. For example, if you select only three levels of a particular type of overcurrent protection, the corresponding Level 4 overcurrent element settings do not appear on the communications terminal screen. Hiding unused elements and settings that you have not enabled greatly simplifies the task of setting the SEL-421 Relay.

The ACSELERATOR software uses a similar method to focus your attention on the active settings. Unused relay elements and inactive settings are dimmed (grayed) in the ACSELERATOR software menus. See *Section 3: PC Software in the User's Guide* for more information on the ACSELERATOR software.

Settings Structure

The SEL-421 Relay settings structure assigns each relay setting to a specific location based on the setting type. A top-down organization allocates relay settings into these layers:

- ► Class
- ► Instance
- ► Category
- ► Setting

Examine *Figure 4.11* to understand the settings structure in the SEL-421 Relay. The top layer of the settings structure contains classes and instances. Class is the primary sort level; all classes have at least one instance, and some classes have multiple instances. Settings classes and related instances for the SEL-421 Relay are listed in *Table 4.5 on page 4.17*.

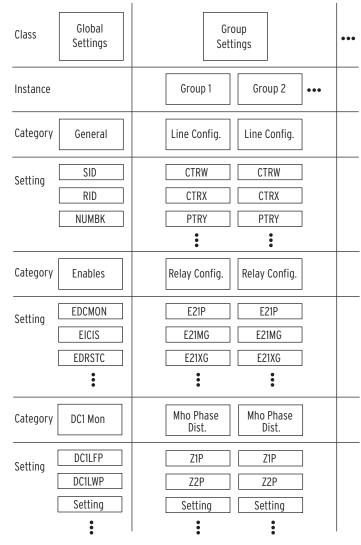


Figure 4.11 Relay Settings Structure Overview.

Class	Description	Instance	Description	ASCII Command
Global	Relay-wide appli- cations settings	Global		SET G
Group	Individual scheme settings	Group 1	Group 1 settings	SET 1, SET S 1
		•	•	•
		•	•	
		Group 6	Group 6 settings	SET 6, SET S 6
Breaker Monitor	Circuit breaker monitoring settings	Breaker Monitor		SET M
Port	Communications port settings	Port F	Front-panel port	SET P F
		Port 1	Port 1 settings	SET P 1
		•	•	•
		•	•	•
		Port 3	Port 3 settings	SET P 3
		Port 5	Communications card settings	SET P 5
Report	Event report and SER ^a settings	Report		SET R
Front Panel	Front-panel HMI settings	Front Panel		SET F
Protection SELOGIC [®] control equations	Protection-related SELOGIC control equations	Group 1	Group 1 protection SELOGIC control equations	SET L 1
Ĩ	1	•	•	•
		•	•	•
		• Group 6	• Group 6 protection SELOGIC control equations	• SET L 6
Automation SELOGIC control equations	Automation- related SELOGIC control equations	Block 1	Block 1 automation SELOGIC control equations	SET A 1
1	Ĩ	•	•	•
		•	•	•
		•	•	•
		Block 10	Block 10 automation SELOGIC control equations	SET A 10
DNP	Direct Network Protocol data remapping	DNP		SET D
Output SELOGIC control equations	Relay control output settings and Mirrored Bits communication transmit equations	Output		SET O

Table 4.5	Settinas	Classes	and	Instances
	occurrys	0103503	ana	motuneco

^a SER is the Sequential Events Recorder; see SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook. Note that some settings classes have only one instance and you do not specify the instance designator when accessing these classes. An example is the Global settings class. You can view or modify Global settings with a communications terminal by entering **SET G** as shown in the ASCII Command column of *Table 4.5 on page 4.17*. The relay presents the Global settings categories at the **SET G** command; no instance numbers follow **SET G**. Conversely, the Port settings command has five instances (Port F, Port 1, Port 2, Port 3, and Port 5). To access the Port 1 settings, you must type **SET P 1<Enter>**. If you do not specify which port to set, the relay defaults to the active port (the port you are presently using).

The Group settings can have the optional one-letter acronym 'S' attached to the command; you can enter **SET 1** or **SET S 1** for Group 1 settings, **SET 2** or **SET S 2** for Group 2 settings, etc. If you do not specify which group to set, the relay defaults to the present active group. If Group 6 is the active group, and you type **SET<Enter>**, for example, you will see the settings prompts for the Group 6 settings.

Settings: Terminal

When you change settings (with any **SET** command) from a terminal, the relay shows the setting category, prompt, present value, and action prompt. *Figure 4.12* shows two settings examples: multiple-line settings (SID and RID) and an in-line setting (NUMBK) for relay Global settings from Access Level P (protection). The relay prompts you for input by presenting an action prompt. You have many options for navigating the settings at the "?" action prompt. *Table 4.6 on page 4.19* lists the operations possible from a settings action prompt. This table denotes the enter key <Enter> with the \dashv symbol.

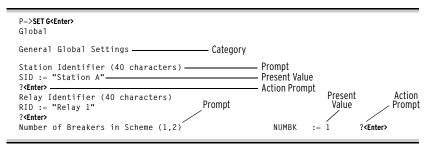


Figure 4.12 Components of SET Commands.

Action ^a	Relay Response
ل	Accept setting and move to the next setting; if at the last setting, exit settings.
[value]₊┘	Enter the given <i>value</i> and move to the next setting if valid; if at the last setting, exit settings.
^₊	Move to the previous setting; if at the top of settings, stay at the present setting.
<₊J	Move to the top of the previous settings category; if at the top of set- tings, stay at the present setting.
>,1	Move to the top of the next settings category; if in the last category, exit settings.
END↓	Go to the end of the present settings session. Prepare to exit settings via the "Save settings (Y,N) ?" prompt.
<ctrl+x></ctrl+x>	Abort editing session without saving changes.

Table 4.6 Actions at Settings Prompts^a

^a In this table, the \downarrow symbol represents the Enter key <Enter>.

When you exit settings entry from the SET commands, the relay responds, "Save settings (Y,N) ?". If you answer **Y**<**Enter**> (Yes), the relay writes the new settings to nonvolatile storage. If you answer **N** <**Enter**> (No), the relay discards any settings changes you have made.

Making Settings Changes: Initial Global Settings

You must configure the SEL-421 Relay for specific conditions found in the power system where you are connecting the relay. In particular, you must set the nominal frequency and phase rotation.

The procedure in the following steps assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

This example jumps to a Global setting that is not at the beginning of the Global settings list. Thus, you enter **SET G**, the setting name, and **<Enter>**. To start at the beginning of the Global settings, simply type **SET G<Enter>** without a settings name.

- Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 2. Set the nominal system frequency. Use the NFREQ setting, which has options of 50 Hz and 60 Hz. Type SET G NFREQ<Enter>. The relay responds with a terminal screen display similar to the beginning of *Figure 4.13*.

=>>SET G NFREQ<Enter> Global

General Global Settings Nominal System Frequency (50,60 Hz) System Phase Rotation (ARC ACR)

Settings Saved =>>

Figure 4.13 Initial Global Settings.

Step 3. Accept default settings. For a 60 Hz system, simply press <Enter> to accept the NFREQ existing value of 60 (Hz). The relay presents the next setting, which is the PHROT (phase rotation) setting. Type <Enter> to accept the ABC phase rotation default.

Step 4. Set the date format. The SEL-421 Relay reports dates in three formats: MDY, YMD, and DMY (where M = month, D = date, and Y = year). For this procedure type **YMD**<**Enter>**. At each setting in turn, the relay presents the settings prompt, name, present value, and action prompt. Note that SELOGIC control equation settings, such as FAULT in *Figure 4.13*, appear on multiple lines.

If you make a mistake or want to go backward through the settings, type the ^ character (on most computer keyboards, this is a shifted numeral 6) and **<Enter>**. Refer to *Table 4.6 on page 4.19* for this and other navigational aids.

Step 5. End the settings session. Type END<Enter> at the FAULT action prompt. (The FAULT SELOGIC control equation remains unchanged.) The relay next scrolls a readback of all the Global settings, eventually displaying the "Save settings (Y, N) ?" prompt. (In *Figure 4.13*, a vertical ellipsis represents the relay information during readback.) Examine the settings readback to verify your new settings. Answer Y<Enter> to save your new settings.

The TERSE Option

You can avoid viewing the entire class settings summary the relay displays when you type **END**<**Enter**> midway through a settings class or instance. On slow data speed links, waiting for the complete settings readback can clog your automation control system or take too much of your time for a few settings changes. Eliminate the settings readback by appending **TERSE** to the **SET** command.

Text-Edit Mode Line Editing

Some SEL-421 Relay settings present multiple input lines to your terminal; you use basic line text editing commands to construct the setting. For display, the relay references each line of the setting by line number, not by the setting name. See *Making Text-Edit Mode Settings Changes on page 4.21* for an example of a text-edit mode setting.

While in the text-edit mode, you see a prompt consisting of the line number and the present setting for that line. You can keep the setting, enter a new setting, or delete the setting. *Table 4.7* lists the commands for text-edit mode.

Action ^a	Relay Response
L	Accept the setting and move to the next line; if at the last line or at a blank line, exit settings.
>n.	Move to line <i>n</i> . If this is beyond the end of the list, move to a blank line following the last line.
^_	Move to the previous line; if at the first line, stay at the present line.
<₊]	Move to the first line.
>,∣	Move to a blank line following the last line.
LIST↓	List all settings and return to the present action prompt.
DELETE [n]₊J	Delete the present line and subsequent lines for a total of n lines; $n=1$ if not provided. Lines after deletion shift upward by the number of lines deleted.
INSERT↓	Insert a blank line at the present location; the present line and subsequent lines shift downward.
END↓	Go to the end of the present settings session. Prepare to exit settings via the "Save settings (Y,N) ?" prompt.
<ctrl+x></ctrl+x>	Abort editing session without saving changes.

Table 4.7 Actions at Text-Edit Mode Prompts

^a In this table, the \rightarrow symbol represents the Enter key <Enter>.

Use commas to separate the items in a text-edit mode setting when you are entering multiple items per line. After you enter each line, the relay checks the validity of the setting. If the entered setting is invalid, the relay responds with an error message and prompts you again for the setting.

Making Text-Edit Mode Settings Changes

The procedure in the following steps familiarizes you with basic text-edit mode line editing. You set Display Point 1 through Display Point 3 to show the status of Circuit Breaker 1, Circuit Breaker 2, and the operational state (on or off) of the transformer cooling fans near the circuit breaker bay where you have installed the SEL-421 Relay. See *Display Points on page U.5.6 in the User's Guide* for information on programming display points.

For this example, use inputs IN101 through IN103. You can use other inputs for your particular application. See *Control Inputs on page U.2.6 in the User's Guide* for more information on control inputs.

This procedure assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be

familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 2. Access the display point settings. Type **SET F<Enter>** to modify the front-panel settings. Advance through the front-panel settings (repeatedly type > and then **<Enter>**) until you reach the Display Points and Aliases category. *Figure 4.14* shows a representative terminal screen. The relay displays the first line that you can edit. For the case of display points, the line number is the display point number.
- Step 3. Set Display Point 1. At the Line 1 "?" settings action prompt, type IN101, "CB1", CLOSED, OPEN < Enter > to create Display Point 1. The relay verifies that this is a valid entry, then responds with the next line prompt "2:" followed by the "?" settings action prompt (see *Figure 4.15 on page 4.24*).
- Step 4. Set Display Point 2. At the Line 2 "?" settings action prompt, type IN102, "CB2", CLOSED, OPEN < Enter > to create Display Point 2. The relay verifies that this is a valid entry, then responds with the next line prompt "3:" followed by the "?" settings action prompt (see *Figure 4.15 on page 4.24*).
- Step 5. List active display points. At the Display Points and Aliases prompt, use the text-edit mode line editing commands to list the active display points. Type **LIST<Enter>**. After showing the active display points, the relay returns you to line "3:" followed by the "?" settings action prompt.
- Step 6. Set Display Point 3. Type IN105,"5 MVA XFMR Fans",ON,OFF<Enter> to create Display Point 3. The relay verifies that this is a valid entry, then responds with the next line prompt "4:" followed by the "?" settings action prompt (See Figure 4.14).
- Step 7. End the settings session. Type END<Enter>. The relay scrolls a readback of all the Front-Panel settings, eventually displaying the "Save settings (Y,N)?" prompt. (A vertical ellipsis in *Figure 4.14* represents the readback.) At the end of the readback information, just before the "Save settings (Y,N)?" prompt, you can verify the new display point information. Answer Y<Enter> to save the new settings.

Display Points and Aliases Syntax: Relay word bit, alias name, alias for set state, alias for clear state ? IN101,"CB1","CLOSED","OPEN"<Enter> 2: ? IN102."CB2"."CLOSED"."OPEN"<Enter> 3. ? LIST<Enter> 1: IN101,"CB1","CLOSED","OPEN" 2: IN102,"CB2","CLOSED","OPEN" 3. ? IN105,"5 MVA XFMR Fans",ON,OFF<Enter> 4 . END<Enter> ? Display Points and Aliases Syntax: Relay word bit, alias name, alias for set state, alias for clear state 1: IN101,"CB1","CLOSED","OPEN" 2: IN102,"CB2","CLOSED","OPEN" 3: IN105,"5 MVA XFMR Fans","ON","OFF" Save settings (Y,N) ?Y<Enter> Saving Settings. Please Wait..... Settings Saved =>>



This procedure proposes connecting the transformer bank fan sensor to relay input IN105. In the **SET G** (GLOBAL) command, verify that the assertion level (setting IN105P) and the debounce time (setting IN105D) are correct for your fan-running sensor. To access separate input parameters, you must first enable independent control input settings with setting EICIS. To change the input conditioning, enter these settings:

- **EICIS := Y** Independent Control Input Settings (Y, N)
- **IN105P := 80** Input IN105 Pickup Level (15–265 Vdc)
- **IN105D := 0.375** Input IN105 Debounce Time (0.00–5.00 cycles)

Use the appropriate interface hardware to connect the fan-running sensor to IN105. Choose any relay input that conforms to your requirements. See *Control Inputs on page U.2.6 in the User's Guide* for more information on SEL-421 Relay control inputs.

Deleting a Display Point

This example shows how you can delete a previously used display point. In the **SET F** command, at the Display Points and Aliases prompt, use the textedit mode line editing commands to set and delete the display points. This procedure shows two previously programmed display points that indicate on the front-panel LCD the status of Circuit Breaker 1 and Circuit Breaker 2. Relay control inputs IN101 and IN102 are the Relay Word bits for the Circuit Breaker 1 and Circuit Breaker 2 display points, respectively (see *Making Text-Edit Mode Settings Changes on page 4.21*). You can use other inputs for your particular application. See *Control Inputs on page U.2.6 in the User's Guide* for more information on control inputs.

The procedure in the following steps assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be

familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 2. Access the Display Points and Aliases prompt. Enter the SET F command. Advance through the front-panel settings (repeatedly type ><Enter>) until you reach the Display Points and Aliases category. *Figure 4.15* shows a representative terminal screen. The relay displays the first line that you can edit. For display points, the line number is the display point number.

Display Points and Aliases

Syntax: Relay word bit, alias name, alias for set state, alias for clear state 1: IN101,"CB1","CLOSED","OPEN"

? LIST<Enter> 1: IN101,"CB1","CLOSED","OPEN" 2: IN102,"CB2","CLOSED","OPEN" 3: IN105, "5 MVA XFMR Fans", "ON", "OFF" 1: IN101,"CB1","CLOSED","OPEN" ? <Enter> 2: IN102, "CB2", "CLOSED", "OPEN" ? DELETE<Enter> 2: IN105,"5 MVA XFMR Fans","ON","OFF" ? LIST<Enter> 1: IN101, "CB1", "CLOSED", "OPEN" 2: IN105,"5 MVA XFMR Fans","ON","OFF" 2: IN105,"5 MVA XFMR Fans","ON","OFF" ? END<Enter> Display Points and Aliases Syntax: Relay word bit, alias name, alias for set state, alias for clear state 1: IN101,"CB1","CLOSED","OPEN" 2: IN105,"5 MVA XFMR Fans","ON","OFF" Save settings (Y,N) ?Y<Enter> Saving Settings, Please Wait..... Settings Saved =>>

Figure 4.15 Using Text-Edit Mode Line Editing to Delete a Display Point.

- Step 3. List the present display points. At the Control Points and Aliases prompt, use the text-edit mode line editing commands to list the active display points. Type LIST<Enter>. After showing the active display points, the relay returns you to line "1:" followed by the "?" settings action prompt.
- Step 4. Ready the relay to edit line 2. Type **<Enter>** once to proceed to the line 2 present value and "?" settings action prompt.
- Step 5. Delete Display Point 2. Type DELETE<Enter>.
- Step 6. Examine the remaining display points. Type **LIST<Enter>**. Former Display Point 2 is eliminated, and Display Point 3 moves up to position 2. The relay returns you to line "2:" followed by the "?" settings action prompt.

Step 7. End the settings process. Type **END**<**Enter**>. The relay next scrolls a readback of all the Front-Panel settings, eventually displaying the "Save settings (Y,N) ?" prompt. (In *Figure 4.15*, a vertical ellipsis represents this scrolling readback.) At the end of the readback information, just before the "Save settings (Y,N) ?" prompt, you can verify the new display point information. Answer **Y**<**Enter**> to save your new settings.

You can use the ACSELERATOR software to develop settings for the SEL-421 Relay offline. The ACSELERATOR software automatically checks interrelated settings and alerts you to out-of-range settings. Upload the off-line ACSELERATOR software settings to the relay via the communications ports. See *Checking Relay Status: ACSELERATOR Software on page 4.12* for an introductory tutorial on using the ACSELERATOR software.

You can also use the ACSELERATOR software as a terminal program to interact in real time with the relay. For an introduction to the ACSELERATOR software and all of features of this software, see *Section 3: PC Software in the User's Guide*.

Making Initial Global Settings: ACSELERATOR Software

The ACSELERATOR software makes setting the relay an easy task. The purpose of the procedure in the following steps is to familiarize you with reading, modifying, and sending settings with the ACSELERATOR software.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software; see *Section 3: PC Software in the User's Guide*, and *Checking Relay Status: ACSELERATOR Software on page 4.12*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Communication Parameters. You will see the Communication Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Type **<Ctrl+T>** to open the ACSELERATOR software terminal window. Type **<Enter>** to see whether the communications link is active between the ACSELERATOR software and the relay. You will see the = action prompt in the terminal window. Exit the terminal window.
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. Read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all configuration and settings data to the ACSELERATOR software.

Settings: the ACSELERATOR Software

- Step 4. Select Global settings. Click on the plus mark (+) next to the Global branch of the left-hand ACSELERATOR software tree structure shown in *Figure 4.16*. Click on Global Settings/Enables. You will see the Global Settings/Enables window with General Global Settings and Global Enables (See *Figure 4.17*).
- Step 5. Change settings. Click on the button for the correct option for NFREQ and PHTROT to specify your system frequency and phase rotation. When you tab or click to the next field, the relay validates the new setting.

The right-click mouse button performs two special functions when you are editing settings: Previous Value and Default Value. Right click in the setting dialog box and select Previous Value if you want to revert to the setting value before you made a change. Right click in the setting dialog box and select Default Value if you want to restore the factory default setting value.

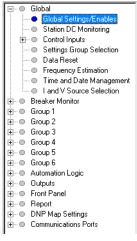


Figure 4.16 Selecting Global Settings in the ACSELERATOR Software.

Global Enables General Global Settings SID Station Identifier (40 characters) STATION A/ RID Relay Identifier (40 characters)	
RELAY 1 TIDW Terminal W Identifier (40 characters) BREAKER NUMBK Number Breakers in Scheme © 1 © 2	TIDX Terminal X Identifier (40 characters) BREAKER
BID1 Breaker 1 Identifier (40 characters) BREAKER 1	BID2 Breaker 2 Identifier (40 characters) BREAKER 2
NFREQ Nominal System Frequency © 50 © 60	PHROT System Phase Rotation ABC C ACB
DATE_F Date Format MDY CYMD C DMY	
FAULT Fault Condition Equation (SELOGIC)	EB

Figure 4.17 The ACSELERATOR Software Global Settings Window.

- Step 6. Save the new settings in the ACSELERATOR software. On the Relay Editor File menu, click Save, specify a Relay Name, and click OK.
- Step 7. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class or instance you want to send to the relay, as shown in the first dialog box of *Figure 4.18*. Click the check box for Global. Click OK. The ACSELERATOR software responds with the second dialog box of *Figure 4.18*. If you see no error message, the new settings are loaded in the relay.

Settings Class Select	×
Select Classes to Send Global Group 1 Group 2	
Group 3 Group 4 Group 5 Group 5 Automation 1 Automation 2	OK Cancel
Transfer Status	
Writing 1 of 1	
Sending File: SETTINGS\SET_G1.T Sending settings	KT

Figure 4.18 Uploading Global Settings to the SEL-421 Relay.

You can use the relay front panel to enter some of the relay settings. The SEL-421 Relay presents the settings in order from class to instance (if applicable) to category to the particular setting, in a manner similar to setting the relay using a terminal. Use the LCD and the adjacent navigation pushbuttons to enter each character of the setting in sequence. This can be a laborious process for some settings (e.g., long SELOGIC control equations).

However, if you need to make a quick correction or have no faster means to make settings, settings functions are available at the front panel. For more information on making settings changes from the front panel, see *SET/SHOW* on page U.5.21 in the User's Guide.

Entering DATE and TIME from the Front Panel

The purpose of the procedure in the following steps is to familiarize you with entering data from the SEL-421 Relay front panel. Refer to *Connecting and Applying Power on page 4.4* before performing this example.

- Step 1. Prepare to use the front panel. Apply power to the relay; note that the relay front-panel display shows a sequence of LCD screens called the ROTATING DISPLAY. (If you do not operate the front panel for a certain period, the relay will enter front-panel time-out mode and you will see the sequential screens of the ROTATING DISPLAY.)
- Step 2. View the MAIN MENU. Press the **{ENT}** pushbutton to display the MAIN MENU of *Figure 4.19*.
- Step 3. View settings screens. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the SET/SHOW action item (See *Figure 4.19*). Press the {ENT} pushbutton. You will see the SET/SHOW submenu (the second screen in *Figure 4.19*).

NOTE: The Relay Editor dialog boxes shown in Figure 4.18 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

Settings: Front Panel

Step 4. View the date/time screen. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the DATE/TIME action item (*Figure 4.19*, second screen). Press the {ENT} pushbutton. The relay next displays the DATE/TIME submenu (the third screen of *Figure 4.19*).

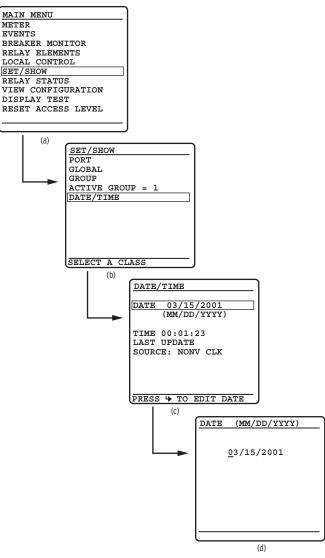


Figure 4.19 DATE and TIME Settings: Front-Panel LCD.

Step 5. Set the date. Press the {ENT} pushbutton. The relay shows the last screen of *Figure 4.19*, the DATE edit screen. Use the {Up} arrow and {Down} arrow navigation pushbuttons to increase and decrease the date position numbers. Step to the next or previous position by using the {Left} and {Right} arrow pushbuttons. When finished adjusting the new date, press {ENT}.

The relay returns the display to the DATE/TIME submenu. Note that the relay reports the TIME SOURCE as FP DATE (front-panel date).

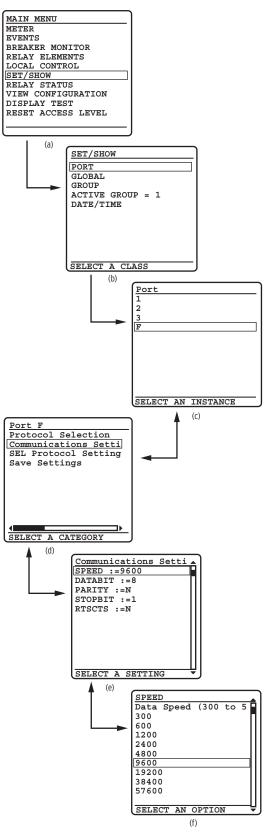
Step 6. Normalize the front-panel display. Press {ESC} repeatedly.

Changing a Relay Setting From the Front Panel

The purpose of the procedure in the following steps is to provide additional practice at entering relay settings from the front panel. In this example, you change the PORT F front-panel communications port settings.

- Step 1. View the MAIN MENU. If you have been using the front panel (as in the previous example), press the **{ESC}** key repeatedly until you see the MAIN MENU. If the relay is displaying the ROTATING DISPLAY, press the **{ENT}** pushbutton to display the MAIN MENU. The first screen of *Figure 4.20* shows the MAIN MENU at the beginning of the front-panel settings process.
- Step 2. View the settings screens. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the SET/SHOW action item (See *Figure 4.20*). Press the {ENT} pushbutton. You will see the SET/SHOW submenu (the second screen in *Figure 4.20*).
- Step 3. Select PORT F. Highlight PORT and press the {ENT} pushbutton. Next, the relay displays the PORT instances (the third screen of *Figure 4.20*). Choose the port you want to configure by using the {Up} and {Down} arrow navigation pushbuttons to move the screen arrow. For this example, select PORT F and press {ENT}.
- Step 4. View the Communications Settings category screen. The relay shows the fourth screen of *Figure 4.20*, the PORT F category screen. Use the {Up} and {Down} arrow navigation pushbuttons to select the settings category. For this example, highlight Communications Settings and press {ENT}. The relay displays the fifth screen of *Figure 4.20*, the Communications Settings screen.
- Step 5. Change settings. Highlight the SPEED setting. Press {ENT}. (The relay possibly requires a password here; see *Passwords on page 4.10* and *Section 5: Front-Panel Operations in the User's Guide.*) The LCD displays the SPEED selection submenu that has all the possible choices for serial data speeds. The highlight in the sixth screen of *Figure 4.20* indicates the default setting of 9600 (bps). Use the {Up} and {Down} arrow navigation pushbuttons to select a different speed. Once you have selected a data speed, press the {ENT} pushbutton.
- Step 6. End the settings session. The relay returns to the previous category settings list screen. Press {ESC} to return to the categories screen where you see the Save Settings item at the bottom of the screen. Use the {Up} and {Down} arrow pushbuttons to highlight Save Settings and press {ENT}. Highlight YES, and then press {ENT}. The relay validates the setting and returns you to the PORT screen (the third screen of *Figure 4.20*).
- Step 7. Normalize the front-panel display. Press **{ESC}** repeatedly to return to the MAIN MENU.

NOTE: Once you have changed communications parameters, you must change the corresponding parameters in your terminal emulation program to communicate with the relay via a communications port.





Examining Metering Quantities

	The SEL-421 Relay features high-accuracy power system metering. You can view fundamental and rms quantities by using a communications terminal, th ACSELERATOR software, or the front panel. For more information on SEL-421 Relay metering, see <i>Metering on page A.2.28 in the Applications Handbook</i> .							
View Metering: Terminal	The procedure in the following steps shows how to use a termina emulation computer program to view power system metering. In you connect specific voltages and currents for a 5 A, 60 Hz relay quantities appropriately for your particular relay. For more inform testing the relay and making test connections, see <i>Section 6: Test</i> <i>Troubleshooting in the User's Guide</i> .							
	This example assumes that you have successfully established communic with the relay; see <i>Making an EIA-232 Serial Port Connection on page 4</i> a step-by-step procedure. In addition, you must be familiar with relay ac levels and passwords. See <i>Changing the Default Passwords: Terminal on page 4.10</i> to change the default access level passwords.							
	Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC <enter>. Type th Level 1 password and press <enter>. You will see the action prompt. Type the 2AC<enter> command, and the correct password to go to Access Level 2. You wil =>> action prompt.</enter></enter></enter>							
	Step 2. Set the relay to a nominal operation mode. Use a term perform the initial global settings relay setup in <i>Maki Settings Changes: Initial Global Settings on page 4.1</i> relay for 60-Hz operation, ABC phase rotation.							
	Step 3.	Set the relay for a basic voltage and current configuration. See <i>Figure 4.21</i> . Use the terminal to set global settings ESS := 1. Type SET G ESS TERSE<enter></enter> . Type 1<enter></enter> if the ESS setting is not 1. Type END<enter></enter> to finish this settings session. Answer Y <enter></enter> to the save settings prompt.						
	=>> SET G ESS TERSE<enter></enter> Global							
		Voltage Source Selection						
		Voltage Source Selection (Y,N,1,2,3,4) ESS := N ?1 <enter≻ Source (IW,COMB) LINEI := IW ?END<enter≻< th=""></enter≻<></enter≻ 						
	Save settings (Y,N) ? Y<enter></enter> Saving Settings, Please Wait Settings Saved =>>							

Figure 4.21 Setting ESS: Terminal.

Step 4. Set CT and PT ratios. Use the terminal to confirm that Group 1 setting CTRW := 200 (the current transformer W-input ratio), and PTRY := 2000 (the potential transformer Y-input ratio). Type SET CTRW TERSE<Enter>. If the CTRW setting is not 200, type 200<Enter>. Proceed as shown in *Figure 4.22* to PTRY and change PTRY to 2000, if needed. Type END<Enter> to finish this settings session. Answer Y
<Enter> to the save settings prompt.

=>>SET CTRW TERSE<Enter>

```
Group 1
Line Configuration
```

Current Transformer Ratio - Input W (1-50000) CTRW := 1000 ?200

 Current Transformer Ratio - Input X (1-50000)
 CTRX := 1000 ?

 Potential Transformer Ratio - Input Y (1-10000)
 PTRY := 2000 ?END

 Save settings (Y,N) ?Y
 Enter>

 Saving Settings, Please Wait.....

 Settings Saved

 =>>

Figure 4.22 Setting CTRW and PTRY: Terminal.

Step 5. Turn relay power off.

Step 6. Connect analog inputs. If three voltage sources and three current sources are available, connect the sources to the relay as shown in *Figure 4.23*. If three voltage sources and two current sources are available, use the connection diagram of *Figure 4.24*. Apply 67 V per phase (line-to-neutral) in ABC phase rotation. Apply 2.0 A per phase, in phase with the applied phase voltages.

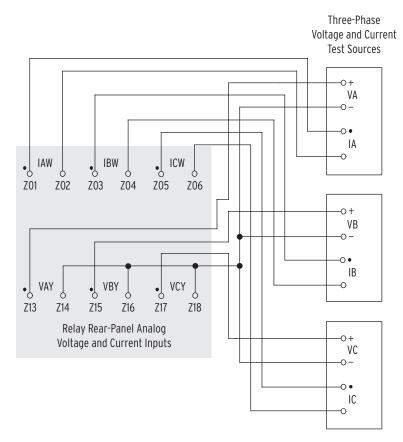


Figure 4.23 Test Connections Using Three Voltage Sources/Three Current Sources.

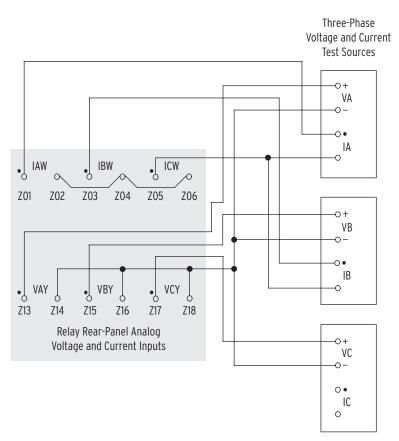


Figure 4.24 Test Connections Using Two Current Sources for Three-Phase Faults and METER Test.

- Step 7. Turn relay power on.
- Step 8. View metering. Type ACC<Enter> to log-in to relay Access Level 1, then type your password and press <Enter>. Type MET<Enter>. The relay displays the fundamental frequency (50 Hz or 60 Hz) metering information in a manner similar to that in *Figure 4.25*.

=>>MET <enter></enter>						
Relay 1 Station A				e: 03/15/20 ial Number		00:00:14.938 34
	Ph	ase Current	S			
	IA	ΙB	IC			
I MAG (A)	400.000	400.345	400.431			
I ANG (DEG)	00.00	-120.10	119.90			
	Ph	ase Voltage	s	Phas	e-Phase Vo	ltages
	VA	VB	VC	VAB	VBC	VCA
V MAG (kV)	134.001	133.999	134.001	232.095	232.093	232.097
V ANG (DEG)	00.00	-120.10	119.90	00.00	-00.10	00.10
	Sec	uence Curre	ents (A)	Segu	ence Volta	iges (kV)
	I1	312	310	٧1	3V2	3V0
MAG	400.252	0.739	0.861	133.954	0.003	0.001
ANG (DEG)	0.01	-50.86	-63.65	0.00	-49.97	-120.70
	А	В	С		3P	
P (MW)	53.60	53.60	53.60	14	5r 60.08	
0 (MVAR)	0.00	-0.00	-0.00		-0.00	
S (MVA)	0.00	0.00	0.00		0.00	
POWER FACTOR	1.00	0.00	1.00		1.00	
. Such Thoron	1.00	LAG	1.00		1.00	
FREQ (Hz) =>>	60.00	VDC1(V)	125.00	VDC2(V)	48.00	

Figure 4.25 Terminal Screen MET Metering Quantities.

The metering quantities of *View Metering: Terminal on page 4.31* are the fundamental line quantities. Other variants of the **MET** command give different relay metering quantities. For example, you can see the line RMS (harmonics-included) quantities by issuing the **MET RMS** command. See *Metering on page A.2.28 in the Applications Handbook* and *METER on page R.8.28 in the Reference Manual* for more information on the **MET** command.

Use the procedures in the following steps to examine the SEL-421 Relay metering with the ACSELERATOR software HMI.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Checking Relay Status: ACSELERATOR Software on page 4.12* and *Section 3: PC Software in the User's Guide.*

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.

View Metering: ACSELERATOR Software

- Step 3. Set the relay to a nominal operation mode. Perform the initial global settings relay setup of *Making Initial Global Settings: ACSELERATOR Software on page 4.25* to set the relay for 60-Hz operation, ABC phase rotation.
- Step 4. Set a basic voltage and current configuration. In the ACSELERATOR software Settings tree view, double-click the Global entry of the Settings tree view to expand the Global branch (See *Figure 4.26*). Click the I and V Source Selection branch. You will see the Current and Voltage Source Selection dialog box of *Figure 4.26*. Click on the down button to select 1 for ESS (Current and Voltage Source Selection).

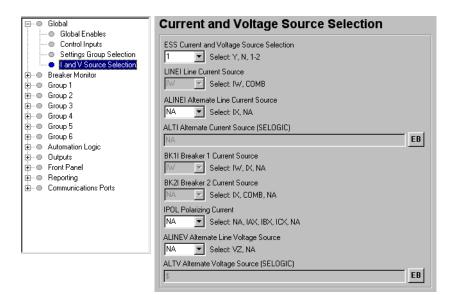


Figure 4.26 Global Alternate Source Selection Settings in the ACSELERATOR Software.

Step 5. Set PT and CT ratios. In the ACSELERATOR Settings tree view, click the "+" mark next to Group 1 to expand this branch (See *Figure 4.27*). Click the plus (+) mark next to Set 1. Click Line Configuration. You will see the Line Configuration window similar to *Figure 4.27*. Confirm that setting CTRW is 200 (the current transformer W-input ratio), and PTRY is 2000 (the potential transformer Y-input ratio). Save the settings and send the Group 1 settings if you change the settings. See *Step 6* and *Step 7 on page 4.27*.

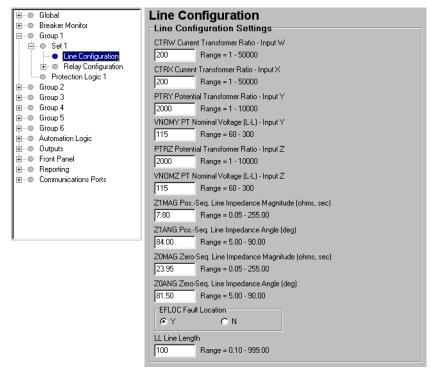


Figure 4.27 Group 1 Terminal Configuration Settings: ACSELERATOR Software.

- Step 6. Start the ACSELERATOR software operator interface. In the top toolbar HMI menu, click Meter and Control.
- Step 7. View phasors. Click the Phasors button of the HMI tree view. See *Figure 4.28*. The ACSELERATOR software displays fundamental line metering quantities with a display similar to *Figure 4.29*. (The test setup is adjusted for an approximately 30-degree lagging current.)



Figure 4.28 HMI Tree View: ACSELERATOR Software.

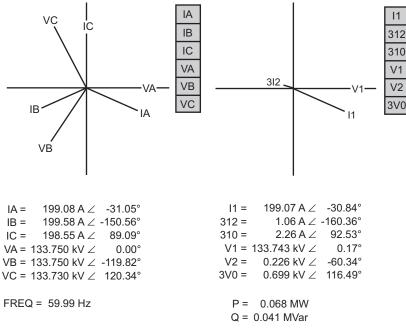


Figure 4.29 Phasor Metering Quantities: ACSELERATOR HMI.

Step 8. View metering data. Click the Instantaneous button of the HMI tree view to see metering information similar to the terminal display of *Figure 4.25*.

You can use the front-panel display and navigation pushbuttons to view the metering quantities of the SEL-421 Relay. See *METER on page U.5.11 in the User's Guide* for more information on viewing metering on the relay front panel. The screens in this procedure are for one circuit breaker, and this example assumes that you have not enabled the demand metering and synchronism check features.

- Step 1. Prepare to use the front panel. After applying power to the relay, note that the LCD shows a sequence of screens called the ROTATING DISPLAY. (If you do not operate the front panel for a certain period, the relay will enter front-panel time-out mode and you will see the sequential screens of the ROTATING DISPLAY.)
- Step 2. View the MAIN MENU. Press the **{ENT}** pushbutton to display the MAIN MENU at the top of *Figure 4.30*.
- Step 3. View the metering selection screen. Highlight the METER action item (see the first screen of *Figure 4.30*). Press the $\{ENT\}$ pushbutton. The relay displays the METER submenu (the second screen in *Figure 4.30*).
- Step 4. View the metering screens. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the FUNDAMENTAL METER action item (See *Figure 4.30*, middle screen). Press the {ENT} pushbutton. The relay displays the first FUNDAMENTAL METER screen (the third screen of *Figure 4.30*). Use the {Up} and {Down} arrow navigation pushbuttons to move among the fundamental line quantities metering screens.
- Step 5. Normalize the front-panel display. To exit metering, press the {ESC} pushbutton repeatedly to return to the MAIN MENU.

View Metering: Front Panel

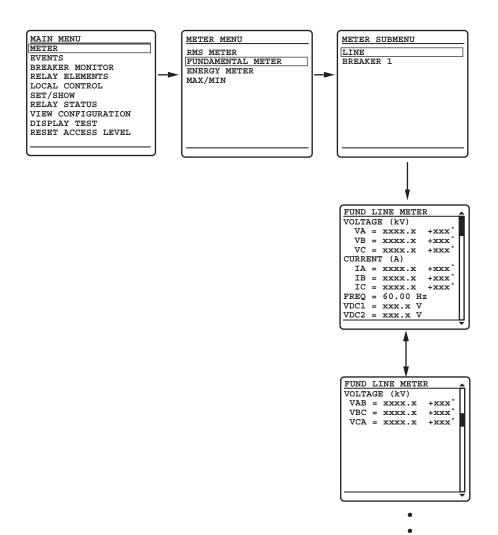


Figure 4.30 Front-Panel Screens for METER.

Reading Oscillograms, Event Reports, and SER

The SEL-421 Relay has great capabilities for storing and reporting power system events. These include high-resolution oscillography with sampling as high as 8 kHz, event reports that encompass important variables in the power system, and the SER that reports changing power system conditions and relay operating states.

You can view oscillograms taken from high-resolution raw data or from filtered event report data. Each type of presentation gives you a unique view of the power system. High-resolution oscillograms are useful for viewing system transients and dc artifacts outside the relay filter system; event report oscillograms give you a picture of the quantities that the relay used in the protection algorithms.

The examples listed in this subsection give step-by-step procedures to acquaint you with these features. *Section 3: Analyzing Data in the Applications Handbook* gives a complete discussion of these relay features.

Generating an Event To view high-resolution raw data oscillograms and event reports, you must generate a relay event. High-resolution oscillography and event reports use the same event triggering methods. The relay uses three sources to initiate a data capture: Relay Word bit TRIP asserts, SELOGIC control equation ER (event report trigger), and the **TRI** command. (Factory default setup no longer includes the **PUL** command as an event report trigger. You can add the **PUL** command by entering the Relay Word bit TESTPUL in the ER SELOGIC control equation.) See *Test Commands on page U.6.6 in the User's Guide*.

Triggering an Event

You can use an event trigger to initiate capturing power system data. The procedure in the following steps shows how to use the ACSELERATOR HMI to generate the **TRI** command, which triggers an event capture. In this example, the relay uses default parameters to record the event. These parameters are at a sampling rate (SRATE) of 2000 samples per second (2 kHz), a pretrigger or prefault recording length (PRE) of 0.1 seconds, and an event report length (LER) of 0.5 seconds. See *Duration of Data Captures and Event Reports on page A.3.6 in the Applications Handbook* for complete information on changing these default settings to match your application.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Checking Relay Status: ACSELERATOR Software on page 4.12* and *Section 3: PC Software in the User's Guide.* In addition, you should perform *View Metering: Terminal on page 4.31* to connect secondary test voltages and currents, and to set the relay to meter these quantities correctly.

Step 1. Connect voltage and current sources to the relay secondary voltage and secondary current inputs. Use the connections of *View Metering: Terminal on page 4.31* and *Figure 4.23* or *Figure 4.24*.

- Step 2. Apply power to the relay and establish communication. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 3. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 4. Start the ACSELERATOR software operator interface. In the top toolbar HMI menu, click Meter and Control.
- Step 5. View the Control Window. Click the Control Window button of the HMI tree view. See *Figure 4.31*. The ACSELERATOR software displays the Control Window similar to that in *Figure 4.32*.



Figure 4.31 ACSELERATOR HMI Tree View.

Metering Demand Reset	Peak Reset	Energy Reset	Maximum/Minimum Reset	Breaker 1 Wear Reset	Breaker 2 Wear Reset		
Records History Clear	STA Clear	SER Clear	Mirrored Bits A Clear	Mirrored Bits B Clear	Event Trigger		
Breaker 1 CLOSED		Close Trip	Breaker 2 CLO	SED	Close Trip		
-Pulse Output Outputs OUT101		conds	Pulse	1	Group		
Target, IRIG, Date, Time Date Time IRIG Sync							
Remote Bits 1 2 3	4 5 20 21	6 7 8 22 23 24	9 10 11		14 15 16 		

Figure 4.32 ACSELERATOR HMI Control Window.

Step 6. Trigger an event. Click the Event Trigger box. The ACSELERATOR software displays a prompt in a dialog box similar to that in *Figure 4.33*. Click Yes to trigger an event.

🛃 AcSELerator 🛛 🔣							
?	Trigge	er an event?					
Yes		<u>N</u> o					

Figure 4.33 Event Trigger Prompt: ACSELERATOR Software.

The SEL-421 Relay has two convenient methods for checking whether you successfully captured power system data. You can view the event history data with the ACSELERATOR software, or you can examine internal relay file folders for the recorded data.

Reading the Event History: ACSELERATOR Software

The procedure in the following steps shows how to use the ACSELERATOR HMI to gather relay event history information. See *Event History on page A.3.31 in the Applications Handbook* for more information on event history.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Checking Relay Status: ACSELERATOR Software on page 4.12* and *Section 3: PC Software in the User's Guide.*

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm that you have loaded the correct passwords in the ACSELERATOR software. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. View the event history report. Open the ACSELERATOR Analysis menu and click Read History. You will see the Relay Event History dialog box similar to that in *Figure 4.34*.

Reading the Event History

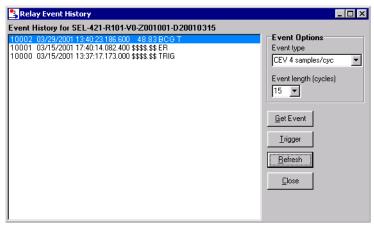


Figure 4.34 Relay Event History Dialog Box.

Reading the Event History: Terminal

The procedure in the following steps shows how to use the SEL-421 Relay file structure to confirm that you captured power system data with an event trigger. This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt.
- Step 2. Examine the event history. Type **HIS**<**Enter**>. You will see a screen display similar to *Figure 4.35 on page 4.42*.

=>>HIS<	Enter>								
RELAY	1		Dat	:e:	05/25/20	001 Ti	me:	21:12:	:16.974
Statio	on A		Ser	ial	Number:	2001	0012	234	
#	DATE	TIME	EVE	ΝT	LOCAT	CUR	R GF	RP TA	RGETS
10134	05/25/2001	21:10:56.948	ABC	Т	20.56	1998	1	INST	ZONE_1A_PHASE
10133	05/25/2001	21:10:41.715	ABC	Т	20.55	1998	1	INST	ZONE_1A_PHASE
10132	05/25/2001	21:10:35.482	ABC	Т	20.56	1997	1	INST	ZONE_1A_PHASE
=>>									

Figure 4.35 Sample HIS Command Output: Terminal.

For more information on the event history, see *Event History on page A.3.31 in the Applications Handbook.*

Once you have successfully generated an event, you can view high-resolution oscillograms and event report oscillograms about this event. When gathered from a field-installed relay, this information helps you assess power system operating conditions. In addition, when you first install the relay, this reporting information helps you confirm that you have connected the relay correctly.

The SEL-421 Relay outputs high-resolution oscillography data in the binary COMTRADE file format (*IEEE/ANSI standard C37.111-1999*). File transfer is the only mechanism for retrieving high-resolution COMTRADE data from

Viewing High-Resolution Oscillograms

the relay. The SEL-5601 Analytic Assistant is a program you can use to view COMTRADE data. Many third-party software suppliers can provide you with programs to display and manipulate COMTRADE files.

Retrieving High-Resolution COMTRADE Data: Terminal

The relay recorded the event triggered in *Triggering an Event on page 4.39*. The procedure in the following steps shows you how to retrieve the high-resolution raw oscillography data for this event. Perform the steps listed in *Triggering an Event on page 4.39* before executing the instructions in this example. For this procedure, you must use a communications terminal emulation computer program capable of file transfers (this function is not available in the ACSELERATOR software). If you need help finding a terminal emulation program, please contact the SEL factory or your local Technical Service Center.

- Step 1. Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt.
- Step 2. View the events file directory. Type **FILE DIR EVENTS <Enter>** to view the contents of the SEL-421 Relay events file directory. The relay lists file names for recently recorded events in a manner similar to that shown in *Figure 4.36 on page 4.43*. The relay shows three high-resolution oscillography files with the file extensions .HDR, .CFG, and .DAT for each event. This procedure uses HR_10001 as the number of the event that you recently triggered; use the event number corresponding to your triggered event.

=>>FILE DIR EVENTS <enter></enter>			
CHISTORY.TXT	RW		
HISTORY.TXT	RW		
C4_10001.TXT	RW	03/15/2001	00:25:45.384
C8_10001.TXT	RW	03/15/2001	00:25:45.384
E4_10001.TXT	RW	03/15/2001	00:25:45.384
E8_10001.TXT	RW	03/15/2001	00:25:45.384
HR_10001.HDR	RW	03/15/2001	00:25:45.384
HR_10001.CFG	RW	03/15/2001	00:25:45.384
HR_10001.DAT	RW	03/15/2001	00:25:45.384
=>>			

Figure 4.36 EVENTS Folder Files.

- Step 3. Prepare the relay to download the high-resolution oscillography files. Type **FILE READ EVENTS HR_10001.*<Enter>** to ready the relay to transfer the HR_10001.HDR, HR_10001.CFG, and HR_10001.DAT files to your computer.
- Step 4. Download the files. Perform the steps necessary for your terminal emulation program to receive a file. Typically, these are the file transfer steps:
 - Specify the destination file location in your computer file storage system and file name.
 - Select the transfer type as Y-Modem (if this transfer type is not already enabled).
 - > Click on Receive.

You will usually see a confirmation message when the file transfer is complete. When these files have transferred successfully, you have the entire COMTRADE file for the high-resolution raw data capture.

Step 5. Analyze the data. Use the SEL-5601 Analytic Assistant, SEL-5030 ACSELERATOR Software Program, or other COMTRADE-capable programs to play back high-resolution raw data oscillograms of the high-resolution raw data capture files you just transferred.

Retrieving High Resolution COMTRADE Data: ACSELERATOR Software

The procedure in the following steps shows how to use the ACSELERATOR software to view the event that you triggered in *Triggering an Event on page 4.39*. You can use this procedure to view other events stored in the SEL-421 Relay.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Checking Relay Status: ACSELERATOR Software on page 4.12* and *Section 3: PC Software in the User's Guide.*

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. View the Event History. Open the ACSELERATOR software Analysis menu and click Read History. You will see the Relay Event History dialog box similar to that shown in *Figure 4.37*.

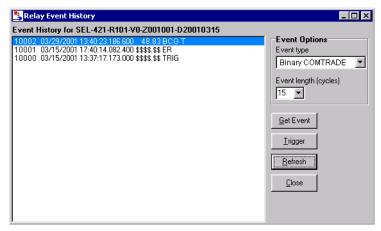


Figure 4.37 Relay Event History Dialog Box in the ACSELERATOR Software.

Step 4. Get the event. Select Binary COMTRADE in the Event Type dialog box. Highlight the event you want to view and click the Get Event button. The relay saves the .HDR, .CFG, and .DAT files in the ACSELERATOR 421\EVENTS\ directory with the HR_nnnnn file prefix (nnnn represents the event number). The ACSELERATOR software then presents the Event Waveform window similar to that in *Figure 4.38* and the sample event oscillogram of *Figure 4.39*.

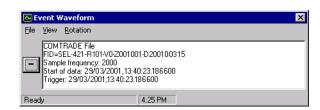


Figure 4.38 ACSELERATOR Event Waveform Window.

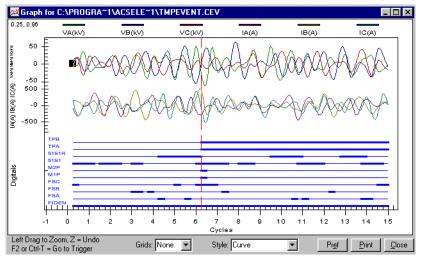


Figure 4.39 Sample Event Oscillogram.

You can also examine a phasors display, an event harmonic analysis display, and the event summary from the Event Waveform View menu. See *Analyze Events on page U.3.15 in the User's Guide* and *Section 3: Analyzing Data in the Applications Handbook* for more information.

Viewing Event Report Data

Examine relay event reports to inspect the operating quantities the SEL-421 Relay used at each triggered event. Unlike the raw data samples/second high-resolution oscillography files, these reports contain the filtered samples/cycle data the relay uses to make protection decisions. Event reports are useful for determining why the relay operated for a particular set of power system conditions. For more information on event reports, see *Event Report on page A.3.12 in the Applications Handbook*.

Retrieving Event Report Data Files: Terminal

The relay recorded the event triggered in *Triggering an Event on page 4.39*. The procedure in the following steps shows you how to retrieve the event report data files for this event. Perform the steps listed in *Triggering an Event on page 4.39* before executing the instructions in this example. For this procedure, you must use a terminal program capable of Ymodem protocol file transfer.

- Step 1. Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt.
- Step 2. View the events file directory. Type FILE DIR EVENTS
 <Enter>. The relay lists file names for recently recorded events in a manner similar to that shown in *Figure 4.36 on page 4.43*. In the figure, the relay shows two event report files: E4_10001.TXT and E8_10001.TXT, and two Compressed ASCII event report files: C4_10001.TXT and C8_10001.TXT.
- Step 3. Prepare the relay to download the 8-samples/cycle event report. Type **FILE READ EVENTS C8_10001.TXT<Enter>** to transfer the Compressed ASCII event report file to your computer.
- Step 4. Download the file. Perform the steps necessary for your terminal emulation program to receive a file. Typically, these are the file transfer steps:
 - Specify the destination file location in your computer file storage system and file name.
 - Select the transfer type as Y-Modem (if not already enabled).
 - > Click on Receive.
 - > You will usually see a confirmation message when the file transfer is complete.
- Step 5. When this file has transferred successfully, use the SEL-5601 Analytic Assistant to play back the event report oscillograms of the 8-samples/cycle event report file you just transferred.

Use the ASCII command **CEVENT** to retrieve event report files in Compressed ASCII format. See *SEL Compressed ASCII Commands on page R.5.6 in the Reference Manual* and *CEVENT on page R.8.5 in the Reference Manual* for more information.

Viewing SER Records The relay SER records relay operating changes and relay element states. In response to an element change of state, the SER logs the element, the element state, and a time stamp. Program the relay elements that the relay stores in the SER records, thus capturing significant system events such as an input/output change of state, element pickup/dropout, recloser state changes, etc. The

SEL-421 Relay stores the latest 1000 entries to a nonvolatile record. Use the relay communications ports or the ACSELERATOR software to view the SER records. For more information on the SER, see *Section 3: Analyzing Data in the Applications Handbook*.

Setting the SER and Examining an SER Record: ACSELERATOR Software

The procedure in the following steps shows you how to use the ACSELERATOR software to program relay elements into the SER. Also, use these procedures to review SER records with the ACSELERATOR software.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. Read the present configuration of the SEL-421 Relay. Download the present configuration in the SEL-421 Relay by opening the Settings menu, then click Read. The relay sends all configuration and settings data to the ACSELERATOR software.
- Step 4. View the SER settings entry screen. Click on the Report branch of the ACSELERATOR Settings tree view structure (See *Figure 4.40*). You will see the SER Points and Aliases window similar to *Figure 4.41*.



Figure 4.40 Selecting SER Points and Aliases Settings: ACSELERATOR Software.

SER Points and Aliases						
Select Word Bit, then drag and drop to setting below.						
Time and Date Eleme Output Elements Pushbutton Elements Data Reset Bits Mirrored Bits Mirrored Bits		BK1BFT BK2BFT GROUND PHASE_A PHASE_B PHASE_C	RSTTRGT TRGTR			
Name	Relay Word Bit, Alias Name, SET Alias, CLEAR Alias					
SITM1	TRGTR,TARGET RESET PB,TEST,OFF					
SITM2						

Figure 4.41 SER Points and Aliases Settings: ACSELERATOR Software.

- Step 5. Enter SER trigger settings. For this example, select Target Logic Bits in the Relay Word bits list (See *Figure 4.41*). Click and drag the TRGTR Relay Word bit to the SER Points and Aliases text box for Element Name 1 (labeled SITM1). If you want the relay to display an alias for the element, enter an alias name of 20 or fewer characters following the comma after TRGTR. For this example, type **TARGET RESET PB**. Similarly, type **,TEST,OFF** to enter a Set Alias and a Clear Alias. Click in any other row or push Tab; the ACSELERATOR software validates your entry. You can enter as many as 250 relay elements in the SER Points and Aliases list.
- Step 6. Save the new settings in the ACSELERATOR software. On the File menu, click Save.
- Step 7. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the first dialog box of *Figure 4.42*. Click the check box for Report. Click OK. The ACSELERATOR software responds with the second dialog box of *Figure 4.42*. If you see no error message, the new settings are loaded in the relay.

Settings Class Select	×
Select Classes to Send Automation 8 Automation 10 Output Front Panel Port 1 Port 2 Port 3 Port F Cancel	
Transfer Status	
Writing 1 of 1	
Sending File: SETTINGS\SET_01.TXT Sending settings	ncel

Figure 4.42 Uploading Report Settings to the SEL-421 Relay.

- Step 8. Generate an SER record. Press and release the front-panel {TARGET RESET} pushbutton.
- Step 9. View the SER report. Start the ACSELERATOR software operator interface. In the top toolbar HMI menu, click Meter and Control. Click the SER button of the HMI tree view. See *Figure 4.43*. The ACSELERATOR software displays the SER records with a display similar to *Figure 4.44*.

NOTE: The Relay Editor dialog boxes shown in Figure 4.42 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.



Figure 4.43 Retrieving SER Records With the ACSELERATOR Software.

SE Rel:	H av 1		Date: 03	3/15/2001 Time: 08:09:05.480	
Station A			Serial Number: 2001001234		
FID	=SEL-421-R101	-V0-Z001001-D20	0010315		
#	DATE	TIME	ELEMENT	STATE	
5	03/15/2001	07:30:52.861	Power-up	Group 1	
4	03/15/2001	07:30:52.861	Relay	Enabled	
3	03/15/2001	07:31:24.293	Settings changed	Class R 1	
2	03/15/2001	08:09:02.770	TARGET RESET PB	TEST	
1	03/15/2001	08:09:03.791	TARGET RESET PB	OFF	
s	ER 30	то	Upda	ate SER	

Figure 4.44 SER Records in the ACSELERATOR HMI.

The relay lists the SER records in chronological order from top to bottom as shown in *Figure 4.44*. In addition, the relay numbers each record with the most recent record as number 1; new events are usually more important for determining the effects of recently occurring power system events. For each application of power to the relay, the SER reports a "Power-up" indication and the active settings group (Group 1 in *Figure 4.44*). A properly operating relay immediately goes to the enabled state, an event that causes the SER to report another SER record. The SER reports the TARGET RESET button when you first press the pushbutton. When you release the pushbutton, the SER records the pushbutton release. For more information on the Sequential Events Recorder, see *SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook*.

Setting the SER and Examining the SER Record: Terminal

The procedure in the following steps shows how to use a terminal connected to an SEL-421 Relay communications port to set an element in the SER. Use text edit mode line editing to enter the SER settings; see *Text-Edit Mode Line Editing on page 4.21*. Also included is a procedure for viewing the SER report with a terminal. For more information on the SER, see *SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook*.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the =>

action prompt. Type the **2AC**<**Enter**> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.

Step 2. Enter SER trigger data. Type SET R TERSE<Enter> to access the Report settings (See *Figure 4.45*). Type <Enter> to move past the SER Chatter Criteria setting. At the SER Points and Aliases action prompt line, type TRGTR,"TARGET RESET PB",TEST,OFF<Enter>. At the next line, type END<Enter>. The relay prompts you to save the new setting; type Y<Enter>.

=>>SET R TERSE<Enter>

```
Report

SER Chatter Criteria

Automatic Removal of Chattering SER Points (Y,N) ESERDEL := N ?<Enter>

SER Points and Aliases

(Relay Word Bit, Alias Name, Alias for Set State, Alias for Clear State)

1:

? TRGTR, "TARGET RESET PB", TEST, OFF

2:

? END<Enter>

Save settings (Y,N) ?Y<Enter>

Saving Settings, Please Wait......

Settings Saved

=>>
```

Figure 4.45 Setting an SER Element: Terminal.

- Step 3. Generate an SER record. Press and release the front-panel {TARGET RESET} pushbutton.
- Step 4. View the SER report. Type **SER<Enter>** (at the Access Level 1 prompt or higher). The relay presents a screen similar to the SER display of *Figure 4.44*.

Downloading an SER Report File

The procedure in the following steps shows you how to retrieve the SER report stored in the relay as a file. For this procedure you must use a terminal emulation program with file transfer capability. For more information on the SER, see *SER* (*Sequential Events Recorder*) on page A.3.34 in the Applications Handbook.

- Step 1. Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt.
- Step 2. View the events file directory. Type FILE DIR REPORTS <Enter>. The terminal lists the file names for standard reports as shown in *Figure 4.46*.
- Step 3. Prepare the relay to download SER report. Type **FILE READ REPORTS SER.TXT<Enter>**. If you want the Compressed ASCII file, type **FILE READ REPORTS CSER.TXT<Enter>**.

=>FILE DIR REPORTS <enter></enter>	
BRE_1.TXT	R
BRE_2.TXT	R
BRE_S1.TXT	R
BRE_S2.TXT	R
CBRE.TXT	R
CHISTORY.TXT	R
CSER.TXT	R
HISTORY.TXT	R
SER.TXT	R
=>	

Figure 4.46 Reports File Structure.

- Step 4. Download the SER report. Perform the steps necessary for your terminal emulation program to receive a file. Typically, these are the file transfer steps:
 - Specify the destination file location in your computer file storage system and file name.
 - Select the transfer type as Y-Modem (if not already enabled).
 - ➤ Click on Receive.

You will usually see a confirmation message when the file transfer is complete.

Step 5. Confirm a successful download. When the SER.TXT file has transferred successfully, use a word-processing program to view the contents of the file. You will see the SER records in a format similar to *Figure 4.44*. The CSER.TXT file viewed with a word-processing program is similar to the example in CSER, SER (Sequential Events Recorder), in *CSER on page A.3.35 in the Applications Handbook*.

Operating the Relay Inputs and Outputs

The SEL-421 Relay gives you great ability to perform control actions at bay and substation locations via the relay control outputs. The control outputs close and open circuit breakers, switch disconnects, and operate auxiliary station equipment such as fans and lights. The relay reads data from the power system and interfaces with external signals (contact closures and data) through the control inputs. This subsection is an introduction to operating the SEL-421 Relay control outputs and control inputs. For more information on connecting and applying the control outputs and control inputs, see *Section 2: Installation in the User's Guide*.

Control Output The SEL-421 Relay features Standard, Hybrid (High-Current Interrupting), and Fast Hybrid (Fast High-Current Interrupting) control outputs that you can use to control circuit breakers and other devices in an equipment bay or substation control house. See *Control Outputs on page U.2.6 in the User's Guide* for more information on control outputs.

Pulsing a Control Output: Terminal

When first connecting the relay, or at any time that you want to test relay control outputs, perform the following procedure. The procedure in the following steps shows how to use a communications terminal to pulse the control output contacts. Perform the steps in this example to become familiar with relay control and serial communication. For more information on the **PULSE** command, see *PULSE* on page *R.8.36* in the Reference Manual.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to control the relay at Access Level B. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the BAC<Enter> command, and then type the correct password to go to Access Level B. You will see the ==> action prompt.
- Step 2. Connect an output monitor. Attach an indicating device (ohmmeter with a beep sounder or a test set) to the terminals for control output OUT104. This output is a Standard control output and is not polarity sensitive. For more information on connecting control outputs, see *Control Outputs on page U.2.6 in the User's Guide*.
- Step 3. Perform the pulse operation. Type **PULSE OUT104<Enter>**. The relay confirms your request to pulse an output with a prompt such as that shown in *Figure 4.47*. Type **Y<Enter>** at the prompt. You will see or hear the indicating device turn on for a second and then turn off.

==>PULSE OUT104 <Enter>

Pulse contact OUT104 for 1 seconds(Y/N) ?Y<Enter>

>

Figure 4.47 Terminal Display for PULSE Command.

NOTE: To PULSE an output, the circuit breaker control enable jumper, J18C, must be installed on the main board.

You can also pulse an output for longer than the default 1-second period. If you enter a number after the PULSE command, that number specifies the duration in seconds for the pulse. For example, if you enter **PULSE OUT104 3**<**Enter**>, the relay pulses OUT104 for 3 seconds.

Pulsing a Control Output: Front Panel

The procedure in the following steps shows you how to use the front-panel display and navigation pushbuttons to check for proper operation of the SEL-421 Relay control outputs. See *Section 5: Front-Panel Operations in the User's Guide* for information on using the relay front panel.

- Step 1. Connect an output monitor. Attach an indicating device (an ohmmeter with a beep sounder or a test set) to the terminals for control output OUT104. This output is a Standard control output and is not polarity sensitive. For more information on connecting control outputs, see *Control Outputs on page U.2.6 in the User's Guide*.
- Step 2. View the front-panel display. After applying power to the relay, note that the LCD shows a sequence of screens called the ROTATING DISPLAY. (Also, if you do not operate the front panel for a certain period, the relay will enter front-panel time-out mode and you will see the sequential screens of the ROTATING DISPLAY.)
- Step 3. View the MAIN MENU. Press the **{ENT}** pushbutton to cause the relay to display a MAIN MENU similar to that at the top of *Figure 4.48*.

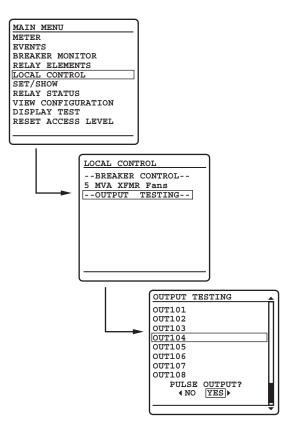


Figure 4.48 Front-Panel Menus for Pulsing OUT104.

- Step 4. View the local control screen. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the LOCAL CONTROL action item (See *Figure 4.48*). Press the {ENT} pushbutton. You will see the LOCAL CONTROL submenu (the middle screen in *Figure 4.48*).
- Step 5. View the output testing screen. Press the {Up} and {Down} arrow navigation pushbuttons to highlight the --OUTPUT TESTING-- action item (See *Figure 4.48*, middle screen). Press the {ENT} pushbutton. The relay next displays the OUTPUT TESTING submenu (the last screen of *Figure 4.48*).
- Step 6. Command the relay to pulse the control output. Press the {**Up**} and {**Down**} arrow navigation pushbuttons to highlight OUT104 (See *Figure 4.48*, last screen). Press the {**RIGHT**} arrow navigation pushbutton to highlight YES under "PULSE OUTPUT?" Press the {**ENT**} pushbutton. The relay detects your request for a function at an access level for which you do not yet have authorization. Whenever this condition occurs, the relay displays the password access screen of *Figure 4.49*.

<u>P</u> 2	ASS	SWO	DRI		REG	2U.	IRED	_
A	в	C	D	Е	F	G	н	
Ι	J	ĸ	г	М	Ν	0	Ρ	
Q	R	S	т	U	v	W	Х	
Y	\mathbf{Z}	a	b	С	d	е	f	
g	h	i	j	k	1	m	n	
	р	q	r	s	t	u	v	
w	x	y	\mathbf{z}	0	1	2	3	
4	5	6	7	8	9			
AC	CCI	SP1	C .	BZ	ACI	(SI	PACE	

Figure 4.49 Password Entry Screen.

Step 7. Input a password and pulse the output. Enter a valid Access Level B, P, A, O, or 2 password. (The front panel is always at Access Level 1, so you do not enter the Access Level 1 password.) Enter a valid password by using the navigation pushbuttons to select, in sequence, the alphanumeric characters that correspond to your password. Press the {ENT} pushbutton at each password character. (If you make a mistake, highlight the BACKSPACE option and press {ENT} to reenter a character or characters.) After entering all password characters, press the {Up} arrow or {Down} arrow pushbuttons to highlight ACCEPT, and press {ENT}. The relay pulses the output, and you will see the indicating device turn on for a second and then turn off.

Controlling a Relay Control Output With a Local Bit: Terminal

In this example, you set Local Bit 3 to start the transformer cooling fans near the breaker bay where you have installed the SEL-421 Relay. Thus, you can use the LCD screen and navigation pushbuttons to toggle relay Local Bit 3 to control the state of the cooling fans. For more information on local bits, see *Local Control Bits on page U.5.18 in the User's Guide*.

The procedure in the following steps proposes connecting the transformer bank fan control to relay output OUT105. You can choose any relay output that conforms to your requirements. See *Control Outputs on page U.2.6 in the User's Guide* for more information on SEL-421 Relay control outputs.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 2. Access the local control settings. Type SET F <Enter> command. Repeatedly type > and then <Enter> to advance through the front-panel settings until you reach the Display Points and Aliases category. Press <Enter> to access the Control Points and Aliases Category. Figure 4.50 shows a representative terminal screen.

```
Control Points and Aliases
(Local Bit, Alias Name, Alias for Set State, Alias for Clear State,
Pulse Enable)
1:
? LIST<Enter>
1:
? LB03,"5 MVA XFMR Fans","ON","OFF",N<Enter>
2:
? END<Enter>
Control Points and Aliases
(Local Bit, Alias Name, Alias for Set State, Alias for Clear State,
Pulse Enable)
1: 1803."5 MVA XMER Fans"."ON"."OFF".N
Save settings (Y,N) ?Y<Enter>
Saving Settings, Please Wait.....
Settings Saved
 =>>
```

Figure 4.50 Using Text-Edit Mode Line Editing to Set Local Bit 3.

- Step 3. List the active control points. Type **LIST<Enter>** at the Local Control and Aliases prompt, This example assumes that you are using no local bits, so the relay returns you to line "1:" followed by the "?" settings action prompt.
- Step 4. Create Local Bit 3. Type LB03,"5 MVA XFMR Fans","ON","OFF",N<Enter> at the line 1 prompt:
 - 1: LB03,"5 MVA XFMR Fans","ON","OFF",N<Enter>

The relay checks that this is a valid entry and responds with the next line prompt "2:" followed by the "?" settings action prompt.

Step 5. End the settings session. Type **END**<**Enter**>. The relay scrolls a readback of all the front-panel settings, eventually displaying the "Save settings (Y,N) ?" prompt. (In *Figure 4.50* a vertical ellipsis represents the readback.) At the end of the readback information, just before the "Save settings (Y,N) ?" prompt, you can see the new local bit information. Answer **Y**<**Enter**> to save your new settings.

Step 6. Set OUT105 to respond to Local Bit 3. Type SET O OUT105<Enter> (See *Figure 4.51*). At the ? action prompt, type LB03<Enter>. At the next ? action prompt, type END<Enter>. When prompted to save settings, answer Y<Enter>.

=>> SET 0 OUT105<enter></enter> Output	
Main Board	
OUT105 :== NA ? LBO3 <enter></enter>	
OUT106 := NA	
? END <enter> Output</enter>	
Main Board	
OUT101 := 3PT AND NOT PLT04 OUT102 := 3PT AND NOT PLT04 OUT103 := BK1 CL AND NOT PLT04 OUT104 := KEY AND PLT02 AND NOT PLT04 OUT105 := LB03 OUT106 := NA OUT107 := PLT04 OUT108 := NOT (HALARM OR SALARM)	
Save settings (Y,N) ? Y<enter></enter> Saving Settings, Please Wait Settings Saved =>>	

Figure 4.51 Setting Control Output OUT105: Terminal.

Step 7. Test the connection and programming. Use the appropriate interface hardware to connect the fan control start circuit to OUT105. At the relay front-panel MAIN MENU, select LOCAL CONTROL and press the {ENT} pushbutton (See *Figure 4.52*). Select 5 MVA XFMR Fans on the LOCAL CONTROL screen as shown in *Figure 4.52*. Press {ENT} to see the last screen of *Figure 4.52*. Highlight "1 ON" and press {ENT}. The graphical local control handle moves to the 1 position. At this time, the transformer fans will begin running.

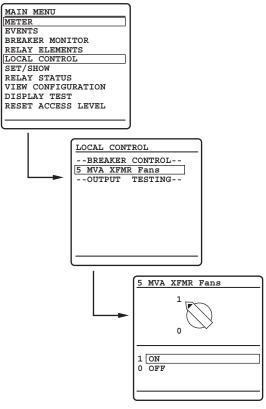


Figure 4.52 Front-Panel LOCAL CONTROL Screens.

Setting Outputs for Tripping and Closing

To actuate power system circuit breakers, you must configure the SEL-421 Relay control outputs to operate the trip bus and close bus. The relay uses internal logic and SELOGIC control equations to activate the control outputs.

Trip Output Signals

The SEL-421 Relay is capable of single-pole tripping and three-pole tripping. There are many Relay Word bits (e.g., TPA1, TPA2, RTA1, and 3PT) that you can program to drive control outputs to trip circuit breakers. See *Section 1: Protection Functions in the Reference Manual* for complete information on tripping equations and settings. For target illumination at tripping, see *Section 5: Front-Panel Operations in the User's Guide*.

Close Output Signals

The SEL-421 Relay features an automatic recloser for single circuit breaker and two circuit breaker applications. The relay provides as many as two single-pole and four three-pole reclose shots. See *Section 2: Auto-Reclose and Synchronism Check in the Reference Manual* for more information. Close the circuit breakers using Relay Word bits BK1CLS and BK2CLS for Circuit Breaker 1 and Circuit Breaker 2, respectively.

Assigning Control Outputs for Tripping and Closing

The procedure in the following steps shows a method for setting the relay to operate the trip bus and the close bus at a typical substation. Relay factory defaults assign control outputs OUT101 and OUT102 to the trip bus and OUT103 to the close bus for a three-pole tripping circuit breaker. This procedure assigns an additional close output at OUT106.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. Read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all configuration and settings data to the ACSELERATOR software.
- Step 4. Access the Main Board output settings. Expand the Outputs branch of the Settings tree view. Click on Main Board (See *Figure 4.53*).

🖅 🗢 Global	Main Board Outputs	
🗄 🔍 🕒 Breaker Monitor		
⊞… ● Group 1	OUT101 Main Board Output OUT101 (SELogic equation)	
🗄 🔍 🕒 Group 2	(3PT OR TPA1) AND NOT PLT04 #THREE POLE TRIP	EB
🗄 💿 Group 3		
⊞ ● Group 4	OUT102 Main Board Output OUT102 (SELogic equation)	
⊞ ● Group 5	(3PT OR TPA1) AND NOT PLT04 #THREE POLE TRIP	EB
🕀 🗢 Group 6	OUT103 Main Board Output OUT103 (SELogic equation)	
Automation Logic	BK1CL AND NOT PLT04 #BREAKER CLOSE COMMAND	EB
Outputs	12	ED
Main Board	OUT104 Main Board Output OUT104 (SELogic equation)	
Interface Board Outputs	KEY AND PLT02 AND NOT PLT04 #KEY TX	EB
 Communication Card Outputs Mirrored Bits Transmit Equations 	OUT105 Main Board Output OUT105 (SELogic equation)	
Grant Panel	NA	EB
E···· Report		
ONP Map Settings	OUT106 Main Board Output OUT106 (SELogic equation)	
Communications Ports	BK1CL AND NOT PLT04 #BREAKER CLOSE COMMAND	EB
	OUT107 Main Board Output OUT107 (SELogic equation)	
	PLT04 #RELAY TEST MODE	EB
	OUT108 Main Board Output OUT108 (SELogic equation)	
	NOT(SALARM OR HALARM)	EB

Figure 4.53 Assigning an Additional Close Output: ACSELERATOR Software.

- Step 5. Assign a control output for the close bus. In the Main Board Outputs dialog box click in the OUT106 text box and type BK1CL AND NOT PLT04#BREAKER CLOSE COMMAND. (The # indicates that a comment follows.) Click or tab to another text box. The ACSELERATOR software checks that your entry is valid.
- Step 6. Save the new settings in the ACSELERATOR software. On the File menu, click Save.

Step 7. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class or instance you want to send to the relay. Click the check box for Outputs as shown in the first dialog box of *Figure 4.54*. Click OK. The ACSELERATOR software responds with the second dialog box of *Figure 4.54*. If you see no error message, the new settings are loaded in the relay.

Settings Class Select	×
Select Classes to Send	
Automation 6 Automation 7 Automation 8 Automation 9 Automation 10	
Contract Co	OK Cancel
Fransfer Status	
Writing 1 of 1	
Sending File: SETTINGS\SET	_01.TXT
Sending settings	Cancel

Figure 4.54 Uploading Output Settings to the SEL-421 Relay.

Control Input Assignment

The SEL-421 Relay features high-isolation direct connection control inputs that the relay uses to detect contact closures and signal level changes in an equipment bay or substation control house. See *Control Inputs on page U.2.6 in the User's Guide* for more information on control inputs.

If all of the control inputs share common signal properties of assertion level, debounce time, and dropout or deassertion level, you can enter these settings for all inputs. These settings are **GINP**, **GIND**, and **GINDF** for global input pickup level, global input debounce, and global input dropout (hysteresis) factor, respectively. See *Global Settings on page R.9.3 in the Reference Manual* for more information. When you enable setting EICIS (Enable Independent Control Input Settings), you can set separate specific assert/deassert levels and debounce times for control inputs that are exceptions to these global control input settings.

Setting a Control Input: Circuit Breaker Auxiliary Contacts (52A): Terminal

This is a step-by-step procedure to configure a control input that reflects the state of the circuit breaker auxiliary (52A) NO (normally open) contact. A common relay input is from circuit breaker auxiliary contacts; the relay monitors the 52A contacts to detect the closed/open status of the circuit breaker. Perform the following steps to connect three-pole circuit breaker auxiliary contacts to the SEL-421 Relay. This example is for a 125 Vdc system; the open state of the auxiliary contacts is 0 Vdc (circuit breaker open), and the closed state of the auxiliary contacts is approximately 125 Vdc (circuit breaker closed). The voltage drop in the connecting wires from the auxiliary contacts through the station battery to the relay gives a slightly lower voltage than the station battery at the relay control input terminals. The default value for GINP (Global Control Input Pickup Level) at 85 Vdc is sufficient.

NOTE: The Relay Editor dialog boxes shown in Figure 4.54 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar. This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 2. Configure the relay to read the circuit breaker auxiliary contact. Type **SET M<Enter>** (See *Figure 4.55*). These settings are the breaker monitor settings. Type **<Enter>** to bypass the Breaker 1 Monitoring enable, and **<Enter>** again to bypass the Breaker 2 Monitoring enable (NUMBK := 2 in this example). At the BK1TYP setting, type **3<Enter>** for a three-pole circuit breaker for this particular example. (Use the setting BK1TYP appropriate for your circuit breaker(s).) At the BK2TYP setting, type **3**<**Enter>** for a three-pole circuit breaker for this example. The relay next displays the 52AA1 SELOGIC control equation action prompt. Type IN101<Enter> at the ? prompt to specify input IN101 as the control input that represents the close/open state of Circuit Breaker 1. The relay next displays the 52AA2 SELOGIC control equation action prompt. Type **IN102<Enter>** at the ? prompt to specify input IN102 as the control input that represents the close/open state of Circuit Breaker 2.
- Step 3. End the settings process. The relay next scrolls a readback of all the Global settings, eventually displaying the "Save settings (Y,N) ?" prompt. In the readback information, just before the "Save settings (Y,N) ?" prompt, you can confirm the new control input information. Answer **Y**<**Enter>** to save your new settings.

=>>SET M<Enter> Breaker Monitor Breaker Configuration Breaker 1 Monitoring (Y,N) EB1MON := N ? <Enter> Breaker 2 Monitoring (Y,N) Breaker 1 Trip Type (Single Pole=1,Three Pole=3) Breaker 2 Trip Type (Single Pole=1,Three Pole=3) EB2MON := N ? <Enter> $\begin{array}{rcl} \mathsf{BK1TYP} & := 1\\ \mathsf{BK2TYP} & := 1 \end{array}$?3<Enter> ? 3<Enter> Breaker 1 Inputs N/O Contact Input -BK1 (SELogic Equation) 52AA1 := NA ? IN101<Enter> Breaker 2 Inputs A-Phase N/O Contact Input -BK2 (SELogic Equation) 52AA2 := NA ? IN102<Enter> Breaker Monitor Breaker Configuration BK2TYP := 3 EB1MON := N EB2MON := N BK1TYP := 3 Breaker 1 Inputs 52AA1 := IN101 Breaker 2 Inputs 52AA2 := IN102 Save settings (Y,N) ?Y<Enter> Saving Settings, Please Wait..... Settings Saved =>>

Figure 4.55 Setting 52AA1: Terminal.

Setting a Control Input for Circuit Breaker Auxiliary Contacts (52A): ACSELERATOR Software

The procedure in the following steps shows how to program the SEL-421 Relay control input IN101 to read the state of circuit breaker auxiliary contacts. This example uses a single three-pole tripping breaker. Modify the procedure listed here for your application.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords. You should also be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. Read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all configuration and settings data to the ACSELERATOR software.
- Step 4. Access the Global Enable settings. Click on the + mark next to the Global branch of the Settings tree view. Click on the Global Settings/Enables branch of the Settings tree view. See *Figure 4.56*.
- Step 5. Change settings. Set EICIS (Independent Control Input Settings) to Y by clicking the Y button.

	 Global Global Settings/Enables Global Settings/Enables Global Settings/Enables General Global Settings Station DC Monitoring Station A RiD Relay Identifier (40 characters) Relay 1 TIDW Terminal W Identifier (40 characters) Breaker 1 Breaker 2 NUMBK Number Breakers in Scheme 1 C 2 BID1 Breaker 1 Identifier (40 characters) Breaker 2 MUMBK Number Breakers in Scheme 1 C 2 BID1 Breaker 1 Identifier (40 characters) Breaker 2 BID1 Breaker 1 Identifier (40 characters) Breaker 2 Monitor 1 C 2 BID1 Breaker 1 Identifier (40 characters) Breaker 2 MID Relay I C 2 BID1 Breaker 1 Identifier (40 characters) Breaker 2 Monitor 1 C 2 BID2 Breaker 2 Identifier (40 characters) Breaker 2 Monitor 1 C 2 BID2 Breaker 2 Identifier (40 characters) Breaker 2 MID Relay I C 2 BID Are Format MDY C YMD C DMY FAULT Fault Condition Equation (SELOGIC) Fault T Fault Condition Equation (SELOGIC) 	
Global Settings/Enables Global Settings/Enables Station DC Monitoring Site and DC Monitoring B- Control Inputs Site and DC Monitoring B- Settings Group Selection Finequency Estimation B- Data Reset Finequency Estimation B- Time and Date Management Ind V Source Selection B- Breaker Monitor Breaker Monitor B- Group 1 TIDW Terminal W Identifier (40 characters) Breaker Monitor Breaker 1 B- Group 2 DUMBK Number Breakers in Scheme Group 3 Go 1 B- Group 4 BID1 Breaker 1 B- Group 5 BiD1 Breaker 1 B- Group 6 NFREQ Nominal System Frequency C Tor Panel NFREQ Nominal System Frequency B- Report So 60 B- Onthy Pans Settings DATE_F Date Format C MDY C YMD C DMY Automation Logic	I JOPT OR STST OR M2P OR Z2G OR M3P OR Z3G	General Global Settings SID Station Identifier (40 characters) Station A RID Relay Identifier (40 characters) Relay 1 TIDW Terminal W Identifier (40 characters) Breaker 1 Breaker 1 © 1 © 2 BID1 Breaker 1 Identifier (40 characters) Breaker 1 Breaker 1 BID2 Breaker 2 Identifier (40 characters) BID2 Breaker 2 Identifier (40 characters) Breaker 1 Breaker 1 Breaker 1 Breaker 1 BID2 Breaker 2 Identifier (40 characters) Breaker 1 Breaker 1 Breaker 2 NFREQ Nominal System Frequency © 50 © 60 PARC ACB DATE_F Date Format © MDY MDY FAULT Fault Condition Equation (SELOGIC)
		EDCMON Station DC Monitoring N C 1 C 2 EICIS Independent Control Input Settings
Global Settings/Enables Station DC Monitoring Outrol Inputs Settings Group Selection Data Reset Data Reset Otranel Amagement I and V Source Selection Group 1 Group 2 Group 2 Group 5 Group 5 Group 5 Outputs Outputs P Report P OINP Map Settings		

Figure 4.56 Accessing Global Enable Settings in the ACSELERATOR Software.

Step 6. Access the Control Inputs settings. In the expanded Global Settings tree view, click on the plus (+) mark next to Control Inputs. Click on Main Board. You will see the input window similar to that in *Figure 4.57*.

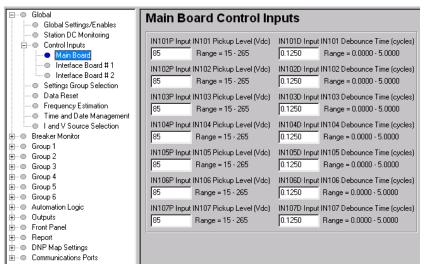


Figure 4.57 Control Input Settings in the ACSELERATOR Software.

Step 7. Set the control input IN101 debounce time. For this example, assume that the auxiliary contacts are slow and noisy; you must provide a slightly longer debounce time for these contacts. Double-click the mouse cursor (or use the Tab key) to highlight IN101D Input101 Debounce Time. Delete the present setting by using the Delete key. Type **0.25<Enter>**. The relay checks the new value and enters the value in the ACSELERATOR database.

- Step 8. Set the control input IN101 pickup threshold. For this example, obtain added security by setting the threshold voltage higher than the default. Click the mouse cursor (or use the Tab key) to highlight IN101P Main Board Input 101 Assertion Level. Delete the present setting by using the Delete key. Type 100, and then click or Tab to another value. The relay checks the new value and enters the value in the ACSELERATOR database.
- Step 9. Configure the relay to read the circuit breaker auxiliary contact. Expand the Breaker Monitor branch of the Settings tree view by clicking the "+" button (See *Figure 4.58*). In the tree view, click on Breaker Monitor to select circuit breaker monitor settings for Circuit Breaker 1. At the BK1TYP setting, click 3 for the three-pole circuit breaker of this particular example. (Use the setting BK1TYP appropriate for your circuit breaker(s).) Click the Breaker 1 branch as shown in *Figure 4.59*. Set the 52AA1 SELOGIC control equation by clicking in the text box labeled N/O Contact Input –BK1. Type IN101, and then click or tab to another field to specify input IN101 as the control input that represents the close/open state of Circuit Breaker 1.

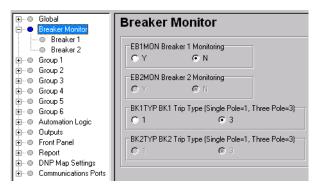


Figure 4.58 Setting BK1TYP in the ACSELERATOR Software.

Global Breaker Monitor Breaker 1 Breaker 2	Breaker 1 Breaker 1 Inputs 52AA1 N/O Contact Input - BK1 (SELogic Equation)
🗄 🔍 🕒 Group 1	IN101 EB
🗄 🖷 Group 2	52AB1 B-Phase N/O Contact Input -BK1 (SELOGIC)
🗄 🔍 🕒 Group 3	52AA1 EB
🗄 🖷 🔲 Group 4	
🗄 🖷 Group 5	52AC1 C-Phase N/O Contact Input -BK1 (SELOGIC)
🕂 🔍 🕒 Group 6	52AA1 EB
🗄 🖷 🕒 Automation Logic	

Figure 4.59 Setting 52AA1 in the ACSELERATOR Software.

- Step 10. Save the new settings in the ACSELERATOR software. On the File menu, click Save.
- Step 11. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class or instance you want to send to the relay. Click the check box for Global and the check box for Breaker Monitor, as shown in the first dialog box of *Figure 4.60*. Click OK. The ACSELERATOR software responds with the second dialog box of *Figure 4.60*. If you see no error message, the new settings are loaded in the relay.

NOTE: The Relay Editor dialog boxes shown in Figure 4.60 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

Settings Class Select	×
Select Classes to Send	
Group 3 Group 4 Group 5 Group 5 Automation 1 Automation 2	OK Cancel
Transfer Status	
Writing 1 of 1	
Sending File: SETTINGS\SET_G1.T Sending settings	XT Cancel

Figure 4.60 Uploading Global and Breaker Monitor Settings to the SEL-421 Relay.

Configuring High-Accuracy Timekeeping

	these modes are IR reports and SER da information on hig <i>Oscillography on p</i>	EL-421 Relay in two high-accuracy timekeeping IG mode and PPS mode. The relay can time-state to 10 μ s accuracy with a proper time reference h-accuracy timekeeping and state estimation, see bage A.3.8 in the Applications Handbook, and See Measurements in the Applications Handbook.	mp event e. For more e
IRIG-B	(Inter-Range Instru receiver, etc.). The year time stamping verify that the SEL command to view of <i>Reference Manual</i>) maintain the proper	me signals from many sources that produce the l imentation Group-B) time code format (SEL-202 IRIG-B signal includes code for time-of-day an the signal does not include a code to identify the -421 Relay calendar is set to the proper year, use for change the date (see <i>DATE on page R.8.17 in</i>). The relay stores the year in nonvolatile memory r year even if relay power cycles off and on. The month, and day in nonvolatile memory while relay	30, GPS d day-of- he year. To the DATE <i>the</i> ty and will relay also
	pulses divided into	data format consists of a 1-second frame contair fields. The relay decodes the second, minute, ho internal time clock upon detecting valid time dat	ur, and day
	IRIG-B input signa to IRIG mode when	the input IRIG-B signal must be less than ± 3 m al meets this requirement, the relay switches auton n relay setting ETIRIG := Y (default). See <i>Auton</i> <i>n page 4.66</i> for more information.	omatically
1k PPS	of a GPS receiver. 1000 PPS (1k PPS) power system even 1k PPS satellite tim receivers from vari option. Be sure that	the	IG-B and tamping of rom the equency in ordering
	IRIG-B input that i 1k PPS signal with meet this requirem	automatically to PPS mode timekeeping if you is stable to within $\pm 200 \ \mu s$ of the 1k PPS signal, absolute stability of $\pm 500 \ ns$ (0.5 μs). If the two ent, the relay automatically switches to PPS mode S := Y (default). See <i>Automatic Time Source Sel</i> information.	and a o signals de when
Automatic Time Source Selection	the timekeeping au	y automatically switches time source inputs. <i>Tab</i> tomatic switching enable settings.	ole 4.8 lists
		ource Automatic Switching Enable Settings	
	Setting	Description	Default
	ETIRIG	IRIG Time Source (Y, N)	Y
	ETPPS	PPS/IRIG Time Source (Y, N)	Y

With ETIRIG and ETPPS set to Y, the relay at power up first attempts to achieve PPS mode. If the relay cannot find a 1k PPS source coupled to an IRIG-B source, or if the relay determines the sources are unreliable, then the

relay switches to IRIG mode. When ETPPS := Y and ETIRIG := N, the relay uses PPS timing mode for a valid 1k PPS signal locked to an IRIG-B input signal. If the PPS source becomes unavailable, the relay does not switch to IRIG mode.

If the IRIG-B time source is unavailable or is unreliable, then the relay switches to a lower-priority source (DNP, MIRRORED BITS, and ASCII, for example). The relay automatically switches up to a higher priority time source (PPS/IRIG-B, or IRIG-B only) when the relay measures an acceptable time source stability and reliability.

The procedure in the following steps assumes that you have a modern highaccuracy GPS receiver with BNC jack outputs for both an IRIG-B signal and a 1000 PPS signal. Use a communications terminal to send commands and receive data from the relay (see *Making an EIA-232 Serial Port Connection on page 4.6*).

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on page 4.10* to change the default access level passwords.

- Step 1. Confirm that the relay is operating. See *Connecting and Applying Power on page 4.4*.
- Step 2. Prepare to control the relay at Access Level 2. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt. Type the 2AC<Enter> command, and then type the correct password to go to Access Level 2. You will see the =>> action prompt.
- Step 3. Connect cables. Attach the IRIG-B signal with a BNC-to-BNC coaxial jumper cable from the GPS receiver IRIG-B output to the SEL-421 Relay TIME IRIG-B BNC jack. Connect the 1k PPS signal with a BNC-to-BNC coaxial jumper cable from the GPS receiver 1000 PPS output to the SEL-421 Relay TIME 1k PPS BNC jack. See *Figure 4.61*.



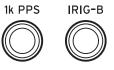


Figure 4.61 TIME BNC Jacks.

Step 4. Confirm/Enable automatic detection and changeover to high-accuracy PPS timing mode. Verify that the relay default settings are "Y" for settings ETIRIG and ETPPS. At the communications terminal, type SET G EGADVS
TERSE<Enter>. (See Making Simple Settings Changes on page 4.15.) The relay will return the settings in Figure 4.62. Type Y<Enter> to enable advanced global settings. Type ><ENTER> to skip settings categories to advance to the Time and Date Management category. Confirm that ETPPS := Y. Because you are viewing this data from the SET command, you can change setting ETPPS to Y if this setting is N. Press the <Enter> key on the terminal. The relay responds with setting ETIRIG. Confirm that ETIRIG := Y and then type

Connecting High-Accuracy Timekeeping

END<Enter> to end the settings session. Type **N<Enter>** (for no) to return to the Access Level 2 prompt. (If you changed either setting ETPPS or ETIRIG from N to Y, save the new settings by answering **Y<Enter>** to the Save settings (Y,N) ? prompt).

=>>SET G EGADVS TERSE <enter> Global</enter>			
Global Enables			
Advanced Global Setting (Y,N)	EGADVS	:= N	?Y <enter></enter>
Control Inputs (Global)			
Input Pickup Level (15–265 Vdc)	GINP	:= 85	?> <enter></enter>
Settings Group Selection			
Select Setting Group 1 (SELogic Equation) SS1 :- PB3 AND NOT SG1 ? >Enter>			
Frequency Estimation			
Alternate Freq. Source (SELogic Equation) EAFSRC := NA ? >Enter>			
Time and Date Management			
PPS/IRIG Time Source (Y,N) IRIG Time Source (Y,N)	ETPPS ETIRIG	•	? <enter> ?<enter></enter></enter>
Current and Voltage Source Selection			
Current and Voltage Source Selection (Y,N,1,2)	ESS	:= N	?END <enter></enter>
Save settings (Y,N) ? N<enter></enter> Settings aborted			

Figure 4.62 Confirming the High-Accuracy Timekeeping Enable Settings.

Step 5. Confirm that the relay is operating in the high-accuracy PPS mode. Type **TIME Q<Enter>**. The relay displays information similar to *Figure 4.63*. The Time Source will be PPS, indicating that the relay internal clock is locked to the 1k PPS input signal.

=>TIME Q<Enter>

Relay 1 Date: 03/15/2001 Time: 14:09:14.803Station A Serial Number: 2001001234Time Source: PPS Last Update Source: PPS Sync Status: SYNC FF Time Mark Period: $0.000 \ \mu$ s PPS Time Mark Period: $1000.018 \ \mu$ s IRIG Time Mark Period: $1000.000 \ ms$ Internal Clock Period: $24.999816 \ ns$ =>

Figure 4.63 Results of the TIME Q Command.

TIME Q Descriptions

The TIME Q command provides details about relay timekeeping *Figure 4.63* on page 4.68. The header line internal clock setting is initially calibrated at the SEL factory; you do not need to connect a PPS mode satellite receiver to get good time results from the SEL-421 Relay. The Time Source provides the present high-accuracy timing input source; entries for this line are PPS, IRIG, and OTHER. The Last Update Source reports the source from which the relay referenced the last time value measurement. Entries for this line can be high-accuracy or low-accuracy sources. *Table 4.9* lists the possible Last Update Source values for the SEL-421 Relay.

Time Input Source Mode (QQQQQ)	Accuracy	Time Source	Front Panel Editing?
PPS	High	Time/date from the IRIG-B input coupled to the 1000 PPS (pulse per second) pulse signal	No
IRIG	High	Time/date from the IRIG-B format time base signal	No
COMM CRD	Low	Time/date signal from the commu- nications card	Date and Time
DNP	Low	Time/date from the DNP commu- nications port	Date and Time
MIRROR B	Low	Time/date from the MIRRORED BIT port	Date and Time
ASC TIME	Low	Time from the relay serial ports	Date only
ASC DATE	Low	Date from the relay serial ports	Time only
NONV CLK	Low	Time/date from the nonvolatile random access memory clock	Date and Time
FP TIME	Low	Time from the front-panel TIME entry screen	Date and Time
FP DATE	Low	Time from the front-panel DATE entry screen	Date and Time

 Table 4.9
 Date/Time Last Update Sources

Sync Status shows whether the relay internal clock is locked. The PPS Time Mark Period value and the IRIG Time Mark Period value indicate the instantaneous period in which the relay measures the time source inputs. The relay displays the time mark periods showing the present time precision derived from the applied time source signals. (The FF Time Mark Period is for a future fiber port time input).

Adaptive Internal Clock Period Adjustment

The Internal Clock Period is the internal relay timekeeping period. The relay adjusts this master internal clock when you apply PPS mode timekeeping, adapting the internal relay clock for your installation temperature conditions. If you lose the PPS timing lock, the relay internal clock operates at this precisely adapted clock period until PPS mode is restored. Time tags for event reports during a loss of PPS mode timekeeping remain very accurate. Lower accuracy time sources do not adaptively adjust the internal relay clock period.

The purpose of the procedure in the following steps is to show one method for deriving the TIME Q Time Source information from Relay Word bits TPPS and TIRIG. The TPPS Relay Word bit is at logical 1 when the relay is in PPS time mode. The relay sets Relay Word bit TUPDH to logical 1, if the updating source is a high-accuracy time source. For this application example, use a PSV (Protection SELOGIC Variable) to monitor time keeping status.

PSV01 asserts when the relay uses a high-priority source to update the time value, the synchronizing time source is PPS, and the relay is not synchronizing to the PPS source. This condition triggers the relay alarm output (OUT108 for this application example).

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page 4.6* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords: Terminal on*

Monitoring High-Accuracy Time Source Status

page 4.10 to change the default access level passwords. Also, you should be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

- Step 1. Configure the communications port. Start the ACSELERATOR software. On the top toolbar, open the Communication menu, and then click Port Parameters. You will see the Port Parameters dialog box similar to *Figure 4.8*. Select the Data Speed, Data Bits, Parity, and Stop Bits that match the relay settings. Defaults are 9600, 8, N, 1, respectively. Click OK to update the ACSELERATOR software communications parameters. Confirm that the Communications Status bar at the bottom of the ACSELERATOR window says "Connected."
- Step 2. Confirm the correct ACSELERATOR software passwords. Reopen the Communication menu and click Port Parameters. Enter your Access Level 1 password in the Level One Password text box, and your Access Level 2 password in the Level Two Password text box. Click the OK button to accept changes and close the dialog box.
- Step 3. Read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all configuration and settings data to the ACSELERATOR software.
- Step 4. Access the protection free-form SELOGIC settings. Click on the + mark next to Group 1 in the Settings tree view. Click the Protection Logic 1 settings (See *Figure 4.64*).
- Step 5. Set a PSV. Enter the three lines of SELOGIC control equation programming in the Protection Free-Form Logic Settings shown in *Figure 4.64*. Comments begin with the # character; see *Fixed SELOGIC Control Equations on page R.3.5 in the Reference Manual*.

	Protecti	Protection Free-Form Logic Settings				
	EB	Free-Form SELogic. Click the EB button to run the Expression Builder.				
	Name	SELOGIC				
Protection Logic 1	PROTSEL1	#CHECK THE TIME SOURCE RELAY WORD BITS FOR PPS MODE				
🗄 🔍 🕒 Group 2	PROTSEL2	PSV01:=TUPDH AND TPPS AND NOT TSYNCA				
⊞ Group 3 ⊞ Group 4	PROTSEL3	#(TSYNCA CHANGES STATE AT LOSS OF TPPS.)				
⊞… ● Group 4 ⊞… ● Group 5	PROTSEL4					
	PROTSEL5					
🗄 🔲 Automation Logic	PROTSEL6					
🗄 🔍 🔍 Outputs	PROTSEL7					
🕂 🔍 🕒 Front Panel	PROTSEL8	-				
	PROTSEL9					

Figure 4.64 Programming a PSV in the ACSELERATOR Software.

Step 6. Configure a control output to alarm a loss of PPS mode. In the Settings tree view, double-click Outputs and then click Main Board (See *Figure 4.65*). In the Main Board Outputs OUT108 text box, enter the PSV01 condition to the preexisting OUT108 := NOT (SALARM OR HALARM) equation, as shown in *Figure 4.65*.

Global Global Breaker Monitor	Main Board Outputs	
	OUT101 Main Board Output 101 (SELOGIC) (3PT OR TPA1) AND NOT PLT04#THREE POLE TRIP OUT102 Main Board Output 102 (SELOGIC) (3PT OR TPA1) AND NOT PLT04#THREE POLE TRIP OUT103 Main Board Output 103 (SELOGIC) BKTCL AND NOT PLT04#BREAKER CLOSE COMMAND OUT104 Main Board Output 104 (SELOGIC) VIT04 Main Board Output 104 (SELOGIC)	EB
Communication Card Outputs Mirrored Bits Transmit Equations Front Panel P- Report Communications Ports	KEY AND PLT02 AND NOT PLT04#KEY TX OUT105 Main Board Output 105 (SELOGIC) NA OUT106 Main Board Output 106 (SELOGIC) NA	EB EB EB
	OUT107 Main Board Output 107 (SELOGIC) PLT04 #RELAY TEST MODE OUT108 Main Board Output 108 (SELOGIC) NOT (SALARM OR HALARM OR NOT PSV01)	EB

Figure 4.65 Setting OUT108 in the ACSELERATOR Software.

- Step 7. Save the new settings in the ACSELERATOR software. On the File menu, click Save.
- Step 8. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class or instance you want to send to the relay. Click the check box for Group 1 and the check box for Breaker Monitor, as shown in the first dialog box of *Figure 4.66*. Click OK. The ACSELERATOR software responds with a display similar to the second dialog box of *Figure 4.66*. If you see no error message, the new settings are loaded in the relay.

Settings Group/Class S Select Groups/Classes t Global Group 2 Group 2 Group 4 Group 5 Group 5 Group 5 Automation 1 Automation 2	o Send	OK Cancel
Transfer Status		
Writing 1 of 1		
Sending File: SETTINGS\S Sending settings	ET_G1.TX	T Cancel

Figure 4.66 Uploading Group 1 and Breaker Monitor Settings to the SEL-421 Relay.

To confirm that you have prepared an out-of synchronization/loss of PPS mode alarm, disconnect the PPS input. The relay alarm will activate.

NOTE: The Relay Editor dialog boxes shown in Figure 4.66 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

Readying the Relay for Field Application

Before applying the SEL-421 Relay in your power system, set the relay for your particular field application. Be sure to modify the relay factory default settings for your power system conditions to enable relay features to help you protect and control your system.

This procedure is a guide to help you ready the relay for field application. If you are unfamiliar with the steps in this procedure, see the many relay usage examples presented in this section. This is a suggested procedure; modify the procedure as necessary to conform to your standard company practices.

- Step 1. Open the appropriate low-voltage breaker(s) and remove fuses to verify removal of control power and ac signals from the SEL-421 Relay. Isolate the relay TRIP control output.
- Step 2. Perform point-to-point continuity checks on the circuits associated with the SEL-421 Relay to verify the accuracy and correctness of the ac and dc connections.
- Step 3. Apply power to the relay. See *Connecting and Applying Power on page 4.4*. The green enable LED on the front panel will illuminate.
- Step 4. Use an SEL Cable C234A to connect a serial terminal to the relay. Start the terminal (usually a PC with terminal emulation software). Establish communication with the relay at Access Level 0. Proceed to Access Level 2 (see *Changing the Default Passwords on page 4.8*).
- Step 5. Change the default passwords. See *Changing the Default Passwords on page 4.8.*
- Step 6. Set the DATE and TIME. See *Making Simple Settings Changes* on page 4.15.
- Step 7. Use test sources to verify relay ac connections. See *Examining Metering Quantities on page 4.31*.
- Step 8. Verify control input connections. See Operating the Relay Inputs and Outputs on page 4.52 and Control Inputs on page U.2.6 in the User's Guide.
- Step 9. Verify control output connections. See Operating the Relay Inputs and Outputs on page 4.52 and Control Outputs on page U.2.6 in the User's Guide.
- Step 10. Perform protection element tests. See Checking Relay Operation on page U.6.24 in the User's Guide.
- Step 11. Set the relay. See Making Simple Settings Changes on page 4.15, Section 1: Protection Application Examples in the Applications Handbook, and Section 1: Protection Functions in the Reference Manual.
- Step 12. Connect the relay for tripping/closing duty. See AC/DC Connection Diagrams on page U.2.47 in the User's Guide.
- Step 13. Clear the relay data buffers. From Access Level 2, use a communications terminal to issue the commands listed in *Table 4.10 on page 4.73*.

Communications Port Command	Task Performed
MET RD	Reset demand meter data
MET RP	Reset peak demand meter data
MET RE	Reset energy meter data
MET RM	Reset maximum/minimum meter data
HIS CA	Reset event report and history buffers
SER CA	Reset Sequential Events Recorder data

 Table 4.10
 Communications Port Commands That Clear Relay Buffers

Step 14. Connect the secondary voltage and current inputs. See *User's Guide Section 2: Installation*.

Step 15. Confirm secondary connections. Use the MET command or the ACSELERATOR HMI to view relay metering. See *Examining Metering Quantities on page 4.31*.

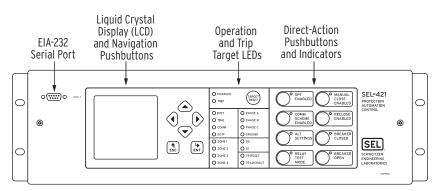
This page intentionally left blank

Section 5 Front-Panel Operations

The SEL-421 Relay front panel makes power system data collection and system control quick and efficient. Using the front panel, you can analyze power system operating information, view and change relay settings, and perform relay control functions. The relay features a straightforward menudriven control structure presented on the front-panel liquid crystal display (LCD). Front-panel targets and other LED indicators give a quick look at SEL-421 Relay operation status. You can perform often-used control actions rapidly by using the large direct-action pushbuttons. All of these features help you operate the relay from the front panel and include:

- ► Reading metering
- ► Inspecting targets
- ► Accessing settings
- ► Controlling relay operations

Front-Panel Layout



The front panel for the horizontal 3U (3 rack unit) SEL-421 Relay configuration is shown in *Figure 5.1* (other configurations are similar).

Figure 5.1 SEL-421 Relay Front Panel.

A 128 x 128 pixel LCD (liquid crystal display) shows relay operating data including event summaries, metering, settings, and relay self-test information. Six navigation pushbuttons adjacent to the LCD window control the relay menus and information screens. Sequentially rotating display screens relate important power system metering parameters; you can easily change this ROTATING DISPLAY to suit your particular on-site monitoring needs. Use a simple and efficient menu structure to operate the relay from the front panel. With these menus you can quickly access SEL-421 Relay metering, control, and settings.

Front-panel LEDs (light emitting diodes) indicate the relay operating status. You can confirm that the SEL-421 Relay is operational by viewing the ENABLED LED. The relay illuminates the TRIP LED target to indicate a tripping incident. The relay is factory programmed for particular relay elements to illuminate the other target LEDs. You can program these target LEDs to show the results of the most recent relay trip event. Change the pushbutton and pushbutton LED labels with the slide-in label carriers adjacent to the pushbuttons.

The SEL-421 Relay front panel features large operator control pushbutton switches with annunciator LEDs that facilitate local control. Factory default settings associate specific relay functions with these eight direct-action pushbuttons and LEDs. Using SELOGIC[®] control equations, you can readily change the default direct-action pushbutton functions and LED indications to fit your specific control and operational needs. Change the pushbutton and pushbutton LED labels with the slide-in labels adjacent to the pushbuttons. Change the pushbutton and pushbutton LED labels with the slide-in labels with the slide-in label carriers adjacent to the pushbuttons.

The SEL-421 Relay front panel includes an EIA-232 serial port (labeled PORT F) for connecting a communications terminal or using the SEL-5030 ACSELERATOR[®] Software Program. Use the common EIA-232 open ASCII communications protocol to communicate with the relay via front-panel Port F. Other communications protocols available with the front-panel port are MIRRORED BITSTM communications, and DNP 3.0. For more information on communications protocols and Port F, see *Communications Ports Connections on page U.2.44 in the User's Guide* and *Serial Communication on page R.4.3 in the Reference Manual*.

Front-Panel LCD

The LCD is the prominent feature of the SEL-421 Relay front panel. *Figure 5.2 on page 5.3* shows the areas contained in the LCD:

- ➤ Title area
- ► Main area
- Message area
- Scroll bars

The scroll bars are present only when a display has multiple screens.

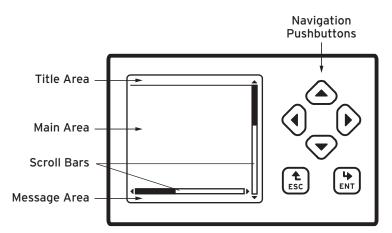


Figure 5.2 LCD Display and Navigation Pushbuttons.

Front-Panel Inactivity Time Out

The LCD has a backlight that illuminates the screen when you press any frontpanel pushbutton. This backlight extinguishes after a front-panel inactivity time out. You can control the duration of the time out with relay setting FP_TO, listed in *Table 5.1*. To set FP_TO, use the **SET F** (set front panel) settings from any communications port or use the Front Panel branch of the ACSELERATOR software settings tree view. The maximum backlight time is one hour. Obtain this 60-minute maximum backlight time by setting FP_TO to 60 or to OFF. When the front-panel times out, the relay displays an automatic ROTATING DISPLAY, described later in this section under *Screen Scrolling on page 5.4*.

Name	Description	Range	Default
FP_TO	Front-panel display time-out	OFF, 1–60 minutes	15 minutes

The SEL-421 Relay front panel presents a menu system for accessing metering, settings, and control functions. Use the LCD and the six pushbuttons adjacent to the display (see *Figure 5.2*) to navigate these front-panel menus.

The navigation pushbutton names and functions are the following:

- ► {ESC}-Escape pushbutton
- ► {ENT}-Enter pushbutton
- ► {Left}, {Right}, {Up}, and {Down}-Navigation pushbuttons

Navigating the Menus

Relay menus show lists of items that display information or control the relay. A rectangular box around an action or choice indicates the menu item you have selected. This rectangular box is the menu item highlight. *Figure 5.3 on page 5.4* shows an example of the highlighted item RELAY ELEMENTS in the MAIN MENU. When you highlight a menu item, pressing the **{ENT}** pushbutton selects the highlighted item.

MAIN MENU
METER
EVENTS
BREAKER MONITOR
RELAY ELEMENTS
LOCAL CONTROL
SET/SHOW
RELAY STATUS
VIEW CONFIGURATION
DISPLAY TEST
RESET ACCESS LEVEL

Figure 5.3 RELAY ELEMENTS Highlighted in MAIN MENU.

The {Up} pushbutton and {Down} pushbutton scroll the highlight box to the previous or next menu selection, respectively. When there is more than one screen of menu items, pressing {Up} while at the first menu item causes the display to show the previous set of full-screen menu items, with the last menu item highlighted. Pressing {Down} while at the bottom menu item causes the display to show the next set of full-screen menu items, with the first menu item highlighted.

Pressing the **{ESC}** pushbutton reverts the LCD display to the previous screen. Pressing **{ESC}** repeatedly returns you to the MAIN MENU. If a status warning or event condition is active (not acknowledged or reset), the relay displays the full-screen status warning or trip event screen in place of the MAIN MENU.

Screen Scrolling

The SEL-421 Relay has two screen scrolling modes: autoscrolling mode and manual-scrolling mode. After front-panel time out, the LCD presents each of the display screens in this sequence:

- ► Any active (filled) display points screens
- ► Enabled metering screens

The relay displays enabled metering screens in the order listed in *Table 5.2*. (see *Figure 5.13 on page 5.13* for samples of the metering screens.) This sequence comprises the ROTATING DISPLAY.

 Table 5.2
 Metering Screens Enable Settings (Sheet 1 of 2)

Name	Description	Range	Default
RMS_V	RMS Line Voltage Screen	Y, N	Ν
RMS_I	RMS Line Current Screen ^a	Y, N	Y
RMS_VPP	RMS Line Voltage Phase-to-Phase Screen	Y, N	Ν
RMS_W	RMS Active Power Screen	Y, N	Ν
FUNDVAR	Fundamental Reactive Power Screen	Y, N	Ν
RMS_VA	RMS Apparent Power Screen	Y, N	Ν
RMS_PF	RMS Power Factor Screen	Y, N	Ν
RMS_BK1	RMS Breaker 1 Currents Screen	Y, N	Ν
RMS_BK2	RMS Breaker 2 Currents Screen	Y, N	Ν
STA_BAT	Station Battery Screen	Y, N	Ν

NOTE: The initial display can present only the RMS_I line current screen. This can occur when you have not enabled any of the metering screens and display points.

Table 5.2	Metering	Screens	Enable	Settings	(Sheet 2 of 2

Name	Description	Range	Default
FUND_VI	Fundamental Voltage and Current Screen ^a	Y, N	Y
FUNDSEQ	Fundamental seqUence Quantities Screen	Y, N	Ν
FUND_BK	Fundamental Breaker Currents Screen	Y, N	Ν

^a The default displays are RMS_I and FUND_VI.

Use the front-panel settings (the **SET F** command from a communications port or the Front Panel settings in the ACSELERATOR software) to access the metering screen enables. Entering a Y (Yes) for a metering screen enable setting causes the corresponding metering screen to appear in the ROTATING DISPLAY. Entering an N (No) hides the metering screen from presentation in the ROTATING DISPLAY. *Figure 5.4 on page 5.5* shows a sample ROTATING DISPLAY consisting of an example display points screen, and the two factory-default metering screens, RMS_I and FUND_VI (the screen values in *Figure 5.4* are representative values).

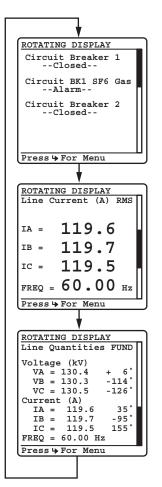


Figure 5.4 Sample ROTATING DISPLAY.

The active display points are the first screens in the ROTATING DISPLAY (see *Display Points*). Each display points screen shows as many as four enabled display points. (With 32 display points, the SEL-421 Relay can present a maximum of eight display points screens.) If a display point does not have text to display, the screen space for that display point is maintained.

Autoscrolling Mode

Autoscrolling mode shows each screen for five seconds. When you first apply power to the relay, the LCD shows the autoscrolling ROTATING DISPLAY.

The autoscrolling ROTATING DISPLAY also appears after a front-panel inactivity time out (see *Front-Panel Inactivity Time Out on page 5.3*). The relay retrieves data prior to displaying each new screen. The relay does not update screen information during the five-second display interval. At any time during autoscrolling mode, pressing **{ENT}** takes you to the MAIN MENU. Pressing any of the four navigation pushbuttons switches the display to manual-scrolling mode.

Manual-Scrolling Mode

In the manual-scrolling mode you can use the directional navigation arrow pushbuttons to select the next or previous screen. Pressing the **{Down}** or **{Right}** pushbuttons switches the display to the next screen; pressing the **{Up}** or **{Left}** pushbuttons switches the display to the previous screen. In manualscrolling mode, the display shows arrows at the top and bottom of the vertical scroll bar. The screen arrows indicate that you can navigate between the different screens at will. The relay retrieves data prior to displaying each new screen. Unlike the autoscrolling mode, the relay continues to update screen information while you view it in the manual-scrolling mode. To return to autoscrolling mode, press **{ESC}** or wait for a front-panel time out.

Display Points You can display messages on the SEL-421 Relay front-panel LCD that indicate conditions in the power system. The relay uses display points to place these messages on the LCD. *Figure 5.5* shows a sample display points screen. The relay has 32 possible display points; *Table 5.3 on page 5.7* lists the display points settings. The relay updates the display points data once per second if you are viewing the display points in manual-scrolling mode; in autoscrolling mode, the relay updates the display points information each time the screen appears in the ROTATING DISPLAY sequence.

ROTATING DISPLAY	
Circuit Breaker Closed	1
Circuit BK1 SF6 Alarm	Gas
Circuit Breaker Closed	2
Press & For Menu	Ų
(11000 / 101 110114	

Figure 5.5 Sample Display Points Screen.

To enable a display point, enter the display point settings listed in *Table 5.3*. The format for entering the display point data is the following commadelimited string:

Relay Word bit, display point name, alias for set state, alias for clear state

Names or aliases can contain any valid ASCII character. Enclose the name or alias within double quotation marks. See *Example 5.1* for particular information on the format for entering display point data.

Table 5.3 Display Point Settings

Description	Range
Relay Word Bit	Any valid relay element
Display Point Name	20-character maximum ASCII string
Display Point SET Alias (logical 1)	20-character maximum ASCII string
Display Point CLR Alias (logical 0)	20-character maximum ASCII string

If you enter a Relay Word bit that does not match a valid relay element, the relay displays "Invalid element." If you enter an alias or name that is too long, the relay displays "Too many characters, limit 20 characters per alias."

If a display point was used previously and you want to remove the display point, you can delete the display point. In the Front Panel settings (SET F), at the Display Points and Aliases prompt, use the text-edit mode line editing commands to set the display points. (See *Text-Edit Mode Line Editing on page U.4.21 in the User's Guide* for information on text-edit mode line editing.) To delete Display Point 1, type **DELETE<Enter>** at the Front Panel settings Line 1 prompt.

EXAMPLE 5.1 Creating a Display Point

Display points screens provide operator feedback about the readiness of equipment connected to the SEL-421 Relay. A display points screen contains four display points; this example demonstrates a method to set the top (first) display point message that is shown in Figure 5.5 on page 5.6. The SEL-421 Relay in this example has an additional I/O interface board.

Use appropriate interface hardware to connect the circuit breaker auxiliary contacts to IN201 to read the circuit breaker status. Assume a 125 Vdc system and use the factory defaults for settings EICIS, GINP, GIND, and GINDF (see Control Input Assignment on page U.4.59 in the User's Guide.

In the Front Panel settings (**SET F**), enter the following after the Display Points and Aliases line 1 prompt:

1: IN201,"Circuit Breaker 1"," --Closed--"," --Open--"

This example sets input IN201, represented by Relay Word bit IN201, as Circuit Breaker 1. The circuit breaker closed condition is indicated by the set state, "--Closed--" where leading spaces are added to center the set state message. Add a clear state named "--Open--" to show that the circuit breaker is open.

EXAMPLE 5.2 Monitoring Test Modes With Display Points

This example uses the Relay Word bit TESTFM (Fast Meter test running) to activate a front-panel display point that alerts an on-site operator that the relay is in Fast Meter test mode.

In the Front Panel settings (**SET F**), enter the following after the line 4 prompt:

4: TESTFM,, "FAST METER TEST!!!!"

The LCD displays the screen shown in Figure 5.6 on page 5.8 as a part of the ROTATING DISPLAY if the Fast Meter test is running. (Instruct the operator to view the relay front panel for messages or warnings as the last item on a "Leaving the Substation" checklist.)

Again, this display point application example does not require a clear state, so the clear state is blank. If the Fast Meter test is not running and no other display points are active, the relay shows a blank screen in the ROTATING DISPLAY.

ROTATING D	ISPLAY
	П
	п.
FAST METER	TEST!!!!
Press 🗣 For	Menu

Figure 5.6 Fast Meter Display Points Sample Screen.

Front-Panel Menus and Screens

Operate the SEL-421 Relay front panel through a sequence of menus that you view on the front-panel display. The MAIN MENU is the introductory menu for other front-panel menus (see *Figure 5.3 on page 5.4*). These additional menus allow you on-site access to metering, control, and settings for configuring the SEL-421 Relay to your specific application needs. Use the following menus and screens to set the relay, perform local control actions, and read metering:

- ➤ Support Screens
 - ➤ Contrast
 - > Password
- MAIN MENU
 - > METER
 - ≻ EVENTS
 - ➢ BREAKER MONITOR
 - ➢ RELAY ELEMENTS
 - > LOCAL CONTROL
 - > SET/SHOW
 - ➤ RELAY STATUS
 - > VIEW CONFIGURATION
 - > DISPLAY TEST
 - ➤ RESET ACCESS LEVEL

Support Screens The relay displays special screens over the top of the menu or screen that you are using to control the relay or view data. These screens are the contrast adjustment screen and the PASSWORD REQUIRED screen.

ContrastYou can adjust the LCD screen contrast to suit your viewing angle and
lighting conditions. To change screen contrast, press and hold the {ESC}
pushbutton for one second. The relay displays a contrast adjustment box
superimposed over the display. Figure 5.7 shows the contrast adjustment box
with the MAIN MENU screen in the background. Pressing the {Right}
pushbutton increases the contrast. Pressing the {Left} pushbutton decreases
the screen contrast. When finished adjusting the screen contrast, press the
{ENT} pushbutton.

Figure 5.7 Contrast Adjustment.

Password

WARNING: This device is shipped with default passwords. Default passwords should be changed to private passwords at installation. Failure to change each default password to a private password may allow unauthorized access. SEL shall not be responsible for any damage resulting from unauthorized access. The SEL-421 Relay uses passwords to control access to settings and control menus. The relay has six access-level passwords. See *Changing the Default Passwords on page U.4.8 in the User's Guide* for more information on access levels and setting passwords. The SEL-421 Relay front panel is at Access Level 1 upon initial power-up and after front-panel time out.

Password validation occurs only when you request a menu function that is at a higher access level than the presently authorized level. At this point, the relay displays a password entry screen, shown in *Figure 5.8*. This screen has a blank password field and an area containing alphabetic, numeric, and special password characters with a movable highlight box.

Pa	as	SWO	or	d I	Re	qu:	ire	ed		_		Passwo Field
						-	_				I 1	rieiu
A	в	С	D	Е	F	G	н					
I	J	к	L	М	N	0	Ρ				I 1	
Q	R	s	т	υ	v	W	х				I 1	
Y	\mathbf{Z}	a	b	C	d	е	f				I 1	
g	h	i	j	k	1	m	n				I 1	
0	р	q	r	s	t	u	v				I 1	
w	х	У	\mathbf{z}	0	1	2	3				I 1	
4	5	6	7	8	9	_					I 1	
ACCEPT			BACKSPACE									

Figure 5.8 Enter Password Screen.

Enter the password by pressing the navigation pushbuttons to move the highlight box through the alphanumeric field. When at the desired character, press {**ENT**}. The relay enters the selected character in the password field and moves the dark box cursor one space to the right. You can backspace at any time by highlighting the BACKSPACE character and then pressing {**ENT**}. When finished, enter the password by highlighting the ACCEPT option and then pressing {**ENT**}.

If you entered a valid password for an access level greater than or equal to the required access level, the relay authorizes front-panel access to the combination of access levels (new level and all lower levels) for which the password is valid. The relay replaces the password screen with the menu screen that was active before the password validation routine. When you enter Access Levels B, P, A, O, and 2, the Relay Word bit SALARM pulses for one second.

If you did not enter a valid password, the relay displays the error screen shown in *Figure 5.9 on page 5.10*. Entering a valid password for an access level below the required access level also causes the relay to generate the error screen. In both password failure cases, the relay does not change the frontpanel access level (it does not reset to Access Level 1 if at a higher access level). The relay displays the PASSWORD INVALID screen for five seconds. If you do not want to wait for the relay to remove the message, press any of the six navigational pushbuttons during the five-second error message to return to the previous screen in which you were working.

Password Invalid
The Password Entered Is Not Sufficient for The Required Access Level.

Figure 5.9 Invalid Password Screen.

MAIN MENU

The MAIN MENU is the starting point for all other front-panel menus. The relay MAIN MENU is shown in *Figure 5.10*. When the front-panel LCD is in the ROTATING DISPLAY, press the **{ENT}** pushbutton to show the MAIN MENU.

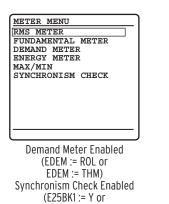
MAIN MENU
METER
EVENTS
BREAKER MONITOR
RELAY ELEMENTS
LOCAL CONTROL
SET/SHOW
RELAY STATUS
VIEW CONFIGURATION
DISPLAY TEST
RESET ACCESS LEVEL

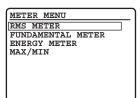
Figure 5.10 MAIN MENU.

METER

The SEL-421 Relay displays metering screens on the LCD. Highlight METER on the MAIN MENU screen to select these screens. The METER MENU, shown in *Figure 5.11*, allows you to choose the following metering screens corresponding to the relay metering modes:

- ► RMS METER
- ► FUNDAMENTAL METER
- ► DEMAND METER (if enabled)
- ENERGY METER
- ► MAX/MIN
- ► SYNCHRONISM CHECK (if enabled)





No Synchronism Check No Demand Metering (E25BK1 := N) (E25BK2 := N) (EDEM := OFF)



E25BK2 := Y)

Combinations of relay Global settings ESS and NUMBK give you metering data for Line, Circuit Breaker 1, and Circuit Breaker 2 when you view RMS METER, FUNDAMENTAL METER, and MAX/MIN metering screens. The relay shows the METER SUBMENU of *Figure 5.12* so you can choose the line or circuit breaker data that you want to display.

For example, if you have two sources feeding a transmission line through two circuit breakers and you set ESS := 3, NUMBK := 2, then the SEL-421 Relay measures BREAKER 1 currents, BREAKER 2 currents, and combined (Circuit Breakers 1 and 2) currents for LINE. The relay displays the METER SUBMENU screen when you make this settings configuration.

Other combinations of settings ESS and NUMBK do not require separate circuit breaker metering screens; for these configurations, the relay does not present the METER SUBMENU screen. See *Current and Voltage Source Selection on page R.1.2 in the Reference Manual* and *Global Settings on page R.9.3 in the Reference Manual* for information on configuring global settings ESS, NUMBK, LINEI, BK1I, and BK2I.

METER SU	JBMENU
LINE	
BREAKER	1
BREAKER	2

Figure 5.12 METER SUBMENU.

The relay presents the meter screens in the order shown in each column of *Figure 5.13 on page 5.13* and *Figure 5.14 on page 5.14*. Once you have selected the type of metering data to display (RMS METER, FUNDAMENTAL METER, DEMAND METER, ENERGY METER, MAX/ MIN, or SYNCHRONISM CHECK), you can scroll through the particular display column by pressing the **{Down}** pushbutton. Return to a previously viewed screen in each column by pressing the **{Up}** pushbutton. Press **{ESC}** to revert the LCD screen to the METER SUBMENU and METER MENU screens.

The metering screens show reset options for the MAX/MIN, ENERGY METER, PEAK DEMAND METER, and DEMAND METER metering quantities at the end of each screen column. Use the {Left} and {Right} pushbuttons to select a NO or YES response to the reset prompt, and then press {ENT} to reset the metering quantity.

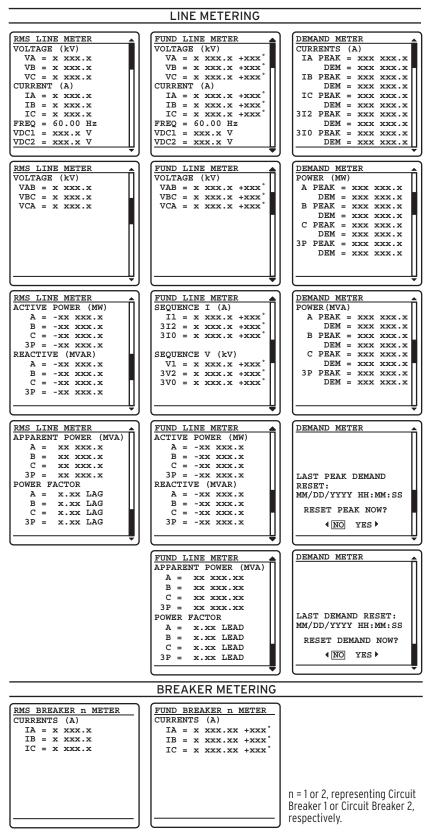


Figure 5.13 RMS, FUND, and DEMAND Metering Screens.



Figure 5.14 ENERGY, MAX/MIN, and SYNCH CHECK Metering Screens.

EVENTS

The SEL-421 Relay front panel features summary event reporting, which simplifies post-fault analysis. These summary event reports include all trip events, event and data capture triggering (via the ER SELOGIC control equation), and manual triggers. The relay displays event reports based on the Relay Word bit elements in the ER (event report trigger) SELOGIC control equation. See *Event Report on page A.3.12 in the Applications Handbook* for more information on event reports.

The front-panel event buffer size is 100 summaries. The relay numbers summary events in order from 10000 through 42767 and displays the most recent summaries on the LCD. You can view summary event reports from the

relay front-panel display by selecting EVENTS from the MAIN MENU. *Figure 5.15* shows sample EVENT SUMMARY screens for a phase-to-phase-to-ground fault. Use the {**Right**} and {**Left**} pushbuttons to show each of the summary screens for the event. The horizontal scroll bar indicates that you can view other event 10002 screens. Use the {**Up**} and {**Down**} pushbuttons to move among the events in the summary buffer. Press {**ESC**} to return to the MAIN MENU.



Figure 5.15 EVENT SUMMARY Screens.

BREAKER MONITOR

The SEL-421 Relay features an advanced circuit breaker monitor. Select BREAKER MONITOR screens from the MAIN MENU to view circuit breaker monitor alarm data on the front-panel display. *Figure 5.16* shows sample breaker monitor display screens. The BKR n ALARM COUNTER screen displays the number of times the circuit breaker exceeded certain alarm thresholds (see *Circuit Breaker Monitor on page A.2.2 in the Applications Handbook*). If you have two circuit breakers and have set NUMBK := 2, the alarm submenu in *Figure 5.16* appears first. Use the navigation pushbuttons to choose either Circuit Breaker 1 or Circuit Breaker 2. Press {ENT} to view the selected circuit breaker monitor information. An example of the Circuit Breaker 1 ALARM COUNTER screen for a single-pole tripping circuit breaker is shown on the right side of *Figure 5.16*.

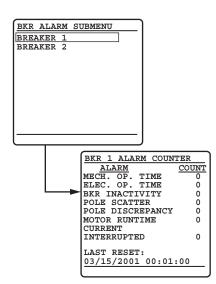


Figure 5.16 BREAKER MONITOR Report Screens.

RELAY ELEMENTS (Relay Word Bits)

You can view the RELAY ELEMENTS screen to check the state of the Relay Word bits in the SEL-421 Relay. The relay has two unique manual-scrolling features for viewing these elements:

- Accelerated navigation
- ► Search

These Relay Word bit scrolling features make selecting elements from among the many relay targets easy and efficient. *Figure 5.17* shows an example of the RELAY ELEMENTS screen. The asterisk (*) in *Figure 5.17* indicates that this Relay Word bit position is reserved for future use.

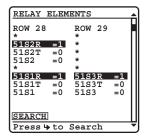


Figure 5.17 RELAY ELEMENTS Screen.

When you move item by item through the Relay Word bit table, pressing the **{Up}** or **{Down}** pushbuttons shows each previous or next screen in turn. Accelerated navigation occurs when you press and hold the **{Up}** or **{Down}** pushbuttons. Holding the **{Up}** or **{Down}** pushbuttons repeats the regular pushbutton action at 2 rows every second for the first 10 rows. Continue pressing the **{Up}** or **{Down}** pushbutton to cause the relay screen scrolling to accelerate to 20 rows per second. When scrolling up in accelerated scrolling, scrolling will stop at the first relay elements screen. When scrolling down, scrolling will stop at the last screen.

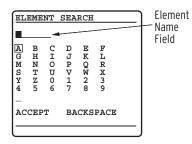


Figure 5.18 ELEMENT SEARCH Screen.

Search mode allows you to find a specific relay target element quickly. *Figure 5.18* shows the menu screen that the relay displays when you select the SEARCH option of the RELAY ELEMENTS initial menu. When you first enter this search menu, the block cursor is at the beginning of the element name field and the highlight box in the alphanumeric field is around the letter "A." Use the navigation pushbuttons to move through the alphanumeric characters. If the highlight is on one of the characters, pressing {**ENT**} enters the character at the block cursor location in the element name field. Next, the block cursor moves automatically to the character placeholder to the right. If the block cursor remains at the end of the name field. To backspace the cursor in the element name field, move the highlight to BACKSPACE and press {**ENT**}. When you have finished entering an element name, move the highlight to ACCEPT and press {**ENT**}. At any time, pressing {**ESC**} returns the display to the RELAY ELEMENTS screen.

If the highlight is on "ACCEPT," the relay finds the matching relay element when you press **{ENT}**. The relay seeks an exact match. If the relay does not find an exact match, it initiates a partial string search. If the relay finds no match, the screen displays an error message and stays in the ELEMENT SEARCH screen. If the relay finds a match, the screen displays the element row containing the matching element.

LOCAL CONTROL

The SEL-421 Relay provides great flexibility in power system control through the LOCAL CONTROL menus. You can use the front-panel LOCAL CONTROL menus to perform these relay functions:

- ► Trip and close circuit breakers (password required)
- Assert, deassert, and pulse relay control outputs to command station control actions
- ► Test relay outputs (password required)

In the first LOCAL CONTROL submenu of *Figure 5.19*, you can choose BREAKER CONTROL, local bits control, or OUTPUT TESTING. You must install the circuit breaker control enable jumper to enable circuit breaker control and output testing capability. See *Operating the Relay Inputs and Outputs on page U.4.52 in the User's Guide* and *Password and Circuit Breaker Jumpers on page U.2.17 in the User's Guide*. The submenu will not display the --BREAKER CONTROL-- option and the --OUTPUT TESTING-- option if the breaker jumper is not installed. (The relay checks the status of the breaker jumper whenever you activate the front-panel settings and at power-up.) If the breaker jumper is not installed, and there are no local bits enabled, the relay displays an information message when you attempt to enter LOCAL CONTROL and the screen returns to the MAIN MENU after a short delay.

Local bit names that you have programmed (see *Example 5.3 on page 5.20*) appear in the local control bit names field between --BREAKER CONTROL-- and --OUTPUT TESTING--, as shown in *Figure 5.19*. Use the {**Up**} and {**Down**} pushbuttons to highlight the local control action you want to perform. Pressing {**ENT**} takes you to the specific LOCAL CONTROL screen.

LOCAL CONTROL
BREAKER CONTROL
Enable Bus Switching
North Bus MOD
South Bus MOD
Bus Tie Interlock
Alternate Settings 3
OUTPUT TESTING

Figure 5.19 LOCAL CONTROL Initial Menu.

BREAKER CONTROL

The BREAKER CONTROL option presents a circuit breaker selection submenu if NUMBK := 2. Use the navigation pushbuttons and {ENT} to select the circuit breaker you want to control. *Figure 5.20 on page 5.18* shows the BREAKER CONTROL submenu and sample circuit breaker control screens for BREAKER 1. Use the {Up} and {Down} pushbuttons to highlight the TRIP BREAKER 1 or CLOSE BREAKER 1 control actions. When you highlight the trip option and press {ENT}, the relay displays the confirmation message "OPEN COMMAND ISSUED" and trips Circuit Breaker 1. The BREAKER 1 STATUS changes to OPEN. When you highlight the close option and press {ENT}, the relay displays the confirmation message "CLOSE COMMAND ISSUED" and closes Circuit Breaker 1. The BREAKER 1 STATUS changes to CLOSED.

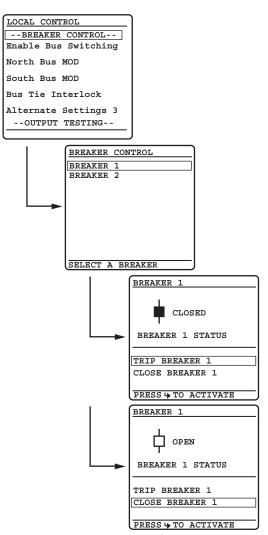


Figure 5.20 BREAKER CONTROL Screens.

Local Control Bits

The relay provides 32 local control bits. These local bits replace substation control handles to perform switching functions such as bus transfer switching. The SEL-421 Relay saves the states of the local bits in nonvolatile memory and restores the local bit states at relay power-up.

Any unused local control bits default to the clear (logical 0) state. Also, any reconfigured local bit retains the existing bit state after you change the bit setting. Deleting a local bit sets that bit to the clear (logical 0) state.

Figure 5.21 on page 5.19 shows a control example using the LOCAL CONTROL menus. The LCD shows a graphic representation of a substation control handle. If the local bit is in the clear state, the graphic control handle points to 0; if the local bit is in the set state, the switch points to 1. You can program names or aliases for the local bit clear and set states; these appear next to logical 0 and logical 1, respectively, in the lower portion of the sample Bus Tie Interlock screens of *Figure 5.21*. Use the {**Up**} and {**Down**} pushbuttons to highlight the set (1) or clear (0) control actions. Highlighting the set option (shown in *Figure 5.21* as "Closed (OK to TIE)") and pressing {**ENT**} changes the local control bit and performs the required control action. The graphical switch moves to 1 to indicate the new local bit status.

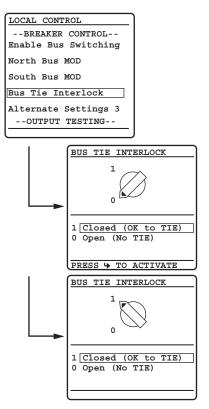


Figure 5.21 LOCAL CONTROL Example Menus.

To enable a local bit, enter the local bit settings in *Table 5.4* (n = 1-32). The format for entering the local bit data is the comma-delimited string:

local bit, control function name, alias for the set state, alias for the clear state, pulse enable

Names or aliases can contain any printable ASCII character except double quotation marks. Use double quotation marks to enclose the name or alias. See *Example 5.3 on page 5.20* for particular information on enabling a local control bit.

Table 5.4 Local Bit Control Settings^a

Range	Default
1–32	1
20-character maximum ASCII string	(blank)
20-character maximum ASCII string	(blank)
20-character maximum ASCII string	(blank)
Y, N	Ν
	1–32 20-character maximum ASCII string 20-character maximum ASCII string 20-character maximum ASCII string

^a n = 1−32

The pulse state enable setting at the end of the setting string is optional. If your application requires a pulsed or momentary output, you can activate an output pulse by setting the option at the end of the local bit command string to "Y" (for Yes). The default for the pulse state is "N" (for No); if you do not specify "Y," the local bit defaults at "N" and gives a continuous set or clear switch level. If you enter an invalid setting, the relay displays an error message prompting you to correct your input. If you do not enter a valid local bit number, the relay displays "A local bit number must be entered." If you enter a local bit number and that local bit is already in use, the relay displays "The local bit number is already in use." Likewise, if you do not enter valid local bit name, set alias, and clear alias, the relay returns an error message. If an alias is too long, the relay displays "Too many characters, limit 20 characters per alias."

EXAMPLE 5.3 Enabling Local Bit Control

This application example demonstrates a method to create one of the control points in the LOCAL CONTROL screens of Figure 5.21 on page 5.19 to control the interlock on a power bus tie circuit breaker. Perform the following actions to create a local control bit:

- Eliminate previous usage of the local bit and condition the state of the local bit
- ► Set the local bit
- > Assign the local bit to a relay output

If you are using a previously used local bit, delete all references to the local bit from the SELOGIC control equations already programmed in the relay. A good safety practice would be to disconnect any relay output that was programmed to that local bit.

To change the local bit state, select the bit and set it to the state you want. In addition, you can delete the local bit, which changes the state of this local bit to logical 0 when you save the settings. To delete, use the front-panel settings. When using a communications port and terminal, use the text-edit mode line setting editing commands at the Local Bits and Aliases prompt to go to the line that lists Local Bit 9. (See Text-Edit Mode Line Editing on page U.4.21 in the User's Guide for information on text-edit mode line editing.) To delete Local Bit 9, type DELETE<Enter> after the line that displays Local Bit 9 information. For example, if a previously programmed Local Bit 9 appears in the SET F line numbered listings on Line 1, then typing DELETE<Enter> at Line 1 deletes Local Bit 9.

Next, set the local bit. In the Front Panel settings ($\ensuremath{\textbf{SET F}}\xspace),$ enter the following:

1: LB09,"Bus Tie Interlock","Closed (OK to TIE)","Open (No TIE)",N

This sets Local Bit 9 to "Bus Tie Interlock" with the set state as "Closed (OK to TIE)" and the clear state as "Open (No TIE)."

Assign the local bit to a relay output. In the Output settings (**SET 0**), set the SELOGIC control equation, OUT201, to respond to Local Bit 9.

OUT201 := LB09

Use the appropriate interface hardware to connect the circuit breaker interlock to OUT201.

OUTPUT TESTING

NOTE: The circuit breaker control enable jumper J18C must be installed to perform output testing. See Main Board Jumpers on page U.2.17 in the User's Guide. You can check for proper operation of the SEL-421 Relay control outputs by using the OUTPUT TESTING submenu of the LOCAL CONTROL menu. A menu screen similar to *Figure 5.22 on page 5.21* displays a list of the control outputs available in your relay configuration. For more information on output testing, see *Control Output on page U.4.52 in the User's Guide*.

(
OUTPUT TESTING
OUT101
OUT102
OUT103
OUT104
OUT105
OUT106
OUT107
OUT108
PULSE OUTPUT?
INO YES
PRESS 4 TO PULSE

Figure 5.22 OUTPUT TESTING Screen.

You can use the SET/SHOW menus to examine or modify SEL-421 Relay port settings, global settings, active group settings, and date/time. From the front panel you can change only the settings classes and settings listed in *Table 5.5*.

Table 5.5 Settings Available From the Front Panel

Class/Setting	Description
PORT	Relay communications port settings
GLOBAL	Global relay settings
GROUP	Relay group settings
ACTIVE GROUP	Active settings group number 1-6
DATE/TIME	Date and time settings

Figure 5.23 on page 5.22 shows how to enter the setting CTRW (Terminal W CT ratio) from the front panel. At the MAIN MENU, select the SET/SHOW item and press {ENT}. The LCD screen displays the SET/SHOW screen of *Figure 5.23*. Use the navigation pushbuttons to select the relay settings class (PORT, GROUP, and GLOBAL) or to change the ACTIVE GROUP or the DATE/TIME. Select the GROUP class.

Next, select the particular instance of the settings class. For the PORT settings class, the instances are Port 1, Port 2, Port 3, Port F, and Port 5. For the GROUP class, the instances are the numbered groups from 1 through 6 and M, the breaker monitor (see the GROUP screen in *Figure 5.23*). The class GLOBAL, the setting ACTIVE GROUP = n (where n is a number from 1 to 6), and the settings for DATE/TIME have no settings instance screens. In the GROUP screen, move the highlight box to "3" and press {ENT}.

Proceed to selecting the settings category. The GROUP submenu in *Figure 5.23* is an example of settings Group 3 categories. Once you have highlighted the settings category, pressing {**ENT**} causes the relay to display the particular settings in that category. The LINE CONFIGURATION screen in *Figure 5.23* shows the settings that you can set in the line configuration settings category.

To edit or examine a setting, use the {Up} and {Down} pushbuttons to highlight that setting, then press {ENT}. The relay displays a settings entry screen with the existing setting value (see the SET CTRW screen in *Figure 5.23*). If the prompt for the selected setting does not fit on the line, the relay scrolls the setting prompt across the screen.

Enter the setting name using a method similar to the method described in *RELAY ELEMENTS (Relay Word Bits) on page 5.15.* Place characters in the element name field (with the block cursor) using the navigation pushbuttons. If the data you entered is valid (within settings range checks), the front-panel display returns to the settings category screen that shows each setting and

NOTE: You cannot use the frontpanel SET/SHOW menus to change front-panel settings. To change frontpanel settings, use a communications port interface and the **SET F** command or use the ACSELERATOR software Front Panel settings.

SET/SHOW

corresponding present value (see the LINE CONFIGURATION screen of *Figure 5.23*). If the data you entered are invalid, the relay displays an error message screen, then returns to the particular settings entry screen so you can attempt a valid settings entry (see the CTRW screen of *Figure 5.23*).

When finished entering the new settings data, press {**ESC**}. The relay prompts you with a Save Settings screen. Using the navigation pushbuttons, answer YES to make the settings change(s), or NO to abort the settings change(s).

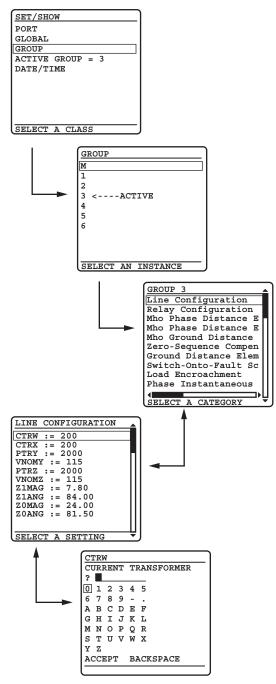


Figure 5.23 SET/SHOW Screens.

The SEL-421 Relay displays different settings entry screens depending on the settings type. For the CTRW setting in *Figure 5.23 on page 5.22*, the relay requires basic alphanumeric input. Other settings can have other data input requirements. The front-panel settings input data types are the following:

- ► Basic alphanumeric
- Character or string or SELOGIC control equations
- ► Setting options

For alphanumeric settings, the relay presents the character or string input screen. Some settings have specific options; use the setting options screens to select these options. *Figure 5.24* shows examples of the settings input screens.

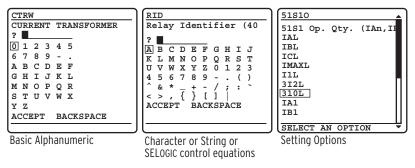


Figure 5.24 Sample Settings Input Screens.

ACTIVE GROUP

Select the ACTIVE GROUP option of the SET/SHOW submenu screen (shown in *Figure 5.23 on page 5.22*) to change the settings group. The relay performs a password validation test at this point to confirm that you have Breaker Access Level authorization or above. If access is allowed, and all the results of SELOGIC control equations SS1–SS6 are not logical 1 (asserted), then the relay displays the EDIT ACTIVE GROUP screen in *Figure 5.25*. The relay shows the active group and underlines the group number after "NEW GROUP =." Use the {**Up**} and {**Down**} pushbuttons to increase or decrease the NEW GROUP number. Once you have selected the new active group, press {**ENT**} to change the relay settings to this new settings group.

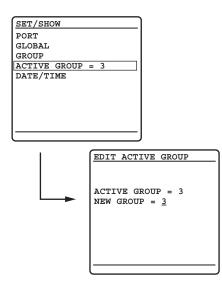


Figure 5.25 Changing the ACTIVE GROUP.

DATE/TIME

Another submenu item of the SET/SHOW first screen (*Figure 5.23 on page 5.22*) is the DATE/TIME screen shown in *Figure 5.26*. The SEL-421 Relay generates date and time information internally, or you can use external high-accuracy time modes with time sources such as a GPS receiver.

Figure 5.26 is the relay date/time screen when a high accuracy source is in use. Possible time sources, qqqqq, are listed in *Table 4.9 on page U.4.69 in the User's Guide*. If you use a high-accuracy time source, edits are disabled, the DATE/TIME display does not show the highlight, and the screen does not show the help message on the bottom line.



Figure 5.26 DATE/TIME Screen.

When operating from a non-high-accuracy time source, you can use the frontpanel DATE and TIME entry screens to set the date and time. *Figure 5.27* shows an example of these edit screens. Use the {Left} and {Right} navigation pushbuttons to move the underscore cursor; use the {Up} and {Down} navigation pushbuttons to increment or decrement each date and time digit as appropriate to set the date and time. For a description of the LAST UPDATE SOURCE field, see *Configuring High-Accuracy Timekeeping on page U.4.66 in the User's Guide*.

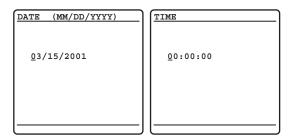


Figure 5.27 Edit DATE and Edit TIME Screens.

To enable a high-accuracy external time source, connect a GPS receiver to the relay. For a discussion of the IRIG and PPS timing modes in the SEL-421 Relay see *Configuring High-Accuracy Timekeeping on page U.4.66 in the User's Guide*. See *TIME Input Connections on page U.2.43 in the User's Guide* for more information on connecting time source inputs.

The SEL-421 Relay performs continuous hardware and software selfchecking. If any vital system in the relay approaches a failure condition, the relay issues a status warning. If the relay detects a failure, the relay displays the status failure RELAY STATUS screen immediately on the LCD. For both warning and failure conditions, the relay shows the error message for the system or function that caused the warning or failure condition. You can access the RELAY STATUS screen via the MAIN MENU. The RELAY STATUS screen shows the firmware identification number (FID), serial number, whether the relay is enabled, and any status warnings. *Figure 5.28*

RELAY STATUS

shows examples of a normal RELAY STATUS screen, a status warning RELAY STATUS screen, and a status failure RELAY STATUS screen. For more information on status warning and status failure messages, see *Relay Self-Tests on page U.6.37 in the User's Guide*.

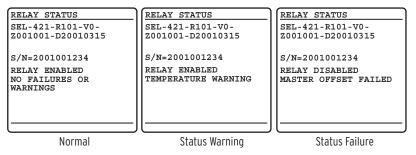


Figure 5.28 Relay STATUS Screens.

VIEW CONFIGURATION

You can use the front panel to view detailed information about the configuration of the firmware and hardware components in the SEL-421 Relay. In the MAIN MENU, highlight the VIEW CONFIGURATION option by using the navigation pushbuttons. The relay presents five screens in the order shown in *Figure 5.29*. Use the navigation pushbuttons to scroll through these screens. When finished viewing these screens, press **{ESC}** to return to the MAIN MENU.



Figure 5.29 VIEW CONFIGURATION Sample Screens.

DISPLAY TEST

NOTE: The LCD DISPLAY TEST does NOT reset the front-panel LED targets.

You can use the DISPLAY TEST option of the MAIN MENU to confirm operation of all of the LCD pixels. The LCD screen alternates the on/off state of the display pixels once every time you press {ENT}. *Figure 5.30* shows the resulting two screens. The DISPLAY TEST option also illuminates all of the front-panel LEDs. To exit the test mode, press {ESC}.

DISPLAY TEST	DISPLAY TEST
All LEDs should be lit.	All LEDs should be lit.

Figure 5.30 DISPLAY TEST Screens.

RESET ACCESS LEVEL

The SEL-421 Relay uses various passwords to control access to front-panel functions. As you progress through these menus, the relay detects the existing password level and prompts you for valid passwords before allowing you access to levels greater than Access Level 1 (see *Password on page 5.10* in this section). When you want to return the front-panel to the lowest access level (Access Level 1), highlight RESET ACCESS LEVEL item on the MAIN MENU. Pressing {ENT} momentarily displays the screen of *Figure 5.31* and places the front panel at Access Level 1.

The relay automatically resets the access level to Access Level 1 upon frontpanel timeout (setting FP_TO is not set to OFF). Use this feature to reduce the front-panel access level before the timeout occurs.

RESET	ACCESS LEVEL
	panel access
TEVET	leset.

Figure 5.31 RESET ACCESS LEVEL Screen.

Front-Panel Automatic Messages

The SEL-421 Relay automatically displays alert messages. Any message generated due to an alert condition takes precedence over the normal ROTATING DISPLAY and the MAIN MENU. Alert conditions include these significant events:

- Event reports and trips
- Status warnings
- ► Status failures

For event reports (including trip events) and status warnings, the relay displays the full-screen automatic message that corresponds to this event, only if the front-panel display is in the time-out or standby condition (the relay is scrolling through the default display points/enabled metering screens of the ROTATING DISPLAY or is displaying the MAIN MENU). When a status warning or event is triggered, the relay full-screen presentation is similar to the screens of *Figure 5.32*.

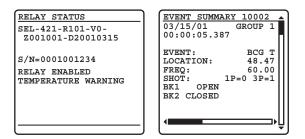


Figure 5.32 Sample Status Warning and Trip EVENT SUMMARY Screens.

If you are on site using the SEL-421 Relay front panel in menus and screens other than the MAIN MENU and a status warning occurs or an event report triggers, the relay shows automatic messages at the bottom of the active screen in the message area. For example, the message area shows RELAY STATUS WARNING for a status warning. *Figure 5.33* is an example of a status warning notification that appears in the message area of a LOCAL CONTROL (local bit) screen. If a trip event occurs while you are using a front-panel screen, the message area notification reads RELAY EVENT. When you repeatedly press {ESC} (as if returning to the MAIN MENU) during this warning or trip alert situation, the relay displays the full-screen automatic message concerning the warning or trip in place of the MAIN MENU. If the front-panel display is at the MAIN MENU and a status warning occurs, the full-screen warning replaces the MAIN MENU. After you view the warning or trip screen, pressing {ESC} returns the LCD to the MAIN MENU.

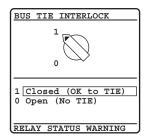


Figure 5.33 Sample Status Warning in the LCD Message Area.

For a status failure, the relay immediately displays the full-screen status alert regardless of the present front-panel operating state. The relay displays no further LCD screens until the status failure clears. Should an unlikely status failure event occur, contact your local Technical Service Center or an SEL factory representative (see *Factory Assistance on page U.6.43 in the User's Guide*).

Operation and Target LEDs

The SEL-421 Relay gives you at-a-glance confirmation of relay conditions via operation and target LEDs. These LEDs are located in the middle of the relay front panel.

You can reprogram all of these indicators except the ENABLED and TRIP LEDs to reflect other operating conditions than the factory default programming described in this subsection. Settings Tn_LED are SELOGIC control equations that, when asserted during a relay trip event, light the corresponding LED. Parameter *n* is a number from 1 through 16 that indicates each LED. LED positions are described in parenthesis next to each LED in *Figure 5.34*. Program settings Tn_LED := Y to latch the LEDs during trip events; when you set Tn_LEDL := N, the trip latch supervision has no effect and the LED follows the state of the Tn_LED SELOGIC control equation. The relay reports these targets in event reports; set the alias name listed in the report (up to eight characters) with settings Tn_LEDA . After setting the target LEDs, issue the **TAR R** command to reset the target LEDs. For a concise listing of the default programming on the front-panel LEDs, see *Front-Panel Settings on page R.9.33 in the Reference Manual*.

Use the slide-in labels to mark the LEDs with custom names. Included on the SEL-421/SEL-421-1 Relay Product Literature CD are Customer Label Templates to print labels for the slide-in label carrier.

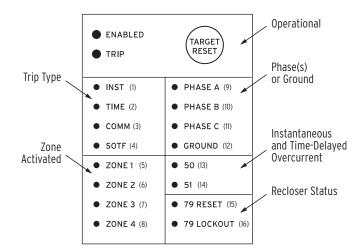


Figure 5.34 Factory Default Front-Panel Target Areas.

Figure 5.34 shows the arrangement of the operation and target LEDs region into six areas.

The six front-panel target LED areas are the following:

- ► Operational-ENABLED, TRIP
- ➤ Trip Type-INST, TIME, COMM, SOTF
- ► Zone Activated–ZONE 1, ZONE 2, ZONE 3, ZONE 4
- ➤ Phase(s) or Ground-PHASE A, PHASE B, PHASE C, GROUND
- ► Instantaneous and Time-Delayed Overcurrent-50, 51
- ► Recloser Status-79 RESET, 79 LOCKOUT

Operational

The green ENABLED LED indicates that the relay is active. Trip events illuminate the TRIP LED. The prominent location of the red TRIP LED in the top target area helps you recognize a trip event quickly.

TARGET RESET and Lamp Test

For a trip event, the relay latches the trip-involved target LEDs (except for the ENABLED LED and the Recloser Status area LEDs). Press the TARGET RESET pushbutton to reset the latched target LEDs. When a new trip event occurs and you have not reset the previously latched trip targets, the relay clears the latched targets and displays the new trip targets.

Pressing the TARGET RESET pushbutton illuminates all the LEDs. Upon releasing the TARGET RESET pushbutton, two possible trip situations can exist: the conditions that caused the relay to trip have cleared or the trip conditions remain present at the relay inputs. If the trip conditions have cleared, the latched target LEDs turn off. If the trip event conditions remain, the relay re-illuminates the corresponding target LEDs. The TARGET RESET pushbutton also removes the trip automatic message displayed on the LCD menu screens if the trip conditions have cleared.

Lamp Test Function With TARGET RESET

The TARGET RESET pushbutton also provides a front-panel lamp test. Pressing TARGET RESET illuminates all the front-panel LEDs, and these LEDs remain illuminated for as long as you press TARGET RESET. The target LEDs return to a normal operational state after you release the TARGET RESET pushbutton.

Lamp Test Function With LCD DISPLAY TEST Menu

The LCD menus provide a front-panel DISPLAY TEST mode. This menuactivated lamp test, from the DISPLAY TEST menu, does not reset the target LEDs (see *DISPLAY TEST on page 5.27*).

Other Target Reset Options

You can reset the target LEDs with the ASCII command **TAR R**; see *TARGET* on page R.8.48 in the Reference Manual for more information. You can reset the targets from the ACSELERATOR software Control branch of the HMI tree view. Programming specific conditions in the SELOGIC control equation RSTTRGT is another method to reset the relay targets. Access RSTTRGT in the relay Global settings (Data Reset Control); to use RSTTRGT, you must enable data reset control with global setting EDRSTC := Y.

The SEL-421 Relay indicates essential information about the most recent relay trip event with the LEDs of the Trip Type area. These trip types are INST, TIME, COMM, and SOTF. For information on setting the corresponding trip logic, see *Trip Logic on page R.1.103 in the Reference Manual*.

The INST target LED illuminates, indicating operation of the SEL-421 Relay instantaneous elements. This LED lights if elements M1P (the Zone 1 mho phase distance element) or Z1G (the Zone 1 mho ground distance element) pick up and the relay has not illuminated the COMM or SOTF targets.

The TIME target LED indicates that a timed relay element caused a relay trip. *Table 5.6* lists the elements that activate the TIME LED in the factory default settings.

Trip Type

	Mho	Quadrilateral
	M2PT	Z2GT
	M3PT	Z3GT
	M4PT	Z4GT
	M5PT	Z5GT
	The COMM LED illuminates, indicatin communications-assisted trip. The relay a relay tripping condition and the Relay (communications-assisted trip permission)	y lights the COMM target when there is y Word bit COMPRM
	The SOTF target LED indicates that th operated. The relay illuminates the SO condition and the Relay Word bit SOT	TF target when there is a relay tripping
Zone Activated	The zone activated area target indicator and ZONE 4 LEDs. These targets illun distance elements pick up and there is a default programming, the lowest zone is corresponding to the closest protection pickups.	ninate when the corresponding zone a relay tripping condition. In factory LED has priority; only the LED
	The ZONE 1 target illuminates if e elements operated or if the high-sp	
	The ZONE 2 target illuminates if e elements operated or if the high-sp similar elements in Zone 1 did not	beed Zone 2 elements operated and the
	The ZONE 3 target illuminates if e elements operated or if the high-sp similar elements in Zone 1 and Zo	beed Zone 3 elements operated and the
	The ZONE 4 target illuminates if e elements operated and the similar e did not operate.	either the M4P or Z4G distance elements in Zone 1, Zone 2, and Zone 3
Phase(s) or Ground	The phase(s) or ground targets illumina special targeting logic. This logic accur and/or ground were involved in a trip e	rately classifies which phase, phases,
	The PHASE A target LED lights for fa Single-phase-to-ground faults from A PHASE A and GROUND targets. A ph and B-phase illuminates the PHASE A relay displays faults involving other ph phase-to-phase fault includes ground, t target. The relay lights the PHASE A, I for a three-phase fault.	phase to ground illuminate both the ase-to-phase fault between A-phase target and the PHASE B target. The ase combinations similarly. If the he relay also lights the GROUND
Instantaneous and Time-Delayed Overcurrent	The 50 target LED indicates that an ins up. These elements are the nondirection 50Qn negative-sequence overcurrent el overcurrent elements, where n is the ov	nal 50Pn phase overcurrent elements, lements, and the 50Gn ground

Table 5.6	TIME Target LED Trigger Elements-Factory Defaults
-----------	---

The 51 target LED illuminates if a time-overcurrent element has timed out. The relay lights this LED if any of the selectable operating quantity inversetime overcurrent elements 51S1T, 51S2T, and 51S3T assert.

Recloser Status

The 79 RESET and the 79 LOCKOUT target LEDs show the operating status of the SEL-421 Relay reclosing function. The 79 RESET LED indicates that the relay recloser is in the reset or ready-to-reclose state for Circuit Breaker 1 (Relay Word bit BK1RS is asserted). The 79 LOCKOUT target illuminates when the relay has completed the reclose attempts unsuccessfully (a drive-to-lockout condition), or when other programmed lockout conditions exist. If the 79 RESET and the 79 LOCKOUT LEDs are not lit, the relay is in the cycle state for Circuit Breaker 1. See *Section 2: Auto-Reclose and Synchronism Check in the Reference Manual* for complete information on the SEL-421 Relay recloser function.

Front-Panel Operator Control Pushbuttons

The SEL-421 Relay front panel features large operator control pushbuttons coupled with amber annunciator LEDs for local control. *Figure 5.35* shows this region of the relay front panel with factory default configurable front-panel label text.

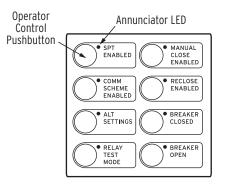


Figure 5.35 Operator Control Pushbuttons and LEDs.

Factory default programming associates specific relay functions with the eight pushbuttons and LEDs, as listed in *Table 5.7*. For a concise listing of the default programming for the front-panel pushbuttons and LEDs, see *Front*-*Panel Settings on page R.9.33 in the Reference Manual*.

Table 5.7 Operator Control Pushbuttons and LEDs-Factory Defaults

LED	Pushbutton	Function
SPT ENABLED		Enable single-pole tripping
COMM SCHEME ENABLED		Enable communications scheme
ALT SETTINGS		Change to alternate settings
RELAY TEST MODE		Enter test mode
MANUAL CLOSE ENABLED		Enable manual closing
RECLOSE ENABLED		Enable automatic reclosing
BREAKER CLOSED	CLOSE	Close Circuit Breaker 1
BREAKER OPEN	TRIP	Open Circuit Breaker 1

Press the operator control pushbuttons momentarily to toggle on and off the functions listed adjacent to each LED/pushbutton combination. The CLOSE and TRIP pushbuttons momentarily assert the close and trip relay outputs after a short delay.

The operator control pushbuttons and LEDs are programmable. *Figure 5.36* on page 5.35 describes the factory defaults for the four operator controls on the left side of the display, and *Figure 5.37 on page 5.36* describes the factory defaults for the operator controls on the right side of the display.

Using SELOGIC control equations, you can readily change the default pushbutton and LED functions. Use the slide-in labels to mark the pushbuttons and pushbutton LEDs with custom names to reflect any programming changes that you make. The labels are keyed; you can insert each Operator Control Label in only one position on the front of the relay. Included on the SEL-421/SEL-421-1 Relay Product Literature CD are word processor templates for printing slide-in labels. See *Front-Panel Labels on* page 2.26 in Section 2: Installation for more information on changing the slide-in labels.

The SEL-421 Relay has two types of outputs for each of the front-panel pushbuttons. Relay Word bits represent the pushbutton presses. One set of Relay Word bits follows the pushbutton and another set pulses for one processing interval when the button is pressed. Relay Word bits PB1 through PB8 are the "follow" outputs of operator control pushbuttons. Relay Word bits PB1 PUL through PB8 PUL are the pulsed outputs.

Annunciator LEDs for each operator control pushbutton are PB1_LED through PB8_LED. The factory defaults programmed for these LEDs are protection latches (PLT01, for example), settings groups, Relay Word bits (NOT SG1), and the status of the circuit breaker auxiliary contacts (52AA1). You can change the LED indications to fit your specific control and operational requirements. This programmability allows great flexibility and provides operator confidence and safety, especially in indicating the status of functions that are controlled both locally and remotely.

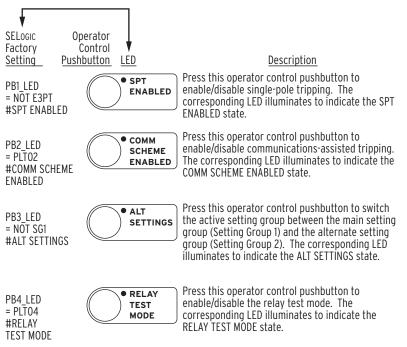


Figure 5.36 Factory Default Operator Control Pushbuttons-Left Side.

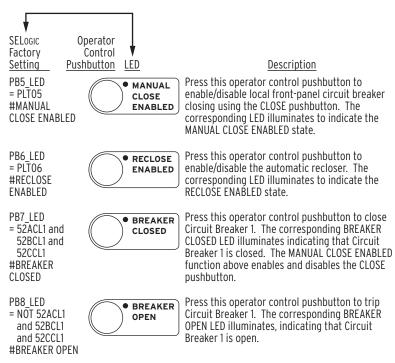


Figure 5.37 Factory Default Operator Control Pushbuttons-Right Side.

Section 6 Testing and Troubleshooting

This section contains guidelines for determining and establishing test routines for the SEL-421 Relay. Follow the standard practices of your company in choosing testing philosophies, methods, and tools. The relay incorporates self-tests to help you diagnose potential difficulties should these occur. The subsection *Relay Troubleshooting on page 6.40* contains a quick-reference table for common relay operation problems.

Topics, tests, and troubleshooting procedures presented in this section include the following:

- ► Testing philosophy
- ► Testing features and tools
- ► Relay test connections
- ► Test methods
- Relay element tests (selected elements)
- ► Relay self-tests
- ► Relay troubleshooting
- ► Factory assistance

The SEL-421 Relay is factory calibrated; this section contains no calibration information. If you suspect that the relay is out of calibration, contact your Technical Service Center or the SEL factory.

Testing Philosophy

Protective relay testing generally consists of three categories: acceptance testing, commissioning testing, and maintenance testing. The categories differ in testing complexity and according to when these activities take place in the life of the relay.

Each testing category includes particular details as to when to perform the test, the testing goals at that time, and the relay functions that you need to test. This information is a guide to testing the SEL-421 Relay; be sure to follow the practices of your company for relay testing.

Acceptance Testing SEL performs detailed acceptance testing on all new relay models and versions. We are certain that your SEL-421 Relay meets published specifications. Even so, you can perform acceptance testing on a new relay model to become familiar with the relay operating theory and settings; this familiarity helps you apply the relay accurately and correctly. A summary of acceptance testing guidelines is presented in *Table 6.1*.

Details	Description
Time	Test when qualifying a relay model for use on the utility system.
Goals	a) Confirm that the relay meets published critical performance specifications such as operating speed and element accuracy.
	b) Confirm that the relay meets the requirements of the intended application.
	c) Gain familiarity with relay settings and capabilities.
Test	Test all protection elements and logic functions critical to your intended application.

Table 6.1 Acceptance Testing

Commissioning Testing

SEL performs a complete functional check and calibration of each SEL-421 Relay before shipment so that your relay operates correctly and accurately. You should perform commissioning tests to verify proper connection of the relay to the power system and all auxiliary equipment. Check control signal inputs and outputs. Check breaker auxiliary inputs, SCADA control inputs, and monitoring outputs. Use an ac connection test to verify that the relay current and voltage inputs are the proper magnitude and phase rotation.

Brief fault tests confirm that the relay settings and protection scheme logic are correct. You do not need to test every relay element, timer, and function in these tests.

At commissioning, use the relay **METER** command to verify the ac current and voltage magnitude and phase rotation (see *Examining Metering Quantities on page U.4.31 in the User's Guide*). Use the **PUL** command to pulse relay control output operation. Use the **TAR** command to view relay targets and verify that control inputs are operational. Use **TEST FM**, **TEST DNP**, and **TEST DB** to check SCADA interfaces. (See *TEST DB on page R.8.49 in the Reference Manual* for information on these relay commands.) *Table 6.2 on page 6.3* lists guidelines for commissioning testing. For further discussion of these tests, see *Checking Relay Operation on page 6.24*.

Details	Description	
Time	Test when installing a new protection system.	
Goals	a) Validate all system ac and dc connections.	
	b) Confirm that the relay functions as intended using your settings.	
	c) Check that all auxiliary equipment operates as intended.	
	d) Check SCADA interface.	
Tests	Test all connected/monitored inputs and outputs, and the polarity and phase rotation of ac connections. Make simple checks of protection elements. Test communications interfaces.	

Table 6.2 Commissioning Testing

Maintenance Testing

The SEL-421 Relay uses extensive self-testing routines and features detailed metering and event reporting functions. These features reduce your dependence on routine maintenance testing. When you want to perform maintenance testing, follow the recommendations in *Table 6.3*.

Table 6.3 Maintenance Testing

Details	Description
Time	Test at scheduled intervals or when there is an indication of a problem with the relay or power system.
Goals	a) Confirm that the relay is measuring ac quantities accurately.
	b) Check that scheme logic and protection elements function correctly.
	c) Verify that auxiliary equipment functions correctly.
Tests	Test all relay features/power system components that did not operate during an actual fault within the past maintenance interval.

You can use the SEL-421 Relay reporting features as maintenance tools. Periodically compare the relay **METER** command output to other meter readings on a line to verify that the relay measures currents and voltages correctly and accurately. Use the circuit breaker monitor, for example, to detect slow breaker auxiliary contact operations and increasing or varying breaker pole operating times. For details on these features, see *Circuit Breaker Monitor on page A.2.2 in the Applications Handbook*.

Each occurrence of a fault tests the protection system and relay application. Review relay event reports in detail after each fault to determine the areas needing your attention. Use the event report current, voltage, and relay element data to determine that the relay protection elements and communications channels operate properly. Inspect event report input and output data to determine whether the relay asserts outputs at the correct times and whether auxiliary equipment operates properly.

At each maintenance interval, the only items to be tested are those that have not operated (via fault conditions and otherwise) during the maintenance interval. The basis for this testing philosophy is simple: you do not need to perform further maintenance testing for a correctly set and connected relay that measures the power system properly and for which no relay self-test has failed. The SEL-421 Relay is based on microprocessor technology; the relay internal processing characteristics do not change over time. For example, if time-overcurrent element operating times change, these changes occur because of alterations to relay settings and/or differences in the signals applied to the relay. You do not need to verify relay element operating characteristics as a part of maintenance checks.

SEL recommends that you limit maintenance tests on SEL relays according to the guidelines listed in *Table 6.3 on page 6.3*. You will spend less time checking relay operations that function correctly. You can use the time you save to analyze event data and thoroughly test systems needing more attention.

Testing Features and Tools

The SEL-421 Relay provides the following features to assist you during relay testing:

- ► Metering
- High-resolution oscillography
- ► Event reports
- ► Event summary reports
- ► SER (Sequential Events Recorder) reports

Certain relay commands are useful in confirming relay operation. The following commands, for example, aid you in testing the relay:

- ► TAR
- ► PUL
- ► TEST DB
- ► TEST FM
- ► TEST DNP

In addition, the SEL-421 Relay incorporates a low-level test interface where you can interrupt the connection between the relay input transformers and the input processing module. Use the low-level test interface to apply reduced-scale test quantities from the SEL-4000 Relay Test System; you do not need to use large power amplifiers to perform relay testing.

Test Features

Metering

The metering data show the ac currents and voltages (magnitude and phase angle) connected to the relay in primary values. In addition, metering shows many other quantities including the power system frequency (FREQ) and the voltage input to the station dc battery monitors (Vdc1 and Vdc2). Compare these quantities against quantities from other devices of known accuracy. The metering data are available at the serial ports, from the SEL-5030 ACSELERATOR[®] Software Program HMI, and at the front-panel LCD METER menu. See *MET on page R.8.28 in the Reference Manual, METER on page U.5.11 in the User's Guide, HMI Meter and Control on page U.3.19 in the User's Guide*, and *Examining Metering Quantities on page U.4.31 in the User's Guide* for more information.

High-Resolution Oscillography

The SEL-421 Relay takes an unfiltered data snapshot of the power system at each event trigger or trip. The relay samples power system data at high sample rates from 1 kHz to 8 kHz. You can use the SEL-5601 Analytic Assistant or other COMTRADE viewing program to export and view these raw data in a binary COMTRADE file format. Use high-resolution oscillography to capture fast power system transients or to examine low frequency anomalies in the power system. See *Raw Data Oscillography on page A.3.8 in the Applications Handbook* for more information.

Event Reports

The relay also generates a filtered-quantities event report in response to faults or disturbances. Each event report contains information on current and voltage, relay element states, control inputs, and control outputs. If you are unsure of the relay response or your test method, the event report provides you with information on the operating quantities that the relay used at the event trigger. The relay provides oscillographic displays of the filtered event report data, which give you a visual tool for testing relay operating quantities. You can use the serial ports and the ACSELERATOR software to view event reports. See *Event Reports, Event Summaries, and Event Histories on page A.3.12 in the Applications Handbook* for a complete discussion of event reports.

Event Summary Reports

The relay generates an event summary for each event report; use these event summaries to quickly verify proper relay operation. With event summaries, you can quickly compare the reported fault current and voltage magnitudes and angles against the reported fault location and fault type. If you question the relay response or your test method, you can obtain the full event report and the high-resolution oscillographic report for a more detailed analysis. See *Event Summary on page A.3.28 in the Applications Handbook* for more information on the event summary.

SER Reports

The relay provides an SER report that time tags changes in relay elements, control inputs, and control outputs. Use the SER for convenient verification of the pickup and dropout of any relay element. For a complete discussion of the SER, see *SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook.*

Test Commands

TAR Command

Use the **TAR** command to view the state of relay control inputs, relay outputs, and relay elements individually during a test. You can see relay targets at the serial ports, and from the front-panel LCD. See *TARGET on page R.8.48 in the Reference Manual* and *Operation and Target LEDs on page U.5.30 in the User's Guide*.

PUL Command

Use the **PUL** command to test the control output circuits. The specified output closes if open, or opens if closed. You can use the **PUL** command at the serial ports, in the ACSELERATOR HMI, and from the front-panel LCD. See *PULSE* on page R.8.36 in the Reference Manual, HMI Meter and Control on page U.3.19 in the User's Guide, and Operation and Target LEDs on page U.5.30 in the User's Guide.

TEST DB Command

Use the **TEST DB** command for testing the communications card relay database. You can use the **TEST DB** command to override any value in the relay database. Use the **MAP 1** command and the **VIEW1** command to inspect the relay database (see *MAP on page R.8.27 in the Reference Manual*). You must be familiar with the relay database structure to use the **TEST DB**

command effectively; see *Communications Card Database on page R.4.6 in the Reference Manual* for more information.

TEST DNP Command

Use the **TEST DNP** command to test the DNP 3.0 interface. Values you enter in the DNP map are "override values." Use the **TEST DNP** command to write override values in the DNP map. For more information on DNP 3.0 and the SEL-421 Relay, see *Section 6: DNP 3.0 Communications in the Reference Manual.*

TEST FM Command

Use the **TEST FM** command to override normal Fast Meter quantities for testing purposes. You can only override "reported" Fast Meter values (perphase voltages and currents). You cannot directly test Fast Meter values that the relay derives from the reported values (power, sequence components, and so on). For more information on Fast Meter and the SEL-421 Relay, see *Section 5: SEL Communications Protocols in the Reference Manual*.

The SEL-421 Relay has a low-level test interface between the calibrated input module and the processing module. You can check the relay in two ways: by using secondary injection testing, or by applying low-magnitude ac voltage signals to the low-level test interface.

Connection

Access the test interface by removing the relay front panel. The top circuit board is the relay main board and the bottom circuit board is the input module board. At the right side of the relay main board (the top board) is the processing module. The input to the processing module is multipin connector J20, the analog or low-level test interface connection. Receptacle J20 is on the right side of the main board; for a locating diagram, see *Figure 2.13 on page U.2.18 in the User's Guide*.

Figure 6.1 shows the low-level interface connections. Note the nominal voltage levels, current levels, and scaling factors listed in *Figure 6.1* that you can apply to the relay. Never apply voltage signals greater than 6.6 Vp-p sinusoidal signal (2.33 Vrms) to the low-level test interface.

To use the low-level test interface, remove the ribbon cable from the main board J20 receptacle, and substitute a test cable with the signals specified in *Figure 6.1*.

SEL-421 Relay Low-Level Test Interface



Input Module Output (J3): 66.6 mV At Nominal Current (1 A or 5 A). 446 mV at Nominal Voltage (67 V_{I N}).

Processing Module Input (J20): 6.6 Vp-p Maximum.

U.S. Patent 5,479,315.



Low-Level Test Interface

CAUTION: Equipment components are sensitive to electrostatic discharge (ESD). Undetectable permanent damage can result if you do not use proper ESD procedures. Ground yourself, your work surface, and this equipment before removing any cover from this equipment. If your facility is not equipped to work with these components, contact SEL about returning this device and related SEL equipment for service.

Main Board Processing Module Tests

Use signals from the SEL-4000 Low-Level Relay Test System to test the relay processing module. Apply appropriate signals to the low-level test interface J20 from the SEL-4000 Relay Test System (see *Figure 6.1 on page 6.7*). These signals simulate power system conditions, taking into account PT ratio and CT ratio scaling. Use relay metering to determine whether the applied test voltages and currents produce correct relay operating quantities.

The UUT Database entries for the SEL-421 Relay in the SEL-5401 Relay Test System Software are shown in *Table 6.4* and *Table 6.5*.

	Label	Scale Factor	Unit
1	IAW	75	А
2	IBW	75	А
3	ICW	75	А
4	IAX	75	А
5	IBX	75	А
6	ICX	75	А
7	VAY	150	V
8	VBY	150	V
9	VCY	150	V
10	VAZ	150	V
11	VBZ	150	V
12	VCZ	150	V

Table 6.4UUT Database Entries forSEL-5401 Relay Test System Software-5 A Relay

Table 6.5 UUT Database Entries for

SEL-5401 Relay Test	: System	Software-1	Α	Relay
---------------------	----------	------------	---	-------

	Label	Scale Factor	Unit
1	IAW	15	А
2	IBW	15	А
3	ICW	15	А
4	IAX	15	А
5	IBX	15	А
6	ICX	15	А
7	VAY	150	V
8	VBY	150	V
9	VCY	150	V
10	VAZ	150	V
11	VBZ	150	V
12	VCZ	150	V

Relay Test Connections

NOTE: The procedures specified in this subsection are for initial relay testing only. Follow your company policy for connecting the relay to the power system.

Test Setup

The SEL-421 Relay is a flexible tool that you can use to implement many protection and control schemes. Although you can connect the relay to the power system in many ways, connecting basic bench test sources helps you model and understand more complex relay field connection schemes.

Test Source Connections

For each relay element test, you must apply ac voltage and current signals to the relay. The text and figures in this subsection describe the test source connections you need for relay protection element checks. You can use these connections to test protective elements and simulate all fault types.

Connections for Three Voltage Sources and Three Current Sources

Figure 6.2 shows the connections to use when you have three voltage sources and three current sources available.

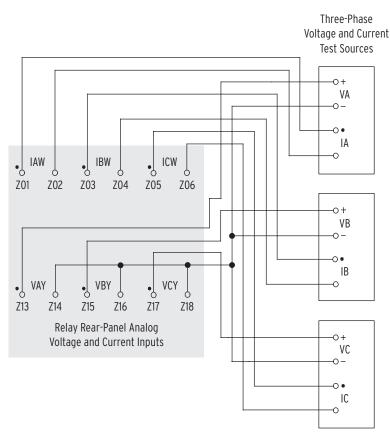


Figure 6.2 Test Connections Using Three Voltage and Three Current Sources.

Connections for Three Voltage Sources and Two Current Sources

Figure 6.3 on page 6.10 and *Figure 6.4 on page 6.11* show connections to use when you have three voltage sources and two current sources. You can use the connections shown in *Figure 6.3* to simulate phase-to-phase, phase-to-ground, and two-phase-to-ground faults. Use the connections shown in *Figure 6.4 on page 6.11* to simulate three-phase faults.

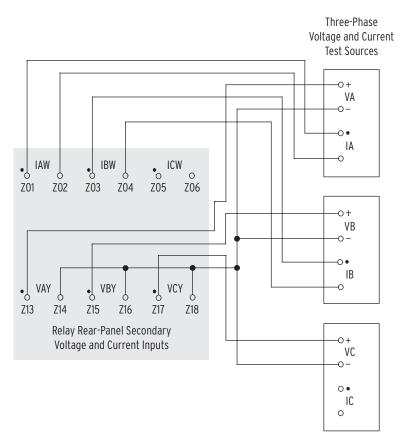


Figure 6.3 Test Connections Using Two Current Sources for Phase-to-Phase, Phase-to-Ground, and Two-Phase-to-Ground Faults.

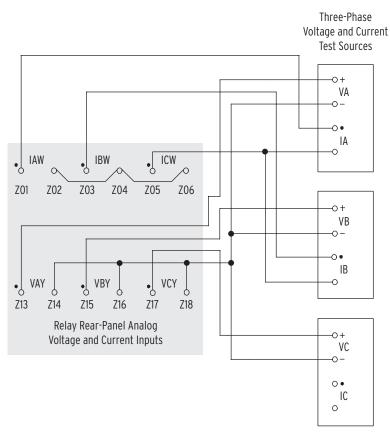
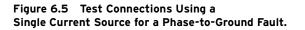


Figure 6.4 Test Connections Using Two Current Sources for Three-Phase Faults.

Connections for Three Voltage Sources and One Current Source

Figure 6.5 on page 6.12 and *Figure 6.6 on page 6.13* show connections to use when you have three voltage sources and a single current source. You can use the connections shown in *Figure 6.5* to simulate phase-to-ground faults. Use the connections shown in *Figure 6.6* to simulate phase-to-phase faults.

Three-Phase Voltage and Current Test Sources -0+ VA -0 --0 • IA • ICW -0 • IBW o IAW 6 0 Z01 Z05 Z02 Z03 Z04 Z06 -0+ VB -0 -0• IB 0 VAY VBY VCY • • 6 6 6 Z13 Z17 Z14 Z15 Z16 Z18 Relay Rear-Panel Secondary -0+ Voltage and Current Inputs VC -0-0. IC 0



•

•

Three-Phase

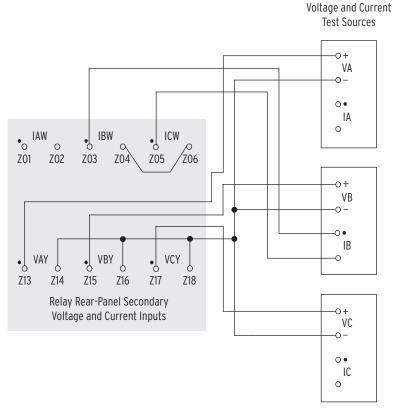


Figure 6.6 Test Connections Using a Single Current Source for a Phase-to-Phase Fault.

Test Methods

Use the following methods to conveniently test the pickup and dropout of relay elements and other relay functions:

- ► Target indications (element pickup/dropout)
- ► Control output closures
- ► SER reports

The tests and procedures in the following subsections are for 5A relays. Scale values appropriately for 1A relays.

Once you have completed a test, return the relay settings that you modified for the test to default or operational values.

Testing With Targets Use the communications port **TAR** command or the front panel to display the state of relay elements, control inputs, and control outputs. Viewing a change in relay element (Relay Word bit) status is a good way to verify the pickup settings you have entered for protection elements.

View Relay Elements With a Serial Terminal

The procedure in the following steps shows you how to view a change in state for the 50P1 Phase Instantaneous Overcurrent element from a communications port. Use the factory defaults for the pickup level (see *Table 6.6*). For more information on the 50P elements, see *Instantaneous Line Overcurrent Elements on page R.1.62 in the Reference Manual.*

Table 6.6	Phase	Instantaneous	Overcurrent Pickup
-----------	-------	---------------	--------------------

Setting	Description	Default (5A)	
50P1P	Level 1 Pickup (OFF, 0.25-100 amps secondary)	10.0	

For this procedure, you must have a serial terminal or computer with terminal emulation software and a variable current source for relay testing.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page U.4.6 in the User's Guide* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords on page U.4.8 in the User's Guide* to change the default access level passwords and enter higher relay access levels.

- Prepare to monitor the relay at Access Level 1. Using a communications terminal, type ACC<Enter>. Type the Access Level 1 password and press <Enter>. You will see the => action prompt.
- 2. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see *Figure 6.5 on page 6.12* and *Section 2: Installation in the User's Guide*).
- 3. View the initial element status. Type **TAR 50P1<Enter>**. The relay returns a target terminal screen similar to *Figure 6.7 on page 6.15*.

=>TAR 50PI<Enter>
50P1 50P2 50P3 50P4 67P1 67P2 67P3 67P4
0 0 0 0 0 0 0 0 0
=>

Figure 6.7 Sample Targets Display on a Serial Terminal.

Step 4. View the element status change. Type TAR 50P1 1000<Enter> (this command causes the relay to repeat the TAR 50P1 command 1000 times). Increase the current source to produce a current magnitude greater than 10.00 A secondary in the relay. You will see the 50P1 element status change to 1 when the input current exceeds the 50P1P setting threshold. Type <Ctrl+X> to stop the relay from presenting the target display before completion of the 1000 target repeats.

View Relay Elements With the Front-Panel LCD

You can use the front-panel display and navigation pushbuttons to check Relay Word bit elements. See *Section 5: Front-Panel Operations in the User's Guide* for more information on using the relay front panel.

This procedure uses the 50P1 Phase Instantaneous Overcurrent element. Use the factory defaults for the pickup level (*Table 6.6 on page 6.14*). For more information on the 50P elements, see *Instantaneous Line Overcurrent Elements on page R.1.62 in the Reference Manual*.

- Step 1. Display the MAIN MENU. If the relay LCD is in the Rotating Display, press the **{ENT}** pushbutton to display the MAIN MENU similar to that in *Figure 6.8 on page 6.16*.
- Step 2. Prepare to view the elements on the front-panel LCD. Press the {Down} arrow navigation pushbutton to highlight the RELAY ELEMENTS action item (see the first screen of *Figure 6.8*). Press the {ENT} pushbutton. You will see a RELAY ELEMENTS screen (the second screen of *Figure 6.8*).

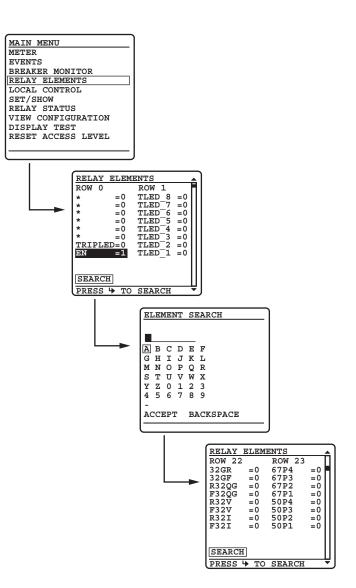


Figure 6.8 Viewing Relay Word Bits From the Front-Panel LCD.

- Step 3. Display the 50P1 Relay Word bit on the front-panel LCD screen. Press {ENT} to go to the ELEMENT SEARCH submenu of *Figure 6.8*. Use the navigation keys to highlight 5 and then press {ENT} to enter the character 5 in the text input field. Enter the "0, P, and 1 characters in the same manner. Highlight ACCEPT and press {ENT}. The relay displays the LCD screen containing the 50P1 element, as shown in the last screen of *Figure 6.8*.
- Step 4. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see Figure 6.5 on page 6.12 and Secondary Circuits on page U.2.5 in the User's Guide).

- Step 5. View the target status change. Increase the current source to produce a current magnitude greater than 10.00 A secondary in the relay. Observe the 50P1 target on the front-panel display. You will see the 50P1 element status change to 1 when the input current exceeds the 50P1P setting threshold.
- Step 6. Normalize the display. To return to the MAIN MENU, press **{ESC}**.

View Relay Elements With a Front-Panel LED

The procedure in the following steps shows you how to use a front-panel LED to view a change-in-state for the 50P1 Phase Instantaneous Overcurrent element. Use the factory defaults for the pickup level (see *Table 6.6 on page 6.14*). For more information on the 50P elements, see *Instantaneous Line Overcurrent Elements on page R.1.62 in the Reference Manual.*

In this example, use the ACSELERATOR software to configure the relay. You must have a computer that is communicating with the SEL-421 Relay and running the ACSELERATOR software. See *Making Settings Changes: Initial Global Settings on page U.4.19 in the User's Guide.* In addition, you need a variable current source suitable for relay testing.

- Step 1. Prepare to control the relay with the ACSELERATOR software. Establish communication, check passwords, and read relay settings; see *Making Settings Changes: Initial Global Settings* on page U.4.19 in the User's Guide.
- Step 2. Set a pushbutton LED SELOGIC control equation. Expand the Front Panel branch of the Settings tree view and click Pushbuttons (see *Figure 6.9*). The ACSELERATOR software displays the Pushbuttons dialog box similar to *Figure 6.9*. Click in the PB4_LED text box and type 50P1. Tab or click to any other text box. The ACSELERATOR software checks to confirm that this is a valid setting.

⊡ Global	Pushbuttons
	Pushbutton LEDs
	PB1_LED_Pushbutton_LED_1 (NA, SELOGIC Equation)
	PLT01 EB
Group 4	
	PB2_LED Pushbutton LED 2 (NA, SELOGIC Equation)
	PLT02
	PB3_LED Pushbutton LED 3 (NA, SELOGIC Equation)
	NOT SG1 EB
🚊 🗝 Front Panel	PB4 LED Pushbutton LED 4 (NA, SELOGIC Equation)
Pushbuttons	ISOP1 EB
Target LEDs	
Selectable Screens	PB5_LED Pushbutton LED 5 (NA, SELOGIC Equation)
Display Points and Aliases	NA EB
Local Control	PB6 LED Pushbutton LED 6 (NA, SELOGIC Equation)
i⊞ ● Report	EB EB

Figure 6.9 Setting Pushbutton LED Response: ACSELERATOR Software.

- Step 3. Save the new settings in ACSELERATOR software. On the File menu, click Save.
- Step 4. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box of *Figure 6.10 on page 6.18*. Click the check box for Front Panel. Click OK. The relay responds with the Transfer Status dialog box of *Figure 6.10*. If you see no error message, the new settings are loaded in the relay.

U.6.18 | Testing and Troubleshooting Test Methods

NOTE: The Relay Editor dialog boxes shown in Figure 6.10 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

iroup Select	×		
Select Groups to Send Automation 8 Automation 9 Automation 10 Output Front Panel Report Pot 1 Pot 2 Pot 3 Pot F	Select All OK Cancel	Transfer Status Writing 1 of 1 Sending File: SETTINGS\SET_F1.TXT Sending settings	Writing 1 of 1 Sending File: SETTINGS\SET_F1.TXT

Figure 6.10 Uploading Front-Panel Settings to the SEL-421 Relay.

- Step 5. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see Figure 6.5 on page 6.12 and Secondary Circuits on page U.2.5 in the User's Guide).
- Step 6. View the target status change. Increase the current source to produce a current magnitude greater than 10.00 A secondary in the relay. Observe the LED next to the RELAY TEST MODE pushbutton (PB4) on the SEL-421 Relay front panel. You will see the LED light when the input current exceeds the 50P1P setting threshold.

Testing With Control Outputs

You can set the relay to operate a control output to test a single element. Set the SELOGIC control equation for a particular output (OUT101 through OUT108, for example) to respond to the Relay Word bit for the element under test. See *Operating the Relay Inputs and Outputs on page U.4.52 in the User's Guide* for configuring control inputs and control outputs. The *Appendix A: Relay Word Bits in the Reference Manual* lists the names of the relay element logic outputs.

Testing the 50P1 Element With a Control Output

This procedure shows how to set control output OUT105 to test the 50P1 Phase Instantaneous Overcurrent element. Use the factory defaults for the pickup level (see *Table 6.6 on page 6.14*). For more information on the 50P elements, see *Instantaneous Line Overcurrent Elements on page R.1.62 in the Reference Manual*.

For this test, you must have a computer with the ACSELERATOR software for the SEL-421 Relay, a variable current source for relay testing, and a control output closure indicating device such as a test set or a VOM (volt ohmmeter).

In this example, use the ACSELERATOR software to configure the relay. You must have a computer that is communicating with the SEL-421 Relay and running the ACSELERATOR software; see *Making Settings Changes: Initial Global Settings on page U.4.19 in the User's Guide.*

- Step 1. Prepare to control the relay with the ACSELERATOR software. Establish communication, check passwords, and read relay settings; see *Making Settings Changes: Initial Global Settings* on page U.4.19 in the User's Guide.
- Step 2. View Output settings. Click on the Outputs > Main Board branch of the ACSELERATOR software Settings tree structure shown in *Figure 6.11 on page 6.19*. You will see the Main Board Outputs dialog box.

Er	Main Board Outputs	
Group 1 Group 2 Group 3 Group 5 Group 5 Outputs Main Board Minrored Bits Transmit Equations Front Panel Group Communications Ports	OUT101 Main Board Output 101 (SELOGIC) [3PT AND NOT PLT04#THREE POLE TRIP OUT102 Main Board Output 102 (SELOGIC) [3PT AND NOT PLT04#THREE POLE TRIP OUT103 Main Board Output 103 (SELOGIC) [BK1CL AND NOT PLT04#BREAKER CLOSE COMMAND OUT104 Main Board Output 103 (SELOGIC) [KEY AND PLT02 AND NOT PLT04#KEY TX OUT105 Main Board Output 105 (SELOGIC) [SOP1 OUT106 Main Board Output 106 (SELOGIC) [NA OUT107 Main Board Output 107 (SELOGIC) [PLT04#RELAY TEST MODE OUT108 Main Board Output 108 (SELOGIC) [NOT (SALARM OR HALARM)	EB EB EB EB EB EB EB EB EB EB

Figure 6.11 Setting Main Board Outputs: ACSELERATOR Software.

- Step 3. Set OUT105 to respond to the 50P1 element pickup. Move the cursor to the OUT105 Main Board Output105 (SELOGIC) text box and double-click the left (regular) mouse button. Delete the NA default setting. Type 50P1. Push <Tab> or click in any other text box. The relay checks the validity of the setting you entered. An invalid setting (you could have mistyped the element name) causes the OUT105 text box to turn red. If the setting is valid, the text box displays the new setting on a white background.
- Step 4. Save the new settings in the ACSELERATOR software. On the File menu, click Save.
- Step 5. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box in *Figure 6.12*. Click the check box for Output. Click OK. The relay responds with the Transfer Status dialog box in *Figure 6.12*. If you see no error message, the new settings are loaded in the relay.

og boxes he	Settings Class Select	×	
Relay	Select Classes to Send		
	Automation 6 Automation 7 Automation 8 Automation 9 Automation 10 Outout Front Panel Report Port 1 Port 2 Port 2	OK Cancel	Transfer Status Writing 1 of 1 Sending File: SETTINGS\SET_01.TXT Sending settings

Figure 6.12 Uploading Output Settings to the SEL-421 Relay.

- Step 6. Connect an indicating device to OUT105 on the relay rear panel. A VOM multi-tester on a low resistance scale can indicate an OUT105 control output closure.
- Step 7. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see Figure 6.5 on page 6.12 and Secondary Circuits on page U.2.5 in the User's Guide).

NOTE: The Relay Editor dialog boxes shown in Figure 6.12 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar. Step 8. Test the element. Increase the current source to produce a current magnitude greater than 10.00 A secondary in the relay. When the 50P1 element picks up, the relay changes the 50P1 Relay Word bit to logical 1 and closes the output contacts of control output OUT105. The indicating device operates.

Testing With SER

You can set the relay to generate a report from the SER to test relay elements; include the element that you want to test in the SER Points and Aliases list. Set aliases for the element name, set state, and clear state in the SEL-421 Relay SER to simplify reading the SER report. See *SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook* for complete information on the SER.

Testing the 51S1 Element Using the SER

The SER gives exact time data for testing time-overcurrent element timeouts. Subtract the 51S1T assertion time from the 51S1 assertion time to check the operation time for this element. Use the factory defaults for the operating quantity, pickup level, curve, time dial, and electromechanical reset (*Table 6.7*).

The procedure in the following steps shows how to set the SER trigger lists to capture the selectable operating quantity time-overcurrent element 51S1 operating times. The procedure also shows how to set the torque control supervision for the 51S1 element.

Setting	Description	Default 5A
51810	51S1 Operating Quantity (IAn, IBn, ICn, IMAXn, I1L, 3I2L, 3I0L) ^a	310L
51S1P	51S1 Overcurrent Pickup (0.50–16 amps, secondary)	0.75
51S1C	51S1 Inv-Time Overcurrent Curve (U1–U5, C1–C5) U3	
51S1TD	51S1 Inv-Time Overcurrent Time Dial (0.50–15.0)	1.0
51S1RS	51S1 Inv-Time Overcurrent EM Reset (Y, N) N	
51S1TC	51S1 Torque Control (SELOGIC control equation)	32GF

Table 6.7 Selectable Operating Quantity Time-Overcurrent Element (51S1) Default Settings

^a n is L, 1, and 2 for Line, Circuit Breaker 1, and Circuit Breaker 2, respectively.

The relay uses *Equation 6.1* and *Equation 6.2* to determine the operating time for the 51S1 element. For a current input 50 percent greater than the default pickup, the test value, I_{TEST} is:

 $I_{\text{TEST}} = M \cdot (51S1P) = 1.5 \cdot (0.75 \text{ A}) = 1.125 \text{ A Equation 6.1}$

where M is the pickup multiple and 51S1P is the element pickup value (see *Table 6.7*).

The operating time (t_p) for a time dial (TD) equal to 1 for the U3 (Very Inverse) Curve is:

$$t_{p} = TD \cdot \left(0.0963 + \frac{3.88}{M^{2} - 1}\right)$$
$$= 1 \cdot 0.0963 + \frac{3.88}{1.5^{2} - 1}$$
$$= 3.2 \text{ seconds}$$

Equation 6.2

For more information on the 51S elements, see *Inverse Time-Overcurrent Elements on page R.1.69 in the Reference Manual.*

In this example, use the ACSELERATOR software to configure the relay. You must have a computer that is communicating with the SEL-421 Relay and running the ACSELERATOR software; see *Making Settings Changes: Initial Global Settings on page U.4.19 in the User's Guide*. You also need a variable current source for relay testing.

- Step 1. Prepare to control the relay with the ACSELERATOR software. Establish communication, check passwords, and read relay settings; see *Making Settings Changes: Initial Global Settings* on page U.4.19 in the User's Guide.
- Step 2. Set the selectable operating quantity time-overcurrent element for test operation. Open the Group 1 > Relay Configuration > Time Overcurrent branch of the Settings tree view (see *Figure 6.13*). In the Time Overcurrent dialog box, check that setting 51S1O Operating Quantity is at 3IOL. Check the remaining element configurations against *Table 6.7 on page 6.20*. In addition, set torque control 51S1TC to 1 to constantly operate the 51S1 element; type 1 in the text box for 51S1TC. (For more information on using the ACSELERATOR software to change settings, see *Making Initial Global Settings: ACSELERATOR Software on page U.4.25 in the User's Guide.*)

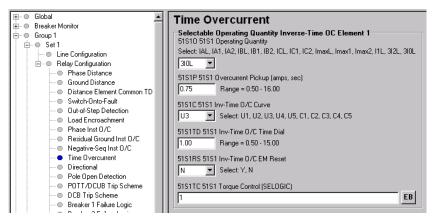
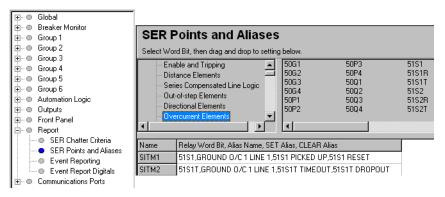


Figure 6.13 Checking the 51S1 Overcurrent Element: ACSELERATOR Software.

Step 3. View SER settings. Click on the + mark next to the Report branch of the ACSELERATOR software Settings tree view structure shown in *Figure 6.14 on page 6.22*. Click on the SER Points and Aliases branch. You will see the SER Points and Aliases dialog box (see *Figure 6.14*).





Step 4. Enter SER element names and aliases. Type the SER points and aliases in the open text boxes beginning at SITM1. Click Overcurrent Elements in the Relay Word Bits column on the left of the SER Points and Aliases dialog box to see a list of available overcurrent elements. Select, click, and drag the 51S1 element from the right side of the SER Points and Aliases dialog box to text box SITM1. For this example enter 51S1,GROUND O/C 1 LINE 1,51S1 PICKED UP,51S1 RESET for SITM1, and enter 51S1T,GROUND O/C 1 LINE 1,51SIT TIMEOUT,51S1T DROPOUT for SITM2 as shown in *Figure 6.14*.

You can enter as many as 250 relay elements in the SER Points and Aliases list. See *SER (Sequential Events Recorder) on page A.3.34 in the Applications Handbook.*

- Step 5. Save the new settings in the ACSELERATOR software. On the File menu, click Save.
- Step 6. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box of *Figure 6.15*. Click the check box for Group 1 and for Report. Click OK. The ACSELERATOR software responds with a Transfer Status dialog box as in *Figure 6.15*. If you see no error message, the new settings are loaded in the relay.

Group Select	×	
Select Groups to Send Automation 7 Automation 8	3	Transfer Status
Automation 9 Automation 10 Output	📕 Select All	Writing 1 of 1
Front Panel	ОК	Sending File: SETTINGS\SET_R1.TXT
Port 2 Port 3 Port F	Cancel	Sending settings

Figure 6.15 Uploading Group 1 and Report Settings to SEL-421 Relay.

Step 7. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see Figure 6.5 on page 6.12 and Secondary Circuits on page U.2.5 in the User's Guide).

NOTE: The Relay Editor dialog boxes shown in Figure 6.15 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

- Step 8. Test the element. Increase the current source to produce a current magnitude of 1.125 A secondary in the relay. Keep the current source at this level past the expected element timeout (longer than 3.2 seconds). Return the current source to zero after the element time out.
- Step 9. Examine the SER report. Start the ACSELERATOR HMI interface by selecting the HMI menu (top toolbar) and then clicking Meter and Control.
- Step 10. View the SER report. Click the SER button of the HMI tree view (see *Figure 6.16*). The ACSELERATOR software displays the SER report similar to *Figure 6.17*. The time difference between SER entries "51S1 PICKED UP" and "51S1 TIMOUT" is approximately 3.2 seconds.





	ay 1 tion A			: 03/15/2001 Time: 00:32:29 al Number: 0001001234	. 718
#	DATE	TIME	ELEMENT	STATE	
6	03/15/2001	00:00:00.004	Power-up	Group 1	
5	03/15/2001	00:00:00.222	Relay	Enabled	
4	03/15/2001	00:30:00.021	GROUND O/C 1 L	INE 1 51S1 PICKED UP	
3	03/15/2001	00:30:03.221	GROUND O/C 1 L	INE 1 51S1 TIMEOUT	
2	03/15/2001	00:32:00.114	GROUND O/C 1 L	INE 1 51S1 RESET	
1	03/15/2001	00:32:00.114	GROUND O/C 1 L	INE 1 51S1 DROPOUT	
	ER 30	то		Jpdate SER	

Figure 6.17 SER Report: ACSELERATOR HMI.

Checking Relay Operation

	The SEL-421 Relay comes to you with all functions fully checked and calibrated so that the relay operates correctly and accurately. You can perform tests on the relay to verify proper relay operation, but you do not need to test every relay element, timer, and function in this evaluation. The following checks are valuable for confirming proper SEL-421 Relay connections and operation:
	 AC connection check (metering)
	 Commissioning tests
	 Functional tests
	 Element verification
	An ac connection check uses relay metering to verify that the relay current and voltage inputs are the proper magnitude and phase rotation; see <i>Examining Metering Quantities on page U.4.31 in the User's Guide</i> . Commissioning tests help you verify that you have properly connected the relay to the power system and all auxiliary equipment. These tests confirm proper connection of control inputs and control outputs as well; see <i>Operating the Relay Inputs and Outputs on page U.4.52 in the User's Guide</i> . Brief functional tests and element verification confirm correct internal relay processing.
Selected	This subsection discusses tests of the following relay elements:
Element Tests	 Overcurrent element
	 Negative-sequence instantaneous, 50Q1
	 Directional element
	 Negative-sequence portion, F32Q/R32Q, of the phase directional element, F32P/R32P
	 Distance element
	 Phase-to-phase mho element, MBC2, of Zone 2 mho distance element M2P
Testing Overcurrent	Overcurrent elements operate by detecting power system sequence quantities and asserting when these quantities exceed a preset threshold.
Elements	Apply current to the analog current inputs and compare relay operation to the element pickup settings to test the instantaneous and definite-time overcurrent elements. Be sure to apply the test current to the proper input set (IW or IX), according to the Global Current and Voltage Source Selection settings (ESS and ALINEI, for example) to accept the input. See <i>Current and Voltage Source Selection on page R.1.2 in the Reference Manual</i> .
	Phase Overcurrent Elements
	The SEL-421 Relay phase overcurrent elements compare the phase current applied to the secondary current inputs with the phase overcurrent element pickup setting. The relay asserts the phase overcurrent elements when any of the three phase currents exceeds the corresponding element pickup setting.

Negative-Sequence Overcurrent Elements

The SEL-421 Relay negative-sequence overcurrent elements compare a negative-sequence calculation of the three-phase secondary inputs with the corresponding negative-sequence overcurrent element pickup setting. The relay makes this negative-sequence calculation (assuming ABC rotation):

 $3I_2 = A$ -phase + B-phase (shifted by -120°) + C-phase (shifted by 120°)

The relay asserts negative-sequence overcurrent elements when the $3I_2$ calculation exceeds the corresponding negative-sequence current pickup setting. If balanced currents are applied to the relay, the relay reads $3I_2 \approx 0$ (load conditions) and does not pick up the negative-sequence overcurrent elements.

For testing, apply current to a single phase of the relay, causing the negativesequence overcurrent elements to operate. For example, assume 1 A of current on A-phase and zero current input on the B-phase and C-phase:

 $3I_2 = 1 A + 0$ (shifted -120°) + 0 (shifted 120°) = 1 A (a simulated ground fault condition)

Ground Overcurrent Elements

The SEL-421 Relay ground overcurrent elements compare a residual ground calculation of the three-phase inputs with the residual overcurrent setting. The relay makes this residual current calculation:

 $3I_0 = A$ -phase + B-phase + C-phase

The relay asserts ground overcurrent elements when the $3I_0$ calculation exceeds the ground current element pickup setting. If balanced currents are applied to the relay, the relay reads $3I_0 = 0$ (load conditions) because the currents cancel in the calculation; the relay does not pick up the ground overcurrent elements.

For testing, apply current to a single phase of the relay, causing the residual overcurrent elements to operate. For example, assume 1 A of current on A-phase and zero current input on B-phase and C-phase:

 $3I_0 = 1 A + 0 + 0 = 1 A$ (a simulated ground fault condition)

Checking the Negative-Sequence Instantaneous Overcurrent Element, 50Q1

The procedure in the following steps tests the 50Q1 negative-sequence overcurrent element. Use a similar procedure to test other overcurrent elements.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page U.4.6 in the User's Guide* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords on page U.4.8 in the User's Guide* to change the default access level passwords and enter higher relay access levels. You should be familiar with the ACSELERATOR software; see *Section 3: PC Software in the User's Guide*.

Step 1. Configure the relay. Start the ACSELERATOR software and read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all settings and

NOTE: As you perform this test, other protection elements can assert. This causes the relay to assert other targets and possibly close control outputs. Be sure to isolate the relay from the power system to avoid unexpected system effects.

configuration data to the ACSELERATOR software. Expand the Group 1 settings and click the Relay Configuration branch of the Settings tree view as shown in *Figure 6.18*. Click the arrow in the Instantaneous and Definite Time Overcurrent Element Levels E50Q dialog box and select 1.

⊕… ● Global ⊕… ● Breaker Monitor	Relay Configuration			
Group 1 Set 1 Group Configuration Relay Configuration Phase Distance Ground Distance Switch-Onto-Fault Coad Encroachment Phase Inst 0/C Negative-Seq Inst 0/C Time Overcurrent	Distance Element Zones E21P Mho Phase E21MG Mho Ground E21XG Quadrilateral Ground 3 Select: N, 1-5 3 Select: N, 1-5 N Select: N, 1-5 ECVT CVT Trans Detect ESERCMP Series-Comp ECDTD Dist Common TD C Y C N C Y C N ESOTF Switch-Onto-Fault EOOS Out of Step ELOAD Load Encroach C Y C N C Y N			
Directional Directional Directional Ore Open Detection OPOT/DCUB Trip Sch Trip Logic and ER Trig	Instantaneous and Definite Time Overcurrent Element Levels E50P Phase E50G Residual Ground E50Q Negative Sequence 1 Select: N, 1-4 N Select: N, 1-4			

Figure 6.18 Group 1 Relay Configuration Settings: ACSELERATOR Software.

Step 2. Set the instantaneous overcurrent element pickup value. Click the Negative-Seq Inst O/C button of the Settings tree view as shown in *Figure 6.19*. You will see the Negative Sequence Instantaneous Overcurrent dialog box similar to *Figure 6.19*. For this test, set the 50Q1P level to **1.00**.

Global Global Global Global	Negative Sequence Instantaneous Overcurrent
Group 1 Group 1 Gro	Negative Sequence Instantaneous Overcurrent Elements 50Q1P Level 1 Pickup (amps, sec) 1.00 Range = 0.25 · 100.00, OFF 50Q2P Level 2 Pickup (amps, sec) OFF Range = 0.25 · 100.00, OFF
Coad Encroachment Phase Inst 0/C Negative-Seq Inst 0/C Time Overcurrent Directional Pole Open Detection	5003P Level 3 Pickup (amps, sec) 0FF Range = 0.25 · 100.00, 0FF 5004P Level 4 Pickup (amps, sec) 0FF Range = 0.25 · 100.00, 0FF

Figure 6.19 Negative-Sequence Instantaneous Overcurrent Element Settings: ACSELERATOR Software.

Step 3. Upload the new setting to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box in *Figure 6.20*. Click the check box for Group 1. Click OK. The relay responds with the Transfer Status dialog box similar to *Figure 6.20*. If you see no error message, the new settings are loaded in the relay.

Settings Class Select	X
Select Classes to Send	
Global	
□ Breaker Monitor	
Group 2	
Group 3	
Group 5 OK	
Automation 1	
Automation 2	

Figure 6.20 Uploading Group 1 Settings to the SEL-421 Relay.

NOTE: The Relay Editor dialog boxes shown in Figure 6.20 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.

Step 4. Display the 50Q1 Relay Word bit on the front-panel LCD screen. Access the front-panel LCD MAIN MENU. Highlight RELAY ELEMENTS and press {ENT}. Press {ENT} to go to the ELEMENT SEARCH submenu of *Figure 6.21*. Use the navigation keys to highlight 5 and then press {ENT} to enter characters in the text input field. Enter the 0, Q, and 1 characters in turn. Highlight ACCEPT and press {ENT}. The relay displays the screen containing the 50Q1 element, as shown in *Figure 6.22*.

EI	E	(E)	ΙT	SI	EARCH	_
Α	в	C	D	Е	F	
G	н	Ι	J	к	L	
М	N	0	Ρ	Q	R	
S	т	U	v	W	х	
Y	\mathbf{Z}	0	1	2	3	
4	5	6	7	8	9	
-						
ACCEPT BACKSPACE						
						-

Figure 6.21 ELEMENT SEARCH Screen.

				_
RELAY	ELEM	ENTS		
ROW 2	6	ROW 2	7	П
67Q4	= 0	*	=0	П.
6703	= 0	*	=0	Ш
67Q2	= 0	*	=0	Ш
67Q1	=0	*	=0	Ш
50Q4	= 0	67Q4T	=0	Ш
50Q3	=0	67Q3T		Ш
50Q2	=0	67Q2T		Ш
50Q1	=0	67Q1T	=0	Ш
				Ш
SEARC	H			Ш
PRESS	4 то	SEARCH	-	÷
(TREDD	10	DEARCI	1	_

Figure 6.22 RELAY ELEMENTS Screen Containing Element 50Q1.

- Step 5. Connect a test source to the relay. Set the current output of a test source to zero output level. Connect a single-phase current output of the test source to the IAW analog input (see Figure 6.5 on page 6.12 and Secondary Circuits on page U.2.5 in the User's Guide).
- Step 6. Test the element. Increase the current source to produce a current magnitude greater than 1.00 A secondary in the relay. You will see that the 50Q1 element state changes on the LCD screen from 50Q1 = 0 to 50Q1 = 1.

The SEL-421 Relay features a phase directional element (represented by Relay Word bits F32P/R32P) to supervise the phase distance elements and to control phase directional elements. The negative-sequence directional element, F32Q/R32Q, is a part of the phase directional element, F32P/R32P. Whenever the negative-sequence directional element asserts, the phase directional element asserts.

The relay also contains a ground directional element, F32G/R32G, for directional control of the ground distance elements and ground overcurrent elements. For more information on directional elements, see *Ground Directional Element on page R.1.21 in the Reference Manual*, and *Section 1: Protection Application Examples in the Applications Handbook*.

The SEL-421 Relay calculates the negative-sequence impedance Z2 from the magnitudes and angles of the negative-sequence voltage and current. *Equation 6.3 on page 6.28* defines this function (the 'c' in Z2c indicates "calculated").

Negative-Sequence Directional Element for Phase Faults

$$Z2c = \frac{\text{Re}[V_2 \cdot (1 \angle Z1 \text{ANG} \cdot I_2)^*]}{|I_2|^2}$$
$$= \frac{|V_2|}{|I_2|} \cdot \cos(\angle V_2 - \angle Z1 \text{ANG} - \angle I_2)$$
Equation 6.3

Where:

V₂ is the negative-sequence voltage

 I_2 is the negative-sequence current

Z1ANG is the positive-sequence line impedance angle

Re indicates the real part of the term in brackets, for example, (Re[A + jB] = A)

* indicates the complex conjugate of the expression in parentheses, $(A + jB)^* = (A - jB)$

The result of *Equation 6.3* is an impedance magnitude that varies with the magnitude and angle of the applied current. Normally, a forward fault results in a negative Z2c relay calculation.

Test Current

Solve *Equation 6.3* to find the test current values that you need to apply to the relay to test the element. For the negative sequence current I_2 , the result is

. .

$$|I_2| = \frac{|V_2|}{Z2c}$$
 Equation 6.4

when:

$$\angle I_2 = \angle V_2 - \angle Z1ANG$$
 Equation 6.5

Multiply the quantities in *Equation 6.4* by three to obtain $3I_2$, the negativesequence current that the relay processes. With a fixed applied negativesequence voltage V_A , the relay negative sequence voltage is $3V_2$. Set Z2c = Z2F to find the test current magnitude at the point where the impedance calculation equals the forward fault impedance threshold. *Equation 6.4* becomes:

$$|I_{\text{TEST}}| = |3I_2| = \frac{|3V_2|}{Z2c} = \frac{|3V_2|}{Z2F}$$
 Equation 6.6

when:

$$\angle I_{\text{TEST}} = \angle 3I_2 = \angle 3V_2 - \angle Z1ANG$$
 Equation 6.7

For a reverse fault impedance threshold, where Z2c = Z2R, *Equation 6.4* becomes:

$$|I_{\text{TEST}}| = |3I_2| = \frac{|3V_2|}{Z2c} = \frac{|3V_2|}{Z2R}$$
 Equation 6.8

when the angle calculation is the same as *Equation 6.7*.

For more information on the directional elements, see *Ground Directional Element on page R.1.21 in the Reference Manual* and *Quadrilateral Ground Distance Elements on page R.1.51 in the Reference Manual*. For settings and application information, see *Section 1: Protection Application Examples in the Applications Handbook*.

Checking the Negative-Sequence Directional Element (Phase Faults)

This test confirms operation of the F32Q and the R32Q negative-sequence directional elements. This test procedure is for a 5A relay; scale values appropriately for a 1A relay.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page U.4.6 in the User's Guide* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords on page U.4.8 in the User's Guide* to change the default access level passwords and enter higher relay access levels. You should be familiar with the ACSELERATOR software, see *Section 3: PC Software in the User's Guide*.

Step 1. Configure the relay. Begin the ACSELERATOR software and read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all settings and configuration data to the ACSELERATOR software. Expand the Group 1 settings and click the Relay Configuration branch of the Settings tree view as shown in *Figure 6.23*. Confirm Directional Element Control E32 is AUTO.

Disable element supervisory conditions. Select the Relay Configuration button in the ACSELERATOR software Settings tree view. Confirm that ELOAD and ELOP are set to N.

 Global Breaker Monitor	Relay Configuration
Group 1 Group 1 Group 1 Group 2 Group 2 Group 3 Group 5 Group 5 Group 5 Group 5 Group 6 Outputs Outputs Group 1 Group 5 Group 6 Group 6 Group 6 Group 7 Group 6 Group 7 G	Distance Element Zones E21P Mho Phase E21MG Mho Ground E21XG Quadrilateral Ground 3 Select: N, 1-5 3 Select: N, 1-5 N Select: N, 1-5 ECVT CVT Trans Detect ESERCMP Series-Comp ECDTD Dist Common TD C Y C N C Y N ESOTF Switch-Onto-Fault E00S Out of Step ELOAD Load Encroach C Y N C Y N Instantaneous and Definite Time Overcurrent Element Levels E500 Residual Ground E500 Negative Sequence 1 Select: N, 1-4 N Select: N, 1-4 N Select: N, 1-4
	E51S Selectable Inv. Time 0/C Elements CN C1 C2 C3 CY CAUTO
	Loss-Of-Potential ELOP Loss-of-Potential C Y C Y1 C N

Figure 6.23 Group 1 Relay Configuration Settings: ACSELERATOR Software.

NOTE: As you perform this test, other protection elements can assert. This causes the relay to assert other targets and possibly close control outputs. Be sure to isolate the relay from the power system to avoid unexpected system effects. Defeat the pole-open logic. Click the + button next to Breaker Monitor to expand the Breaker Monitor branch of the Settings tree view (see *Figure 6.24*). Click Breaker 1. You will see the Breaker 1 dialog box similar to *Figure 6.24*. Enter **1** in the text boxes for 52AA1 A-Phase N/O Contact Input–BK1, 52AB1 B-Phase N/O Contact Input–BK1, and 52AC1 C-Phase N/O Contact Input–BK1. The text boxes in *Figure 6.24* appear if Breaker Monitor setting BK1TYP := 1. If BK1TYP := 3, enter 1 in the 52AA1 N/O Contact Input–BK1 text box (the other circuit breaker input boxes are dimmed.)

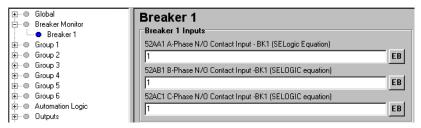


Figure 6.24 Breaker 1 Breaker Monitor Settings: ACSELERATOR Software.

Step 2. Set test values in the relay. Expand the Group 1 settings as shown in *Figure 6.25* and select the Line Configuration button. You will see the Line Configuration dialog box of *Figure 6.25*. Confirm the default settings of Z1MAG at 7.80 and Z1ANG at 84.00. Click the + mark next to the Relay Configuration branch to expand that Settings branch. Select the Directional button. You will see the Directional dialog box similar to *Figure 6.26* on page 6.31. Confirm the following settings: 50FP is 0.60, 50RP is 0.40, Z2F is 3.90, Z2R is 4.00, a2 is 0.10, and k2 is 0.2.

The dialog box is dim since there are no settings to change. The relay calculates these settings automatically because E32 is set to AUTO. If you need to change these settings, set E32 to Y. *Table 6.8 on page 6.31* shows the calculations. See *Ground Directional Element on page R.1.21 in the Reference Manual* for details on these relay calculations.

Global 	Line Configuration
Group 1 Group 1 Group 1 Group 2 Group 2 Group 3 Group 5 Group 5 Group 5 Group 6 Automation Logic Group 6 Automation Logic Group 6 Group 7 Group 8 Group 9 Group	Line Configuration Settings CTRW Current Transformer Ratio - Input W 200 Range = 1 · 50000 CTRX Current Transformer Ratio - Input X 200 Range = 1 · 50000 PTRY Potential Transformer Ratio - Input Y 200 Range = 1 · 50000 PTRY Potential Transformer Ratio - Input Y 2000 Range = 1 · 10000 VNDMY PT Nominal Voltage (L-L) - Input Y 115 Range = 60 · 300 PTR2 Potential Transformer Ratio - Input Z 2000 Range = 1 · 10000 VNDMZ PT Nominal Voltage (L-L) - Input Z 115 Range = 60 · 300 Z1MAG PosSeq. Line Impedance Magnitude (ohms, sec) 7.80 Range = 0.05 · 255.00 Z1ANG PosSeq. Line Impedance Angle (deg) 84.00 Range = 5.00 · 90.00 Z0MAG Zero-Seq. Line Impedance Magnitude (ohms, sec) 24.80 Range = 0.05 · 255.00 Z0ANG Zero-Seq. Line Impedance Magnitude (ohms, sec) 24.80 Range = 0.05 · 255.00 Z0ANG Zero-Seq. Line Impedance Angle (deg) 81.50 Range = 5.00 · 90.00

Figure 6.25 Group 1 Line Configuration Settings: ACSELERATOR Software.

Directional
DIR3 Zone/Level 3 Directional Control
DIR4 Zone/Level 4 Directional Control
© F C R
DIR5 Zone/Level 5 Directional Control
© F C R
Directional Control/Element Settings
ORDER Ground Dir. Element Priority (combine Q,V,I)
QV Select: Q, V, I, QV, QI, VQ, VI, IV, IQ, QVI, QIV, VQI, VIQ, IQV, IVQ
50FP Forward Dir Overcurrent Pickup (amps, sec)
0.60 Range = 0.25 - 5.00
50RP Reverse Dir Overcurrent Pickup (amps, sec)
0.40 Range = 0.25 - 5.00
Z2F Forward Dir Z2 Threshold (ohms, sec)
3.90 Range = -64.00 - 64.00
Z2R Reverse Dir Z2 Threshold (ohms, sec)
4.00 Range = -64.00 - 64.00
a2 Positive-Sequence Restraint Factor, 12/11
0.1 Range = 0.02 · 0.50
k2 Zero-Sequence Restraint Factor, 12/10
0.2 Range = 0.10 · 1.20

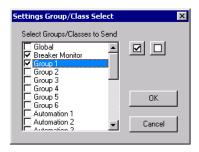
Figure 6.26 Directional Settings: ACSELERATOR Software.

Table 6.8	Negative-Sequence Directional Element Settings AUTO	
Calculation	5	

Setting	Calculation
50FP	0.12 • I _{nom}
50RP	0.08 • I _{nom}
Z2F	0.5 • Z1MAG
Z2R	$Z2F + 1 / (2 \cdot I_{nom})$
a2	0.1
k2	0.2

Step 3. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box in *Figure 6.27*. Click the check box for Group 1 and for Breaker Monitor. Click OK. The ACSELERATOR software responds with a Transfer Status dialog box as in *Figure 6.27*. If you see no error message, the new settings are loaded in the relay.

NOTE: The Relay Editor dialog boxes shown in Figure 6.27 are for the SEL-421 Relay. The SEL-421-1 Relay dialog boxes are similar.



Transfer Status	
Writing 1 of 1	
Sending File: SETTINGS\SET_S1.TXT	
Sending settings	Cancel

Figure 6.27 Uploading Group 1 and Breaker Monitor Settings to the SEL-421 Relay.

Step 4. Display the F32Q and R32Q Relay Word bits on the front-panel LCD screen. Access the front-panel LCD MAIN MENU. Highlight RELAY ELEMENTS and press {ENT}. You will see a RELAY ELEMENTS screen with SEARCH highlighted at the bottom of the screen. Press {ENT} to go to the ELEMENT SEARCH submenu of *Figure 6.21 on page 6.27*. Enter characters in the text input field using the navigation keys. Highlight F and press {ENT} to enter the F character. Enter the 3, 2, and Q characters in like manner. Highlight ACCEPT and press {ENT}. The relay displays the screen containing the F32Q and R32Q elements, as shown in *Figure 6.28*.

RELAY I	SLEMI	INTS		. I.
ROW 20		ROW 2	1 🖡	11
32SPOR	=0	32IE	=0	11
32SPOF	=0	32VE	=0	11
32QR	=0	32QGE	=0	11
32QF	=0	32QE	=0	11
R32Q	=0	50GR	=0	11
F32Q	=0	50GF	=0	11
R32P	=0	50QR	=0	11
F32P	=0	50QF	=0	11
				11
	_			11
SEARCH				11
PRESS 4	• TO	SEARCH	H F	IJ
				-

Figure 6.28 RELAY ELEMENTS LCD Screen Containing Elements F32Q and R32Q.

Step 5. Calculate impedance thresholds. For this test, apply an A-phase voltage of $V_A = 3V_2 = 18.0 \angle 180^\circ$ V secondary. Use *Equation 6.8 on page 6.28* to find the current that is equal to the reverse impedance threshold Z2R:

$$|I_{\text{TEST}}| = |3I_2| = \frac{|3V_2|}{Z2R} = \frac{|18.0 \angle 180^\circ \text{V}|}{4.00} = 4.50 \text{ A}$$

Step 6. Use *Equation 6.6 on page 6.28* to find the current that is equal to the forward impedance threshold Z2F:

$$|I_{\text{TEST}}| = |3I_2| = \frac{|3V_2|}{Z2RF} = \frac{|18.0 \angle 180^{\circ}V|}{3.90} = 4.62 \text{ A}$$

Step 7. Use *Equation 6.7 on page 6.28* to determine the applied current angle ($\angle I_{\text{TEST}}$):

$$\angle I_{\text{TEST}} = \angle 3I_2 = \angle 3V_2 - \angle Z1ANG = 180^\circ - 84^\circ = 96^\circ$$

Step 8. Apply a test current to confirm operation of R32Q and F32Q. Connect a single current test source as shown in Figure 6.5 on *page 6.12*. Apply an A-phase voltage of $V_A = 18.0 \angle 180^\circ V$ secondary. Set the current source for $I_A = 0.0 \angle 96^\circ$ A. Slowly increase the magnitude of I_A to apply the source test current Observe the RELAY ELEMENT LCD screen. Relay Word bit R32Q asserts when $|I_A| = 0.4$ A, indicating that the relay negative-sequence current is greater than the 50RP pickup threshold. R32Q deasserts when $|I_A| = 4.5$ A, indicating that the relay negative-sequence calculation Z2c is now less than the Z2 reverse threshold Z2R. (See *Reverse Threshold on page R.1.30* in the Reference Manual and Forward Threshold on page R.1.30 in the Reference Manual.) Continue to increase the current source while you observe the RELAY ELEMENT LCD screen. Relay Word bit F32Q asserts when $|I_A| = 4.62$ A, indicating that the relay negative-sequence calculation Z2c is less than the Z2 forward threshold Z2F.

Distance Elements

Apply voltages and currents to the relay analog inputs that simulate fault and load conditions to test distance elements. The relay supervises distance elements so that these elements operate under the appropriate conditions. Be sure to satisfy all the element supervisory conditions before testing a relay element. For supervisory conditions for a particular element, see *Mho Ground Distance Elements on page R.1.46 in the Reference Manual*.

Phase-to-Phase Distance Element MBC2

The SEL-421 Relay contains mho phase distance elements among the many protection elements in the relay. The relay has phase distance elements to detect phase-to-phase faults, phase-to-phase-to-ground faults, and three-phase faults. The SEL-421 Relay has five independent zones of mho phase distance protection; each zone consists of phase-to-phase elements that the relay combines to produce a particular zone output. For example, the OR combination of MAB2, MBC2, and MCA2 produces the M2P Zone 2 mho phase element. For more information on the mho phase elements and other distance elements, see *Section 1: Protection Functions in the Reference Manual* and *Section 1: Protection Application Examples in the Applications Handbook*.

Test Current and Voltage for a Phase-to-Phase Fault

To find the test current for a phase-to-phase fault, consider *Equation 6.9* for a B-phase to C-phase fault:

$$I_{\text{TEST}} = I_{\text{B}} = -I_{\text{C}}$$
 Equation 6.9

The B-phase to C-phase current vector, I_{BC} , is:

$$I_{BC} = I_B - I_C = I_B + (I_B) = 2 \cdot I_B = 2 \cdot I_{TEST}$$
 Equation 6.10

Choose a convenient test source current magnitude, $|I_{TEST}| = 2.5$ A; then $|I_{BC}| = 2 \cdot |I_{TEST}| = 5$ A.

Find the magnitude of the test source voltage $|V_{TEST}|$:

$$\begin{aligned} |\mathbf{V}_{\text{TEST}}| &= |\mathbf{V}_{\text{BC}}| = |\mathbf{I}_{\text{BC}}| \cdot |\mathbf{Z}_{\text{BC}}| = |\mathbf{I}_{\text{BC}}| \cdot \mathbf{Z2P} \\ &= 2 \cdot |\mathbf{I}_{\text{TEST}}| \cdot \mathbf{Z2P} \end{aligned}$$
 Equation 6.11

where relay setting Z2P (Zone 2 Reach) substitutes for the B-phase to C-phase impedance Z_{BC} . For setting Z2P of 9.36 Ω , the test voltage magnitude $|V_{BC}|$ is:

$$|V_{TEST}| = 2 \cdot |I_{TEST}| \cdot Z2P$$

= 2 \cdot 2.5 \cdot 9.36 = 46.8 V Equation 6.12

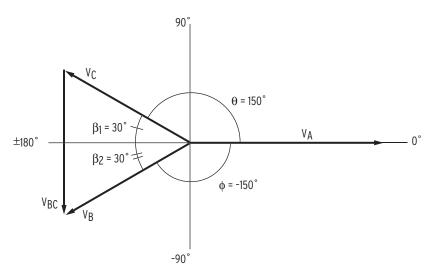


Figure 6.29 Finding Phase-to-Phase Test Quantities.

One way to create a V_{BC} phasor is to equate $|V_B|$ and $|V_C|$ and determine the appropriate angles to make an equilateral triangle as shown in *Figure 6.29*. Subtract 30 degrees (angle β_1) from 180 degrees to obtain the angle for test source V_C phasor, V_C = 46.8 $\angle 150^{\circ}$ V. Similarly, add 30 degrees (angle β_2) to -180 degrees to obtain test source V_B phasor; V_B = 46.8 $\angle -150^{\circ}$ V. Test voltage V_A can be the nominal value, V_A = 67 $\angle 0^{\circ}$ V. Thus, the resulting phase-to-phase voltage is V_{BC} = 46.8 $\angle -90^{\circ}$ V, referenced to the V_A phasor at 0 degrees.

The relay measures phase distance element maximum reach when the faulted phase-to-phase current lags the faulted phase-to-phase voltage by the distance element maximum torque angle. In the SEL-421 Relay, the phase distance element maximum torque angle is setting Z1ANG. Current I_{BC} should lag voltage V_{BC} by Z1ANG.

In this example, Z1ANG is 84.0 degrees. From *Equation 6.9 on page 6.33*, the angle of I_B is the angle of I_{TEST} , and the angle of I_C is 180 degrees from the angle of I_{TEST} . The test source current for I_B is:

 $I_B = 2.5 \angle (-90^\circ - Z1ANG)A$ = 2.5 \angle (-90^\circ - 84^\circ)A = 2.5 \angle -174^\circ A Equation 6.13

And the test source current for I_C is:

 $I_{C} = -I_{B} = -(2.5 \angle -174^{\circ}A) = 2.5 \angle 6^{\circ}A$ Equation 6.14

Checking the MBC2 Portion of the M2P Phase Distance Element

The following procedure describes how to test the B-phase to C-phase distance element MBC2. Although this test refers directly to the Zone 2 phase distance element, you can apply this procedure to any other forward-reaching phase-to-phase distance element zone.

This example assumes that you have successfully established communication with the relay; see *Making an EIA-232 Serial Port Connection on page U.4.6 in the User's Guide* for a step-by-step procedure. In addition, you must be familiar with relay access levels and passwords. See *Changing the Default Passwords on page U.4.8 in the User's Guide* to change the default access

NOTE: As you perform this test, other protection elements can assert. This causes the relay to assert other targets and possibly close control outputs. Be sure to isolate the relay from the power system to avoid unexpected system effects. level passwords and enter higher relay access levels. You should be familiar with the ACSELERATOR software. See *Section 3: PC Software in the User's Guide*.

Step 1. Configure the relay. Begin the ACSELERATOR software and read the present configuration in the SEL-421 Relay. On the Settings menu, click Read. The relay sends all settings and configuration data to the ACSELERATOR software. Expand the Group 1 settings and click the Relay Configuration branch of the Settings tree view as shown in *Figure 6.23 on page 6.29*. Confirm that E21P is 2 or greater (the factory default is 3).

> Disable element supervisory conditions. On the Relay Configuration dialog box, confirm that ELOAD and ELOP are set to N. See *Mho Phase Distance Elements on page R.1.55 in the Reference Manual* to determine the supervisory conditions for the MBC2 element. Confirm that Directional Element Control E32 is AUTO.

> Defeat the pole-open logic. Click the + button next to Breaker Monitor to expand the Breaker Monitor branch of the Settings tree view (see *Figure 6.24 on page 6.30*). Click Breaker 1. You will see the Breaker 1 dialog box similar to *Figure 6.24*. Enter 1 in the text boxes for 52AA1 A-Phase N/O Contact Input– BK1, 52AB1 B-Phase N/O Contact Input–BK1, and 52AC1 C-Phase N/O Contact Input–BK1. The text boxes in *Figure 6.24 on page 6.30* appear if Breaker Monitor setting BK1TYP := 1. If BK1TYP := 3, enter 1 in the 52AA1 N/O Contact Input–BK1 text box (the other circuit breaker input boxes are dimmed.)

- Step 2. Set test values in the relay. Expand the Group 1 settings as shown in *Figure 6.25 on page 6.30* and select the Line Configuration button. You will see the Line Configuration dialog box of *Figure 6.25*. Confirm the default settings of Z1MAG at 7.80 and Z1ANG at 84.00. Click the + mark next to the Relay Configuration branch to expand that Settings branch. Select the Directional button. You will see the Directional dialog box similar to *Figure 6.26 on page 6.31*. Confirm the settings 50FP to 0.60, 50RP to 0.40, Z2F to 3.90, Z2R to 4.00, a2 to 0.10, and k2 to 0.2. The relay calculates these settings to change; the dialog box is dim. *Table 6.8 on page 6.31* shows the calculations. See *Ground Directional Element on page R.1.21 in the Reference Manual* for details on these relay calculations.
- Step 3. Set the phase distance element reach. Select the Phase Distance button of the ACSELERATOR software Settings tree view. You will see the Phase Distance Elements dialog box similar to *Figure 6.30 on page 6.36*. Confirm the default settings of Z1P at 6.24 and Z2P at 9.36.

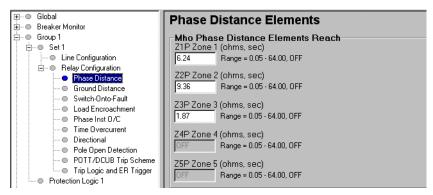


Figure 6.30 Phase Distance Elements Settings: ACSELERATOR Software.

- Step 4. Upload the new settings to the SEL-421 Relay. On the File menu, click Send. The ACSELERATOR software prompts you for the settings class you want to send to the relay, as shown in the Group Select dialog box of *Figure 6.27 on page 6.31*. Click the check box for Group 1. Click OK. The ACSELERATOR software responds with a dialog box similar to the second dialog box of *Figure 6.27*. If you see no error message, the new settings are loaded in the relay.
- Step 5. Display the MBC2 Relay Word bit on the front-panel LCD screen. Access the front-panel LCD MAIN MENU. Highlight RELAY ELEMENTS and press {ENT}. You will see a RELAY ELEMENTS screen with SEARCH highlighted at the bottom of the screen. Press {ENT} to go to the ELEMENT SEARCH submenu of *Figure 6.21 on page 6.27*. Use the navigation keys to highlight M and press {ENT} to enter character in the text input field. Enter the B, C, and 2 characters in like manner. Highlight ACCEPT and press {ENT}. The relay displays the LCD screen containing the MBC2 element, as shown in *Figure 6.31*.

RELAY	ELEM	ENTS		₽
ROW 8		ROW 9		
*	=0	*	=0	Ш
MCA2	=0	MCA4	=0	Ш
MBC2	=0	MBC4	=0	Ш
MAB2	=0	MAB4	=0	Ш
*	=0	*	=0	Ш
MCA1	=0	MCA3	=0	Ш
MBC1	=0	MBC3	=0	Ш
MAB1	=0	MAB3	=0	Ш
				Ш
SEARCH				
DDRGG	<u>ч</u> то	GRADO		₽ I
PRESS		SEARC	н	ັ

Figure 6.31 RELAY ELEMENTS LCD Screen Containing Element MBC2.

- Step 6. Set the magnitudes and angles of the test signals for a B-phase-to-C-phase fault. Connect the test sources (with power off) to the relay, as in *Figure 6.6 on page 6.13*. This connection is a B-phase-to-C-phase fault where $I_A \approx 0$ and $I_B = -I_C$. Adjust the voltage sources to provide the following test voltages: $V_A = 67$ V $\angle 0^\circ$, $V_B = 46.8$ V $\angle -150^\circ$, and $V_C = 46.8$ V $\angle 150^\circ$. Set the current source for $I_B = 0.0$ A $\angle -174^\circ$.
- Step 7. Apply the sources to confirm operation of MBC2. Apply the source test current by slowly increasing the magnitude of I_{B.} Observe the RELAY ELEMENT LCD screen. Relay Word bit MBC2 asserts when $|I_B| \ge 2.5$ A, indicating that the relay impedance calculation is less than the Z2P reach setting.

Relay Self-Tests

The SEL-421 Relay continuously runs many self-tests to detect out-oftolerance conditions. These tests run at the same time as relay protection and automation logic, but do not degrade SEL-421 Relay performance.

Status Warning and Status Failure

The relay reports out-of-tolerance conditions as a status warning or a status failure. For conditions that do not compromise relay protection, yet are beyond expected limits, the relay issues a status warning and continues to operate. A severe out-of-tolerance condition causes the relay to declare a status failure and enter a protection-disabled state. During a protection-disabled state, the relay suspends protection element processing and trip/close logic processing and deenergizes all control outputs. When disabled, the ENABLED front-panel LED is not illuminated.

The relay signals a status warning by pulsing the HALARM Relay Word bit (hardware alarm) to logical 1 for five seconds. For a Status Failure, the relay latches the HALARM Relay Word bit at logical 1. To provide remote status indication, connect the 'b' contact of OUT108 to your control system remote alarm input and program the output SELOGIC control equation to respond to NOT (SALARM OR HALARM). See *Alarm Output on page U.2.42 in the User's Guide* on connecting this alarm output for the SEL-421 Relay.

If you repeatedly receive status warnings, check the relay operating conditions as soon as possible. Take preventive action early during the development of potential problems to avoid system failures. For any status failure, contact your Technical Service Center or the SEL factory immediately (see *Factory Assistance on page 6.43*).

The relay generates an automatic status report at the serial ports for a self-test status failure if you set Port setting AUTO := Y. The relay issues a status message with a format identical to the STATUS command output (see *Status*), except that the power supply information from the STA A response is included after the SELOGIC control equation error messages.

The relay also displays status warning and status failure automatic messages on the front-panel LCD. Use the serial port **STATUS** and **CSTATUS** commands, the ACSELERATOR HMI Status button, and the front-panel RELAY STATUS menu to display status warnings and status failures. See *STATUS on page R.8.45 in the Reference Manual, Checking Relay Status on page U.4.12 in the User's Guide*, and *RELAY STATUS on page U.5.24 in the User's Guide* for more information on automatic status notifications and on viewing relay status.

Status

Figure 6.32 on page 6.38 is a sample **STATUS** screen from the Status option of the ACSELERATOR HMI > Meter and Control tree view (the terminal **STATUS** report is similar). *Figure 6.33 on page 6.38* is the **STATUS** A report showing all status information on a terminal.

Firmware Version Number

At the top of each status report the relay displays the present firmware version number that identifies the software program that controls relay functions. The firmware version is the four-place designator immediately following the relay model number (the first characters in the firmware identification string). The first character in the four-place firmware version number is "R" (representing "Release"). For example, in *Figure 6.32* and *Figure 6.33*, the firmware version number is R101. SEL numbers subsequent firmware releases sequentially; the next revision following R101 is R102. See *Appendix A: Firmware Versions in the User's Guide* for firmware version information.

Status Relay 1 Station A Date: 03/15/2001 Time: 09:11:54.451 Serial Number: 2001001234 FID=SEL-421-R101-V0-Z001001-D20010315 CID=0x6d72 Failures No Failures Warnings No Failures Warnings SELogic Relay Programming Environment Errors No Errors Relay Enabled



=>>STA A <enter></enter>					
	te: 03/15/2001 Time: 04:48:49.938 rial Number: 2001001234				
FID=SEL-421-R101-V0-Z001001-D20010315 CI	D=0x4572				
Failures No Failures					
Warnings No Warnings					
Channel Offsets (mV) W=Warn F=Fail CH1 CH2 CH3 CH4 CH5 CH6 CH7 CH8 CH9 0 0 0 0 0 0 0 0 0 0	0 CH10 CH11 CH12 MOF 0 0 0 0 0				
Power Supply Voltages (V) W=Warn F=Fail 3.3V_PS 5V_PS N5V_PS 15V_PS N15V_PS 3.28 4.91 -4.93 14.70 -14.79					
Temperature 23.7 degrees Celsius					
Communication Interfaces					
Active High Accuracy Time Synchronization Source: PPS/IRIG-B PPS/IRIG-B Source PRESENT IRIG-B Source PRESENT Fast Fiber Source ABSENT					
SELogic Relay Programming Environment Errors No Errors					
Relay Enabled					
=>>					

Figure 6.33 Relay Status From a STATUS A Command on a Terminal.

CSTATUS

The relay also reports status information in the Compressed ASCII format when you issue the **CST** command. The Compressed ASCII status message is the following:

"RID","SID","FID","yyyy",

"relay_name","station_name","FID=SEL-xxx-x-Rxxx-Vx-Zxxxxxx-Dxxxxxxxx","yyyy"

"MONTH", "DAY", "YEAR", "HOUR", "MIN", "SEC", "MSEC", "yyyy"

(Month),(Day),(Year),(Hour),(Min),(Sec),(MSec),"yyyy"

- "CPU_RAM","CPU_Prog","SELB00T","CPU_Settings","DSP_RAM","DSP","DSP_Chksum","DSP_TIME OUT","CPU_CARD_RAM","CPU_DSP_RAM","FRONT_PANEL","CAL_B0ARD","Comm_Card","Comm_Ca rd_Code","QUART","Analog_Conv","I0_1","I0_2","I0_3","I0_4","yyyy"
- (0k or F),(0k or W), (0k or W or F),(0k or W),(0crdh),(0k or F),(0k or
- "AtoD_Offset","Master_Offset","3.3V_PS","5V_PS","N5V_PS","15V_PS","N15V_PS","Temp_St atus","Temp","FPGA","ADC_FPGA","yyyy"
- (Ok or W),(Ok or W or F),(Ok or Fail),(Ok or Fail),"yyyy"

"Fast_Fiber_Port","MBA","MBB","Active_Time_Source","Prot_SELOGIC","Auto_SELOGIC","FM_ Test","CCrd_Test","DNP_Test","Event_Playback_Mode","Relay_Status","Port_F_Transp ","Port_1_Transp","Port_2_Transp","Port_3_Transp","Port_4_Transp","Port_5_Transp ","yyyy"

(Ok_or_F),(Inac or Ok or F),(Inac or Ok or F),(PPS/IRIG or IRIG).(errbh),(Errbh).(Enabled or Disabled),(Enabled or Disabled),(Enabled or Disabled),(Enabled or Disabled),(Enabled or Disabled),(F, 0 - 5),(F, 0 - 5),(F, 0 - 5),(F, 0 - 5),(F, 0 - 5),"yyyy"

Definitions for the items and fields in the Compressed ASCII configuration are listed below:

- ► yyyy is the checksum
- ► x is text in the FID (Firmware ID) string
- ccrd is the communications card hex code
- errb is a hex value representing the SELOGIC control equation error bits
- ► (description) is text that the relay supplies
- (Ok or W or F) is normal, warning, or failure, respectively

Figure 6.34 is a sample Compressed ASCII status message.

=>CST<Enter>

Figure 6.34 Compressed ASCII CST Command on a Terminal.

Relay Troubleshooting

Inspection Procedure	Complete the following inspection procedure before disturbing the system. After you finish the inspection, proceed to <i>Troubleshooting Procedures</i> .	
	Step 1. Confirm that the power is on. Do not turn the relay off.	
	Step 2. Measure and record the control power voltage at the relay POWER terminals marked "+" and "-" on the rear-panel terminal strip.	
	Step 3. Measure and record the voltages at all control inputs.	
	Step 4. Measure and record the state of all control outputs.	
	Step 5. Inspect the serial communications ports cabling to be sure that a communications device is connected to at least one communications port.	
Troubleshooting Procedures	Troubleshooting procedures for common problems are listed in <i>Table 6.9</i> . The table lists each symptom, possible causes, and corresponding diagnoses/ solutions. Related SEL-421 Relay commands are listed in bold capitals. See <i>Section 8: ASCII Command Reference in the Reference Manual</i> for details on SEL-421 Relay commands and <i>Section 9: Settings in the Reference Manual</i> for details on relay settings.	

Possible Cause	Diagnosis/Solution	
Dark Front Panel		
Power is off.	Verify that substation battery power is operational.	
Input power is not present.	Verify that power is present at the rear- panel terminal strip.	
Blown power supply fuse.	Replace the fuse. See Power Supply Fuse Replacement on page U.2.39 in the User's Guide.	
Poor contrast adjustment.	Press and hold { ESC } for two seconds. Press { Up } and { Down } pushbuttons to adjust contrast.	
Status Failure Notice on Front Panel		
Self-test failure.	Contact the SEL factory or your Technical Service Center. The OUT108 relay control output b con- tacts will be closed if you programmed NOT HALARM to OUT108, see <i>Alarm</i> <i>Output on page U.2.42 in the User's Guide</i>	
Alarm Output Asserts		
Power is off.	Restore power.	
Blown power supply fuse.	Replace the fuse. See <i>Power Supply Fuse</i> <i>Replacement on page U.2.39 in the User's</i> <i>Guide</i> .	
Power supply failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	
Main board or interface board failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	

Table 6.9 Troubleshooting Procedures (Sheet 1 of 3)

Possible Cause	Diagnosis/Solution
Other self-test failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.
System Does Not Respond to Commands	
No communication.	Confirm cable connections and types. If OK, type <ctrl+x></ctrl+x> , then <enter></enter> . This resets the terminal program.
Communications device is not connected to the system.	Connect a communications device.
Incorrect data speed (baud rate) or other communications parameters.	Configure your terminal port parameters to the particular relay port settings. Use the front panel to check port settings. See <i>SET/SHOW on page U.5.21 in the User's Guide</i> .
Incorrect communications cables.	Use SEL communications cables, or cables you build according to SEL specifications. See Communications Ports Connections on page U.2.44 in the User's Guide.
Communications cabling error.	Check cable connections.
Handshake line conflict; system is attempt- ing to transmit information, but cannot do so.	Check communications cabling. Use SEL communications cables, or cables you build according to SEL specifications. See <i>Communications Ports Connections on page U.2.44 in the User's Guide.</i>
System is in the XOFF state, halting com- munications.	Type <ctrl+q></ctrl+q> to put the system in the XON state.
Terminal Displays Meaningless Character	S
Data speed (baud rate) is set incorrectly.	Check the terminal parameters configura- tion. See Communications Ports Connec- tions on page U.2.44 in the User's Guide.
Terminal emulation is not optimal.	Try other terminal types, including VT-100 and VT-52 terminal emulations.
System Does Not Respond to Faults	
Relay is set improperly.	Review the relay settings. See Section 1: Protection Application Examples in the Applications Handbook.
Improper test settings.	Restore operating settings.
PT or CT connection wiring error.	Confirm PT and CT wiring.
Input voltages and currents phasing, and rotation errors.	Use relay metering. Use the TRI event trig- ger command and examine the generated event report. See <i>Examining Metering</i> <i>Quantities on page U.4.31 in the User's</i> <i>Guide</i> .
The analog input (flat multipin ribbon) cable between the input module board and the main board is loose or defective.	Reseat both ends of the analog input cable, observing proper ESD precautions. See Installing Optional I/O Interface Boards on page U.2.13 in the User's Guide.
Check the relay self-test status.	Take preventive action as directed by relay Status Warning and Status Failure informa- tion. See <i>Relay Self-Tests on page 6.37</i> and <i>Checking Relay Status on page U.4.12 in</i> <i>the User's Guide.</i>

Table 6.9	Troubleshooting	Procedures	(Sheet 2 of 3)
-----------	-----------------	------------	----------------

Possible Cause	Diagnosis/Solution	
Tripping Output Relay Remains Closed Fo	llowing a Fault	
Auxiliary contact control inputs are improperly wired.	Check circuit breaker auxiliary contacts wiring.	
Control output relay contacts have burned closed.	Remove relay power. Remove the control output connection. Check continuity; 'a' contacts will be open and 'b' contacts will be closed. Contact the SEL factory or your Technical Service Center if continuity checks fail.	
I/O interface board failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	
Power Supply Voltage Status Warning		
Power supply voltage(s) are out-of-toler- ance.	Log the Status Warning. If repeated warn- ings occur, take preventive action.	
A/D converter failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	
Power Supply Voltage Status Failure		
Power supply voltage(s) are out-of-tolerance.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	
A/D converter failure.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	
A/D OFFSET WARN Status Warning		
Loose ribbon cable between the input module board and the main board.	Reseat both ends of the analog input cable.	
A/D converter drift.	Log the Status Warning. If repeated warn- ings occur, contact the SEL factory or your Technical Service Center.	
Master offset drift.	LCD displays STATUS FAILURE screen. Contact the SEL factory or your Technical Service Center.	

 Table 6.9
 Troubleshooting Procedures (Sheet 3 of 3)

Factory Assistance

The employee-owners of Schweitzer Engineering Laboratories are dedicated to making electric power safer, more reliable, and more economical.

We appreciate your interest in SEL products and services. If you have any questions or comments, please contact us at:

Schweitzer Engineering Laboratories, Inc.

2350 NE Hopkins Court

Pullman, WA USA 99163-5603

Tel: (509) 332-1890

Fax: (509) 332-7990

Internet: www.selinc.com

You can also contact your local Technical Service Center. Telephone us at (509) 332-1890 or visit the SEL web page http://www.selinc.com/techsvc.htm to locate your Technical Service Center.

We guarantee prompt, courteous, and professional service. We appreciate receiving any comments and suggestions about new products or product improvements that would help us make your job easier.

This page intentionally left blank

Appendix A Firmware Versions

Firmware Versions

This manual covers SEL-421/SEL-421-1 Relays containing firmware bearing the following firmware version numbers (most recent firmware listed at top):

Table A.1	Firmware	Versions
-----------	----------	----------

Firmware Identification (FID) Number	Description of Changes	
This firmware differs from the previous version as follows:		
SEL-421-R103-V0-Z002002-D20020417 SEL-421-1-R103-V0-Z002002-D20020417	Spurious Quart interrupts caused by vary- ing character spacing will cause the relay to disable. This condition occurs when a com- munications processor is automatically retrieving data from the relay simulta- neously with a serial port terminal session.	
This firmware differs from the previous version as follows:		
SEL-421-R102-V0-Z002001-D20020403 SEL-421-1-R102-V0-Z002001-D20020403	Initial Release with Synchrophasor Mea- surement capability to the SEL-421 (not in the SEL-421-1)	
	Added VAZ, VBZ, VCZ settings options to SYNCP	
	Added VAY, VBY, VCY settings options to SYNCS1, SYNCS2 and ASYNCS2	
	Added ACOS, ASIN, CEIL, FLOOR and LOG math functions to SELOGIC control equations	
	Added new analog quantities for use in SELOGIC control equations:	
	Terminal W and X current magnitudes	
	Terminal Y and Z voltage magnitudes Instantaneous sequence quantities Contact inputs	
	Modified CHI output for SEL-2030 com- patibility	

This firmware differs from the previous version as follows:

SEL-421-R101-V0-Z001001-D20010104	Added 8-cycle lockout for subsequent ALTI or ALTV switches
SEL-421-1-R101-V0-Z001001-D20010104	Initial SEL-421-1 Relay Release
SEL-421-R100-V0-Z001001-D20010703	Initial SEL-421 Relay Release.

Instructions for determining the firmware version of your SEL-421/ SEL-421-1 Relay are in *Firmware Version Number on page U.6.37 in the User's Guide*. This page intentionally left blank

Glossary

"a" Contact	A breaker auxiliary contact (ANSI Standard Device Number 52A) that closes when the breaker is closed and opens when the breaker is open.
"a" Output	A relay control output that closes when the output relay asserts.
"b" Contact	A breaker auxiliary contact (ANSI Standard Device Number 52B) that opens when the breaker is closed and closes when the breaker is open.
"b" Output	A relay control output that opens when the output relay asserts.
"c" Contact	A breaker auxiliary contact that can be set to serve either as an "a" contact or as a "b" contact.
"c" Output	An output with both an "a" output and "b" output sharing a common post.
3 U, 4 U, 5 U	The designation of the vertical height of a device in rack units. One rack unit, U, is approximately 1.75 inches or 44.45 mm.
Α	Abbreviation for amps or amperes; unit of electrical current flow.
ABS Operator	An operator in math $SELOGIC^{\mathbb{R}}$ control equations that provides absolute value.
AC Ripple	The peak-to-peak ac component of a signal or waveform. In the station dc battery system, monitoring ac ripple provides an indication of whether the substation battery charger has failed.
Acceptance Testing	Testing that confirms that the relay meets published critical performance specifications and requirements of the intended application. Such testing involves testing protection elements and logic functions when qualifying a relay model for use on the utility system.
Access Level	A relay command level with a specified set of relay information and commands. Except for Access Level 0, you must have the correct password to enter an access level.
Access Level 0	The least secure and most limited access level. No password protects this level. From this level, you must enter a password to go to a higher level.
Access Level 1	A relay command level you use to monitor (view) relay information. The default access level for the relay front panel.
Access Level 2	The most secure access level where you have total relay functionality and control of all settings types.
Access Level A	A relay command level you use to access all Access Level 1 and Access Level B (Breaker) functions plus Automation, Global, Front Panel, Report, Port, and DNP settings.
Access Level B	A relay command level you use for Access Level 1 functions plus circuit breaker control and data.

GL.2 | Glossary Access Level O-Anti-Aliasing Filter

Access Level O	A relay command level you use to access all Access Level 1 and Access Level B (Breaker) functions plus Output, Global, Front Panel, Report, Port, and DNP settings.		
Access Level P	A relay command level you use to access all Access Level 1 and Access Level B (Breaker) functions plus Protection, SELOGIC, Global, Group, Breaker Monitor, Front Panel, Report, Port, and DNP settings.		
ACSELERATOR [®]	A Windows ^{\mathbb{R}} -based program that simplifies settings and provides analysis support.		
Active Settings Group	The settings group that the SEL-421 Relay is presently using from among six settings groups available in the relay.		
Admittance	The reciprocal of impedance; I/V.		
Advanced Settings	Settings for customizing protection functions; these settings are hidden unless you set EADVS := Y and EGADVS := Y.		
Alias	An alternate name for a Relay Word bit used in the SEL-421 Relay Sequential Events Recorder (SER) function. The assigned alias appears in the SER report in place of the Relay Word bit, making the SER report easier to review.		
Analog Quantities	Variables represented by such fluctuating measurable quantities as temperature, frequency, current, and voltage.		
AND Operator	Logical AND. An operator in Boolean SELOGIC control equations that requires fulfillment of conditions on both sides of the operator before the equation is true.		
ANSI Standard Device Numbers	A list of standard numbers used to represent electrical protection and control relays. The standard device numbers used in this instruction manual include the following:		
	25 Synchronism-check element		
	27 Undervoltage Element		
	32 Directional Elements		
	50 Overcurrent Element		
	51 Inverse Time-Overcurrent Element		
	52 AC Circuit Breaker		
	59 Overvoltage Element		
	67 Definite Time Overcurrent		
	79 Recloser		
	86 Breaker Failure Lockout		
	89 Disconnect		
	These numbers are frequently used within a suffix letter to further designate their application. The suffix letters used in this instruction manual include the following:		
	P Phase Element		
	G Residual/Ground Element		
	N Neutral/Ground Element		
	Q Negative-Sequence (312) Element		
Anti-Aliasing Filter	A low pass filter that blocks frequencies too high for the given sampling rate to accurately reproduce.		

Apparent Power, S	Complex power expressed in units of volt-amps (VA), kilovolt-amps (kVA), or megavolt-amps (MVA). Accounts for both real (P) and reactive (Q) power dissipated in a circuit: $S = P + jQ$. This is power at the fundamental frequency only; no harmonics are included in this quantity.
Arcing Resistance	The resistance in the arc resulting from a power line fault.
ASCII	Abbreviation for American Standard Code for Information Interchange. Defines a standard set of text characters. The SEL-421 Relay uses ASCII text characters to communicate using front-panel and rear-panel EIA-232 serial ports on the relay and through virtual serial ports.
ASCII Terminal	A terminal without built-in logic or local processing capability that can only send and receive information.
Assert	To activate. To fulfill the logic or electrical requirements needed to operate a device. To set a logic condition to the true state (logical 1) of that condition. To apply a closed contact to an SEL-421 Relay input. To close a normally open output contact. To open a normally closed output contact.
AT Modem Command Set Dialing String Standard	The command language standard that Hayes Microcomputer Products, Inc. developed to control auto-dial modems from an ASCII terminal (usually EIA-232 connected) or a PC (personal computer) containing software allowing emulation of such a terminal.
Autoconfiguration	The ability to determine relay type, model number, metering capability, port ID, baud rate, passwords, relay elements, and other information that an IED (an SEL-2020/2030 communications processor) needs to automatically communicate with relays.
Automatic Messages	Messages including status failure and status warning messages that the relay generates at the serial ports and displays automatically on the front-panel LCD.
Automatic Reclose	Automatic closing of a circuit breaker after a breaker trip by a protective relay.
Automation Variables	Variables that you include in automation SELOGIC control equations.
Auto-Reclose- Drive-to-Lockout	A logical condition that drives the auto-reclose function out of service with respect to a specific circuit breaker.
Autotransformer	A transformer with at least two common windings.
Bandpass Filter	A filter that passes frequencies within a certain range and blocks all frequencies outside this range.
Best Choice Ground Directional Supervision™ logic	An SEL logic that determines the directional element that the relay uses for ground faults.
Bit Label	The identifier for a particular bit.
Bit Value	Logical 0 or logical 1.
Block Trip Extension	Continuing the blocking signal at the receiving relay by delaying the dropout of Relay Word bit BT.

Blocking Signal Extension	The blocking signal for the DCB (directional comparison blocking) trip scheme is extended by a time delay on dropout timer to prevent unwanted tripping following current reversals.
Bolted Fault	A fault with essentially zero impedance or resistance between the shorted conductors.
Boolean Logic Statements	Statements consisting of variables that behave according to Boolean logic operators such as AND, NOT, and OR.
Breaker Auxiliary Contact	An electrical contact associated with a circuit breaker that opens or closes to indicate the breaker position. A form-a breaker auxiliary contact (ANSI Standard Device Number 52A) closes when the breaker is closed and opens when the breaker is open. A form-b breaker auxiliary contact (ANSI Standard Device Number 52B) opens when the breaker is closed and closes when the breaker is open.
Breaker-and-a-half Configuration	A switching station arrangement of three circuit breakers per two circuits; the two circuits share one of the circuit breakers.
Category	A collection of similar relay settings.
CCVT	Coupling-capacitor voltage transformer that uses a capacitive voltage divider to reduce transmission voltage to a level safe for metering and relaying devices. See CVT.
Checksum	A method for checking the accuracy of data transmission involving summation of a group of digits and comparison of this sum to a previously calculated value.
CID	Checksum identification of the firmware.
Circuit Breaker Failure Logic	This logic within the SEL-421 Relay detects and warns of failure or incomplete operation of a circuit breaker in clearing a fault or in performing a trip or close sequence.
Circuit Breaker History Report	A concise circuit breaker event history that contains as many as 128 events. This breaker history report includes circuit breaker mechanical operation times, electrical operation times, interrupted currents, and dc battery monitor voltages.
Circuit Breaker Report	A full report of breaker parameters for the most recent operation. These parameters include interrupted currents, number of operations, and mechanical and electrical operating times among many parameters.
Class	The first level of the relay settings structure including Global, Group, Breaker Monitor, Port, Report, Front Panel, DNP settings, Protection SELOGIC control equations, Automation SELOGIC control equations, and Output SELOGIC control equations.
Cold Start	Beginning a system from power up without carryover of previous system activities.
Commissioning Testing	Testing that serves to validate all system ac and dc connections and confirm that the relay, auxiliary equipment, and SCADA interface all function as intended with your settings. Perform such testing when installing a new protection system.

Common Class Components	Composite data objects that contain instances of UCA standard data types.
Common Inputs	Relay control inputs that share a common terminal.
Common Time Delay	Both ground and phase distance protection follow a common time delay on pickup.
Common Zone Timing	Both ground and phase distance protection follow a common time delay on pickup.
Communications Protocol	A language for communication between devices.
Communications-Assisted Tripping	Circuit breaker tripping resulting from the transmission of a control signal over a communications medium.
Comparison	Boolean SELOGIC control equation operation that compares two numerical values. Compares floating-point values such as currents, total counts, and other measured and calculated quantities.
COMTRADE	Abbreviation for Common Format for Transient Data Exchange. The SEL-421 Relay supports the IEEE Standard Common Format for Transient Data Exchange (COMTRADE) for Power Systems, IEEE C37.111–1999.
Conditioning Timers	Timers for conditioning Boolean values. Conditioning timers either stretch incoming pulses or allow you to require that an input take a state for a certain period before reacting to the new state.
Contact Input	See Control input.
Contact Output	See Control output.
Coordination Timer	A timer that delays an overreaching element so that a downstream device has time to operate.
Control Input	Relay inputs for monitoring the state of external circuits. Connect auxiliary relay and circuit breaker contacts to the control inputs.
Control Output	Relay outputs that affect the state of other equipment. Connect control outputs to circuit breaker trip and close coils, breaker failure auxiliary relays, communications-assisted tripping circuits, and SCADA systems.
COS Operator	Operator in math SELOGIC control equations that provides the cosine function.
Counter	Variable or device such as a register or storage location that either records or represents the number of times an event occurs.
Cross-country fault	A cross-country fault consists of simultaneous separate single phase-to- ground faults on parallel lines.
СТ	Current transformer.
CT Subsidence Current	Subsidence current appears as a small exponentially decaying dc current with a long time constant. This current results from the energy trapped in the CT magnetizing branch after the circuit breaker opens to clear a fault or interrupt load.
СТР	Current transformer ratio

Current Reversal Guard Logic	Under this logic, the relay does not key the transmitter and ignores reception of a permissive signal from the remote terminal when a reverse-looking element detects an external fault.
Current Transformer Saturation	The point of maximum current input to a current transformer; any change of input beyond the saturation point fails to produce any appreciable change in output.
CVT	Capacitive voltage transformer that uses a capacitive voltage divider to reduce transmission voltage to a level safe for metering and relaying devices. See CCVT.
CVT Transient Blocking	Logic that prevents transient errors on capacitive voltage transformers from causing false operation of Zone 1 mho elements.
CVT Transient Detection Logic	Logic that detects transient errors on capacitive voltage transformers.
Data Bit	A single unit of information that can assume a value of either logical 0 or logical 1 and can convey control, address, information, or frame check sequence data.
Data Label	The identifier for a particular data item.
Data Objects	Individual pieces of UCA data created from instances of common class components or data items that are instances of standard data types.
DC Offset	A dc component of fault current that results from the physical phenomenon preventing an instantaneous change of current in an inductive circuit.
DCB (Directional Comparison Blocking)	A communications-assisted protection scheme. A fault occurring behind a sending relay causes the sending relay to transmit a blocking signal to a remote relay; the blocking signal interrupts the tripping circuit of the remote relay and prevents tripping of the protected line.
DCE Devices	Data communication equipment devices (modems).
DCUB (Directional Comparison Unblocking)	A communications-assisted tripping scheme with logic added to a POTT scheme that allows high-speed tripping of overreaching elements for a brief time during a loss of channel. The logic then blocks trip permission until the communications channel guard returns for a set time.
Deadband	The range of variation an analog quantity can traverse before causing a response.
Deassert	To deactivate. To remove the logic or electrical requirements needed to operate a device. To clear a logic condition to its false state (logical 0). To open the circuit or open the contacts across an SEL-421 Relay input. To open a normally open output contact. To close a normally closed output contact.
Debounce Time	The time that masks the period when relay contacts continue to move after closing; debounce time covers this indeterminate state.
Default Data Map	The default map of objects and indices that the SEL-421 Relay uses in DNP protocol.
Delta	A phase-to-phase series connection of circuit elements, particularly voltage transformers or loads.

Demand Meter	A measuring function that calculates a rolling average or thermal average of instantaneous measurements over time.
Direct Tripping	Local or remote protection elements provide tripping without any additional supervision.
Directional Start	A blocking signal provided by reverse reaching elements to a remote terminal used in DCB communications-assisted tripping schemes. If the fault is internal (on the protected line), the directional start elements do not see the fault and do not send a blocking signal. If the fault is external (not on the protected line), the directional start elements start sending the block signal.
Directional Supervision	The relay uses directional elements to determine whether protective elements operate based on the direction of a fault relative to the relay.
Disabling Time Delay	A DCUB scheme timer (UBDURD) that prevents high-speed tripping following a loss-of-channel condition.
Distance Calculation Smoothness	A relay algorithm that determines whether the distance-to-fault calculation varies significantly or is constant.
Distance Protection Zone	The area of a power system where a fault or other application-specific abnormal condition should cause operation of a protective relay.
DMTC Period	The time of the demand meter time constant in demand metering.
DNP (Distributed Network Protocol)	Manufacturer-developed, hardware-independent communications protocol.
Dropout Time	The time measured from the removal of an input signal until the output signal deasserts. You can set the time, in the case of a logic variable timer, or the dropout time can be a result of the characteristics of an element algorithm, as in the case of an overcurrent element dropout time.
DTE Devices	Data terminal equipment (computers, terminals, printers, relays, etc.).
DTT (Direct Transfer Trip)	A communications-assisted tripping scheme. A relay at one end of a line sends a tripping signal to the relay at the opposite end of the line.
Dumb Terminal	See ASCII terminal.
DUTT (Direct Underreaching Transfer Trip)	A communications-assisted tripping scheme. Detection of a Zone 1 fault at either end of a line causes tripping of the local circuit breaker as well as simultaneous transmission of a tripping signal to the relay at the opposite end of the line. The scheme is said to be underreaching because the Zone 1 relays at both ends of the line reach only 80 percent (typically) of the entire line length.
Echo	The action of a local relay returning (echoing) the remote terminal permissive signal to the remote terminal when the local breaker is open or a weak infeed condition exists.
Echo Block Time Delay	A time delay that blocks the echo logic after dropout of local permissive elements.
Echo Duration Time Delay	A time delay that limits the duration of the echoed permissive signal.

ECTT (Echo Conversion to Trip)	An element that allows a weak terminal, after satisfaction of specific conditions, to trip by converting an echoed permissive signal to a trip signal.
EEPROM	Electrically Erasable Programmable Read-Only Memory. Nonvolatile memory where relay settings, event reports, SER records, and other nonvolatile data are stored.
EHV	Extra high voltage. Voltages greater than 230 kV.
EIA-232	Electrical definition for point-to-point serial data communications interfaces, based on the standard EIA/TIA-232. Formerly known as RS-232.
EIA-485	Electrical standard for multidrop serial data communications interfaces, based on the standard EIA/TIA-485. Formerly known as RS-485.
Electrical Operating Time	Time between trip or close initiation and an open phase status change.
Electromechanical Reset	Setting of the relay to match the reset characteristics of an electromechanical overcurrent relay.
End-Zone Fault	A fault at the farthest end of a zone that a relay is required to protect.
Energy Metering	Energy metering provides a look at imported power, exported power, and net usage over time; measured in MWh (megawatt hours).
Equalize Mode	A procedure where substation batteries are overcharged intentionally for a preselected time in order to bring all cells to a uniform output.
ESD (Electrostatic Discharge)	The sudden transfer of charge between objects at different potentials caused by direct contact or induced by an electrostatic field.
Ethernet	A network physical and data link layer defined by IEEE 802.2 and IEEE 802.3.
Event History	A quick look at recent relay activity that includes a standard report header; event number, date, time, and type; fault location; maximum fault phase current; active group at the trigger instant; and targets.
Event Report	A text-based collection of data stored by the relay in response to a triggering condition, such as a fault or ASCII TRI command. The data show relay measurements before and after the trigger, in addition to the states of protection elements, relay inputs, and relay outputs each processing interval. After an electrical system fault, use event reports to analyze relay and system performance.
Event Summary	A shortened version of stored event reports. An event summary includes items such as event date and time, event type, fault location, time source, recloser shot counter, prefault and fault voltages, currents, and sequence current, and MIRRORED BITS communications channel status (if enabled).
	The relay sends an event report summary (if auto messaging is enabled) to the relay serial port a few seconds after an event.
EXP Operator	Math SELOGIC control equation operator that provides exponentiation.
F_TRIG	Falling-edge trigger. Boolean SELOGIC control equation operator that triggers an operation upon logic detection of a falling edge.

Fail-Safe	Refers to an output that is open during normal relay operation and closed when relay power is removed or if the relay fails. Configure alarm outputs for fail-safe operation.
Falling Edge	Transition from logical 1 to logical 0.
Fast Hybrid Control Output	A control output similar to, but faster than, the hybrid control output. The fast hybrid output uses an insulated gate bipolar junction transistor (IGBT) to interrupt (break) high inductive dc currents and to very rapidly make and hold the current until a metallic contact operates, at which time the IGBT turns off and the metallic contact holds the current. Unlike the hybrid control output, this output is not polarity sensitive; reversed polarity causes no misoperations.
Fast Meter	SEL binary serial port command used to collect metering data with SEL relays.
Fast Operate	SEL binary serial port command used to perform control with SEL relays.
Fault Type Identification Selection	Logic the relay uses to identify balanced and unbalanced faults (FIDS).
FID	Relay firmware identification string. Lists the relay model, firmware version and date code, and other information that uniquely identifies the firmware installed in a particular relay.
Firmware	The nonvolatile program stored in the relay that defines relay operation.
Flash Memory	A type of nonvolatile relay memory used for storing large blocks of nonvolatile data.
Flashover	A disruptive discharge over the surface of a solid dielectric in a gas or liquid.
Float High	The highest charging voltage supplied by a battery charger.
Float Low	The lowest charging voltage supplied by a battery charger.
Free-Form Logic	Custom logic creation and execution order.
Free-Form SELOGIC Control Equations	Free-form relay programming that includes mathematical operations, custom logic execution order, extended relay customization, and automated operation.
FTP	File transfer protocol.
Function Code	A code that defines how you manipulate an object in DNP 3.0 protocol.
Functional Component	Portion of a UCA GOMSFE brick dedicated to a particular function including status, control, and descriptive tags.
Fundamental Frequency	The component of the measured electrical signal with a frequency equal to the normal electrical system frequency, usually 50 Hz or 60 Hz. Generally used to differentiate between the normal system frequency and any harmonic frequencies present.
Global Settings	General settings including those for relay and station identifiers, number of breakers, date format, phase rotation, nominal system frequency, enables, station dc monitoring, control inputs, settings group selection, data reset controls, frequency tracking, time and date management, and current and voltage source selection.

GL.10 | Glossary GOMSFE-IA, IB, IC

GOMSFE	Generic Object Model for Substation and Feeder Equipment; a system for presenting and exchanging IED data.
GOOSE	Generic Object Oriented Substation Event; a GOMSFE object for control messaging.
GPS	Global Positioning System. Source of position and high-accuracy time information.
Ground Directional Element Priority	The order the relay uses to select directional elements to provide ground directional decisions; relay setting ORDER.
Ground Distance Element	A mho or quadrilateral distance element the relay uses to detect faults involving ground along a transmission line.
Ground Fault Loop Impedance	The impedance in a fault-caused electric circuit connecting two or more points through ground conduction paths.
Ground Overcurrent Elements	Elements that operate by comparing a residual ground calculation of the three- phase inputs with the residual overcurrent threshold setting. The relay asserts ground overcurrent elements when a relay residual current calculation exceeds ground current setting thresholds.
Ground Quadrilateral Distance Protection	Ground distance protection consisting of a four-sided characteristic on an R-X diagram.
Ground Return Resistance	Fault resistance that can consist of ground path resistance typically in tower footing resistance and tree resistance.
Guard-Present Delay	A timer that determines the minimum time before the relay reinstates permissive tripping following a loss-of-channel condition in the DCUB communications-assisted tripping scheme; relay setting GARD1D.
GUI	Graphical user interface.
Hexadecimal Address	A register address consisting of a numeral with an "h" suffix or a "0x" prefix.
High-Resolution Data Capture	Reporting of 3 kHz low-pass analog filtered data from the power system at each event trigger or trip at high sample rates of 8000 samples/second, 4000 samples/second, 2000 samples/second, and 1000 samples/second.
HMI	Human machine interface.
Homogeneous System	A power system with nearly the same angle ($<$ 5 ° difference) for the impedance angles of the local source, the protected line, and the remote source.
HV	High voltage. System voltage greater than or equal to 100 kV and less than 230 kV.
Hybrid Control Output	Contacts that use an insulated gate bipolar junction transistor (IGBT) in parallel with a mechanical contact to interrupt (break) high inductive dc currents. The contacts can carry continuous current, while eliminating the need for heat sinking and providing security against voltage transients. These contacts are polarity dependent and cannot be used to switch ac control signals.
IA, IB, IC	Measured A-phase, B-phase, and C-phase currents.

IED	Intelligent electronic device.
IG	Residual current, calculated from the sum of the phase currents. In normal, balanced operation, this current is very small or zero.
IGBT	Insulated gate bipolar junction transistor.
Independent Zone Timing	The provision of separate zone timers for phase and ground distance elements.
Infinite Bus	A constant-voltage bus.
Input Conditioning	The establishment of debounce time and assertion level.
Instance	A subdivision of a relay settings class. Group settings have several subdivisions (Group 1–Group 6), while the Global settings class has one instance.
Instantaneous Meter	Type of meter data presented by the SEL-421 Relay that includes the present values measured at the relay ac inputs. The word "Instantaneous" is used to differentiate these values from the measurements presented by the demand, thermal, energy, and other meter types.
IRIG-B	A time code input that the relay can use to set the internal relay clock.
Jitter	Time, amplitude, frequency, or phase-related abrupt, spurious variations in duration, magnitude, or frequency.
L/R	Circuit inductive/resistive ratio.
Latch Bits	Nonvolatile storage locations for binary information.
LED	Light-emitting diode. Used as indicators on the relay front panel.
Left-Side Value	LVALUE. Result storage location of a SELOGIC control equation.
Line Impedance	The phasor sum of resistance and reactance in the form of positive-sequence, negative-sequence, and zero-sequence impedances of the protected line.
LMD	SEL distributed port switch protocol.
LN Operator	Math SELOGIC control equation operator that provides natural logarithm.
Load Encroachment	The load-encroachment feature allows setting of phase overcurrent elements and phase distance elements independent of load levels.
Local Bits	The Relay Word bit outputs of local control switches that you access through the SEL-421 Relay front panel. Local control switches replace traditional panel-mounted control switches.
Lockout Relay	An auxiliary relay that prevents operation of associated devices until it is reset either electrically or by hand.
Logical 0	A false logic condition, dropped out element, or deasserted control input or control output.
Logical 1	A true logic condition, picked up element, or asserted control input or control output.

Loss of Channel	Loss of guard and no permissive signal from communications gear in a DCUB (directional comparison unblocking scheme) for either two or three terminal lines.
Loss of Guard	No guard signal from communications gear.
Loss of Potential	Loss of one or more phase voltage inputs to the relay secondary inputs.
Low-Level Test Interface	An interface that provides a means for interrupting the connection between the relay input transformers and the input processing module and allows inserting reduced-scale test quantities for relay testing.
Maintenance Testing	Testing that confirms that the relay is measuring ac quantities accurately and verifies correct functioning of auxiliary equipment, scheme logic, and protection elements.
Math Operations	Calculations for automation or extended protection functions.
Math Operators	Operators that you use in the construction of math SELOGIC control equations to manipulate numerical values and provide a numerical base-10 result.
Maximum Dropout Time	The maximum time interval following a change of input conditions between the deassertion of the input and the deassertion of the output.
Maximum/Minimum Meter	Type of meter data presented by the SEL-421 Relay that includes a record of the maximum and minimum of each value, along with the date and time that each maximum and minimum occurred.
Mechanical Operating Time	Time between trip initiation or close initiation and the change in status of an associated circuit breaker auxiliary 52A normally open contacts.
Mho Characteristic	A directional distance relay characteristic that plots a circle for the basic relay operation characteristic on an R-X diagram.
MIRRORED BITS TM Communications	Patented relay-to-relay communications technique that sends internal logic status, encoded in a digital message, from one relay to the other. Eliminates the need for some communications hardware.
MMS	Manufacturing Messaging Specification, a data exchange protocol used by UCA.
MOD	Motor-operated disconnect.
Model	Model of device (or component of a device) including the data, control access, and other features in UCA protocol.
Motor Running Time	The circuit breaker motor running time. Depending on your particular circuit breaker, you can use the motor running time to monitor the charge time of the circuit breaker springs or the running time of the compressor motor.
MOV	Metal-oxide varistor.
Negation Operator	A SELOGIC control equation math operator that changes the sign of the argument. The argument of the negation operation is multiplied by -1 .
Negative-Sequence	A configuration of three-phase currents and voltages. The currents and voltages have equal magnitude and a phase displacement of 120°, and have clockwise phase rotation with current and voltage maxima that occur

	differently from that for positive-sequence configuration. If positive-sequence maxima occur as ABC, negative-sequence maxima occur as ACB.
Negative-Sequence Current Supervision Pickup	An element allowed to operate only when a negative-sequence current exceeds a threshold.
Negative-Sequence Directional Element	An element that provides directivity by the sign, plus or minus, of the measured negative-sequence impedance.
Negative-Sequence Impedance	Impedance of a device or circuit that results in current flow with a balanced negative-sequence set of voltage sources.
Negative-Sequence Overcurrent Elements	Elements that operate by comparing a negative-sequence calculation of the three-phase secondary inputs with negative-sequence overcurrent setting thresholds. The relay asserts these elements when a relay negative-sequence calculation exceeds negative-sequence current setting thresholds.
Negative-Sequence Voltage-Polarized Directional Element	These directional elements are 32QG and 32Q. 32QG supervises the ground distance elements and residual directional overcurrent elements; 32Q supervises the phase distance elements.
NEMA	National Electrical Manufacturers' Association.
Neutral Impedance	An impedance from neutral to ground on a device such as a generator or transformer.
No Current/Residual Current Circuit Breaker Failure Protection Logic	Logic for detecting and initiating circuit breaker failure protection with a logic transition, or when a weak source drives the fault or a high-resistance ground fault occurs.
Nondirectional Start	A blocking signal provided by nondirectional overcurrent elements to a remote terminal used in DCB communications-assisted tripping schemes. The nondirectional start elements start sending the block signal.
Nonhomogeneous System	A power system with a large angle difference (>5° difference) for the impedance angles of the local source, the protected line, and the remote source.
Nonvolatile Memory	Relay memory that persists over time to maintain the contained data even when the relay is deenergized.
NOT Operator	A logical operator that produces the inverse value.
OR Operator	Logical OR. A Boolean SELOGIC control equation operator that compares two Boolean values and yields either a logical 1 if either compared Boolean value is logical 1 or a logical 0 if both compared Boolean values are logical 0.
OSI	Open Systems Interconnect. A model for describing communications protocols. Also an ISO suite of protocols designed to this model.
Out-of-Step Blocking	Blocks the operation of phase distance elements during power swings.
Out-of-Step Tripping	Trips the circuit breaker(s) during power swings.
Override Values	Test values you enter in Fast Meter, DNP, and communications card database storage.

Parentheses Operator	Math operator. Use paired parentheses to control the execution of operations in a SELOGIC control equation.
РС	Personal computer.
Peak Demand Metering	Maximum demand and a time stamp for phase currents, negative-sequence and zero-sequence currents, and powers. The SEL-421 Relay stores peak demand values and the date and time these occurred to nonvolatile storage once per day, overwriting the previously stored value if the new value is larger. Should the relay lose control power, the relay restores the peak demand information saved at 23:50 hours on the previous day.
Phase Distance Element	A mho distance element the relay uses to detect phase-to-phase and three- phase faults at a set reach along a transmission line.
Phase Overcurrent Element	Elements that operate by comparing the phase current applied to the secondary current inputs with the phase overcurrent setting. The relay asserts these elements when any combination of the phase currents exceeds phase current setting thresholds.
Phase Rotation	The sequence of voltage or current phasors in a multiphase electrical system. In an ABC phase rotation system, the B-phase voltage lags the A-phase voltage by 120°, and the C-phase voltage lags B-phase voltage by 120°. In an ACB phase rotation system, the C-phase voltage lags the A-phase voltage by 120°, and the B-phase voltage lags the C-phase voltage by 120°.
Phase Selection	Ability of the relay to determine the faulted phase or phases.
Pickup Time	The time measured from the application of an input signal until the output signal asserts. You can set the time, as in the case of a logic variable timer, or the pickup time can be a result of the characteristics of an element algorithm, as in the case of an overcurrent element pickup time.
Pinout	The definition or assignment of each electrical connection at an interface. Typically refers to a cable, connector, or jumper.
Polarizing Memory	A circuit that provides a polarizing source for a period after the polarizing quantity has changed or gone to zero.
Pole Discrepancy	A difference in the open/closed status of circuit breaker poles. The relay continuously monitors the status of each circuit breaker pole to detect open or close conditions among the three poles.
Pole-Open Logic	Logic that determines the conditions that the relay uses to indicate an open circuit breaker pole.
Pole Scatter	Deviation in operating time between pairs of circuit breaker poles.
Port Settings	Communications port settings such as Data Bits, Speed, and Stop Bits.
Positive-Sequence	A configuration of three-phase currents and voltages. The currents and voltages have equal magnitude and a phase displacement of 120°. With conventional rotation in the counter-clockwise direction, the positive-sequence current and voltage maxima occur in ABC order.
Positive-Sequence Current Restraint Factor, a2	This factor compensates for highly unbalanced systems with many untransposed lines and helps prevent misoperation during current transformer

	saturation. The a2 factor is the ratio of the magnitude of negative-sequence current to the magnitude of positive-sequence current ($I2/I1$).	
Positive-sequence Current Supervision Pickup	An element that operates only when a positive-sequence current exceeds a threshold.	
Positive-Sequence Impedance	Impedance of a device or circuit that results in current flow with a balanced positive-sequence set of voltage sources.	
POTT (Permissive Overreaching Transfer Trip)	A communications-assisted line protection scheme. At least two overreaching protective relays must receive a permissive signal from the other terminal(s) before all relays trip and isolate the protected line.	
Power Factor	The cosine of the angle by which phase current lags or leads phase voltage in an ac electrical circuit. Power factor equals 1.0 for power flowing to a pure resistive load.	
PPS	Pulse per second from a GPS receiver. PPS time mode is present when both 1k PPS and IRIG-B signals are applied to the relay Time inputs.	
Protection and Automation Separation	Segregation of protection and automation processing and settings.	
Protection Settings Group	Individual scheme settings for as many as six different schemes (or instances).	
Protection-Disabled State	Suspension of relay protection element and trip/close logic processing and deenergization of all control outputs.	
РТ	Potential transformer. Also referred to as a voltage transformer or VT.	
PTR	Potential transformer ratio.	
Quadrilateral Characteristic	A distance relay characteristic on an R-X diagram consisting of a directional measurement, reactance measurement, and two resistive measurements.	
Qualifier Code	Specifies type of range for DNP 3.0 objects. With the help of qualifier codes, DNP master devices can compose the shortest, most concise messages.	
R_TRIG	Rising-edge trigger. Boolean SELOGIC control equation operator that triggers an operation upon logic detection of a rising edge.	
RAM	Random Access Memory. Volatile memory where the relay stores intermediate calculation results, Relay Word bits, and other data.	
Reactance Reach	The reach of a distance element in the reactive (X) direction in the R-X plane.	
Real Power	Power that produces actual work. The portion of apparent power that is real, not imaginary.	
Reclose	The act of automatically closing breaker contacts after a protective relay trip has opened the circuit breaker contacts and interrupted current through the breaker.	
Relay Word Bit	A single relay element or logic result. A Relay Word bit can equal either logical 1 or logical 0. Logical 1 represents a true logic condition, picked up element, or asserted control input or control output. Logical 0 represents a false logic condition, dropped out element, or deasserted control input or control output. Use Relay Word bits in SELOGIC control equations.	

GL.16 | Glossary

Remapping-SELOGIC Control Equation

Remapping	The process of selecting data from the default map and configuring new indices to form a smaller data set optimized to your application.	
Remote Bit	A Relay Word bit with a state that is controlled by serial port commands, including the CONTROL command, a binary Fast Operate command, DNP binary output operation, or a UCA control operation.	
Report Settings	Event report and Sequential Events Recorder settings.	
Residual Current	The sum of the measured phase currents. In normal, balanced operation, this current is very small or zero.	
Residual Directional Overcurrent Element	A residual overcurrent element allowed to operate in only the forward or reverse direction.	
Residual Overcurrent Protection	Overcurrent protection that operates at conditions exceeding a threshold of system unbalance $(3I_0 = I_A + I_B + I_C)$.	
Resistance Blinder	An operate boundary in the resistive direction of a ground quadrilateral distance element.	
Resistive Reach	The reach of a distance element in the resistive (R) direction in the R-X plane.	
Retrip	A subsequent act of attempting to open the contacts of a circuit breaker after the failure of an initial attempt to open these contacts.	
Reverse Fault	A fault operation behind a relay terminal.	
Rising Edge	Transition from logical 0 to logical 1, or the beginning of an operation.	
RMS	Root-mean-square. This is the effective value of the current and voltage measured by the relay, accounting for the fundamental frequency and higher-order harmonics in the signal.	
Rolling Demand	A sliding time-window arithmetic average in demand metering.	
RTU	Remote Terminal Unit.	
RXD	Received data.	
SCADA	Supervisory control and data acquisition.	
Self-Description	A feature of GOMSFE in the UCA2 protocol. A master device can request a description of all of the GOMSFE models and data within the IED.	
Self-Test	A function that verifies the correct operation of a critical device subsystem and indicates detection of an out-of-tolerance condition. The SEL-421 Relay has self-tests that validate the relay power supply, microprocessor, memory, and other critical systems.	
SELOGIC Expression Builder	A rules-based editor within the SEL-5030 ACSELERATOR Software Program for programming SELOGIC control equations.	
SELOGIC Math Variables	Math calculation result storage locations.	
SELOGIC Control Equation	A relay setting that allows you to control a relay function (such as a control output) using a logical combination of relay element outputs and fixed logic outputs.	

Sequencing Timers	Timers designed for sequencing automated operations.	
Sequential Events Recorder	A relay function that stores a record of the date and time of each assertion and deassertion of every Relay Word bit in a list that you set in the relay. SER provides a useful way to determine the order and timing of events of a relay operation.	
SER	Sequential Events Recorder or the relay serial port command to request a report of the latest 1000 sequential events.	
Series-Compensated Line	A power line on which the addition of series capacitance compensates for excessive inductive line impedance.	
Settle/Settling Time	Time required for an input signal to result in an unvarying output signal within a specified range.	
Shot Counter	A counter that records the number of times a recloser attempts to close a circuit breaker.	
Shunt Admittance	The admittance resulting from the presence of a device in parallel across other devices or apparatus that diverts some current away from these devices or apparatus.	
Shunt Capacitance	The capacitance between a network connection and any existing ground.	
Shunt Current	The current that a parallel-connected high-resistance or high-impedance device diverts away from devices or apparatus.	
SIN Operator	Operator in math SELOGIC control equations that provides the sine function.	
Single-Pole Trip	A circuit breaker trip operation that occurs when one pole of the three poles of a circuit breaker opens independently of the other poles.	
SIR	Source-to-line impedance ratio.	
SOTF (Switch-Onto-Fault Protection Logic)	Logic that provides tripping if a circuit breaker closes into a zero voltage bolted fault, such as would happen if protective grounds remained on the line following maintenance.	
Source Impedance	The impedance of an energy source at the input terminals of a device or network.	
SQRT Operator	Math SELOGIC control equation operator that provides square root.	
Stable Power Swing	A change in the electrical angle between power systems. A control action can return the angular separation between systems to less than the critical angle.	
Status Failure	A severe out-of-tolerance internal operating condition. The relay issues a status failure message and enters a protection-disabled state.	
Status Warning	Out-of-tolerance internal operating conditions that do not compromise relay protection, yet are beyond expected limits. The relay issues a status warning message and continues to operate.	
Strong Password	A mix of valid password characters in a six-character combination that does not spell common words in any portion of the password. Valid password characters are numbers, upper- and lower-case alphabetic characters, "." (period), and "-" (hyphen).	

Subsidence Current	See CT subsidence current.	
Synch Reference	A phasor the relay uses as a polarizing quantity for synchronism check calculations.	
Synchronism Check	Verification by the relay that system components operate within a preset frequency difference and within a preset phase angle displacement between voltages.	
Synchronized Phasor	A phasor calculated from data samples using an absolute time signal as the reference for the sampling process. The phasors from remote sites have a defined common phase relationship. Also known as Synchrophasor.	
Telnet	An Internet protocol for exchanging terminal data that connects a computer to a network server and allows control of that server and communication with other servers on the network.	
Terminal Emulation Software	Software such as Microsoft [®] HyperTerminal or ProComm [®] Plus that can be used to send and receive ASCII text messages and files via a computer serial port.	
Thermal Demand	Thermal demand is a continuous exponentially increasing or decreasing accumulation of metered quantities; used in demand metering.	
Thermal Withstand Capability	The capability of equipment to withstand a predetermined temperature value for a specified time.	
Three-Phase Fault	A fault involving all three phases of a three-phase power system.	
Three-Pole Trip	A circuit breaker operation that occurs when the circuit breaker opens all three poles at the same time.	
Time Delay on Pickup	The time interval between initiation of a signal at one point and detection of the same signal at another point.	
Time Dial	A control that governs the time scale of the time-overcurrent characteristic of a relay. Use the time-dial setting to vary relay operating time.	
Time-Delayed Tripping	Tripping that occurs after expiration of a pre-determined time.	
Time-Overcurrent Element	An element that operates according to an inverse relationship between input current and time, with higher current causing faster relay operation.	
Torque Control	A method of using one relay element to supervise the operation of another.	
Total Clearing Time	The time interval from the beginning of a fault condition to final interruption of the circuit.	
Tower Footing Resistance	The resistance between true ground and the grounding system of a tower.	
Transformer Impedance	The resistive and reactive parameters of a transformer looking in to the transformer primary or secondary windings. Use industry accepted open- circuit and short-circuit tests to determine these transformer equivalent circuit parameters.	
Tree Resistance	Resistance resulting from a tree in contact with a power line.	
TXD	Transmitted data.	

UCA2	Utility Communications Architecture. A network-independent protocol suite that serves as an interface for individual intelligent electronic devices.	
Unbalanced Fault	All faults that do not include all three phases of a system.	
Unconditional Tripping	Protection element tripping that occurs apart from conditions such as those involving communication, switch-onto-fault logic, etc.	
Unstable Power Swing	A change in the electrical angle between power systems for which a control action cannot return the angular separation between systems to an angle less than the critical angle.	
Untransposed Line	A transmission line with phase conductors that are not regularly transposed. The result is an imbalance in the mutual impedances between phases.	
User ST	Region in GOOSE for user-specified applications.	
VA, VB, VC	Measured A-phase-to-neutral, B-phase-to-neutral, and C-phase-to-neutral voltages.	
VAB, VBC, VCA	Measured or calculated phase-to-phase voltages.	
VG	Residual voltage calculated from the sum of the three phase-to-neutral voltages, if connected.	
Virtual Terminal Connection	A mechanism that uses a virtual serial port to provide the equivalent functions of a dedicated serial port and a terminal.	
Volatile Storage	A storage device that cannot retain data following removal of relay power.	
VT	Voltage transformer. Also referred to as a potential transformer or PT.	
Warm Start	The reset of a running system without removing and restoring power.	
Weak Infeed Logic	Logic that permits rapid tripping for internal faults when a line terminal has insufficient fault current to operate protective elements.	
Wye	A phase-to-neutral connection of circuit elements, particularly voltage transformers or loads. To form a wye connection using transformers, connect the nonpolarity side of each of three voltage transformer secondaries in common (the neutral), and take phase to neutral voltages from each of the remaining three leads. When properly phased, these leads represent the A-phase-, B-phase-, and C-phase-to-neutral voltages. This connection is frequently called 'four-wire wye,' alluding to the three phase leads plus the neutral lead.	
Zero-Sequence	A configuration of three-phase currents and voltages with currents and voltages that occur simultaneously, are always in phase, and have equal magnitude $(3I_0 = I_A + I_B + I_C)$.	
Zero-Sequence Compensation Factor	A factor based on the zero-sequence and positive-sequence impedance of a line that modifies a ground distance element to have the same reach as a phase distance element.	
Zero-Sequence Impedance	Impedance of a device or circuit resulting in current flow when a single voltage source is applied to all phases.	

Zero-Sequence Mutual Coupling	Zero-sequence current in an unbalanced circuit in close proximity to a second circuit induces voltage into the second circuit. When not controlled by protection system design and relay settings, this situation can cause improper operation of relays in both systems.	
Zero-Sequence Overcurrent Element	Overcurrent protection that operates at conditions exceeding a threshold of system unbalance.	
Zero-Sequence Voltage-Polarized Directional Element	An element that provides directionality by the sign, plus or minus, of the measured zero-sequence impedance.	
Z-Number	That portion of the relay FID string that identifies the proper ACSELERATOR software relay driver version and HMI driver version when creating or editing relay settings files.	
Zone Time Delay	Time delay associated with the forward or reverse step distance and zone protection.	

Index

Page numbers appearing in bold mark the location of the topic's primary discussion.

U=User's Guide; A=Application Handbook; R=Reference Manual

Symbols

*, largest current A.3.16, A.3.19 >, trigger row A.3.16, A.3.19

A

Acceptance Testing U.6.2 See also Testing ACCESS Command U.4.9, R.8.2 Access Levels U.4.8-U.4.10 1, B, P, A, O, 2 levels U.4.10 communications ports U.4.9 front panel U.4.9 Accuracy energy metering A.2.41 instantaneous metering A.2.32 maximum/minimum metering A 2 34 ACSELERATOR Software U.1.4, U.3.1-U.3.20, A.7.6 communications setup U.3.4-U.3.5 **FTP U.3.4** serial U.3.4 Telnet U.3.5 terminal U.3.5 COMTRADE U.3.15-U.3.18 control window U.3.20 database manager U.3.6-U.3.7 device overview screen U.3.20 drivers U.3.7-U.3.8 event reports U.3.15-U.3.18 event phasor display U.3.17 event settings screen U.3.18 expression builder U.3.13-U.3.14 harmonic analysis U.3.17 HMI U.3.19 HMI phasors screen U.3.20 installation U.3.2-U.3.3 metering U.3.20 Relay Editor U.3.11 relay part number U.3.11-U.3.12 setting the relay U.3.9-U.3.12 summary event screen U.3.18 system requirements U.3.2 Alarm dc battery system monitor A.2.26 HALARM U.6.37 relay output U.2.42

Analog Quantities in SELOGIC control equations **R.3.11** list sorted alphabetically **R.B.7**

list sorted by function **R.B.2** ASCII Commands U.4.5, A.2.17, R.4.2, R.5.5, **R.8.1–R.8.57** See Commands

Automatic Restoration See Substation Automatic Restoration

Automessages U.6.37, A.6.6 See also SEL Binary Protocols

Auto-Reclose R.2.1–R.2.40 application example A.1.136– A.1.150 external recloser R.2.10 logic diagrams R.2.32–R.2.40 one circuit breaker R.2.5, R.2.10 single- and three-pole reclose

> R.2.7 application example A.1.140-A.1.146 single-pole reclose R.2.5-R.2.6 three-pole reclose R.2.6-R.2.7 application example A.1.136-A.1.139 trip logic R.2.10 Relay Word bits R.2.31-R.2.32 settings R.2.29, R.9.25-R.9.27 states R.2.2-R.2.4 lockout R.2.3 reset R.2.2 single-pole auto-reclose R.2.3 start R.2.2 state diagram R.2.4 three-pole auto-reclose R.2.3

two circuit breakers R.2.11–R.2.26 single- and three-pole reclose R.2.14 single-pole reclose R.2.11– R.2.13 three-pole reclose R.2.13–R.2.14 trip logic R.2.25–R.2.26 voltage checks R.2.27–R.2.28

В

Battery Monitor See DC Battery System Monitor Best Choice Ground Directional Element U.1.2 See also Ground Directional Elements Boolean Equations R.3.5 See also SELOGIC Control Equations Breaker Bit A.6.11 BREAKER Command A.2.17, R.8.2-**R.8.4** BREAKER CONTROL front panel U.5.17–U.5.18 Breaker Failure Protection See Circuit Breaker Failure Breaker History Report See Circuit Breaker, history report Breaker Monitor See Circuit Breaker, monitor Breaker Report See Circuit Breaker, breaker report

С

Cable See Communications **CCVT U.1.2** See also CVT Transient Detection CEVENT Command A.3.24-A.3.28, R.8.5-R.8.9 See also Event Report CHISTORY Command A.3.33, R.8.9 See also Event History Circuit Breaker auxiliary contacts (52A) application example U.4.62-U 4 65 breaker report A.2.18 Compressed ASCII CBR A.2.20 contact wear curve A.2.5-A.2.7 choose midpoint A.2.6 creating A.2.6 I²t A.2.6 maximum interrupted current limit A.2.6 mechanical circuit breaker service life A.2.6 contact wear monitor A.2.3-A.2.9 loading maintenance data A.2.4

preload contact wear A.2.7 history report A.2.19 maintenance curve A.2.5 monitor A.2.2-A.2.21 application example A.1.5, A.1.23, A.1.56–A.1.57, A.1.89, A.2.4-A.2.17 electrical operating time A.2.11 application example A.2.12 enabling A.2.3-A.2.4 external trip initiation A.2.8 inactivity time A.2.16 application example A.2.16 kA interrupt monitor A.2.9 mechanical operating time A.2.10 application example A.2.10 motor running time A.2.17 application example A.2.17 pole discrepancy A.2.15 application example A.2.15 B1PDD time equation A.2.15 pole scatter A.2.13 application example A.2.13 Circuit Breaker Failure R.1.112-R.1.122 application example A.1.155-A.1.168 failure to interrupt fault current A.1.151-A.1.155 Scheme 1 R.1.112-R.1.113 application example A.1.155-A.1.160 Scheme 2 R.1.113-R.1.115 application example A.1.160-A.1.168 failure to interrupt load current R.1.116-R.1.117 flashover R.1.117-R.1.118 logic diagrams R.1.121–R.1.122 no current/residual current R.1.116 application example A.1.157-A.1.158 retrip single-pole R.1.114–R.1.115 three-pole R.1.113 subsidence current R.1.112 types R.1.112 Circuit Breaker Jumper U.2.19 See also Jumpers Circuit Breaker Monitor See Circuit Breaker, monitor Cleaning U.4.2 Close CLOSE n Command R.8.9-R.8.10 output U.4.57–U.4.59 Commands R.8.1 ACCESS R.8.2

ASCII R.8.1-R.8.57 BREAKER A.2.17, R.8.2-R.8.4 CBREAKER A.2.20-A.2.21 CEVENT A.3.24-A.3.28, R.8.5-R.8.9 CHISTORY A.3.32-A.3.33, R.8.9 CLOSE n R.8.9-R.8.10 COM R.8.10-R.8.12 CSER A.3.35-A.3.36, R.8.13-R.8.15 CSTATUS U.6.39, R.8.15 CSUMMARY A.3.30-A.3.31, R.8.15-R.8.17 EVENT A.3.12-A.3.14, R.8.18-R.8.21 FILE **R.8.22** HELP R.8.22 HISTORY A.3.32-A.3.33, R.8.23-**R.8.24** ID R.8.24 METER A.2.28, R.8.28-R.8.32 OPEN n R.8.32 PASSWORD R.8.33-R.8.34 PULSE U.6.6, R.8.36 QUIT R.8.36 SER U.4.50, A.3.34-A.3.35, R.8.36-R.8.38 SET R.8.38-R.8.42 STATUS U.6.37-U.6.38, R.8.45-**R.8.47** SUMMARY A.3.30, R.8.47-R.8.48 TARGET U.6.6, R.8.48-R.8.49 TEST DB U.6.6, R.8.49-R.8.50 TEST DNP U.6.7, R.8.50-R.8.51 TEST FM U.6.7, R.8.51-R.8.53 TIME Q U.4.68-U.4.69, R.8.53 TRIGGER U.4.39, A.3.5, R.8.54 VERSION R.8.54-R.8.55 Commissioning procedure U.4.72-U.4.73 Commissioning Testing U.6.2-U.6.3 See also Testing Communications ACSELERATOR software FTP U.3.4 serial U.3.4 Telnet U.3.5 terminal U.3.5 ASCII commands See ASCII Commands cable U.2.45, U.4.6, R.4.4 **DNP 3.0** See DNP 3.0 EIA-232 R.4.3 hardware flow control R.5.2 pin functions R.4.3 EIA-485 R.4.5, R.5.25

interfaces U.2.10, R.4.2 LMD See Distributed Port Switch MIRRORED BITS communications See MIRRORED BITS Communications protocol R.4.2 serial U.2.45-U.2.46, R.4.3-R.4.4 application example U.4.6-U.4.7 transparent mode R.8.13, R.8.35 UCA2 See UCA2 virtual serial ports R.5.4 Communications Card A.7.2 application example A.7.7-A.7.9 database R.4.6 Ethernet A.7.5, R.4.8 installation U.2.15 SEL-2701 A.6.4, A.7.5, R.4.8 settings R.4.8, R.9.41 Communications Processor A.6.2 application example A.6.6 Communications-Assisted Tripping R.1.88-R.1.102 See also DCB; DCUB; POTT DCB R.1.89-R.1.92 DCUB R.1.99-R.1.102 POTT R.1.93-R.1.98 Compressed ASCII R.5.6 See also ASCII Commands COMTRADE A.3.8-A.3.11, A.4.5 See also Event .CFG file A.3.10–A.3.11 .DAT file A.3.11 .HDR file A.3.9 Configuration serial number label U.4.2-U.4.3 Connection U.2.33-U.2.46 1k PPS U.2.44 ac/dc diagram U.2.47-U.2.49 alarm output U.2.42 battery monitors U.2.40 close output U.2.43 communications ports U.2.44 Connectorized U.2.41 control inputs U.2.41 control outputs U.2.41 grounding U.2.36 IRIG-B U.2.43 power U.2.38, U.4.4 screw terminal connectors U.2.35 secondary circuits U.2.40-U.2.41 serial port U.2.45 terminal blocks U.2.40 test connections U.6.9-U.6.13

trip output U.2.43 wire insulation U.2.33 wire size U.2.36, U.4.4 Connectorized U.2.3, U.2.40-U.2.41 SEL-WA0421 U.2.3, U.2.40 wiring harness U.2.3, U.2.40 Connectors U.2.2-U.2.3 Connectorized U.2.3 screw terminal connectors U.2.2 terminal blocks U.2.2 Contact Card See SEL Contact Card Contact Inputs See Control Inputs Contact Outputs See Control Outputs Contact Wear Curve See Circuit Breaker, contact wear curve Contact Wear Monitor See Circuit Breaker, contact wear monitor Contrast, LCD U.5.9 Control Inputs U.2.6, U.2.12, U.2.41 breaker auxiliary contacts (52A) application example ACSELERATOR software U.4.62-U.4.65 terminal U.4.59-U.4.61 common U.2.6 connecting U.2.41 debounce U.2.6, U.4.59 dropout factor, GINDF U.2.6 independent U.2.6 INT1, INT5, and INT6 U.2.12 main board U.2.9 pickup adjust U.2.6, U.4.59 range U.2.6 sample rate U.2.6 time COMTRADE report A.3.21 event report A.3.21 Control Outputs U.2.6-U.2.9, U.2.13, U.2.41-U.2.43 application example A.1.15, A.1.43, A.1.81, A.1.112 close outputs U.4.57-U.4.59 connecting U.2.41 fast hybrid (fast high-current interrupting) U.2.8-U.2.9 diagrams U.2.8 precharging U.2.8 ratings U.2.8 Form A U.2.7-U.2.9 Form C U.2.6, U.2.9

hybrid (high-current interrupting) U.2.7 diagram U.2.8 ratings U.2.7 INT1, INT5, and INT6 U.2.13 local bit control application example U.4.54-U 4 57 main board U.2.9 MOV U.2.6 pulsing application example front panel U.4.53-U.4.54 terminal U.4.52-U.4.53 sample rate U.2.6 standard U.2.7 diagram U.2.7 ratings U.2.7 trip outputs U.4.57-U.4.59 Counters See SELOGIC Control Equations Coupling Capacitor Voltage Transformer See CCVT Cross-Country Faults R.1.95 See also POTT CSER Command A.3.35-A.3.36, R.8.13-R.8.15 See also SER (Sequential Events Recorder) CST Command U.6.39 CSUMMARY Command A.3.30-A.3.31, R.8.15-R.8.17 See also Event Summary Current and Voltage Source Selection U.1.7, R.1.2-R.1.8 application example A.1.4-A.1.5, A.1.22–A.1.23, A.1.56, A.1.89 ESS := N (single circuit breaker) R.1.2 ESS := 1 (single circuit breaker) R.1.2-R.1.3 ESS := 2 (single circuit breaker) R.1.3-R.1.4 ESS := 3 (double circuit breaker) R.1.4-R.1.5 ESS := 4 (double circuit breaker) R.1.5-R.1.6 ESS := Y R.1.6 - R.1.8current polarizing source R.1.7-R.1.8 CVT Transient Detection A.1.6, A.1.25, A.1.58, A.1.90, R.1.36-R.1.37 logic diagram R.1.36

D Data

filtered data A.3.3 high-resolution raw data A.3.3 Database See ACSELERATOR Software: Communications Card DC Battery System Monitor U.1.3, A.2.22-A.2.27 ac ripple, definition A.2.22 ac ripple, measuring A.2.24 alarm A.2.26 application example A.2.23-A.2.26 dc ground detection A.2.25 equalize mode voltage level A.2.23 float high voltage level A.2.23 float low voltage level A.2.23 metering A.2.26 open-circuit voltage level A.2.23 reset metering A.2.27 thresholds, warn and fail A.2.23 trip/close voltage level A.2.23 Vdc1 A.2.22 Vdc2 A.2.22 DCB R.1.89-R.1.92 application example A.1.76-A.1.79 blocking signal extension R.1.90-R.1.91 coordination timers R.1.89-R.1.90 logic diagram R.1.92 starting elements R.1.90 stopping elements R.1.91 DCUB R.1.99-R.1.102 logic diagrams R.1.101-R.1.102 loss-of-guard, LOG R.1.99 permissive trip blocking, UBB R.1.99 POTT scheme similarities R.1.99 three-terminal lines R.1.99-R.1.100 timers R.1.100 Demand Metering A.2.35-A.2.40 See also Meter reset A.2.40 Dimensions U.2.32 rack units, defined U.2.2 Directional Comparison Blocking See DCB Directional Comparison Unblocking See DCUB Directional Control R.1.35 See also Ground Directional Elements; Phase and Negative-Sequence Directional Elements Directional Elements See Ground Directional Elements; Phase and Negative-Sequence **Directional Elements** Directional Overcurrent Elements

See Overcurrent Elements

Display See LCD, Front Panel Display Points U.5.6 creating, application examples U.5.7-U.5.8 deleting, application example U.4.23-U.4.25 Distance Elements See Mho Ground Distance Elements; Quadrilateral Ground Distance Elements Distributed Port Switch R.4.2, R.5.25 DNP 3.0 A.6.3. R.4.2 access method R.6.4 polling See DNP 3.0, access method DNP 3.0 A.7.3-A.7.4, R.6.1-R.6.12 access method R.6.6 application example R.6.29–R.6.32 conformance testing R.6.5 Device Profile document R.6.13 event data R.6.4 objects R.6.2, R.6.14-R.6.18 settings R.6.9 testing R.6.11 User's Group R.6.2

Е

Earthing See Grounding EIA-232 See Communications EIA-485 See Communications Energy Metering A.2.40-A.2.41 See also Meter accuracy A.2.41 reset A.2.41 ESS, setting See Current and Voltage Source Selection Ethernet U.1.4 See also Communications Card EVE Command A.3.12-A.3.14, R.8.18-**R.8.21** See also Event Event data capture initiate A.3.4-A.3.5 data capture time A.3.6 duration A.3.6-A.3.7 effective sample rate, SRATE A.3.6 ER equation A.3.4-A.3.5 application example A.3.4-A.3.5 EVE command A.3.12-A.3.14, R.8.18-R.8.21

initiate, TRI command U.4.39, A.3.5, R.8.54 application example ACSELERATOR software U.4.39–U.4.41 length, LER A.3.6 prefault, PRE A.3.6 storage capability A.3.7 TRIP initiate A.3.4 Event History A.3.31-A.3.33 See also Event ACSELERATOR software U.3.15, A 3 33 blank row A.3.32 CHISTORY command A.3.33, **R.8.9** contents A.3.31 event types A.3.32 HIS command A.3.32, R.8.23-**R.8.24** retrieving history U.3.15, U.4.41-U.4.42 application example ACSELERATOR software U.4.41-U.4.42 terminal U.4.42 terminal A.3.32-A.3.33 Event Report U.1.3, A.3.12-A.3.28 See also Event *, largest current A.3.16, A.3.19 >, trigger row A.3.16, A.3.19 ACSELERATOR software A.3.14 analog section A.3.14-A.3.19 Compressed ASCII CEVENT A.3.24-A.3.28 application example A.3.24-A.3.28 currents and voltages A.3.15 digital section A.3.19-A.3.21 label header A.3.20 reading, application example A.3.21 selecting elements A.3.21 header A.3.14 phasor calculation application example A.3.16-A.3.19 retrieving event data U.3.15 application example ACSELERATOR software U.4.44-U.4.45 terminal U.4.46 settings section A.3.22 summary section A.3.22 terminal A.3.14, A.3.28 trigger U.4.39

Event Summary A.3.28–A.3.31 See also Event ACSELERATOR software A.3.30 contents A.3.29 CSUMMARY command A.3.30– A.3.31, R.8.15–R.8.17 event types A.3.29 SUM command A.3.30, R.8.47– R.8.48 terminal A.3.30 Expression Builder U.3.13, A.4.3

See also ACSELERATOR Software

F

Factory Assistance U.6.43 Fast Meter See SEL Binary Protocols Fast Operate See SEL Binary Protocols Fast SER See SEL Binary Protocols FAULT metering suspend A.2.35 Fault Locator U.1.3, R.1.11-R.1.12 Fault Type Identification Selection R.1.20 Fiber Optic R.4.4 multimode R.4.4 single mode R.4.5 FIDS See Fault Type Identification Selection File See FTP; FILE Command FILE Command R.8.22 application example U.4.43, U.4.50 Frequency Estimation R.1.10 Front Panel access level U.5.10 automatic messages U.5.28-U.5.29 labels U.5.30, U.5.34 layout U.2.4, U.5.2 LCD U.5.2-U.5.3 contrast U.5.9 pushbuttons U.5.2-U.5.4, U.5.34-U.5.36 ROTATING DISPLAY U.5.5-U.5.6 screen scrolling U.5.4-U.5.6 serial port U.5.2 set relay, application example U.5.21-U.5.22 setting screen types U.5.23 targets U.5.2 template U.2.4

Front-Panel Menus U.5.9–U.5.27 **BREAKER MONITOR U.5.15** DISPLAY TEST U.5.27 EDIT ACTIVE GROUP U.5.23 EVENTS U.5.14-U.5.15 LOCAL CONTROL U.5.17-U.5.21 **BREAKER CONTROL U.5.17 OUTPUT TESTING U.5.20** MAIN MENU U.5.11 METER U.5.11-U.5.14 **RELAY ELEMENTS U.5.15-**U 5 16 **RELAY STATUS U.5.24 RESET ACCESS LEVEL U.5.27** SET/SHOW U.5.21-U.5.24 DATE/TIME U.5.24 VIEW CONFIGURATION U.5.26 FTP A.6.3, A.7.5

Fuse U.2.38-U.2.40 replacement U.2.39-U.2.40 size U.2.38

G

GOMSFE See UCA2 GOOSE See UCA2 GPS Receiver U.2.44, A.4.2 See also Time Synchronization Ground Directional Elements R.1.21-R.1.32 32I, zero-sequence current polarized R.1.21 32QG, negative-sequence polarized R.1.21 32V, zero-sequence voltage polarized R.1.21 application example A.1.12, A.1.36-A.1.37, A.1.70-A.1.76, A.1.106-A.1.108 automatic settings calculation R 1 22 Best Choice Ground Directional logic R.1.27 logic flow chart R.1.27 calculations A.1.107, R.1.30-R.1.32 logic diagrams R.1.25, R.1.28-R.1.29 ORDER R.1.24 Ground Distance Elements See Mho Ground Distance

Elements; Quadrilateral Ground Distance Elements

Grounding U.2.36

н

Help ACSELERATOR software U.4.5

terminal U.4.5

High-Speed Elements mho ground distance R.1.46 mho phase distance R.1.55

HIS Command A.3.32, R.8.23-R.8.24 See also Event History

History Report circuit breaker A.2.3

See also Circuit Breaker, history report

L I/O

See Input/Output I²t application example A.2.6-A.2.7 fault current arcing time A.2.3

ICCP **R.7.2** See also UCA2

ID Command R.8.24 codes R.8.24 sample response R.8.24

Input Processing A.3.2-A.3.3 Input/Output communications card U.2.15 See also Communications Card INT1 U.2.12-U.2.15 INT5 U.2.12-U.2.15 INT6 U.2.12-U.2.15 interface board inputs U.2.12 interface board installation U.2.13-U.2.15 interface board jumpers U.2.21-U.2.25 See also Jumpers interface board outputs U.2.13 jumpers U.2.21 See also Jumpers U.2.21 main board U.2.9

Installation U.2.31-U.2.46 dimensions U.2.32 panel mounting U.2.32 physical location U.2.31 rack mounting U.2.31

Instantaneous Metering A.2.29-A.2.33 See also Meter

Instantaneous Overcurrent Elements See Overcurrent Elements

Interface Boards INT1, INT5, and INT6 U.2.12-U.2.15

inputs U.2.12 installation U.2.13-U.2.15 outputs U.2.13-U.2.15

Inverse Time-Overcurrent Elements See Overcurrent Elements

IRIG-B U.2.10, U.2.43, A.4.2 See also Time Synchronization

J

Jumpers U.2.17-U.2.25 interface boards U.2.21-U.2.25 main board U.2.17-U.2.21 circuit breaker jumper U.2.17, U 2 19 output control jumper U.2.17-U.2.19 password jumper U.2.17, U.2.19 serial port U.2.19-U.2.21

L

Labels See Front Panel, labels Latch Bits R.3.14 LCD. Front Panel U.5.3 autoscrolling mode U.5.6 contrast U.5.9 manual-scrolling mode U.5.6 LEDs front panel U.5.30-U.5.36 labels U.5.30, U.5.34 targets U.5.30-U.5.33 LMD See Distributed Port Switch Load Encroachment R.1.39-R.1.40 application example A.1.66-A.1.68 Local Bits U.5.18-U.5.20 See also Local Control application example U.5.20 delete a local bit U.5.20 enter a local bit U.5.19 names U.5.17, U.5.19 states U.5.18 Local Control U.5.17-U.5.21 See also Breaker Control application examples U.4.52-U.4.57 graphic display U.5.18 local bits U.5.18-U.5.20 output testing U.5.20-U.5.21 LOP See Loss-of-Potential Loss-of-Potential U.1.3, R.1.16-R.1.19 application example A.1.7-A.1.8, A.1.26, A.1.59, A.1.91–A.1.92 logic diagram R.1.19

logic flow chart R.1.17

Low-Level Test Interface U.6.7-U.6.8 Lugs, Crimp U.2.35 Μ Maintenance Curve See Circuit Breaker, maintenance curve Maintenance Data See also Circuit Breaker, contact wear monitor load circuit breaker A.2.4 Maintenance Testing U.6.3-U.6.4 See also Testing Manual Trip See Trip Logic Maximum/Minimum Metering A.2.33-A.2.35 See also Meter accuracy A.2.34 reset A.2.34 Menus See Front-Panel Menus; ACSELERATOR Software MET Command metering analog quantities A.2.28 See also Analog Quantities metering external quantities A.2.28 metering internal variables A.2.28 metering synchronism check A.2.28 See also Synchronism Check Meter U.1.3, A.2.28 accuracy A.2.32, A.2.34, A.2.41 current A.2.29 dc battery monitor A.2.26 demand A.2.35-A.2.40 rolling A.2.36-A.2.38 thermal A.2.36 energy A.2.40-A.2.41 error coefficients A.2.32-A.2.33 frequency A.2.29 fundamental A.2.29 instantaneous A.2.29-A.2.33 maximum/minimum A.2.33-A.2.35 power A.2.30 rms A.2.29 view metering U.4.31-U.4.37 application example ACSELERATOR software U.4.34-U.4.37 front panel U.4.37 terminal U.4.31-U.4.34 voltage A.2.29 METER Command R.8.28-R.8.32

Mho Ground Distance Elements R.1.46-R.1.50 application example A.1.8-A.1.9, A.1.27-A.1.28, A.1.64 high-speed elements R.1.46 logic diagrams R.1.48-R.1.50 zero-sequence compensation R.1.46 Mho Phase Distance Elements R.1.55-R.1.58 application example A.1.8, A.1.27, A.1.60–A.1.63, A.1.92 high-speed elements R.1.55 logic diagrams R.1.57-R.1.58 MIRRORED BITS Communications U.1.4, R.4.2, R.5.18-R.5.24 Pulsar modem R.5.21 virtual terminal R.8.35 MMS R.7.2 MOD (Motor Operated Disconnect) A.5.2, A.5.4 Modbus Plus A.6.3 Modbus RTU A.6.3 Monitor, Circuit Breaker See Circuit Breaker, monitor MOV control outputs U.2.6 Multidrop Network A.6.4 0 OOSB See Out-of-Step OOST See Out-of-Step OPEN n Command R.8.32 Open Phase Detection Logic R.1.13 Operator Control LEDs U.5.34-U.5.36 See also LEDs factory defaults U.5.35-U.5.36 Operator Control Pushbuttons U.5.34-U.5.36 See also Pushbuttons; LEDs factory defaults U.5.34 Oscillography U.1.3, U.4.39-U.4.45, A.3.8-A.3.11 See also Event COMTRADE A.3.8 event report A.3.8, A.3.11 retrieving high-resolution COMTRADE U.3.15-U.3.16, U.4.43 application example ACSELERATOR software U.4.44-U.4.45 terminal U.4.43-U.4.44

OSI Protocol Stack R.7.2 Out-of-Step R.1.41-R.1.45 blinders A.1.120, A.1.125, A.1.130 blocking, OOSB U.1.3, R.1.41 application example A.1.118-A.1.128 logic diagrams R.1.44-R.1.45 setting rules A.1.123, A.1.131, R.1.42 single pole R.1.42 three-phase fault R.1.42 trip-on-way-in A.1.131 trip-on-way-out A.1.131 tripping, OOST U.1.3, R.1.41 application example A.1.128-A.1.135 Output SELOGIC Control Equations R.3.4 Output Testing front panel U.5.20-U.5.21 Overcurrent Elements R.1.62-R.1.84 application example A.1.11-A.1.12, A.1.35-A.1.36, A.1.68-A.1.70, A.1.102-A.1.106 definite-time negative-sequence R.1.63-**R.1.64** phase R.1.62, R.1.64 residual ground R.1.63, R.1.65 direction R.1.62 instantaneous negative-sequence A.1.102-A.1.103, R.1.63–R.1.64 phase A.1.11, A.1.35, A.1.68, A.1.102, **R.1.62**, R.1.64 residual ground A.1.68-A.1.69. R.1.63, R.1.65 inverse time A.1.11-A.1.12, A.1.35-A.1.36, R.1.69-R.1.84 curves R.1.74-R.1.83 formulas R.1.71-R.1.73 selectable operating quantity A.1.35-A.1.36, A.1.69-A.1.70, A.1.105–A.1.106, R.1.69-R.1.84 logic diagrams R.1.66-R.1.68, R.1.84 selectable operating quantity A.1.11-A.1.12, A.1.35-A.1.36, A.1.69-A.1.70, A.1.105-A.1.106, R.1.69-R.1.84 current selections R.1.69 time-current characteristics R.1.71-R.1.83 torque control R.1.62

D

Panel Mount U.2.32 dimensions U.2.32

Metering

See Meter

Password U.1.4, U.4.8-U.4.11 defaults U.4.8-U.4.9 changing, application example U.4.10-U.4.11 front-panel screen U.5.10 jumper U.2.19 See also Jumpers unauthorized U.4.10 PC Software See ACSELERATOR Software Permissive Overreaching Transfer Trip See POTT Phase and Negative-Sequence Directional Elements R.1.33-R.1.34 32P, phase R.1.33 32Q, negative-sequence voltage polarized R.1.21, R.1.33 logic diagrams R.1.33 ZLOAD effect R.1.33 Phase Distance Elements See Mho Phase Distance Elements Phase Instantaneous Definite-Time **Overcurrent Elements** See Overcurrent Elements Phasors calculate from event report application example A.3.16-3 19 hand calculation method A.3.16-A.3.19 polar calculator method A.3.19 Plug-In Boards U.2.12-U.2.16 See also Input/Output communications card U.2.15 interface boards U.2.12-U.2.15 Pole-Open Logic R.1.14 application example A.1.13, A.1.37, A.1.76, A.1.108 POTT R.1.93-R.1.98 application example A.1.37-A.1.39, A.1.109-A.1.110 cross-country faults R.1.95 application example A.1.43-A.1.46 current reversal guard A.1.38, A.1.109, R.1.93 echo A.1.38, A.1.109, R.1.93-R.1.94 logic diagrams R.1.96-R.1.98 three-terminal lines R.1.95 weak infeed A.1.39, A.1.110, R.1.94-R.1.95 Power Flow analysis A.4.7-A.4.9 power flow convention A.2.30 Power Supply connections U.2.38, U.4.4

types U.4.4 voltage ranges U.2.38, U.4.4 PPS U.2.10, A.4.2 See also Time Synchronization 1k PPS U.2.10, U.4.67, A.3.1 Protection and Automation Separation R.3.3 See also SELOGIC Control Equations Pulsar Modem See MIRRORED BITS Communications PULSE Command U.6.6, R.8.36 application example front panel U.4.53-U.4.54 terminal U.4.52-U.4.53 include TESTPUL in ER A.3.5 no event data A.3.4 Pushbuttons factory defaults U.5.34 front panel U.5.2 labels U.5.34 LEDs See Operator Control LEDs navigation U.5.3-U.5.4 operator control U.5.34-U.5.36 programming U.5.34-U.5.35 Q Quadrilateral Ground Distance Elements R.1.51-R.1.54

application example A.1.28–A.1.32, A.1.93–A.1.97 logic diagrams R.1.53–R.1.54 polarization R.1.51 application example A.1.30– A.1.32, A.1.95–A.1.96 Z1ANG R.1.51 zero-sequence compensation R.1.51

QUIT Command R.8.36

R

Rack Mount U.2.31–U.2.32 dimensions U.2.32 Rear Panel alert symbols U.2.35 layout U.2.5, U.2.33–U.2.35 template U.2.5 Recloser See Auto-Reclose RELAY TRIP EVENT front panel U.5.28 Relay Word Bits in SELOGIC control equations R.3.11 list sorted alphabetically R.A.2

listed by row, sorted by function R.A.19-R.A.72 Remote Bit A.6.11, R.3.15, R.7.5, R.8.12 See also UCA2 Remote Terminal Unit (RTU) R.6.2 Reset battery monitor metering A.2.27 demand metering A.2.40 energy metering A.2.41 maximum/minimum metering A.2.34 targets U.5.31 Rolling Demand Metering A.2.36-A.2.38 See also Demand Metering

S

Schweitzer Engineering Laboratories contact information U.6.43 Screw Terminal Connectors U.2.35-U.2.37 keying U.2.36 receptacle keying U.2.37 removal and insertion U.2.35 tightening torque U.2.35 Scrolling See Front Panel, screen scrolling Secondary Connections U.2.5-U.2.6, U.2.40-U.2.41 levels U.2.5 SEL Binary Protocols R.4.2 Fast Meter A.6.6, R.5.9, R.8.2, R.8.17, R.8.51-R.8.53 Fast Operate A.6.11, R.5.9 Fast SER R.5.9, R.8.45 SEL Contact Card U.4.2 SEL-2020 See Communications Processor SEL-2030 See Communications Processor SEL-2701 See Communications Card SEL-421 Relav features U.1.1-U.1.4 models U.1.5 options U.1.5 SEL-421-1 Relay features U.1.1-U.1.4 models U.1.5 options U.1.5 SEL-5030 ACSELERATOR Software See ACSELERATOR Software

Selectable Operating Quantity Time **Overcurrent Elements** See Overcurrent Elements, selectable operating quantity Self-Tests U.4.12, U.6.37-U.6.39 See also Testing; Troubleshooting SELOGIC Control Equations U.1.3 analog quantities R.3.11 automation R.3.8, R.9.30 Boolean equations R.3.5-R.3.6, R.3.24-R.3.28 capacity R.3.10 comments **R.3.7**, R.3.34 conditioning timers R.3.16 convert R.3.36 counters R.3.21 fixed result R.3.5 free-form R.3.5 LVALUE R.3.6 math equations R.3.5-R.3.6, R.3.28-R.3.33 math error R.3.29 math variables **R.3.13** output R.3.8 protection R.3.8, R.9.29 Relay Word bits R.3.11 sequencing timers R.3.19 substation automatic restoration A.5.9-A.5.11 time synchronization A.4.3-A.4.4 variables R.3.12 Sequential Events Recorder See SER (Sequential Events Recorder) SER (Sequential Events Recorder) U.1.3, U.4.46, A.3.34-A.3.37 ACSELERATOR software A.3.34 automatic deletion A.3.36-A.3.37 chattering elements A.3.36 contents A.3.34 CSER command A.3.35-A.3.36, R.8.13-R.8.15 file download U.4.50 SER command U.4.50, A.3.34-A.3.35, R.8.36-R.8.38 set points and aliases U.4.47-U.4.50, A.3.36 application example ACSELERATOR software U.4.47-U.4.48 terminal U.4.49-U.4.50 terminal A.3.34 view SER report application example ACSELERATOR software U.4.48-U.4.49 terminal U.4.50

Serial Number Label U.4.2-U.4.3 Serial Port A.7.2, R.4.3 See also Communications cable See Communications EIA-232 See Communications EIA-485 See Communications front panel U.5.2 jumper U.2.19-U.2.21 See also Jumpers Series-Compensated Line R.1.38 ground directional element R.1.23 Setting U.4.15-U.4.30, R.8.38-R.8.42 ACSELERATOR software U.3.9-U.3.12 application example U.4.25-U.4.27 application example A.1.4-A.1.19, A.1.22-A.1.52, A.1.56-A.1.85, A.1.88-A.1.117 ASCII commands U.4.17 class U.4.15, U.4.17 date U.5.24, R.8.17 from front panel U.4.27-U.4.30, U.5.21-U.5.24 application example U.4.27-U 4 30 instance U.4.15, U.4.17 reduction U.1.4 **SER U 4 47** See also SER (Sequential Events Recorder) structure U.4.16 terminal U.4.18-U.4.25 application example U.4.19-U.4.20, U.4.22–U.4.25 TERSE U.4.20 text-edit mode U.4.21-U.4.25 time U.5.24, R.8.53 SIR A.1.6, A.1.25, A.1.58, R.1.37 SOTF See Switch-Onto-Fault Source to Line Impedance Ratio See SIR Specifications U.1.11 Star Network Topology A.6.2, A.6.4 State Estimation A.4.10 Station DC Battery System Monitor See DC Battery System Monitor Status U.6.37 check relay status U.4.12-U.4.14 application example

SER Command R.8.36-R.8.38

ACSELERATOR software U.4.12-U.4.13 front panel U.4.14 terminal U.4.12 CST command U.6.39, R.8.15 STATUS command R.8.45-R.8.47 Status Failure U.6.37-U.6.38 front panel U.5.29 Status Warning U.6.37-U.6.38 front panel U.5.28 Subsidence Current R.1.112 See also Circuit Breaker Failure Substation Automatic Restoration A.5.1-A.5.16 philosophy A.5.3-A.5.5 SELOGIC control equations A.5.9-A.5.11 settings A.5.6-A.5.12 timing diagram A.5.3 Substation Automation R.3.3 See also SELOGIC Control Equations SUM Command A.3.30, R.8.47-R.8.48 See also Event Summary Switch-Onto-Fault U.1.3, R.1.85-R.1.87 application example A.1.9-A.1.11, A.1.33-A.1.35, A.1.65-A.1.66, A.1.101-A.1.102 close signal monitor, CLSMON A.1.11, A.1.66, A.1.102, R.1.85 duration A.1.10, A.1.35, A.1.66, A.1.101, R.1.85 end A.1.10, A.1.34, A.1.65, A.1.101, R.1.85 initiation A.1.10, A.1.34, A.1.66, A.1.101, R.1.85 logic diagram R.1.87 single pole A.1.34, R.1.86 trip A.1.9-A.1.10, A.1.34, A.1.65, A.1.101 validation R.1.85 Synchronism Check R.2.41-R.2.57 alternate source 2 R.2.56-R.2.57 angle checks R.2.50 application example A.1.146-A.1.150 block synchronism check R.2.49 circuit breaker closing R.2.45 enable logic R.2.49 healthy voltage window R.2.48 input angle compensation R.2.46-R 2 49 input voltage magnitude compensation R.2.46-R.2.48 no slip R.2.50-R.2.51 PT connections R.2.46 Relay Word bits R.2.44-R.2.45

settings R.2.43-R.2.44 single-phase voltage inputs R.2.42-R 2 43 slip, no compensate R.2.52-R.2.53 slip, with compensate R.2.54-R 2 56 Synchrophasor A.4.1–A.4.10 See also Time-Synchronized

Measurements MET PM Command R.8.30 Time-Synchronized Metering A.2.42

System Integration A.6.2

т

TARGET Command U.6.6, R.8.48-**R.8.49** Targets U.5.30-U.5.33 front panel U.5.2 instantaneous/time O/C U.5.32 operational U.5.31 phases/ground U.5.32 recloser status U.5.33 regions U.5.30 reset U.5.31 trip type U.5.31 zone activated U.5.32 TASE.2 R.7.2 See also UCA2 TCP/IP R.7.2 Technical Service Center U.6.43 Telnet A.7.5 TEST DB Command U.6.6, R.8.49-R.8.50 TEST DNP Command U.6.7, R.8.50-R.8.51 TEST FM Command U.6.7, R.8.51-R.8.53 Testing U.6.2-U.6.36 acceptance testing U.6.2 ASCII commands U.6.6-U.6.7 commissioning testing U.6.2-U.6.3 directional elements U.6.27-U.6.33 application example U.6.29-U 6 33 distance elements U.6.33-U.6.36 application example U.6.34-U.6.36 element tests U.6.24-U.6.36 features U.6.5 low-level test interface U.6.7-U.6.8 maintenance testing U.6.3-U.6.4 methods U.6.14-U.6.23 application example control outputs U.6.18-U.6.20 front panel U.6.17

SER U.6.20-U.6.23 targets, LCD U.6.15-U.6.17 targets, LED U.6.17-U.6.18 targets, terminal U.6.14-U.6.15 overcurrent elements U.6.24-U.6.27 application example U.6.25-U 6 27 self-tests U.6.37-U.6.39 test connections U.6.9-U.6.13 Thermal Demand Metering A.2.36 See also Demand Metering Time U.4.66-U.4.71 See also Time Synchronization high-accuracy U.4.66-U.4.71 application example U.4.67-U.4.71 Time Inputs U.2.10, U.2.43 See also IRIG-B; PPS 1k PPS U.2.10 connecting U.4.67 IRIG-B U.2.10 Time Out front panel U.5.3 TIME Q Command U.4.68-U.4.69, R.8.53 Time Synchronization U.1.3 See also Time U DNP 3.0 R.6.8 IRIG-B U.4.66, A.6.2, A.6.5 **PPS U.4.66** Time-Overcurrent Curves R.1.74-R.1.83 See also Overcurrent Elements Time-Overcurrent Elements See Overcurrent Elements Timers See SELOGIC Control Equations Time-Synchronized Measurements A.4.1-A.4.10 See also Time Synchronization GPS receiver A.4.2 power flow analysis A.4.7-A.4.9 state estimation A.4.10 time trigger A.4.2-A.4.5 application example A.4.2-A.4.5 Trigger data capture A.3.4 event A.3.4 TRIGGER Command R.8.54 V Trip output U.2.43, U.4.57 Relay Word bit, TRIP A.3.4 Trip Bus capture external/internal trips A.2.8

Trip Logic R.1.103-R.1.111 application example A.1.13-A.1.15, A.1.40-A.1.42, A.1.79-A.1.81, A.1.110-A.1.112 logic diagrams R.1.108–R.1.111 manual trip R.1.106 single-pole tripping A.1.42, R.1.103 three-pole tripping A.1.15, A.1.81, A.1.112, R.1.103 trip equations A.1.13-A.1.14, A.1.40, A.1.79–A.1.80, A.1.110, **R.1.104** DTA, DTB, DTC R.1.104 TR R.1.104 TRCOMM R.1.104 TRSOTF R.1.104 trip Relay Word bits R.1.105 trip timers A.1.14-A.1.15, A.1.42, A.1.80, A.1.112, R.1.105 TDUR1D and TDUR3D R.1.105 TOPD R.1.105 trip unlatch options A.1.14, A.1.41, A.1.80, A.1.111, R.1.104-R.1.105 TULO A.1.14, A.1.41, A.1.80, A.1.111, R.1.105 ULTR A.1.14, A.1.41, A.1.80, A.1.111, R.1.105 Troubleshooting U.6.40–U.6.42 UCA2 A.6.4, A.7.6, R.4.2, R.7.2-R.7.6 brick R.7.3 browser R.7.3 domain R.7.5, R.C.3

GOMSFE A.6.3, R.7.2, R.7.5 DI R.7.5-R.7.6, R.C.4, R.C.9 FAULT R.7.5, R.C.10 GCTL R.7.5-R.7.6, R.C.5, R.C.10 GLOBE R.7.5-R.7.6, R.C.5, **R.C.11** MMTR R.7.5, R.C.15 MMXU R.7.3, R.7.5, R.C.15 XCBR R.7.5, R.C.15 GOOSE A.6.3, R.7.4, R.7.6 application example R.7.7 DNA **R.7.4** User ST R.7.4, R.7.6 model R.7.3 Utility Communications Architecture

See UCA2

VERSION Command R.8.54-R.8.55 release numbers R.8.54 sample response R.8.55

Virtual File Interface R.5.14–R.5.17

W

Wire grounding size U.2.36 insulation U.2.33 power connection size U.2.38, U.4.4

Ζ

Zero-Sequence Current Compensation **R.1.46**, R.1.51 application example A.1.9, A.1.32– A.1.33, A.1.64–A.1.65, A.1.97– A.1.99

Zone Time Delay **R.1.59–R.1.61** common timing R.1.59 application example A.1.9, A.1.33, A.1.65, A.1.100 independent timing R.1.59 logic diagram R.1.61

Zone/Level Direction A.1.106 application example A.1.36, A.1.70

SEL-421 Relay Command Summary

SEL-421 Relay Commands^{a, b} (Sheet 1 of 2)

Command	Description	
2ACCESS	Go to Access Level 2 (complete relay monitoring and control)	
AACCESS	Go to Access Level A (automation control)	
ACCESS	Go to Access Level 1 (monitor relay)	
BACCESS	Go to Access Level B (monitor relay and control circuit breakers)	
BNAME	ASCII names of all relay status bits (Fast Meter)	
BREAKER n	Display the circuit breaker report and breaker history; preload and reset breaker monitor data ($n = 1$ is BK1; $n = 2$ is BK2)	
CASCII	Generate the Compressed ASCII response configuration message	
CBREAKER	BREAKER command for the Compressed ASCII response	
CEVENT	EVENT command for the Compressed ASCII response	
CHISTORY	HISTORY command for the Compressed ASCII response	
CLOSE n	Close the circuit breaker ($n = 1$ is BK1; $n = 2$ is BK2)	
COMM c	Display relay-to-relay MIRRORED BITS communications data ($c = A$ is channel A; $c = B$ is channel B; $c = M$ is either enabled single channel)	
CONTROL nn	Set, clear, or pulse an internal remote bit (<i>nn</i> is the remote bit number from 01–32)	
COPY m n	Copy settings between instances in the same class (m and n are instance numbers; for example: $m = 1$ is Group 1; $n = 2$ is Group 2)	
CSER	SER command for the Compressed ASCII response	
CSTATUS	STATUS command for the Compressed ASCII response	
CSUMMARY	SUMMARY command for the Compressed ASCII response	
DATE	Display and set the date	
DNAME X	ASCII names of all relay digital I/O (Fast Meter)	
DNP	Access or modify DNP settings (similar to SHOW D and SET D)	
EVENT	Display and acknowledge event reports	
FILE	Transfer data between the relay and external software	
GROUP	Display the active group number or select the active group	
HELP	Display available commands or command help at each access level	
HISTORY	View event summaries/histories; clear event data	
ID	Display the firmware id, user id, device code, part number, and configuration information	
IRIG	Update the internal clock/calendar from the IRIG-B input	
LOOPBACK	Connect MIRRORED BITS data from transmit to receive on the same port	
MAP 1	Analyze the communications card database	
METER	Display metering data and internal relay operating variables	
OACCESS	Go to Access Level O (output control)	
OPEN n	Open the circuit breaker ($n = 1$ is BK1; $n = 2$ is BK2)	
PACCESS	Go to Access Level P (protection control)	

SEL-421 Relay Commands^{a, b} (Sheet 2 of 2)

Command	Description	
PASSWORD	Display or change relay passwords	
PORT p	Connect to a remote relay via MIRRORED BITS virtual terminal (p is port number 1–3, and F)	
PULSE OUTnnn	Pulse a relay control output (OUT <i>nnn</i> is a control output number)	
QUIT	Reduce access level to Access Level 0 (exit relay control)	
SER	View Sequential Events Recorder reports	
SETC	Enter relay settings	
SHOW ^c	Display relay settings	
SNS	Display Sequential Events Recorder settings name strings (Fast SER)	
STATUS	Report or clear relay status and SELOGIC control equation errors	
SUMMARY	View summary event reports	
TARGET	Display relay elements for a row in the Relay Word table	
TEST DB	Display or place values in the communications card database	
TEST DNP	Display or place values in the DNP object map	
TEST FM	Display or place values in metering database (Fast Meter)	
TIME	Display and set the internal clock	
TRIGGER	Initiate a data capture and record an event report	
VERSION	Display the relay hardware and software configurations	
VIEW 1	View data from the communications card database	

^a See Section 8: ASCII Command Reference on page R8.1 in Reference Manual

^b For help on a specific command, type **HELP [command]<Enter>** at an ASCII terminal communicating with the relay.

^c See the table below for SET/SHOW options.

SET/SHOW Command Options

Option	Setting Type	Description
[S] <i>n</i>	Group Settings 1–6	Particular application settings
A n	Automation Logic Block 1–10	Automation SELOGIC control equations
D	DNP	Direct Network Protocol remapping
F	Front Panel	Front-panel HMI settings
G	Global 1–6	Relay-wide settings
L n	Protection Logic Group 1-6	Protection SELOGIC control equations
Μ	Breaker Monitor	Circuit breaker monitor settings
0	Outputs	Output SELOGIC control equations
P n	Port 1–3, F, 5	Communications port settings
R	Report	Event report and SER settings