

SEL-321-3

**PHASE AND GROUND DISTANCE RELAY
DIRECTIONAL OVERCURRENT RELAY
FAULT LOCATOR**

INSTRUCTION MANUAL

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This product is covered by U.S. Patent Numbers: 4,996,624; 5,041,737; 5,208,545; 5,262,679; 5,317,472; 5,325,061; 5,349,490; 5,365,396; 5,367,426; 5,479,315; 5,515,227; 5,790,418; 5,793,750; 5,883,578; and U.S. Patent(s) Pending, and Foreign Patent(s) Issued and Pending.

MANUAL CHANGE INFORMATION

The date code at the bottom of each page of this manual reflects the creation or revision date. Date codes are changed only on pages that have been revised and any following pages affected by the revisions (i.e., pagination). If significant revisions are made to a section, the date code on all pages of the section will be changed to reflect the revision date.

Each time revisions are made, both the main table of contents and the affected individual section table of contents are regenerated and the date code is changed to reflect the revision date.

Changes in this manual to date are summarized below (most recent revisions listed at top).

Revision Date	Summary of Revisions
The <i>Manual Change Information</i> section has been created to begin a record of revisions to this manual. All changes will be recorded in this Summary of Revisions table.	
20010417	Added note in <i>Selecting Elements to Trip</i> in <i>Section 2</i> identifying elements that should not be used in any trip logic equations. Added note to the <i>Target Information</i> sheet identifying elements that should not be used in any trip logic equations.
20010226	Updated Power Supply information in <i>Section 2</i> . Updated <i>Appendix A</i> to include all versions of the SEL-321-3 firmware as well as SEL-321-1 firmware information.
20010213	New manual release.

SEL-321-3 INSTRUCTION MANUAL

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SECTION 1: INTRODUCTION

GETTING STARTED

This instruction manual provides descriptive information and instructions for the SEL-321-3 Relay. The instructions in this manual are designed for use by personnel with a background in power engineering and experience in protective relay applications. A detailed technical description of the relay and examples of its application are included. While reasonable examples and illustrations of relay uses are given, sound judgment must be exercised at all times in its application.

The manual is divided into sections with the following information:

<i>Section 1: Introduction</i>	General information
<i>Section 2: Specifications</i>	Detailed technical description of each feature
<i>Section 3: Communications</i>	User interface and protocol
<i>Section 4: Event Reporting</i>	Describes content and use
<i>Section 5: Applications</i>	How to apply and set
<i>Section 6: Installation</i>	Wiring and configuration
<i>Section 7: Maintenance and Testing</i>	Initial checkout and tests
<i>Section 8: Appendices</i>	

OVERVIEW

The following pages present a brief overview of the functions and characteristics of the relay.

From Front Panel:

- Set relay
- Read meter and other data
- Switch setting groups
- Password protection

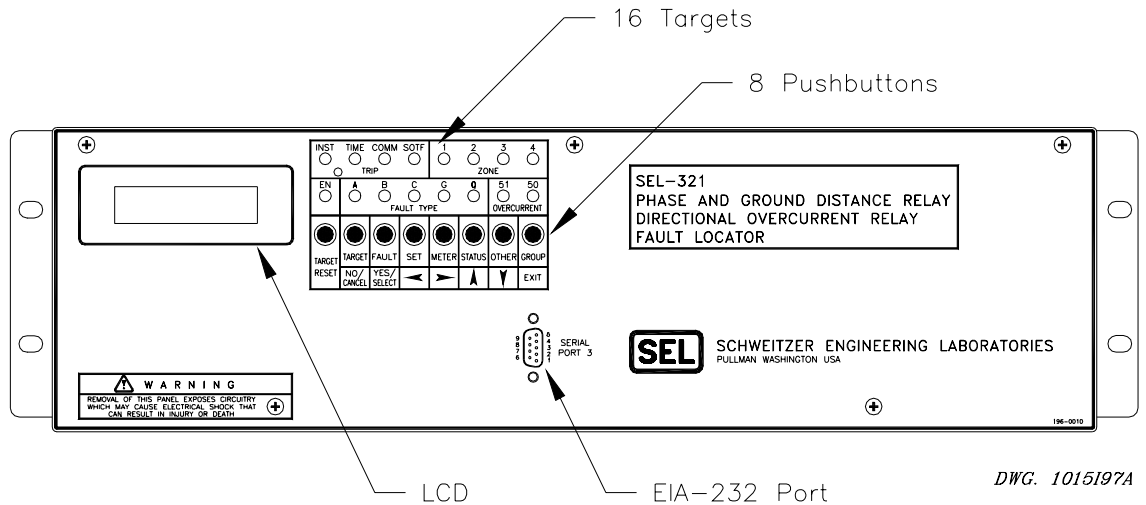


Figure 1.1: SEL-321 Front Panel (One I/O Board Version)

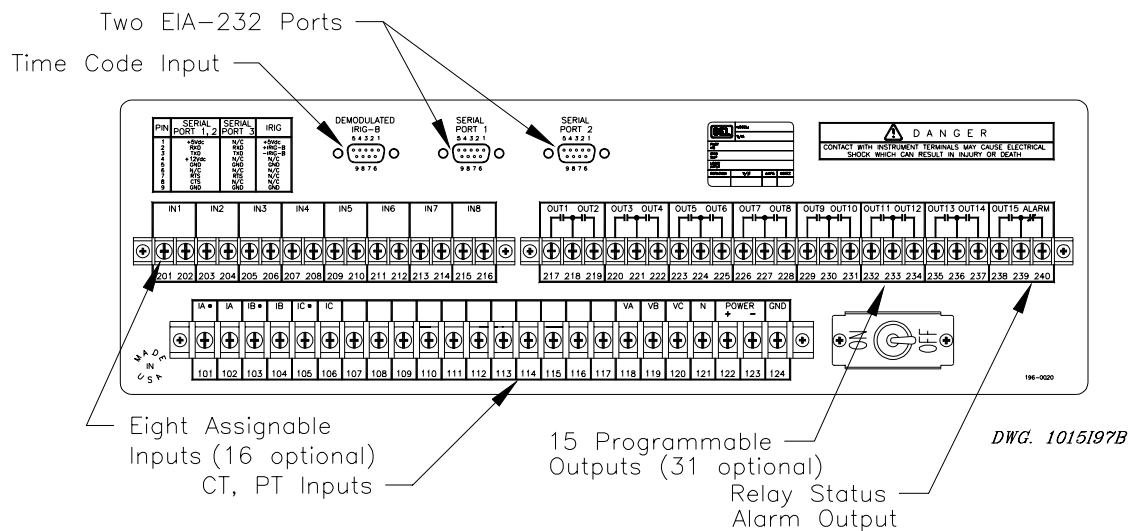
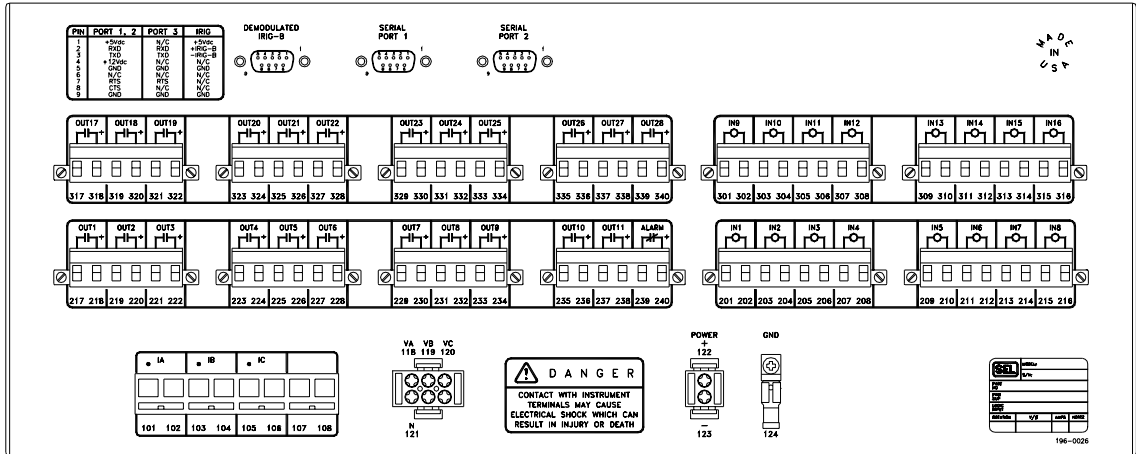


Figure 1.2: SEL-321 Rear Panel (One I/O Board Version, showing conventional terminal blocks – other options are available)



DWG. 11146

Figure 1.3: SEL-321 Rear Panel (Two I/O Board Version, showing plug-in connectors option - other options are available)

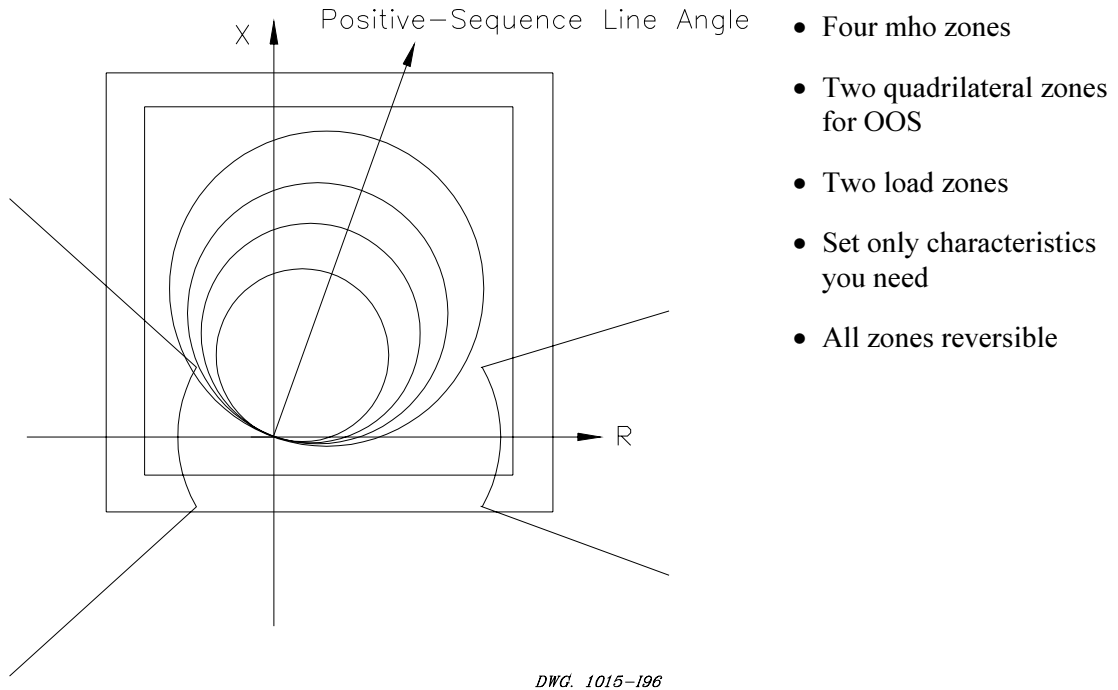


Figure 1.4: Three-Phase and Phase-Phase Distance Characteristics

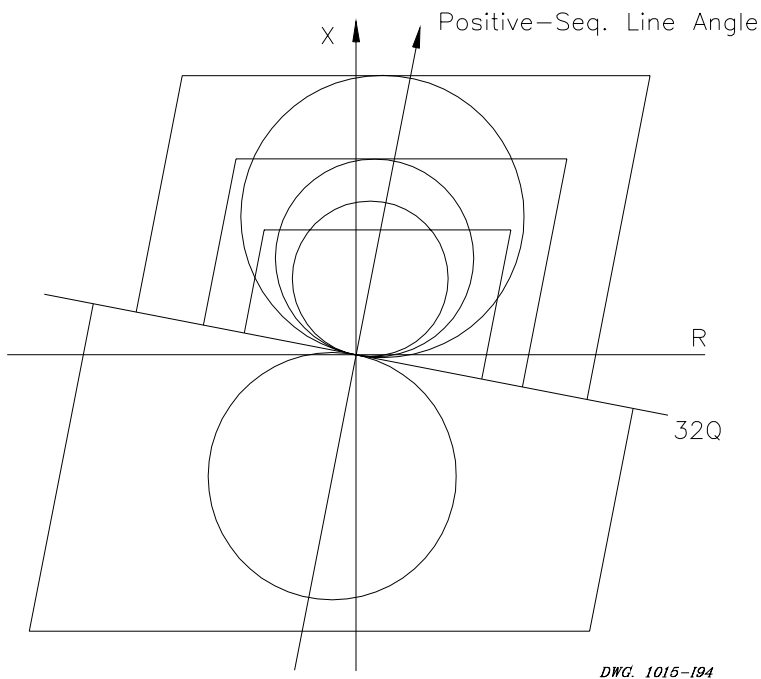


Figure 1.5: Ground Distance Characteristics

- Four mho zones
- Four quadrilateral zones
- Use quadrilateral, mho, none, or both

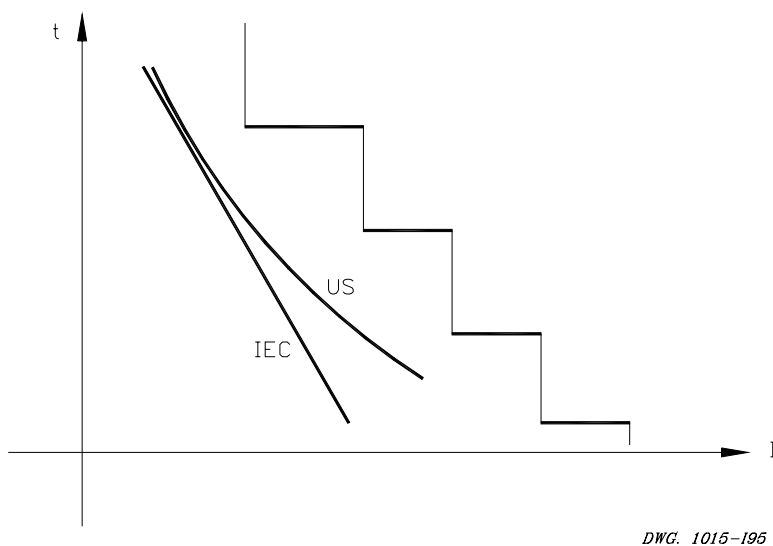


Figure 1.6: Instantaneous, Definite-Time, and Time-Overcurrent Characteristics

- Four US, four IEC curve families
- Phase, residual, and negative-sequence elements
- Torque-controllable by distance and directional elements
- One-cycle or electro-mechanical reset characteristics
- Four instantaneous/definite-time elements for negative-sequence and for residual overcurrent

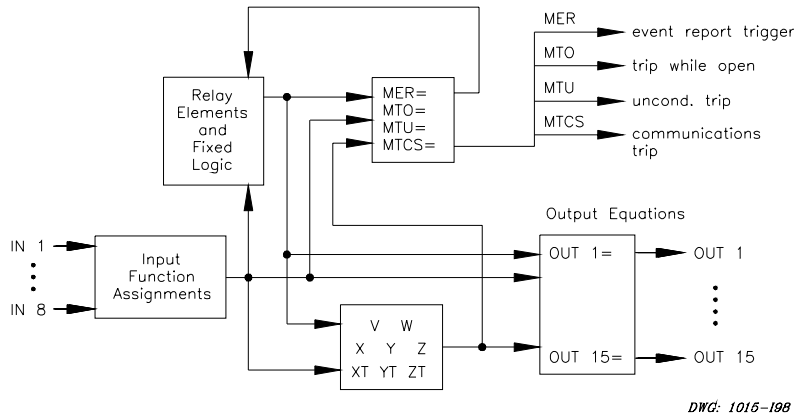


Figure 1.7: SELOGIC® Control Equations Programmable Control Logic

- Assign input functions
- Create output functions specific to any application
- Design unique trip and control schemes
- Minimize external timers, auxiliary relays, wiring, and panel space
- Event reporting records all logic

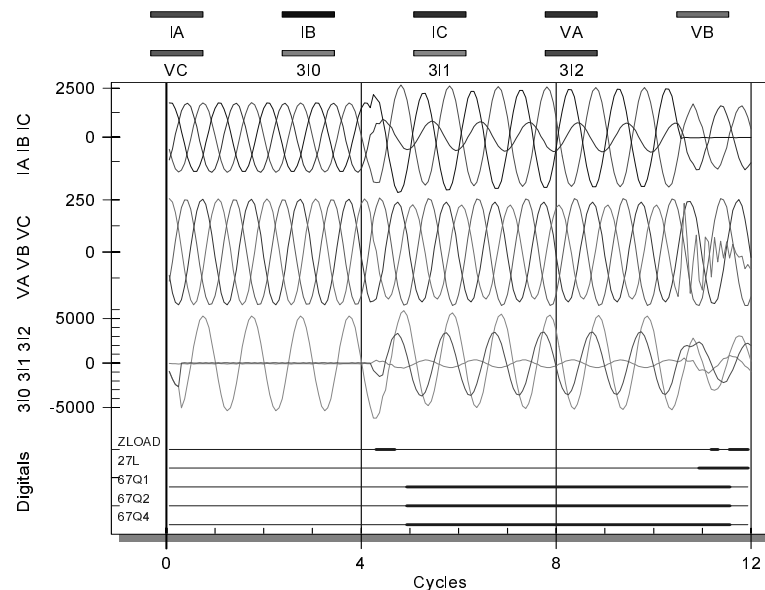


Figure 1.8: SEL-5601 Analytic Assistant

- Oscillographic displays using the SEL-5601 Analytic Assistant and 16 samples/cycle data
- Condensed 4 samples/cycle reporting
- Full report gives complete state of inputs, outputs, and elements every 1/16-cycle
- Read the ASCII text format with any computer – no proprietary formats are used

Event Reporting

Provides four types of event reports:

- Automatic summary report with abbreviated information
- Default report is 11-cycles duration, 4 samples/cycle
- Long event report is 11-cycles duration, 16 samples/cycle
- Unfiltered report for computer analysis of data
- Forty summaries are stored in nonvolatile memory

Applications Highlights

A list of applications and key specifications:

Applications	Key Specifications
Series Compensated Lines	<ul style="list-style-type: none">• Positive-sequence memory polarization• Long memory duration for directional stability
Single-Pole Tripping	<ul style="list-style-type: none">• Advanced phase-selection methods• Secure protection during open-pole interval• Pole-discordance logic trips three-pole for excessive single-pole-open events
Multiple-Breaker Applications	<ul style="list-style-type: none">• SPT one; 3PT other• SPT both; 3PT both• Trip coil monitors for up to six poles• Stub protection
Long Lines	<ul style="list-style-type: none">• Load-encroachment elements prevent unwanted trips on load• Voltage elements detect local and remote bus overvoltages• Sensitive negative-sequence and residual over-current elements provide sensitive backup protection
Tapped and Three-Terminal Lines	<ul style="list-style-type: none">• Four zones• Two zero-sequence compensation factors for more accurate ground-distance reach on either side of tap• Independent reach settings for phase, ground mho, and ground reactance elements• Multiple setting groups cover any switching configurations
Bus-Tie Breakers	<ul style="list-style-type: none">• Multiple setting groups<ul style="list-style-type: none">– match relay settings group to each line substitution– eliminate current reversing switches• Local or remote operator switches the setting groups
Subtransmission Lines	<ul style="list-style-type: none">• Time-stepped distance• Ground directional overcurrent protection• Torque controlled time-overcurrent elements
Lines with Transformers	<ul style="list-style-type: none">• Negative-sequence overcurrent protection
Lines with Reactors	<ul style="list-style-type: none">• Overvoltage elements control reactor insertion and tripping

Applications	Key Specifications
Short Transmission Lines	<ul style="list-style-type: none"> • Twenty-cycle polarizing memory duration
Permissive Overreaching Transfer Tripping Schemes (POTT)	<ul style="list-style-type: none"> • Current reversal guard logic • Open breaker echo keying logic • Weak- and zero-infeed logic • Time-step distance backup
Directional Comparison Unblocking Tripping Schemes (DCUB)	<ul style="list-style-type: none"> • Includes all POTT logic • All loss-of-channel logic inside the relay • Time-step backup
Permissive Underreaching Transfer Tripping Schemes (PUTT)	<ul style="list-style-type: none"> • Supported by POTT logic • Time-step backup
Directional Comparison Blocking Trip Scheme (DCB)	<ul style="list-style-type: none"> • Current reversal guard logic • Carrier coordinating timers • Carrier send and receive extend logic • Zone 3 latch eliminates the need for offset three-phase distance elements • Time-step backup
Zone 1 Extension Schemes	<ul style="list-style-type: none"> • Settable Zone 1 extension multiplier • Settable Zone 1 extension enable delay
Direct Underreaching Transfer Tripping Schemes (DUTT)	<ul style="list-style-type: none"> • SELOGIC control equations program which elements key direct trip

Other Features

- Fault locator
- Metering
- Automatic self-testing
- Forty event report summaries stored in non-volatile memory
- Three general purpose timers
- Five choices for controlling the trip circuits
- Trip circuit monitoring
- Hardware options for inputs, output contacts, and rear-panel terminals

Electronic-Level Input Option

The SEL relay instruction manuals address standard current (1 or 5 A) and voltage (67 V) inputs. If you ordered your SEL relay with an electronic-level input option, references in the instruction manual to Current Inputs and Voltage Inputs should be noted accordingly. Since the input circuits are designed to accept electronic levels, do not subject them to Dielectric Strength,

Interference, or Impulse Tests. Stickers on the rear of the relay indicate which inputs should only be connected to low-level electronic sources. We recommend that you use twisted-shielded-pair (TSP) cable between the source and relay and that you ground the shield at one end of the cable.

The SEL-321-3 Relay provides several electronic-level input options. Option A provides the best accuracy in each case. The 1.314 V secondary input-voltage option should be used in most applications. Determine your secondary input-current option by multiplying your 1 per-unit primary current by the sensor scaling factor.

Examples: Secondary Input-Voltage Option = 1.314 V

1 PU = 2000 A, Sensor Scaling Factor = 0.1 mV/A

Secondary Input-Current Option = $2000 \cdot 0.1 = 200$ mV

Since the SEL-321-3 Relay is set in secondary quantities and nonconventional sensor outputs are in primary quantities you must scale the relay settings using PTR (Potential Transformer Ratio) and CTR (Current Transformer Ratio). Determine the PTR setting by dividing the primary line-neutral voltage by 67 V. The CTR is determined by dividing your 1 per-unit primary current by 5 A. Use the PTR and CTR to determine the settings in secondary quantities.

Examples: $\text{PTR} = (525 \text{ kV}_{\text{L-L}}) / (\sqrt{3} \cdot 67) = 4524 \approx 4500$

$\text{CTR} = 2000 / 5 = 400$

Maximum Continuous Rating

Input: $15 \text{ V}_{\text{peak}} \approx 10.6 \text{ V}_{\text{rms}}$

Relay Test System (RTS)

The SEL-RTS Relay Test System is designed to bypass a relay's internal CTs and PTs (or low-level input module) so that it can provide low-level signals directly to the relay's processing module. You can use the SEL-RTS to test a relay's low-level input module at the terminal screws by modifying Scale Factors in the SELTEST™ Configuration Window. To determine the current channel ratio, divide 5 A by the secondary 1 PU input. To determine the voltage channel ratio, divide 67 V by the secondary 1 PU input.

Examples: $(5 \text{ A}) / (200 \text{ mV}) = 25$

$(67 \text{ V}) / (1.314 \text{ V}) = 50.99 \approx 51$

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SECTION 2: SPECIFICATIONS

OVERVIEW

The relay contains protection elements, many logic schemes, programmable I/O and logic, event recording, fault locating, metering, and other functions.

Outputs from all of the protection elements, logic schemes, etc., are available to the programmable logic (SELOGIC® control equations) for tripping, alarming, keying communications, and any other desired functions.

The relay includes three serial communications ports and a front-panel user interface for entering settings, reviewing operations, checking metering, and other functions.

SETTING STRUCTURE

The relay has five types of settings, as shown in Table 2.1.

Table 2.1: Relay Setting Structure

Communications Port Settings (SET P command) Assign the parameters of the three EIA-232 ports
Global Settings (SET G command) Assign contact inputs, LCD illumination timeout, and setting group switch delay
Logic Settings (SET L command) Program tripping functions and output contacts using SELOGIC control equations
SER Settings (SET R command) Program the Relay Word bits to be recorded in the Sequential Events Record (SER) report
All Remaining Settings (SET command) Select and set protective element boundaries and thresholds, communications assisted trip and other schemes

The setting procedure has enables for each group of features and characteristics. If you do not select a feature (e.g., out-of-step protection), the relay does not prompt you for those settings.

The following information is set using the **SET** command for each of the six setting groups.

LINE AND RELAY TERMINAL INFORMATION

The relay accepts information which describes the line section in terms of positive- and zero-sequence secondary impedances. The fault location algorithm uses these replica impedances directly. The distance elements use the positive-sequence impedance angle for calculations.

Other terminal information includes:

- Fault location option (Y = Two-terminal, R = Radial, N = Disable)
- Line length (LL)
- Current and potential transformer ratios (for presenting metering and event report data in primary values).

ENABLING DISTANCE ZONES

Zero to four zones of phase mho, ground mho, and ground quadrilateral protection can be individually selected. Use the PMHOZ, GMHOZ, and QUADZ settings to specify how many zones of each type of distance element you need.

Element Label Comment

Elements with zone labels are associated with distance elements. Elements with level labels are associated with negative-sequence and residual overcurrent elements.

SETTING THE DIRECTION OF ZONES AND OVERCURRENT ELEMENTS

The DIR1 - DIR4 settings establish the direction of characteristics associated with Zones and Levels 1 - 4. Table 2.2 shows which elements are affected by DIR1 - DIR4.

Table 2.2: Zone and Level Elements Affected by DIR1 - DIR4

Setting (F/R)	Affected Characteristics			
	Phase Mho	Ground Mho and Quad	$I_R >>$	$3I_2 >>$
DIR1	M1P	Z1G	67N1	67Q1
DIR2	M2P	Z2G	67N2	67Q2
DIR3	M3P	Z3G	67N3	67Q3
DIR4	M4P	Z4G	67N4	67Q4
(F = Forward, R = Reverse)				

PHASE MHO DISTANCE CHARACTERISTICS

Each phase mho zone has independent phase-to-phase overcurrent supervision. All instantaneous and time delayed outputs can be used in the programmable logic to create control, alarm, and indication schemes.

<u>Settings</u>	<u>Zone 1</u>	<u>Zone 2</u>	<u>Zone 3</u>	<u>Zone 4</u>
Zone Reach	Z1P	Z2P	Z3P	Z4P
O/C Supervisory	50PP1	50PP2	50PP3	50PP4
<u>Outputs</u>				
Instantaneous	M1P	M2P	M3P	M4P
Time Delayed		M2PT	M3PT	M4PT

Supporting Drawings: Figure 2.5 through Figure 2.9

GROUND MHO AND QUADRILATERAL DISTANCE CHARACTERISTICS

Each zone has separate phase and residual overcurrent supervision. The Zone 1 zero-sequence compensation factor (k01) is independent from the compensation factor (k0) used for all other zones.

<u>Settings</u>	<u>Zone 1</u>	<u>Zone 2</u>	<u>Zone 3</u>	<u>Zone 4</u>
Mho Reach	Z1MG	Z2MG	Z3MG	Z4MG
Quad Reactance	XG1	XG2	XG3	XG4
Quad Resistance	RG1	RG2	RG3	RG4
Phase O/C Sup.	50L1 ¹	50L2	50L3	50L4
Res. O/C Sup.	50G1	50G2	50G3	50G4
k0 magnitude	k01M	k0M	k0M	k0M
k0 angle	k01A	k0A	k0A	k0A
<u>Outputs</u>				
Instantaneous	Z1G	Z2G	Z3G	Z4G
Time Delayed		Z2GT	Z3GT	Z4GT

¹ 50L1 is also used for open pole logic and trip unlatch logic.

(The mho and quadrilateral characteristics share the same logical outputs Z1G - Z4G.)

Supporting Drawings: Figure 2.10 through Figure 2.18.

OUT-OF-STEP (OOS) CHARACTERISTICS

The rectangular impedance-plane characteristics use positive-sequence impedance and overcurrent supervision.

When the impedance remains between Zones 5 and 6 longer than the OOS blocking delay (OSBD), the relay logic prevents designated zones from tripping for up to two seconds.

Negative-sequence overcurrent conditions, detected by the 50Q1 - 50Q4 elements, remove OOS blocking to permit tripping for unbalanced faults which may occur during swings.

The OOS characteristics do not affect ground-fault protection.

Zone Blocking Enable Settings		OOSB1 - OOSB4		
<u>Timer Settings</u>				
OOS Blocking Delay		OSBD		
OOS Tripping Delay		OSTD		
Rectangular OOS				
<u>Characteristic Settings</u>	<u>Top</u>	<u>Bottom</u>	<u>Right</u>	<u>Left</u>
Zone 5	X1T5	X1B5	R1R5	R1L5
Zone 6	X1T6	X1B6	R1R6	R1L6
Overcurrent Supervision Setting		50ABC		
		50Q1 for removing OSB1 condition in the M1P logic		
		50Q2 for removing OSB2 condition in the M2P logic		
		50Q3 for removing OSB3 condition in the M3P logic		
		50Q4 for removing OSB4 condition in the M4P logic		
Maximum Time of Block		2 seconds		
<u>Outputs</u>				
Zone 5 Element		X5ABC		
Zone 6 Element		X6ABC		
Overcurrent Element		50ABC		
Out-of-Step Block Condition		OSB		
Zone 1 - 4 Blocked		OSB1 OSB2 OSB3 OSB4		
Out-of-Step Trip Initiated		OSTI		
Out-of-Step Trip Condition		OST		

These outputs may be used for alarming or controlling other equipment.

Supporting Drawings: Figure 2.19 and Figure 2.20.

LOAD-ENCROACHMENT CHARACTERISTICS

The load-encroachment feature permits setting the distance protection independent of the line loading.

Two independent positive-sequence impedance characteristics monitor load conditions. When load is in either of these characteristics, and the load-encroachment logic is enabled (ELE = Y), then the three-phase distance elements are blocked.

One characteristic monitors load-flow out, and the other monitors load-flow in. The settings are load impedance magnitude and angle limits. Normally, these characteristics are set to accommodate maximum load (minimum load impedance), and some margin, to ensure heavy loads remain inside the load characteristic.

<u>Settings</u>	<u>Load-Out Region</u>	<u>Load-In Region</u>
Minimum load impedance	ZLF	ZLR
Load-angle limits	PLAF (-90° to +90°)	PLAR (90° to 270°)
	NLAF (-90° to +90°)	NLAR (90° to 270°)

Output

Load Element Asserted

ZLOAD

Load detected in the load-in or load-out regions. $|I_1|$ must exceed $0.1 \cdot I_{nom}$ A.

Supporting Drawing: Figure 2.21.

I_{nom} = Nominal rated current

NEGATIVE-SEQUENCE DIRECTIONAL CHARACTERISTICS

These characteristics supervise:

All distance operations for unbalanced faults

Directional overcurrent outputs 67N1 - 67N4 and 67Q1 - 67Q4

They can also be used to torque-control the 51N and 51Q elements. Directional elements may be set to either default forward or deassert on loss-of-potential (LOP).

The characteristics easily accommodate strong or weak sources, long or short lines, series-compensation, and high fault resistance.

The directional characteristics are two settable (one forward and one reverse) negative-sequence reactance characteristics. The reaches are independently settable, and the forward and reverse characteristics have independent negative-sequence overcurrent supervision. Thus, forward and reverse sensitivity and selectivity are user-settable.

Both characteristics are supervised by a negative- to positive-sequence current ratio (I_2/I_1) check. This supervision restrains the negative-sequence directional elements for three-phase faults with errant I_2 . The a2 setting determines the minimum (I_2/I_1) ratio where directional calculations are permitted.

<u>Settings</u>	<u>Forward</u>	<u>Reverse</u>
Reach	Z2F	Z2R
3I ₂ Overcurrent Supervision	50QF	50QR
$ I_2 > a2 \cdot I_1 $ Restraint Factor	a2	a2

Outputs

Forward unbalanced fault	32QF
Reverse unbalanced fault	32QR
50QF or 50QR elements asserted	50Q

Supporting Drawing: Figure 2.22.

TIME-OVERCURRENT ELEMENTS

Phase, negative-sequence, and residual time-overcurrent elements are available as enabled. Both US and IEC curve shapes are supported. The phase element uses the highest measured phase current, while the negative-sequence and residual current elements use 3I₂ and I_R currents, respectively.

<u>Settings</u>	<u>Phase</u>	<u>Residual</u>	<u>Neg.-Seq.</u>
Pickup	51PP	51NP	51QP
Curve Family (US or IEC)	51PC	51NC	51QC
Time Dial	51PTD	51NTD	51QTD
Reset Delay	51PRS	51NRS	51QRS
Torque Control	51PTC	51NTC	51QTC
Torque Control Options:			
• Zone 2 Phase Mho (M2P)	X		X
• Load Encroachment	X		
• Zone 2 Ground Dist (Z2G)		X	X
• 32QF (forward)		X	X
• 32QR (reverse)		X	X
• Nondirectional	X	X	X

Reset delay setting choices permit one-cycle resetting or slow resetting, which emulates induction disk resetting.

<u>Outputs</u>	<u>Phase</u>	<u>Residual</u>	<u>Neg.-Seq.</u>
Pickup	51PP	51NP	51QP
Timed Out	51PT	51NT	51QT
Resetting	51PR	51NR	51QR

Supporting Drawings: Figure 2.23 through Figure 2.25.

INSTANTANEOUS/DEFINITE-TIME OVERCURRENT ELEMENTS: LEVELS 1 - 4

Zero to four levels of residual and negative-sequence overcurrent protection can be individually selected, using the E50N and E50Q settings respectively.

<u>Settings</u>	<u>Level 1</u>	<u>Level 2</u>	<u>Level 3</u>	<u>Level 4</u>
$I_R >>$	50N1	50N2	50N3	50N4
$3I_2 >>$	50Q1	50Q2	50Q3	50Q4

Instantaneous Nondirectional Outputs

$I_R >>$	50N1	50N2	50N3	50N4
$3I_2 >>$	50Q1	50Q2	50Q3	50Q4

The appropriate 50Q1 - 50Q4 element must be enabled and set to provide unbalanced fault detection for OOS blocking in phase distance trip logic.

<u>Instantaneous Directional Outputs</u>	<u>Level 1</u>	<u>Level 2</u>	<u>Level 3</u>	<u>Level 4</u>
$I_R >>$		67N2	67N3	67N4
$3I_2 >>$		67Q2	67Q3	67Q4

Time Delayed Directional Outputs

$I_R >>$	67N1	67N2T	67N3T	67N4T
$3I_2 >>$	67Q1	67Q2T	67Q3T	67Q4T

The negative-sequence directional elements, 32QF and 32QR, provide the directional supervision for 67N1 - 67N4 and 67Q1 - 67Q4 elements. The 32QF element supervises the forward-looking overcurrent elements, while the 32QR element supervises those set in the reverse direction. Forward set elements are supervised by SPO. All elements are supervised by fault selection logic when ESPT = N1 or Y1. The nondirectional outputs are always available.

Each level of residual and negative-sequence overcurrent protection has a designated settable timer.

Supporting Drawings: Figure 2.26 and Figure 2.27.

ADDITIONAL VOLTAGE ELEMENTS

The relay contains seven independent voltage elements. Use these elements by themselves or in combination with other relay elements using the programmable output contact logic to create custom control and supervision schemes. Possible applications might include undervoltage supervision of instantaneous overcurrent elements, local and remote overvoltage alarms, etc.

Phase Voltage Elements

Single-phase and three-phase elements compare individual voltage magnitudes against under- and overvoltage thresholds.

Zero-Sequence Overvoltage Element

The zero-sequence overvoltage element (59N) is used in the Weak-Infeed logic of the Permissive-Overreaching Transfer Trip Scheme logic. The 59N element output is also available for use in the programmable logic.

Positive-Sequence Overvoltage Elements

There are two positive-sequence (V_1) overvoltage elements: local bus (59PB) and remote bus (59PR). The 59PB element measures V_1 at the local bus. The 59PR element operates on an estimate of the voltage at the remote bus. The estimate is $V_{1\text{remote}} = V_1 - a1 \cdot Z_{1L} \cdot I_1$, where Z_{1L} is the positive-sequence replica line impedance, I_1 is the positive-sequence current, and $a1$ is a settable scale factor.

<u>Settings</u>	<u>Mag.</u>	<u>Delay</u>	<u>I_1 Comp.</u>
Zero-Seq. O/V	59N		
Bus Phase U/V	27L		
Bus Phase O/V	59L		
V_1 Local O/V	59PB	59PBD	
V_1 Remote O/V	59PR	59PRD	a1

<u>Outputs</u>	<u>1Ø</u>	<u>3Ø</u>	<u>Seq.</u>	<u>Use in Other Logic</u>
Zero-Seq. O/V			59N	Weak-Infeed Logic
Neg.-Seq. O/V			59QL	Loss-of-Potential Logic
Bus Phase U/V	27L	3P27		Weak-Infeed Logic (27L)
Bus Phase O/V	59L	3P59		No
V ₁ Voltage			59PL	Loss-of-Potential Logic
V ₁ Local O/V			59PB (w/ 59PBD Delay)	No
V ₁ Remote O/V			59PR (w/ 59PRD Delay)	No

Supporting Drawings: Figure 2.28 and Figure 2.29.

TIME-STEP BACKUP LOGIC TIMERS

Independent timers are provided for Zones 2, 3, and 4 of phase and ground distance protection and for each level of residual and negative-sequence overcurrent protection.

<u>Timer Settings</u>	<u>Phase 21</u>	<u>Gnd 21</u>	<u>67N</u>	<u>67Q</u>
Zone/Level 1			67NL1D	67QL1D
Zone/Level 2	Z2PD	Z2GD	67NL2D	67QL2D
Zone/Level 3	Z3PD	Z3GD	67NL3D	67QL3D
Zone/Level 4	Z4PD	Z4GD	67NL4D	67QL4D

<u>Timer Inputs and Outputs</u>	<u>Phase 21</u>		<u>Gnd 21</u>		<u>67N</u>		<u>67Q</u>	
	In	Out	In	Out	In	Out	In	Out
Zone/Level 1					67N1	67N1	67Q1	67Q1
Zone/Level 2	M2P	M2PT	Z2G	Z2GT	67N2	67N2T	67Q2	67Q2T
Zone/Level 3	M3P	M3PT	Z3G	Z3GT	67N3	67N3T	67Q3	67Q3T
Zone/Level 4	M4P	M4PT	Z4G	Z4GT	67N4	67N4T	67Q4	67Q4T

COMMUNICATIONS-ASSISTED TRIPPING SCHEMES

The relay includes tripping schemes which provide unit protection for transmission lines with the help of communications. No external coordination devices are required. The three scheme selections from the relay setting procedure are:

- Permissive-Overreaching Transfer Trip (POTT)
- Directional Comparison Unblocking (DCUB)
- Directional Comparison Blocking (DCB)

All three schemes require Zone 2 set forward and Zone 3 set reverse. Develop other communications-assisted tripping schemes using logic inputs and the programmable output logic. Examples are discussed later in this section.

To use a communications scheme, select and set the scheme and program inputs and outputs to monitor and control the communications receiver and transmitter.

Permissive Overreaching Transfer Trip (POTT) Logic

This logic performs the following tasks:

- Keys the communications equipment to send permissive trip when any element you include in the MTCS logic variable asserts and the current reversal logic is not asserted.
- Prevents keying and tripping by the POTT logic following a current reversal.
- Echoes the received permissive signal to the remote terminal.
- Prevents channel lockup during echo and test.

External Input

Received Permissive

Trip Signal	PT	Assign PT to a programmable input. Drive with receiver output.
-------------	----	--

Timer Settings

Zone 3 Rev. Block Delay	Z3RBD	Current-reversal guard timer.
Echo Block Delay	EBLKD	Prevents echoing of received PT, for settable delay, after dropout of local permissive elements. Set to OFF to ignore EBLKD and defeat echo input to ATB logic.
Echo Time Delay P/U	ETDPU	Sets minimum time requirement for received PT, before echo begins. Set to OFF for no echo.
Echo Duration	EDURD	Limits echo duration, to prevent channel lockup.

Logic Outputs

Zone 3 Reverse Block	Z3RB	Current reversal guard asserted.
Echo Conversion to Trip	ECTT	PT received, converted to a tripping condition for weak-infeed.
Key Permissive Trip	KEY	Signals communications equipment to transmit permissive trip.
Echo Key Permissive Trip	EKEY	Permissive trip signal keyed by Echo logic.
Assisted Trip Block	ATB	Blocks MTCS variable. Driven by ECHO and DCUB logic.

Supporting Drawing: Figure 2.30.

Directional Comparison Unblocking (DCUB) Logic

The DCUB logic is an extension of the POTT logic. The extension monitors the loss-of-guard output from the communications receiver, through an input programmed to the LOG function.

The typical application is a POTT scheme using FSK carrier as the communications medium.

External Inputs

Received Permissive

Trip Signal	PT	Assign PT to a programmable input. Drive with receiver output.
Loss-of-Guard	LOG	Assign LOG to a programmable input. Drive with contact from communications equipment.

Timer Settings

Guard-Present Delay	GARD1D	Sets minimum time requirement for reinstating permissive tripping following a loss-of-channel condition.
DCUB Disable Delay	UBDURD	Prevents tripping by POTT logic after a settable time following a loss-of-channel condition.
DCUB Duration Delay	UBEND	Sets minimum time required to declare a loss-of-guard condition.

Logic Outputs

Same as POTT outputs

Unblocking Block	UBB	Disables tripping by the DCUB logic.
Permissive Trip Receive	PTRX	Permissive trip signal receive input to POTT logic.

Supporting Drawings: Figure 2.30 and Figure 2.31.

Directional Comparison Blocking (DCB) Logic

This logic performs the following tasks:

- Provides the individual carrier coordination timers for the Zone 2 and Level 2 elements to allow time for the block trip signal to arrive from the remote terminal.
- Instantaneously keys the communications equipment to transmit block trip for reverse faults and extends this signal for a settable time following the dropout of all Zone 3 and Level 3 elements.
- Latches block trip send condition by the phase distance elements following a close-in zero-voltage three-phase fault where the polarizing memory expires. Latch is removed when the polarizing memory voltage returns or current is removed.
- Extends the received block trip signal by a settable time.

External Input

Received Block Trip Signal	BT	Assign BT to a programmable input. Drive with block trip receive output.
----------------------------	----	--

Timer Settings

Zone 3 Dropout Extension Delay	Z3XD	Current reversal guard timer.
Block Receive Extension Delay	BTXD	Sets reset time of block trip received condition after the reset of block trip input.
Zone 2 Phase 21 (M2P) Carrier Coord. Delay	Z2PSD	Delays M2P element output.
Zone 2 Ground 21 (Z2G) Carrier Coord. Delay	Z2GSD	Delays Z2G element output.
67N2 Carrier Coordination Delay	67N2SD	Delays 67N2 element output.
67Q2 Carrier Coordination Delay	67Q2SD	Delays 67Q2 element output.

Logic Outputs

Stop carrier	STOP	Program to an output contact to stop carrier.
Start carrier	START	Program to an output contact to start carrier. Includes current reversal guard logic.
Block Trip Extension	BTX	Block trip receive signal extended by BTXD timer.

Supporting Drawings: Figure 2.32 and Figure 2.33.

For further information, request *Application Guide 93-06: Applying the SEL-321 Relay to Directional Comparison Blocking (DCB) Schemes* from your representative or the factory.

Creating Other Tripping Schemes

Permissive Underreaching Transfer Trip Schemes

Use the POTT logic for the echo keying and Weak-Infeed logic. Program an output contact with Zone 1 distance elements to key permissive trip.

Direct Underreaching Transfer Trip Schemes

Three-Pole Trip Applications. Assign an input to DT (Direct Trip). Program this element in the unconditional trip variable (MTU) to trip the breaker upon assertion of the DT input. Program an output contact with Zone 1 distance elements to key the communication equipment to send the direct trip signal when any Zone 1 element asserts.

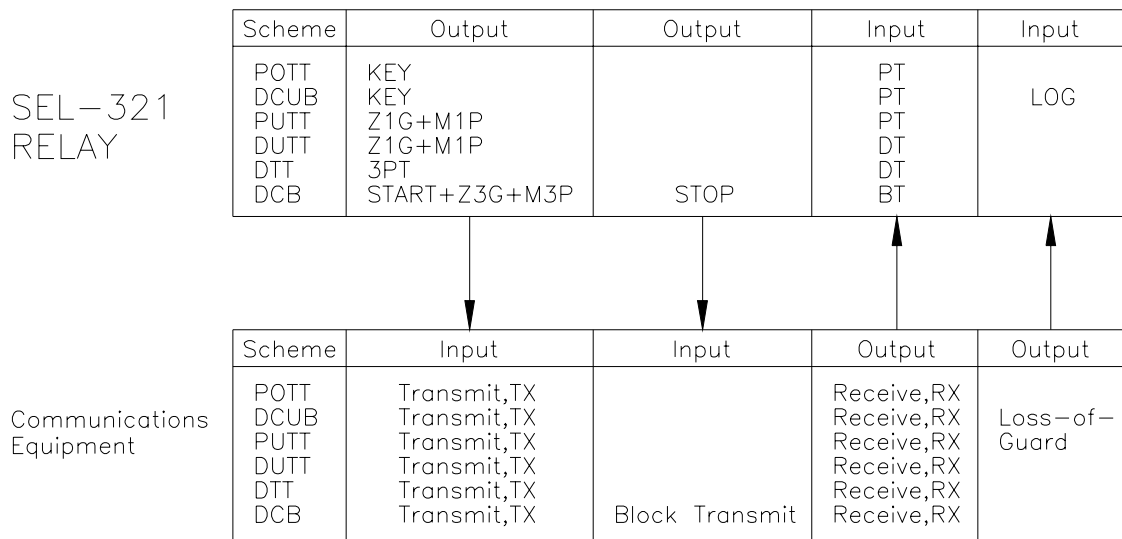
Single-Pole Trip Applications. Assign inputs to DTA, DTB, and DTC. Assertion of an input causes the corresponding trip variable to assert.

Direct Transfer Trip Schemes

Three-Pole Trip Applications. Assign an input to DT (Direct Trip). Program this element in the unconditional trip variable to trip the breaker upon assertion of the DT input. Program an output contact with a tripping element to key the communication equipment to send the direct trip signal when the relay asserts a tripping signal.

Single-Pole Trip Applications. Assign inputs to DTA, DTB, and DTC. Assertion of an input causes the corresponding trip variable to assert.

Figure 2.1 shows the necessary connections between the SEL-321 Relay and the communication equipment.



DWG: 10151105

Figure 2.1: Signal Connections Between Relay and Communication Equipment

OTHER LOGIC

Zone 1 Extension (Z1X) Scheme Logic

This logic modifies the reach of all Zone 1 distance elements by multiplier Z1EXTM once all three poles are closed for Z1EXTD time.

The Zone 1 reaches cannot be extended if any of the following elements are asserted:
M1P - M4P, Z1G - Z4G, 51NP, or 51QP.

All Zone 1 reaches retreat to their set reach when the programmable input assigned to CLOSE asserts.

Settings

Zone 1 Extension Delay	Z1EXTD	Sets the minimum time all three breaker poles must be closed before extending the Zone 1 reach.
Zone 1 Extension Multiplier	Z1EXTM	Sets the scalar by which all Zone 1 reaches are multiplied. Never less than one.

External Input

Close Signal	CLOSE	Assign CLOSE to a programmable input. Drive with the close signal to the breaker(s).
--------------	-------	--

Logic Output

Extend Zone 1 Reaches	Z1X	When asserted, Zone 1 reaches are extended.
-----------------------	-----	---

Supporting Drawing: Figure 2.34.

Remote-End-Just-Opened (REJO) Logic

The REJO logic accelerates tripping for one- or two-phase in-section faults without using a communications channel. This logic generates a tripping condition, if any elements in the MTCS variable assert and a REJO condition exists.

Settings

Coordinating Timer	REJOD	Delays REJO assertion to permit coordination for out-of-section faults.
Current Detectors	3P50R	Sets phase current threshold for detecting load.

Logic Outputs

Current above 3P50R threshold in all three phases	3P50R	Three-phase current is present to indicate remote breaker is closed. This must drop out to declare REJO.
Current above 3P50R threshold in one phase	50P	One-phase current is above the 3P50R threshold. This must remain asserted for REJO declaration.
Remote-End-Just-Opened	REJO	Enables tripping by elements in the MTCS variable.

Supporting Drawing: Figure 2.35.

Switch-Onto-Fault (SOTF) Logic

The SOTF logic permits specified elements to trip for a settable time after the breaker closes. Specify these elements in the programmable logic variable called MTO.

Tripping by elements in the MTO variable may be enabled two ways: asserting the CLOSE input or by timing the slowest 52a contact transition period. Select either or both means in the setting procedure.

This logic is only active following all breaker poles being open.

External Input

Close Signal	CLOSE	Drive with the close signal to the breaker(s).
52A1 Breaker Aux. Contacts	52A1 52A2 52AA1 52AA2 52AB1 52AB2 52AC1 52AC2	Drive with breaker auxiliary contacts. The number of inputs depends on the application and whether single- or three-pole tripping is used.

Settings

Close Enable Delay	CLOEND	Sets minimum time duration after all currents drop out, before CLOSE input activates SOTF logic.
52A Enable Delay	52AEND	Sets minimum time after all breaker poles open before activating SOTF logic.
SOTF Time Duration	SOTFD	Sets how long tripping by elements in MTO is active following breaker closure.
High-Set Phase O/C Pickup	50H	

Logic Output

Switch-Onto-Fault		
Logic Enabled	SOTFE	Enables three-pole tripping by elements in MTO logic variable.

Supporting Drawing: Figure 2.36.

Loss-of-Potential (LOP) Logic

This logic detects one, two, or three blown potential fuses. The LOP condition blocks all distance elements. Settings options will either force forward or block the directional decision for overcurrent elements.

The relay includes advanced loss-of-potential logic. This logic requires no settings other than the choice of enable settings. The use of advanced loss-of-potential logic is recommended, however the option to use the original loss-of-potential logic and settings has been retained to maintain compatibility with previous versions of the relay. Settings ELOP = N or Y use the original loss-of-potential logic. Settings ELOP = N1, Y1, or Y2 use the advanced loss-of-potential logic. See *Loss-of-Potential (LOP) Enable Setting (ELOP)* in *Section 5: Applications* for a description of the LOP logic.

If setting ELOP = N1, Y1, or Y2 , then settings LOPD, 59QL, and 59PL are not used and are hidden. Setting 50M is still visible since it is used in stub protection logic.

Settings

Enable Loss-of-Potential	ELOP	N = Disable element blocking. Monitor LOP with original logic. Y = LOP blocks distance elements with original logic. Overcurrent elements default forward during LOP condition. N1= Disable element blocking. Monitor LOP with advanced logic. Y1= LOP blocks distance elements and overcurrent directional elements with advanced logic. Y2= LOP blocks distance elements with advanced logic. Overcurrent elements default forward during LOP condition.
LOP Time Delay	LOPD	Sets time delay before LOP can assert following the loss of one or two potential fuses.
Medium-Set Phase O/C Pickup	50M	Single-phase overcurrent threshold for blocking LOP during faults, and for use in stub protection logic.
Neg.-Seq. (V2) O/V Pickup	59QL	Sets V2 threshold for detecting one or two blown fuses.
Pos.-Seq. (V1) O/V Pickup	59PL	Sets V1 threshold for detecting three blown fuses.

Outputs

LOP indication	LOP	Always available even if ELOP = N or N1. Does not block distance elements.
Internal LOP block	ILOP	Enabled by ELOP = Y, Y1, or Y2. Blocks distance elements.

Supporting Drawings: Figure 2.22 and Figure 2.37.

Pole-Discordance Logic

This logic can be used to alarm or trip. The logic checks the 52A inputs from either one or two breakers. The timer, SPPDD, cycles after any single-pole trip signal drops out. If all three 52A inputs from a breaker disagree, the appropriate pole-discordance output variable (PD1 or PD2) immediately asserts.

Timer Setting

Single-Pole Trip

Phase-Discordance Delay	SPPDD	Sets time delay for checking the 52A input statuses following the dropout of a single-pole trip signal.
-------------------------	-------	---

Outputs

Pole Discordance 1	PD1	Breaker 1 pole discordance.
Pole Discordance 2	PD2	Breaker 2 pole discordance.

Supporting Drawing: Figure 2.38.

Pole Open Logic

This logic discriminates between a partially and fully-open line terminal. The Three-Pole Open (3PO) condition asserts when all three phases of the line are disconnected. The Single-Pole Open (SPO) condition asserts when one or two phases of the line remain energized.

A pole is open if the one (or two) 52A inputs associated with that phase are deasserted and if the current in that phase is below pickup of the four overcurrent elements 50L1 - 50L4.

The output of this logic influences both phase and ground distance element operations. SPO and 3PO conditions have independent Time Delayed Dropout (TDDO) timers.

Timer Settings

Single-Pole Open Delay	SPOD	Stabilizing time delay after single-pole reclose.
Three-Pole Open Delay	3POD	Security time delay for dissimilar breaker pole closing.
Trip-Open Pole Delay	TOPD	Any trip which occurs while TOPD is timing results in a three-pole trip.

Outputs

Phase A Open	SPOA	Blocks 21AG, 21AB, and 21CA elements.
Phase B Open	SPOB	Blocks 21BG, 21AB, and 21BC elements.
Phase C Open	SPOC	Blocks 21CG, 21BC, and 21CA elements.
Single-Pole Open	SPO	Blocks all quadrilateral ground distance, clears LOP, and asserts 32QF. Includes SPOD delay.
Three-Pole Open	3PO	Blocks all ground distance. Includes 3POD delay.
Trip-Open-Pole	TOP	TOPD timer is timing.

Supporting Drawing: Figure 2.38 and Figure 2.39.

Stub Protection Logic

The LOP condition can enable a definite-time overcurrent element to detect faults on bus sections not having PTs or to provide backup protection if potentials are lost. The same 50M overcurrent element used in the LOP logic serves as the fault detector for this logic. If ELOP = N or N1, this logic is not enabled.

Timer Setting

Stub Protection Coord. Delay	50MFD	Define-time delay for 50MF.
------------------------------	-------	-----------------------------

Output

Stub Protection O/C Element	50MF	Asserts for faults during LOP conditions if 50M asserted for 50MFD delay.
-----------------------------	------	---

Supporting Drawing: Figure 2.40.

Trip Coil Monitor (TCM) Logic

Programmable inputs can be assigned to monitor the integrity of up to six trip-coil circuits. Each input must be connected in parallel with the appropriate tripping contacts.

If any monitoring input disagrees with the corresponding 52A input for 60 cycles, then the TCM element asserts. Table 2.3 shows the logic input assignments required to activate the TCM logic.

Table 2.3: Trip Coil Monitor Logic Input Assignment Options

Breaker 1		Breaker 2	
3PT	SPT	3PT	SPT
52A1,TCM1	52AA1, TCMA1 52AB1, TCMB1 52AC1, TCMC1	52A2,TCM2	52AA2, TCMA2 52AB2, TCMB2 52AC2, TCMC2

Logic Output

Trip Coil

Monitor condition TCM Trip coil path invalid condition.

Supporting Drawing: Figure 2.41.

If you set 52A1, and 52AA1, 52AB1, and 52AC1, the relay will treat this as a conflict. Either set 52A1, or set 52AA1, 52AB1, and 52AC1, but not both sets. Similar conflicts will occur with 52A2, TCM1, etc. and their single-pole trip equivalents.

Close Logic

This logic controls the CC element. Remotely close a circuit breaker with the **CLOSE** command. This command is available in the Breaker and Level 2 access levels. Both of these levels have separate passwords.

Issuing the **CLOSE** command asserts the CC element if the breaker is open. Use a SELOGIC control equation to program the CC element to any output contact connected to the closing circuit of the breaker.

The CC element asserts for 30 cycles or until the breaker closes or a tripping condition is detected.

Supporting Drawing: Figure 2.42.

Trip Suspicion Logic

Transferring polarizing potentials from one source to another during high loading conditions may result in a race condition between assertion of three-phase LOP and the phase distance elements. The Trip Suspicion logic ensures distance element security during this transfer.

Assign a relay input to monitor the device which initiates the potential transfer. The input assignment is PTXFR. For a five second period after asserting the PTXFR input, the Trip Suspicion logic delays tripping for 3 cycles.

Input

Potential Transfer	PTXFR	Drive with potential transfer switch initiation indication.
--------------------	-------	---

Output

Trip Suspicion	TS	Blocks all tripping conditions for 3 cycles.
----------------	----	--

Supporting Drawing: Figure 2.43.

Fault Identification Selection (FIDS) Logic

This logic identifies the faulted phase(s) for all faults involving ground by comparing the angle between I_0 and I_2 .

The logic is not active during an SPO condition.

Outputs

FIDS Selects A-phase	FSA	Enables A-phase ground distance and blocks AB and CA phase distance elements.
FIDS Selects B-phase	FSB	Enables B-phase ground distance and blocks AB and BC phase distance elements.
FIDS Selects C-phase	FSC	Enables C-phase ground distance and blocks BC and CA phase distance elements.

Open Phase Alarm Logic

This logic detects negative-sequence current in the presence of balanced voltages when all poles of the breaker are closed. This condition asserts an alarm element labeled OPA.

Use a SELOGIC control equation to program OPA to an output contact for alarming.

Output

Open Pole Alarm Element	OPA	Indicates an open phase condition.
-------------------------	-----	------------------------------------

Supporting Drawing: Figure 2.44.

Contact Input Assignments

The one I/O board relay has eight assignable logic inputs IN1 - IN8. The two I/O board relay has 16 inputs, IN1 - IN16. You assign functions to each of the inputs from the assignments listed in Table 2.4 by using the **SET G** command. The status of all assigned inputs are available in Relay Word rows 21 - 25 (see Table 2.9).

Table 2.4: Logic Input Assignment List

Function	Label	Application
Not Assigned	NA	Input not assigned
Setting Selection 1	SS1	Setting Group Selection Input 1
Setting Selection 2	SS2	Setting Group Selection Input 2
Setting Selection 3	SS3	Setting Group Selection Input 3
Permissive Trip	PT	Drive with PT receive output for POTT scheme
Block Trip	BT	Drive with BT receive output for DCB scheme
Direct Trip	DT	Asserts the DT element
Single-Pole Direct Trip A	DTA	Direct Trip A
Single-Pole Direct Trip B	DTB	Direct Trip B
Single-Pole Direct Trip C	DTC	Direct Trip C
Loss-of-Guard	LOG	Drive with loss-of-guard output from communications equipment
Potential Transfer	PTXFR	Drive with contact from the potential transfer switch
Single-Pole Trip Enable	SPTE	Assert to enable single-pole trip
Parallel A-phase Block	PARA	Assert to block A-phase ground distance protection
Parallel B-phase Block	PARB	Assert to block B-phase ground distance protection
Parallel C-phase Block	PARC	Assert to block C-phase ground distance protection
Bkr. 1 Position	52A1	Drive with Bkr. 1 auxiliary in 3PT applications ¹
Bkr. 2 Position	52A2	Drive with Bkr. 2 auxiliary in 3PT applications ²
Bkr. 1, A-phase Pole Position	52AA1	Monitors Breaker 1 position, A-phase
Bkr. 2, A-phase Pole Position	52AA2	Monitors Breaker 2 position, A-phase
Bkr. 1, B-phase Pole Position	52AB1	Monitors Breaker 1 position, B-phase
Bkr. 2, B-phase Pole Position	52AB2	Monitors Breaker 2 position, B-phase
Bkr. 1, C-phase Pole Position	52AC1	Monitors Breaker 1 position, C-phase
Bkr. 2, C-phase Pole Position	52AC2	Monitors Breaker 2 position, C-phase
Close	CLOSE	Drive with breaker close signal
Trip Coil Monitor 1	TCM1	Monitors Breaker 1 trip coil ³
Trip Coil Monitor 2	TCM2	Monitors Breaker 2 trip coil ⁴
Trip Coil Monitor, A-phase 1	TCMA1	Monitors Breaker 1, A-phase trip coil
Trip Coil Monitor, B-phase 1	TCMB1	Monitors Breaker 1, B-phase trip coil

Function	Label	Application
Trip Coil Monitor, C-phase 1	TCMC1	Monitors Breaker 1, C-phase trip coil
Trip Coil Monitor, A-phase 2	TCMA2	Monitors Breaker 2, A-phase trip coil
Trip Coil Monitor, B-phase 2	TCMB2	Monitors Breaker 2, B-phase trip coil
Trip Coil Monitor, C-phase 2	TCMC2	Monitors Breaker 2, C-phase trip coil
External Trigger	EXT	Assert to trigger event reports
Logic Point 1	LP1	Controls general purpose element LP1
Logic Point 2	LP2	Controls general purpose element LP2
Logic Point 3	LP3	Controls general purpose element LP3
Logic Point 4	LP4	Controls general purpose element LP4
Logic Point 5	LP5	Controls general purpose element LP5
Logic Point 6	LP6	Controls general purpose element LP6
Logic Point 7	LP7	Controls general purpose element LP7
Logic Point 8	LP8	Controls general purpose element LP8
Logic Point 9	LP9	Controls general purpose element LP9
Logic Point 10	LP10	Controls general purpose element LP10
Ext. Trip Unlatch	EXTUL	Assert to unlatch TPA, TPB, TPC, and 3PT

Invert the sense of any input assignment by including the SELOGIC control equation invert operator “!” immediately in front of the input assignment (e.g., !52A1 changes a 52a input to a 52b input).

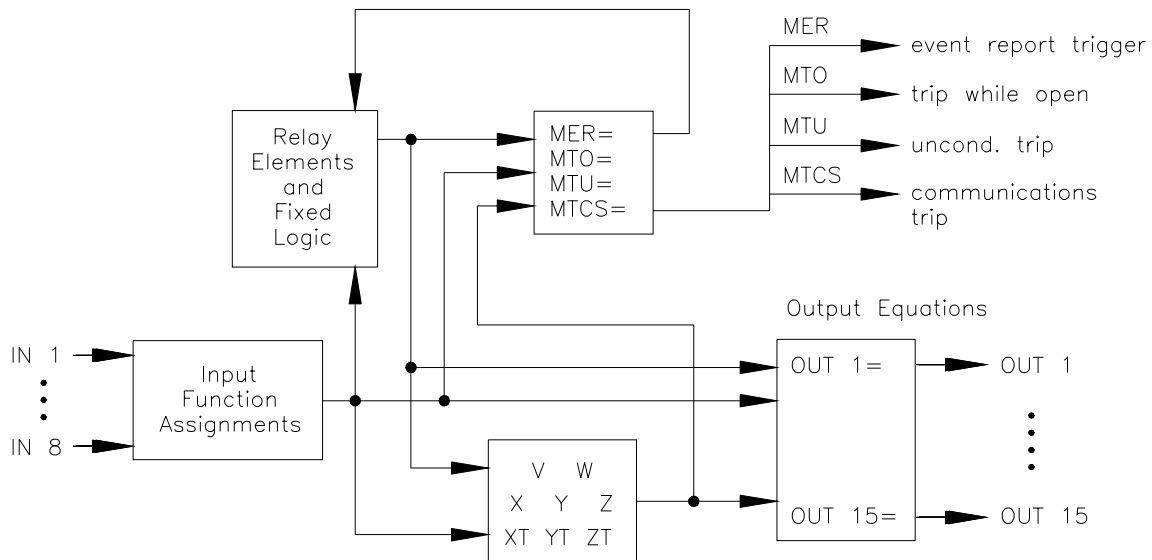
- ¹ 52AA1, 52AB1, and 52AC1 follow 52A1 if they are not assigned to an input.
- ² 52AA2, 52AB2, and 52AC2 follow 52A2 if they are not assigned to an input.
- ³ TCMA1, TCMB1, and TCMC1 follow TCM1 if they are not assigned to an input.
- ⁴ TCMA2, TCMB2, and TCMC2 follow TCM2 if they are not assigned to an input.

SELOGIC CONTROL EQUATIONS

SELOGIC control equations perform the following tasks:

- Define what conditions assert the output contacts
- Define which elements and conditions trigger event reports
- Select the elements which trip for switch-onto-fault conditions
- Select the elements which trip unconditionally
- Select the elements which trip with communications assistance

Figure 2.2 gives an overview of SELOGIC control equations in the SEL-321 Relay.



DWG: 1015-198

Figure 2.2: SEL-321 SELOGIC Control Equations Overview

Programming SELOGIC control equations is easy.

1. Use the **SET G** command to enter your input assignments into the global settings of the relay. (“Global” means that only one set of input assignments is permitted. There are six sets of logic and element settings.) Table 2.4 lists all available input assignment choices.
2. Determine the relay element combinations you want for the following four purposes:

Communications-aided trip	(set with MTCS logic variable)
Unconditional trip	(set with MTU logic variable)
Switch-onto-fault trip	(set with MTO logic variable)
Event report triggering	(set with MER logic variable)
3. Determine the output functions you require, including tripping, keying communications, etc. First, refer to the rear-panel wiring diagram, and choose the specific output contacts you wish to assign to various functions. For example, assume you want OUT1 and OUT2 to be three-pole trip outputs, OUT3 to follow the **CLOSE** command, and OUT4 to key communications. Any output contact may be assigned for tripping duty.

When you are designing your trip condition, event trigger, and output logic, you may use AND, OR, and NOT operators to develop virtually any combination of elements for each condition. There are also five intermediate variables (V, W, X, Y, and Z) which you can first program and subsequently use in Steps 2 and 3 above. Three of these (X, Y, and Z) also have independent general-purpose time delay pickup/dropout timers. The outputs after these timers (XT, YT, and ZT) are also available.
4. Use the **SET L** command to enter your logic equations for V, W, X, Y, Z, MTCS, MTU, MTO, MER, and each of the outputs (except ALARM). Each setting group has its own associated logic equations.

5. If you want the same logic and relay element settings in more than one group, you do not need to re-type the equations and settings. Instead copy them using the **COPY** command. To copy Group 1 settings to Group 2, use the command **COPY 1 2**.

Equation Programming

Program intermediate logic points (elements listed in Table 2.12) and the output contacts with SELOGIC control equations. This permits you to combine any element in Table 2.7, Table 2.9, or Table 2.12, use nondedicated timers for special applications, and assign these combinations to output contacts. Inputs can be assigned labels listed in Table 2.4.

Programming SELOGIC control equations consists of combining relay elements with logical AND (*), OR (+), and inversion (!) variables in a single string for each output contact. The following list defines the use of these variables. The simplest string consists of directly entering a single element.

- * **AND** Requires elements on both sides of the * symbol be asserted before the logic condition is true. For example, to supervise the **M1P** element with the **27L** element, program the SELogic control equation as: **M1P * 27L**.
- + **OR** Requires one element on either side of the + symbol be asserted before the logical condition is true. The following setting closes the OUT9 output contact when either the **M1P** or **27L** element asserts: **OUT9 = M1P + 27L**.
- ! **Invert** Inverts the value of the element immediately following the ! symbol. For example, to block the **50H** element if the voltages of all three phases are below the **27L** threshold, program the SELOGIC control equations as: **50H * !3P27**.
- \ Insert a \ symbol at the end of the first line of a SELOGIC control equation (just before pressing [RETURN]), to continue the same equation to the second line. Otherwise, the equation may only be one line. There is a two-line (80 characters per line – 160 characters max) limit for a single equation and a 100-term (element names and operators) limit per equation.

The total number of overall SELOGIC control equation terms is limited to 160 in the 50 Hz version and 100 in the 60 Hz version. If the overall number of SELOGIC control equation terms is exceeded, the relay will issue an error message at the end of the SELOGIC control equation setting procedure (**SET L** command). You can determine the total number of SELOGIC control equation terms by counting each AND (*) operator, OR (+) operator, and relay element used in the SELOGIC control equation programming. Note that the Invert (!) operator is not counted.

For example, the SELOGIC control equation string **M1P + 27L** contains three terms. The string **50H * !3P27** also contains three terms. The string **TPA * SOTFE + TPB * SOTFE + TPC * SOTFE** contains eleven terms.

SELogic Control Equation Operator Order of Operations

When the SELOGIC control equations are computed, the ! is applied first, followed by AND (*) functions, and finally OR (+) functions are computed. The *, +, and ! functions may be used in any combination for any output contact. For example, to signal that the relay tripped by a switch-onto-fault operation, program one of the output contacts as follows (OUT 4 shown as an example):

$$\text{OUT4} = \text{TPA} * \text{SOTFE} + \text{TPB} * \text{SOTFE} + \text{TPC} * \text{SOTFE}$$

This logic says that if **TPA**, **TPB**, or **TPC** assert while **SOTFE** is asserted, that OUT4 asserts to indicate a SOTF operation.

Exceptions

1. Variables (V, W, X, Y, or Z) cannot be programmed to themselves.
2. SELOGIC control equation variables can only be programmed with elements defined before them in the element list. Within Table 2.12, before means those elements to the right of the one being programmed.
3. Table 2.5 lists combinations of SELOGIC control equation operators that are not acceptable:

Table 2.5: Unacceptable SELOGIC Control Equation Operator Combinations

*+	**	!*	!+
+*	++	!!	

Program any single internal-use element from Table 2.14 to an output contact as long as nothing else is programmed to that output.

Programming an output equation to NA disables that output contact.

Relay Elements

Table 2.6 through Table 2.18 show the set of relay elements. Display any row of relay elements using the **TARGET** command and the TAR numbers in the left column of each table.

Table 2.6 shows front-panel status indicators. These are not logic elements. They correspond to the front-panel targets and bear the front-panel target names.

Table 2.6: Front-Panel Status Indicators

TAR	Status Indicators							
0	INST	TIME	COMM	SOTF	ZONE1	ZONE2	ZONE3	ZONE4
1	EN	A	B	C	G	Q	51	50

The relay's primary elements are listed in Table 2.7. The status of these elements is updated by the relay logic, and these elements serve as a source for use in SELOGIC control equations. All outputs, except ALARM, can be programmed using the primary elements and SELOGIC control equations.

Table 2.7: Primary Elements

TAR	Elements							
2	Z4G	Z3G	Z2G	Z1G	M4P	M3P	M2P	M1P
3	Z4GT	Z3GT	Z2GT	LOP	M4PT	M3PT	M2PT	OPA
4	67Q4	67Q3	67Q2	67Q1	67N4	67N3	67N2	67N1
5	67Q4T	67Q3T	67Q2T	OST	67N4T	67N3T	67N2T	OSB
6	PD1	3P27	27L	50H	50MF	51NT	51QT	51PT
7	ZLOAD	SOTFE	TCM	ANYTRP	3PO	SPO	REJO	PD2
8	3P50R	51NP	51QP	51PP	50G	50PP	50M	50L
9	50Q4	50Q3	50Q2	50Q1	50N4	50N3	50N2	50N1
10	50ABC	X6ABC	X5ABC	3PT	TPC	TPB	TPA	32QF
11	3P59	59L	59N	59PR	59PB	59QL	59PL	50Q
12	BTX	SPTI	STOP	START	FIDEN	FSC	FSB	FSA
13	32QR	Z1X	CC	EKEY	Z3RB	ATB	ECTT	KEY
14	XAG4	XAG3	XAG2	XAG1	MAG4	MAG3	MAG2	MAG1
15	XBG4	XBG3	XBG2	XBG1	MBG4	MBG3	MBG2	MBG1
16	XCG4	XCG3	XCG2	XCG1	MCG4	MCG3	MCG2	MCG1
17	MBC4	MBC3	MBC2	MBC1	MAB4	MAB3	MAB2	MAB1
18	SPOC	SPOB	SPOA	Z1	MCA4	MCA3	MCA2	MCA1
19	50HH	OSTI	50CA	50BC	50AB	Z4	Z3	Z2
20	RBAD	CBAD	LBOK	ROK	3PTC	3PTB	3PTA	TOP

Note: For the highlighted elements, see the note following Table 2.8.

Table 2.8: Primary Element Summary

Element	Comment
Z4G	Zone 4 Mho and/or Quad. Distance, Instantaneous
Z3G	Zone 3 Mho and/or Quad. Distance, Instantaneous
Z2G	Zone 2 Mho and/or Quad. Distance, Instantaneous
Z1G	Zone 1 Mho and/or Quad. Distance, Instantaneous
M4P	Zone 4 Phase Distance, Instantaneous
M3P	Zone 3 Phase Distance, Instantaneous
M2P	Zone 2 Phase Distance, Instantaneous
M1P	Zone 1 Phase Distance, Instantaneous
Z4GT	Zone 4 Ground Distance, Time Delayed
Z3GT	Zone 3 Ground Distance, Time Delayed
Z2GT	Zone 2 Ground Distance, Time Delayed
LOP	Loss-of-Potential Condition Indication
M4PT	Zone 4 Phase Distance, Time Delayed
M3PT	Zone 3 Phase Distance, Time Delayed
M2PT	Zone 2 Phase Distance, Time Delayed
OPA	Open Phase Alarm

Element	Comment
67Q4	Level 4 Directional Neg.-Seq. Overcurrent, Instantaneous
67Q3	Level 3 Directional Neg.-Seq. Overcurrent, Instantaneous
67Q2	Level 2 Directional Neg.-Seq. Overcurrent, Instantaneous
67Q1	Level 1 Directional Neg.-Seq. Overcurrent
67N4	Level 4 Directional Residual Overcurrent, Instantaneous
67N3	Level 3 Directional Residual Overcurrent, Instantaneous
67N2	Level 2 Directional Residual Overcurrent, Instantaneous
67N1	Level 1 Directional Residual Overcurrent
67Q4T	Level 4 Directional Neg.-Seq. Overcurrent, Time Delayed
67Q3T	Level 3 Directional Neg.-Seq. Overcurrent, Time Delayed
67Q2T	Level 2 Directional Neg.-Seq. Overcurrent, Time Delayed
OST	Out-of-Step Trip Condition Declaration
67N4T	Level 4 Directional Residual Overcurrent, Time Delayed
67N3T	Level 3 Directional Residual Overcurrent, Time Delayed
67N2T	Level 2 Directional Residual Overcurrent, Time Delayed
OSB	Out-of-Step Block Condition Declaration
PD1	Breaker 1 Phase Discordance Declaration
3P27	Three-Phase Undervoltage Condition
27L	Single-Phase Undervoltage Condition
50H	High-Set Phase Overcurrent, Instantaneous
50MF	Medium-Set Phase Overcurrent Time Delayed by 50MF Timer
51NT	Residual Time-Overcurrent Timed Out
51QT	Negative-Sequence Time-Overcurrent Timed Out
51PT	Phase Time-Overcurrent Timed Out
ZLOAD	Load Element
SOTFE	Switch-Onto-Fault Logic Enabled
TCM	Trip Coil Monitor Alarm
ANYTRP	TPA + TPB + TPC
3PO	Three Poles Open
SPO	Single-Pole Open
REJO	Remote End Just Opened Condition
PD2	Breaker 2 Phase Discordance Declaration
3P50R	REJO Logic Overcurrent Element Pickup
51NP	Residual Time-Overcurrent Element Pickup
51QP	Negative-Sequence Time-Overcurrent Element Pickup
51PP	Phase Time-Overcurrent Element Pickup
50G	50G1 + 50G2 + 50G3 + 50G4
50PP	50PP1 + 50PP2 + 50PP3 + 50PP4
50M	Medium-Set Phase Overcurrent
50L	50L1 + 50L2 + 50L3 + 50L4

Element	Comment
50Q4	Level 4 Nondirectional Neg.-Seq. Overcurrent, Instantaneous
50Q3	Level 3 Nondirectional Neg.-Seq. Overcurrent, Instantaneous
50Q2	Level 2 Nondirectional Neg.-Seq. Overcurrent, Instantaneous
50Q1	Level 1 Nondirectional Neg.-Seq. Overcurrent, Instantaneous
50N4	Level 4 Nondirectional Residual Overcurrent, Instantaneous
50N3	Level 3 Nondirectional Residual Overcurrent, Instantaneous
50N2	Level 2 Nondirectional Residual Overcurrent, Instantaneous
50N1	Level 1 Nondirectional Residual Overcurrent, Instantaneous
50ABC	OOS Supervising Overcurrent Element, Pos.-Seq., Instantaneous
X6ABC	Zone 6, Out-of-Step Distance Element, Instantaneous
X5ABC	Zone 5, Out-of-Step Distance Element, Instantaneous
3PT	Three-Pole Trip
TPC	Trip C
TPB	Trip B
TPA	Trip A
32QF	Negative-Sequence Directional Element: Forward
3P59	Three-Phase Overvoltage Element
59L	Single-Phase Overvoltage Element
59N	Residual Overvoltage Element Status
59PR	Current Compensated Positive-Sequence Overvoltage Element Status
59PB	Local Positive-Sequence Overvoltage Element Status
59QL	Loss-of-Potential Negative-Sequence Overvoltage Element Status
59PL	Loss-of-Potential Positive-Sequence Overvoltage Element Status
50Q	50QF + 50QR
BTX	Block Trip Input Extension (active if EDCB = Y)
SPTI	TPA*!3PT + TPB*!3PT + TPC*!3PT
STOP	Carrier Stop for DCB (active if EDCB = Y)
START	Carrier Start for DCB (active if EDCB = Y)
FIDEN	FIDS Logic Enable
FSC	FIDS logic selects C-phase
FSB	FIDS logic selects B-phase
FSA	FIDS logic selects A-phase
32QR	Negative-Sequence Directional Element: Reverse
Z1X	Zone 1 Extension Enable (active if EZ1EXT = Y)
CC	Close Command Control Element
EKEY	Echo Key (active if EPOTT = Y)
Z3RB	Zone 3 Reverse Block (active if EPOTT = Y)
ATB	Aided Trip Block (active if EPOTT = Y)
ECTT	Echo Conversion to Trip (active if EPOTT = Y)
KEY	Key Permissive Trip Signal Start (active if EPOTT = Y)

Element	Comment
XAG4	Quadrilateral Ground Distance A-phase, Zone 4
XAG3	Quadrilateral Ground Distance A-phase, Zone 3
XAG2	Quadrilateral Ground Distance A-phase, Zone 2
XAG1	Quadrilateral Ground Distance A-phase, Zone 1
MAG4	Mho Ground Distance A-phase, Zone 4
MAG3	Mho Ground Distance A-phase, Zone 3
MAG2	Mho Ground Distance A-phase, Zone 2
MAG1	Mho Ground Distance A-phase, Zone 1
XBG4	Quadrilateral Ground Distance B-phase, Zone 4
XBG3	Quadrilateral Ground Distance B-phase, Zone 3
XBG2	Quadrilateral Ground Distance B-phase, Zone 2
XBG1	Quadrilateral Ground Distance B-phase, Zone 1
MBG4	Mho Ground Distance B-phase, Zone 4
MBG3	Mho Ground Distance B-phase, Zone 3
MBG2	Mho Ground Distance B-phase, Zone 2
MBG1	Mho Ground Distance B-phase, Zone 1
XCG4	Quadrilateral Ground Distance C-phase, Zone 4
XCG3	Quadrilateral Ground Distance C-phase, Zone 3
XCG2	Quadrilateral Ground Distance C-phase, Zone 2
XCG1	Quadrilateral Ground Distance C-phase, Zone 1
MCG4	Mho Ground Distance C-phase, Zone 4
MCG3	Mho Ground Distance C-phase, Zone 3
MCG2	Mho Ground Distance C-phase, Zone 2
MCG1	Mho Ground Distance C-phase, Zone 1
MBC4	Mho BC Phase Distance Zone 4, Instantaneous
MBC3	Mho BC Phase Distance Zone 3, Instantaneous
MBC2	Mho BC Phase Distance Zone 2, Instantaneous
MBC1	Mho BC Phase Distance Zone 1, Instantaneous
MAB4	Mho AB Phase Distance Zone 4, Instantaneous
MAB3	Mho AB Phase Distance Zone 3, Instantaneous
MAB2	Mho AB Phase Distance Zone 2, Instantaneous
MAB1	Mho AB Phase Distance Zone 1, Instantaneous
SPOC	Single-Pole Open, Phase C, Instantaneous
SPOB	Single-Pole Open, Phase B, Instantaneous
SPOA	Single-Pole Open, Phase A, Instantaneous
Z1	M1P + Z1G + 67N1 + 67Q1
MCA4	Mho CA Phase Distance Zone 4, Instantaneous
MCA3	Mho CA Phase Distance Zone 3, Instantaneous
MCA2	Mho CA Phase Distance Zone 2, Instantaneous
MCA1	Mho CA Phase Distance Zone 1, Instantaneous

Element	Comment
50HH	Two or Three Phases Over High-Set, Instantaneous
OSTI	Out-of-Step Trip Initiate
50CA	50CA1 + 50CA2 + 50CA3 + 50CA4
50BC	50BC1 + 50BC2 + 50BC3 + 50BC4
50AB	50AB1 + 50AB2 + 50AB3 + 50AB4
Z4	M4P + Z4G + 67N4 + 67Q4
Z3	M3P + Z3G + 67N3 + 67Q3
Z2	M2P + Z2G + 67N2 + 67Q2
RBAD	MIRRORED BITS™ outage duration over threshold
CBAD	MIRRORED BITS channel unavailability over threshold
LBOK	Looped back relay-to-relay communications established and validated
ROK	Relay-to-relay communications established and validated
3PTC	TPC + 3PT
3PTB	TPB + 3PT
3PTA	TPA + 3PT
TOP	Trip During Pole Open Timer is Timing

Note: The ANYTRIP, SPTI, Z1, Z2, Z3, Z4, 3PTC, 3PTB, and 3PTA elements (highlighted) are to be used for annunciation or auxiliary functions (for example, recloser control, SCADA, and indication). These elements should not be used in any trip logic equations (MTU, MTCS or MTO).

Table 2.9 lists the assignment choices for the programmable inputs (excluding the 52A1, 52A2, TCM1, and TCM2 elements) using the **SET G** command. **Section 3: Communications** gives detailed instructions on the use of the **SET G** command. The 52A1, 52A2, TCM1, and TCM2 elements (listed in Table 2.4) are unique due to the fact that they allow a single input to control three functional elements for three-pole trip applications where single-phase information is unavailable. Use inputs LP1 through LP10 for functions you define. These inputs may be used in SELOGIC control equations.

Table 2.9: Assigned Input Statuses

TAR	Assigned Input Status Indicators							
21	LP1	SS3	SS2	SS1	EXT	DT	BT	PT
22	EXTUL	PARC	PARB	PARA	SPT	PTXFR	LP2	LOG
23	LP3	CLOSE	52AC2	52AC1	52AB2	52AB1	52AA2	52AA1
24	LP5	LP4	TCMC2	TCMC1	TCMB2	TCMB1	TCMA2	TCMA1
25	DTA	DTB	DTC	LP6	LP7	LP8	LP9	LP10

Please refer to Contact Input Assignments in this section for the definitions of the inputs listed in Table 2.9.

The following tables show additional SELOGIC control equation variables available in the SEL-321-3 Relay. Table 2.10 lists command-settable Remote Bits, RB1 through RB16. You may set, clear, or pulse the Remote Bits via the **CONTROL** command. These Remote Bits can be used in SELOGIC control equations to design logic which can be set, cleared, or pulsed locally or remotely by entering a command. Refer to *Section 3: Communications* of this instruction manual for an explanation of the **CONTROL** command.

Table 2.10: Remote Bits

TAR	Elements							
26	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1
27	RB16	RB15	RB14	RB13	RB12	RB11	RB10	RB9

Table 2.11: Remote Bit Summary

Element	Comment
RB8	Remote Bit 8
RB7	Remote Bit 7
RB6	Remote Bit 6
RB5	Remote Bit 5
RB4	Remote Bit 4
RB3	Remote Bit 3
RB2	Remote Bit 2
RB1	Remote Bit 1
RB16	Remote Bit 16
RB15	Remote Bit 15
RB14	Remote Bit 14
RB13	Remote Bit 13
RB12	Remote Bit 12
RB11	Remote Bit 11
RB10	Remote Bit 10
RB9	Remote Bit 9

Table 2.12 lists intermediate elements V, W, X, Y, and Z, which can be defined with SELOGIC control equations. The XT, YT, and ZT elements are time delayed pickup and dropout representations of X, Y, and Z, respectively. Use these variables in multiple masks or output equations, or when a general purpose timer is required.

Table 2.12: Intermediate Elements

TAR	Elements							
28	ZT	Z	YT	Y	XT	X	W	V

Table 2.13: Intermediate Element Summary

Element	Comment
ZT	SELOGIC control equations Z Equation Output, Time Delayed
Z	SELOGIC control equations Z Equation Output, Instantaneous
YT	SELOGIC control equations Y Equation Output, Time Delayed
Y	SELOGIC control equations Y Equation Output, Instantaneous
XT	SELOGIC control equations X Equation Output, Time Delayed
X	SELOGIC control equations X Equation Output, Instantaneous
W	SELOGIC control equations W Equation Output, Instantaneous
V	SELOGIC control equations V Equation Output, Instantaneous

Table 2.14 lists internal elements. With the exception of MER, MTO, MTU, and MTCS, these elements are available for testing purposes and are not available for SELOGIC control equations. Use SELOGIC control equations to define MER, MTO, MTU, and MTCS. MER controls triggering of event reports. MTO, MTU, and MTCS establish tripping conditions.

Table 2.14: Internal Elements

TAR	Elements							
29	RAG4	RAG3	RAG2	RAG1	MER	MTO	MTU	MTCS
30	RCG4	RCG3	RCG2	RCG1	RBG4	RBG3	RBG2	RBG1
31	50AL4	50AL3	50AL2	50AL1	VPOLV	N3PT	L3PT	PTRX
32	50CL4	50CL3	50CL2	50CL1	50BL4	50BL3	50BL2	50BL1
33	50G4	50G3	50G2	50G1	50CL	50BL	50AL	*
34	OSB4	OSB3	OSB2	OSB1	50PP4	50PP3	50PP2	50PP1
35	TS	TC	TB	TA	ZLOUT	ZLIN	ILOP	50P
36	SPT_EN	*	*	*	*	52AC	52AB	52AA
37	50AB4	50AB3	50AB2	50AB1	ATPC	ATPB	ATPA	50PPL
38	50CA4	50CA3	50CA2	50CA1	50BC4	50BC3	50BC2	50BC1
39	*	51NR	51QR	51PR	*	*	*	*

Table 2.15: Internal Element Summary

Element	Comment
RAG4	A-phase-Ground Resistance Blinder, Zone 4
RAG3	A-phase-Ground Resistance Blinder, Zone 3
RAG2	A-phase-Ground Resistance Blinder, Zone 2
RAG1	A-phase-Ground Resistance Blinder, Zone 1
MER	Mask to Trigger Event Report Variable
MTO	Mask for Trip - Breaker Open Variable
MTU	Mask for Trip Unconditional Variable
MTCS	Mask for Trip Communications Scheme Variable
RCG4	C-phase-Ground Resistance Blinder, Zone 4
RCG3	C-phase-Ground Resistance Blinder, Zone 3
RCG2	C-phase-Ground Resistance Blinder, Zone 2
RCG1	C-phase-Ground Resistance Blinder, Zone 1
RBG4	B-phase-Ground Resistance Blinder, Zone 4
RBG3	B-phase-Ground Resistance Blinder, Zone 3
RBG2	B-phase-Ground Resistance Blinder, Zone 2
RBG1	B-phase-Ground Resistance Blinder, Zone 1
50AL4	A-phase Supervisory Overcurrent, Zone 4
50AL3	A-phase Supervisory Overcurrent, Zone 3
50AL2	A-phase Supervisory Overcurrent, Zone 2
50AL1	A-phase Supervisory Overcurrent, Zone 1
VPOLV	Positive-Sequence Polarizing Voltage Valid
N3PT	Not Three-Pole Trip
L3PT	Line Three-Pole Trip
PTRX	Permissive Trip Received
50CL4	C-phase Supervisory Overcurrent, Zone 4
50CL3	C-phase Supervisory Overcurrent, Zone 3
50CL2	C-phase Supervisory Overcurrent, Zone 2
50CL1	C-phase Supervisory Overcurrent, Zone 1
50BL4	B-phase Supervisory Overcurrent, Zone 4
50BL3	B-phase Supervisory Overcurrent, Zone 3
50BL2	B-phase Supervisory Overcurrent, Zone 2
50BL1	B-phase Supervisory Overcurrent, Zone 1
50G4	Residual Overcurrent Supervision, Zone 4
50G3	Residual Overcurrent Supervision, Zone 3
50G2	Residual Overcurrent Supervision, Zone 2
50G1	Residual Overcurrent Supervision, Zone 1
50CL	Any C-phase Overcurrent Supervision Element Picked Up
50BL	Any B-phase Overcurrent Supervision Element Picked Up
50AL	Any A-phase Overcurrent Supervision Element Picked Up
*	Reserved For Future Use

Element	Comment
OSB4	Out-of-Step Block, Zone 4
OSB3	Out-of-Step Block, Zone 3
OSB2	Out-of-Step Block, Zone 2
OSB1	Out-of-Step Block, Zone 1
50PP4	Phase-to-Phase Supervisory Overcurrent, Zone 4
50PP3	Phase-to-Phase Supervisory Overcurrent, Zone 3
50PP2	Phase-to-Phase Supervisory Overcurrent, Zone 2
50PP1	Phase-to-Phase Supervisory Overcurrent, Zone 1
TS	Trip Suspicion Condition
TC	C-phase Trip
TB	B-phase Trip
TA	A-phase Trip
ZLOUT	Load Element - Load Out
ZLIN	Load Element - Load In
ILOP	Internal Loss-of-Potential Condition
50P	Single-Phase REJO Overcurrent Element
SPT_EN	SPTE asserted or ESPT = Y or Y1
*	Reserved For Future Use
*	Reserved For Future Use
*	Reserved For Future Use
*	Reserved For Future Use
52AC	Breaker(s) Auxiliary Contact Pole C
52AB	Breaker(s) Auxiliary Contact Pole B
52AA	Breaker(s) Auxiliary Contact Pole A
50AB4	AB Overcurrent Supervision, Zone 4
50AB3	AB Overcurrent Supervision, Zone 3
50AB2	AB Overcurrent Supervision, Zone 2
50AB1	AB Overcurrent Supervision, Zone 1
ATPC	Assert Trip C
ATPB	Assert Trip B
ATPA	Assert Trip A
50PPL	Current latch for DCB scheme after polarizing memory expires.
50CA4	CA Overcurrent Supervision, Zone 4
50CA3	CA Overcurrent Supervision, Zone 3
50CA2	CA Overcurrent Supervision, Zone 2
50CA1	CA Overcurrent Supervision, Zone 1
50BC4	BC Overcurrent Supervision, Zone 4
50BC3	BC Overcurrent Supervision, Zone 3
50BC2	BC Overcurrent Supervision, Zone 2
50BC1	BC Overcurrent Supervision, Zone 1

Element	Comment
*	Reserved For Future Use
51NR	Residual Time-Overcurrent Element Resetting
51QR	Negative-Sequence Time-Overcurrent Element Resetting
51PR	Phase Time-Overcurrent Element Resetting
*	Reserved For Future Use
*	Reserved For Future Use
*	Reserved For Future Use
*	Reserved For Future Use

Table 2.16 shows the status indicators for the input and output contacts for one I/O board relays.
Table 2.17 shows status indicators for the input and output contacts for two I/O board relays.

Table 2.16: Input/Output Contact Targets (One I/O Board Version)

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
43	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
44	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
45	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

Table 2.17: Input/Output Contact Targets (Two I/O Board Version)

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	OUT17	OUT18	OUT19	OUT20	OUT21	OUT22	OUT23	OUT24
43	OUT25	OUT26	OUT27	OUT28	OUT29	OUT30	OUT31	OUT32
44	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
45	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
46	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
47	IN16	IN15	IN14	IN13	IN12	IN11	IN10	IN9
48	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

**Table 2.18: Input/Output Contact Targets Summary
(One I/O Board Version and Two I/O Board Version)**

Element	Comment
MIRBRK	Break detected on MIRRORED BITS communication channel
MIRFRA	Framing error detected on MIRRORED BITS communication channel
MIRPAR	Parity error detected on MIRRORED BITS communication channel
MIROVR	Data received too quickly on MIRRORED BITS communication channel
MIRIN	Too much idle time detected on MIRRORED BITS communication channel
MIRSYC	Synchronization request received on MIRRORED BITS communication channel
MIRDAT	Data error detected on MIRRORED BITS communication channel
MIRDIS	MIRRORED BITS not enabled or relay is disabled

TRIP LOGIC

The relay contains both three-pole and single-pole tripping logic.

The user programs the desired trip output signals to output contacts using SELOGIC control equations.

The user selects relay elements to trip:

- Unconditionally,
- For switch-onto-fault actions,
- And with communications assistance.

It also includes five choices for deasserting the trip output signals.

Selecting Single-Pole or Three-Pole Tripping Logic

The relay uses single-pole tripping logic if:

- Single-pole trip enable setting ESPT = Y, Y1, or
- Programmable input variable SPTE is asserted.

Otherwise, the relay uses three-pole tripping logic.

Tripping Output Signals

There are four tripping output variables, which can be programmed to drive output contacts for tripping breakers: TPA, TPB, TPC, and 3PT.

Variables TPA, TPB, and TPC are phase-dependent tripping signals, designed to control the individual poles of a circuit breaker in single-pole tripping schemes.

Variable 3PT indicates three-pole trips.

Single-Pole Tripping Conditions

When the single-pole tripping logic is active, the SEL-321 Relay trips single-pole for the following trip conditions:

- Zone 1 SLG faults detected by the ground distance elements
- Zone 2 SLG faults detected by the ground distance elements and permitted to trip through the communications scheme logic.
- DTA, DTB, DTC assigned and asserted.
- See the special single-pole tripping appendix, *Appendix E*, for other schemes.

All other tripping conditions (including switch-onto-fault, time-step trips, overcurrent trips, and trips during the SPO condition) cause three-pole trips.

Selecting Elements to Trip

The user selects the desired relay elements for unconditional trip, for switch-onto-fault, and for tripping with communications assistance.

The user programs three variables with the desired elements, using the **SET L** command: MTU, MTO, and MTCS.

Note: The ANYTRIP, SPTI, Z1, Z2, Z3, Z4, 3PTC, 3PTB, and 3PTA elements are to be used for annunciation or auxiliary functions (for example, recloser control, SCADA, and indication). These elements should not be used in any trip logic equations (MTU, MTCS or MTO).

MTU (Unconditional Trip Variable)

Include Zone 1 and time-delayed protective elements in this equation, for example:

$$MTU = M1P + Z1G + M2PT + Z2GT + M3PT + Z3GT + 51NT$$

MTO (Switch-Onto-Fault Trip Variable)

Include more-sensitive elements for instantaneous and sensitive tripping when the breaker is first closed onto a fault. For example, to trip instantaneously on Zone 2 elements:

$$MTO = M2P + Z2G$$

MTCS (Communications-Scheme Trip Variable)

Set the combination of overreaching elements which can trip only if the communications logic permits (on the basis of POTT permission received, for example). If Zone 2 elements are the desired overreaching elements, then set:

$$MTCS = M2P + Z2G$$

Unlatch Logic Selections

This logic deasserts asserted tripping elements.

One of five unlatch options is chosen with the TULO (Trip Unlatch Option) setting:

<u>Option</u>	<u>Setting</u>	<u>Description</u>
N	TULO = N	Time delayed dropout extension
1	TULO = 1	Undercurrent unlatch
2	TULO = 2	Breaker auxiliary unlatch
3	TULO = 3	Requires conditions of Options 1 and 2
4	TULO = 4	Unlatch when input assigned to EXTUL asserts

Supporting Drawings: Figure 2.45 through Figure 2.47.

MULTIPLE SETTING GROUPS

The relay has six independent setting groups. Each group is a complete relay setting.

Select groups by two means: contact inputs or the **GROUP** command. Inputs assigned to SS1 - SS3 control changing group settings by control switches. Input functions not assigned are treated as zero.

Table 2.19 shows what combinations of asserted logic inputs select which group.

Table 2.19: Setting Group Selections

SS1	SS2	SS3	Group Selected
0	0	0	Group designated by the GROUP command
1	0	0	Group 1
0	1	0	Group 2
1	1	0	Group 3
0	0	1	Group 4
1	0	1	Group 5
0	1	1	Group 6
1	1	1	Group designated by the GROUP command

Active Groups and Group Variables

The relay only uses one group setting at a time. The other setting groups are stored in nonvolatile memory.

The setting group used at any one time is called the Active Group. Contact inputs control the Active Group selection. The setting group selected by the **GROUP** command is labeled Group Variable. If the inputs select Group Variable, the **GROUP** command controls the setting group selection.

Global Settings

Inputs	SS1 - SS3	Assign to any input. Assignment order is not important.
Timed Group Reset	TGR	Minimum delay that inputs (or input) selecting a new setting group must be asserted before group is switched.

METERING

Units:	Primary, computed from secondary inputs times instrument transformer ratio settings.
Accuracy:	$\pm 1.0\%$ of nominal input at rated voltage and current.

SYSTEM FREQUENCY TRACKING

The relay adjusts its sampling rate by monitoring the system frequency using a zero-crossing detector on the A-phase voltage input. The relay can be ordered with a nominal frequency of either 60 or 50 Hz.

The frequency tracking range is 55 to 63 Hz for 60 Hz relays and 45 to 55 Hz for 50 Hz relays. When the relay is first powered on, it assumes the nominal frequency.

Accuracy:	± 0.028 Hz at 60 Hz
	± 0.020 Hz at 50 Hz

FAULT LOCATOR

Fault locations are computed from data stored in the event report.

Select the fault locating method in the relay settings: set LOCAT = Y when there are current sources in front of the relay location, and set LOCAT = R for radial applications. Set LOCAT = N to disable the fault location feature.

One of the elements in Table 2.20 must assert in the event report data for the relay to calculate a fault location.

Table 2.20: Fault Location Triggering Elements

Fault Type	Elements Which Must be Asserted
Phase-to-Phase Faults	M1P - M4P
Three-Phase Faults	M1P - M4P
Phase-to-Phase-Ground Faults	M1P - M4P
Line-Ground Faults	Z1G - Z4G, 67N1 - 67N4, 51NP

Fault locations are calculated from the data in the longest contiguous sequence of rows where at least one of the elements in Table 2.20 is asserted.

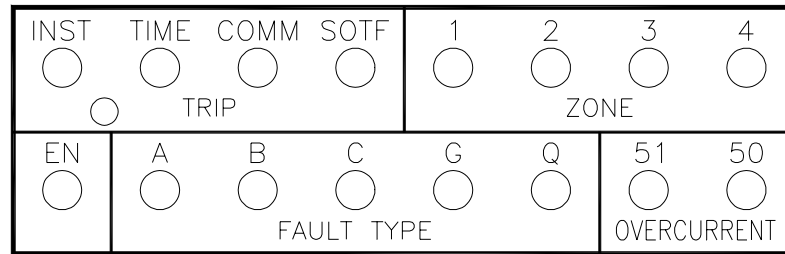
If the longest contiguous sequence duration is less than one-half cycle, a single-pole open condition is detected (SPO is asserted), or if none of the elements in Table 2.20 assert, the relay does not calculate a fault location. For these cases, \$\$\$\$\$\$ is reported for a fault location.

FRONT-PANEL TARGETS

The relay presents targets by two means:

- A two row, 16 column back lighted LCD display
- Two rows of eight target/indicator LEDs

The LCD display shows the detailed information pertaining to a fault detected by the relay, displaying metering information, relay self-test status information, etc. The LEDs designations are shown in Figure 2.3.



DWG. 1015197C

Figure 2.3: SEL-321 Front-Panel Targeting

General Target LED Description

Under normal operating conditions, only the enable (EN) LED is illuminated. Other LEDs illuminate when the relay trips. These LEDs are latching until reset by pressing the Target Reset Button, executing the **TARGET R** command, or removing power from the relay.

When a new trip occurs, the targets clear and display the latest tripping target.

Only elements masked for tripping illuminate the front-panel target LEDs for a tripping event; unused elements do not target. Refer to the following list of target illumination conditions for the rising edge of TPA, TPB, TPC, or 3PT.

Targets Definition and Conditions for Illumination

INST **Definition: Instantaneous tripping event.** Illuminates if any element of Table 2.21 is used in MTU and asserts for less time than the ITTD time delay setting (Instantaneous Target Time) when TPA, TPB, TPC, or 3PT assert. The INST target shall also illuminate if TPA, TPB, TPC, or 3PT assert and the other tripping targets (TIME, COMM, or SOTF) do not illuminate.

TIME **Definition: Time-delayed tripping event.** Illuminates if any element of Table 2.21 is used in MTU and asserts for more time than ITTD when TPA, TPB, TPC, or 3PT assert.

Table 2.21: INST and TIME LED Qualifying Elements

M1P - M4P	Z1G - Z4G
67N1 - 67N4	67Q1 - 67Q4
51PT	51NT
51QT	

COMM **Definition: Communications scheme assisted tripping event.** Tripping is a result of the communications-assisted trip logic.

SOTF **Definition: Switch-onto-fault tripping event.** SOTFE is asserted.

ZONE 1 **Definition: Zone 1 or Level 1 element asserted.** Illuminates if any of the following elements are asserted: M1P, Z1G, 67N1, or 67Q1

ZONE 2 **Definition: Zone 2 or Level 2 element asserted.** Illuminates if any of the following elements assert and like elements of shorter reach are not asserted: M2P, Z2G, 67N2, or 67Q2.

ZONE 3 **Definition: Zone 3 or Level 3 element asserted.** Illuminates if any of the following elements assert and like elements of shorter reach are not asserted: M3P, Z3G, 67N3, or 67Q3.

ZONE 4 **Definition: Zone 4 or Level 4 element asserted.** Illuminates if any of the following elements assert and like elements of shorter reach are not asserted: M4P, Z4G, 67N4, or 67Q4.

EN **Definition: Relay enabled** (not latching).

A **Definition: A-phase is involved.** Illuminates if any of the following distance elements are asserted:

- MAG1 - MAG4
- XAG1 - XAG4
- MAB1 - MAB4 if $2I_{AB} < 2I_{BC}$ and $2I_{CA}$ and $|I_2| > |0.3 \cdot I_1|$
- M1P - M4P and $|I_2| < |0.3 \cdot I_1|$

B **Definition: B-phase is involved.** Illuminates if any of the following distance elements are asserted:

- MBG1 - MBG4
- XBG1 - XBG4
- MBC1 - MBC4 if $2I_{BC} < 2I_{AB}$ and $2I_{CA}$ and $|I_2| < |0.3 \cdot I_1|$
- M1P - M4P and $|I_2| < |0.3 \cdot I_1|$

- C** **Definition: C-phase is involved.** Illuminates if any of the following distance elements are asserted:
- MCG1 - MCG4
 - XCG1 - XCG4
 - MCA1 - MCA4 if $2I_{CA} < 2I_{AB}$ and $2I_{BC}$ and $|I_2| < |0.3 \cdot I_1|$
 - M1P - M4P and $|I_2| < |0.3 \cdot I_1|$
- G** **Definition: Ground is involved.** Illuminates if any of the following elements are asserted:
- Z1G - Z4G
 - 67N1 - 67N4
- Q** **Definition: Negative-sequence current detected.** Illuminates if 51QP, or 50Q1 - 50Q4 are asserted.
- 51** **Definition: Time-overcurrent element timed out.** Illuminates if 51PT, 51QT, or 51NT are asserted.
- 50** **Definition: Level 1 - 4, high-set, or Stub Logic overcurrent elements are asserted.** Illuminates if any of the following elements listed are asserted:
- 67N1 * ZONE 1 LED conditions satisfied
 - 67N2 * ZONE 2 LED conditions satisfied
 - 67N3 * ZONE 3 LED conditions satisfied
 - 67N4 * ZONE 4 LED conditions satisfied
 - 67Q1 * ZONE 1 LED conditions satisfied
 - 67Q2 * ZONE 2 LED conditions satisfied
 - 67Q3 * ZONE 3 LED conditions satisfied
 - 67Q4 * ZONE 4 LED conditions satisfied
 - 50H
 - 50HH
 - 50MF

COMMUNICATIONS PORTS SPECIFICATIONS

Table 2.22 gives specifications for the three serial communications ports and the time-code input.

Table 2.22: Communications Ports Specifications

	Port 1	Port 2	Port 3	IRIG-B	Comment
Description					
Type	EIA-232			Time Code	
Protocol	SEL LMD		N/A		SEL = Standard Communications LMD = Distributed Port Switch Protocol (See <i>Appendix F</i>) MB = Relay-to-Relay digital communications only one port (See <i>Appendix G</i>) DNP = Distributed Network Protocol (See <i>Appendix I</i>)
	MB				
	DNP				
Baud Rate	300 1200 2400 (Default) 4800 9600 19.2 k 38.4 k		300 1200 2400 (default) 4800 9600 19.2 k	N/A	
Data Bits	8 (Default) 7 6		8	N/A	
Parity	N (Default) E O		N	N/A	N = None E = Even O = Odd
Stop Bits	1 (Default) 2		1	N/A	0 = Port does not timeout
Time Out	0-30 Minutes			N/A	
	0 (Default)	5 (Default)			
Auto	Y N			N/A	Y = Designated auto N = Not auto
	N (Default)	Y (Default)			
RTS_CTS	Y N (Default) MBT		N/A	N/A	Y = Enable RTS/CTS hardware handshake N = Disable RTS/CTS hardware handshake MBT = MBT9600 modem used for Relay-to-Relay Digital Communications

	Port 1	Port 2	Port 3	IRIG-B	Comment
Description					
Type	EIA-232			Time Code	
FAST_OP	Y N (Default)			N/A	Y = Enable fast operate command processing N = Disable fast operate command processing
Connector Pin Assignments					
1	+5 Vdc		N/C	+5 Vdc	N/C = No connection
2	RXD			+IRIG-B	RXD = Receive data input
3	TXD			-IRIG-B	TXD = Transmit data output
4	+12 Vdc		N/C	N/C	+12 Vdc @ 4 mA (max)
5	GND			GND	Signal Ground
6	N/C			N/C	No connection
7	RTS		RTS always asserted	N/C	RTS = Data buffer full when asserted Port 3 always asserted
8	CTS		N/C	N/C	N/C = No connection CTS = Transmit if asserted
9	GND			GND	Signal ground

Internal Time Clock Time-Code Synchronization Specifications

The relay internal time clock is the time reference for all relay functions. Connect the rear panel port marked DEMODULATED IRIG-B to synchronize to an external time source.

Without an external IRIG-B time-code source, the internal time clock drift rate is ± 0.086 sec./day. With IRIG-B, the internal clock is synchronized to within ± 1 ms of the time source.

Note that without an external IRIG-B time-code source, the date and time must be set whenever the relay power is cycled. See **Section 6: Installation** for further information.

SELF-TESTS

The relay runs a variety of self-tests. Table 2.23 summarizes the tests and their outputs and parameters. Some tests have warning and failure states, others only failure states. The relay generates a status report after any change in self-test status. This report may be retrieved using the **STATUS** command. Table 2.23 shows relay actions for any self-test condition: warning (W) or failure (F).

Table 2.23: Self-Test Summary

Self-Test	Limits		Message	Protection Disabled	ALARM Output
RAM	---		OK or U1 - U8	Yes	Latched
ROM	---		OK or U28, U29, U30, U31	Yes	Latched
CR_RAM	---		OK or GROUP 1 - 6 LOGIC 1 - 6 GLOBAL CAL CODE	Yes	Latched
SETTINGS	---		OK or GROUP LOGIC CAL GLOBAL	Yes	Latched
EEPROM	---		OK or GROUP 1 - 6 LOGIC 1 - 6 GLOBAL CAL CODE	Yes	Latched
A/D	---		OK/FAIL	Yes	Latched
+5 V PS	4.8	5.2	W	No	Latched
	4.65	5.4	F	Yes	
±5 V REG	±4.8	±5.25	W	No	Latched
	±4.5	±5.5	F	Yes	
±12 V REG	±11.5	±12.5	W	No	Latched
	±11.2	±14.0	F	Yes	
±15 V PS	±14.6	±15.60	W	No	Latched
	±14.0	±16.0	F	Yes	
TEMP	-40°C	+80°C	W	No	Latched
	-50°C	+95°C	F	Yes	
CHANNEL OFFSETS	30 mV		W	No	Pulsed
MASTER OFFSET	20 mV		W	No	Pulsed
	30 mV		F	Yes	Latched

TECHNICAL SPECIFICATIONS (1A NOMINAL RELAY)

General Element Ranges and Accuracy

Phase Mho Distance	Secondary Reach Setting Range:	0.25 - 320 Ω at the line angle
Ground Mho Distance	Secondary Reach Setting Range:	0.25 - 320 Ω at the line angle
	$ k_{01} $ and $ k_0 $ setting range*:	0 - 4
	Angle k_{01} and k_0 setting range*:	$\pm 180^\circ$ in 0.1° steps
	* Note: Same setting applies to Quadrilateral Ground Distance.	
Quadrilateral Distance	Secondary Reactive Reach:	0.25 - 320 Ω
	Secondary Resistive Reach:	0.25 - 250 Ω
	Nonhomogeneous Factor (T, degrees):	$\pm 20^\circ$ in 0.1° steps
Out-of-Step Distance	Secondary Reactance Setting Range:	$\pm 480 \Omega$
	Secondary Resistance Setting Range:	$\pm 350 \Omega$
Load Encroachment Detection	Secondary Impedance Setting Range:	0.25 - 320 Ω
	Forward Load Angle Setting (in degrees):	-90° to $+90^\circ$
	Reverse Load Angle Setting (in degrees):	$+90^\circ$ to 270°
Distance Element Accuracy	Secondary Steady-State Error:	$\pm 5\%$ of set reach $\pm 0.05 \Omega$ at line angle (LA) for $V > 5 \text{ V}$ and $I > 0.4 \text{ A}$
		$\pm 10\%$ of set reach $\pm 0.05 \Omega$ at LA for $1 \text{ V} < V < 5 \text{ V}$ and $0.2 \text{ A} < I < 0.4 \text{ A}$
	Transient Overreach Error:	$\pm 5\%$ of set reach, plus steady-state error
Negative-Sequence Directional Element	Secondary Positive-Sequence Current Restraint Range:	0.02 - 0.5
	Secondary Forward Directional Current Supervision:	0.05 - 1 A
	Secondary Reverse Directional Current Supervision:	0.05 - 1 A
	Secondary Forward Directional Impedance Setting:	$\pm 320 \Omega$
	Secondary Reverse Directional Impedance Setting:	$\pm 320 \Omega$
Supervisory Overcurrent		
Phase	Secondary Pickup Setting Range:	0.1 - 20 A, $\pm 0.01 \text{ A}$, $\pm 3\%$ of setting
	• Supervises ground distance	
Phase-to-Phase	Secondary Pickup Setting Range:	0.2 - 34 A, $\pm 0.01 \text{ A}$, $\pm 3\%$ of setting
	• Supervises phase distance	
Positive-Sequence	Secondary Pickup Setting Range:	0.2 - 20 A, $\pm 0.01 \text{ A}$, $\pm 3\%$ of setting
	• Supervises OOS logic	
Residual	Secondary Pickup Setting Range:	0.1 - 20 A, $\pm 0.01 \text{ A}$, $\pm 3\%$ of setting
	Transient Overreach:	$\pm 5\%$ of pickup
	• Supervises ground distance	

Directional Time-Overcurrent	Selectable Curve Shape:	Moderately inverse (US) or Longtime Standby (IEC) Inverse (US) or Standard Inverse (IEC) Very Inverse (US or IEC) Extremely Inverse (US or IEC)
	Phase Pickup setting range:	0.1 A - 3.4 A, ± 0.05 A, $\pm 3\%$ of setting
	Neg.-Seq. Pickup setting range:	0.1 A - 3.2 A, ± 0.05 A, $\pm 3\%$ of setting
	Residual Pickup setting range:	0.1 A - 3.2 A, ± 0.05 A, $\pm 3\%$ of setting
	Time Dial setting range:	0.5 - 15 in 0.01 steps (US) 0.05 - 1 in 0.01 steps (IEC)
	Timing:	$\pm 4\%$ and ± 1.5 cycles for current magnitudes between 2 and 20 multiples of pickup.
Nondirectional Residual/Neg.-Seq. Overcurrent	Secondary Pickup setting range:	0.05 - 16 A, ± 0.01 A, $\pm 3\%$ of setting
	Transient Overreach:	$\pm 5\%$ of pickup
Overvoltage	Pickup:	0 - 150 V, $\pm 5\%$ of setting, ± 1 V
	Transient Overreach:	$\pm 5\%$ of pickup
Undervoltage	Pickup:	0 - 100 V, $\pm 5\%$ of setting, ± 1 V
	Transient Overreach:	$\pm 5\%$ of pickup
Miscellaneous Timers	Step Distance	
	Time Delay:	0 - 2000 cycles
	Communications Scheme	
	Time Delay:	0 - 2000 cycles
	DCB Carrier Coordination	
	Time Delay:	0 - 60 cycles
	Short Delay	
	Time Delay:	0 - 2000 cycles
	Long Delay	
	Time Delay:	0 - 8000 cycles
	Loss-of-Potential Set	
	Time Delay:	1 - 60 cycles

TECHNICAL SPECIFICATIONS (5A NOMINAL RELAY)

General Element Ranges and Accuracy

Phase Mho Distance	Secondary Reach Setting Range:	0.05 - 64 Ω at the line angle
Ground Mho Distance	Secondary Reach Setting Range: $ k_{01} $ and $ k_0 $ setting range*: Angle k_{01} and k_0 setting range*:	0.05 - 64 Ω at the line angle 0 - 4 $\pm 180^\circ$ in 0.1° steps
* Note: Same setting applies to Quadrilateral Ground Distance.		
Quadrilateral Distance	Secondary Reactive Reach: Secondary Resistive Reach: Nonhomogeneous Factor (T, degrees):	0.05 - 64 Ω 0.05 - 50 Ω $\pm 20^\circ$ in 0.1° steps
Out-of-Step Distance	Secondary Reactance Setting Range: Secondary Resistance Setting Range:	$\pm 96 \Omega$ $\pm 70 \Omega$
Load Encroachment Detection	Secondary Impedance Setting Range: Forward Load Angle Setting (in degrees): Reverse Load Angle Setting (in degrees):	0.05 - 64 Ω -90° to $+90^\circ$ $+90^\circ$ to 270°
Distance Element Accuracy	Secondary Steady-State Error: $\pm 5\%$ of set reach $\pm 0.01 \Omega$ at line angle (LA) for $V > 5 \text{ V}$ and $I > 2 \text{ A}$ $\pm 10\%$ of set reach $\pm 0.01 \Omega$ at LA for $1 \text{ V} < V < 5 \text{ V}$ and $1 \text{ A} < I < 2 \text{ A}$ Transient Overreach Error: $\pm 5\%$ of set reach, plus steady-state error	
Negative-Sequence Directional Element	Secondary Positive-Sequence Current Restraint Range: Secondary Forward Directional Current Supervision: Secondary Reverse Directional Current Supervision: Secondary Forward Directional Impedance Setting: Secondary Reverse Directional Impedance Setting:	0.02 - 0.5 0.25 - 5 A 0.25 - 5 A $\pm 64 \Omega$ $\pm 64 \Omega$
Supervisory Overcurrent		
Phase	Secondary Pickup Setting Range: • Supervises ground distance	0.5 - 100 A, $\pm 0.05 \text{ A}$, $\pm 3\%$ of setting
Phase-to-Phase	Secondary Pickup Setting Range: • Supervises phase distance	1.0 - 170 A, $\pm 0.05 \text{ A}$, $\pm 3\%$ of setting
Positive-Sequence	Secondary Pickup Setting Range: • Supervises OOS logic	1.0 - 100 A, $\pm 0.05 \text{ A}$, $\pm 3\%$ of setting
Residual	Secondary Pickup Setting Range: Transient Overreach: • Supervises ground distance	0.5 - 100 A, $\pm 0.05 \text{ A}$, $\pm 3\%$ of setting $\pm 5\%$ of pickup

Directional Time-Overcurrent	Selectable Curve Shape:	Moderately inverse (US) or Longtime Standby (IEC) Inverse (US) or Standard Inverse (IEC) Very Inverse (US or IEC) Extremely Inverse (US or IEC)
	Phase Pickup setting range:	0.5 A - 16 A, ± 0.05 A, $\pm 3\%$ of setting
	Neg.-Seq. pickup setting range:	0.5 A - 16 A, ± 0.05 A, $\pm 3\%$ of setting
	Residual Pickup setting range:	0.5 A - 16 A, ± 0.05 A, $\pm 3\%$ of setting
	Time Dial setting range:	0.5 - 15 in 0.01 steps (US) 0.05 - 1 in 0.01 steps (IEC)
	Timing:	$\pm 4\%$ and ± 1.5 cycles for current magnitudes between 2 and 20 multiples of pickup.
Nondirectional Residual/Neg.-Seq. Overcurrent	Secondary Pickup setting range:	0.25 - 80 A, ± 0.05 A, $\pm 3\%$ of setting
	Transient Overreach:	$\pm 5\%$ of pickup
Overvoltage	Pickup:	0 - 150 V, $\pm 5\%$ of setting, ± 1 V
	Transient Overreach:	$\pm 5\%$ of pickup
Undervoltage	Pickup:	0 - 100 V, $\pm 5\%$ of setting, ± 1 V
	Transient Overreach:	$\pm 5\%$ of pickup
Miscellaneous Timers	Step Distance	
	Time Delay:	0 - 2000 cycles
	Communications Scheme	
	Time Delay:	0 - 2000 cycles
	DCB Carrier Coordination	
	Time Delay:	0 - 60 cycles
	Short Delay	
	Time Delay:	0 - 2000 cycles
	Long Delay	
	Time Delay:	0 - 8000 cycles
	Loss-of-Potential Set	
	Time Delay:	1 - 60 cycles

GENERAL SPECIFICATIONS

Voltage Inputs 67 V_{L-N}, three-phase four-wire connection. 150 V_{L-N} continuous (connect any voltage from 0 to 150 Vac). 365 Vac for 10 seconds.
Burden: 0.13 VA @ 67 V; 0.45 VA @ 120 V.

Current Inputs 5 A nominal: 15 A continuous, 500 A for 1 second, linear to 100 A symmetrical. 1250 A for 1 cycle.
Burden: 0.27 VA @ 5 A, 2.51 VA @ 15 A.

1 A nominal: 3 A continuous, 100 A for 1 second, linear to 20 A symmetrical. 250 A for 1 cycle.
Burden: 0.13 VA @ 1 A, 1.31 VA @ 3 A.

Output Contacts **Standard:**

Per *IEC 255-0-20 : 1974*, using the simplified method of assessment

6 A continuous carry

30 A make per *IEEE C37.90 : 1989*

100 A for one second

270 Vac/360 Vdc MOV for differential surge protection.

Pickup time: < 5 ms

Dropout time: < 8 ms

Breaking Capacity (L/R = 40 ms):

48 V	0.5 A	10,000 operations
------	-------	-------------------

125 V	0.3 A	10,000 operations
-------	-------	-------------------

250 V	0.2 A	10,000 operations
-------	-------	-------------------

Cyclic Capacity (L/R = 40 ms):

48 V	0.5 A	2.5 cycles per second
------	-------	-----------------------

125 V	0.3 A	2.5 cycles per second
-------	-------	-----------------------

250 V	0.2 A	2.5 cycles per second
-------	-------	-----------------------

High-current interrupting option:

6 A continuous carry

30 A make per *IEEE C37.90 : 1989*

330 Vdc MOV for differential surge protection

Pickup time: < 5 ms

Dropout time: < 8 ms

Breaking Capacity: 10 A 10,000 operations

48 and 125 V	(L/R = 40 ms)
--------------	---------------

250 V	(L/R = 20 ms)
-------	---------------

Cyclic Capacity: 10 A 4 cycles in 1 second, followed by 2 minutes
idle for thermal dissipation

48 and 125 V	(L/R = 40 ms)
--------------	---------------

250 V	(L/R = 20 ms)
-------	---------------

Note: Do not use high-current interrupting output contacts to switch ac control signals. These outputs are polarity dependent.

Fast high-current interrupting option:

6 A continuous carry

30 A make per *IEEE C37.90 : 1989*

330 Vdc MOV for differential surge protection

Pickup time: < 200 μ s

Dropout time: < 8 ms (typical)

Breaking Capacity: 10 A 10,000 operations

48 and 125 V (L/R = 40 ms)

250 V (L/R = 20 ms)

Cyclic Capacity: 10 A 4 cycles in 1 second, followed by 2 minutes
idle for thermal dissipation

48 and 125 V (L/R = 40 ms)

250 V (L/R = 20 ms)

Note: Fast high-current interrupting output contacts are **not** polarity dependent.

See *Appendix H* for further details.

**Optoisolated
Input Ratings**

Standard fixed inputs (operating voltage shown, nominal input current is 4 mA):

24 Vdc: 15 - 30 Vdc

48 Vdc: 30 - 60 Vdc

125 Vdc: 80 - 150 Vdc

250 Vdc: 150 - 300 Vdc

Fixed level-sensitive inputs (nominal input current is 4 mA):

48 Vdc: on for 38.4 - 60 Vdc; off below 28.8 Vdc

125 Vdc: on for 105 - 150 Vdc; off below 75 Vdc

250 Vdc: on for 200 - 300 Vdc; off below 150 Vdc

Time-Code Input

Relay accepts demodulated IRIG-B time-code input

Communications

Two rear panel and one front-panel EIA-232 serial communications ports.

Power Supply

Rated: 125/250 Vdc or Vac

Range: 85 - 350 Vdc or 85 - 264 Vac

Burden: < 25 W

Rated: 48/125 Vdc or 125 Vac

Range: 38 - 200 Vdc or 85 - 140 Vac

Burden: < 25 W

Rated: 24/48 Vdc

Range: 18 - 60 Vdc polarity dependent

Burden: < 25 W

Dimensions

One I/O Board: 5.22" H x 19" W x 11.66" D (133 mm x 483 mm x 296 mm)

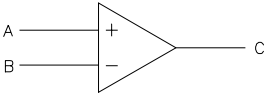

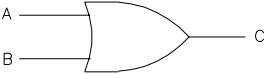


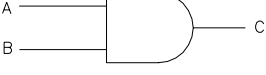
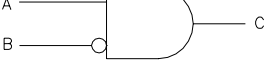
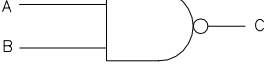
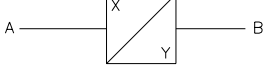
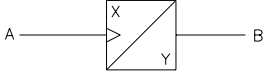
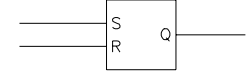

Two I/O Boards: 6.97" H x 19" W x 11.66" D (177 mm x 483 mm x 296 mm)

**Dielectric
Strength**

V, I inputs: 2500 Vac for 10 seconds

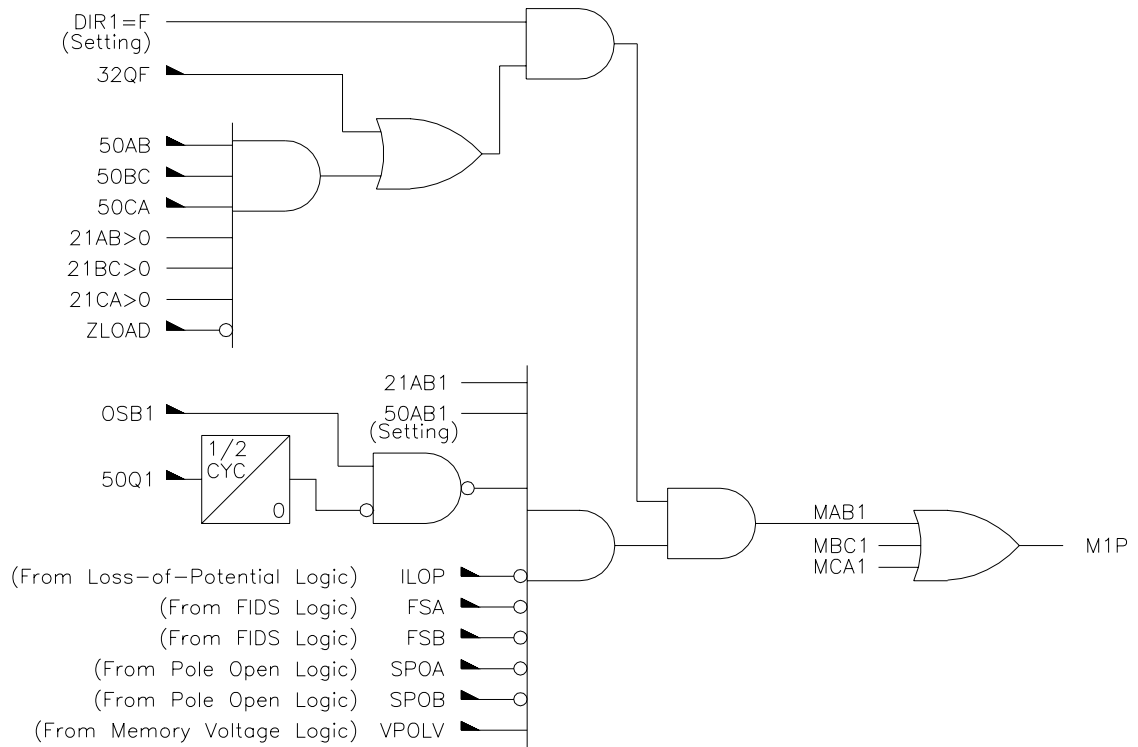
Other: 3000 Vdc for 10 seconds (excludes EIA-232)

Operating Temp.	-40° to 185°F (-40° to +85°C)
Environment	<i>IEC 68-2-30</i> Temperature/Humidity Cycle Test - six day (type tested)
Interference Tests	<i>IEEE C37.90</i> SWC Test (type tested) <i>IEC 255-22-1</i> 1 MHz Burst Disturbance (type tested) <i>IEC 801-4</i> Electrical Fast Transient/Burst (type tested)
Impulse Tests	<i>IEC 255-5</i> 0.5 joule 5000 volt test (type tested) <i>IEC 1000-4-5</i> Installation Class 4 (type tested)*
	<p>* Note: Using the following communications cables: SEL-C274, SEL-C274 FZ/FD (without IRIG) SEL-C238, SEL-C238 FZ/FD (with IRIG)</p>
RFI Tests	<i>IEEE C37.90.2 IEEE Trial-Use Standard, Withstand Capability of Relay Systems to Radiated Electromagnetic Interference from Transceivers.</i> 10 V/M. <u>Exceptions:</u> 5.5.2 (2) Performed with 200 frequency steps per octave 5.5.3 <i>Digital Equipment Modulation Test</i> not performed 5.5.4 Test signal turned off between frequency steps to simulate keying <i>IEC 255-22-3</i> Radiated EMI Test (type tested) <u>Exception:</u> 4.3.2.2 Frequency sweep approximated with 200 frequency steps per octave
Vibration and Shock Test	<i>IEC 255-21-1</i> and -2, Class 1 Test (type tested) <u>Exception:</u> 4.1.4 Vibration Response Amplitude Tolerance increased to ±25% (Two I/O board version - rear-panel plug-in connectors option only)
ESD Test	<i>IEC 801-2</i> Electrostatic Discharge Test (type tested) Severity Level: 3
Weight	One I/O Board: 20 lbs (9.1 kg); shipping weight 32 lbs (14.5 kg) Two I/O Boards: 26.5 lbs (12 kg); shipping weight 40.6 lbs (18.5 kg)

NAME	SYMBOL	FUNCTION
COMPARATOR		Input A is compared to input B. Output C asserts if A is greater than B.
INPUT FLAG		Input A comes from other logic.
OR		Either input A or input B asserted cause output C to assert.
EXCLUSIVE OR		If A or B are asserted, output C is asserted. If A and B are of the same state, C is deasserted.
NOR		If neither A nor B asserts, output C asserts.
AND		Input A and input B must assert to assert output C.
AND W/ INVERTED INPUT		If input A is asserted and input B is deasserted, output C asserts. Inverter "0" inverts any input or output on any gate.
NAND		If A and/or B are deasserted, output C is asserted.
TIME DELAYED PICK UP AND/OR TIME DELAYED DROP OUT		X is a time-delay-pickup value; Y is a time-delay-dropout value. B asserts time X after input A asserts; B will not assert if A does not remain asserted for time X. If X is zero, B will assert when A asserts. If Y is zero, B will deassert when A deasserts.
EDGE TRIGGER TIMER		Rising edge of A starts timers. Output B will assert time X after the rising edge of A. B will remain asserted for time Y. If Y is zero, B will assert for a single processing interval. Input A is ignored while the timers are running.
SET RESET FLIP FLOP		Input S asserts output Q until input R asserts. Output Q deasserts or resets when R asserts.
FALLING EDGE		B asserts at the falling edge of input A.

DWG. NO. 1015-181

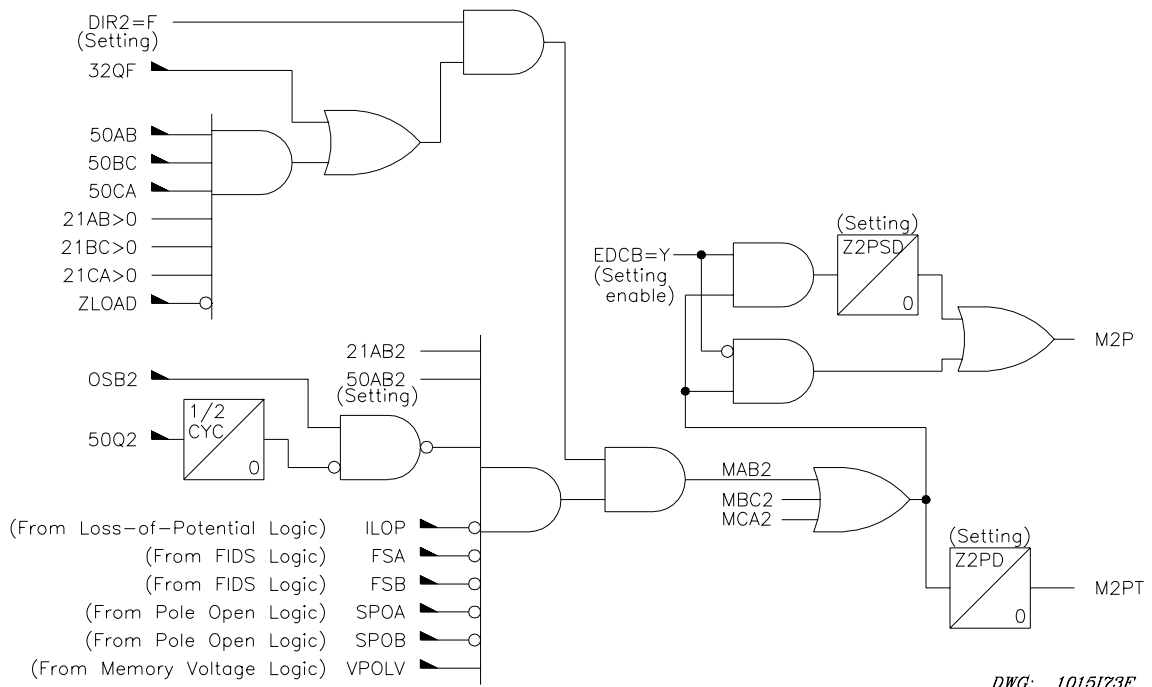
Figure 2.4: Logic Symbol Legend



NOTE: VPOLV deasserts if the positive-sequence memory voltage expires.

DWG: 1015I73E

Figure 2.5: Zone 1 Mho Phase Distance Element Logic



DWG: 1015I73F

Figure 2.6: Zone 2 Mho Phase Distance Element Logic

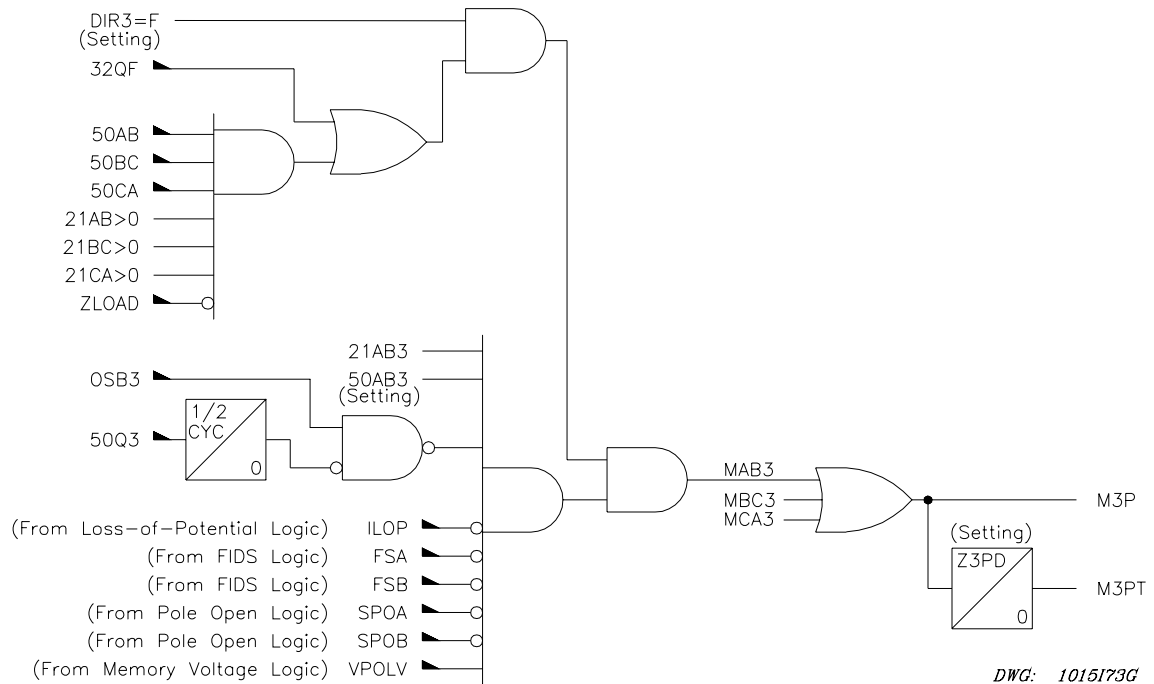


Figure 2.7: Zone 3 Mho Phase Distance Element Logic

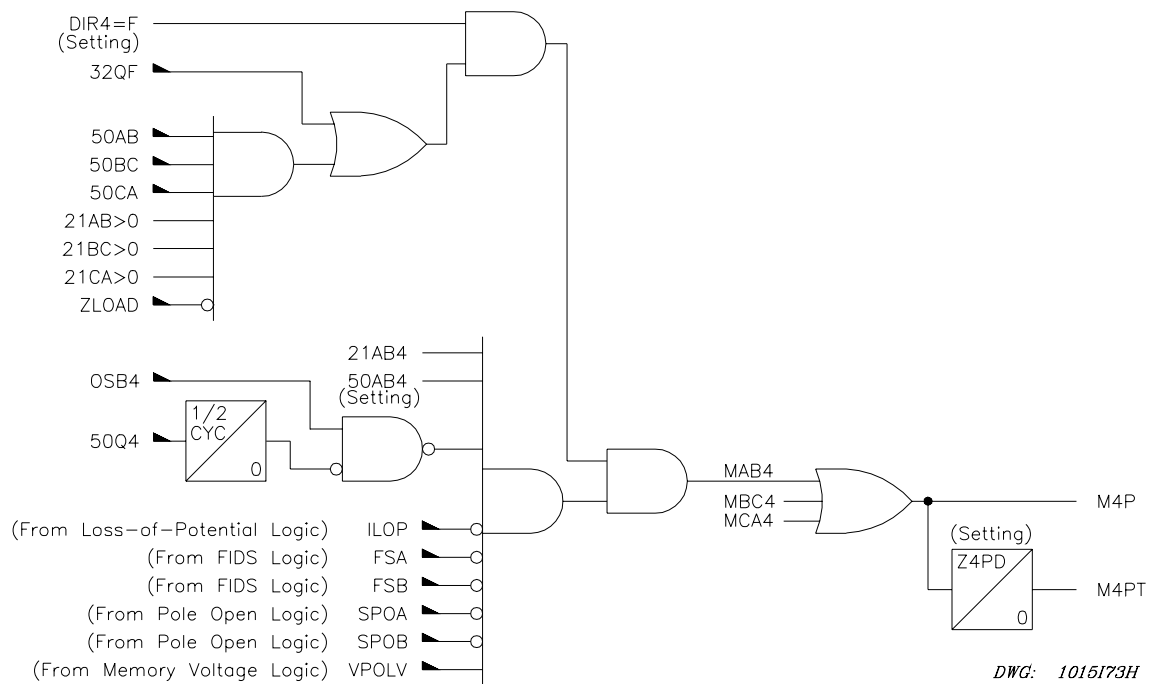
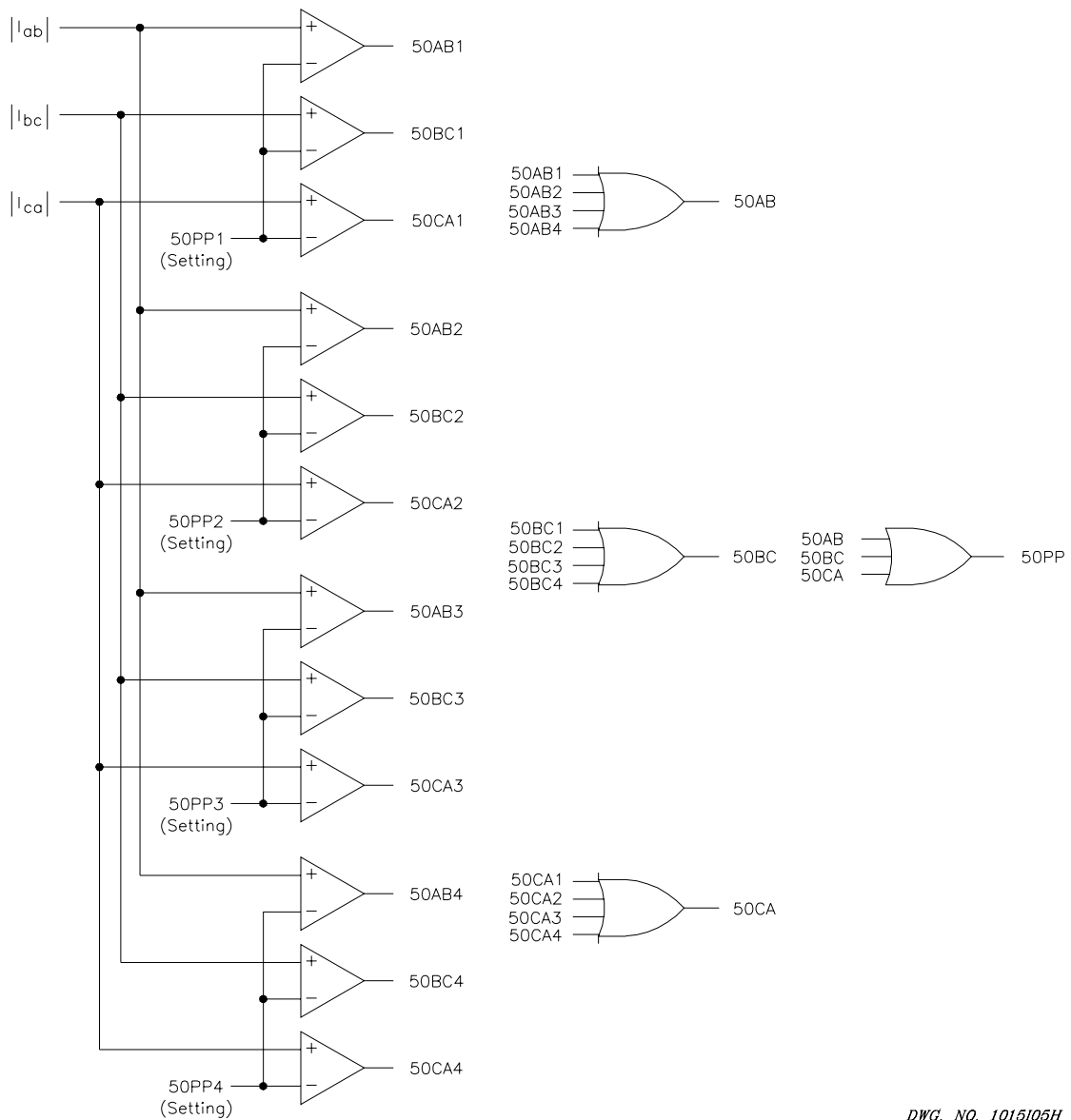
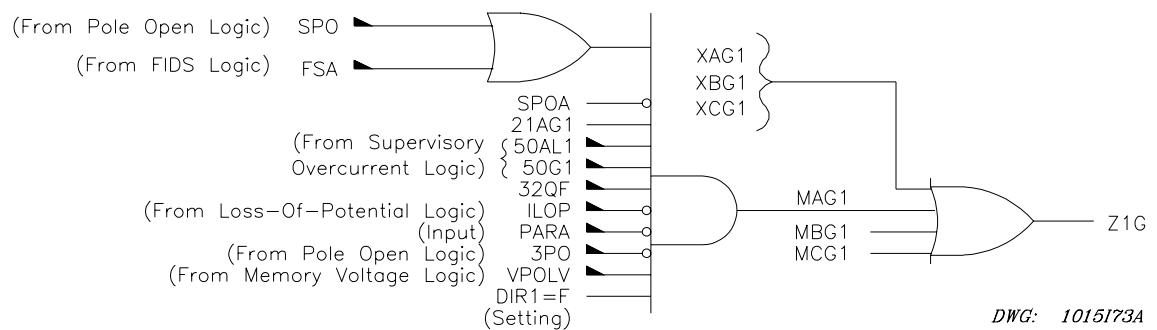


Figure 2.8: Zone 4 Mho Phase Distance Element Logic



DWG. NO. 1015105H

Figure 2.9: Supervisory Phase-to-Phase Overcurrent Elements



DWG: 1015173A

Figure 2.10: Zone 1 Mho Ground Distance Element Logic

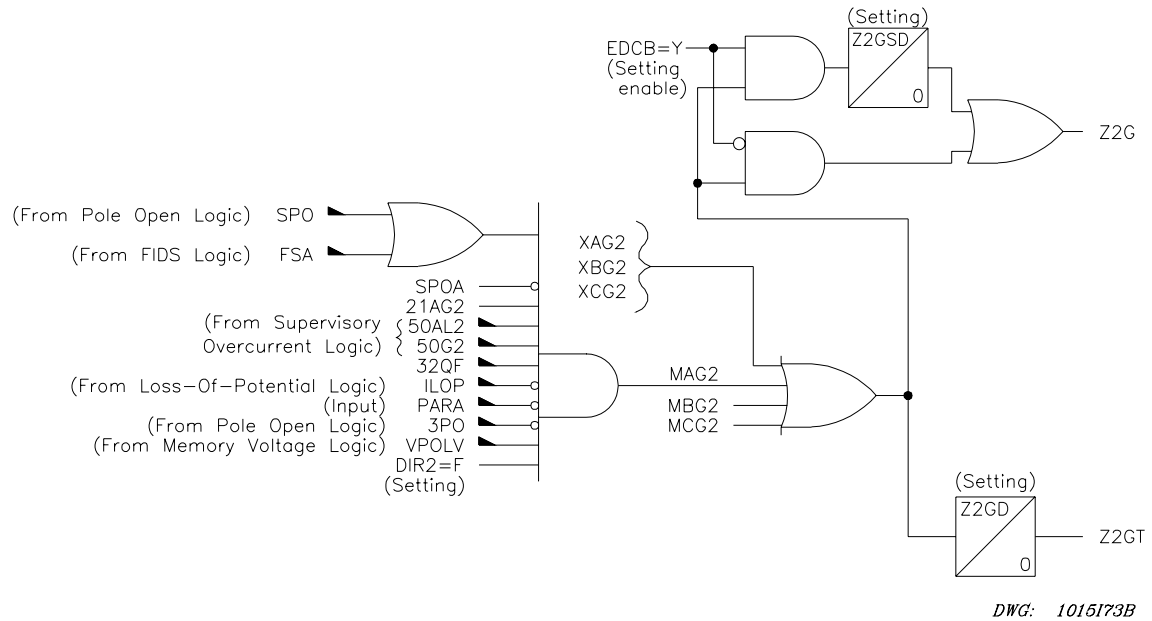


Figure 2.11: Zone 2 Mho Ground Distance Element Logic

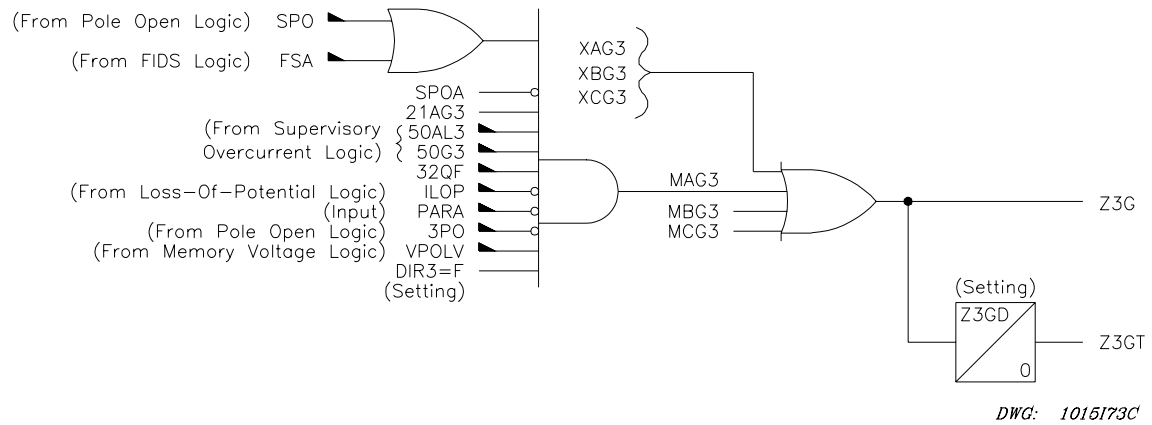


Figure 2.12: Zone 3 Mho Ground Distance Element Logic

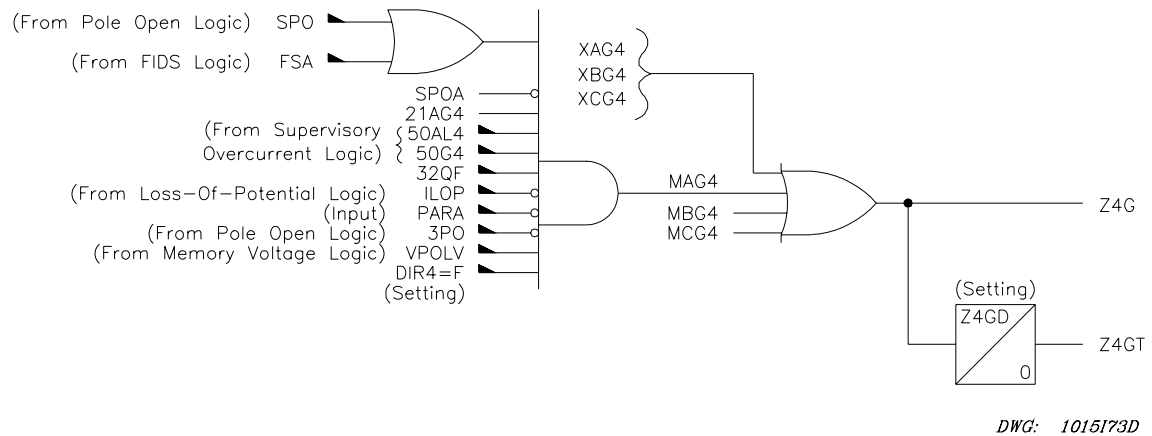


Figure 2.13: Zone 4 Mho Ground Distance Element Logic

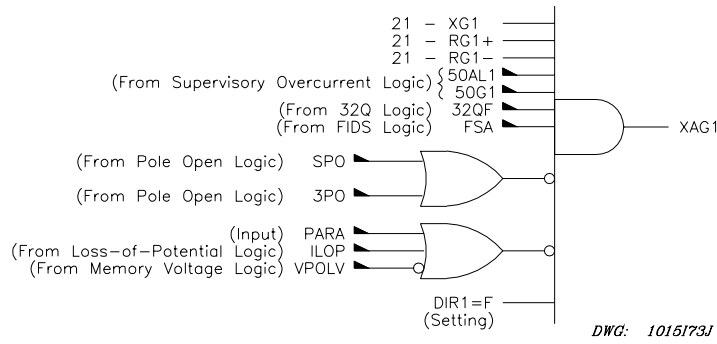


Figure 2.14: Zone 1 Quadrilateral Ground Distance Element Logic

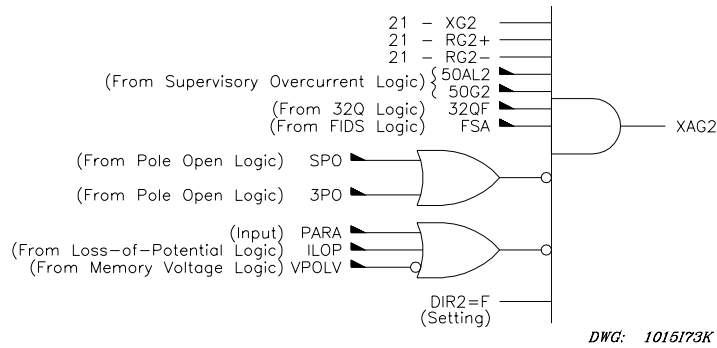


Figure 2.15: Zone 2 Quadrilateral Ground Distance Element Logic

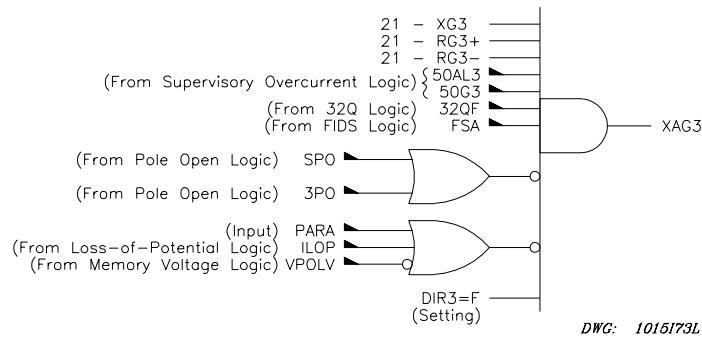


Figure 2.16: Zone 3 Quadrilateral Ground Distance Element Logic

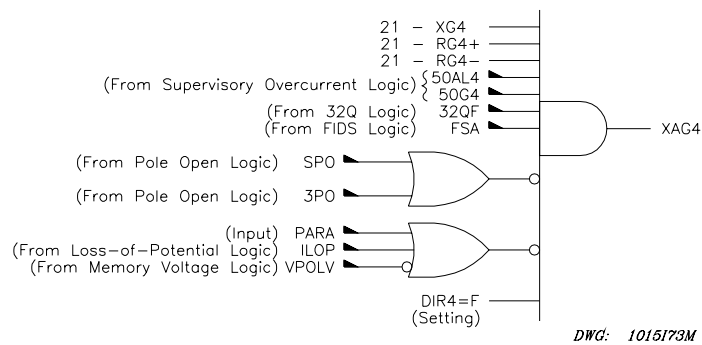


Figure 2.17: Zone 4 Quadrilateral Ground Distance Element Logic

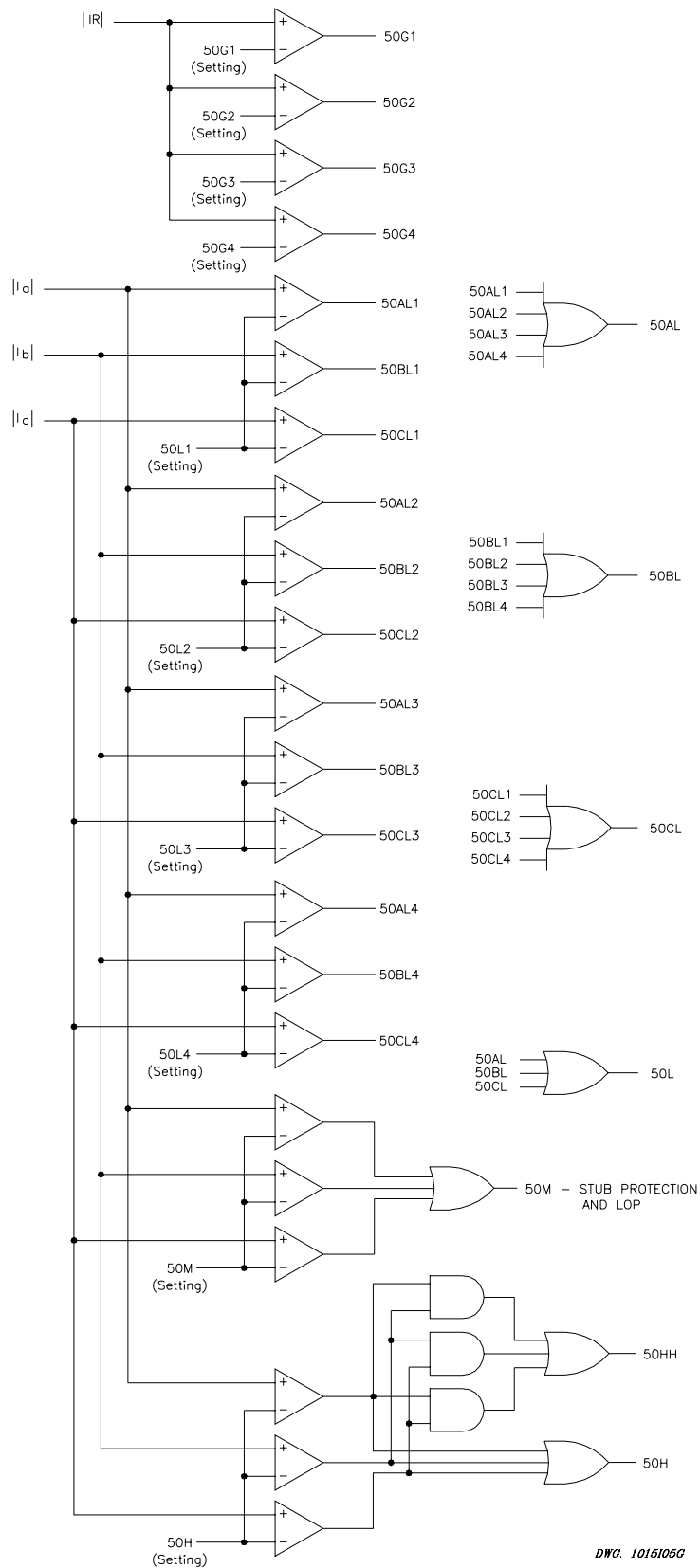


Figure 2.18: Supervisory Phase Overcurrent Elements

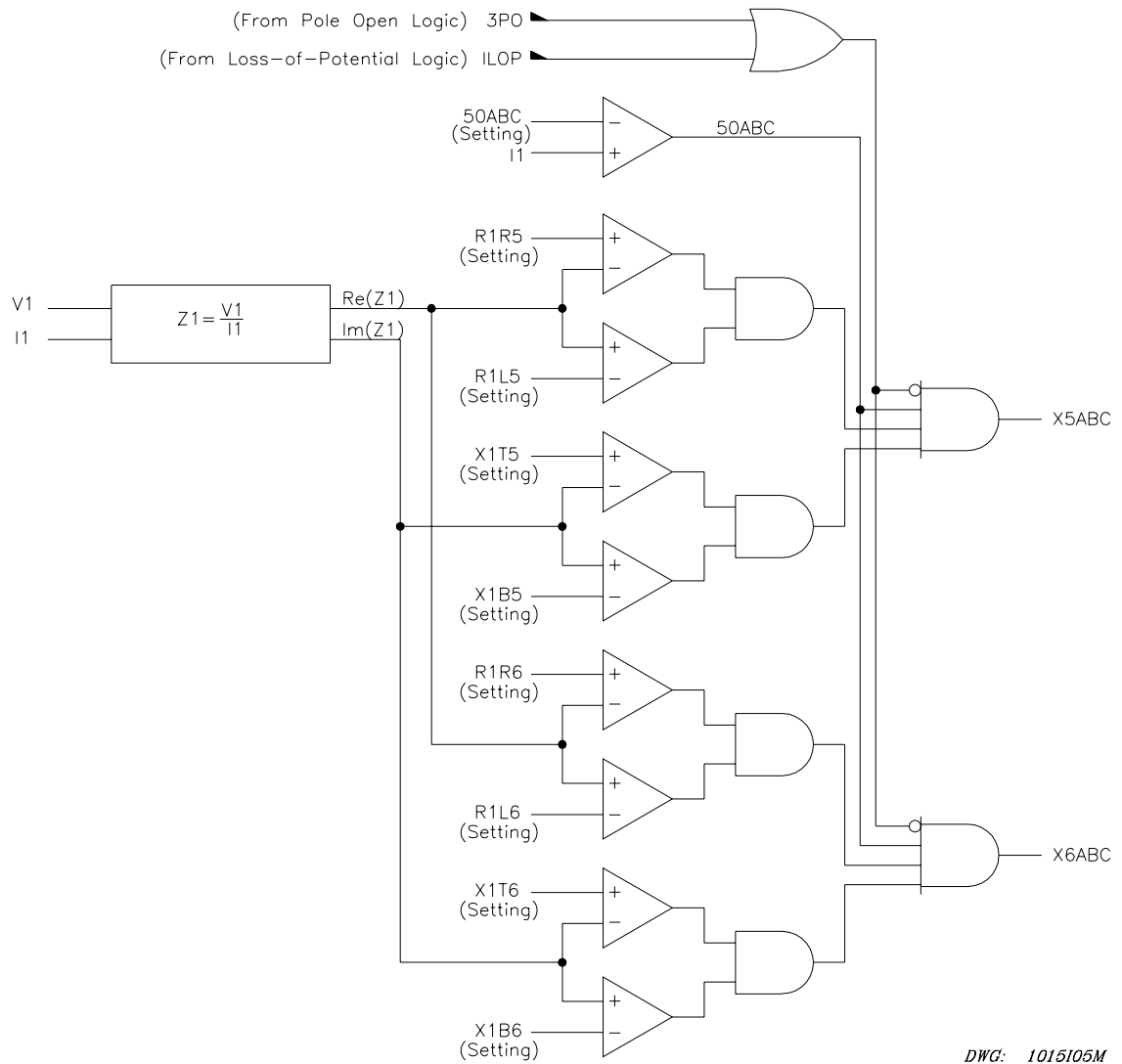
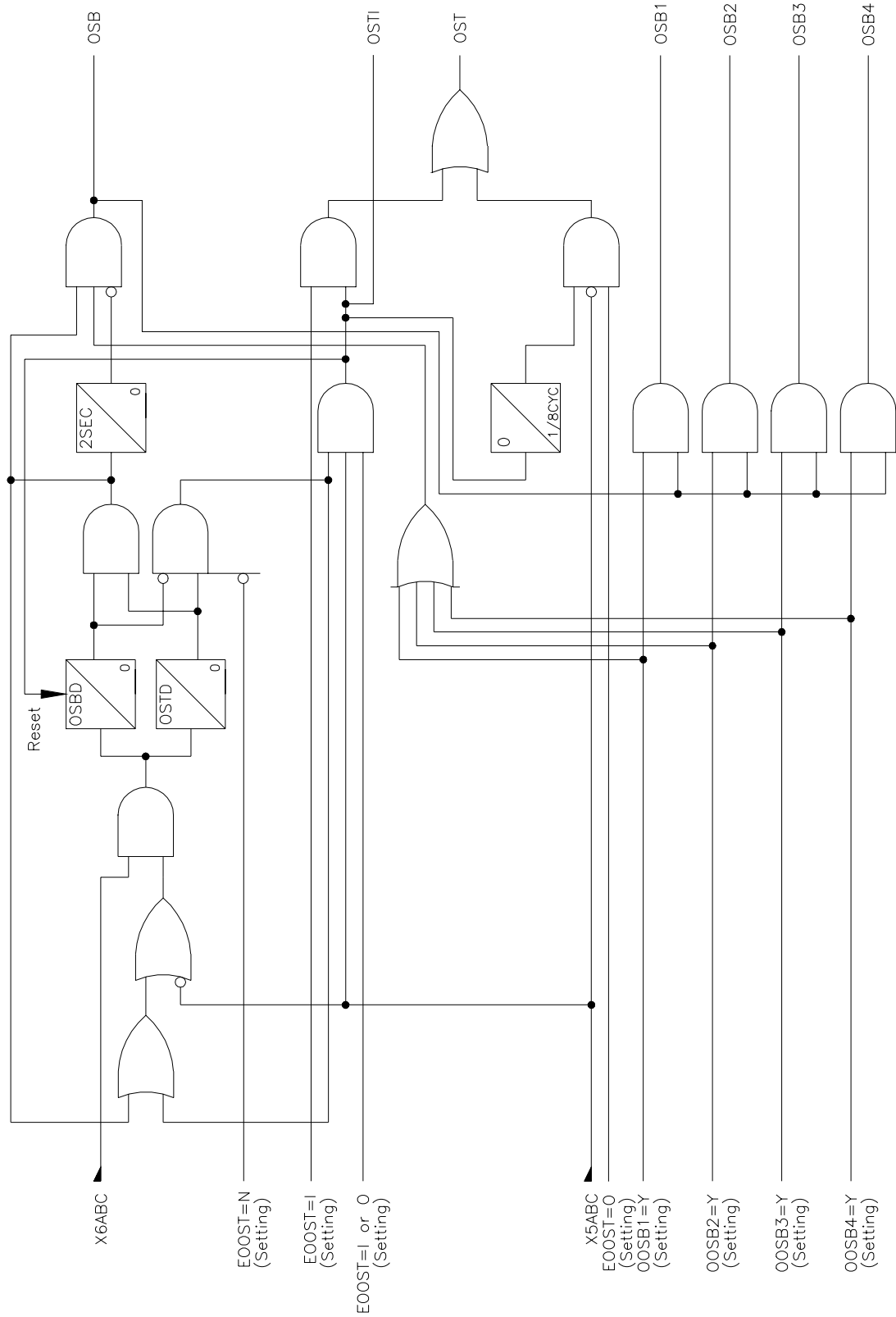
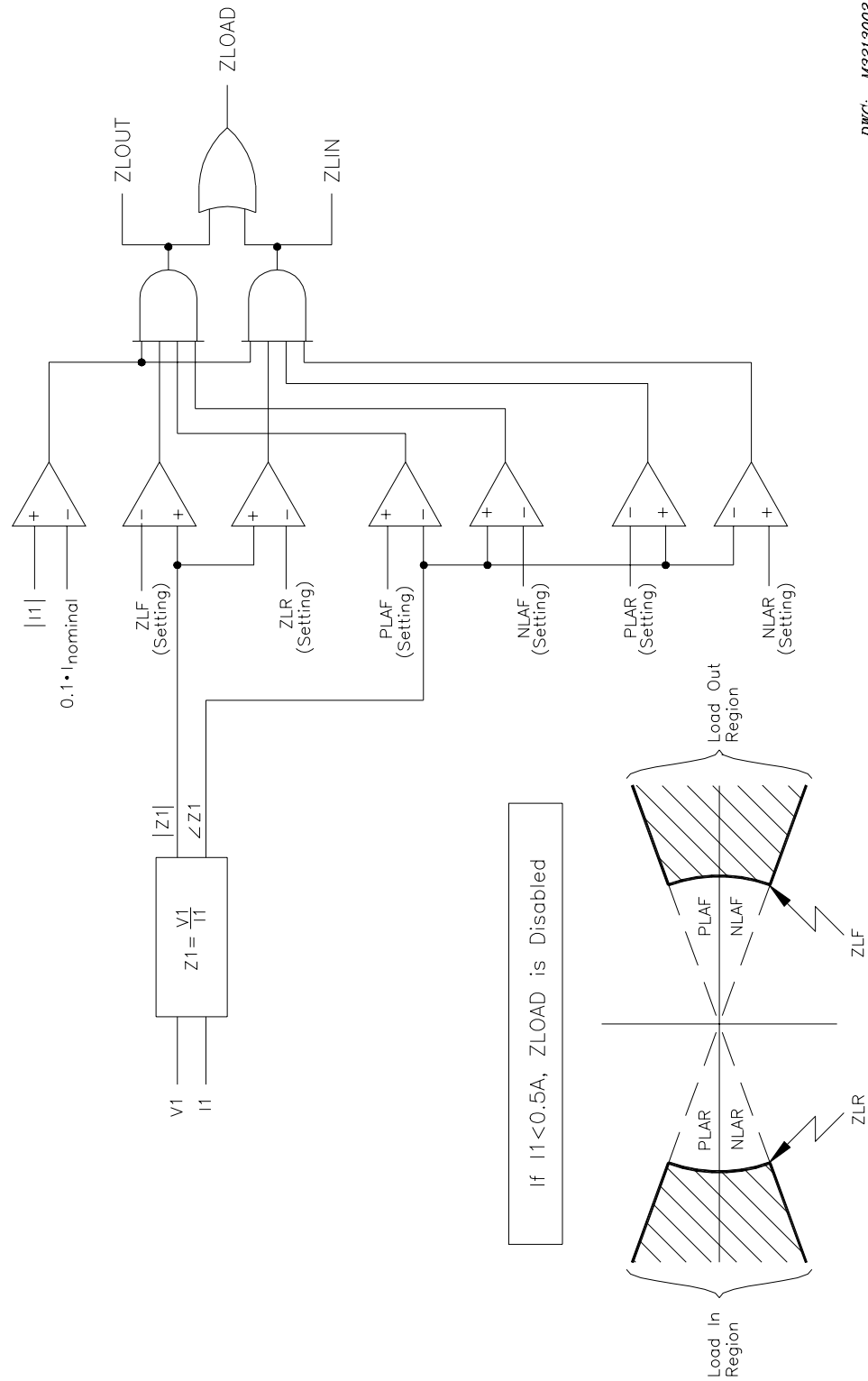


Figure 2.19: Out-of-Step Distance Element Logic



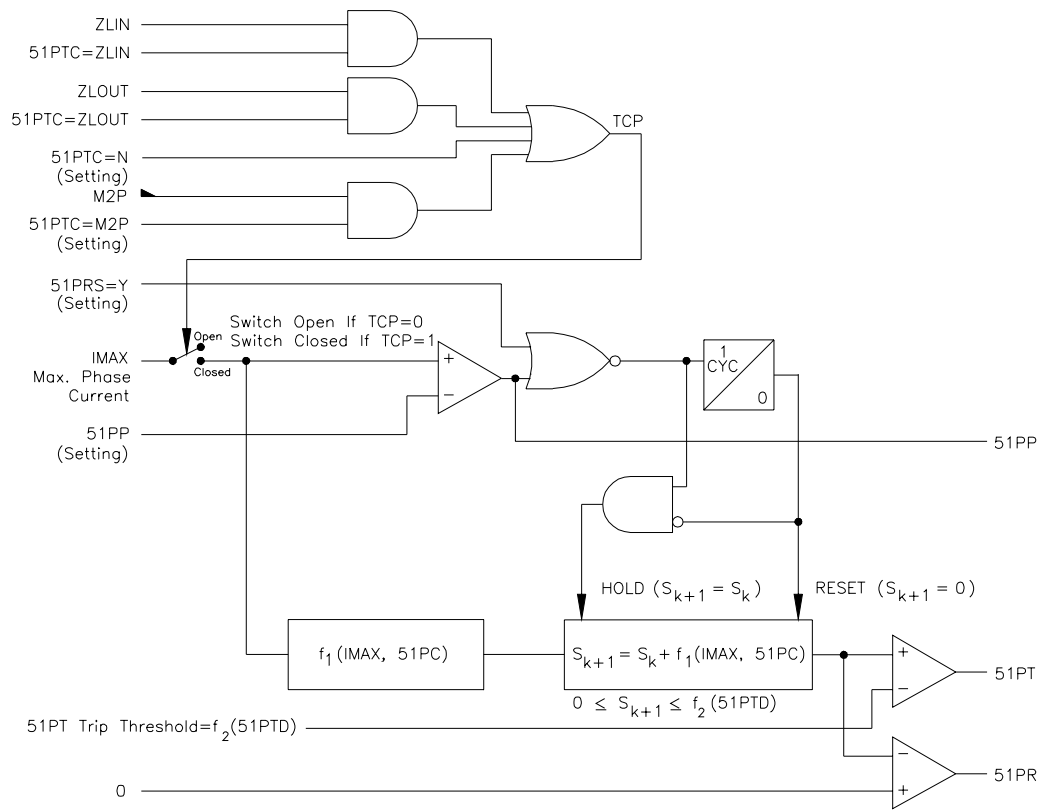
DWG: 1015-199

Figure 2.20: Out-of-Step Block and Trip Logic



DWG: M3213002

Figure 2.21: Load-Encroachment Logic



DWG: 1015105N

Figure 2.23: Phase Time-Overcurrent Element Logic

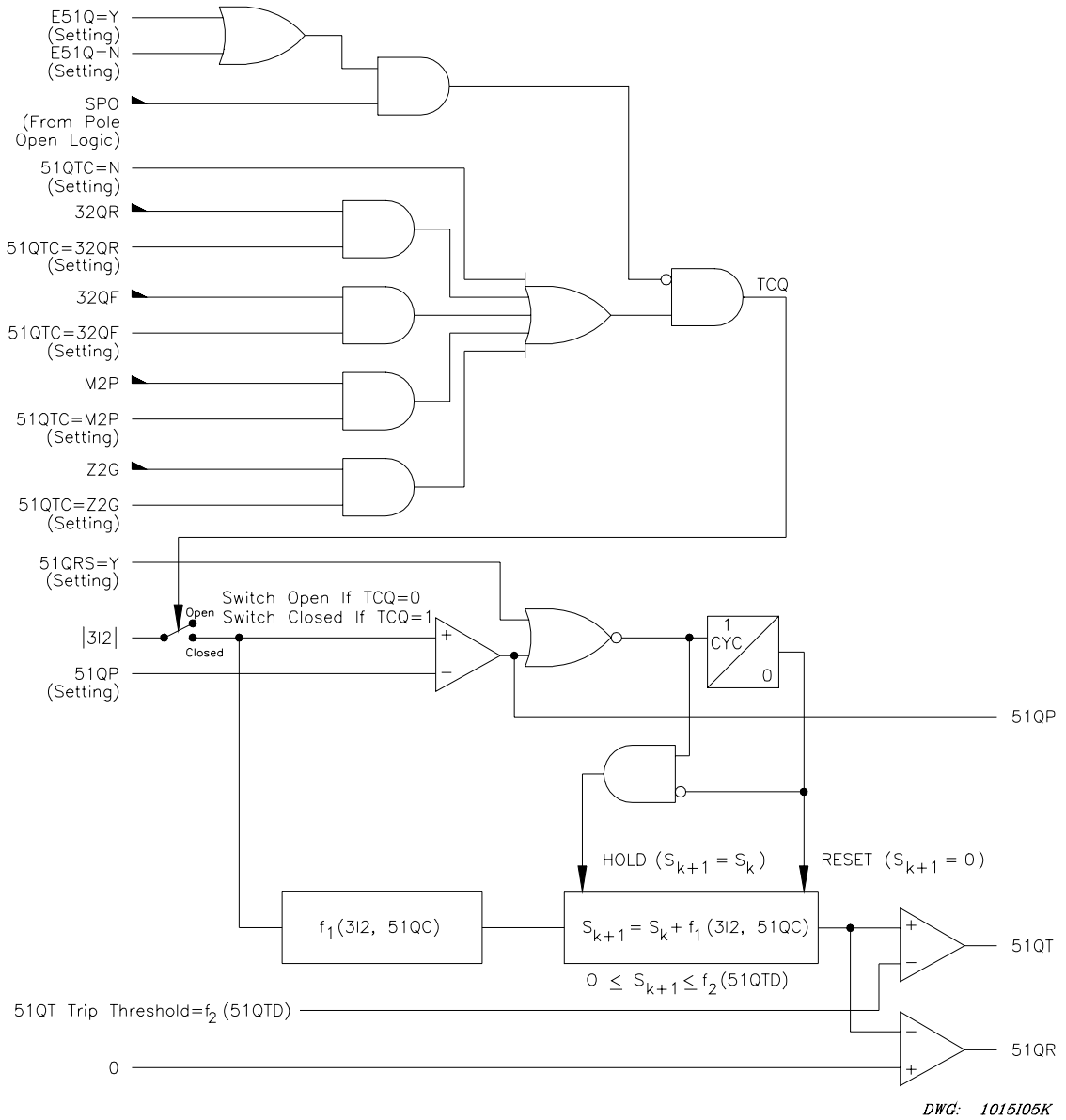


Figure 2.24: Negative-Sequence Time-Overcurrent Element Logic

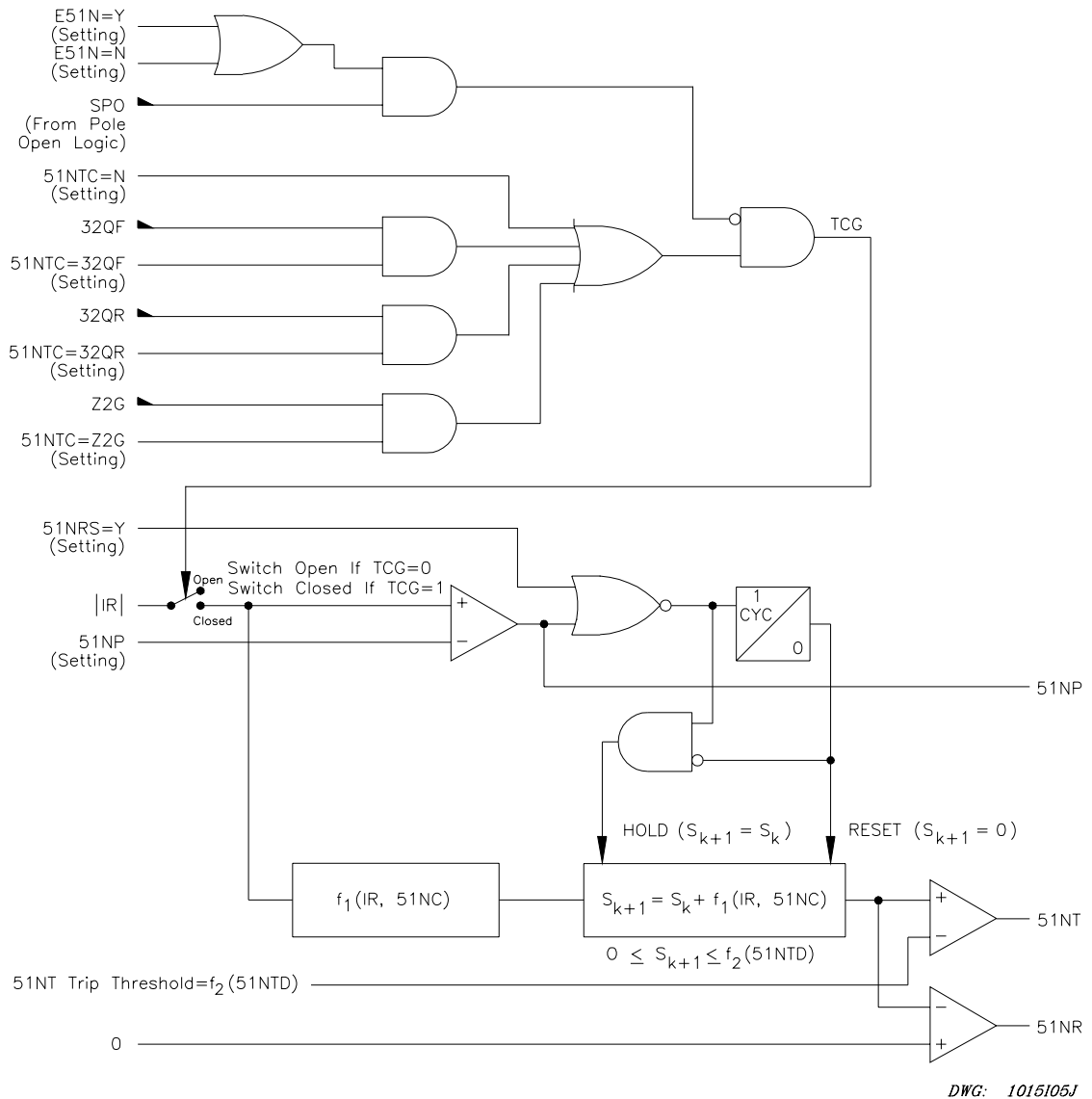
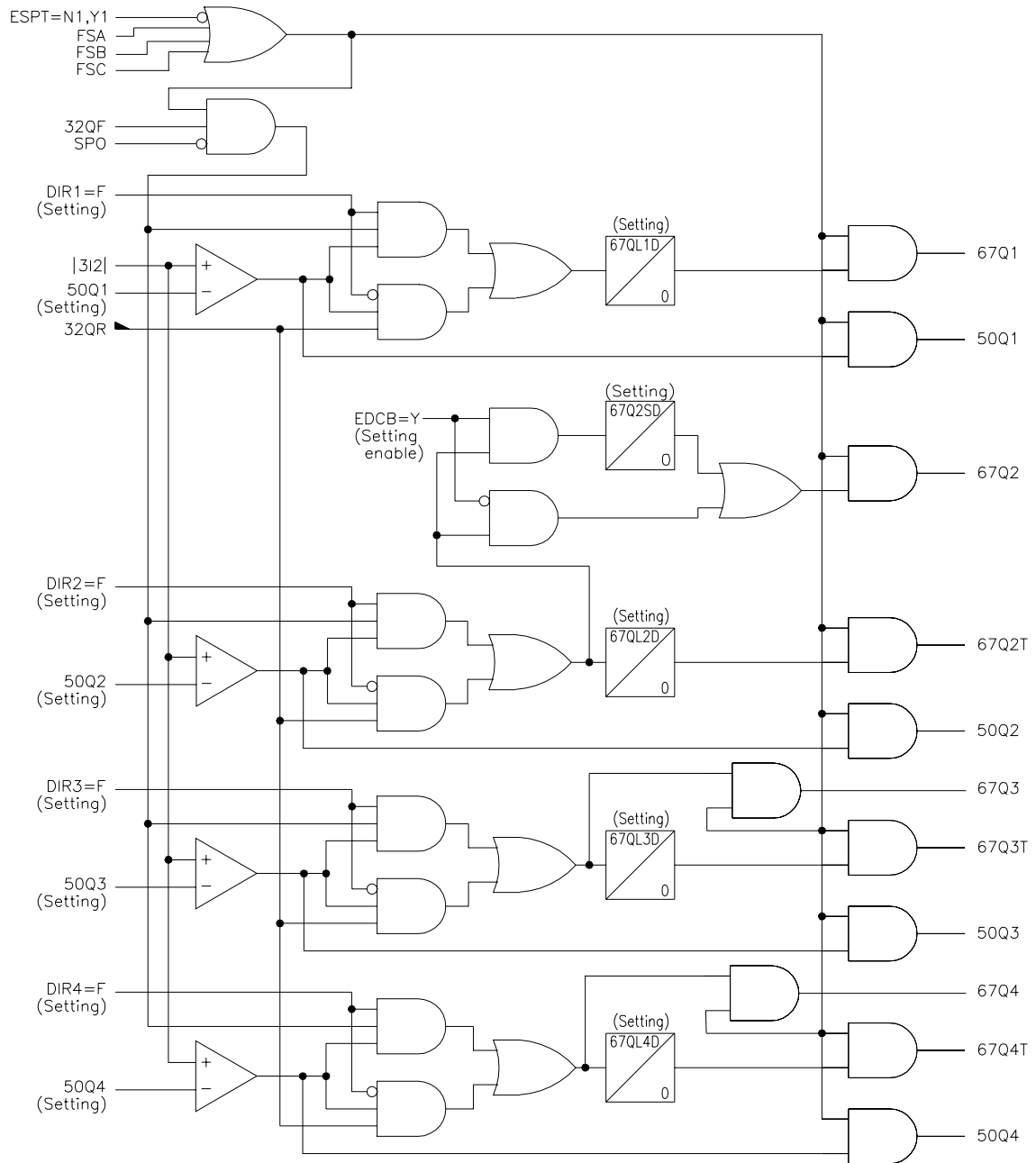
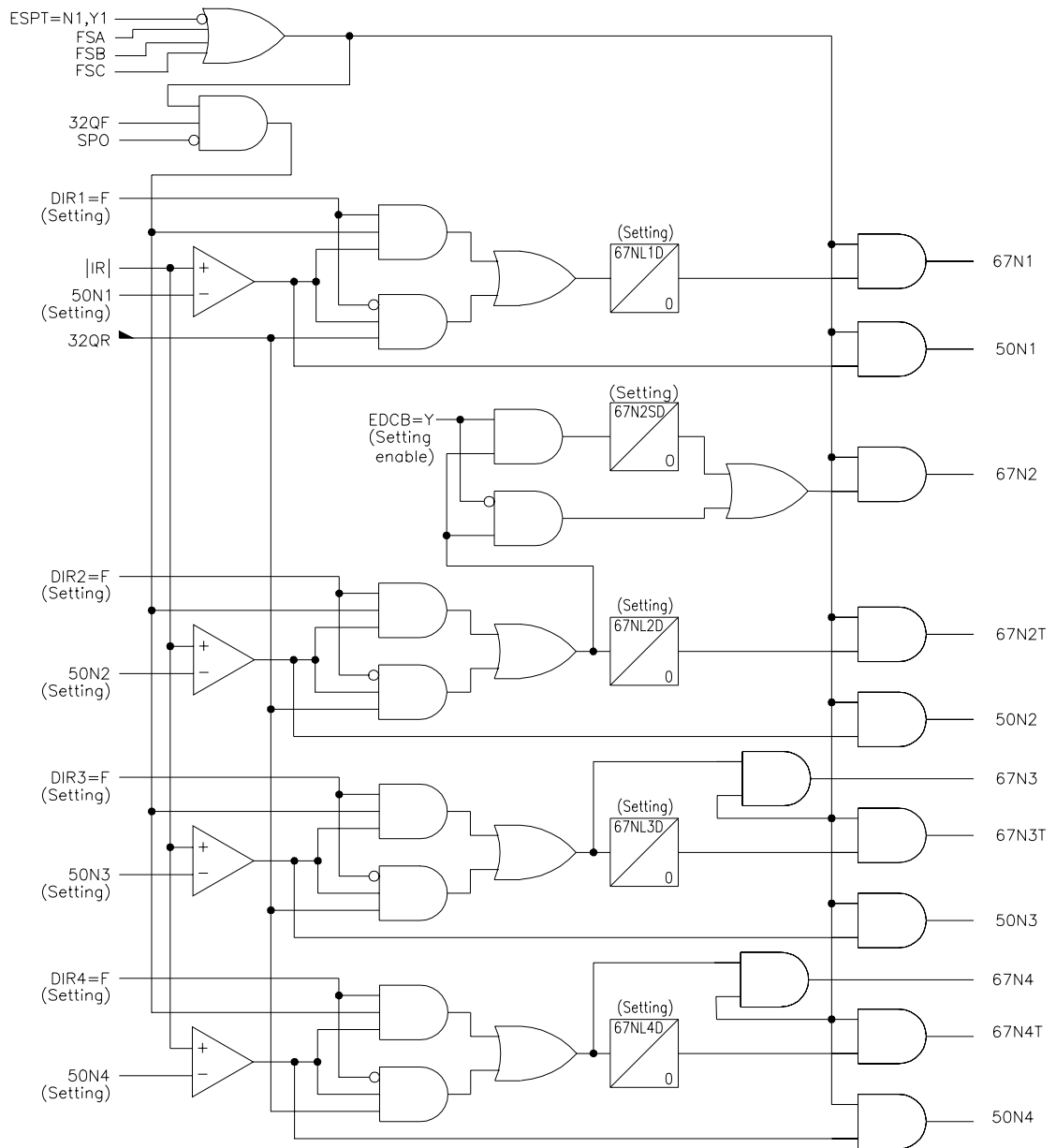


Figure 2.25: Residual Time-Overcurrent Element Logic



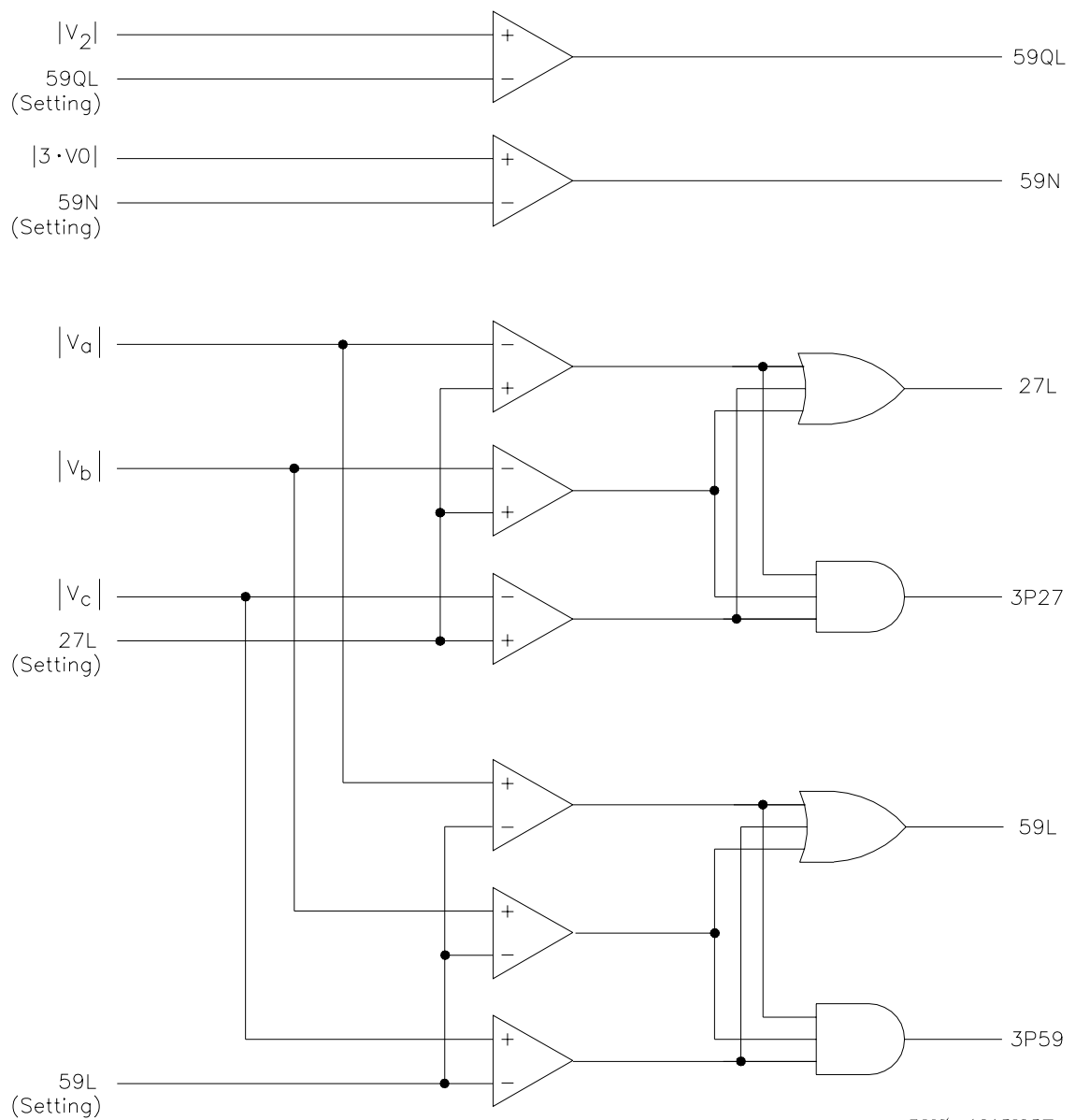
DWG: M321002

Figure 2.26: Negative-Sequence Overcurrent Element Logic for Levels 1 - 4



DWG: M321003

Figure 2.27: Residual Overcurrent Element Logic for Levels 1 - 4



DWG. 1015105F

Figure 2.28: Voltage Element Logic

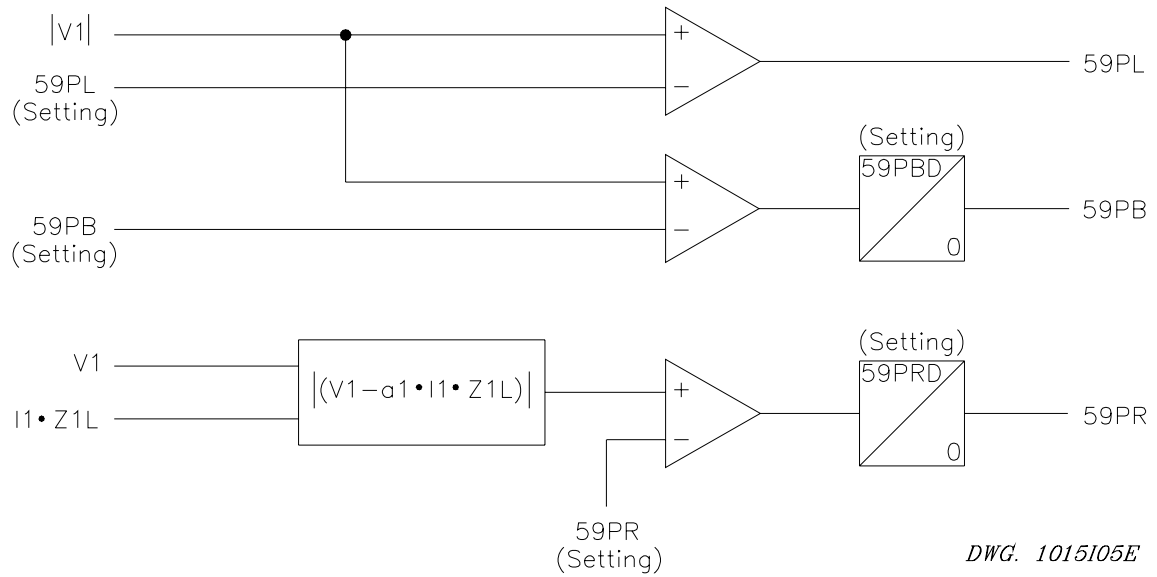


Figure 2.29: Positive-Sequence Overvoltage Element Logic

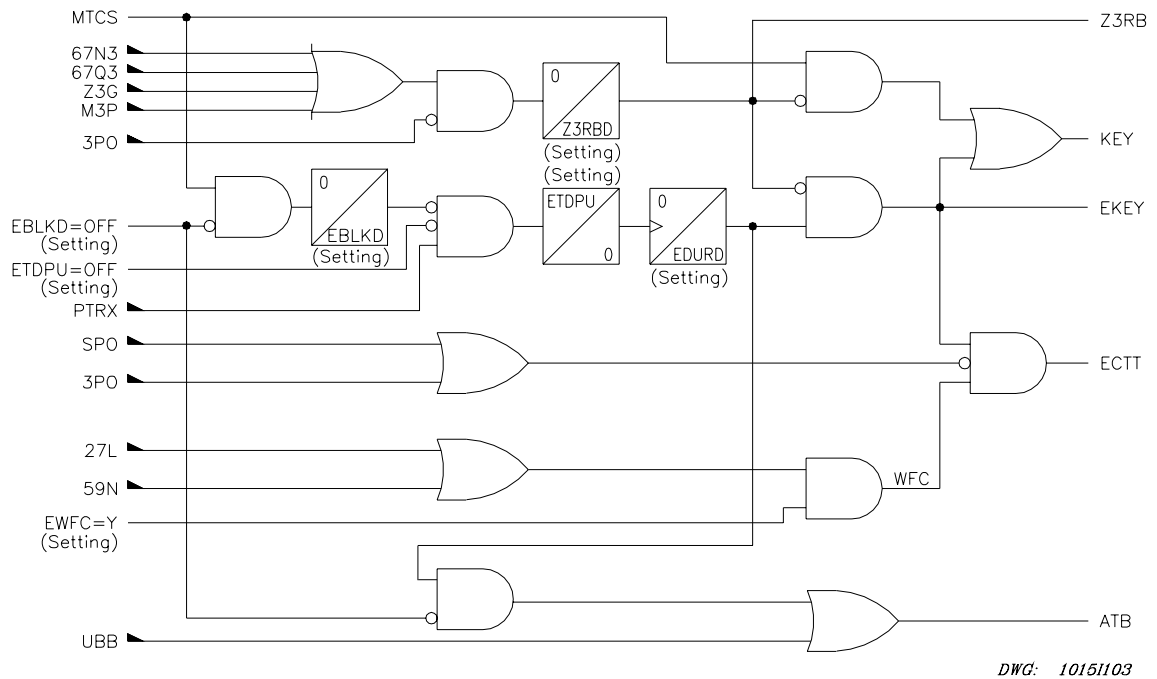


Figure 2.30: Permissive Overreaching Transfer Trip Scheme Logic

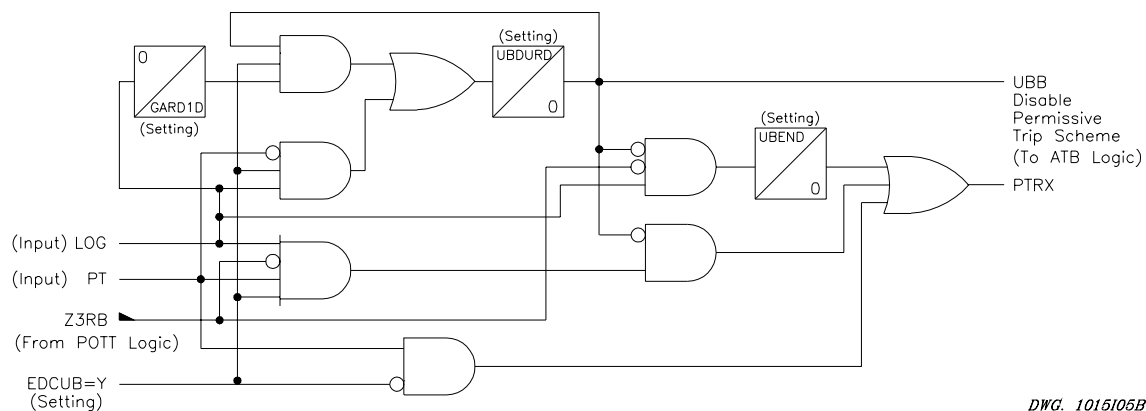


Figure 2.31: Directional Comparison Unblocking Scheme Logic

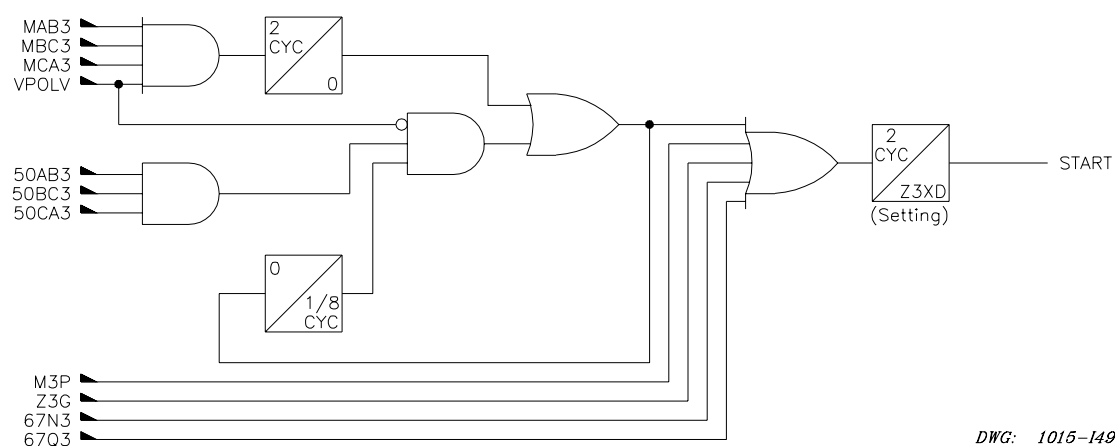


Figure 2.32: Directional Comparison Blocking Scheme Logic - 1 of 2

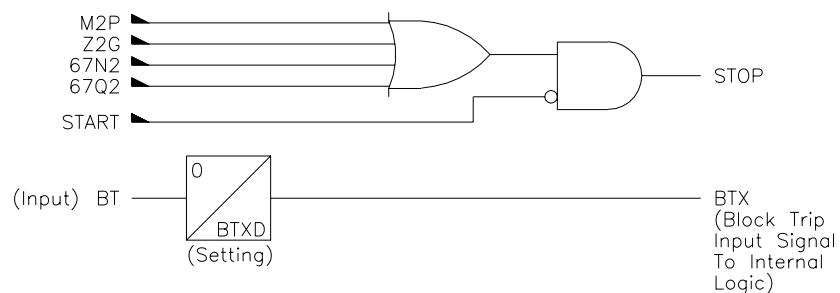


Figure 2.33: Directional Comparison Blocking Scheme Logic - 2 of 2

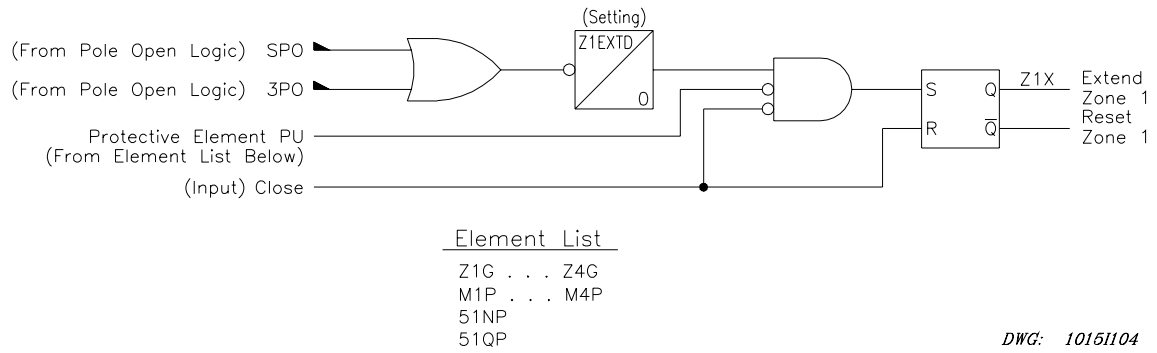


Figure 2.34: Zone 1 Extension Logic

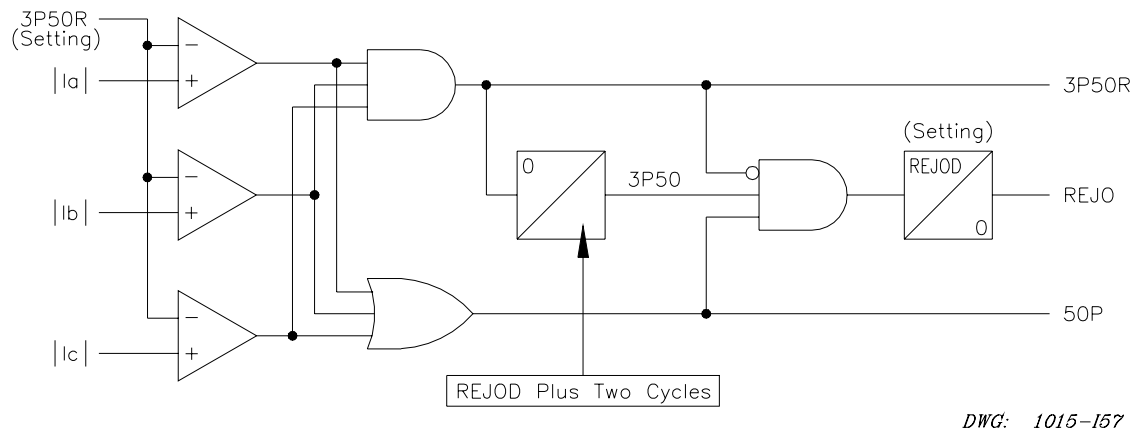


Figure 2.35: Remote-End-Just-Opened Logic

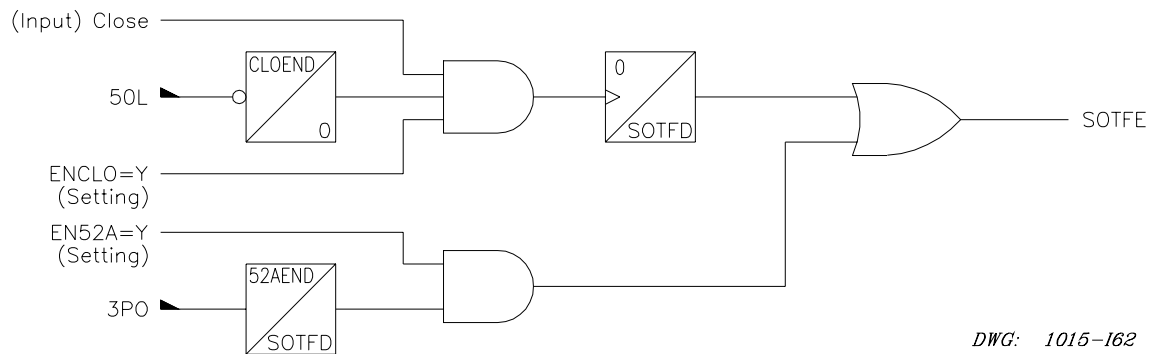


Figure 2.36: Switch-Onto-Fault Enable Logic

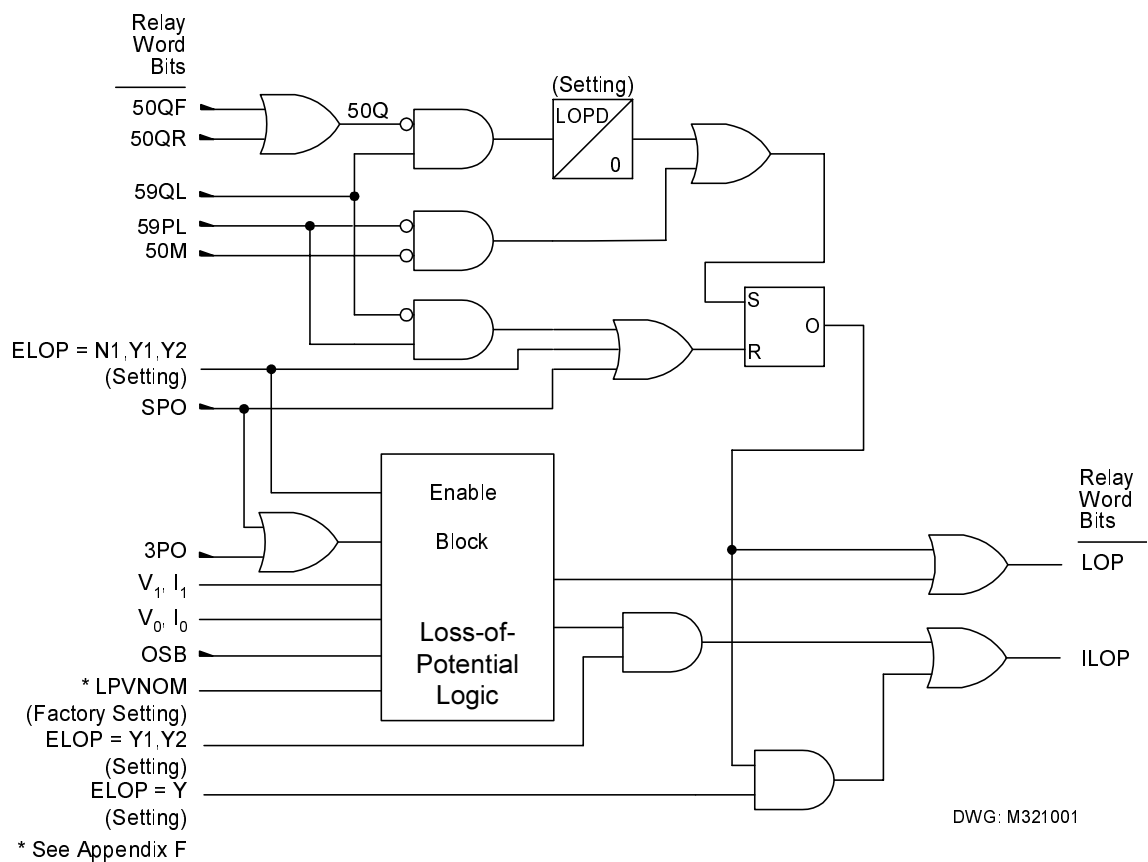


Figure 2.37: Loss-of-Potential Logic

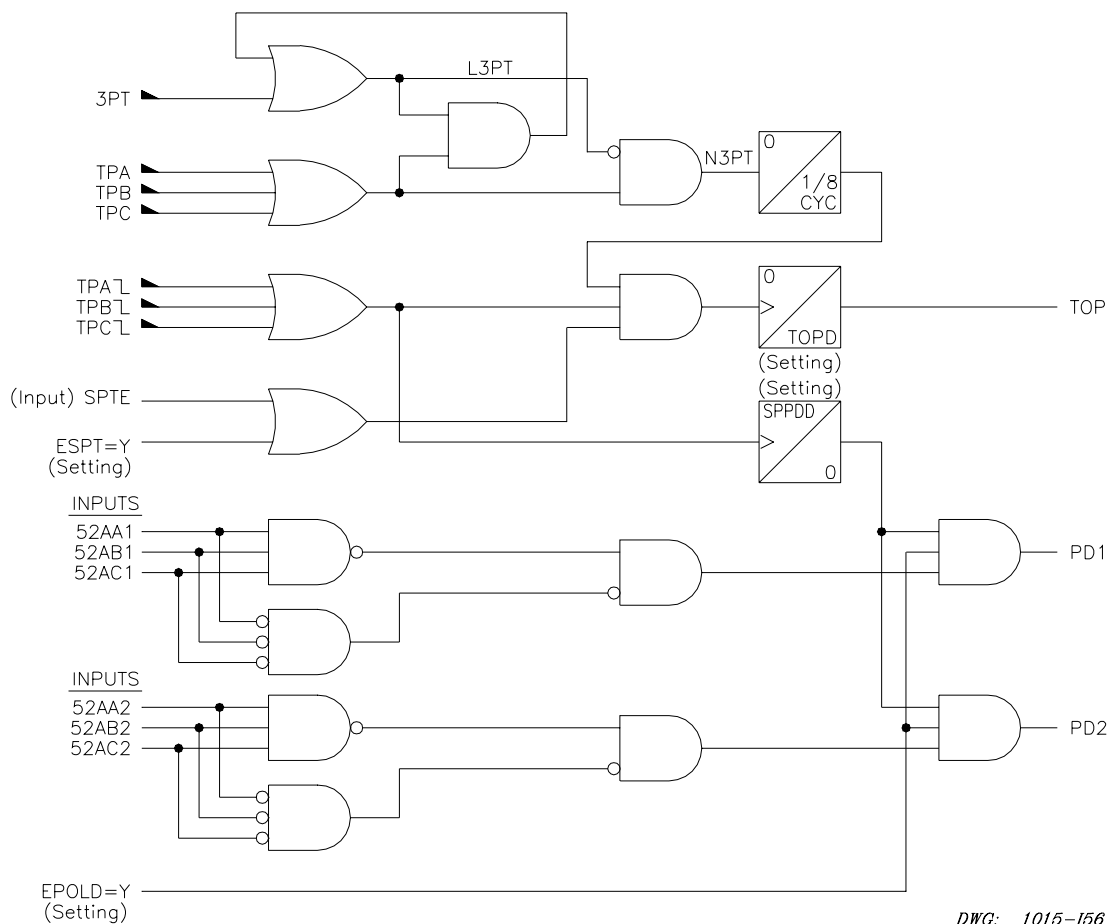


Figure 2.38: Pole-Discordance and Trip During Pole Open Logic

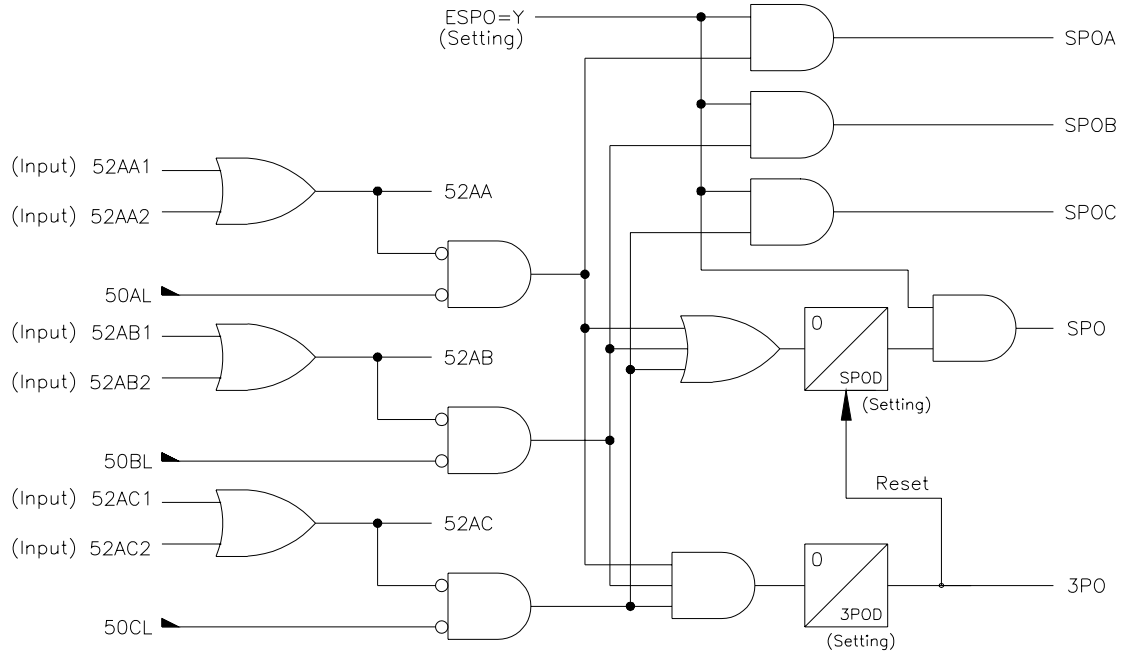


Figure 2.39: Pole Open Logic

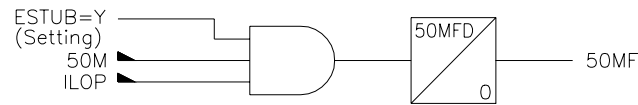


Figure 2.40: Stub Protection Logic

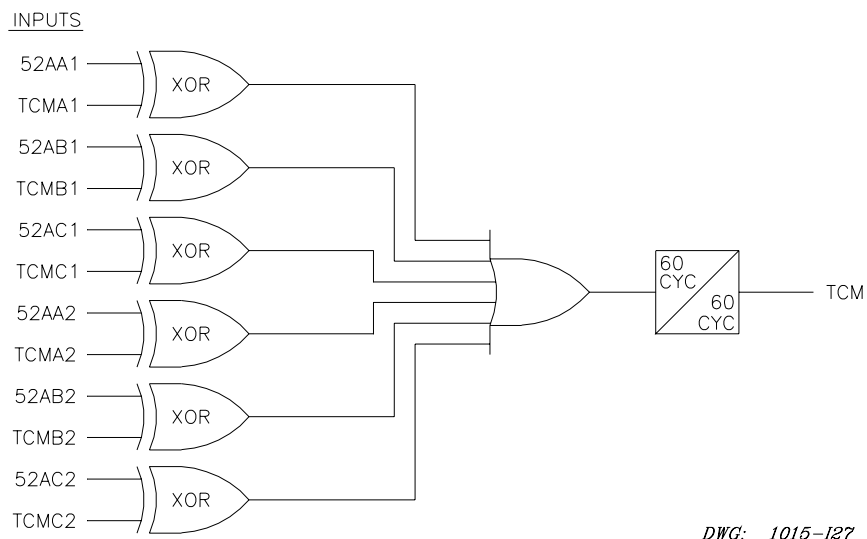


Figure 2.41: Trip Coil Monitor Logic

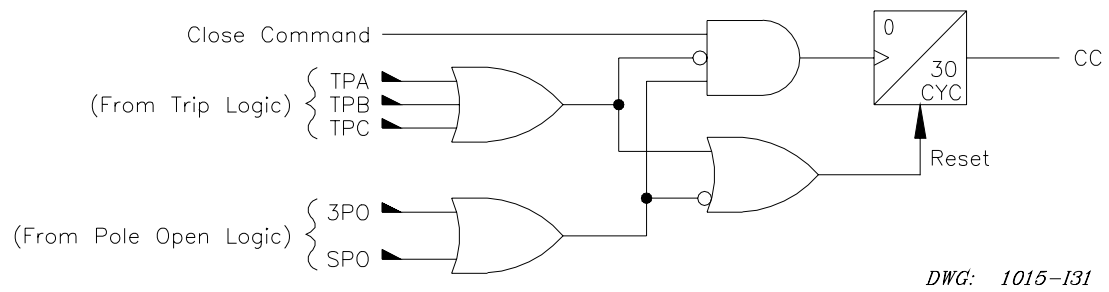


Figure 2.42: Close Logic

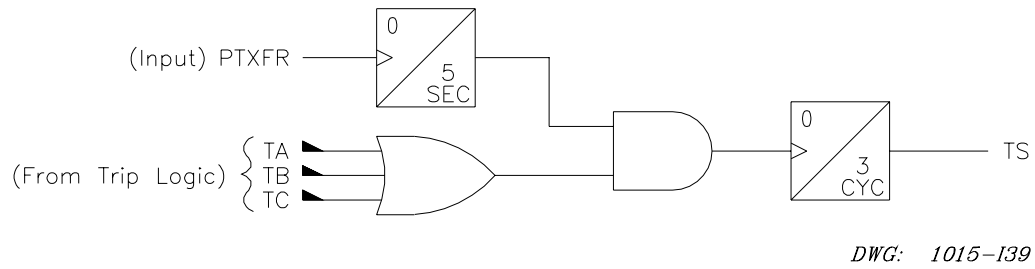


Figure 2.43: Trip Suspicion Logic

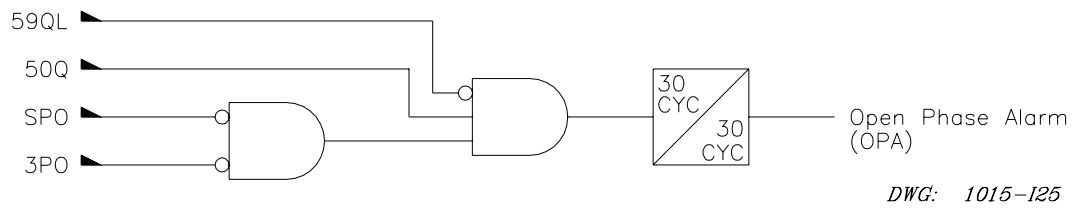


Figure 2.44: Open Phase Alarm Logic

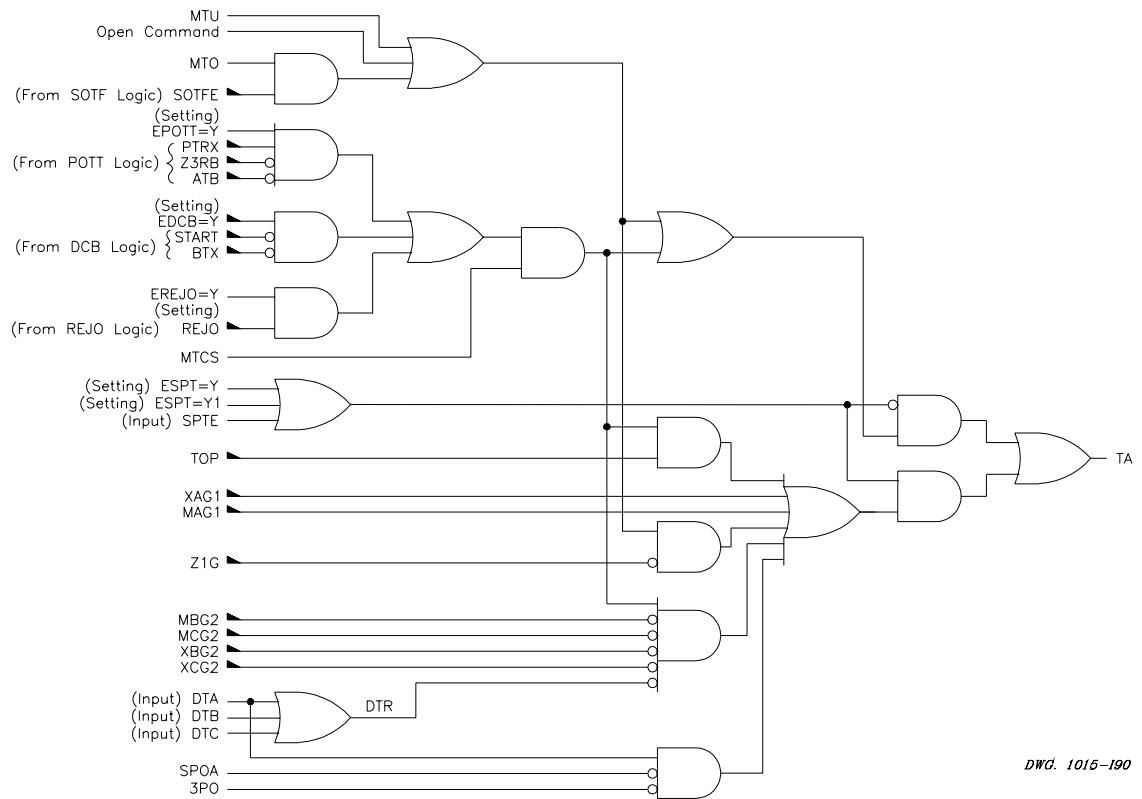


Figure 2.45: Trip Decision Logic for Phase A

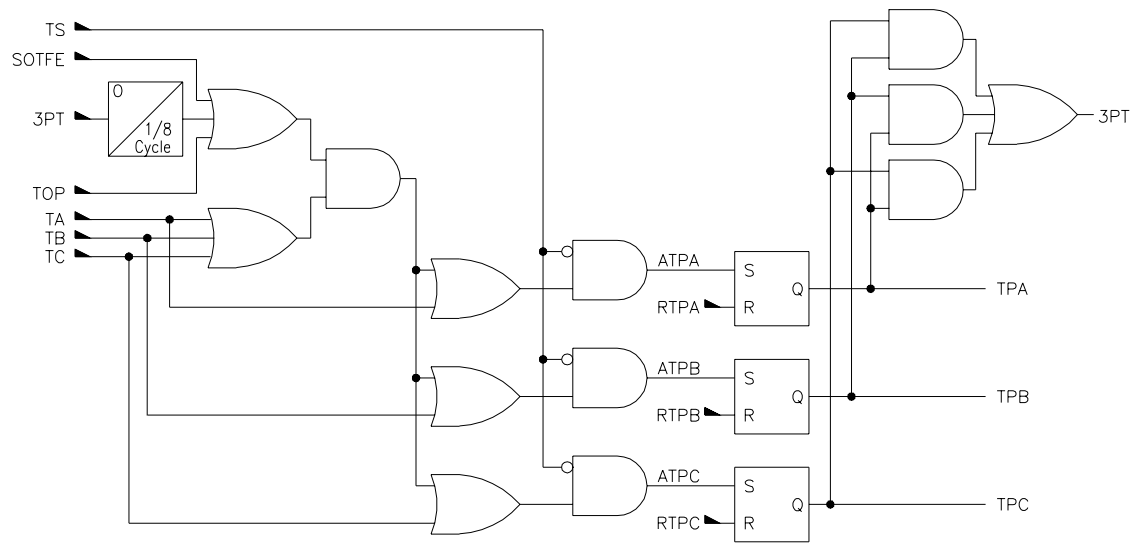
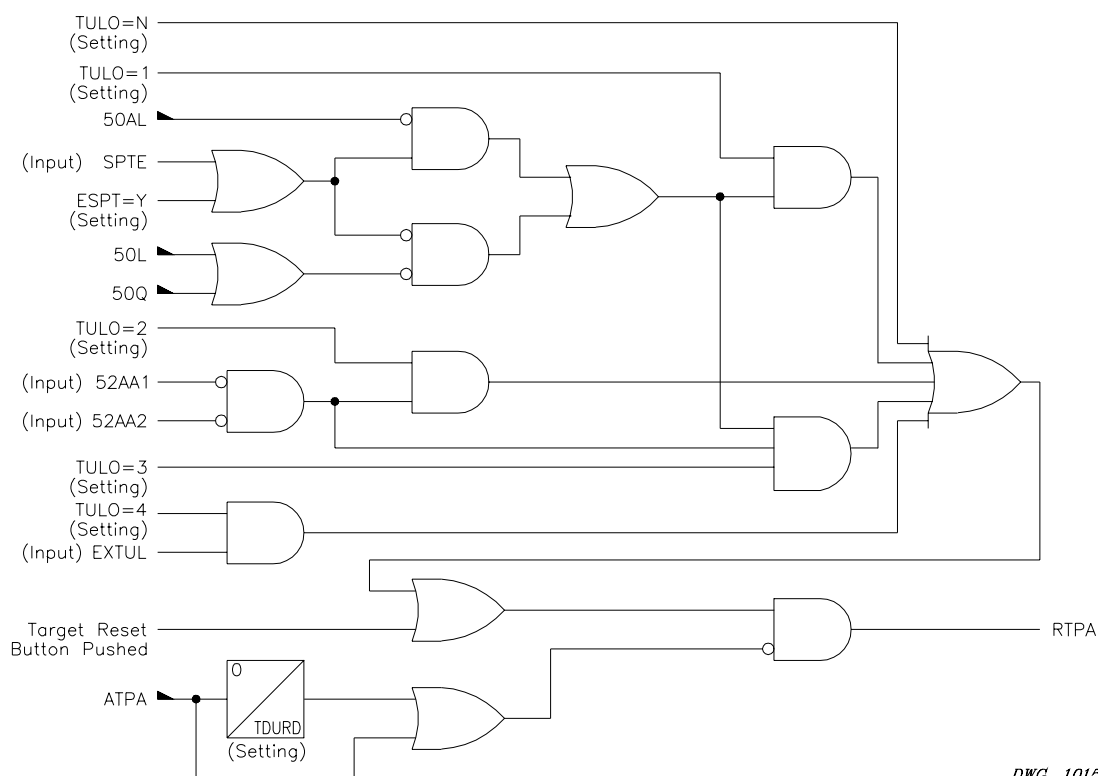


Figure 2.46: Trip Latch Logic



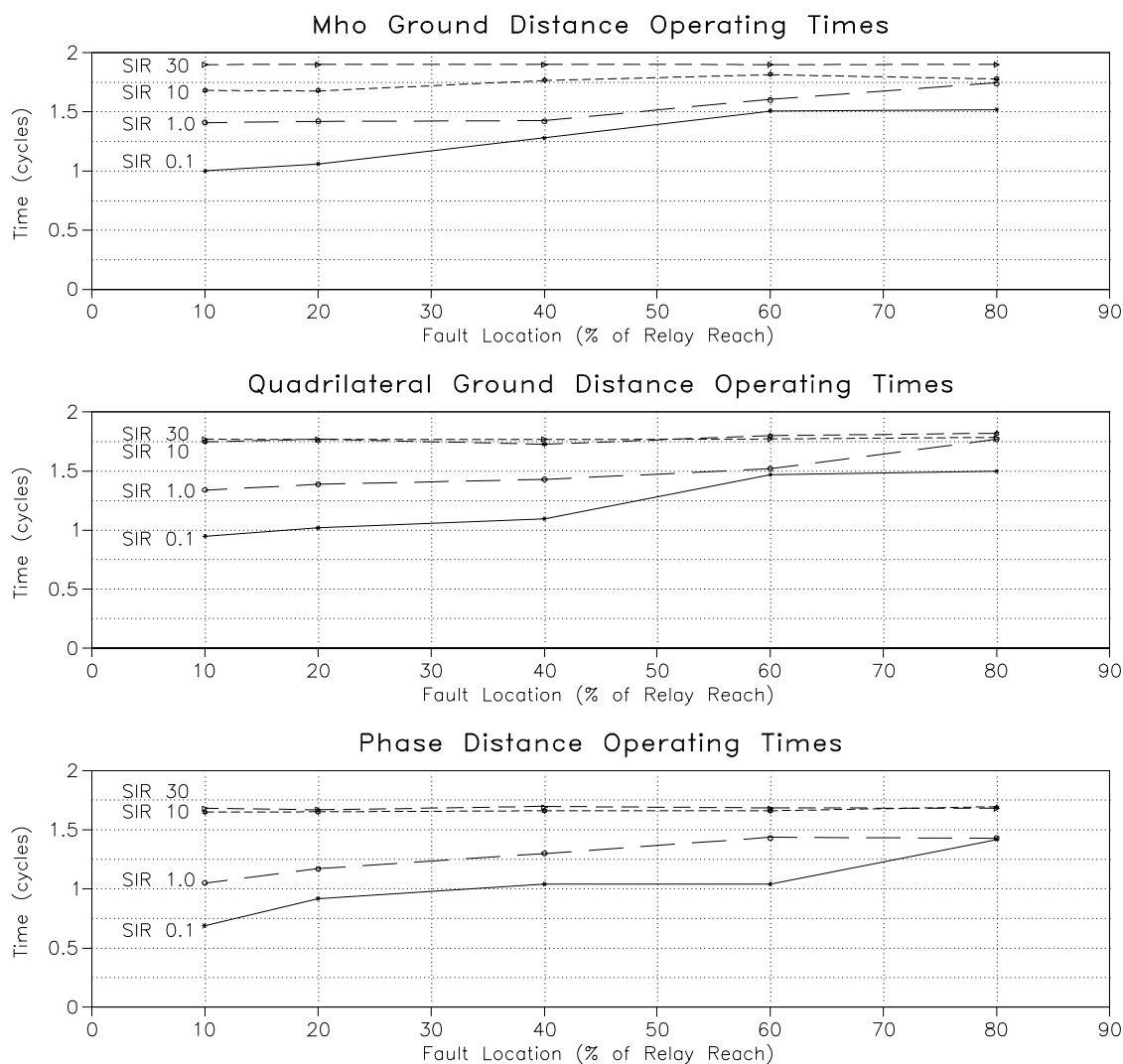
DWG. 1016-192

Figure 2.47: Trip Unlatch Logic for Phase A

DISTANCE ELEMENT OPERATING TIME CURVES AT NOMINAL FREQUENCY

Figure 2.48 shows operating times for the SEL-321 Relay distance elements. The diagrams show operating times at each test point. Operating times include output contact closure time (for standard and interrupting duty contact outputs).

For the distance element test, a fault was applied at a location representing a percentage of the Zone 1 relay reach setting. Tests were performed for source impedance ratios (SIR) of 0.1, 1.0, 10.0, and 30.0. No pre-fault load current or fault resistance was included. Operating times are the same for both 50 Hz and 60 Hz.



DWG: 321CURV

Figure 2.48: Ground and Phase Distance Speed Curves

TIME-OVERCURRENT CURVE EQUATIONS

Both US and IEC time-overcurrent curves are provided in the SEL-321 Relay. Use the **SET** command to select the curve characteristics you desire. Refer to **Section 3: Communications** for a complete description of the use of the **SET** command and selection of time-overcurrent characteristics.

These time curve equations are valid for all time-overcurrent elements. Plots showing operating time versus multiples of pickup current are shown on the following pages. The equations and curves apply while the product of the multiples of pickup and pickup setting is less than $32 \cdot I_{\text{nominal}}$ amps, secondary.

Equations for US Curves

t_M = curve operating time in seconds

t_r = reset time in seconds (for time delay reset)

TD = time dial setting

M = multiples of pickup. For curve operating time (t_M), $M > 1$.

For reset time (t_r), $M \leq 1$.

Curve U1: Moderately Inverse - See Figure 2.49

$$t_m = TD \left[0.0226 + \frac{0.0104}{M^{0.02} - 1} \right] \quad t_r = \frac{TD \cdot 1.08}{1 - M^2}$$

Curve U2: Inverse - See Figure 2.50

$$t_m = TD \left[0.180 + \frac{5.95}{M^2 - 1} \right] \quad t_r = \frac{TD \cdot 5.95}{1 - M^2}$$

Curve U3: Very Inverse - See Figure 2.51

$$t_m = TD \left[0.0963 + \frac{3.88}{M^2 - 1} \right] \quad t_r = \frac{TD \cdot 3.88}{1 - M^2}$$

Curve U4: Extremely Inverse - See Figure 2.52

$$t_m = TD \left[0.0352 + \frac{5.67}{M^2 - 1} \right] \quad t_r = \frac{TD \cdot 5.67}{1 - M^2}$$

Equations for IEC Curves

t = operating time in seconds,
TD = time dial setting,
M = multiples of pickup.

Curve C1: Standard Inverse - See Figure 2.53

$$t_m = TD \left[\frac{0.14}{M^{0.02} - 1} \right] \qquad t_r = \frac{TD \cdot 13.5}{1 - M^2}$$

Beyond 20 multiples of pickup, all characteristics become definite-time equal to the time of M = 20.

Curve C2: Very Inverse - See Figure 2.54

$$t_m = TD \left[\frac{13.5}{M - 1} \right] \qquad t_r = \frac{TD \cdot 47.3}{1 - M^2}$$

Curve C3: Extremely Inverse - See Figure 2.55

$$t_m = TD \left[\frac{80.0}{M^2 - 1} \right] \qquad t_r = \frac{TD \cdot 80}{1 - M^2}$$

Curve C4: Long Time Backup - See Figure 2.56

$$t_m = TD \left[\frac{120.0}{M - 1} \right] \qquad t_r = \frac{TD \cdot 120}{1 - M}$$

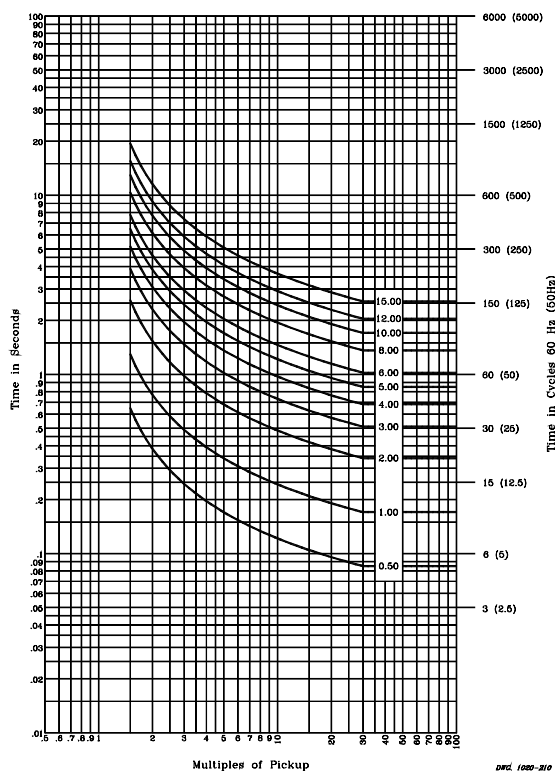


Figure 2.49: Time Curve U1

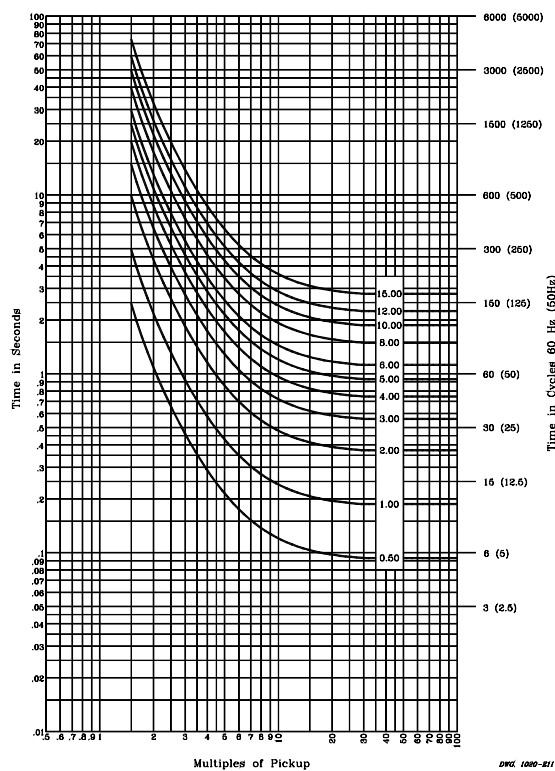


Figure 2.50: Time Curve U2

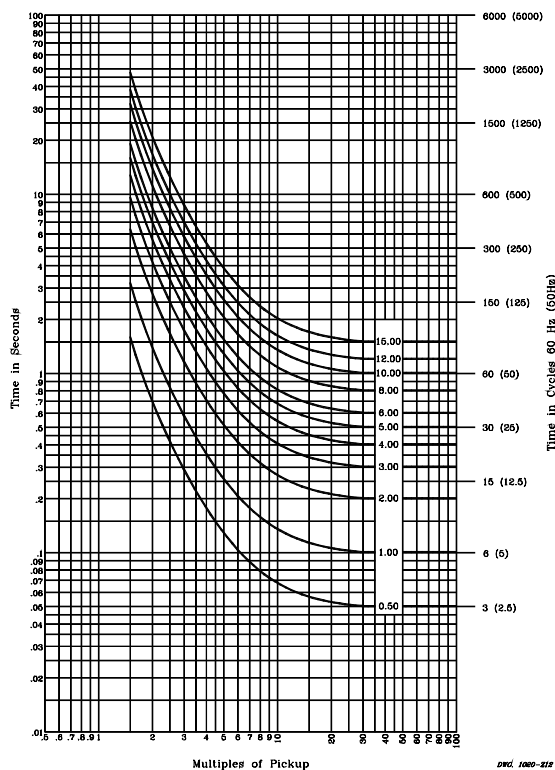


Figure 2.51: Time Curve U3

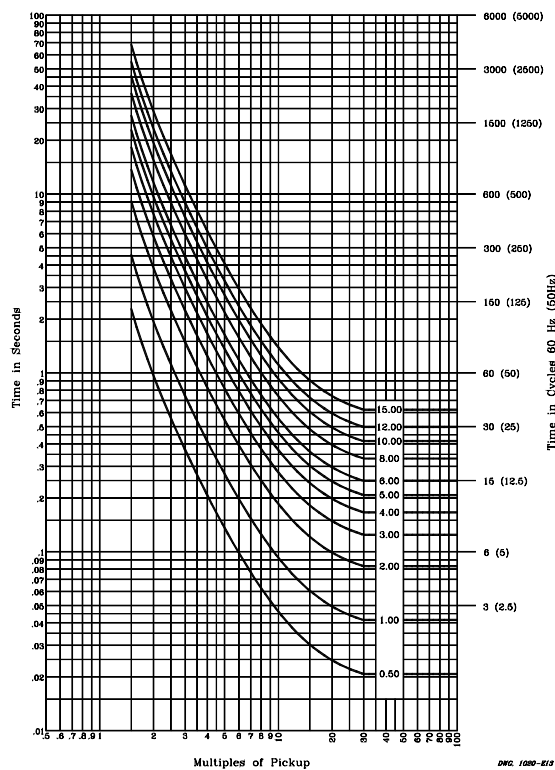


Figure 2.52: Time Curve U4

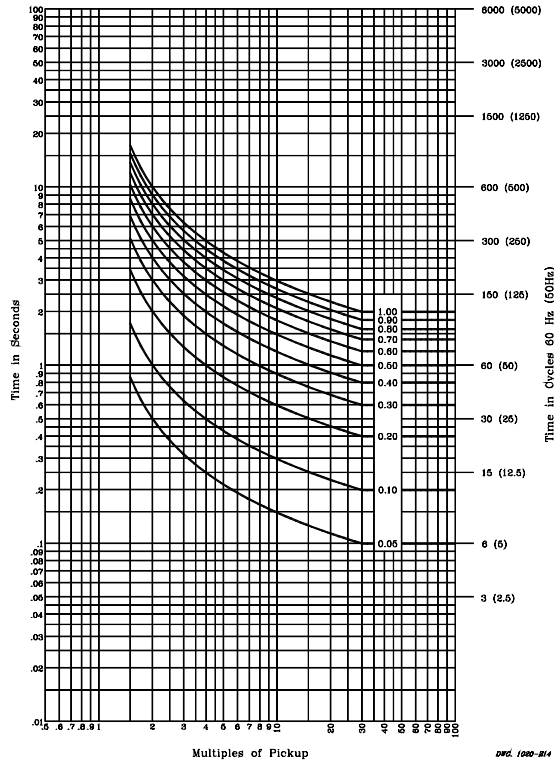


Figure 2.53: Time Curve C1

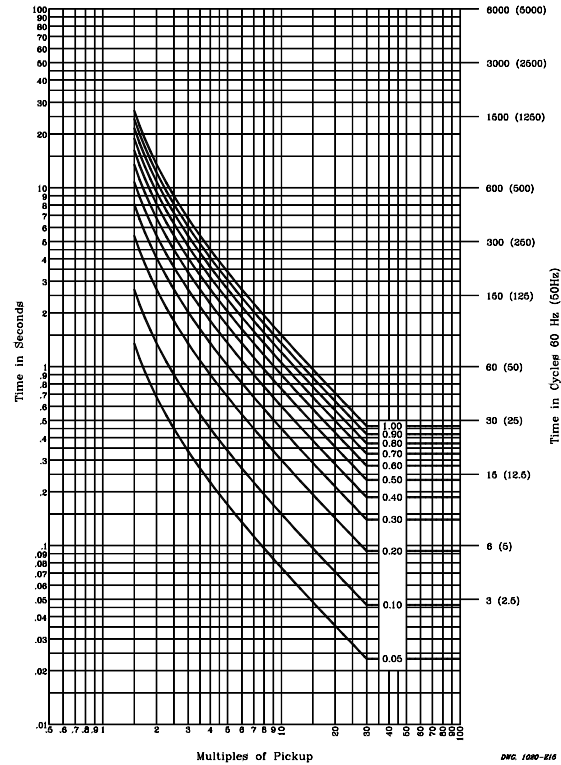


Figure 2.54: Time Curve C2

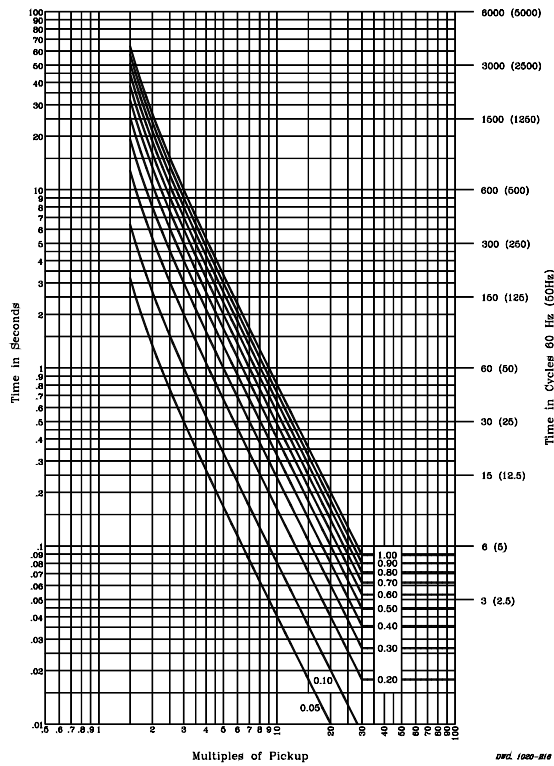


Figure 2.55: Time Curve C3

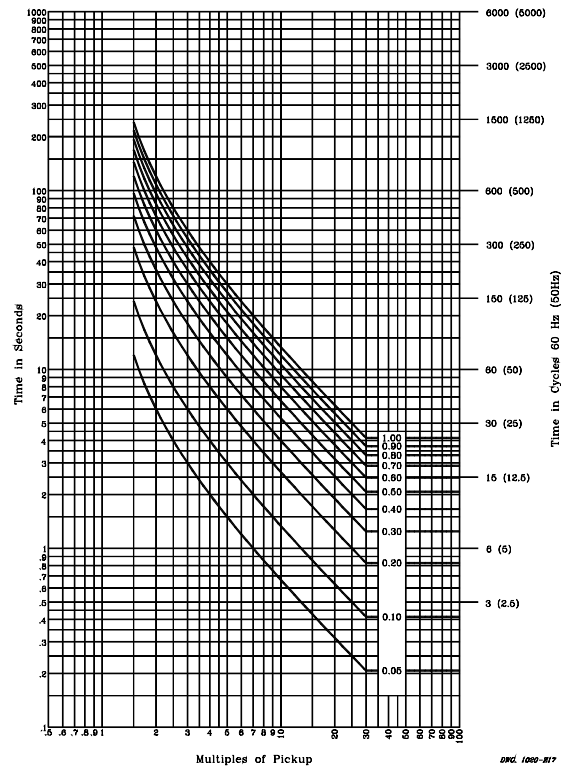


Figure 2.56: Time Curve C4

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SECTION 3: COMMUNICATIONS

INTRODUCTION

This section explains the communications protocol. It also gives examples of commands and front-panel operations for the SEL-321 Relay.

You set and operate the SEL-321 Relay via front-panel controls and serial communications interfaces. The serial interfaces may be connected to a computer terminal and/or modem. Relay communication serves these purposes:

- The relay responds to commands spanning all functions, (e.g., setting, metering, and control operations).
- The relay generates an event record for TRIP output assertions, for an event triggering command, or for the pickup of any relay element that triggers an event record.
- The relay transmits messages in response to changes in system status, e.g., self-test warning.
- No priority is set for communications ports. The last settings saved supersede all other settings. The relay avoids race conditions when two ports are addressed simultaneously.

Note: In this manual, commands you type appear in bold/uppercase: **OTTER**. Keys you press appear in bold/uppercase/brackets: **<ENTER>**.

Relay output appears boxed and in the following format:

EXAMPLE: BUS B, BREAKER 3 Date: 08/21/00 Time: 00:03:25.180

COMMUNICATIONS PROTOCOL

The communications protocol consists of hardware and software features.

Software Protocol

The following software protocol is designed for manual and automatic communications.

1. All commands received by the relay must be of the form:

`<command><CR>` or `<command><CR><LF>`

A command transmitted to the relay should consist of the following:

- A command followed by either a carriage return or a carriage return and line feed.
- You may truncate commands to the first three characters. **EVENT 1 <ENTER>** would become **EVE 1 <ENTER>**.
- Upper and lower case characters may be used without distinction, except in passwords.

Note: The ENTER key on most keyboards is configured to send the ASCII character 13 (^M) for a carriage return. This manual instructs you to press the ENTER key after commands, which should send the proper ASCII code to the relay.

2. The relay transmits all non-interactive messages in the following format:

```
<STX><CR><LF><MESSAGE LINE 1><CR><LF>
<MESSAGE LINE 2><CR><LF>
.
.
<LAST MESSAGE LINE><CR><LF><ETX><STX> <PROMPT><ETX>
```

Each message begins with the start-of-transmission character STX (ASCII character 02) and ends with the end-of-transmission character EXT (ASCII character 03). Each line of the message ends with a carriage return and line feed.

3. The relay indicates the volume of data in its received buffer through an XON/XOFF protocol.

The relay transmits XON (ASCII hex 11) when the buffer drops below one-quarter full.

The relay transmits XOFF (ASCII hex 13) when the buffer is over three-quarters full. Automatic transmission sources should monitor for the XOFF character so they do not overwrite the buffer. Transmission should terminate at the end of the message in progress when XOFF is received and may resume when the relay sends XON.

4. You can use an XON/XOFF procedure to control the relay during data transmission. When the relay receives an XOFF command during transmission, it pauses until it receives an XON command. If there is no message in progress when the relay receives an XOFF command, it blocks transmission of any message presented to its buffer.

The CAN character (ASCII hex 18) aborts a pending transmission. This is useful in terminating an unwanted transmission.

5. Control characters can be sent from most keyboards with the following keystrokes:

```
XON:  <CTRL>Q  (hold down the Control key and press Q)
XOFF: <CTRL>S  (hold down the Control key and press S)
CAN:  <CTRL>X  (hold down the Control key and press X)
```

Additional Software Protocol

The SEL-321-3 Relay includes additional software protocol which supports limited multidrop, fast meter, compressed ASCII, MIRRORED BITS, and DNP 3.00. Refer to *Appendix F*, *Appendix G*, and *Appendix I* for more information on the additional protocols.

Hardware Protocol

The following hardware protocol is designed for manual and automatic communications.

1. If RTS_CTS = N, RTS will always be asserted.
2. If RTS_CTS = Y, RTS deasserts when the relay is busy (momentarily unable to accept characters).
3. Port 3 does not support RTS_CTS hardware handshaking.
4. If RTS_CTS = Y, the relay does not send characters until the CTS input is asserted.

Alarm Conditions

The SEL-321 Relay asserts the ALARM output until self-tests pass when power is applied and at any diagnostic test failure. In addition to these, the ALARM output pulses with the commands and conditions shown in Table 3.1.

Table 3.1: Commands With Alarm Conditions

Command	Condition
2ACCESS	Entering Access Level 2 or Three wrong password attempts
ACCESS	Three wrong password attempts
BREAKER	Entering Breaker Access Level or Three wrong password attempts
COPY	Copying a group into the active setting group
GROUP	Changing the active setting group
PASSWORD	Any password is changed
SET commands	Changing the global settings, an active logic setting group, or the active group setting

Main Board Jumpers

Installing and removing certain main board jumpers affects execution of some commands. Table 3.2 lists the jumpers you should be concerned with and their effects. See ***Jumper Settings*** in ***Section 6: Installation*** for details.

Table 3.2: Hardware Jumpers That Affect Commands

Jumper	Comment
P7: J105	Disables password protection when installed
P7: J106	Enables OPEN and CLOSE commands when installed

Automatic Messages

The relay may send the following messages to the port(s) designated automatic:

Startup Message:

Immediately after power is applied, the relay transmits the following message to the port(s) designated automatic:

```
EXAMPLE: BUS B, BREAKER 3   Date: 08/21/00   Time: 00:00:00.186
SEL-321
=
```

The ALARM relay should pull in.

Group Switch Message:

```
EXAMPLE: BUS B, BREAKER 3   Date: 08/21/00   Time: 23:31:17.489

Active Group = 2
Group Variable = 2

=>>
```

Status Report:

```
SEE THE STATUS COMMAND FOR THE FORMAT OF THE STATUS REPORT
```

Summary Event Report:

```
SEE THE EVENT REPORTING SECTION FOR THE FORMAT OF THE SUMMARY EVENT REPORT
```

On CR_RAM failure, if ERESTART = Y:

```
EXAMPLE: BUS B, BREAKER 3   Date: 08/21/00   Time: 23:31:17.489

Detected Critical RAM Failure. The Relay Is Restarting.

=>>
```

COMMAND CHARACTERISTICS

The relay responds to commands sent from a terminal to each serial communications interface. The relay may also be accessed from the front-panel controls. For relay access via the front-panel controls, see ***Front-Panel Operation*** later in this section.

Access Level 0	- On power-up the relay is in Access Level 0 and honors only the ACCESS command, which moves to Access Level 1. Relay responds "Invalid Command" or "Invalid Access Level" to any other entry.
Access Level 1	- Allows access to only those commands listed under Access Level 1 in Figure 3.1.
Breaker Access Level	- Allows access to CLOSE , OPEN and GROUP commands in addition to Access Level 1 commands.
Access Level 2	- Allows access to COPY , PASSWORD , TARGET , and SET commands plus all commands at lower levels.

Each level has an associated screen prompt and password. Figure 3.1 shows the access levels, passwords, prompts, commands available from each access level, and commands that move you between access levels.



3-5

Changing Access Levels

To enter Level 1, type the following on a terminal connected to the relay via a serial port:

```
=ACCESS <ENTER>
```

The response is:

```
Password: ? @@@@
```

Enter the Level 1 password: **OTTER** and press <ENTER>. The response is:

```
EXAMPLE: BUS B, BREAKER 3    Date: 08/21/00    Time: 15:10:49.966
```

```
Level 1  
=>
```

At the "=>" prompt you can execute any Level 1 command. Commands at this level involve display of information and generation of reports. No relay settings can be changed from Access Level 1. Change to other access levels in a similar manner using the commands and passwords shown in Figure 3.1.

Command Format

Commands consist of three or more characters; only the first three characters of any command are required. You may use upper or lower case characters without distinction, except in passwords.

You must separate arguments from the command by spaces, commas, semicolons, colons, or slashes. Enter commands after the terminal displays the access level prompt.

DESCRIPTION OF COMMANDS

2ACCESS

Use the **2ACCESS** command to enter Access Level 2. A password is required. The default password at this level is set to TAIL at the factory. Use the **PASSWORD** command at Level 2 to change passwords.

The following display indicates successful access:

```
=>2ACCESS <ENTER>
Password: ? TAIL <ENTER>

EXAMPLE: BUS B, BREAKER 3    Date: 08/21/00    Time: 15:10:58.903

Level 2
==>
```

You may use any command from the "=>>" prompt. The relay pulses the ALARM contact closed for one second after any Level 2 access attempt (unless an alarm condition exists).

ACCESS

ACCESS allows you to enter Access Level 1. A password is required. The default password at this level is set to OTTER at the factory; from Access Level 2, use the **PASSWORD** command to change this password, if you wish.

The following display indicates successful access:

```
=ACCESS <ENTER>
Password: ? OTTER <ENTER>

EXAMPLE: BUS B, BREAKER 3    Date: 08/21/00    Time: 15:10:58.903

Level 1
=>
```

If you enter wrong passwords during three consecutive attempts, the relay pulses the ALARM contact closed for one second. This feature can alert personnel to an unauthorized access attempt if the ALARM contact is connected to a monitoring system.

BREAKER

Use the **BREAKER** command to enter breaker control access, Access Level B. A password is required to access this level. The default password for this level is set to EDITH at the factory; use the **PASSWORD** command to change this password.

The following display indicates successful access:

```
=>BREAKER <ENTER>
Password: ? EDITH <ENTER>

EXAMPLE: BUS B, BREAKER 3    Date: 08/21/00    Time: 15:11:14.607

Breaker Level
==>
```

You may use any Level 1 or Level B command from the "==" prompt. The relay pulses the ALARM contact closed for one second after any Level B access attempt (unless an alarm condition exists).

CLOSE

The **CLOSE** command asserts the CC element if no trip is asserted and the breaker is open. The CC element then remains asserted for 30 cycles, or until the breaker closes.

To use the CC element for breaker closing, program the CC element to an output contact using the **SET L** command. For example, if you want to use Output 15 to close the breaker, set OUT15 = CC.

To close the circuit breaker with this command, type **CLOSE <ENTER>**. The prompting message "Close BREAKER (Y/N) ?" is displayed. Then "Are you sure (Y/N)?" Typing **N <ENTER>** after either of the above prompts aborts the closing operation with the message "Command Aborted."

If the Breaker Jumper (P7: J106) is not in place, the relay responds: "Aborted: Breaker Jumper Not in Place."

```
==>CLOSE <ENTER>
Close BREAKER (Y/N) ? Y <ENTER>
Are you sure (Y/N) ? Y <ENTER>
Breaker CLOSED
==>
```

COMM

The **COMM** command displays integral relay-to-relay communications data. To get a summary report, enter the command without any parameters.

```
=>COMM <ENTER>

EXAMPLE: BUS B, BREAKER 3          Date: 08/21/00   Time: 10:45:08.993
SEL-321 POTT

FID=SEL-321-3-R400-V656112pb-Z000000-D20010213

Summary for Mirrored Bits Channel

For 08/15/00 17:18:12.993 to 08/21/00 10:45:08.993

    Total failures      3          Last error  Re-sync
    Relay disabled     1
    Data error         0          Longest failure  0 00:00:00.499
    Re-sync            0
    Underrun           1          Unavailability  0.000688 %
    Overrun            0
    Parity error        1
    Framing error       0

=>
```


Use the **L** parameter to get a summary report, followed by a listing of the COMM records.

```
=>COMM L <ENTER>

EXAMPLE: BUS B, BREAKER 3          Date: 08/21/00   Time: 10:45:19.750
SEL-321 POTT

FID=SEL-321-3-R400-V656112pb-Z000000-D20010213

Summary for Mirrored Bits Channel

For 08/15/00 17:18:12.993 to 08/21/00 10:45:19.750

    Total failures      3          Last error  Re-sync
    Relay disabled      1
    Data error          0          Longest failure  0 00:00:00.499
    Re-sync             0
    Underrun            1          Unavailability  0.000688 %
    Overrun             0
    Parity error        1
    Framing error       0

#   START   START      END   END      DURATION   EVENT
#   DATE    TIME      DATE   TIME
1   08/20/00 13:18:09.236 08/20/00 13:18:09.736 00:00:00.499 Parity error
2   08/18/00 11:43:35.547 08/18/00 11:43:35.637 00:00:00.089 Underrun
3   08/15/00 17:18:12.993 08/15/00 17:18:13.115 00:00:00.121 Relay disabled

=>
```

There may be up to 255 records in the extended report. To limit the number of COMM records displayed in the report to the 10 most recent records, type **COMM 10 L <ENTER>**. To select lines 10 through 20 of the COMM records for display in the report, type **COMM 10 20 L <ENTER>**. To reverse the order of the COMM records in the report, supply a range of row numbers, with the larger number first, i.e., **COMM 40 10 L <ENTER>**. To display all the COMM records that started on a particular day, supply that date as a parameter, i.e., **COMM 2/8/98 L <ENTER>**. To display all the COMM records that started between a range of dates, supply both dates as parameters, i.e., **COMM 2/21/98 2/7/98 L <ENTER>**. Reversing the order of the dates will reverse the order of the records in the report. To receive a summary report for a subset of the records, use one of the above methods while omitting the **L** parameter.

Events occurring while loop-back mode is enabled will have an **L** appended to the record in the report.

To clear the COMM records, type **COMM C <ENTER>**. The prompting message “Are you sure (Y/N) ?” is displayed. Typing **N <ENTER>** aborts the clearing operation with the message “Canceled.”

CONTROL *n*

The **CONTROL** command is a two-step, Access Level 2 command that allows you to control Relay Word bits RB1 through RB16. At the Access Level 2 prompt, type **CONTROL**, a space, and the number of the bit you wish to control (1 - 16). The relay responds by repeating your command followed by a colon. At the colon, type the **CONTROL** subcommand you wish to perform (see Table 3.3).

The following example shows the steps necessary to pulse Remote Bit 5 (RB5) for three seconds.

```
=>>CONTROL 5 <ENTER>
CONTROL RB5: PRB 5 3 <ENTER>
=>>
```

Table 3.3: SEL-321-3 Relay CONTROL Subcommands

Subcommand	Description
SRB <i>n</i>	Set Remote Bit <i>n</i>
CRB <i>n</i>	Clear Remote Bit <i>n</i>
PRB <i>n t</i>	Pulse Remote Bit <i>n</i> for <i>t</i> seconds <i>t</i> = 1 if not otherwise specified Note: <i>n</i> must match the CONTROL command bit number.

COPY m n

The **COPY** command copies settings and logic from setting Group *m* to Group *n* (*m* and *n* equal any combination of 1, 2, 3, 4, 5, or 6). Usually, there are few setting or logic differences between groups. If you enter one setting group with the **SET** command, you can copy it to other groups with the **COPY** command. Use **SET** to modify copied setting groups.

If you copy settings to a group for which event reports exist, those event reports will show "SETTINGS CHANGED SINCE EVENT" when recalled with the **EVE** command. The ALARM output contact closes momentarily when you change settings in an active setting group.

```
=>>COPY 4 6 <ENTER>
COPY 4 to 6
Are you sure (Y/N) ? Y <ENTER>

Please wait...
Settings copied
=>>
```

DATE

The **DATE** command displays the date stored by the internal calendar/clock. Set the date by typing **DATE mm/dd/yy <ENTER>**.

Set the date to August 1, 2000, by entering:

```
=>DATE 08/01/00 <ENTER>
08/01/00
=>
```

The relay sets and displays the new date.

DNP *n*

The **DNP** command is used to re-map the DNP data. Check *Appendix I* for detailed descriptions.

EVENT

The **EVENT** command displays an event report. To select one of the twelve events stored in relay memory, enter the **EVENT** command with a number from 1 for the newest event, through 12 for the oldest event. If no event report is selected, the relay displays the newest event report. Type **EVENT 9 <ENTER>** to display an event report for the 9th event. To view an alternate format event report, append a format selector to the command. For example, type **EVENT 2 L <ENTER>** (parameters following **EVENT** can be entered in any order) to see the long event report for event number 2. The following list shows all possible format selectors.

<u>Format Selector</u>	<u>Event Report Type</u>
Omitted	1/4-Cycle Standard (Default) Event Report
L	1/16-Cycle Long Event Report
R	1/16-Cycle Unfiltered Long Event Report
C	1/16-Cycle Computer Event Report
U	1/16-Cycle Unfiltered Computer Event Report

Interruption of control power clears the event buffers. All event data are lost when event buffers are cleared. However, the relay retains a short history of each of the 40 newest events in non-volatile memory (see the **HISTORY** command).

Note: Adding a space M following the format selector replaces OUT1 - OUT8 with TMB1 - TMB8 and IN1 - IN8 with RMB1 - RMB8.

If an event buffer is empty when you request an event, the relay returns an error message:

```
=>EVENT 12 <ENTER>
Invalid event
=>
```

Refer to *Section 4: Event Reporting* for a detailed explanation of the generation and analysis of event reports.

GROUP

The **GROUP** command designates the Group Variable. This variable (1 - 6) specifies which setting group is the active group when no Setting Group Selection inputs (SS1, SS2, SS3) are assigned or all assigned SS inputs are deasserted. See *Section 2: Specifications* for additional details on group switches.

```
=>>GROUP 2 <ENTER>
Change Group Variable:
Are you sure (Y/N) ? Y <ENTER>
=>>
```

The **GROUP** command does not clear the event report buffer. If the active group is changed, the relay pulses the ALARM output contacts and transmits the following message to ports designated automatic:

```
EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 23:31:17.489

Active Group = 2
Group Variable = 2
=>>
```

If you do not designate a setting group, the relay displays present group information:

```
=>>GROUP <ENTER>

Active Group = 1
Group Variable = 3

=>>
```

Note: The relay will be disabled momentarily while the group switch takes place.

The **GROUP** command at Access Level 1 shows the active group but does not allow changes. The **GROUP** command may also be accessed from the front panel (see *Group Selector* under **LCD Functions and Front-Panel Commands**).

HISTORY

The **HISTORY** command displays up to 40 event summaries. Each summary shows the date, time, event type, fault location, active setting group, and relay targets.

The time is saved to the nearest millisecond and referenced to the Trigger row of data in the event report. If a long fault triggers two event reports, determine the duration by calculating the time difference between the first event report, generated at fault inception, and the second event report generated at the trip. The history is retained in non-volatile EEPROM, so it is there through power failures. Enter **HISTORY C** to clear the history archive. Enter **HISTORY n**, where *n* is a positive number, to limit the history report to the most recent "*n*" events.

The date, time, and type of event are shown for each of the forty most recent events. If the event is a fault, the distance and duration are also shown. An example of the display appears below. Note that in this example only eight events have occurred since the History was reset:

```
=>HISTORY <ENTER>

EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 15:15:09.818

#    DATE      TIME      EVENT    LOCAT  GRP  TARGETS
1  06/21/99  00:01:38.302  AG      94.45   1  INST A G
2  06/20/99  00:31:23.982  ABC     95.09   1  TIME A B C
3  06/20/99  00:31:22.905  AG       9.02   1  INST A G
4  06/20/99  00:31:21.811  BC       9.05   1  TIME B C
5  06/20/99  00:31:20.732  BC      36.01   2  TIME B C
6  06/20/99  00:31:19.655  BC      36.08   2  TIME B C
7  06/20/99  00:31:18.562  BC      35.98   2  TIME B C
8  06/20/99  00:31:17.482  BC      36.25   2  TIME B C
```

If there has been no event, the headings are displayed with the message: History Buffer Empty. Table 3.4 describes entries in the History report.

Table 3.4: History Report Description

Parameter	Entry	Comment
#	1	Event report number
DATE	06/21/92	Date event occurred
TIME	00:01:38.302	Time report triggered
EVENT	AG	A-phase to Ground Fault
	BG	B-phase to Ground Fault
	CG	C-phase to Ground Fault
	AB	AB Two-Phase Fault
	BC	BC Two-Phase Fault
	CA	CA Two-Phase Fault
	ABG	AB Two-Phase to Ground Fault
	BCG	BC Two-Phase to Ground Fault
	CAG	CA Two-Phase to Ground Fault
	ABC T	Three-Phase Faults (T = TPA, TPB, TPC, or 3PT assertion).
	TRIP	Report triggered by TPA, TPB, TPC, or 3PT assertion, no fault.
	EXT	Report triggered by assertion of EXT (external trigger) designated input.
	EXTC	Report triggered by TRIGGER command.
	ER	Report triggered by MER SELOGIC [®] control equations, but no fault detecting element asserted in event report.
LOCAT	94.95	Distance to fault. Entry may be \$\$\$\$\$\$ if the fault locator is unable to generate a reliable location.
GRP	1	Group number of active setting group at time event triggered.
TARGETS	INST AG	Targets asserted for each event. Targets are identified just as they are on front panel.

IRIG

IRIG directs the relay to read the demodulated IRIG-B time-code input at the port on the back panel labeled "DEMOMULATED IRIG-B."

If the relay reads the time code successfully, it updates the internal clock/calendar time and date to the time-code reading. The relay then transmits a message with relay ID, date, and time.

```
=>IRIG <ENTER>
```

```
EXAMPLE: BUS B, BREAKER 3    Date: 08/21/00    Time: 01:45:40.762  
=>
```

If no IRIG-B signal is present or the code cannot be read successfully, the relay sends the error message "IRIG-B DATA ERROR."

Note: Normally, it is not necessary to synchronize using this command because the relay automatically synchronizes every few minutes. The **IRIG** command is provided to prevent delays during testing and installation checkout.

LOOP

The **LOOP** command is used for testing the MIRRORED BITS™ communications channel. With the transmitter of the communications channel physically looped back to the receiver, the MIRRORED BITS addressing will be wrong and ROK will be deasserted (refer to *Appendix G* for more information). The **LOOP** command tells the MIRRORED BITS software to temporarily expect to see its own data looped back as its input. In this mode, LBOK will assert if error-free data is received.

The **LOOP** command without any additional parameters enables looped back mode for 5 minutes, while the inputs are forced to the default values.

```
=>>LOOP <ENTER>
```

```
Loopback will be enabled on the Mirrored Bits port for the next 5 minutes.  
The RMB values will be forced to default values while loopback is enabled.
```

```
Are you sure (Y/N) ? Y <ENTER>
```

```
=>>
```

To enable looped back mode for other than the default 5 minutes, enter the desired number of minutes (1 - 5000) as a command parameter. To allow the looped back data to modify the RMB values, include the DATA parameter.

```
=>>LOOP 10 DATA <ENTER>
```

```
Loopback will be enabled on the Mirrored Bits port for the next 10 minutes.  
The RMB values will be allowed to change while loopback is enabled.
```

```
Are you sure (Y/N) ? N <ENTER>
```

```
Canceled.
```

```
=>>
```

To disable looped back mode before the selected number of minutes, reissue the **LOOP** command with the R parameter.

```
=>>LOOP R <ENTER>

Loopback is disabled.

=>>
```

METER

A **METER** report displays the phase-to-neutral and phase-to-phase voltages and currents in primary kilovolts and amperes. It also displays real and reactive power in megawatts and megavars. An example is shown below.

Use the **METER** command with a number to repeatedly display the meter data that many times. To display a series of eight meter readings, type **METER 8 <ENTER>**.

```
=>METER <ENTER>

EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 15:15:24.640

      A          B          C          AB          BC          CA
I (A)    202      198      197      349      339      344
V (kV)   134.0    133.8    133.6    231.5    230.9    231.9

P (MW)    78.61
Q (MVAR)   13.85

=>
```

The **METER** command may also be executed from the front panel (see *Meter Display* under *LCD Functions and Front-Panel Commands*).

OPEN

The 3PT element asserts in response to the **OPEN** command. If 3PT or TPA, TPB and TPC are assigned to outputs with the **SET L** command, the command will trip the breaker. The 3PT condition remains closed for a minimum duration (TDURD setting) starting with the rising edge of the TRIP output. The 3PT condition drops out only if the trip unlatch conditions are met or if you push the TARGET RESET button on the front panel.

If the TDURD setting is zero, the **OPEN** command is disabled.

To open the circuit breaker by command, type **OPEN <ENTER>**. The prompt "Open BREAKER (Y/N) ?" is transmitted. Answering **Y <ENTER>** yields a second prompt: "Are you sure (Y/N) ?" Answering **Y <ENTER>** again closes the TRIP output relay as described above. If the port is designated AUTO, a summary event report is displayed.

If the Breaker Jumper (P7: J106) is not in place, the relay responds: "Aborted: Breaker Jumper Not in Place."

```

=>>OPEN <ENTER>
Open BREAKER (Y/N) ? Y <ENTER>
Are you sure (Y/N) ? Y <ENTER>
Breaker OPEN
=>>

EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 23:32:38.293

Event: TRIP      Location: +50.00      Frequency:      60.0

Target: EN                                V1 Mem:      131.2 / 77

=>>

```

PASSWORD

The **PASSWORD** command allows you to inspect or change existing passwords. To inspect passwords, type **PASSWORD <ENTER>**. The password for Level 2 and all lower levels are displayed.

```

=>>PASSWORD <ENTER>
1:OTTER
B:EDITH
2:TAIL
=>>

```

To change the password for Access Level 1 to BIKE enter the following:

```

=>>PASSWORD 1 BIKE <ENTER>
Set
=>>

```

The relay sets the password, pulses the ALARM relay closed for approximately one second, and transmits the response "Set" to the display.

After entering new passwords, type **PASSWORD <ENTER>** to inspect them. Make sure they are what you intended, and record the new passwords.

Passwords can be any length up to six numbers, letters, or any other printable characters except delimiters (space, comma, semicolon, colon, and slash). Upper and lower case letters are treated as different characters. Examples of valid, distinct passwords include:

OTTER otter Ot3456 +TAIL+ !@#\$%^ 123456 12345. 12345

If the passwords are lost or you wish to operate the relay without password protection, install the Password Jumper (P7: J105) on the main board. See ***Jumper Settings*** in ***Section 6: Installation*** for details. With no password protection, you may gain access without knowing the passwords and view or change active passwords and settings. Passwords may not be changed from the front panel.

PULSE *n t*

PULSE closes an output contact for testing or control purposes. Close any output contact for 0.125 - 1.0 seconds by executing the command in Access Level 2.

Execute the command **PULSE *n t***, where *n* is the number of the contact you wish to close and *t* is the time, in seconds, the contact remains closed. The contact remains closed for 1 second unless you specify a shorter time. The example below closes output contact 3 for 0.5 seconds.

```
==>PULSE 3 0.5 <ENTER>
```

QUIT

QUIT returns control to Access Level 0 from Level 1, B, or 2. The command displays the relay ID, date, and time of **QUIT** command execution.

Use this command when you finish communicating with the relay to prevent unauthorized access. Control returns to Access Level 0 automatically after a settable interval (see TIMEOUT in Table 3.12) of no activity.

```
=>QUIT <ENTER>
```

```
EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 15:15:32.161  
=
```

RDMEM *m*

The **RDMEM** command allows you to read the contents of selected relay memory areas. This capability helps diagnose failure causes after a CR_RAM self-test failure. Use **RDMEM RAM** to download the information stored in relay RAM (use this command before you remove power from the relay). Use **RDMEM EEPROM** to download the contents of the relay nonvolatile memory. Use **RDMEM ALL** to download all the corrupted information associated with a critical RAM failure.

SET Commands

Configure the relay using four **SET** commands. Table 3.5 lists the various **SET** commands, their formats and uses. Table 3.6 lists the editing keys that you use with all **SET** commands. Following these tables is a detailed discussion of each command.

Table 3.5: Variations on the SET Command

Command	Sets	Format	Application	Front Panel
Note: Parameters following all SET commands may be entered in any order.				
SET	Group settings (see <i>Settings Sheet</i> in <i>Section 5: Applications</i> for complete list)	SET SET 1 SET 2 CTR SET A	Set active group Set Group 1 Set Group 2 starting at entry CTR Access all settings, even if disabled	Yes
SET G	Global settings	SET G SET G IN1	Set input assignments Set front-panel timeout Set group change delay Set global settings starting at entry IN1	Yes
SET P	Set communications port parameters	SET P SET P 1 SET P 1 RTS_CTS	Set active port Set Port 1 Set Port 1 starting at RTS_CTS entry	Yes
SET L	Program SELOGIC control equations	SET L SET L 1 SET L OUT2 SET L 1 OUT2	Program tripping, event reporting, and monitoring conditions for active logic group Program above conditions for Group 1 Program logic for active group starting at OUT2 entry Program logic for Group 1 starting at OUT2 entry	No (comm ports only)
SET R	Set SER	SET R SET R SER1	Set SER SET SER1	No (comm. ports only)

Table 3.6: Editing Keys for SET Commands

Press Key(s)	Results
^ <ENTER>	Moves to previous entry in a setting category until you get to the first entry in the category and then it moves to previous category.
< <ENTER>	Moves to previous settings category when making group settings.
> <ENTER>	Moves to next settings category when making group settings.
<ENTER>	Moves to next entry.
END <ENTER>	Exits editing session and displays all settings. Prompts: "SAVE CHANGES (Y/N)?". Type Y <ENTER> to save changes and exit, N <ENTER> to exit without saving.
<CONTROL> X	Aborts editing session without saving changes.
OFF <ENTER>	Flags a setting as not applicable.

SET *n*

Use the **SET** command to enter group settings for the currently selected group. Edit any desired group with **SET *n*** where *n* = 1...6 corresponding to the group. Enter parameters following the **SET** command in any order.

Normally, as you go through the settings, those settings which are disabled are not shown. Enter **SET A** to access all settings in the active group, regardless of whether or not the setting is disabled. Enter **SET 4 A** to set all settings within Group 4. Enter **SET 4 EOOS A** to set all settings within Group 4, starting with the EOOS setting.

The following screen is displayed by typing **SET 2**. You are prompted to edit each setting by a (?). You are first prompted for a 17-character relay identifier string, then a 39-character terminal identifier string.

After you enter a setting, you are prompted for the next setting. Press **<ENTER>** to move from setting to setting. For a list of all group settings and their parameters, see the ***Settings Sheet*** in **Section 5: Applications**. The settings are arranged into families of related settings to simplify setting changes. You can start at a specific setting by entering the setting name as the indicated argument.

```

=>>SET 2 <ENTER>
GROUP 2
Line Terminal
Relay Identifier: (17 Characters)
RELID =SEL-321 POTT
?
Terminal Identifier: (39 Characters)
TRMID =EXAMPLE: BUS B, BREAKER 3
?
Positive-seq. Line Impedance Magnitude: (ohms sec.) Z1MAG = 7.80
Positive-seq. Line Impedance Angle: (degrees) Z1ANG = 83.97
Zero-sequence Line Impedance Magnitude: (ohms sec.) Z0MAG = 24.79

```

While entering settings, press **<ENTER>** to retain an existing setting, and to move to the next setting. Press **^ <ENTER>** to retain an existing setting and to move to the previous setting. Press **< <ENTER>** to move to the first setting of the previous family. Press **> <ENTER>** to move to the first setting of the next family. To flag a setting as Not Applicable, type **OFF <ENTER>**.

The relay checks each entry to ensure that it is within the allowable input range. If it is not, an "Out of Range" message is generated, and the relay prompts for the setting.

When you finish a setting, it is not necessary to scroll through the remaining settings. Type **END <ENTER>** after your last change to display the new settings and enable prompt.

After you enter all data, the relay displays the new settings and prompts for approval to enable them. Answer **Y <ENTER>** to approve the new settings. If you violate a rule for setting relationships, a fail message in Table 3.7 is displayed, and the settings prompt moves to the first setting that affects the failure. If settings are acceptable, the relay saves them. If a logic scheme was enabled which requires inputs assigned, a warning message in Table 3.8 is displayed. Assign the inputs with the **SET G** command. While the active settings are updated, the relay is disabled and the ALARM output contacts close and all timers and relay elements reset.

Table 3.7: Group SET Fail Messages

SET (Groups)	Comment
UBEND must be less than UBDURD.	Settings for UBEND or UBDURD timers improperly set.
Z2F must be less than Z2R by at least 0.1 ohms.	Z2F and/or Z2R are improperly set in setting procedure.
OSTD must be less than OSBD.	OSTD or OSBD entered wrong in setting procedure.
DIR3 must be R since POTT, DCUB, or DCB is enabled.	DIR3 not set to R in setting procedure.
DIR2 must be F since POTT, DCUB, or DCB is enabled.	DIR2 not set to F in setting procedure.
PLAR must be less than or equal to NLAR.	PLAR or NLAR set incorrectly in setting procedure.
PLAF must be greater than or equal to NLAf.	PLAF or NLAf set incorrectly in setting procedure.
Time dial setting out of range for selected curve family.	Curve family changed without updating time dial.
X1T must be at least 0.1 Ω greater than X1B.	X1T not set at least 0.1 Ω greater than X1B.
R1R must be at least 0.1 Ω greater than R1L.	R1R must be at least 0.1 Ω greater than R1L.
Enabled distance element must not be OFF.	Previously disabled distance element must be given a value.
Enabled supervisory element must not be OFF.	Previously disabled supervisory element must be given a value.

SET (Groups)	Comment
PMHOZ must be > 1 to torque-control 51P with M2P.	M2P is disabled if PMHOZ < 2.
PMHOZ must be > 1 to torque-control 51Q with M2P.	M2P is disabled if PMHOZ < 2.
GMHOZ or QUADZ must be > 1 to torque-control 51N with Z2G.	Z2G is disabled if GMHOZ and QUADZ < 2.
GMHOZ or QUADZ must be > 1 to torque-control 51Q with Z2G.	Z2G is disabled if GMHOZ and QUADZ < 2.
ELE must be Y to torque-control 51P with ZLIN or ZLOUT	ZLIN and ZLOUT are disabled if ELE = N.

Table 3.8: SET or SET G Warning Messages

Message	Comment
EZ1EXT disabled until CLOSE assigned to an input contact.	Logic scheme disabled until CLOSE is assigned to an input.
BT must be assigned to an input contact since DCB is enabled.	DCB scheme disabled if BT is not assigned to an input.
EXTUL must be assigned to an input contact to use TULO = 4.	TULO is set to 4, but EXTUL is not assigned. Logic scheme disabled.
LOG must be assigned to an input contact since DCUB is enabled.	DCUB scheme disabled because LOG is not assigned to an input.
PT must be assigned to an input contact since POTT is enabled.	POTT scheme disabled because PT is not assigned to an input.
Assign PTXFR to an input contact to enable trip suspicion logic.	Trip suspicion logic disabled because PTXFR is not assigned to an input.
PROTOCOL = MB port setting required to use RMBn.	The inputs RMB1 - RMB8 are not updated unless Port 1 or 2 PROTOCOL = MB.

If setting changes were made to the active group, the relay enables them and pulses the ALARM contact.

The Settings Sheet in *Section 5: Applications* gives a complete list of settings made using the **SET** command. For an explanation of the use of the front-panel controls with the **SET** command, see *LCD Functions and Front-Panel Commands* in this section.

SHOWSET

SHOWSET displays the relay settings of the currently selected group. Type **SHOWSET** with a group number (1 - 6) to view the group settings for that particular group. Append this command with an "A" to cause all settings, including inactive settings, to be displayed; normally, settings for disabled functions are not shown. Enter parameters following **SHOWSET** command in any order.

Settings cannot be entered or modified with this command. Change settings with the **SET** command family under Level 2 Access. The **SHOWSET** command results in the following display:

```
=>SHOWSET 2 <ENTER>
GROUP 2

RELID =SEL-321 POTT
TRMID =EXAMPLE: BUS B, BREAKER 3
Z1MAG = 7.80    Z1ANG = 83.97    ZOMAG = 24.79    ZOANG = 81.46
LOCAT = Y      LL    = 100.00    CTR    = 200.0    PTR    = 2000.0
PMHOZ = 3      GMHOZ = 3        QUADZ = 3
DIR1  = F      DIR2  = F        DIR3  = R        DIR4  = F
Z1P   = 6.24    Z2P   = 9.36    Z3P   = 1.87
50PP1 = 2.55    50PP2 = 2.22    50PP3 = 2.45
Z1MG  = 6.24    Z2MG  = 9.36    Z3MG  = 1.87
XG1   = 6.24    XG2   = 9.36    XG3   = 1.87
RG1   = 2.50    RG2   = 5.00    RG3   = 6.00
50L1  = 0.90    50L2  = 0.90    50L3  = 1.30
50G1  = 0.90    50G2  = 0.60    50G3  = 0.50
k01M  = 0.726   k01A  = -3.69    k0M   = 0.726    k0A   = -3.69    T    = 0.00
E00S  = N
ELE   = Y      ZLF   = 9.22    ZLR   = 9.22
PLAF  = 30     NLAF  = -30     PLAR  = 150     NLAR  = 210
Z2F   = 0.77   50QF  = 0.5     Z2R   = 5.45    50QR  = 0.5     a2    = 0.07
E51P  = N
E51N  = Y      51NP  = 0.74    51NC  = U3

Press RETURN to continue
51NTD = 2.00    51NRS = Y        51NTC = 32QF
E50N  = N
E51Q  = Y      51QP  = 2.20    51QC  = U3
51QTD = 2.00    51QRS = N        51QTC = 32QF
E50Q  = N
EVOLT = N
Z2PD  = 20.00   Z3PD  = 0.00
Z2GD  = 20.00   Z3GD  = 0.00
EPOTT = Y      Z3RBD = 5.00    EBLKD = 10.00
ETDPU = 2.00   EDURD = 4.00
EDCUB = N
EZ1EXT= N
EREJO = N
ESOTF = Y      ENCL0 = Y      CLOEND= 10.00    EN52A = N
SOTFD = 30.00  50H   = 11.25
ELOP  = Y      LOPD  = 3.00    50M   = 2.37    59QL  = 14.00    59PL  = 14.00
EPOLD = N      ESPT  = N      ESPO  = N
3POD  = 1.50   ESTUB = Y      50MFD = 20.00    TULO  = 3
TDURD = 9.00   TOPD  = 0.00    TXPU  = 0.00    TXDO  = 0.00
TYPU  = 0.00   TYDO  = 0.00    TZPU  = 0.00    TZDO  = 0.00    ITTD  = 5.00

Press RETURN to continue

=>>
```

SET G

Use the **SET G** command to configure relay inputs, set the front-panel time delay and the group switching time delay. You assign inputs equal to any of the elements listed in Table 2.9. The inputs are then dedicated to monitor those functions. Preceding an entry with (!) causes that input to be treated as the inverse of the given entry. (For example, if connecting a 52B input, assign it as !52A1 to cause it to be interpreted correctly.) The relay displays entered data and prompts for a Y or N response. Enter Y to accept the settings.

IN1 - IN8 (IN1 - IN16 for two I/O board relays) and RMB1 - RMB8 define inputs. See **Section 2: Specifications**, Contact Inputs section, for a complete list of possible assignments for the inputs. FP_TIMEOUT sets the time, in minutes, that the front-panel LCD display waits before resetting. TGR defines the time, in seconds, the relay delays before switching groups. ERESTART enables SEL-321-3 Relays to restart once on detection of a CR_RAM self-test failure. Below are shown the default global settings (one I/O board version - 8 inputs):

```

=>>SET G <ENTER>
Input Contact 1 Assignment:      IN1  = 52A1    ?
Input Contact 2 Assignment:      IN2  = PT      ?
Input Contact 3 Assignment:      IN3  = CLOSE   ?
Input Contact 4 Assignment:      IN4  = PTXFR    ?
Input Contact 5 Assignment:      IN5  = NA      ?
Input Contact 6 Assignment:      IN6  = NA      ?
Input Contact 7 Assignment:      IN7  = NA      ?
Input Contact 8 Assignment:      IN8  = NA      ?
Received Mirrored Bit 1:         RMB1 = NA      ?
Received Mirrored Bit 2:         RMB2 = NA      ?
Received Mirrored Bit 3:         RMB3 = NA      ?
Received Mirrored Bit 4:         RMB4 = NA      ?
Received Mirrored Bit 5:         RMB5 = NA      ?
Received Mirrored Bit 6:         RMB6 = NA      ?
Received Mirrored Bit 7:         RMB7 = NA      ?
Received Mirrored Bit 8:         RMB8 = NA      ?
Front Panel Timeout: (minutes)   FP_TIMEOUT= 5  ?
Group Change Delay: (seconds)    TGR   = 5      ?
CR RAM Diagnostics Action: Restart Enable (Y/N) ERESTART=Y  ?
IN1  = 52A1    IN2  = PT      IN3  = CLOSE   IN4  = PTXFR
IN5  = NA      IN6  = NA      IN7  = NA      IN8  = NA
RMB1 = NA      RMB2 = NA      RMB3 = NA      RMB4 = NA
RMB5 = NA      RMB6 = NA      RMB7 = NA      RMB8 = NA
FP_TIMEOUT= 5      TGR   = 5      ERESTART= Y
Save changes (Y/N) ? Y
Settings saved
=>>

```

To edit a specific global setting, enter that setting name after the **SET G** command. Type **SET G TGR** to edit the TGR global setting. These settings may also be changed from the front panel.

Table 3.9: SET G Fail Messages

Message	Comment
Since a phase of 52A is assigned, all three phases for that breaker must be assigned.	One or more phases of 52A are not assigned for this breaker.
Since a phase of TCM is assigned, all three phases for that breaker must be assigned.	One or more phases are not assigned for this breaker.
Since TCM is assigned for a breaker, 52A must also be assigned for that breaker.	52A has not been assigned to an input contact.
Since some of PARA, PARB, and PARC are assigned, all must be assigned.	One or more of PARA, PARB, or PARC are not assigned.

SHOWSET G

SHOWSET G displays but does not allow you to set the relay global settings.

```
=>SHOWSET G <ENTER>
IN1  = 52A1   IN2  = PT      IN3  = CLOSE  IN4  = PTXFR
IN5  = NA     IN6  = NA     IN7  = NA     IN8  = NA
RMB1 = NA     RMB2 = NA     RMB3 = NA     RMB4 = NA
RMB5 = NA     RMB6 = NA     RMB7 = NA     RMB8 = NA
FP_TIMEOUT= 5      TGR   = 5      ERESTART= Y
=>
```

SET L

SET L manipulates settings made with SELOGIC control equations. See *SELOGIC Control Equations* in **Section 2: Specifications** for a detailed definition of the functions. Use **SET L** to edit the logic settings of the currently selected group. Use **SET L** with a group number (1 - 6) to edit the logic settings of a particular group. Go to a specific logic setting by entering the logic setting label after the group number. For example, enter **SET L 3 MTU** to edit the MTU logic setting within Group 3. Enter parameters following SET command in any order.

Press <ENTER> to retain an existing setting, and move to the next setting. Press ^ <ENTER> to retain an existing setting and move to the previous setting. When you finish entering setting changes, it is not necessary to scroll through the remaining settings. Type **END <ENTER>** after your last change to display the new settings and the enable prompt. After you enter all data, the relay displays the new settings and prompts for approval to enable them. Answer **Y <ENTER>** to approve the new settings.

Settings V through Z can equal any combination of named elements listed in Table 2.7 and Table 2.9. Review SELOGIC control equations Programming in **Section 2: Specifications** if necessary. Some examples of function assignments are shown in the following illustration.

Settings OUT1 through OUT15, TMB1 through TMB8, MTU, MTO, MTCS, and MER may equal any combination of named elements listed in Table 2.7, Table 2.9, or Table 2.10. OUT16 is dedicated to ALARM and is not programmable. The 12 output I/O board option has settings for OUT1 through OUT11. For the two I/O board version of the relay, the second I/O board output settings start with OUT17 regardless of the type of the first I/O board. Some examples of programmable mask and output assignments are as follows (one I/O board version - 15 outputs - shown):


```

=>>SET L 1 <ENTER>
SELogic group 1

V      =NA

?
W      =NA

?
X      =NA

?
Y      =NA

?
Z      =NA

?
MTCS   =M2P + Z2G

?
MTU     =M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF

?
MT0     =M1P + M2P + Z1G + Z2G + 50H

?
MER     =M2P + Z2G + 51NP + 51QP + 50H + LOP*52AA1

?
OUT1    =3PT

?
OUT2    =3PT

?
OUT3    =CC

?
OUT4    =KEY

?
OUT5    =NA

?
OUT6    =NA

?
OUT7    =NA

?
OUT8    =NA

?
OUT9    =NA

?
OUT10   =NA

?
OUT11   =NA

?
OUT12   =NA

```

```

?
OUT13 =NA
?

OUT14 =NA
?
OUT15 =NA

?

?
TMB1 =NA

?
TMB2 =NA

?
TMB3 =NA

?
TMB4 =NA

?
TMB5 =NA

?
TMB6 =NA

?
TMB7 =NA

?
TMB8 =NA

?

V =NA
W =NA
X =NA
Y =NA
Z =NA
MTCS =M2P + Z2G
MTU =M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF
MT0 =M1P + M2P + Z1G + Z2G + 50H
MER =M2P + Z2G + 51NP + 51QP + 50H + LOP*52AA1
OUT1 =3PT
OUT2 =3PT
OUT3 =CC
OUT4 =KEY
OUT5 =NA
OUT6 =NA
OUT7 =NA
OUT8 =NA
OUT9 =NA
OUT10 =NA
OUT11 =NA

Press RETURN to continue
OUT12 =NA
OUT13 =NA
OUT14 =NA
OUT15 =NA
TMB1 =NA
TMB2 =NA
TMB3 =NA

```

```

TMB4  =NA
TMB5  =NA
TMB6  =NA
TMB7  =NA
TMB8  =NA

Save changes (Y/N) ? Y <ENTER>
Settings saved
=>>

EXAMPLE: BUS B, BREAKER 3          Date: 08/21/00    Time: 02:03:04.578

Active Group = 1
Group Variable = 1

=>>

```

Table 3.10: SET L Fail Message

Message	Comment
Overall SELOGIC setting size too large. Try combining equations.	Maximum of 160 SELOGIC terms in the 50 Hz version or 100 in the 60 Hz version exceeded.

SHOWSET L

SHOWSET L displays, but does not allow you to set, the programmable logic settings of the currently selected group. Use the **SHOWSET L** command with a group number (1 - 6) to view the logic settings of any group. You may enter parameters in any order following the **SHOWSET** command. The following illustration shows a report from the one I/O board version (15 outputs) of the relay.

```

=>>SHO L 1 <ENTER>
SELogic group 1

V      =NA
W      =NA
X      =NA
Y      =NA
Z      =NA
MTCS   =M2P + Z2G
MTU    =M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF
MT0    =M1P + M2P + Z1G + Z2G + 50H
MER    =M2P + Z2G + 51NP + 51QP + 50H + LOP*52AA1
OUT1   =3PT
OUT2   =3PT
OUT3   =CC
OUT4   =KEY
OUT5   =NA
OUT6   =NA
OUT7   =NA
OUT8   =NA
OUT9   =NA
OUT10  =NA
OUT11  =NA

```

```

Press RETURN to continue
OUT12 =NA
OUT13 =NA
OUT14 =NA
OUT15 =NA
TMB1  =NA
TMB2  =NA
TMB3  =NA
TMB4  =NA
TMB5  =NA
TMB6  =NA
TMB7  =NA
TMB8  =NA

=>>

```

SET P

Use **SET P** to change settings for the active communications port; Table 3.11 explains the settings. To go to the settings for a particular port, enter the port number (1 - 3) after **SET P**. The following display shows an example for Port 1. To edit a particular setting, enter the setting label after the port number. For example, enter **SET P 3 AUTO** (enter parameters in any order) to edit the AUTO setting for Port 3. The following display shows setting prompts for Port 1. You can also make settings from the front panel (see *Setting Changes via Front Panel* under *LCD Functions and Front-Panel Commands*).

```

=>>SET P 1 <ENTER>
PROTOCOL= SEL      ?
SPEED = 2400      ?
DATA_BITS= 8      ?
PARITY= N         ?
STOP  = 1         ?
TIMEOUT= 0        ?
AUTO  = Y         ?
RTS_CTS= N        ?
FAST_OP= N        ?
PORT:1      XOFF RECEIVED:N      XOFF SENT:N
PROTOCOL= SEL
SPEED = 2400      DATA_BITS= 8      PARITY= N      STOP  = 1
TIMEOUT= 0        AUTO  = Y      RTS_CTS= N      FAST_OP= N
Save changes (Y/N) ? Y <ENTER>
Settings saved
=>>

```

Table 3.11: SET P Fail Message

Message	Comment
MB only allowed on a single port. Port 1 is already using MB.	The MIRRORED BITS protocol can only be in use on a single port.
MB only allowed on a single port. Port 2 is already using MB.	The MIRRORED BITS protocol can only be in use on a single port.

SHOWSET P

SHOWSET P displays communications port settings and XON/XOFF handshaking status of active port without having to use the **SET P** command. To see the settings of a specific port, enter the port number (1 - 3) with the command. Enter **SHOWSET P 1** to view Port 1 settings (parameters may be entered in any order). Table 3.12 describes the settings displayed with the **SHOWSET P** command. See *Section 2: Specifications* for details on communications ports.

```
=>SHOWSET P <ENTER>

PORT:1      XOFF RECEIVED:N      XOFF SENT:N
PROTOCOL= SEL
SPEED = 2400  DATA_BITS= 8      PARITY= N      STOP = 1
TIMEOUT= 0    AUTO = Y          RTS_CTS= N      FAST_OP= N
=>
```

Table 3.12: SET P and SHOWSET P Description

Category	Status	Comment
PORT	1	PORT 1 data shown.
XOFF RECEIVED	N	N = XOFF command not received. Y = XOFF command (CTRL-S) received and no CTRL-Q command received from terminal. If XOFF = Y, relay does not send data.
XOFF SENT	N	N = XOFF message not sent by relay to connected terminal. Y = XOFF message sent to terminal. If data are sent faster than relay can receive, or buffer is 80% full, relay sends XOFF command and sets this setting to Y.
Category	Setting	Comment
PROTOCOL	SEL	SEL = Standard communications. LMD = Distributed Port Switch Protocol (see LMD Application Guide). DNP = Distributed Network Protocol (see <i>Appendix I</i> for the application) MB = Relay-to-Relay communication (7 bits). MB8 = Relay-to-Relay communication (8 bits).
SPEED	2400	Baud rate setting for modem.
DATA_BITS	8	Data bits setting for modem.
PARITY	N	Parity setting for modem.
STOP	1	Stop bit setting for modem.

Category	Setting	Comment
TIMEOUT	0	Time relay waits after last command received before relay reverts to Access Level 0 and aborts any command in process (0.00-30.0 minutes). If set to 0, port never times out.
AUTO	Y	Y = Port set to AUTO.
RTS_CTS	N	N = RS232 request to send - clear to send handshake protocol is OFF (see <i>Communications Protocol</i> earlier in this section). Y = Protocol on. Should be set to Y for use with modem. MBT = MBT9600 modem used with PROTOCOL = MB.
FAST_OP	N	N = Disable fast operate command processing. Y = Enable fast operate command processing. (See Fast Operate Command Processing Application Guide).

SET R

Use **SET R** to change settings for Sequential Event Recorder (SER) report. Check **Section 4: Event Reporting** for a detailed description.

SHOWSET R

SHOWSET R displays Sequential Event Recorder (SER) report settings.

The SHOWSET R report format appears below:

```
=>SHOWSET R <ENTER>

SER trigger lists:

SER1  =IN1 IN2 IN3
SER2  =51PT 51QT M1P Z1G 51NT
SER3  =OUT1
```

STATUS

STATUS allows inspection of self-test status. The relay automatically executes the **STATUS** command whenever the self-test software enters a warning or failure state. If this occurs, the relay transmits a STATUS report from the port(s) designated automatic (see **SET** command, AUTO setting). Type **STATUS 4** to view the status information four times.

The STATUS report format appears below:

```

=>STATUS <ENTER>

EXAMPLE: BUS B, BREAKER 3      Date: 08/21/00      Time: 15:16:42.580
SELF TESTS

W=Warn      F=Fail

      IA      IB      IC      VA      VB      VC      MOF
OS      0      0      0      0      0      0      0

      +5V_PS  +5V_REG -5V_REG +12V_REG -12V_REG +15V_PS -15V_PS
PS      4.96   5.10   -4.98   11.93   -12.09   15.02   -15.21

      TEMP    RAM     ROM     A/D     CR_RAM  EEPROM  SETTINGS
      26.1    OK      OK      OK      OK      OK      OK

Relay Enabled

=>

```

Table 3.13 describes the STATUS report. For a description of self-test and test parameters, see *Self-Test* in *Section 2: Specifications*.

Table 3.13: Status Report Description

Parameter	Status Displayed	Comment
OS:		
IA	0	DC offset voltages in millivolts for the analog channels (IA, IB, IC, VA, VB, VC) and master offset (MOF). F (Failure) or W (Warning) following value in Status Displayed column indicates an out-of-tolerance condition. Only MOF will show a failure condition.
IB	0	
IC	0	
VA	0	
VB	0	
VC	0	
MOF	0	
PS:		
+5V_PS	4.96	Power supply output voltages. W (Warning) or F (Failure) following value indicates out-of-tolerance condition.
+5V_REG	5.10	
-5V_REG	-4.98	
+12V_REG	11.93	
-12V_REG	-12.09	
+15V_PS	15.02	
-15V_PS	-15.12	
TEMP	26.1	Temperature inside the relay in degrees centigrade. W (Warning) or F (Failure) following value indicates out-of-tolerance condition.
RAM	OK	IC socket number in place of OK indicates failure.
ROM	OK	IC socket number in place of OK indicates failure.
A/D	OK	A self-test checks that all analog-to-digital conversion processes complete each sample period.

Parameter	Status Displayed	Comment			
CR_RAM	OK	Critical RAM contents (Global, Group, and Calibration settings) are checked against their image in EEPROM. If normal, OK is displayed. If not, GLOBAL, LOGIC n, GROUP n, CAL, or CODE indicates failed area.			
EEPROM	OK	Checksums of GLOBAL, GROUP, and CAL setting in EEPROM are checked. If agrees with initial checksum, OK is displayed. If not, GLOBAL, LOGIC n, GROUP n, CAL, CODE indicates failed area.			
SETTINGS	OK	Settings self-test checks status of Group, Global, Logic, and Calibration valid settings, and Group LOGVAL settings. If any setting is set to NO, relay protection is disabled and GROUP, LOGIC, CAL, or GLOBAL indicates invalid settings class. Otherwise, OK is displayed.			
The following self-tests are performed by dedicated circuitry in the microprocessor and the SEL-321 Relay main board. Failures in these tests shut down the microprocessor and are not shown in the STATUS report.					
Self-Test	Condition	Limits	Protection Disabled	ALARM Output	Description
Micro-processor Crystal	Failure		Yes	Latched	The relay monitors the microprocessor crystal. If the crystal fails, the relay displays “CLOCK STOPPED” on the LCD display. The test runs continuously.
Micro-processor	Failure		Yes	Latched	The microprocessor examines each program instruction, memory access, and interrupt. The relay displays “VECTOR nn” on the LCD upon detection of an invalid instruction, memory access, or spurious interrupt. The test runs continuously.

The relay settings become invalid by either: (1) setting LOGVAL or VALID to N using the **SET** command, or (2) copying ROM default settings into EEPROM. This occurs when new EEPROMs are installed in the relay, or when the relay is turned off and on after an EEPROM failure.

TARGET

The **TARGET** command displays the target values, and defines the target group used for each target display. The relay maintains a separate target display for each relay display device (the serial ports and the front-panel display).

Entering **TARGET** displays the currently selected target group. To view a different target, enter the target number (0 - 48) after the target command: use **TAR 15** to see Target 15. (Note: The number of targets varies with relay version and number of I/O boards – see *Relay Elements* in **Section 2: Specifications**.) Subsequent **TAR** commands will now show Target 15 as the default. To view a particular target without changing the default, enter an "X" after the target number. **TAR 3 X** shows Target 3, but subsequent **TAR** commands will continue to show Target 15. To view a number of target samples, enter the number of times to view the target (1 - 32000) after the target number. Enter **TAR 44 1000** to repeatedly view the relay inputs on an SEL-321-3 Relay with one I/O board.

When showing multiple samples of targets, the target header repeats every eighth row.

The active target group for the particular display device defaults to TAR 1 when the device (port/panel) times out, the **QUIT** command is executed, or the **TAR R** command is executed.

The **TAR R** command, when executed from any display device, resets the front-panel targets to TAR 1. All targets are listed in Tables 2.6 through 2.24.

Target information may also be accessed from the front panel (see *Target Command* under **LCD Functions and Front-Panel Commands**).

```
=>>TAR 3 <ENTER>

Z4GT   Z3GT   Z2GT   LOP   M4PT   M3PT   M2PT   OPA
0       0       0       1     0      0      0      0
=>>
```

TIME

The **TIME** command displays and sets the internal clock. To set the clock, type **TIME** and the desired setting, then press <ENTER>. Separate the hours, minutes, and seconds with colons, semicolons, spaces, commas, or slashes. To set the clock to 23:30:00, enter:

```
=>TIME 23:30:00 <ENTER>
23:30:00
=>
```

A quartz crystal oscillator provides the time base for the internal clock. You can also set the time clock automatically through the relay time-code input using a source of demodulated IIRIG-B time-code.

TRIGGER

The **TRIGGER** command generates an event record. The command is a convenient way to record all inputs and outputs from the relay at any time you desire (e.g., testing or commissioning).

```
=>TRIGGER <ENTER>
Triggered

=>

EXAMPLE: BUS B, BREAKER 3      Date: 05/01/00      Time: 00:03:34.892

Event: EXTC      Location: $$$$$$      Frequency: 60.0

Targets: EN                      V1 Mem: 0.0 / 180

=>
```

FRONT-PANEL OPERATION

The SEL-321 Relay front panel, shown in Figure 3.2, includes a 2-line, 16-character LCD display, 16 LED target/indicators and eight pushbuttons for enhanced communications.

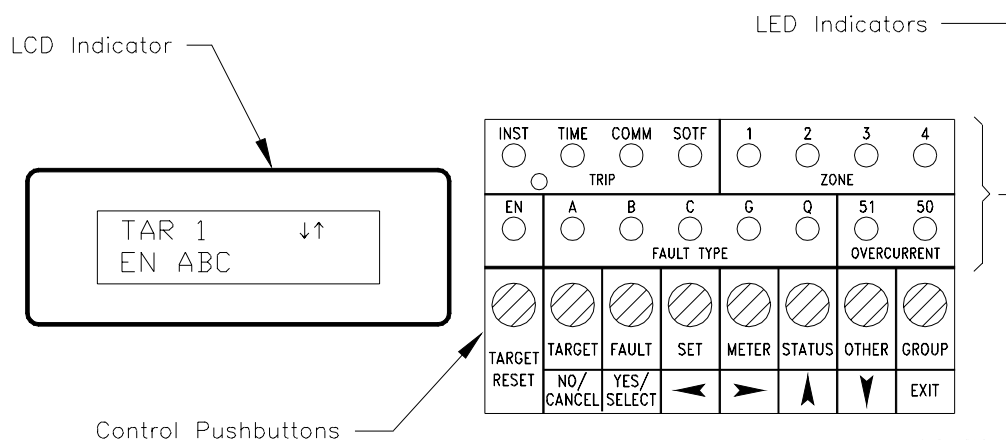


Figure 3.2: SEL-321 Relay Front-Panel Display

LCD FUNCTIONS AND FRONT-PANEL COMMANDS

The LCD display shows fault detection information, metering information, target reset and status display, and self-test status. The display is controlled with eight multifunction pushbuttons that have two corresponding sets of legends. The top row of legends describes button functions for command selection and the bottom row describes specific commands within dialogues. Push-button commands and the corresponding LCD displays are discussed below. Table 3.14 lists commands available from the front-panel control pushbuttons.

Table 3.14: Commands Available From Front Panel

Command	Buttons	See Table	Format	Application	Minimum Access Level
SET	SET	3.18	SET SET 1	Set active group Set Group 1	2
SET G	SET	3.19	SET G	Set input assignments Set front-panel timeout Set group change delay	2
SET P	SET	3.20	SET P 1	Set Port 1	2
TARGET	TARGET	3.15	TAR 1	View target row 1	1
TARGET RESET	TARGET RESET	None	TARGET RESET	LED lamp test target reset and trip unlatch	1
BRE 2AC QUI	OTHER	None	OTHER	BREAKER Level Access Access Level 2 access Return to Access Level 1	1
FAULT	FAULT	3.16	FAULT	View event history information	1
METER	METER	None	METER	View voltage and current inputs	1
STATUS	STATUS	3.17	STATUS	Display self-test status	1
GROUP	GROUP	3.18	GROUP GROUP	View group variable Change group variable	1 B

Front-Panel Reset

If no buttons are pressed on the front panel, the relay waits a time period specified in the FP_TIMEOUT setting and then takes the following actions:

- The front-panel LCD display resets to the default target display.
- The front-panel access level reverts to Access Level 1.
- The LCD back lighting is turned off.
- Any routine being executed via a front-panel command is interrupted.
- The target LEDs revert to the default targets.

FP_TIMEOUT is set to 5 minutes at the factory and can be set from 0 to 30 minutes using the SET G command.

Target Reset

The left-most button is dedicated to the TARGET RESET function. Pressing TARGET RESET causes the front-panel LEDs to illuminate for a one-second lamp test then all target LEDs are cleared except for the LED labeled EN, which is illuminated. It clears trips (TPA, TPB, and TPC

elements) if the trip condition has gone away. It clears automatic diagnostic messages from the front-panel LCD display.

Default Display

If no other display modes are selected, the first line of the LCD display shows the trip target string and the second line contains fault information.

Target Command

Press the TARGET button to display contents of the target registers. Push the Up and Down Arrow (↑ and ↓) buttons to change the target number and view the LEDs. Push the EXIT button or CANCEL button to return to the default display. While the target command is selected, the bottom row of LEDs and value in the LCD display follows the target values as they are updated, thus allowing a monitor function of the targets. Table 3.15 shows a typical TARGET command dialog. The last target row is 40 for a relay with one I/O board, and is 43 for a relay with two I/O boards.

Table 3.15: Target Command Description

Button Pushed	Results Displayed	Comment
TARGET	<div>TAR 1 ↑↓ EN</div>	Target strings shown from TAR Row 1 in Logic Description <i>Section 2: Specifications</i> . EN (enabled) is displayed.
↓	<div>TAR 0 ↑↓</div>	TAR Row 0 displayed.
↓	<div>TAR 43 ↑↓</div>	The last target row is displayed. (↓) starts counting down from the last target. (↑) counts up from target 0.
↑	<div>TAR 0 ↑↓</div>	Pressing (↑) with target 45 displayed returns to the TAR 0 display.
SELECT	<div>TAR 9 ↑↓ MORE→ 50Q4 50Q3 50Q2</div>	(↑) was pressed until TAR 9 was displayed. Second line displays elements picked up. Scroll right to display more elements. Pressing CANCEL or EXIT while in this display causes selected target to revert to default display of TAR 1.
EXIT	<div>DEFAULT DISPLAY</div>	Defaults to display seen before TARGET button was pushed unless an event occurred that would normally update the display, in which case the updated information will be displayed.

Fault Command

Push the FAULT button to display event history records. Use the (↑) and (↓) buttons to scroll between event records, and the (←) and (→) buttons to scroll between fields within a record. Push the EXIT or CANCEL button to return to the default display. The SELECT button has no effect in this mode. Table 3.16 shows a typical FAULT command dialog.

Table 3.16: Fault Command Description

Button Pushed	Results Displayed	Comment
FAULT	<div>1 DATE 05/01/00 TIME 2342:51.732</div>	Displays Date/Time of first event record.
→	<div>1 DATE 05/01/00 TYPE: 1ABC</div>	Displays second field of first event record, showing event faulted phase and type.
→	<div>1 DATE 05/01/00 DIST: 75.13</div>	Displays third field of first event record, showing distance to fault. \$\$\$\$\$\$ may be displayed under some conditions to indicate indeterminate fault location, or event is caused by TRIGGER command.
→	<div>1 DATE 05/01/00 GROUP 5</div>	Displays fourth field of first event record, showing setting group.
↑	<div>2 DATE 05/01/00 TIME 2356:31.238</div>	Displays Date/Time of second event record. Pressing (↓) displays previous event record, (↑) next event record.
EXIT	<div>DEFAULT DISPLAY</div>	Defaults to display seen before TARGET button was pushed unless an event occurred that would normally update the display, in which case the updated information will be displayed.

Meter Display

The METER display is updated every second. Two meter values are displayed at a time. Use the (↑) and (↓) keys to move between meter pairs.

MET IA= -94.31
↑↓ IB= 76.05

Group Selector

When you select GROUP from Access Level 1, the active group and the group variable are shown. To change Groups from the front panel, you first enter Access Level 2 or Breaker Access Level using the OTHER command (see *Password Access*). To change the group, use the up arrow to increment the group variable, the down arrow to decrement it. When the desired group variable is displayed, press SELECT/YES. The display shows:

Execute Group x
Are you sure?

If you choose SELECT/YES again, the keyboard group changes to the group selected. If the group selection logic and inputs are in a state that uses the entered group as the active group, the active group will be switched to the entered group. If you choose CANCEL/NO, the group command is aborted and the default display is shown. (See also *Section 2: Specifications* for discussion of group selection.)

Status Display

When you select STATUS, a STATUS report is displayed. The first row indicates if a warning or failure state exists, or if all self-tests have passed. Use the (↑) and (↓) keys to scroll through the status display. For a complete description of the messages, see the Self-Test portion of *Section 2: Specifications*. An example Status command dialog is shown in Table 3.17. Front-panel status/failure messages include:

Status Messages

OS:IA =0
OS:IB =0
OS:IC =0
OS:VA =0
OS:VB =0
OS:VC =0
OS:MOF =0
+5V_PS =4.86
+5V_REG =5.10
-5V_REG =-4.98
+12V_REG =11.93
-12V_REG =-12.03
+15V_PS =15.02
-15V_PS =-15.21
TEMP =26.1
RAM =OK or U1-8
ROM =OK or U28-31
A/D =OK or FAIL
CR_RAM =OK, GRP1-6, GLO, CAL, or CODE
EEPROM =OK, GRP1-6, GLO, or CAL
SETTINGS =OK

If one of these items has failed or is in a warning state, a "F" or a "W" is appended to the message. (See also Table 2.28 Self-Test Summary.)

Table 3.17: Status Command Description

Button Pushed	Results Displayed	Comment
STATUS	<div> STATUS: FAIL ↑ TEMP 20.1 ↓ </div>	<p>If there is no failure STATUS: OK is displayed. In either event the temperature in degrees centigrade is displayed.</p> <p>Use the (↑and↓) to display status categories in groups of two.</p>
↑	<div> OS:IA = 0 ↑ OS:IB = 0 ↓ </div>	Pressing (↑) selects the next categories.
↑	<div> OS:IC = 0 ↑ OS:VA = 0 ↓ </div>	
↑	<div> OS:VB = 0 ↑ OS:VC = 0 ↓ </div>	

Diagnostic Messages

The first line of the front-panel display may contain a diagnostics message; the second line will then show the former first line.

Password Access

Press OTHER. A three-command OTHER MENU is displayed: 2AC, BRE, and QUI. QUI returns the front panel to Access Level 1. With BRE or 2AC displayed, press SELECT and enter your password for Breaker Access Level or Access Level 2 by scrolling through the set of valid password characters displayed with the (↑) and (↓) buttons. Use the (←) and (→) buttons to move the cursor between characters. Use the SELECT button to deposit the selected character in the password position and advance the active password character. Press EXIT to complete the password entry and validate the password. If you press CANCEL before the password is completely entered, the cursor moves to the active password position and you must use the arrow buttons and the SELECT button to select a new active password character position.

Setting Changes via Front Panel

To make settings from the front panel, you first enter Access Level 2 using the OTHER command (see *Password Access*). There are three settings options: SET GROUP (group settings, Table 3.18), SET G (global settings, Table 3.19), and SET P (port settings, Table 3.20). When you select the setting dialogue, the relay comes up in SET GROUP. Push the Left or Right (←→) buttons to scroll the change settings options. The following example begins after Level 2 is accessed.

Table 3.18: Set Group Command Description

Button Pushed	Results Displayed	Comment
SET	<div> SET GROUP SELECT ↑↓← → </div>	Pressing SET causes the display to come up in SET GROUP. Press SELECT to enter the editing mode for GROUP settings.
SELECT	<div> SET GROUP 1 SELECT ↑↓← → </div>	The active setting group is shown. Press the (↑) button to move to higher setting group, or the (↓) button to go to lower setting group.
↑	<div> SET GROUP 2 SELECT ↑↓← → </div>	Setting group next higher in order is selected. When the desired choice is in the display, press SELECT. See <i>Section 5: Applications</i> for a complete list of Group Settings.
SELECT	<div> Line Terminal SELECT ↑↓← → </div>	<p>Use the (→) or (↓) buttons to move down the list of settings categories and (←) or (↑) to move back up the list. Use the SELECT button to select a settings category. The setting categories appear in the order listed below.</p> <p> Line Terminal Dist Zone Enable Zones/Levels Dir Phase Distance Phase Dist OC Mho Ground Dist Quad Ground Dist Gnd Dist O/C Sup Zero-Seq Comp Out-of-Step Load Encroach Neg-Seq Direct Phase TOC Residual TOC Residual O/C Negative-Seq TOC Neg-Seq O/C Elem Voltage Elements Time-Step Backup Perm Overreach DCUB Scheme Zone 1 Extension REJO SOTF LOP Logic Misc Scheme Logic Misc Timers </p>

Button Pushed	Results Displayed	Comment
		If you press the (→) or (↓) button at the bottom of the list, relay displays Save Settings YES/NO prompt to end session.
→	Dist Zone Enable SELECT ↑↓← →	Next category on list selected.
→	Zone/Levels Dir SELECT ↑↓← →	Next category on list selected.
→	Phase Distance SELECT ↑↓← →	Next category selected again. Press SELECT button to enter the edit mode. Pressing SELECT after making settings saves the settings when the session ends. Pressing NO/CANCEL at any time terminates existing setting.
SELECT	Phase Distance Z1P = 6.24	Once you select a settings category, use the (↑↓) button to scroll among settings in the category. Use the (←) and (→) arrow to select the previous or following category.
↓	Phase Distance Z2P = 9.36	Next variable Z2P is displayed within Phase Distance settings.
SELECT	Phase Distance Z2P = +00009.3 <u>6</u>	Press SELECT to enter edit mode. Use the (←) and (→) buttons to select character to edit. Character selected is underscored.
←	Phase Distance Z2P = +00009.3 <u>6</u>	Use arrow buttons to edit setting values. For settings with limited number of choices, use the (→) or (←) buttons to move within lists. An (*) indicates an item from a list. For numerical values, use the (←) and (→) buttons to move between digit positions. In each position, use the 8 button to increment the digit, the 9 button to decrement. When the desired value is displayed, push SELECT to move to the next setting.
↑	Phase Distance Z2P = +00009. <u>4</u> 6	Pressing (↑) incremented the selected digit.
SELECT	Phase Distance Z3P = 1.87	After you have set the last variable of a sub-group, the next upper-level menu item is displayed. Repeat the process until all desired changes are made. To exit, saving all changes, push the EXIT button, followed by the SELECT button.

Button Pushed	Results Displayed	Comment
EXIT	Save Settings Yes/No?	If you press YES/SELECT, an internal diagnostic checks settings for allowable ranges, and if the resultant settings are OK, the settings are changed. If settings are NOT OK, one of the next displays appears.
	FAIL MORE→	See Table 3.7 for an interpretation of failure messages. Use (← →) keys to read message, then EXIT or CANCEL to resume. The settings editing process is re-entered so you may change the setting.
	WARN MORE→ Warning:	Scheme requirements are checked for and, if not found, a warning message is displayed. See Table 3.7 for a list of warning messages. Use (← →) keys to read warning messages then EXIT or CANCEL to resume.
EXIT	DEFAULT DISPLAY	If settings are OK, changes are saved and display defaults to information shown before SET button was pushed.

Table 3.19: Set G Command Description

Button Pushed	Results Displayed	Comment
SET	SET GROUP SELECT ↑↓← →	Pressing SET causes the display to come up in SET GROUP. Press (←) to get to SET G.
←	SET G SELECT ↑↓← →	Press SELECT to enter the editing mode for SET G settings.
SELECT	SET G IN1 = 52A1	Shows present setting for first setting category: IN1. Press (↓ or →) to move to next category.
↓	SET G IN2 = PT	Next setting category is displayed. Press (↓ or ←) to return to previous category.
↑	SET G IN1 = 52A1	Returns to previous category. Press SELECT to display possible selections for this category.
SELECT	SET G IN1 = 52A1 *	(*) at end of line shows you are in list function. Press (← or →) to move through list of entries.

Button Pushed	Results Displayed	Comment
→	<div>SET G IN1 = 52A2 *</div>	New entry is shown for IN1. While in list function, press (↑or↓) to insert or remove NOT (!) function in front of entry.
SELECT	<div>SET G IN2 = PT</div>	List function is exited, new setting for IN1 was saved, and next category (IN2) is displayed.

Table 3.20: Set P Command Description

Button Pushed	Results Displayed	Comment
SET	<div>SET GROUP SELECT ↑↓← →</div>	Pressing SET causes the display to come up in SET GROUP.
→	<div>SET P SELECT ↑↓← →</div>	Press (→) to step through setting choices.
SELECT	<div>SET P 1 SELECT ↑↓← →</div>	Press (→) to select the port desired. Shows Port 1 selected. Press SELECT to enter edit mode.
SELECT	<div>SET P 1 PROTOCOL = SEL</div>	Shows present protocol setting for this port. Press (↓) to move to next setting category for Port 1.
↓	<div>SET P 1 SPEED = 19.2</div>	Shows present baud rate setting for this port. Press SELECT to enter list mode and select new baud rate.
SELECT	<div>SET P 1 SPEED = 19.2 *</div>	(*) at end of line indicates list mode entered. Press (← or →) to step through list of baud rate selections.
→	<div>SET P 1 SPEED = 300 *</div>	New baud rate is displayed. Press SELECT to save new baud rate and move to next setting category for Port 1.
SELECT	<div>SET P 1 DATA_BITS = 8</div>	Shows present DATA_BITS setting for this port. Press SELECT to enter list mode and select new DATA_BITS.
→	<div>SET P 1 DATA_BITS = 7 *</div>	New DATA_BITS is displayed. Press SELECT to save this choice and move to next setting category for Port 1.

Button Pushed	Results Displayed	Comment
SELECT	<div>SET P 1 PARITY = N</div>	Shows present PARITY setting for this port. Press SELECT to enter list mode and select new setting.
SELECT	<div>SET P 1 PARITY = N *</div>	(*) at end of line indicates list mode entered. Press (← or →) to step through list of PARITY selections.
→	<div>SET P 1 PARITY = E *</div>	New PARITY is displayed. Press SELECT to save this choice and move to next setting category for Port 1.
SELECT	<div>SET P 1 STOP = 1</div>	Shows present STOP bits setting for this port. Press SELECT to enter the list mode and select new setting.
SELECT	<div>SET P 1 STOP = 1 *</div>	(*) at end of line indicates list mode entered. Press (← or →) to step through list of STOP selections.
→	<div>SET P 1 STOP = 2 *</div>	New STOP Bits is displayed. Press SELECT to save this choice and move to next setting category for Port 1.
SELECT	<div>SET P 1 TIMEOUT = 0</div>	Shows present TIMEOUT setting for this port. Press SELECT to enter edit mode and select new setting.
SELECT	<div>SET P 1 TIMEOUT = +000000<u>0</u></div>	Seven digit number is displayed with an underscored digit representing a cursor. Press (← or →) to move from digit to digit. Press (↑ or ↓) to change the underscored digit. Press SELECT to save this setting and move to next category.
SELECT	<div>SET P 1 AUTO = N</div>	Shows Port 1 not presently designated AUTO. Press SELECT to enter list mode and select new setting.
SELECT	<div>SET P 1 AUTO = N *</div>	(*) at end of line indicates list mode entered. Press (← or →) to step through list of AUTO selections.
→	<div>SET P 1 AUTO = Y *</div>	New AUTO setting is displayed. Press SELECT to save this choice and move to next setting category for Port 1.
SELECT	<div>SET P 1 RTS_CTS = N</div>	Shows RTS_CTS for Port 1 set to N. Press SELECT to enter list mode and select new setting.
SELECT	<div>SET P 1 RTS_CTS = N *</div>	(*) at end of line indicates list mode entered. Press (7 or 6) to step through list of RTS_CTS selections.

Button Pushed	Results Displayed	Comment
→	<div> SET P 1 RTS_CTS = Y * </div>	New RTS_CTS setting is displayed. Press SELECT to save this choice and move to next setting category for Port 1.
SELECT	<div> Save Settings Yes/No? </div>	Press SELECT again to save settings and exit the SET P edit session. Press CANCEL to abort new settings.

SEL-321-3 TARGET INFORMATION

SEL-321-3 Relay

TAR	Status Indicators							
0	INST	TIME	COMM	SOTF	ZONE1	ZONE2	ZONE3	ZONE4
1	EN	A	B	C	G	Q	51	50
2	Z4G	Z3G	Z2G	Z1G	M4P	M3P	M2P	M1P
3	Z4GT	Z3GT	Z2GT	LOP	M4PT	M3PT	M2PT	OPA
4	67Q4	67Q3	67Q2	67Q1	67N4	67N3	67N2	67N1
5	67Q4T	67Q3T	67Q2T	OST	67N4T	67N3T	67N2T	OSB
6	PD1	3P27	27L	50H	50MF	51NT	51QT	51PT
7	ZLOAD	SOTFE	TCM	ANYTRP	3PO	SPO	REJO	PD2
8	3P50R	51NP	51QP	51PP	50G	50PP	50M	50L
9	50Q4	50Q3	50Q2	50Q1	50N4	50N3	50N2	50N1
10	50ABC	X6ABC	X5ABC	3PT	TPC	TPB	TPA	32QF
11	3P59	59L	59N	59PR	59PB	59QL	59PL	50Q
12	BTX	SPTI	STOP	START	FIDEN	FSC	FSB	FSA
13	32QR	Z1X	CC	EKEY	Z3RB	ATB	ECTT	KEY
14	XAG4	XAG3	XAG2	XAG1	MAG4	MAG3	MAG2	MAG1
15	XBG4	XBG3	XBG2	XBG1	MBG4	MBG3	MBG2	MBG1
16	XCG4	XCG3	XCG2	XCG1	MCG4	MCG3	MCG2	MCG1
17	MBC4	MBC3	MBC2	MBC1	MAB4	MAB3	MAB2	MAB1
18	SPOC	SPOB	SPOA	Z1	MCA4	MCA3	MCA2	MCA1
19	50HH	OSTI	50CA	50BC	50AB	Z4	Z3	Z2
20	RBAD	CBAD	LBOK	ROK	3PTC	3PTB	3PTA	TOP
21	LP1	SS3	SS2	SS1	EXT	DT	BT	PT
22	EXTUL	PARC	PARB	PARA	SPTE	PTXFR	LP2	LOG
23	LP3	CLOSE	52AC2	52AC1	52AB2	52AB1	52AA2	52AA1
24	LP5	LP4	TCMC2	TCMC1	TCMB2	TCMB1	TCMA2	TCMA1
25	DTA	DTB	DTC	LP6	LP7	LP8	LP9	LP10
26	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1
27	RB16	RB15	RB14	RB13	RB12	RB11	RB10	RB9
28	ZT	Z	YT	Y	XT	X	W	V
29	RAG4	RAG3	RAG2	RAG1	MER	MTO	MTU	MTCS
30	RCG4	RCG3	RCG2	RCG1	RBG4	RBG3	RBG2	RBG1
31	50AL4	50AL3	50AL2	50AL1	VPOLV	N3PT	L3PT	PTRX
32	50CL4	50CL3	50CL2	50CL1	50BL4	50BL3	50BL2	50BL1
33	50G4	50G3	50G2	50G1	50CL	50BL	50AL	*
34	OSB4	OSB3	OSB2	OSB1	50PP4	50PP3	50PP2	50PP1
35	TS	TC	TB	TA	ZLOUT	ZLIN	ILOP	50P
36	SPT_EN	*	*	*	*	52AC	52AB	52AA
37	50AB4	50AB3	50AB2	50AB1	ATPC	ATPB	ATPA	50PPL
38	50CA4	50CA3	50CA2	50CA1	50BC4	50BC3	50BC2	50BC1
39	*	51NR	51QR	51PR	*	*	*	*

SEL-321-3 TARGET INFORMATION

SEL-321-3 Relay – One I/O Board Version

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
43	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
44	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
45	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

SEL-321-3 Relay – Two I/O Board Version

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	OUT17	OUT18	OUT19	OUT20	OUT21	OUT22	OUT23	OUT24
43	OUT25	OUT26	OUT27	OUT28	OUT29	OUT30	OUT31	OUT32
44	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
45	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
46	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
47	IN16	IN15	IN14	IN13	IN12	IN11	IN10	IN9
48	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

Note: The ANYTRIP, SPTI, Z1, Z2, Z3, Z4, 3PTC, 3PTB, and 3PTA elements (highlighted in the first table) are to be used for annunciation or auxiliary functions (for example, recloser control, SCADA, and indication). These elements should not be used in any trip logic equations (MTU, MTCS or MTO).

SEL-321-3 RELAY COMMAND SUMMARY

Access Level 0

ACCESS Answer password prompt (if password protection is enabled) to enter Access Level 1. Three unsuccessful attempts pulse ALARM contacts closed for one second.

Access Level 1

2ACCESS Answer password prompt (if password protection is enabled) to enter Access Level 2. This command always pulses the ALARM contacts closed for one second.

BREAKER Answer password prompt (if password protection is enabled) to enter breaker control Access Level B. Allows execution of OPEN, CLOSE, GROUP N, and Access Level 1 commands.

COMM Displays MİRRORED BITS™ communications summary data.

COMM C Clears MİRRORED BITS communications data.

COMM L Displays MİRRORED BITS communications data.

DATE Shows or sets date. DAT 2/3/92 sets date to Feb. 3, 1992. IRIG-B time code input overrides existing month and day settings. DATE pulses ALARM contacts when year entered differs from year stored.

EVENT Shows event record. EVE 1 shows newest event; EVE 12 shows oldest. Default report is 1/4-cycle standard, EVE n L=1/16-cycle standard, EVE n R=1/16-cycle unfiltered, EVE n C=1/16-cycle SEL-5601 Event Report, EVE n U=1/16-cycle unfiltered.

GROUP Shows setting group to use in lieu of active group.

HISTORY Shows DATE, TIME, ZONE/TYPE, LOCATION (distance), GROUP, and front panel targets for the last 40 events.

IRIG Force immediate attempt to synchronize internal relay clock to time code input. Reports ID, Date, Time, or Error Message.

METER Displays meter data.

QUIT Returns control to Access Level 0; returns target display to Relay Targets TAR O. Displays ID, Date, and Time.

SHOWSET n Shows active group settings for Group n. Shows active relay group settings if n omitted.

SHOWSET C Shows calibration settings.

SHOWSET G Shows global settings.

SHOWSET L Displays active logic settings. Append group number (1-6) to display that group's logic settings.

SHOWSET P Shows active port's settings. Append port number (1-3) to display that port's settings.

SHOWSET R Shows SER settings.

STATUS	Shows self-test status.
TIME	Shows or sets time. TIM 13/32/00 sets clock to 1:32:00 PM. IRIG-B synchronization overrides this setting.
TRIGGER	Triggers an event report.

Access Level B

CLOSE	Asserts the CLOSE condition.
GROUP	Specifies currently selected group. Use GROUP n to change selected group to n.
OPEN	Asserts trip condition.

Access Level 2

CONTROL n	Allows you to control Relay Word bits RB1 through RB16.
COPY m n	Copies settings and logic from setting Group m to Group n.
LOOP	Enables MIRRORED BITS loop back mode for testing communications
LOOP R	Disables MIRRORED BITS loop back mode.
PASSWORD	Shows or sets passwords. Command pulses ALARM contacts closed momentarily after password entry. PAS 1 OTTER sets Level 1 password to OTTER. PAS 2 TAIL sets Level 2 password to TAIL.
PULSE n t	Closes an output contact for testing and control purposes.
RDMEM m	Use to download contents of selected memory areas. m = RAM, EEPROM, or ALL.
SET n	Use to enter group settings. If n argument omitted, edits active group.
SET G	Use to enter new global settings.
SET L	Use SET L n to edit Group n's logic settings. Selects active logic group to edit.
SET P	Use SET P n to edit Port n's settings. Changes active port's settings.
SET R	Use to enter new SER settings.
TARGET	Shows target values, and defines target group for display. TAR n displays target row n. TAR R command resets front panel targets to TAR 1.

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SECTION 4: EVENT REPORTING

EVENT REPORT GENERATION

The relay generates event reports in response to the actions listed in Table 4.1. Four different event report formats are available. Which event report format you select to review depends upon the amount of data resolution you require. These formats are:

- **Summary** Quick review of critical fault information for operations personnel
- **Default** 1/4-cycle data resolution for quick review of routine relay operations
- **Long** 1/16-cycle data resolution for detailed review
- **Computer** Use with the SEL-5601 program for detailed review and oscillograph plotting

All summary event reports are automatically sent to all communications ports designated as AUTO in the relay setting communications port settings. The relay can store up to twelve event reports (see *EVENT Command* in *Section 3: Communications* for more details.)

Table 4.1: Event Report Triggering Actions

- Any tripping element assertions (**TPA**, **TPB**, **TPC**, or **3PT**)
- TRIGGER command execution
- Assertion of any element in the MER (mask for event report trigger) logic variable
- External Trigger input assertions

For event reports triggered by **TPA**, **TPB**, **TPC**, or **3PT** assertion, the TYPE designation is appended with a "T." This makes it easy to distinguish between event reports that involve a trip and those which do not.

Table 4.2 lists relay elements which must assert for the relay to record a fault type and fault location in the event report. If none of these elements assert and any action listed in Table 4.1 is true, the relay generates an event report but does not list a fault type or calculate a fault location.

Table 4.2: Event Report Fault Type and Fault Location Enabling Elements

Fault Type	Elements				
Phase-phase or three-phase	M1P	M2P	M3P	M4P	
Single-Line-Ground	Z1G	Z2G	Z3G	Z4G	
	67N1	67N2	67N3	67N4	51NP

Event records taken with no triggering relay elements have the type shown in Table 4.3.

Table 4.3: Event Record Type

Type	Comment
TRIP	Report triggered by TPA, TPB, TPC, or 3PT assertion, no fault.
EXT	Report triggered by assertion of EXT (external trigger) designated input.
EXTC	Report triggered by TRIGGER command.
ER	Report triggered by MER SELOGIC [®] control equations, but no fault detecting element asserted at trigger instant.

The MER mask triggers event reports on the rising-edge of the first element in the mask. The relay does not generate multiple event reports when additional relay elements within MER pick up; only the first relay element of any continuous sequence triggers an event report.

Tripping and External Trigger events are rising-edge sensitive. For these events, event reports are generated independent of the state of MER. The relay triggers a second report for the same event if **TPA**, **TPB**, **TPC**, or **3PT** asserts. Thus, the relay records the beginning and end of each event. A second event report is not provided, however, if **TPA**, **TPB**, **TPC**, or **3PT** first assert at or less than seven cycles after the first report is triggered.

Event report triggering and time stamping is referenced to the 16th quarter-cycle of data with 1/8-cycle resolution.

SUMMARY EVENT REPORT

The summary report is automatically transmitted to port(s) designated AUTO regardless of access level. The summary event report includes:

- Line terminal identifier (set in the relay setting procedure)
- Date and time
- Event type (see Table 4.4) and fault location
- System frequency at the time of the trip (this is 1/16th of the sampling frequency at the time of the trip)
- Front panel relay targets asserted at the last row of the event report
- The magnitude and angle of positive-sequence polarizing voltage memory at the time of trigger

Table 4.4: Event Types

Event Type	Comment
AG	A-Phase to Ground Fault
BG	B-Phase to Ground Fault
CG	C-Phase to Ground Fault
AB	AB Two-Phase Fault
BC	BC Two-Phase Fault
CA	CA Two-Phase Fault
ABG	AB Two-Phase to Ground Fault
BCG	BC Two-Phase to Ground Fault
CAG	CA Two-Phase to Ground Fault
ABC	Three-Phase Faults

The following shows an example summary event report:

Example: BUS B, BREAKER 3	Date: 08/21/00	Time: 01:36:50.070
Event: AG T Location: 2.43	Frequency: 60.2	
Targets: INST ZONE 1 EN AG	V1 Mem: 131.2/77	
=>		

The relay retains the summary event report buffer when control power is removed. Long event report data is cleared when control power is removed.

DEFAULT EVENT REPORT

Generate the default event report using the EVENT x command, with no format specifier. These reports default to 11-cycle duration, four samples/cycle, and resemble the reports from the SEL-100/200 series relays. Each report contains voltages, currents, factory selected relay elements, inputs and outputs. These reports support analysis of most relay operations. The default report analog data are sampled every 1/16-cycle, but display every quarter-cycle. Binary elements (relay elements, contact inputs, and contact outputs) are displayed as follows:

- If an element is set at any time during a quarter-cycle period, it is displayed as set; otherwise, it is cleared. Given that elements A and B pick up in alternate 1/8-cycles, but not simultaneously, and assuming that element C = A*B, the filtered report would show A and B true, but C false, because A and B were not picked up at the same time.

LONG EVENT REPORT

The long event report is output in response to the **EVENT x L** command. The Header, Summary and Settings sections of the long report are identical to the default report. The event report body differs as follows:

The "L" format option increases the event report resolution to 16 samples/cycle. The bodies of the 4 and 16 samples/cycle reports differ as follows:

- The 16 samples/cycle report has four times as many data rows (total of 11 cycles · 16 rows/cycle = 176 rows).
- The element and contact input and output columns are sampled every 1/8-cycle, and displayed in 1/16-cycle format. If an element asserts for 1/8-cycle, it would indicate assertion for two rows in the long event report.

COMPUTER EVENT REPORT

Generate the computer event report using the **EVENT x C** command. This format provides complete relay element data by attaching a hexadecimal representation of the relay elements on a per processing interval basis. This report is an 11-cycle duration, 16 samples/cycle report. All inputs, outputs, and relay elements are shown in the computer event report.

UNFILTERED EVENT REPORT

Generate the unfiltered event report using the **EVENT x U** command. These reports are identical to the **EVE C** event report, except that the analog data are not digitally filtered. Use the unfiltered event report in computer analysis of data.

MIRRORED BITS™ DISPLAY EVENT REPORT

Generate an event report where TMB1...TMB8 replaces OUT1...OUT8 and RMB1...RMB8 replaces IN1...IN8 by appending any of the event report commands listed above with a space M. With the exception of the display of the first eight inputs and outputs, the remainder of the M form of the event report is identical.

SEQUENTIAL EVENTS RECORDER (SER) REPORT

See the example Sequential Event Recorder (SER) report later in this section.

SER Triggering

The relay triggers (generates) an entry in the SER report for a change of state of any one of the elements listed in the SER1, SER2, and SER3 trigger settings. The factory default settings are:

SER1 = IN1 IN2 IN3

SER2 = 51PT 51QT M1P Z1G 51NT

SER3 = OUT1

The elements are Relay Word bits referenced in Table 2.6 – 2.21. The relay monitors each element in the SER lists every 1/8 cycle. If an element changes state, the relay time-tags the changes in the SER. For example, setting SER2 contains:

time-overcurrent elements(51PT, 51QT, and 51NT)

distance elements(M1P and Z1G)

Thus, any time one of these overcurrent or distance elements picks up or drops out, the relay time-tags the change in the SER.

The other two SER factory settings (SER1 and SER3) trigger rows in the SER event report for such things as optoisolated input (IN1, IN2, or IN3), and output contact (OUT1).

The relay adds the message “Relay newly powered up” to the SER to indicate power up and the message “Relay settings changed” to indicate a settings change (to active setting group).

Each entry in the SER includes SER row number, date, time, element name, and element state.

Making SER Trigger Settings

Enter up to 24 element names in each of the SER settings via the **SET R** command. See Table 2.6 - Table 2.21 for references to valid element (Relay Word bit) names. See the SET R command in Table 3.5 and the relay command summary at the end of **Section 3**. Use either spaces or commas to delimit the elements. For example, if you enter setting SER2 as:

SER2 = 51PT,51QT M1P,,Z1G , 51NT

The relay displays the setting as:

SER2 = 51PT 51QT M1P Z1G 51NT

The relay can monitor up to 72 elements in the SER (24 in each of SER1, SER2, and SER3).

Retrieving SER Reports

The relay saves the latest 256 rows of the SER in volatile memory. Row 1 is the most recently triggered row, and row 256 is the oldest. View the SER report by SER row number as outlined in the example below.

Example SER Serial Port

<u>Commands</u>	<u>Format</u>
SER	If SER entered with no numbers following it, all available rows are displayed (up to row number 256). They display with the oldest row at the beginning (top) of the report and the latest row (row 1) at the end (bottom) of the report.
SER 17	If SER is entered with a single number following it(17 in this example), The display will start at row 17(if it exists) first, and latest row at the end (bottom) of the report.
SER 10 33	If SER is entered with two numbers following it (10 and 33 in this example; 10 < 33), all the rows between (and including) rows 10 and 33 are displayed, if they exist. They display with the oldest row (row 33) at the beginning (top) of the report and the latest row (row 10) at the end (bottom) of the report.

If the requested SER event report rows do not exist, the relay responds:

No SER Data

Clearing SER Report

If you want to clear old SER report and start to record new SER event report, you can use **SER C** command to clear the SER report as:

```
=>SER C <ENTER>  
Clear the SER  
Are you sure (Y/N) ? Y <ENTER>  
Clearing Complete
```

INTERPRETATION OF QUARTER-CYCLE VOLTAGE AND CURRENT DATA

The relay uses secondary quantities presented to the input terminals of the relay. One line of data is displayed for each quarter-cycle. Voltages and currents are shown in primary quantities. The value in each column of the default event report is calculated and scaled as follows:

I_R	Calculated I_R value, multiplied by CTR from group active at time of trigger.
I_A, I_B, I_C	Sampled, filtered value, multiplied by CTR from group active at time of trigger.
V_A, V_B, V_C	Sampled, filtered value, multiplied by PTR from group active at time of trigger.

Analog data are filtered by an analog low-pass filter with a cutoff frequency of 540 Hz. A digital filter processes the sampled data and removes dc and ramp components. The digital filter is a full cycle long, cosine filter centered on the sensed frequency.

Successive lines of the event report occur every 90°. With respect to the present value, the previous value was taken one quarter-cycle earlier and appears to be leading the present value by 90°.

Quarter-cycle event report values can be used to represent the signals as phasors:

The previous value of the output is the Y-component.

The present value of the output is the X-component.

It may seem confusing to refer to the older data as the leading component of the phasor. The following example may help.

Consider a sine wave having zero phase shift with respect to $t = 0$ and a peak amplitude of 1. Now consider two samples, one taken at $t = 0$, the other taken 90° later. They have values 0 and 1, respectively. By the above rules, the phasor components are $(X,Y) = (1,0)$.

Now consider a cosine function. Its samples taken at $t = 0$ and $t+90^\circ$ are 1 and 0; its phasor representation is $(0,1)$. The phasor $(0,1)$ leads the phasor $(1,0)$ by 90° . This coincides with a 90° lead of the cosine function over the sine function.

To construct a phasor diagram of voltages and currents, select a pair of adjacent rows from an area of interest in the quarter-cycle event report. On Cartesian coordinates, plot the lower row (newer data) as the X-components and the upper row (older data) as the Y-components. Rotate the completed diagram to any angle of reference. The magnitude of any phasor equals the square root of the sum of its squares.

Note that moving forward one quarter-cycle rotates all phasors 90° . You can verify this by plotting the phasor diagram with rows 1 and 2, then rows 2 and 3 of an event report. Example Event 1 shows the process of converting the rectangular format voltages and currents displayed in the event report to polar format.

RELAY ELEMENT COLUMNS DATA

The states of all relay elements are indicated in the columns headed "Relay Elements." Active states of the various relay elements are indicated by designator symbols which correspond with the relay element names. The contents of the columns for active relay elements appear as follows.

<u>Column</u>	<u>Value</u>	<u>Description</u>
ZAB	.	If no AB phase-phase distance element set
	1	If Zone 1 AB phase-phase distance element (MAB1) set
	2	If Zone 2 AB phase-phase distance element (MAB2) set, not ZAB1
	3	If Zone 3 AB phase-phase distance element (MAB3) set, not ZAB1 ZAB2
	4	If Zone 4 AB phase-phase distance element (MAB4) set, not ZAB1 ZAB2 ZAB3
ZBC	.	If no BC phase-phase distance element set
	1	If Zone 1 BC phase-phase distance element (MBC1) set
	2	If Zone 2 BC phase-phase distance element (MBC2) set, not ZBC1
	3	If Zone 3 BC phase-phase distance element (MBC3) set, not ZBC1 ZBC2
	4	If Zone 4 BC phase-phase distance element (MBC4) set, not ZBC1 ZBC2 ZBC3

<u>Column</u>	<u>Value</u>	<u>Description</u>
ZCA	.	If no CA phase-phase distance element set
	1	If Zone 1 CA phase-phase distance element (MCA1) set
	2	If Zone 2 CA phase-phase distance element (MCA2) set, not ZCA1
	3	If Zone 3 CA phase-phase distance element (MCA3) set, not ZCA1 ZCA2
	4	If Zone 4 CA phase-phase distance element (MCA4) set, not ZCA1 ZCA2 ZCA3
ZAG	.	If no AG mho or quadrilateral ground distance element asserted
	1	If Zone 1 AG element (XAG1 + MAG1) set
	2	If Zone 2 AG element (XAG2 + MAG2) set, not ZAG1
	3	If Zone 3 AG element (XAG3 + MAG3) set, not ZAG1 ZAG2
	4	If Zone 4 AG element (XAG4 + MAG4) set, not ZAG1 ZAG2 ZAG3
ZBG	.	If no BG mho or quadrilateral ground distance element asserted
	1	If Zone 1 BG element (XBG1 + MBG1) set
	2	If Zone 2 BG element (XBG2 + MBG2) set, not ZBG1
	3	If Zone 3 BG element (XBG3 + MBG3) set, not ZBG1 ZBG2
	4	If Zone 4 BG element (XBG4 + MBG4) set, not ZBG1 ZBG2 ZBG3
ZCG	.	If no CG mho or quadrilateral ground distance element asserted
	1	If Zone 1 CG element (XCG1 + MCG1) set
	2	If Zone 2 CG element (XCG2 + MCG2) set, not ZCG1
	3	If Zone 3 CG element (XCG3 + MCG3) set, not ZCG1 ZCG2
	4	If Zone 4 CG element (XCG4 + MCG4) set, not ZCG1 ZCG2 ZCG3
OOS	t	OOS timing
	B	OOS Block (OSB * !OST)
	T	OOS Trip (OST)
32		Negative-sequence directional element decision. There are two negative-sequence directional elements. Both directional elements cannot be asserted at the same time. The following labeling system is used in the 32 column: Q forward (32QF) q reverse (32QR) . none
51N	.	No 51N condition (!51NT * !51NP)
	p	51N timing (51NP * !51NT)
	T	51N tripped (51NT)
51Q	.	No 51Q condition (!51QP * !51QT)
	p	51Q timing (51QP * !51QT)
	T	51Q tripped (51QT)

<u>Column</u>	<u>Value</u>	<u>Description</u>
51P	.	No 51P condition (!51PP * !51PT)
	p	51P timing (51PP * !51PT)
	T	51P tripped (51PT)
50P	.	No 50P condition (!50L * !50M * !50H)
	L	Low-set overcurrent (50L * !50M * !50H)
	M	Medium-set overcurrent (50M * !50H)
	H	High-set overcurrent (50H)
67N	.	No 67N elements set (!67N1 * !67N2 * !67N3 * !67N4)
	1	Zone 1 67N (67N1)
	2	Zone 2 67N (!67N1 * 67N2)
	3	Zone 3 67N (!67N1 * !67N2 * 67N3)
	4	Zone 4 67N (!67N1 * !67N2 * !67N3 * 67N4)
	.	No 67Q elements set (!67Q1 * !67Q2 * !67Q3 * !67Q4)
67Q	1	Zone 1 67Q (67Q1)
	2	Zone 2 67Q (!67Q1 * 67Q2)
	3	Zone 3 67Q (!67Q1 * !67Q2 * 67Q3)
	4	Zone 4 67Q (!67Q1 * !67Q2 * !67Q3 * 67Q4)
LOP	.	No LOP condition (!LOP)
	*	LOP condition (LOP)

CONTACT INPUTS AND OUTPUTS COLUMNS

The columns headed "Outputs" and "Inputs" show the states of the first eight outputs and the first eight inputs. (These are either the physical outputs and inputs or the mirrored-bit outputs and inputs. The EVE 1 L M shows the long form of the event report with TMB1...TMB8 and RMB1...RMB8 occupying the last columns of the event report.)

Since there are only four columns under each heading, the outputs and inputs are paired in groups of two. If an output is asserted in the first column, a "1" or "2" appears in the column to indicate which output is asserted. If both inputs are asserted, a "B" would appear under the associated column. A period indicates deassertion. All outputs and inputs are assignable. The most important output functions should be assigned to the first eight outputs since they are the only outputs displayed in the standard event report. Functions assigned to outputs above eight are not displayed on the event report but are available in the computer event report format. The following list shows the contents of these columns.

<u>Outputs</u>	<u>Inputs</u>
1 & 2 : Output 1 and Output 2	1 & 2 : Input 1 and Input 2
3 & 4 : Output 3 and Output 4	3 & 4 : Input 3 and Input 4
5 & 6 : Output 5 and Output 6	5 & 6 : Input 5 and Input 6
7 & 8 : Output 7 and Output 8	7 & 8 : Input 7 and Input 8

EXAMPLE EVENT REPORTS

Example Event Report 1

Example: BUS B, BREAKER 3											
FID=SEL-321-3-R400-V656112pb-Z000000-D20010213											
CURRENTS (pri)				VOLTAGES (kV pri)			RELAY	ELEMENTS	OUT	IN	
							ZZZZZZ	555566L	1357	1357	
							ABCABCO	31110770	8888	8888	
IR	IA	IB	IC	VA	VB	VC	BCAGGGS	2NQPPNP	2468	2468	
-4	-447	320	123	-129.3	89.1	40.7	One cycle of data (Quarter-cycle event report)
-2	-112	-328	438	-27.8	-98.5	125.8	
3	447	-320	-124	129.3	-89.1	-40.7	
-1	111	327	-439	27.8	98.4	-125.8	

SEL DIRECTION AND POLARITY CHECK FORM

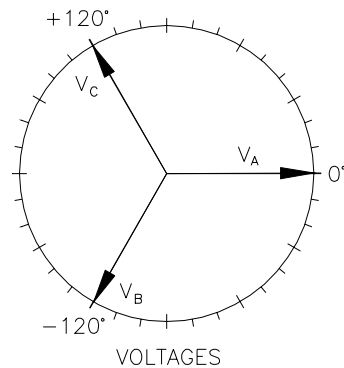
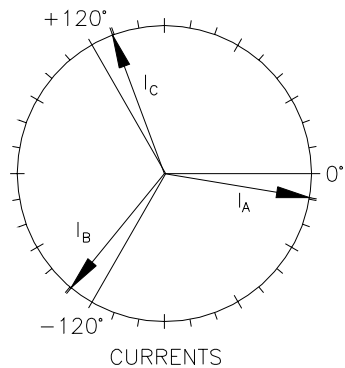
STATION Example 230 kV Line DATE: 02/01/93 TESTED BY _____
 SWITCH NO. _____ EQUIPMENT SEL-321
 INSTALLATION _____ ROUTINE _____ OTHER X

LOAD CONDITIONS:

STATION READINGS: _____ MW (OUT)(IN) _____ MVAR (OUT)(IN) _____ VOLTS _____ AMPS
 SEL READINGS: _____ MW (⊕)(-) _____ MVAR (⊕)(-)

AS SEEN ON SCREEN	I _a	I _b	I _c	V _a	V _b	V _c	
COMPANY NOTATION	I(a)	I(b)	I(c)	V(a)	V(b)	V(c)	
1st LINE CHOSEN (Y COMPONENT)	-447	320	123	-129.3	89.1	40.7	
2nd LINE CHOSEN (X COMPONENT)	-112	-328	438	-27.8	-98.5	125.8	
CALCULATED MAGNITUDE $\sqrt{X^2 + Y^2}$	460.8	458.2	454.9	132.3	132.8	132.2	ROW 1
ANGLE IN DEGREES ARCTAN Y/X	-104.1	135.7	15.7	-102.1	137.9	17.9	
VALUE OF V _a DEGREES TO SUBTRACT TO OBTAIN V _a DEGREES = 0	+102.1	+102.1	+102.1	+102.1	+102.1	+102.1	
@ V _a DEGREES = 0, ANGLE USED TO DRAW PHASOR DIAGRAM	-2.0	-122.2	117.8	0	-120.0	+120.0	ROW 2

USE THE VALUES IN ROWS 1 AND 2 ABOVE TO DRAW PHASOR DIAGRAMS BELOW



DWG: A7-0446X

Example Event Report 2

BUS B, BREAKER 3							Date: 08/21/00		Time: 08:54:29.577		Date and time-tag correspond to the 16th quarter-cycle of this event	
FID=SEL-321-3-R400-V656112pb-Z000000-D20010213							Firmware Identification Code					
CURRENTS (pri)				VOLTAGES (kV pri)			RELAY ELEMENTS		OUT		IN	
							ZZZZZO 555566L		1357		1357	
							ABCABCO 31110770		&&&&		&&&&	
							BCAGGGS 2NQPPNPQ		2468		2468	
IR	IA	IB	IC	VA	VB	VC						
-4	-447	320	123	-129.3	89.1	40.7L...	1...	One cycle of data	
-2	-112	-328	438	-27.8	-98.5	125.8L...	1...		
3	447	-320	-124	129.3	-89.1	-40.7L...	1...		
-1	111	327	-439	27.8	98.4	-125.8L...	1...		
-6	-448	319	123	-129.3	89.1	40.7L...	1...	Input 1 (1) is energized	
-3	-113	-328	438	-27.8	-98.4	125.8L...	1...		
3	447	-320	-124	129.3	-89.1	-40.7L...	1...		
0	112	327	-439	27.8	98.4	-125.8L...	1...		
-5	-447	319	123	-129.3	89.1	40.7L...	1...	50L element asserted	
-3	-113	-328	438	-27.8	-98.4	125.8L...	1...		
2	446	-320	-124	129.3	-89.1	-40.7L...	1...		
0	112	327	-439	27.8	98.4	-125.8L...	1...		
-6	-448	319	123	-129.3	89.1	40.6L...	1...	32QF element asserts 51N element asserts, event trigger 51Q element asserts, event trigger 50M element asserts	
-2	-112	-328	438	-27.9	-98.4	125.8L...	1...		
-582	-138	-320	-124	118.9	-93.4	-44.8L...	1...		
1345	1457	327	-439	21.3	95.3	-129.0	Qpp.M...	1...		
810	368	319	123	-93.4	104.0	55.3	Qpp.M...	1...	Zone 1, A-phase ground distance asserted	
-3301	-3411	-328	438	-14.7	-92.1	132.2	...1...	Qpp.H...	B4..	1...		
-459	-15	-320	-124	78.4	-110.4	-61.6	...1...	Qpp.H...	B4..	1...		
3905	4017	327	-439	14.7	92.0	-132.2	...1...	Qpp.H...	B4..	1...		
456	14	319	123	-78.4	110.4	61.6	...1...	Qpp.H...	B4..	1...	50H element asserted	
-3907	-4017	-328	438	-14.7	-92.0	132.2	...1...	Qpp.H...	B4..	1...		
-460	-15	-321	-124	78.3	-110.5	-61.6	...1...	Qpp.H...	B4..	1...		
3904	4016	327	-439	14.7	92.0	-132.3	...1...	Qpp.H...	B4..	1...		
459	16	320	123	-78.3	110.4	61.6	...1...	Qpp.H...	B4..	1...	KEY bit asserted	
-3907	-4017	-328	438	-14.8	-92.0	132.3	...1...	Qpp.H...	B4..	1...		
126	479	-206	-147	80.1	-108.5	-46.7	...1...	Qpp.H...	B4..	1...		
2555	2610	228	-283	35.0	82.3	-129.8	...1...	Qpp.H...	B4..	1...		
-359	-489	45	85	-98.0	111.4	15.1	...1...	Qpp.H...	B4..	1...	Both OUT1 and OUT2 outputs asserted by 3PT bit	
-604	-602	-65	63	-61.5	-69.0	130.1	...1...	Qpp.M...	B4..		
0	1	-1	0	114.2	-116.3	1.5	Qpp.M...	B...		
-2	-1	-1	0	67.8	65.3	-132.8pp.....	B...		
-2	-2	0	0	-114.2	116.4	-1.5	B...		
-1	0	0	-1	-67.8	-65.2	132.8	B...		
1	2	-1	0	114.2	-116.4	1.5	B...		
-1	-1	0	0	67.8	65.2	-132.8	B...		
-4	-3	0	-1	-114.2	116.4	-1.6	B...		
0	1	0	-1	-67.9	-65.2	132.8	B...		
2	2	0	0	114.2	-116.4	1.6	B...		
-3	-2	-1	0	67.8	65.2	-132.8	B...		
-2	-2	0	0	-114.2	116.4	-1.6	B...		
0	1	0	-1	-67.9	-65.2	132.8	B...		
-1	1	-1	-1	114.2	-116.4	1.6	B...		
-3	-2	-1	0	67.9	65.2	-132.8	B...		
Event: AG Location: +14.92 Frequency: 60.0							A-phase ground fault at 14.92, system frequency is 60 Hz					
Targets: INST ZONE1 EN A G V1 Mem: 132.1 / 77							Front panel targets, V1 memory mag [kV] and angle referenced to A-phase at the trigger instant					

Example Event Report 2 (continued)

GROUP 1				Setting Group 1 was active during this event			
RELID =SEL-321 POTT							
TRMID =BUS B, BREAKER 3							
Z1MAG = 7.80	Z1ANG = 83.97	ZOMAG = 24.79	ZOANG = 81.46				
LOCAT = Y	LL = 100.00	CTR = 200.0	PTR = 2000.0				
PMHOZ = 3	GMHOZ = 3	QUADZ = 3					
DIR1 = F	DIR2 = F	DIR3 = R	DIR4 = F				
Z1P = 6.24	Z2P = 9.36	Z3P = 1.87					
50PP1 = 2.55	50PP2 = 2.22	50PP3 = 2.45					
Z1MG = 6.24	Z2MG = 9.36	Z3MG = 1.87					
XG1 = 6.24	XG2 = 9.36	XG3 = 1.87					
RG1 = 2.50	RG2 = 5.00	RG3 = 6.00					
50L1 = 0.90	50L2 = 0.90	50L3 = 1.30					
50G1 = 0.90	50G2 = 0.60	50G3 = 0.50					
k01M = 0.726	k01A = -3.69	k0M = 0.726	k0A = -3.69	T	= 0.00		
E00S = N							
ELE = Y	ZLF = 9.22	ZLR = 9.22					
PLAF = 30	NLAF = -30	PLAR = 150	NLAR = 210				
Z2F = 0.77	50QF = 0.5	Z2R = 5.45	50QR = 0.5	a2	= 0.07		
E51P = N							
E51N = Y	51NP = 0.74	51NC = U3					
51NTD = 2.00	51NRS = Y	51NTC = 32QF					
E50N = N							
E51Q = Y	51QP = 2.20	51QC = U3					
51QTD = 2.00	51QRS = N	51QTC = 32QF					
E50Q = N							
EVOLT = N							
Z2PD = 20.00	Z3PD = 0.00						
Z2GD = 20.00	Z3GD = 0.00						
EPOTT = Y	Z3RBD = 5.00	EBLKD = 10.00					
ETDPU = 2.00	EDURD = 4.00						
EDCUB = N							
EZ1EXT= N							
EREJO = N							
ESOTF = Y	ENCLO = Y	CLOEND= 10.00	EN52A = N				
SOTFD = 30.00	50H = 11.25						
ELOP = Y	LOPD = 3.00	50M = 2.37	59QL = 14.00	59PL	= 14.00		
EPOLD = N	ESPT = N	ESPO = N					
3POD = 1.50	ESTUB = Y	50MFD = 20.00	TULO = 3				
TDURD = 9.00	TOPD = 0.00	TXPU = 0.00	TXDO = 0.00				
TYPU = 0.00	TYDO = 0.00	TZPU = 0.00	TZDO = 0.00	ITTD	= 5.00		
SELogic group 1				SELOGIC control equations for Group 1			
V =NA							
W =NA							
X =NA							
Y =NA							
Z =NA							
MTCS =M2P + Z2G							
MTU =M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF							
MT0 =M1P + M2P + Z1G + Z2G + 50H							
MER =M2P + Z2G + 51NP + 51QP + 50H + LOP*52AA1							
OUT1 =3PT							
OUT2 =3PT							
OUT3 =CC							
OUT4 =KEY							
OUT5 =NA							
OUT6 =NA							
OUT7 =NA							
OUT8 =NA							
OUT9 =NA							
OUT10 =NA							
OUT11 =NA							
OUT12 =NA							
OUT13 =NA							
OUT14 =NA							
OUT15 =NA							
IN1 = 52A1 IN2 = PT IN3 = CLOSE IN4 = NA							
IN5 = NA IN6 = NA IN7 = NA IN8 = PTXFR							
FP TIMEOUT= 5				TGR = 5			
				Global Settings			

EXAMPLE SEQUENTIAL EVENTS RECORDER (SER) REPORT

```
=>>SER <ENTER>
```

EXAMPLE: BUS B, BREAKER 3		Date: 08/28/00	Time: 08:02:11.998	
FID=SEL-321-3-R400-V656112pb-Z000000-D20010213				
#	DATE	TIME	ELEMENT	STATE
15	08/18/00	00:00:01.286	Relay newly powered up	
14	08/20/00	00:01:30.401	IN1	Asserted
13	08/20/00	00:01:30.442	IN1	Deasserted
12	08/22/00	00:10:49.870	Relay settings changed	
11	08/22/00	00:13:59.728	IN1	Asserted
10	08/28/00	00:10:59.728	Z1G	Asserted
9	08/28/00	00:10:59.730	M1P	Asserted
8	08/28/00	00:10:59.748	OUT1	Asserted
7	08/28/00	00:10:59.836	51QT	Asserted
6	08/28/00	00:11:00.228	IN1	Deasserted
5	08/28/00	00:11:00.228	Z1G	Deasserted
4	08/28/00	00:11:00.228	M1P	Deasserted
3	08/28/00	00:11:00.240	51QT	Deasserted
2	08/28/00	00:11:00.245	OUT1	Deasserted
1	08/28/00	00:11:02.736	IN1	Asserted

```
=>>
```

FIRMWARE IDENTIFICATION

The SEL-321-3 Relay provides a means of interpreting Firmware Identification Data (FID). The FID string is included near the top of each long event report. The string format is as follows:

$$\text{FID} = [\text{PN}] - \text{R}[\text{RN}] - \text{V}[\text{VS}] - \text{Z}[\text{ES}] - \text{D}[\text{RD}]$$

Where:

[PN] = Product Name (e.g., SEL-321-3)

[RN] = Revision Number (e.g., 400)

[VS] = Version Specifications (e.g., 656112pb)

[ES] = External Software Version (e.g., 003002). The first three digits (003) represent the Settings Version Number. The last three digits (002) represent the Protocol Version Number.

[RD] = Release Date (e.g., YYYYMMDD = 20010213)

For the SEL-321-3 Relay, version specifications are interpreted as follows:

$$V[VS] = V[ABCDEFGH]$$

<u>Option</u>	<u>Specifier</u>	<u>Specifier Meaning</u>	<u>Option Description</u>
A	5, 6	50 Hz, 60 Hz	Power System Frequency
B	1, 5	1 A, 5 A	Nominal A per Phase
C	6	67 volts	Nominal Volts per Phase
D	1	Standard 300	Front Panel Type
E	1, 2	1 bank, 2 banks	Number of Banks of Digital Inputs
F	2, 4	2 banks, 4 banks	Number of Banks of Contact Outputs
G	p, n	abc, acb	Phase Rotation Sequence
H			Main Board Version Level

Please contact Schweitzer Engineering Laboratories for more information concerning available versions of the relay (see *Factory Assistance* in *Section 7: Maintenance and Testing*). Version specifications provided above are not intended for ordering purposes but to help users identify software installed in a relay.

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SECTION 5: APPLICATIONS

A 230 kV APPLICATION EXAMPLE FOR POTT SCHEME WITH TIME-STEPPED BACKUP

Purpose

The following is an example of a possible SEL-321 Relay installation. The example shown is for a 5 A nominal relay.

This example shows the steps for setting the relay at Breaker 3 to protect Line 2 in Figure 5.1 between Buses B and C. The basic criteria for protecting this line appear below:

- The communications scheme is Permissive Overreaching Transfer Trip.
- Zone 2 serves as time-step backup.
- Current reversals may occur at the Breaker 3 location.
- The maximum expected load is less than 450 A.

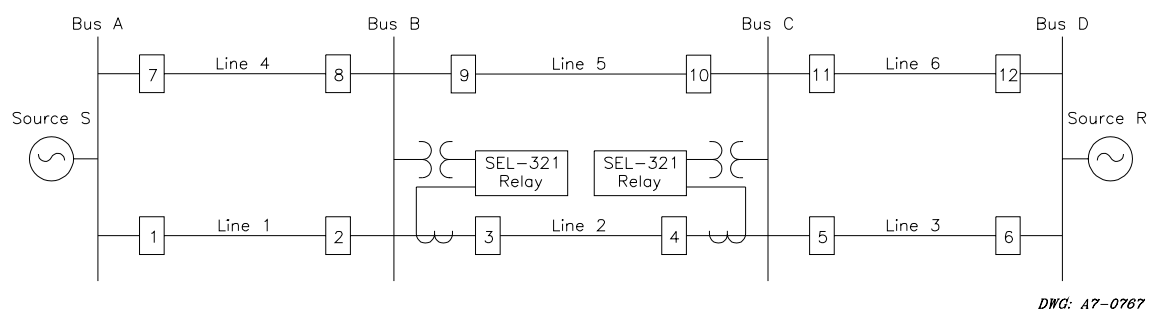


Figure 5.1: 230 kV Setting Example System Single-Line Diagram

System Data

The pertinent system information for this setting example is presented in Table 5.1.

Table 5.1: System Data for 230 kV Setting Example

Nominal System Voltage	: 230 kV (132.8 kV line-to-neutral)	
Line Length	: 100 miles	
Line 2 and Line 5 Impedances:		
Positive-sequence	: $Z_1 = 78.03 \angle 83.97^\circ$	(primary Ω)
Zero-sequence	: $Z_0 = 247.95 \angle 81.46^\circ$	(primary Ω)
Line 1 and Line 4 Impedances	: $Z_1 = 78.24 \angle 83.72^\circ$	(primary Ω)
	: $Z_0 = 239.55 \angle 81.56^\circ$	(primary Ω)
Line 3 and Line 6 Impedances	: $Z_1 = 39.12 \angle 83.72^\circ$	(primary Ω)
	: $Z_0 = 119.78 \angle 81.56^\circ$	(primary Ω)
Source S Impedance	: $Z_{1S} = 17.95 \angle 87.67^\circ$	(primary Ω)
	: $Z_{0S} = 14.99 \angle 80.86^\circ$	(primary Ω)
Source R Impedance	: $Z_{1R} = 3.80 \angle 87.69^\circ$	(primary Ω)
	: $Z_{0R} = 6.02 \angle 80.90^\circ$	(primary Ω)
Current Transformer Ratio	: 1000:5	
Potential Transformer Ratio	: 2000:1	

Relay Settings

Fault voltages and currents in this example are derived from a fault study of the system in Figure 5.1.

Values entered during the actual setting procedure appear in bold immediately after the = prompt in the dashed boxes. A list of all possible relay settings appears in the settings sheet at the end of this section. Use the settings sheet as a worksheet and record for settings.

Relay Terminal Settings

Identifier

The SEL-321 Relay has two identifier strings; the Relay Identifier (RELID) and the Terminal Identifier (TRMID). The RELID is typically used to identify the relay or the type of protection scheme. Typical terminal identifiers include an abbreviation of the substation name and line terminal.

The relay tags each event report with the terminal identifier string. This allows you to distinguish the event report as one generated for a specific breaker and substation. The date of the last functional test may also be included for maintenance purposes.

Positive- and Zero-Sequence Line Impedances

The positive- and zero-sequence secondary impedance values should match those calculated for Line 2. All settings for the SEL-321 Relay are in secondary quantities. The primary impedances must be divided by the ratio of the selected potential transformer ratio (PTR) to the current transformer ratio (CTR).

Fault Locator Enable and Line Length

This setting allows you to enable or disable the fault locating function or use a radial fault locating method. In this example, as with most applications, the fault locating capability of the relay is desired. The line length is selected to match the distance between Bus B and Bus C.

Current and Potential Transformer Ratios

The CTR selected for this example is 1000:5 or 200:1. The PTR selected for this example is 2000:1.

For the relay at Breaker 3:

```
RELID = SEL-321 POTT
TRMID = EXAMPLE: BUS B, BREAKER 3
Z1MAG = 7.80
Z1ANG = 83.97
Z0MAG = 24.79
Z0ANG = 81.46
LOCAT = Y
LL = 100.00
CTR = 200.0
PTR = 2000.0
```

- Other Settings Affected

Values entered for Z1MAG, Z1ANG, Z0MAG, Z0ANG, and LL are used in the fault locator calculations. Z1ANG also sets the maximum torque angle for the phase and ground mho distance elements.

Enable Desired Distance Zones and Directional Sense

The number of phase mho, ground mho, and quadrilateral distance zones is selectable from zero to four. Each number of distance elements is independently selectable. For example, if the quadrilateral ground distance element is not used, set the QUADZ to N.

Once the number of distance element zones is selected, only the elements necessary for the number of selected zones require settings. This includes the distance element reaches and the supervisory overcurrent settings.

Each distance element zone and residual and negative-sequence overcurrent level direction is independently set for forward or reverse directional sense. All four distance element zones and residual and negative-sequence overcurrent levels must be selected for forward (F) or reverse (R) direction sense.

Each directional setting determines the direction for that distance zone and residual or negative-sequence overcurrent level. For example, with DIR1 = F, the Zone 1 phase and ground distance elements and the Level 1 residual and negative-sequence elements are set in the forward-reaching direction.

For this application, three zones of phase and ground distance protection are required. Zone 1, Zone 2, and Zone 4 elements are set in the forward direction. Zone 3 elements are used in the current reversal block logic and are set in the reverse direction.

PMHOZ	=	3
GMHOZ	=	3
QUADZ	=	3
DIR1	=	F
DIR2	=	F
DIR3	=	R
DIR4	=	F

- Other Settings Affected

Number of distance element and supervisory overcurrent settings.

Phase and Ground Distance Element Setting Criteria

Zone 1 Setting

The Zone 1 elements provide instantaneous protection for phase-to-phase, three-phase, and phase-to-ground faults in the first 80-90% of the transmission line. The remainder of the line is protected by the overreaching Zone 2 elements. While the percent error of the impedance element reach is less than 5%, errors in the CT and PT ratios, modeled transmission line data, and fault study data do not permit Zone 1 element settings of 100%.

In this example, the Zone 1 distance elements at Breaker 3 must not reach past Bus C. To prevent overreaching due to the sources of error listed above, the required reach for the Zone 1 three-phase, phase-to-phase, and phase-to-ground mho distance elements are 80% of the positive-sequence impedance of Line 2.

$$\text{Zone 1 Reach} = 0.80 \cdot 78.03 \, \Omega \text{ primary} \angle 84^\circ = 62.42 \, \Omega \text{ primary} \angle 84^\circ$$

The Zone 1 quadrilateral element setting is based upon the same requirements established for the Zone 1 mho elements. The reactive reach is set the same as the mho distance setting. The resistive reach determines sensitivity for high resistance faults on a radial basis. For this example, the Zone 1 resistive reach is set for 25 Ω primary.

Zone 2 Setting

The Zone 2 elements must have adequate reach to detect all phase-to-phase, three-phase and phase-to-ground faults along Line 2, but cannot overreach the Zone 1 elements for faults on either Line 3 or Line 6. In this example, the impedances for Lines 3 and 6 are identical.

$$\text{ZL for Line 2} = 78.03 \, \Omega \text{ primary}$$

$$\text{ZL for Line 3} = \text{ZL for Line 6} = 39.12 \, \Omega \text{ primary}$$

Zone 2 element settings with a reach of 120% of protected line impedance account for the effects of infeed. This point must be verified using a fault study to calculate the apparent ohms at the local terminal for a fault at the remote end of the transmission line. In the example system, 120% is selected for the Zone 2 elements with assurance that all faults in line 2 are detectable, even with infeed from the remote terminals.

Assuming the Zone 1 reach for the line protection at Breakers 5 and 11 is set for 80% of the line impedances of Lines 3 and 6 respectively, verify that a Zone 2 reach of 120% for Breaker 3 does not overreach the Zone 1 elements at Breakers 5 and 11.

$$\begin{aligned}\text{Line 2 Impedance} + [0.8 \cdot \text{Line 3 Impedance}] &= 78.03 \, \Omega + [0.8 \cdot 39.12 \, \Omega] \\ &= 109.33 \, \Omega \text{ primary}\end{aligned}$$

When Zone 2 at Breaker 3 has a set reach of 120%, the effective reach is:

$$\text{Zone 2 at Bkr. 3} = 1.20 \cdot 78.03 \, \Omega = 93.64 \, \Omega \text{ primary } \angle 84^\circ$$

Since $93.64 \, \Omega < 109.33 \, \Omega$, the Zone 2 setting of 120% at Breaker 3 does not overreach the Zone 1 protection of Lines 3 and 6. Any effect of infeed tends to increase the apparent ohms seen at Breaker 3 for faults on Lines 3 and 6.

The Zone 2 quadrilateral element setting is based upon the same requirement established for the Zone 2 mho elements. The reactive reach is set the same as the mho distance setting. The resistive reach determines sensitivity for high resistance faults on a radial basis. For this example, the Zone 2 resistive reach is set for 50 Ω primary.

Zone 3 Setting

This example uses a Permissive Overreaching Transfer Trip (POTT) communications scheme. The current reversal block, echo and weak-infeed logic require reversal of the Zone 3 elements. The Zone 3 element reach at Breaker 3 must be selected to detect all out-of-section faults also detected by the overreaching elements at Breaker 4. At a minimum, the Zone 3 reach setting must equal the impedance the overreaching element at Breaker 4 sees beyond Breaker 3.

Assuming the Zone 2 reach for the line protection at Breaker 4 is set for 120% of the line impedance of Line 2, the Zone 3 reach at Breaker 3 is set at 120% of the Zone 2 overreach from Breaker 4.

When Zone 2 at Breaker 4 has a set reach of 120%, the effective reach is:

$$\text{Zone 2 at Bkr. 4} = 1.20 \cdot 78.03 \, \Omega = 93.64 \, \Omega \angle 84^\circ$$

The Breaker 4 overreach is equal to the Zone 2 setting minus the line impedance:

$$93.64 - 78.03 \, \Omega = 15.61 \, \Omega \text{ primary}$$

$$\text{Zone 3 Reach} = 1.2 \cdot 15.61 \, \Omega \text{ primary } \angle 84^\circ = 18.73 \, \Omega \text{ primary } \angle 84^\circ$$

The Zone 3 quadrilateral element setting is based upon the same requirement established for the Zone 3 mho elements. The reactive reach is set the same as the mho distance setting. The resistive reach determines sensitivity for high resistance faults on a radial basis. The Zone 3 resistive reach must be set greater than the Zone 2 overreach from the remote end, in this case Breaker 4. Assuming the same criteria for the relays at Breaker 4, a conservative setting is to set the Zone 3 resistive reach at 120% of the remote Zone 2 setting. For this example, the Zone 3 resistive reach is set for 120% of 50 Ω primary or 60 Ω primary.

Phase Distance Overcurrent Supervision Setting Criteria

The 50PP elements provide fault detector supervision of the phase distance elements and must pick up for all fault conditions where a phase distance element is expected to operate. Each phase distance element is supervised by independent fault detectors.

The ideal setting for the 50PP element is above load but below minimum fault duty for the most remote three-phase or phase-to-phase fault that the distance element zone must detect. Although it is not ideal, you can set 50PP below load to permit distance element operation for end-of-line faults with magnitudes below load.

The 50PP elements are set based upon the phase-to-phase current for both three-phase and phase-to-phase faults. For three-phase faults, the phase current magnitude must be multiplied by the square root of three to determine the phase-to-phase current magnitude. Phase-to-phase currents for phase-to-phase faults can be derived directly from a fault study. In either case, the lowest current magnitude must be used for the fault detector.

Zone 1 Setting

For the relay at Breaker 3, the governing fault condition for the Zone 1 element is a phase-to-phase fault at Bus C with Line 1 or 4 removed from service. The fault study shows that the lowest phase-to-phase fault current equals 850 A primary for this fault. To ensure that the 50PP1 element picks up for the calculated fault current, select some current value below 850 A. In this example, the value selected for the 50PP1 setting is 510 A (approximately 60% of the minimum fault current).

Zone 2 Setting

The governing fault condition for the Zone 2 elements is a phase-to-phase fault at Bus D with Line 1 or 4 removed from service. The fault study shows that the lowest phase-to-phase fault current equals 743 A primary for this fault. To ensure that the 50PP2 element picks up for the calculated fault current, select some current value below 743 A. In this example, the value selected for the 50PP2 setting is 445 A (approximately 60% of the minimum fault current).

Zone 3 Setting

The governing fault condition for the Zone 3 elements is a phase-to-phase fault at Bus A with Line 1 or 4 removed from service. The fault study shows that the lowest phase-to-phase fault current equals 817 A primary for this fault. To ensure that the 50PP3 element picks up for the calculated fault current, select some current value below 817 A. In this example, the value selected for the 50PP3 setting is 490 A (approximately 60% of the minimum fault current).

Ground Distance Overcurrent Supervision Setting Criteria

The ground distance elements are supervised by phase and ground fault detector overcurrent elements. Each zone has an independent phase and ground fault detector overcurrent element.

Before any ground distance element can pick up, the relay must detect phase and residual current greater than the 50L and 50G settings, respectively. Calculate the phase and residual current for the most remote ground fault or highest expected ground fault resistance in which the distance element zone must operate.

Zone 1 Setting

For the relay at Breaker 3 in the system shown in Figure 5.1, the minimum fault condition for the Zone 1 element is a phase-to-ground fault at Bus C with Line 1 or 4 removed from service. The fault study shows that for this fault, $I_A = 307$ A primary and $I_R = 308$ A primary. To ensure that the 50L1 and 50G1 elements pick up for the calculated fault current, select some current value below the calculated phase and residual current magnitudes.

This value for the 50L1 setting may be below load. In this example, the value selected for the 50L1 setting is 180 A (approximately 60% of the minimum fault current). The value selected for the 50G1 setting is 180 A (approximately 60% of the minimum fault current).

Zone 2 Setting

The minimum fault condition for the Zone 2 element is a phase-to-ground fault at Bus D with Line 1 or 4 removed from service. The fault study shows that for this fault, $I_A = 306$ A primary and $I_R = 202$ A primary. To ensure that the 50L2 and 50G2 elements pick up for the calculated fault current, select some current value below the calculated phase and residual current. This setting accounts for arc resistance and errors in fault study calculations.

This value for the 50L2 setting may be below load. In this example, the value selected for the 50L2 setting is 180 A (approximately 60% of the minimum fault current). In this example, the value selected for the 50G2 setting is 120 A (approximately 60% of the minimum fault current).

Zone 3 Setting

The minimum fault condition for the Zone 3 element is a phase-to-ground fault at Bus A with Line 3 or 6 removed from service. The fault study shows that for this fault, $I_A = 432$ A primary and $I_R = 170$ A primary. To ensure that the 50L3 and 50G3 elements pick up for the calculated fault current, select some current value below the phase and residual current magnitudes.

This value for the 50L3 setting may be below load. In this example, the value selected for the 50L3 setting is 260 A (approximately 60% of the minimum fault current). In this example, the value selected for the 50G3 setting is 100 A (approximately 60% of the minimum fault current.)

Distance Element Setting Calculations

All settings for the SEL-321 Relay are in secondary quantities. For example, the Zone 1 phase distance element is set as follows:

$$\text{Calculations: PTR} = 2000:1 \quad \text{PTR/CTR} = 10$$

$$\text{CTR} = 200:1$$

$$\text{Zone 1 secondary } \Omega = \frac{62.42 \Omega \text{ primary}}{10} = 6.242 \Omega \text{ secondary along the line angle}$$

All phase and ground distance element secondary settings are calculated in the same manner.

All distance elements are supervised by overcurrent elements. For example, the Zone 1 phase distance fault detector is set as follows:

$$\text{Calculations: CTR} = 200:1$$

$$50\text{PP1 secondary } \Omega = \frac{510 \text{ A primary}}{200} = 2.55 \text{ A secondary}$$

All supervisory overcurrent element secondary settings are calculated in the same manner.

Z1P = 6.24
Z2P = 9.36
Z3P = 1.87

50PP1 = 2.55
50PP2 = 2.22
50PP3 = 2.45

Z1MG = 6.24
Z2MG = 9.36
Z3MG = 1.87

XG1 = 6.24
XG2 = 9.36
XG3 = 1.87
RG1 = 2.50
RG2 = 5.00
RG3 = 6.00

50L1 = 0.90
50L2 = 0.90
50L3 = 1.30
50G1 = 0.90
50G2 = 0.60
50G3 = 0.50

- Relay Elements and Other Settings Affected

All set distance and overcurrent supervision elements.

Zero-Sequence Compensation Factor and Non-homogeneous Angle Settings

Zero-Sequence Compensation Factor Setting

The relay uses two zero-sequence compensation factors. The Zone 1 ground distance element has a dedicated zero-sequence compensation factor (k01) and the remaining zones of ground distance protection use a separately set zero-sequence compensation factor (k0).

The zero-sequence compensation factor is set using the following formula:

$$k_0 = (Z_0 - Z_1) / (3 \cdot Z_1)$$

Where:

Z_0 = Zero-sequence impedance

Z_1 = Positive-sequence impedance

For this example both zero-sequence compensation factors are set the same and are based upon the protected line impedance.

$$k_{01} = k_0 = [(247.95 \angle 81.47^\circ) - (78.03 \angle 84^\circ)] / (3 \cdot 78.03 \angle 84^\circ) = 0.726 \angle -3.69^\circ$$

Non-homogeneous Angle Setting

The relay also has a non-homogeneous angle setting (T) which improves the response of the quadrilateral ground distance element. This may be needed when the source impedances at either end of the line and the line itself all have different impedance angles. This angle setting compensates the reactance characteristic of the quadrilateral element to improve the element accuracy.

To determine a setting for T, run single-phase to ground faults where potential overreach may be a concern. These locations are typically at the end of the Zone 1 quadrilateral reach or at the remote bus. Compare the total zero-sequence fault current angle at the fault location and the fault current angle from the relay location. If the angles compare closely, the system is considered homogeneous and compensation is not required.

For our setting example, critical fault locations are those at the end of the Zone 1 reach or remote bus fault where Zone 1 overreach is a concern.

For a single-phase to ground fault at Bus C, the total zero-sequence fault current is 1474 A $\angle -82.7^\circ$. The zero-sequence current contribution from Breaker 3 is 150 A $\angle -82.7^\circ$. Note that the angle between the total fault current and the fault contribution from Breaker 3 is zero. Therefore, the non-homogeneous compensation is not required and T is set to zero.

k01M = 0.726
k01A = -3.69
k0M = 0.726
k0A = -3.69
T = 0

- Relay Elements and Other Settings Affected

All set ground distance elements.

Out-of-Step Setting

Out-of-step tripping or blocking is not required for this application. The out-of-step elements are disabled by setting EOOS = N.

EOOS = N

- Relay Elements and Other Settings Affected

Relay Elements OSB, OST, X5ABC, X6ABC, and 50ABC.

Load-Encroachment Logic Setting

The relay uses a load-encroachment feature, which prevents operation of the three-phase elements under high load conditions. This unique feature permits load to enter a predefined area of the three-phase distance characteristic without causing a tripout.

The load-encroachment characteristic is defined by a load impedance setting in the forward and reverse directions. Defined angle settings determine the load sector in the forward and reverse direction.

The load-encroachment setting should be based upon maximum load flow conditions on the protected line. The maximum short time load flow could be as high as 900 A with Line 5 removed. The maximum conductor current rating is 1200 amps. Assuming a 20% short time overload factor, set the load impedance for 1440 A load. Nominal system voltage is 230 kV line-to-line or 132.8 kV line-to-neutral. Assume a load angle range of $\pm 30^\circ$. Both forward and reverse load ranges are assumed to be the same.

Calculations: CTR = 200:1

PTR = 2000:1

$$I_{load} = \frac{1440}{200} = 7.2 \text{ A secondary}$$

$$V_{bus} = \frac{138790}{2000} = 66.4 \text{ volts secondary}$$

$$Z_{load} = \frac{V_{bus}}{I_{load}} = \frac{66.4}{7.2} = 9.22 \Omega \text{ secondary}$$

ELE = Y
ZLF = 9.22
ZLR = 9.22
PLAF = 30
NLAF = -30
PLAR = 150
NLAR = 210

- Relay Elements and Other Settings Affected

Relay element ZLOAD.

Negative-Sequence Directional Element Settings

The SEL-321 Relay uses a unique negative-sequence directional element. The directional element calculates the negative-sequence impedance at the relaying point and determines the fault direction from the magnitude and sign of the calculated negative-sequence impedance.

Setting the negative-sequence directional element requires careful fault study analysis. Evaluate unbalanced faults (phase-to-phase and phase-to-ground) for the protected line to determine the strongest negative-sequence source at the relay location. Then calculate the negative-sequence impedance seen at the relay location.

Set the forward directional element based upon the strongest negative-sequence source (smallest Z_2) behind the relay for faults in the forward direction. For our example, the strongest negative-sequence source for forward faults is with all lines and sources in service. The negative-sequence source impedance is calculated by applying a phase-to-ground fault at Bus B. Determine the total negative-sequence current contribution from all lines except the protected line and the negative-sequence voltage at Bus B.

The reverse directional element is set based upon the strongest negative-sequence source in front of the relay for faults in the reverse direction. For our example, the strongest negative-sequence source for reverse faults is with Line 5 removed from service. The negative-sequence impedance is calculated by applying a phase-to-ground fault at Bus B. Determine the total negative-sequence current contribution from the protected line and the negative-sequence voltage at Bus B.

The negative-sequence directional element forward (Z_{2F}) and reverse (Z_{2R}) impedance settings are calculated from the Z_{2F} and Z_{2R} impedance values defined above. Sum the magnitudes calculated for Z_{2F} and Z_{2R} , divide by three, and subtract this number from Z_{2R} and add this number to Z_{2F} . The resultant Z_{2F} and Z_{2R} are the forward and reverse setting values. This methodology works for most applications, consult the factory for other setting guidelines for unique applications.

Z_{2F} must be less than Z_{2R} to avoid any overlap where measured Z_2 satisfies both forward and reverse conditions. For security reasons, Z_{2F} and Z_{2R} thresholds must be separated by at least 0.1Ω secondary.

The negative-sequence overcurrent elements, 50QF and 50QR, are set at the minimum setting to provide the maximum sensitivity.

The a_2 factor is used to compensate for highly unbalanced systems. This is typical of systems that have many untransposed lines. The a_2 compensation is a ratio of the negative-sequence current to the positive-sequence current.

The a_2 compensation is typically set based upon the sensitivity requirements of the 50QF and 50QR elements. The a_2 factor must be set so that any load derived positive-sequence current does not prevent operation of the directional element at the minimum negative-sequence current value.

Calculation: PTR = 2000:1

CTR = 200:1

Calculate Z₂ for forward faults:

$$\text{At Bus B: } V_2 F = \frac{28.6 \text{ kV}}{2000} = 14.3 \text{ volts secondary}$$

$$I_2 F = \frac{730}{200} = 3.65 \text{ A secondary}$$

$$\text{From above: } Z_2 F = \frac{-V_2 F}{I_2 F} = \frac{-14.3}{3.65} = -3.91 \Omega \text{ secondary}$$

Calculate Z₂ for reverse faults:

$$\text{At Bus B: } V_2 R = \frac{29.0 \text{ kV}}{2000} = 14.5 \text{ volts secondary}$$

$$I_2 R = \frac{286}{200} = 1.43 \text{ amps secondary}$$

$$\text{From above: } Z_2 R = \frac{-V_2 R}{-I_2 R} = \frac{14.5}{1.43} = 10.13 \Omega \text{ secondary}$$

Summing the magnitudes of the forward and reverse calculated Z₂ as follows:

$$|10.13 \Omega| + |-3.91 \Omega| = 14.04 \Omega$$

Divide the Z₂F and Z₂R plane into three sectors:

$$\frac{14.04 \Omega}{3} = 4.68 \Omega$$

Setting for Z₂F:

$$(-3.91 \Omega) + 4.68 \Omega = 0.77 \Omega$$

Setting for Z₂R:

$$(10.13 \Omega) - 4.68 \Omega = 5.45 \Omega$$

For our example, 50QF = 50QR = 0.5 A (3I₂). The maximum load on Line 2 is 450 amps. For the negative-sequence directional element to operate $I_2 > a_2 \cdot I_1$.

Therefore, the highest a₂ setting is:

$$\frac{I_2 \text{ min}}{I_1 \text{ load}} = \frac{0.167}{2.25} = 0.076$$

Set a2 to some value less than the calculated values for our example a2 is selected for 0.07.

```
Z2F = 0.77
50QF = 0.5
Z2R = 5.45
50QR = 0.5
a2 = 0.07
```

- Relay Elements and Other Settings Affected

32QF and 32QR elements. All ground distance elements and all directionally controlled residual and negative-sequence overcurrent elements.

Phase Time-Overcurrent Element Setting

The phase time-overcurrent element is not required for this application. The phase time-overcurrent element is disabled by setting E51P = N.

```
E51P = N
```

- Relay Elements and Other Settings Affected

Relay elements 51PT and 51PP depend on the 51PP, 51PC, 51PTD, 51PRS, and 51PTC settings.

Residual Overcurrent Settings

Residual Time-Overcurrent Settings

The residual time-overcurrent element provides current dependent, time delayed clearance of faults along the protected line and provides backup protection for remote terminals. Because the measure of residual current varies with system switching configuration, fault location, and fault resistance, a complete fault study is necessary to determine the minimum pickup setting, appropriate time dial, and curve characteristic. When the element is directionally controlled, consider only faults in front of the line terminal for coordinating purposes.

For the relay at Breaker 3, a single line-to-ground fault at Bus C with Line 1 or 4 removed dictates the sensitivity required for the residual time-overcurrent pickup. The residual current magnitude for this fault is 308 A primary. To allow for ground fault resistance, a value of 50% of 308 A is selected as the residual time-overcurrent element pickup. The pickup (51NP), time dial (51NTD), and curve family (51NC) selections are assumed to coordinate with the remaining residual time-overcurrent elements of the example system.

Instantaneous/Definite-Time Residual Overcurrent Settings

The residual instantaneous/ definite-time overcurrent elements are not required for this application. The residual overcurrent elements are disabled by setting E50N = N.

Calculations: CTR = 200:1

$$51NP \text{ secondary amps} = \frac{150 \text{ A primary}}{200} = 0.75 \text{ A secondary}$$

```
E51N = Y
51NP = 0.75
51NC = U3
51NTD = 2.00
51NRS = Y
51NTC = 32QF

E50N = N
```

- Relay Elements and Other Settings Affected

Relay elements 51NT and 51NP depend on the 51NP, 51NTD, 51NC and 51NTC settings. 50N1, 50N2, 50N3, 50N4, 67N1, 67N2, 67N3, 67N4, 67N2T, 67N3T, 67N4T elements.

Negative-Sequence Overcurrent Settings

Negative-Sequence Time-Overcurrent Settings

The negative-sequence time-overcurrent element provides current dependent, time delayed clearance of faults along the protected line and provides backup protection for remote terminals. Because the measure of negative-sequence current varies with system switching configuration, fault location, and fault resistance, a complete fault study is necessary to determine the minimum pickup setting, appropriate time dial, and curve characteristic. When the element is directionally controlled, consider only faults in front of the line terminal for coordinating purposes.

The negative-sequence overcurrent element can provide backup for phase-to-phase or phase-to-ground faults. For this example, the negative-sequence element provides backup for phase-to-phase faults. Phase-to-ground faults need only be considered for coordination purposes.

For the relay at Breaker 3, a phase-to-phase fault at Bus C with Line 1 or 4 open dictates the sensitivity required for the negative-sequence time-overcurrent pickup. The negative-sequence ($3I_2$) current magnitude for this fault is 736 A primary. To allow for fault resistance, a value of 60% of 736 A is selected as the negative-sequence time-overcurrent element pickup. The pickup (51QP), time dial (51QTD), and curve family (51QC) selections are assumed to coordinate with the remaining negative-sequence and residual time-overcurrent elements of the example system.

Instantaneous/Definite-Time Negative-Sequence Setting

The negative-sequence instantaneous/definite-time overcurrent elements are not required for this application. The negative-sequence overcurrent elements are disabled by setting E50Q = N.

Calculations: CTR = 200:1

$$51QP \text{ secondary amps} = \frac{440 \text{ A primary}}{200} = 2.20 \text{ A secondary}$$

```

E51Q  = Y
51QP  = 2.2
51QC  = U3
51QTD = 2.00
51QRS = N
51QTC = 32QF

E50Q  = N

```

- Relay Elements and Other Settings Affected

Relay elements 51QT and 51QP depend on the 51QP, 51QTD, 51QC and 51QTC settings. 50Q1, 50Q2, 50Q3, 50Q4, 67Q1, 67Q2, 67Q3, 67Q4, 67Q2T, 67Q3T, and 67Q4T elements.

Voltage Elements

Voltage elements are not required for this application. The voltage elements are disabled by setting EVOLT = N.

```

EVOLT = N

```

- Relay Elements and Other Settings Affected

Relay elements 27L, 3P27, 59PB, 59PR, 59N, 59L and 3P59.

Time-Step Backup Time Delay Settings

The relay provides time delayed pickup timers for time-stepped backup protection. Separate timers are provided for the Zone 2, 3, and 4 phase and ground distance elements. Timers are provided for all four levels of the residual and negative-sequence overcurrent elements. The residual and negative-sequence overcurrent time delays are independently set.

For our example, three zones of phase and ground distance elements are selected. In this case, the Zone 2 and 3 phase and ground distance time delays must be set. Zone 2 elements must coordinate with downstream Zone 1 elements, plus downstream breaker operating time, plus a safety margin. A typical Zone 2 phase and ground distance time delay setting is 20 cycles.

The Zone 3 element is reverse-reaching and is not required for backup protection. The Zone 3 element is set for a zero time delay and is not set in the tripping mask.

For the relay at Breaker 3:

```

Z2PD  = 20.00
Z3PD  = 0.00
Z2GD  = 20.00
Z3GD  = 0.00

```

- Relay Elements and Other Settings Affected

M2PT, M3PT, Z2GT, and Z3GT elements.

Permissive Overreaching Scheme Logic

For our application, the tripping scheme is permissive overreaching transfer trip. Setting EPOTT = Y enables the Permissive Overreaching Transfer Trip logic and settings. With the permissive tripping logic selected, no settings are required for the Directional Comparison Blocking logic.

The Zone 3 Reverse Block Delay (Z3RBD) timer extends the block signal issued by reverse looking elements after a current reversal occurs and Zone 3 elements drop out. Zone 3 relay elements do not encompass the origin. The recommended time setting for the Z3RBD timer is the remote faulted terminal breaker time plus communications channel reset time, plus remote Zone 2 relay reset time. Assume a typical breaker operation time of three cycles, communications channel reset time of one cycle, and remote Zone 2 relay reset time of one cycle. The sum of these times gives a conservative Z3RBD timer setting of 5 cycles.

The SEL-321 Relay includes logic which echoes the received permissive signal back to the remote end after certain conditions are met. This is used in conjunction with the weak infeed logic so that the relay at the strong terminal may trip even if the relay at the weak terminal does not have any protective elements picked up.

In some applications, with all sources in, one terminal may not contribute enough fault current to operate the protective elements. If the fault lies within the Zone 1 reach of the strong terminal, the fault currents may redistribute after the strong terminal line breaker opens to permit sequential tripping of the weak-infeed terminal line breaker. If currents do not redistribute sufficiently to operate the protective elements at the weak-infeed terminal, it is still desirable to open the local breaker. This prevents the low level currents from maintaining the fault arc and allows successful auto reclosure from the strong terminal. When the fault location is near the weak terminal, the Zone 1 elements of the strong terminal do not pick up and the fault does not clear rapidly. This is because the weak terminal protective elements do not operate. Note that while the weak-infeed terminal contributes little fault current, the phase voltage(s) are depressed.

The SEL-321 Relay provides additional logic for weak-infeed terminals to permit rapid tripping of both line terminals for internal faults near the weak terminal. The strong terminal is permitted to trip via the permissive signal echoed back from the weak terminal. The weak terminal is tripped by converting the echoed permissive signal to a trip signal after the following conditions are met:

1. No reverse looking elements have picked up. For faults behind the relay location, the reverse elements operate to inhibit the operation of the weak-infeed and echo logic.
2. LOP is deasserted and ELOP = Y1
3. At least one single-phase undervoltage or the residual overvoltage element operates.
4. The line terminal breaker is closed.
5. A permissive trip signal is received for ETDPU time period. The received PT signal is initiated by the overreaching remote terminal Zone 2 elements.

After these four conditions are met, the weak-infeed logic sets the Echo Conversion To Trip (ECTT) element. This element may be masked in the MTU logic mask to permit tripping the local breaker under the conditions described above.

The echo logic includes timers for qualifying the permissive signal as well as timers for blocking the echo logic for certain conditions. The Echo Block Time Delay (EBLKD) is used to block the echo logic after dropout of local permissive elements. The recommended time setting for the EBLKD timer is the remote faulted terminal breaker time, plus communications channel round trip time, plus some safety margin. Assume a typical breaker operation time of three cycles and communications channel round trip time of two cycles, and a safety margin of 5 cycles to give a conservative EBLKD timer setting of 10 cycles.

An echo delay ensures that the reverse elements at the receiving end have sufficient time to operate and block the echo repeat for faults behind that terminal. It also insulates the Echo and Weak-Infeed logic (discussed later) against noise bursts which can occur on the communications channel during close-in external faults. Typically, these noise bursts coincide with faults external to the line section.

Since the pickup time of the reverse elements and duration of these noise bursts are very short, the system requires a received permissive signal to be present for a short time before the permissive signal can be echoed back to the remote terminal or used in the Echo Conversion To Trip (ECTT) logic. The Echo Time Delay Pickup (ETDPU) timer specifies the time a permissive trip signal must be present. The ETDPU setting depends upon your communications equipment, but a typical setting for this timer is approximately 2 cycles.

The Echo Duration Time Delay (EDURD) limits the duration of the echoed permissive signal. Once the echo signal is initiated, it should be maintained for a minimum period. The echo signal should be cut off after some time, even if the permissive signal is continuously received. This prevents permissive trip signal lockup between the two line ends. Assume a three-cycle breaker at the remote terminal and half-cycle channel delay. The summation of remote breaker operation time plus channel delay gives an EDURD setting of 4 cycles.

The EWFC setting enables or disables the weak-infeed feature of the relay. When the EWFC setting is Y, the Echo Conversion To Trip (ECTT) logic is enabled. When the setting is N, ECTT logic is disabled.

When weak-infeed tripping is used, typical single-phase undervoltage settings (27L) are 70-80% of the lowest expected system operating voltage. The residual overvoltage setting should be set to approximately twice the expected standing V_0 voltage. With the 59N element set at twice the nominal standing V_0 voltage, the instrument measures only fault induced zero-sequence voltage. These elements are set in the voltage element settings (EVOLT = Y).

In the sample application, the weak infeed feature is not required.

```
EPOTT = Y
Z3RBD = 5.00
EBLKD = 10.00
ETDPU = 2.00
EDURD = 4.00
```

- Other Settings Affected

KEY, ECTT, and EKEY elements.

Directional Comparison Unblocking Scheme Logic

For this application the Directional Comparison Unblocking logic is not required.

The Directional Comparison Unblocking logic is disabled by setting EDCUB = N.

EDCUB = N

- Other Settings Affected

KEY, ECTT, ATB and EKEY elements.

Zone 1 Extension Logic Setting

For our example the Zone 1 extension logic is not required. Setting EZ1EXT = N, disables the scheme logic.

EZ1EXT = N

- Other Settings Affected

Z1X element.

Remote-End-Just-Opened (REJO) Enable Setting (EREJO)

In the example for the relay at Breaker 3, we select EREJO = N. This disables the REJO logic.

EREJO = N

- Other Settings Affected

TA, TB, TC, and 3PT element.

Switch-Onto-Fault Logic Setting

The 50H element is intended for use as a high-set non-directional phase overcurrent detector in the Switch-Onto-Fault logic. If a line breaker is closed into a close-in three-phase bolted fault where line-side potential transformers are used, polarizing voltage for the three-phase distance elements is never established. In this situation, the distance elements do not operate. In this instance, the 50H element is provided to help prevent a failure to trip the line breaker.

The 50H element measures current magnitude in each phase with no dependence on polarizing voltages. This element is non-directional and should be used only in the switch-onto-fault logic mask (MTO) when the line breaker is closed to test the line on a radial basis. If fault duty in front of the line terminal is much greater than behind it, the 50H element can also be used in the unconditional trip logic mask (MTU) to provide rapid clearance of close-in faults.

Typical 50H settings are 50% - 70% of three-phase fault duty at the local bus.

The three-phase fault duty for a fault at Bus B is 4456 A. To assure rapid clearance of this fault, a 50H setting of 2250 A is selected for this example.

Calculations: CTR = 200:1

$$50H \text{ secondary amps} = \frac{2250 \text{ A primary}}{200} = 11.25 \text{ A secondary}$$

The Switch-Onto-Fault logic may be enabled by change in the 52A status showing the breaker has just closed or by asserting the close input to the relay from the breaker close bus.

The 52A method works well for single or multiple breaker applications.

For a single breaker configuration, using the close bus enable is a better selection. The close enable delay (CLOEND) should be set less than the shortest reclose open interval. The Switch-Onto-Fault Delay (SOTFD) determines how long the SOTF logic is allowed to trip after the breaker is closed.

For our example, the close method is used.

```
ESOTF = Y
ENCLO = Y
CLOEND = 10.00
EN52A = N
SOTFD = 30.00
50H = 11.25
```

- Relay Elements and Other Settings Affected

50H element.

Loss-of-Potential (LOP) Enable Setting (ELOP)

Fuses or molded case circuit breakers often protect the secondary windings of the power system potential transformers. An operation of one or more fuses or molded case circuit breakers results in a loss of polarizing potential inputs to the relay. Loss of one or more phase voltage prevents the relay from properly discriminating fault direction.

Because occasional loss-of-potential to the relay is unavoidable, detection of this condition is desirable. Once a true LOP condition is detected, you may elect to block distance element operation, block or enable directional overcurrent elements, and issue an alarm.

Advanced loss-of-potential logic has been added to the relay. This logic requires no settings other than the choice of enable settings. The use of advanced loss-of-potential logic is recommended, however the option to use the original loss-of-potential logic and settings has been retained to maintain compatibility with previous versions of the relay. Settings ELOP = N or Y use the original loss-of-potential logic. Settings ELOP = N1, Y1, or Y2 use the advanced loss-of-potential logic.

Advanced Loss-of-Potential Logic

Inputs into the LOP logic are:

3PO	three-pole open condition (indicates circuit breaker open condition)
SPO	single-pole open condition (indicates circuit breaker pole open condition)
OSB	out-of-step block
V_1	positive-sequence voltage (V secondary)
I_1	positive-sequence current (A secondary)
V_0	zero-sequence voltage (V secondary)
I_0	zero-sequence current (A secondary)

The circuit breaker has to be closed (Relay Word bit 3PO = SPO = logical 0) for the LOP logic to operate.

Loss-of-potential is declared (Relay Word bit LOP = logical 1) when a 10 percent drop in V_1 is detected, with no corresponding change in I_1 or I_0 . If the LOP condition persists for 60 cycles, it latches in. LOP resets (Relay Word bit LOP = logical 0) when V_1 returns above 50 V secondary and V_0 is less than 5 V secondary. Note that ILOP disables all distance elements.

The loss-of-potential enable setting, ELOP, selects between original and advanced LOP logic. It also routes the LOP Relay Word bit to directional logic. Setting ELOP operates as follows:

- N1 Relay sets LOP element when LOP condition is detected using advanced LOP logic.
Distance and directional elements are not blocked.
Set the LOP element in a SELOGIC[®] control equation to indicate condition, if desired.
- Y1 Relay sets LOP element when LOP condition is detected using advanced LOP logic.
Distance elements and directional elements are blocked.
Set the LOP element in a SELOGIC control equation to indicate the LOP condition, if desired.
- Y2 Relay sets LOP element when LOP condition is detected using advanced LOP logic.
Distance elements are blocked and directional elements default forward.
Set the LOP element in a SELOGIC control equation to indicate the LOP condition, if desired.

Original Loss-of-Potential Logic

The relay discriminates between faults (which may reduce voltage magnitudes to nearly zero) and loss-of-potential conditions. The following equation shows the original LOP detection logic for the relay:

$$\begin{aligned} \text{SET LOP} = & [\text{NOT}(50\text{QF} + 50\text{QR}) * 59\text{QL}]: \text{ Detects the presence of negative-sequence} \\ & \text{voltage in the absence of negative-} \\ & \text{sequence current} \\ & + [\text{NOT}(59\text{PL}) * \text{NOT}(50\text{M})]: \text{ Detects the absence of positive-sequence} \\ & \text{voltage in the absence of current above} \\ & \text{the 50M setting} \end{aligned}$$

Where:

- 9QL ≡ Negative-sequence overvoltage detector
- 0QF ≡ Low-set negative-sequence overcurrent detector
- 0QR ≡ Low-set negative-sequence overcurrent detector
- 9PL ≡ Positive-sequence overvoltage detector
- 0M ≡ Medium-set phase overcurrent element

For one or more blown PT fuses, the relay declares an LOP condition when the measured negative-sequence voltage exceeds the 59QL setting and the negative-sequence current is below the 50QF and 50QR settings. These conditions must exist for the LOPD time delay for the LOP element to set.

For three blown PT fuses, the relay declares an LOP condition when the measured positive-sequence voltage is below the 59PL and the low-set phase overcurrent detector (50M) is not picked up.

You determine how the relay uses loss-of-potential detection by selecting the ELOP setting. The ELOP setting choices and their associated results are:

- N Relay sets LOP element when LOP condition is detected using original LOP logic. Distance and directional elements are not blocked.
Set the LOP element in a SELOGIC[®] control equation to indicate condition, if desired.
- Y Relay sets LOP element when LOP condition is detected.
Distance elements are blocked and directional elements default forward.
Set the LOP element in a SELOGIC control equation to indicate the LOP condition, if desired.

The 50QF, 50QR, and 59QL elements are required to be set above the normal expected system unbalance.

The setting for the 50M pickup value requires that the element must never be picked up for load current conditions. The setting must also be below the minimum fault current level for which the relay is required to trip following an LOP condition. In this example, the application should

detect a fault at Bus C after an LOP condition is detected. The maximum expected load for this circuit is 450 A. The minimum fault current level for a fault at Bus C is 491 A. Faults at Bus C do not drop the positive-sequence voltage at Bus B below 14 V. With a small margin for fault study and CT performance error, the 50M setting for this example is 475 A.

$$50M \text{ secondary amps} = \frac{475 \text{ A primary}}{200} = 2.37 \text{ A secondary}$$

For the relay at Breaker 3:

```

E LOP = Y
L O P D = 3.00
50M = 2.37
59Q L = 14.00
59P L = 14.00

```

- Relay Elements and Other Settings Affected

All set distance and directionally controlled overcurrent elements.

Miscellaneous Scheme Logic

In our application, we are using three-pole tripping only and pole-discordance is not required. To disable the Pole-Discordance logic, set EPOLD = N.

The relay is required to trip three-pole only for this application. Setting ESPT = N and ESPO = N disables the single-pole tripping logic.

The 3POD dropout delay timer is used to prevent operation of the ground distance element when all three poles do not close simultaneously. When a breaker is closed, the ground distance elements are blocked for 3POD time. The 3POD dropout time delay should be set for the worst case pole scatter upon breaker closure. For our application a setting of 1.5 cycles is required.

In applications where a portion of the bus (or stub of the bus) is energized by a closed breaker, yet the line is deenergized and isolated by an open disconnect switch, the relay provides definite-time phase overcurrent protection. Distance protection is not applicable if line-side PTs are employed. This logic can only be performed if LOP is enabled.

The stub protection may also be used for definite-time overcurrent protection when the relay detects a loss-of-potential. With ESTUB = Y, set the 50MFD timer to the appropriate delay. The Stub Protection logic is only allowed to trip when the relay detects an LOP condition and the phase current exceeds the 50M pickup threshold.

The relay also provides four methods of trip unlatch (open the trip contact) logic. If no trip unlatch logic is selected, trip output remains closed for the greater duration of the fault or the trip duration timer. The four trip unlatch methods are as follows:

- Option 1 allows the trip contact to open if the trip condition has reset, the minimum trip duration (TDURD) expires, and the lowest set 50L, 50QF, or 50QR element is not picked up.

- Option 2 allows the trip contact to open if the trip condition has reset, the minimum trip duration (TDURD) expires, and the 52A contact has changed state showing the breaker has opened.
- Option 3 allows the trip contact to open if the trip condition has reset, the minimum trip duration (TDURD) expires, the 52A contact has changed state showing the breaker has opened, and the lowest set 50L, 50QF, or 50QR element is not picked up.
- Option 4 allows the trip contact to open if the trip condition has reset, the minimum trip duration (TDURD) expires, and the input assigned to EXTUL is asserted.

For our example, Option 3 is used.

EPOLD	=	N
ESPT	=	N
ESPO	=	N
3POD	=	1.50
ESTUB	=	Y
50MFD	=	20.00
TULO	=	3

- Relay Elements and Other Settings Affected

50MF element.

Miscellaneous Timers

The SEL-321 Relay provides dedicated timers for additional relay element variables so that you may create your own scheme logic. The minimum trip duration, trip during open pole, and instantaneous trip time declaration timers are also included in these settings.

The minimum Trip Duration timer (TDURD) setting determines the minimum length of time the TPA, TPB, TPC, and 3PT relay element asserts. These relay elements are used to control a designated trip contact. The trip output contacts close for the greater of the TDURD time or the duration of the trip condition. A typical setting for this timer is 150 msec or nine cycles.

The trip during Pole Open Time Delay (TOPD) is not used in the three-pole tripping logic and is set to zero.

Timers are provided for the X, Y, and Z SELOGIC control equation variables. This allows you to invent your own protection or control schemes using the internal relay elements.

The Instantaneous Trip Time (ITT) declaration delay qualifies a maximum time for instantaneous targeting. This is determined by the time an element set in the trip equation is picked up before the trip output is asserted. If the element is picked up for less than the ITT time before the trip output, it is declared an instantaneous trip for targeting purposes. The relay also declares an instantaneous target if a trip occurs and no other targeting conditions are true.

For our example, we have to set the minimum trip duration timer and the instantaneous trip time declaration delay.

```
TDURD = 9.00
TOPD  = 0.00
TXPU  = 0.00
TXDO  = 0.00
TYPV  = 0.00
TYDO  = 0.00
TZPU  = 0.00
TZDO  = 0.00
ITTD  = 5.00
```

- Other Settings Affected

XT, YT, and ZT time delayed SELOGIC control equations variable outputs.

SELogic Control Equations

Programming SELOGIC control equations consist of assigning functions to the programmable inputs, designing the internal logic functions your application requires, expressing the logic in terms of the relay element and internal logic variables, and finally defining the output functions.

Additionally, you may program intermediate logic points and the output contacts with SELOGIC control equations. This permits you to combine any element in Tables 2.7, 2.9, or 2.10 in **Section 2: Specifications**, use non-dedicated timers for special applications, and assign these combinations to output contacts.

Logic Variable Equations

Five programmable logic variables are provided which allow you to design your own internal logic conditions. For our example, these variables are not required.

Tripping Logic Equations

There are three logic equations that must be set for tripping.

The MTCS logic equation determines which elements trip via the communications-based logic. Typically the overreaching Zone 2 elements are set in the MTCS logic equation.

The MTU logic equation determines which elements trip unconditionally. Typically all direct tripping and time-delayed tripping elements are set in the MTU logic equation.

The MTO logic equation defines which elements are enabled to trip while SOTFE is asserted. All elements set in this trip instantaneously, if they assert during the SOTFD time. This is referred to as the Switch-Onto-Fault logic.

For our example, all of the instantaneous and time delayed tripping elements are set in MTU. The overreaching Zone 2 elements are set in MTCS. Since the elements set in the MTO are enabled to trip for SOTFD time, the 50H and all overreaching and underreaching instantaneous elements are set in this equation.

Event Report Trigger Condition Logic

The relay allows selection of which elements trigger an event report (MER logic mask). An event report is always generated when the relay issues a trip. However, there may be other conditions that require event report generation.

For our example event reports are generated when the time delayed tripping elements timeout, when the high-set phase overcurrent element picks up and on loss-of-potential when the breaker is closed.

Output Contact Logic

Each output contact is programmed using SELOGIC control equations. For our example the relay is required to trip three-pole, close the breaker via the CLOSE command and key the permissive trip signal.

The remaining contacts can be used for local substation annunciation, sequence-of-events recording, or SCADA indication. These requirements are dictated by your particular relay application.

V	=	NA
W	=	NA
X	=	NA
Y	=	NA
Z	=	NA
MTCS	=	M2P + Z2G
MTU	=	M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF
MT0	=	M1P + M2P + Z1G + Z2G + 50H
MER	=	M2P + Z2G + 51NP + 51QP + 50H + LOP * 52AA1
OUT1	=	3PT
OUT2	=	3PT
OUT3	=	CC
OUT4	=	KEY
OUT5	=	NA
OUT6	=	NA
OUT7	=	NA
OUT8	=	NA
OUT9	=	NA
OUT10	=	NA
OUT11	=	NA
OUT12	=	NA
OUT13	=	NA
OUT14	=	NA
OUT15	=	NA
TMB1	=	NA
TMB2	=	NA
TMB2	=	NA
TMB3	=	NA
TMB4	=	NA
TMB5	=	NA
TMB6	=	NA
TMB7	=	NA
TMB8	=	NA

Global Input Settings

The eight logic inputs may be assigned to any of the variables listed in Table 2.9. in **Section 2: Specifications**. For our example, the relay logic requires a 52A input, the received permissive trip signal, the breaker close signal and an indication from the potential transfer switch.

Miscellaneous Global Settings

Settings are also required for the front panel timeout and the group switching delay.

The front panel timeout defines a time duration in which the relay takes certain actions if no activity occurs via the front panel after the set time period. The actions taken are as follows:

- The front panel LCD display is reset to the default display.
- The front panel access level reverts to Access Level 1.
- The back lighting for the LCD is turned off.
- Any routine that is being executed via a front panel command is interrupted.
- Target LEDs revert to the default targets.

The factory default setting is five minutes. The setting range is from 0 to 30 minutes.

The group switching delay defines a time interval in which the relay delays switch group setting via logic input assertion.

IN1	=	52A1
IN2	=	PT
IN3	=	CLOSE
IN4	=	NA
IN5	=	NA
IN6	=	NA
IN7	=	NA
IN8	=	PTXFR
RMB1	=	NA
RMB2	=	NA
RMB3	=	NA
RMB4	=	NA
RMB5	=	NA
RMB6	=	NA
RMB7	=	NA
RMB8	=	NA
FP_TIMEOUT	=	5
TGR	=	5

SETTINGS SHEET FOR SEL-321-3 RELAY SETTING EXAMPLE

Following is a filled out example setting sheet for this application.

**EXAMPLE SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(5A NOMINAL RELAY)**

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Line Terminal Settings

Relay Identifier: (17 Characters)	RELID =	<u>SEL-321 POTT</u>
Terminal Identifier: (39 Characters)	TRMID =	<u>EXAMPLE: BUS B, BREAKER 3</u>

Positive-Seq. Line Impedance Magnitude: (0.05 - 255 Ω sec.)	Z1MAG =	<u>7.80</u>
Positive-Seq. Line Impedance Angle: (5° - 90°)	Z1ANG =	<u>83.97</u>
Zero-Seq. Line Impedance Magnitude: (0.05 - 255 Ω sec.)	Z0MAG =	<u>24.79</u>
Zero-Seq. Line Impedance Angle: (5° - 90°)	Z0ANG =	<u>81.46</u>
Fault Location Enable: (Y,R,N)	LOCAT =	<u>Y</u>
Line Length: (0.1 - 999 unitless)	LL =	<u>100.00</u>
Current Transformer Ratio: (1 - 6000)	CTR =	<u>200</u>
Potential Transformer Ratio: (1 - 10000)	PTR =	<u>2000</u>

Enable Zones of Distance Settings

Number Distance Zones: Mho Phase: (N,1,2,3,4)	PMHOZ =	<u>3</u>
Mho Ground: (N,1,2,3,4)	GMHOZ =	<u>3</u>
Quad. Ground: (N,1,2,3,4)	QUADZ =	<u>3</u>

Distance Zones and Overcurrent Levels Direction Settings

Distance Zone 1/Overcurrent Level 1 Direction: (F/R)	DIR1 =	<u>F</u>
Distance Zone 2/Overcurrent Level 2 Direction: (F/R)	DIR2 =	<u>F</u>
Distance Zone 3/Overcurrent Level 3 Direction: (F/R)	DIR3 =	<u>R</u>
Distance Zone 4/Overcurrent Level 4 Direction: (F/R)	DIR4 =	<u>F</u>

Mho Phase Distance Settings

Impedance Reach: Zone 1: (0.05 - 64 Ω sec.)	Z1P =	<u>6.24</u>
Zone 2: (0.05 - 64 Ω sec.)	Z2P =	<u>9.36</u>
Zone 3: (0.05 - 64 Ω sec.)	Z3P =	<u>1.87</u>
Zone 4: (0.05 - 64 Ω sec.)	Z4P =	<u> </u>

Mho Phase Distance Overcurrent Supervision Settings

Phase-to-Phase Overcurrent: Zone 1: (1 - 170 amps sec.)	50PP1 =	<u>2.55</u>
Zone 2: (1 - 170 amps sec.)	50PP2 =	<u>2.22</u>
Zone 3: (1 - 170 amps sec.)	50PP3 =	<u>2.45</u>
Zone 4: (1 - 170 amps sec.)	50PP4 =	<u> </u>

**EXAMPLE SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(5A NOMINAL RELAY)**

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Mho Ground Distance Settings

Impedance Reach:	Zone 1: (0.05 - 64 Ω sec.)	Z1MG	=	<u>6.24</u>
	Zone 2: (0.05 - 64 Ω sec.)	Z2MG	=	<u>9.36</u>
	Zone 3: (0.05 - 64 Ω sec.)	Z3MG	=	<u>1.87</u>
	Zone 4: (0.05 - 64 Ω sec.)	Z4MG	=	<u> </u>

Quadrilateral Ground Distance Settings

Reactive Reach:	Zone 1: (0.05 - 64 Ω sec.)	XG1	=	<u>6.24</u>
	Zone 2: (0.05 - 64 Ω sec.)	XG2	=	<u>9.36</u>
	Zone 3: (0.05 - 64 Ω sec.)	XG3	=	<u>1.87</u>
	Zone 4: (0.05 - 64 Ω sec.)	XG4	=	<u> </u>
Resistive Reach:	Zone 1: (0.05 - 50 Ω sec.)	RG1	=	<u>2.50</u>
	Zone 2: (0.05 - 50 Ω sec.)	RG2	=	<u>5.00</u>
	Zone 3: (0.05 - 50 Ω sec.)	RG3	=	<u>6.00</u>
	Zone 4: (0.05 - 50 Ω sec.)	RG4	=	<u> </u>

Ground Distance Overcurrent Supervision Settings

Phase Overcurrent Supervision:	Zone 1: (0.5 - 100 amps sec.)	50L1	=	<u>0.90</u>
	Zone 2: (0.5 - 100 amps sec.)	50L2	=	<u>0.90</u>
	Zone 3: (0.5 - 100 amps sec.)	50L3	=	<u>1.30</u>
	Zone 4: (0.5 - 100 amps sec.)	50L4	=	<u> </u>
Residual Overcurrent Supervision:	Zone 1: (0.5 - 100 amps sec.)	50G1	=	<u>0.90</u>
	Zone 2: (0.5 - 100 amps sec.)	50G2	=	<u>0.60</u>
	Zone 3: (0.5 - 100 amps sec.)	50G3	=	<u>0.50</u>
	Zone 4: (0.5 - 100 amps sec.)	50G4	=	<u> </u>

Zero-Sequence Compensation Factor Settings

Zone 1 Zero-Sequence Comp. Factor 1 Magnitude: (0 - 4 unitless)	k01M	=	<u>0.726</u>
Zone 1 Zero-Sequence Comp. Factor 1 Angle: ($\pm 180^\circ$)	k01A	=	<u>-3.69</u>
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Mag.: (0 - 4 unitless)	k0M	=	<u>0.726</u>
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Angle: ($\pm 180^\circ$)	k0A	=	<u>-3.69</u>
Non-Homogeneous Correction Angle: ($\pm 20^\circ$)	T	=	<u>0</u>

**EXAMPLE SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(5A NOMINAL RELAY)**

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Out-of-Step Blocking and Tripping Settings

Enable OOS: (Y/N)	EOOS	=	<u>N</u>
OOSB Enable: Block Zone 1: (Y/N)	OOSB1	=	<u> </u>
Block Zone 2: (Y/N)	OOSB2	=	<u> </u>
Block Zone 3: (Y/N)	OOSB3	=	<u> </u>
Block Zone 4: (Y/N)	OOSB4	=	<u> </u>
Out-of-Step Block Time Delay (TDPU): (0.5 - 8000 cycles)	OSBD	=	<u> </u>
Enable OOST: (I/O/N)	EOOST	=	<u> </u>
Out-of-Step TOWI Time Delay (TDPU): (0.5 - 8000 cycles)	OSTD	=	<u> </u>
Zone 5 Reactive Reach: Top: (0 to $\pm 96 \Omega$ sec.)	X1T5	=	<u> </u>
Bottom: (0 to $\pm 96 \Omega$ sec.)	X1B5	=	<u> </u>
Zone 5 Resistive Reach: Right: (0 to $\pm 70 \Omega$ sec.)	R1R5	=	<u> </u>
Left: (0 to $\pm 70 \Omega$ sec.)	R1L5	=	<u> </u>
Zone 6 Reactive Reach: Top: (0 to $\pm 96 \Omega$ sec.)	X1T6	=	<u> </u>
Bottom: (0 to $\pm 96 \Omega$ sec.)	X1B6	=	<u> </u>
Zone 6 Resistive Reach: Right: (0 to $\pm 70 \Omega$ sec.)	R1R6	=	<u> </u>
Left: (0 to $\pm 70 \Omega$ sec.)	R1L6	=	<u> </u>
Zone 6 Positive-Sequence Overcurrent Supervision: (1 - 100 amps sec., I1)	50ABC	=	<u> </u>

Load-Encroachment Settings

Enable Load-Encroachment: (Y/N)	ELE	=	<u>Y</u>
Load Impedance: Forward: (0.05 - 64 Ω sec.)	ZLF	=	<u>9.22</u>
Reverse: (0.05 - 64 Ω sec.)	ZLR	=	<u>9.22</u>
Load Angle: Positive Forward: (-90° to +90°)	PLAF	=	<u>30</u>
Negative Forward: (-90° to +90°)	NLAF	=	<u>-30</u>
Positive Reverse: (+90° to +270°)	PLAR	=	<u>150</u>
Negative Reverse: (+90° to +270°)	NLAR	=	<u>210</u>

Negative-Sequence Directional Element Settings

Forward Directional Z2 Threshold: ($\pm 64 \Omega$ sec.)	Z2F	=	<u>0.77</u>
Forward Directional Current Threshold: (0.25 - 5 amps sec., 3I2)	50QF	=	<u>0.50</u>
Reverse Directional Z2 Threshold: ($\pm 64 \Omega$ sec.)	Z2R	=	<u>5.45</u>
Reverse Directional Current Threshold: (0.25 - 5 amps sec., 3I2)	50QR	=	<u>0.50</u>
Positive-Sequence Current Restraint Factor: (0.02 - 0.5 unitless)	a2	=	<u>0.07</u>

**EXAMPLE SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(5A NOMINAL RELAY)**

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Phase Time-Overcurrent Element Settings

Phase Time Overcurrent Element: Enable: (Y/N)	E51P	=	<u>N</u>
Pickup: (0.5 - 16 amps sec.)	51PP	=	<u> </u>
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51PC	=	<u> </u>
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51PTD	=	<u> </u>
Reset Delay: (Y/N)	51PRS	=	<u> </u>
Torque Control: (M2P, N) (SEL-321 Relay Base Version)	51PTC	=	<u> </u>
(ZLIN, ZLOUT, M2P, N) (SEL-321-1 Relay)			

Residual Time-Overcurrent Element Settings

Residual Time Overcurrent Element: Enable: (Y/N/S)	E51N	=	<u>Y</u>
Pickup: (0.5 - 16 amps sec., 3I0)	51NP	=	<u>0.75</u>
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51NC	=	<u>U3</u>
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51NTD	=	<u>2.00</u>
Reset Delay: (Y/N)	51NRS	=	<u>Y</u>
Torque Control: (32QF, 32QR, Z2G, N)	51NTC	=	<u>32QF</u>

Residual Overcurrent Element Settings

Enable Number of Residual Instantaneous Overcurrent Levels: (N,1,2,3,4)	E50N	=	<u>N</u>
Residual Inst. Overcurrent Pickup: Level 1: (0.25 - 80 amps sec., 3I0)	50N1	=	<u> </u>
Level 2: (0.25 - 80 amps sec., 3I0)	50N2	=	<u> </u>
Level 3: (0.25 - 80 amps sec., 3I0)	50N3	=	<u> </u>
Level 4: (0.25 - 80 amps sec., 3I0)	50N4	=	<u> </u>

Negative-Sequence Time Overcurrent Element Settings

Negative-Sequence Time Overcurrent: Enable: (Y/N/S)	E51Q	=	<u>Y</u>
Pickup: (0.5 - 16 amps sec., 3I2)	51QP	=	<u>2.2</u>
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51QC	=	<u>U3</u>
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51QTD	=	<u>2.00</u>
Reset Delay: (Y/N)	51QRS	=	<u>N</u>
Torque Control: (32QF, 32QR, M2P, Z2G, N)	51QTC	=	<u>32QF</u>

Negative-Sequence Overcurrent Element Settings

Enable Number of Neg.-Sequence Inst. Overcurrent Levels: (N,1,2,3,4)	E50Q	=	<u>N</u>
Neg.-Seq. Inst. Overcurrent Pickup: Level 1: (0.25 - 80 amps sec., 3I2)	50Q1	=	<u> </u>
Level 2: (0.25 - 80 amps sec., 3I2)	50Q2	=	<u> </u>
Level 3: (0.25 - 80 amps sec., 3I2)	50Q3	=	<u> </u>
Level 4: (0.25 - 80 amps sec., 3I2)	50Q4	=	<u> </u>

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Voltage Element Settings

Enable Voltage Elements: (Y/N)	EVOLT	=	<u>N</u>
Zero-Sequence Over-Voltage: (0 - 150 V sec., 3V0)	59N	=	<u> </u>
Bus Phase Under-Voltage: (0 - 100 V sec.)	27L	=	<u> </u>
Bus Phase Over-Voltage: (0 - 100 V sec.)	59L	=	<u> </u>
Positive-Sequence Bus Over-Voltage: (0 - 150 V sec., V1)	59PB	=	<u> </u>
Positive-Sequence Bus Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PBD	=	<u> </u>
Positive-Sequence Remote Bus Over-Voltage: (0 - 150 V sec., V1)	59PR	=	<u> </u>
Current Comp. Remote Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PRD	=	<u> </u>
Current Compensated Remote Overvoltage Adjustment: (0 - 2 unitless)	a1	=	<u> </u>

Time Step Backup Time Delay Settings

Zone 2 Phase Long Time Delay (TDPU): (0 - 2000 cycles)	Z2PD	=	<u>20.00</u>
Zone 3 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z3PD	=	<u>0.00</u>
Zone 4 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z4PD	=	<u> </u>
Zone 2 Ground Long Time Delay (TDPU): (0 - 2000 cycles)	Z2GD	=	<u>20.00</u>
Zone 3 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z3GD	=	<u>0.00</u>
Zone 4 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z4GD	=	<u> </u>
Level 1 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL1D	=	<u> </u>
Level 2 Residual Long Time Delay (TDPU): (0 - 2000 cycles)	67NL2D	=	<u> </u>
Level 3 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL3D	=	<u> </u>
Level 4 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL4D	=	<u> </u>
Level 1 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL1D	=	<u> </u>
Level 2 Negative-Sequence Long Time Delay (TDPU): (0 - 2000 cycles)	67QL2D	=	<u> </u>
Level 3 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL3D	=	<u> </u>
Level 4 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL4D	=	<u> </u>

Permissive Overreaching Scheme Settings

Enable Permissive Overreaching Transfer Trip Scheme: (Y/N)	EPOTT	=	<u>Y</u>
Zone 3 Reverse Block Time Delay (TDDO): (0 - 2000 cycles)	Z3RBD	=	<u>5.00</u>
Echo Block Time Delay (TDDO): (OFF, 0 - 2000 cycles)	EBLKD	=	<u>10.00</u>
Echo Time Delay Pickup Time Delay (TDPU): (OFF, 0 - 2000 cycles)	ETDPU	=	<u>2.00</u>
Echo Duration Time Delay (TDDO): (0 - 2000 cycles)	EDURD	=	<u>4.00</u>
Weak-Infeed Enable: (Y/N)	EWFC	=	<u> </u>

Directional Comparison Unblocking Scheme Settings

Enable DCUB: (Y/N)	EDCUB	=	<u>N</u>
Guard Present Security Time Delay (TDDO): (0 - 2000 cycles)	GARD1D	=	<u> </u>
DCUB Disabling Time Delay (TDPU): (0.25 - 2000 cycles)	UBDURD	=	<u> </u>
DCUB Duration Time Delay (TDPU): (0 - 2000 cycles)	UBEND	=	<u> </u>

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Directional Comparison Blocking Scheme Settings

Enable DCB: (Y/N)	EDCB	=	_____
Zone 3 Dropout Extension Time Delay (TDDO): (0 - 2000 cycles)	Z3XD	=	_____
Block Trip Receive Extension Time Delay (TDDO): (0 - 2000 cycles)	BTXD	=	_____
Zone 2 Phase Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2PSD	=	_____
Zone 2 Ground Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2GSD	=	_____
Level 2 Residual Short Delay Time Delay (TDPU): (0 - 60 cycles)	67N2SD	=	_____
Level 2 Neg.-Seq. Short Delay Time Delay (TDPU): (0 - 60 cycles)	67Q2SD	=	_____

Zone 1 Extension Settings

Enable Zone 1 Extension: (Y/N)	EZ1EXT	=	<u>N</u>
Enable Time Delay (TDPU): (0 - 2000 cycles)	Z1EXTD	=	_____
Multiplier: (1 - 5 unitless)	Z1EXTM	=	_____

Remote-End-Just-Opened Settings

Enable: (Y/N)	EREJO	=	<u>N</u>
Pickup Time Delay (TDPU): (0 - 2000 cycles)	REJOD	=	_____
Overcurrent Element Pickup: (0.5 - 100 amps sec.)	3P50R	=	_____

Switch-Onto-Fault Settings

Enable: (Y/N)	ESOTF	=	<u>Y</u>
Enable Close Logic: (Y/N)	ENCLO	=	<u>Y</u>
Close Enable Time Delay (TDPU): (0 - 8000 cycles)	CLOEND	=	<u>10.00</u>
Enable 52A Logic: (Y/N)	EN52A	=	<u>N</u>
52A Enable Time Delay (TDPU): (0 - 8000 cycles)	52AEND	=	_____
Time Duration (TDDO): (0.5 - 8000 cycles)	SOTFD	=	<u>30.00</u>
High-Set Phase Overcurrent Pickup: (0.5 - 100 amps sec.)	50H	=	<u>11.25</u>

Loss-of-Potential Settings

Enable Loss-Of-Potential: (Y, N, N1, Y1, Y2)	ELOP	=	<u>Y</u>
Loss-Of-Potential Time Delay (TDPU): (1 - 60 cycles)	LOPD	=	<u>3</u>
Medium-Set Phase Overcurrent Pickup: (0.5 - 100 amps sec.)	50M	=	<u>2.37</u>
Negative-Sequence Voltage LOP supervision: (0 - 150 V sec., V2)	59QL	=	<u>14.00</u>
Positive-Sequence Voltage LOP supervision: (0 - 150 V sec., V1)	59PL	=	<u>14.00</u>

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Miscellaneous Scheme Settings

Pole-Discordance Enable: (Y/N)	EPOLD	=	<u>N</u>
Single-Pole Trip Pole-Discordance Time Delay (TDPU): (0 - 8000 cycles)	SPPDD	=	<u> </u>
Single-Pole Trip Enable: (Y/N/Y1/N1)	ESPT	=	<u>N</u>
Single-Pole Open Enable: (Y/N)	ESPO	=	<u>N</u>
Single-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	SPOD	=	<u> </u>
Three-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	3POD	=	<u>1.50</u>
Enable Stub Protection: (Y/N)	ESTUB	=	<u>Y</u>
Stub Protection Time Delay (TDPU): (0 - 2000 cycles)	50MFD	=	<u>20.00</u>
Trip Unlatch Option: (N,1,2,3,4)	TULO	=	<u>3</u>

Miscellaneous Timers

Minimum Trip Duration Time Delay (TDDO): (0 - 2000 cycles)	TDURD	=	<u>9.00</u>
Trip During Open Pole Time Delay (TDDO): (0 - 8000 cycles)	TOPD	=	<u>0.00</u>
Relay Element X Time Delay Pickup (TDPU): (0 - 8000 cycles)	TXPU	=	<u>0.00</u>
Relay Element X Time Delay Dropout (TDDO): (0 - 8000 cycles)	TXDO	=	<u>0.00</u>
Relay Element Y Time Delay Pickup (TDPU): (0 - 8000 cycles)	TYPU	=	<u>0.00</u>
Relay Element Y Time Delay Dropout (TDDO): (0 - 8000 cycles)	TYDO	=	<u>0.00</u>
Relay Element Z Time Delay Pickup (TDPU): (0 - 8000 cycles)	TZPU	=	<u>0.00</u>
Relay Element Z Time Delay Dropout (TDDO): (0 - 8000 cycles)	TZDO	=	<u>0.00</u>
Instantaneous Trip Time Declaration Delay (TDPU): (0 - 60 cycles)	ITTD	=	<u>5.00</u>

Logic Variables

LOGIC V	=	<u>NA</u>
LOGIC W	=	<u>NA</u>
LOGIC X	=	<u>NA</u>
LOGIC Y	=	<u>NA</u>
LOGIC Z	=	<u>NA</u>

Tripping Logic

MTCS	=	<u>M2P + Z2G</u>
MTU	=	<u>M1P + Z1G + M2PT + Z2GT + 51NT + 51QT + 50MF</u>
MTO	=	<u>M1P + M2P + Z1G + Z2G + 50H</u>

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Event Report Trigger Condition Logic

MER = M2P + Z2G + 51NP + 51QP + 50H + LOP *52AA1

Output Contact Logic

OUT1	=	<u>3PT</u>
OUT2	=	<u>3PT</u>
OUT3	=	<u>CC</u>
OUT4	=	<u>KEY</u>
OUT5	=	<u>NA</u>
OUT6	=	<u>NA</u>
OUT7	=	<u>NA</u>
OUT8	=	<u>NA</u>
OUT9	=	<u>NA</u>
OUT10	=	<u>NA</u>
OUT11	=	<u>NA</u>
OUT12	=	<u>NA</u>
OUT13	=	<u>NA</u>
OUT14	=	<u>NA</u>
OUT15	=	<u>NA</u>
* OUT17	=	_____
* OUT18	=	_____
* OUT19	=	_____

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* OUT20	=	_____
* OUT21	=	_____
* OUT22	=	_____
* OUT23	=	_____
* OUT24	=	_____
* OUT25	=	_____
* OUT26	=	_____
* OUT27	=	_____
* OUT28	=	_____
* OUT29	=	_____
* OUT30	=	_____
* OUT31	=	_____
* OUT32	=	_____
TMB1	=	_____
TMB2	=	_____
TMB3	=	_____
TMB4	=	_____
TMB5	=	_____
TMB6	=	_____
TMB7	=	_____
TMB8	=	_____

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Global Contact Input Settings

Input Contact 1 Assignment:	IN1	=	<u>52A1</u>
Input Contact 2 Assignment:	IN2	=	<u>PT</u>
Input Contact 3 Assignment:	IN3	=	<u>CLOSE</u>
Input Contact 4 Assignment:	IN4	=	<u>NA</u>
Input Contact 5 Assignment:	IN5	=	<u>NA</u>
Input Contact 6 Assignment:	IN6	=	<u>NA</u>
Input Contact 7 Assignment:	IN7	=	<u>NA</u>
Input Contact 8 Assignment:	IN8	=	<u>PTXFR</u>
* Input Contact 9 Assignment:	IN9	=	<u> </u>
* Input Contact 10 Assignment:	IN10	=	<u> </u>
* Input Contact 11 Assignment:	IN11	=	<u> </u>
* Input Contact 12 Assignment:	IN12	=	<u> </u>
* Input Contact 13 Assignment:	IN13	=	<u> </u>
* Input Contact 14 Assignment:	IN14	=	<u> </u>
* Input Contact 15 Assignment:	IN15	=	<u> </u>
* Input Contact 16 Assignment:	IN16	=	<u> </u>
Received MIRRORED BIT 1:	RMB1	=	<u> </u>
Received MIRRORED BIT 2:	RMB2	=	<u> </u>
Received MIRRORED BIT 3:	RMB3	=	<u> </u>
Received MIRRORED BIT 4:	RMB4	=	<u> </u>
Received MIRRORED BIT 5:	RMB5	=	<u> </u>
Received MIRRORED BIT 6:	RMB6	=	<u> </u>
Received MIRRORED BIT 7:	RMB7	=	<u> </u>
Received MIRRORED BIT 8:	RMB8	=	<u> </u>

Miscellaneous Global Settings

Front panel timeout: (0 - 30 minutes)	FP_TIMEOUT	=	<u>5</u>
Group change delay: (0 - 900 seconds)	TGR	=	<u>5</u>
CR RAM Diagnostics Action: Restart Enable (Y/N)	ERESTART	=	<u>Y</u>

* OUT17 - OUT32 available only on two I/O board relays.

* INPUT9 - INPUT16 available only on two I/O board relays.

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Line Terminal Settings

Relay Identifier: (17 Characters) RELID = _____
Terminal Identifier: (39 Characters) TRMID = _____

Positive-Seq. Line Impedance Magnitude: (0.05 - 255 Ω sec.)	Z1MAG	=	_____
Positive-Seq. Line Impedance Angle: (5° - 90°)	Z1ANG	=	_____
Zero-Seq. Line Impedance Magnitude: (0.05 - 255 Ω sec.)	Z0MAG	=	_____
Zero-Seq. Line Impedance Angle: (5° - 90°)	Z0ANG	=	_____
Fault Location Enable: (Y,R,N)	LOCAT	=	_____
Line Length: (0.1 - 999 unitless)	LL	=	_____
Current Transformer Ratio: (1 - 6000)	CTR	=	_____
Potential Transformer Ratio: (1 - 10000)	PTR	=	_____

Enable Zones of Distance Settings

Number Distance Zones: Mho Phase: (N,1,2,3,4)	PMHOZ	=	_____
Mho Ground: (N,1,2,3,4)	GMHOZ	=	_____
Quad. Ground: (N,1,2,3,4)	QUADZ	=	_____

Distance Zones and Overcurrent Levels Direction Settings

Distance Zone 1/Overcurrent Level 1 Direction: (F/R)	DIR1	=	_____
Distance Zone 2/Overcurrent Level 2 Direction: (F/R)	DIR2	=	_____
Distance Zone 3/Overcurrent Level 3 Direction: (F/R)	DIR3	=	_____
Distance Zone 4/Overcurrent Level 4 Direction: (F/R)	DIR4	=	_____

Mho Phase Distance Settings

Impedance Reach: Zone 1: (0.05 - 64 Ω sec.)	Z1P	=	_____
Zone 2: (0.05 - 64 Ω sec.)	Z2P	=	_____
Zone 3: (0.05 - 64 Ω sec.)	Z3P	=	_____
Zone 4: (0.05 - 64 Ω sec.)	Z4P	=	_____

Mho Phase Distance Overcurrent Supervision Settings

Phase-to-Phase Overcurrent: Zone 1: (1 - 170 amps sec.)	50PP1	=	_____
Zone 2: (1 - 170 amps sec.)	50PP2	=	_____
Zone 3: (1 - 170 amps sec.)	50PP3	=	_____
Zone 4: (1 - 170 amps sec.)	50PP4	=	_____

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Mho Ground Distance Settings

Impedance Reach:	Zone 1: (0.05 - 64 Ω sec.)	Z1MG	=	_____
	Zone 2: (0.05 - 64 Ω sec.)	Z2MG	=	_____
	Zone 3: (0.05 - 64 Ω sec.)	Z3MG	=	_____
	Zone 4: (0.05 - 64 Ω sec.)	Z4MG	=	_____

Quadrilateral Ground Distance Settings

Reactive Reach:	Zone 1: (0.05 - 64 Ω sec.)	XG1	=	_____
	Zone 2: (0.05 - 64 Ω sec.)	XG2	=	_____
	Zone 3: (0.05 - 64 Ω sec.)	XG3	=	_____
	Zone 4: (0.05 - 64 Ω sec.)	XG4	=	_____
Resistive Reach:	Zone 1: (0.05 - 50 Ω sec.)	RG1	=	_____
	Zone 2: (0.05 - 50 Ω sec.)	RG2	=	_____
	Zone 3: (0.05 - 50 Ω sec.)	RG3	=	_____
	Zone 4: (0.05 - 50 Ω sec.)	RG4	=	_____

Ground Distance Overcurrent Supervision Settings

Phase Overcurrent Supervision:	Zone 1: (0.5 - 100 amps sec.)	50L1	=	_____
	Zone 2: (0.5 - 100 amps sec.)	50L2	=	_____
	Zone 3: (0.5 - 100 amps sec.)	50L3	=	_____
	Zone 4: (0.5 - 100 amps sec.)	50L4	=	_____
Residual Overcurrent Supervision:	Zone 1: (0.5 - 100 amps sec.)	50G1	=	_____
	Zone 2: (0.5 - 100 amps sec.)	50G2	=	_____
	Zone 3: (0.5 - 100 amps sec.)	50G3	=	_____
	Zone 4: (0.5 - 100 amps sec.)	50G4	=	_____

Zero-Sequence Compensation Factor Settings

Zone 1 Zero-Sequence Comp. Factor 1 Magnitude: (0 - 4 unitless)	k01M	=	_____
Zone 1 Zero-Sequence Comp. Factor 1 Angle: ($\pm 180^\circ$)	k01A	=	_____
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Mag.: (0 - 4 unitless)	k0M	=	_____
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Angle: ($\pm 180^\circ$)	k0A	=	_____
Non-Homogeneous Correction Angle: ($\pm 20^\circ$)	T	=	_____

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Out-of-Step Blocking and Tripping Settings

Enable OOS: (Y/N)	EOOS	=	_____
OOSB Enable: Block Zone 1: (Y/N)	OOSB1	=	_____
Block Zone 2: (Y/N)	OOSB2	=	_____
Block Zone 3: (Y/N)	OOSB3	=	_____
Block Zone 4: (Y/N)	OOSB4	=	_____
Out-of-Step Block Time Delay (TDPU): (0.5 - 8000 cycles)	OSBD	=	_____
Enable OOST: (I/O/N)	EOOST	=	_____
Out-of-Step TOWI Time Delay (TDPU): (0.5 - 8000 cycles)	OSTD	=	_____
Zone 5 Reactive Reach: Top: (0 to $\pm 96 \Omega$ sec.)	X1T5	=	_____
Bottom: (0 to $\pm 96 \Omega$ sec.)	X1B5	=	_____
Zone 5 Resistive Reach: Right: (0 to $\pm 70 \Omega$ sec.)	R1R5	=	_____
Left: (0 to $\pm 70 \Omega$ sec.)	R1L5	=	_____
Zone 6 Reactive Reach: Top: (0 to $\pm 96 \Omega$ sec.)	X1T6	=	_____
Bottom: (0 to $\pm 96 \Omega$ sec.)	X1B6	=	_____
Zone 6 Resistive Reach: Right: (0 to $\pm 70 \Omega$ sec.)	R1R6	=	_____
Left: (0 to $\pm 70 \Omega$ sec.)	R1L6	=	_____
Zone 6 Positive-Sequence Overcurrent Supervision: (1 - 100 amps sec., I ₁)	50ABC	=	_____

Load-Encroachment Settings

Enable Load-Encroachment: (Y/N)	ELE	=	_____
Load Impedance: Forward: (0.05 - 64 Ω sec.)	ZLF	=	_____
Reverse: (0.05 - 64 Ω sec.)	ZLR	=	_____
Load Angle: Positive Forward: (-90° to +90°)	PLAF	=	_____
Negative Forward: (-90° to +90°)	NLAF	=	_____
Positive Reverse: (+90° to +270°)	PLAR	=	_____
Negative Reverse: (+90° to +270°)	NLAR	=	_____

Negative-Sequence Directional Element Settings

Forward Directional Z2 Threshold: ($\pm 64 \Omega$ sec.)	Z2F	=	_____
Forward Directional Current Threshold: (0.25 - 5 amps sec., 3I ₂)	50QF	=	_____
Reverse Directional Z2 Threshold: ($\pm 64 \Omega$ sec.)	Z2R	=	_____
Reverse Directional Current Threshold: (0.25 - 5 amps sec., 3I ₂)	50QR	=	_____
Positive-Sequence Current Restraint Factor: (0.02 - 0.5 unitless)	a2	=	_____

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Phase Time-Overcurrent Element Settings

Phase Time Overcurrent Element: Enable: (Y/N)	E51P	=	_____
Pickup: (0.5 - 16 amps sec.)	51PP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51PC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51PTD	=	_____
Reset Delay: (Y/N)	51PRS	=	_____
Torque Control: (M2P, N) (SEL-321 Relay Base Version)	51PTC	=	_____
(ZLIN, ZLOUT, M2P, N) (SEL-321-1 Relay)			

Residual Time-Overcurrent Element Settings

Residual Time Overcurrent Element: Enable: (Y/N/S)	E51N	=	_____
Pickup: (0.5 - 16 amps sec., 3I ₀)	51NP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51NC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51NTD	=	_____
Reset Delay: (Y/N)	51NRS	=	_____
Torque Control: (32QF, 32QR, Z2G, N)	51NTC	=	_____

Residual Overcurrent Element Settings

Enable Number of Residual Instantaneous Overcurrent Levels: (N,1,2,3,4)	E50N	=	_____
Residual Inst. Overcurrent Pickup: Level 1: (0.25 - 80 amps sec., 3I ₀)	50N1	=	_____
Level 2: (0.25 - 80 amps sec., 3I ₀)	50N2	=	_____
Level 3: (0.25 - 80 amps sec., 3I ₀)	50N3	=	_____
Level 4: (0.25 - 80 amps sec., 3I ₀)	50N4	=	_____

Negative-Sequence Time Overcurrent Element Settings

Negative-Sequence Time Overcurrent: Enable: (Y/N/S)	E51Q	=	_____
Pickup: (0.5 - 16 amps sec., 3I ₂)	51QP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51QC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51QTD	=	_____
Reset Delay: (Y/N)	51QRS	=	_____
Torque Control: (32QF, 32QR, M2P, Z2G, N)	51QTC	=	_____

Negative-Sequence Overcurrent Element Settings

Enable Number of Neg.-Sequence Inst. Overcurrent Levels: (N,1,2,3,4)	E50Q	=	_____
Neg.-Seq. Inst. Overcurrent Pickup: Level 1: (0.25 - 80 amps sec., 3I ₂)	50Q1	=	_____
Level 2: (0.25 - 80 amps sec., 3I ₂)	50Q2	=	_____
Level 3: (0.25 - 80 amps sec., 3I ₂)	50Q3	=	_____
Level 4: (0.25 - 80 amps sec., 3I ₂)	50Q4	=	_____

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Voltage Element Settings

Enable Voltage Elements: (Y/N)	EVOLT	=	_____
Zero-Sequence Over-Voltage: (0 - 150 V sec., 3V0)	59N	=	_____
Bus Phase Under-Voltage: (0 - 100 V sec.)	27L	=	_____
Bus Phase Over-Voltage: (0 - 100 V sec.)	59L	=	_____
Positive-Sequence Bus Over-Voltage: (0 - 150 V sec., V1)	59PB	=	_____
Positive-Sequence Bus Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PBD	=	_____
Positive-Sequence Remote Bus Over-Voltage: (0 - 150 V sec., V1)	59PR	=	_____
Current Comp. Remote Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PRD	=	_____
Current Compensated Remote Overvoltage Adjustment: (0 - 2 unitless)	a1	=	_____

Time Step Backup Time Delay Settings

Zone 2 Phase Long Time Delay (TDPU): (0 - 2000 cycles)	Z2PD	=	_____
Zone 3 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z3PD	=	_____
Zone 4 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z4PD	=	_____
Zone 2 Ground Long Time Delay (TDPU): (0 - 2000 cycles)	Z2GD	=	_____
Zone 3 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z3GD	=	_____
Zone 4 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z4GD	=	_____
Level 1 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL1D	=	_____
Level 2 Residual Long Time Delay (TDPU): (0 - 2000 cycles)	67NL2D	=	_____
Level 3 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL3D	=	_____
Level 4 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL4D	=	_____
Level 1 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL1D	=	_____
Level 2 Negative-Sequence Long Time Delay (TDPU): (0 - 2000 cycles)	67QL2D	=	_____
Level 3 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL3D	=	_____
Level 4 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL4D	=	_____

Permissive Overreaching Scheme Settings

Enable Permissive Overreaching Transfer Trip Scheme: (Y/N)	EPOTT	=	_____
Zone 3 Reverse Block Time Delay (TDDO): (0 - 2000 cycles)	Z3RBD	=	_____
Echo Block Time Delay (TDDO): (0 - 2000 cycles)	EBLKD	=	_____
Echo Time Delay Pickup Time Delay (TDPU): (0 - 2000 cycles)	ETDPU	=	_____
Echo Duration Time Delay (TDDO): (0 - 2000 cycles)	EDURD	=	_____
Weak-Infeed Enable: (Y/N)	EWFC	=	_____

Directional Comparison Unblocking Scheme Settings

Enable DCUB: (Y/N)	EDCUB	=	_____
Guard Present Security Time Delay (TDDO): (0 - 2000 cycles)	GARD1D	=	_____
DCUB Disabling Time Delay (TDPU): (0.25 - 2000 cycles)	UBDURD	=	_____
DCUB Duration Time Delay (TDPU): (0 - 2000 cycles)	UBEND	=	_____

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Directional Comparison Blocking Scheme Settings

Enable DCB: (Y/N)	EDCB	=	_____
Zone 3 Dropout Extension Time Delay (TDDO): (0 - 2000 cycles)	Z3XD	=	_____
Block Trip Receive Extension Time Delay (TDDO): (0 - 2000 cycles)	BTXD	=	_____
Zone 2 Phase Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2PSD	=	_____
Zone 2 Ground Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2GSD	=	_____
Level 2 Residual Short Delay Time Delay (TDPU): (0 - 60 cycles)	67N2SD	=	_____
Level 2 Neg.-Seq. Short Delay Time Delay (TDPU): (0 - 60 cycles)	67Q2SD	=	_____

Zone 1 Extension Settings

Enable Zone 1 Extension: (Y/N)	EZ1EXT	=	_____
Enable Time Delay (TDPU): (0 - 2000 cycles)	Z1EXTD	=	_____
Multiplier: (1 - 5 unitless)	Z1EXTM	=	_____

Remote-End-Just-Opened Settings

Enable: (Y/N)	EREJO	=	_____
Pickup Time Delay (TDPU): (0 - 2000 cycles)	REJOD	=	_____
Overcurrent Element Pickup: (0.5 - 100 amps sec.)	3P50R	=	_____

Switch-Onto-Fault Settings

Enable: (Y/N)	ESOTF	=	_____
Enable Close Logic: (Y/N)	ENCLO	=	_____
Close Enable Time Delay (TDPU): (0 - 8000 cycles)	CLOEND	=	_____
Enable 52A Logic: (Y/N)	EN52A	=	_____
52A Enable Time Delay (TDPU): (0 - 8000 cycles)	52AEND	=	_____
Time Duration (TDDO): (0.5 - 8000 cycles)	SOTFD	=	_____
High-Set Phase Overcurrent Pickup: (0.5 - 100 amps sec.)	50H	=	_____

Loss-of-Potential Settings

Enable Loss-Of-Potential: (Y, N, N1, Y1, Y2)	ELOP	=	_____
Loss-Of-Potential Time Delay (TDPU): (1 - 60 cycles)	LOPD	=	_____
Medium-Set Phase Overcurrent Pickup: (0.5 - 100 amps sec.)	50M	=	_____
Negative-Sequence Voltage LOP supervision: (0 - 150 V sec., V2)	59QL	=	_____
Positive-Sequence Voltage LOP supervision: (0 - 150 V sec., V1)	59PL	=	_____

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Miscellaneous Scheme Settings

Pole-Discordance Enable: (Y/N)	EPOLD	=	_____
Single-Pole Trip Pole-Discordance Time Delay (TDPU): (0 - 8000 cycles)	SPPDD	=	_____
Single-Pole Trip Enable: (Y/N/Y1/N1)	ESPT	=	_____
Single-Pole Open Enable: (Y/N)	ESPO	=	_____
Single-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	SPOD	=	_____
Three-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	3POD	=	_____
Enable Stub Protection: (Y/N)	ESTUB	=	_____
Stub Protection Time Delay (TDPU): (0 - 2000 cycles)	50MFD	=	_____
Trip Unlatch Option: (N,1,2,3,4)	TULO	=	_____

Miscellaneous Timers

Minimum Trip Duration Time Delay (TDDO): (0 - 2000 cycles)	TDURD	=	_____
Trip During Open Pole Time Delay (TDDO): (0 - 8000 cycles)	TOPD	=	_____
Relay Element X Time Delay Pickup (TDPU): (0 - 8000 cycles)	TXPU	=	_____
Relay Element X Time Delay Dropout (TDDO): (0 - 8000 cycles)	TXDO	=	_____
Relay Element Y Time Delay Pickup (TDPU): (0 - 8000 cycles)	TYPU	=	_____
Relay Element Y Time Delay Dropout (TDDO): (0 - 8000 cycles)	TYDO	=	_____
Relay Element Z Time Delay Pickup (TDPU): (0 - 8000 cycles)	TZPU	=	_____
Relay Element Z Time Delay Dropout (TDDO): (0 - 8000 cycles)	TZDO	=	_____
Instantaneous Trip Time Declaration Delay (TDPU): (0 - 60 cycles)	ITTD	=	_____

Logic Variables

LOGIC V	=	_____
LOGIC W	=	_____
LOGIC X	=	_____
LOGIC Y	=	_____
LOGIC Z	=	_____

Tripping Logic

MTCS	=	_____
MTU	=	_____
MTO	=	_____

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Event Report Trigger Condition Logic

MER = _____

Output Contact Logic

OUT1 = _____

OUT2 = _____

OUT3 = _____

OUT4 = _____

OUT5 = _____

OUT6 = _____

OUT7 = _____

OUT8 = _____

OUT9 = _____

OUT10 = _____

OUT11 = _____

OUT12 = _____

OUT13 = _____

OUT14 = _____

OUT15 = _____

* OUT17 = _____

* OUT18 = _____

* OUT19 = _____

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* OUT20	=	_____
* OUT21	=	_____
* OUT22	=	_____
* OUT23	=	_____
* OUT24	=	_____
* OUT25	=	_____
* OUT26	=	_____
* OUT27	=	_____
* OUT28	=	_____
* OUT29	=	_____
* OUT30	=	_____
* OUT31	=	_____
* OUT32	=	_____
TMB1	=	_____
TMB2	=	_____
TMB3	=	_____
TMB4	=	_____
TMB5	=	_____
TMB6	=	_____
TMB7	=	_____
TMB8	=	_____

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Global Contact Input Settings

Input Contact 1 Assignment:	IN1	=	_____
Input Contact 2 Assignment:	IN2	=	_____
Input Contact 3 Assignment:	IN3	=	_____
Input Contact 4 Assignment:	IN4	=	_____
Input Contact 5 Assignment:	IN5	=	_____
Input Contact 6 Assignment:	IN6	=	_____
Input Contact 7 Assignment:	IN7	=	_____
Input Contact 8 Assignment:	IN8	=	_____
* Input Contact 9 Assignment:	IN9	=	_____
* Input Contact 10 Assignment:	IN10	=	_____
* Input Contact 11 Assignment:	IN11	=	_____
* Input Contact 12 Assignment:	IN12	=	_____
* Input Contact 13 Assignment:	IN13	=	_____
* Input Contact 14 Assignment:	IN14	=	_____
* Input Contact 15 Assignment:	IN15	=	_____
* Input Contact 16 Assignment:	IN16	=	_____
Received MIRRORED BIT 1:	RMB1	=	_____
Received MIRRORED BIT 2:	RMB2	=	_____
Received MIRRORED BIT 3:	RMB3	=	_____
Received MIRRORED BIT 4:	RMB4	=	_____
Received MIRRORED BIT 5:	RMB5	=	_____
Received MIRRORED BIT 6:	RMB6	=	_____
Received MIRRORED BIT 7:	RMB7	=	_____
Received MIRRORED BIT 8:	RMB8	=	_____

Miscellaneous Global Settings

Front panel timeout: (0 - 30 minutes)	FP_TIMEOUT	=	_____
Group change delay: (0 - 900 seconds)	TGR	=	_____
CR RAM Diagnostics Action: Restart Enable (Y/N)	ERESTART	=	_____

* OUT17 - OUT32 available only on two I/O board relays.

* INPUT9 - INPUT16 available only on two I/O board relays.

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Line Terminal Settings

Relay Identifier: (17 Characters) RELID = _____
Terminal Identifier: (39 Characters) TRMID = _____

Positive-Seq. Line Impedance Magnitude: (0.25 - 1275 Ω sec.)	Z1MAG	=	_____
Positive-Seq. Line Impedance Angle: (5° - 90°)	Z1ANG	=	_____
Zero-Seq. Line Impedance Magnitude: (0.25 - 1275 Ω sec.)	Z0MAG	=	_____
Zero-Seq. Line Impedance Angle: (5° - 90°)	Z0ANG	=	_____
Fault Location Enable: (Y,R,N)	LOCAT	=	_____
Line Length: (0.1 - 999 unitless)	LL	=	_____
Current Transformer Ratio: (1 - 6000)	CTR	=	_____
Potential Transformer Ratio: (1 - 10000)	PTR	=	_____

Enable Zones of Distance Settings

Number Distance Zones: Mho Phase: (N,1,2,3,4)	PMHOZ	=	_____
Mho Ground: (N,1,2,3,4)	GMHOZ	=	_____
Quad. Ground: (N,1,2,3,4)	QUADZ	=	_____

Distance Zones and Overcurrent Levels Direction Settings

Distance Zone 1/Overcurrent Level 1 Direction: (F/R)	DIR1	=	_____
Distance Zone 2/Overcurrent Level 2 Direction: (F/R)	DIR2	=	_____
Distance Zone 3/Overcurrent Level 3 Direction: (F/R)	DIR3	=	_____
Distance Zone 4/Overcurrent Level 4 Direction: (F/R)	DIR4	=	_____

Mho Phase Distance Settings

Impedance Reach: Zone 1: (0.25 - 320 Ω sec.)	Z1P	=	_____
Zone 2: (0.25 - 320 Ω sec.)	Z2P	=	_____
Zone 3: (0.25 - 320 Ω sec.)	Z3P	=	_____
Zone 4: (0.25 - 320 Ω sec.)	Z4P	=	_____

Mho Phase Distance Overcurrent Supervision Settings

Phase-to-Phase Overcurrent: Zone 1: (0.2 - 34 amps sec.)	50PP1	=	_____
Zone 2: (0.2 - 34 amps sec.)	50PP2	=	_____
Zone 3: (0.2 - 34 amps sec.)	50PP3	=	_____
Zone 4: (0.2 - 34 amps sec.)	50PP4	=	_____

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Mho Ground Distance Settings

Impedance Reach:	Zone 1: (0.25 - 320 Ω sec.)	Z1MG	=	_____
	Zone 2: (0.25 - 320 Ω sec.)	Z2MG	=	_____
	Zone 3: (0.25 - 320 Ω sec.)	Z3MG	=	_____
	Zone 4: (0.25 - 320 Ω sec.)	Z4MG	=	_____

Quadrilateral Ground Distance Settings

Reactive Reach:	Zone 1: (0.25 - 320 Ω sec.)	XG1	=	_____
	Zone 2: (0.25 - 320 Ω sec.)	XG2	=	_____
	Zone 3: (0.25 - 320 Ω sec.)	XG3	=	_____
	Zone 4: (0.25 - 320 Ω sec.)	XG4	=	_____
Resistive Reach:	Zone 1: (0.25 - 250 Ω sec.)	RG1	=	_____
	Zone 2: (0.25 - 250 Ω sec.)	RG2	=	_____
	Zone 3: (0.25 - 250 Ω sec.)	RG3	=	_____
	Zone 4: (0.25 - 250 Ω sec.)	RG4	=	_____

Ground Distance Overcurrent Supervision Settings

Phase Overcurrent Supervision:	Zone 1: (0.1 - 20 amps sec.)	50L1	=	_____
	Zone 2: (0.1 - 20 amps sec.)	50L2	=	_____
	Zone 3: (0.1 - 20 amps sec.)	50L3	=	_____
	Zone 4: (0.1 - 20 amps sec.)	50L4	=	_____
Residual Overcurrent Supervision:	Zone 1: (0.1 - 20 amps sec.)	50G1	=	_____
	Zone 2: (0.1 - 20 amps sec.)	50G2	=	_____
	Zone 3: (0.1 - 20 amps sec.)	50G3	=	_____
	Zone 4: (0.1 - 20 amps sec.)	50G4	=	_____

Zero-Sequence Compensation Factor Settings

Zone 1 Zero-Sequence Comp. Factor 1 Magnitude: (0 - 4 unitless)	k01M	=	_____
Zone 1 Zero-Sequence Comp. Factor 1 Angle: ($\pm 180^\circ$)	k01A	=	_____
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Mag.: (0 - 4 unitless)	k0M	=	_____
Zones 2, 3, & 4 Zero-Sequence Comp. Factor 2 Angle: ($\pm 180^\circ$)	k0A	=	_____
Non-Homogeneous Correction Angle: ($\pm 20^\circ$)	T	=	_____

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Out-of-Step Blocking and Tripping Settings

Enable OOS: (Y/N)	EOOS	=	_____
OOSB Enable: Block Zone 1: (Y/N)	OOSB1	=	_____
Block Zone 2: (Y/N)	OOSB2	=	_____
Block Zone 3: (Y/N)	OOSB3	=	_____
Block Zone 4: (Y/N)	OOSB4	=	_____
Out-of-Step Block Time Delay (TDPU): (0.5 - 8000 cycles)	OSBD	=	_____
Enable OOST: (I/O/N)	EOOST	=	_____
Out-of-Step TOWI Time Delay (TDPU): (0.5 - 8000 cycles)	OSTD	=	_____
Zone 5 Reactive Reach: Top: (0 to $\pm 480 \Omega$ sec.)	X1T5	=	_____
Bottom: (0 to $\pm 480 \Omega$ sec.)	X1B5	=	_____
Zone 5 Resistive Reach: Right: (0 to $\pm 350 \Omega$ sec.)	R1R5	=	_____
Left: (0 to $\pm 350 \Omega$ sec.)	R1L5	=	_____
Zone 6 Reactive Reach: Top: (0 to $\pm 480 \Omega$ sec.)	X1T6	=	_____
Bottom: (0 to $\pm 480 \Omega$ sec.)	X1B6	=	_____
Zone 6 Resistive Reach: Right: (0 to $\pm 350 \Omega$ sec.)	R1R6	=	_____
Left: (0 to $\pm 350 \Omega$ sec.)	R1L6	=	_____
Zone 6 Positive-Sequence Overcurrent Supervision: (0.2 - 20 amps sec., I_1)	50ABC	=	_____

Load-Encroachment Settings

Enable Load-Encroachment: (Y/N)	ELE	=	_____
Load Impedance: Forward: (0.25 - 320 Ω sec.)	ZLF	=	_____
Reverse: (0.25 - 320 Ω sec.)	ZLR	=	_____
Load Angle: Positive Forward: (-90° to +90°)	PLAF	=	_____
Negative Forward: (-90° to +90°)	NLAF	=	_____
Positive Reverse: (+90° to +270°)	PLAR	=	_____
Negative Reverse: (+90° to +270°)	NLAR	=	_____

Negative-Sequence Directional Element Settings

Forward Directional Z2 Threshold: ($\pm 320 \Omega$ sec.)	Z2F	=	_____
Forward Directional Current Threshold: (0.05 - 1 amps sec., $3I_2$)	50QF	=	_____
Reverse Directional Z2 Threshold: ($\pm 320 \Omega$ sec.)	Z2R	=	_____
Reverse Directional Current Threshold: (0.05 - 1 amps sec., $3I_2$)	50QR	=	_____
Positive-Sequence Current Restraint Factor: (0.02 - 0.5 unitless)	a2	=	_____

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Phase Time-Overcurrent Element Settings

Phase Time Overcurrent Element: Enable: (Y/N)	E51P	=	_____
Pickup: (0.1 - 3.2 amps sec.)	51PP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51PC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51PTD	=	_____
Reset Delay: (Y/N)	51PRS	=	_____
Torque Control: (M2P, N) (SEL-321 Relay Base Version)	51PTC	=	_____
(ZLIN, ZLOUT, M2P, N) (SEL-321-1 Relay)			

Residual Time-Overcurrent Element Settings

Residual Time Overcurrent Element: Enable: (Y/N/S)	E51N	=	_____
Pickup: (0.1 - 3.2 amps sec., 3I ₀)	51NP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51NC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51NTD	=	_____
Reset Delay: (Y/N)	51NRS	=	_____
Torque Control: (32QF, 32QR, Z2G, N)	51NTC	=	_____

Residual Overcurrent Element Settings

Enable Number of Residual Instantaneous Overcurrent Levels: (N,1,2,3,4)	E50N	=	_____
Residual Inst. Overcurrent Pickup: Level 1: (0.05 - 16 amps sec., 3I ₀)	50N1	=	_____
Level 2: (0.05 - 16 amps sec., 3I ₀)	50N2	=	_____
Level 3: (0.05 - 16 amps sec., 3I ₀)	50N3	=	_____
Level 4: (0.05 - 16 amps sec., 3I ₀)	50N4	=	_____

Negative-Sequence Time Overcurrent Element Settings

Negative-Sequence Time Overcurrent: Enable: (Y/N/S)	E51Q	=	_____
Pickup: (0.1 - 3.2 amps sec., 3I ₂)	51QP	=	_____
Curve Family: (U1,U2,U3,U4,C1,C2,C3,C4)	51QC	=	_____
Time Dial: (US 0.5 - 15, IEC 0.05 - 1)	51QTD	=	_____
Reset Delay: (Y/N)	51QRS	=	_____
Torque Control: (32QF, 32QR, M2P, Z2G, N)	51QTC	=	_____

Negative-Sequence Overcurrent Element Settings

Enable Number of Neg.-Sequence Inst. Overcurrent Levels: (N,1,2,3,4)	E50Q	=	_____
Neg.-Seq. Inst. Overcurrent Pickup: Level 1: (0.05 - 16 amps sec., 3I ₂)	50Q1	=	_____
Level 2: (0.05 - 16 amps sec., 3I ₂)	50Q2	=	_____
Level 3: (0.05 - 16 amps sec., 3I ₂)	50Q3	=	_____
Level 4: (0.05 - 16 amps sec., 3I ₂)	50Q4	=	_____

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Voltage Element Settings

Enable Voltage Elements: (Y/N)	EVOLT	=	_____
Zero-Sequence Over-Voltage: (0 - 150 V sec., 3V0)	59N	=	_____
Bus Phase Under-Voltage: (0 - 100 V sec.)	27L	=	_____
Bus Phase Over-Voltage: (0 - 100 V sec.)	59L	=	_____
Positive-Sequence Bus Over-Voltage: (0 - 150 V sec., V1)	59PB	=	_____
Positive-Sequence Bus Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PBD	=	_____
Positive-Sequence Remote Bus Over-Voltage: (0 - 150 V sec., V1)	59PR	=	_____
Current Comp. Remote Over-Voltage Time Delay (TDPU): (0 - 8000 cyc)	59PRD	=	_____
Current Compensated Remote Overvoltage Adjustment: (0 - 2 unitless)	a1	=	_____

Time Step Backup Time Delay Settings

Zone 2 Phase Long Time Delay (TDPU): (0 - 2000 cycles)	Z2PD	=	_____
Zone 3 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z3PD	=	_____
Zone 4 Phase Time Delay (TDPU): (0 - 2000 cycles)	Z4PD	=	_____
Zone 2 Ground Long Time Delay (TDPU): (0 - 2000 cycles)	Z2GD	=	_____
Zone 3 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z3GD	=	_____
Zone 4 Ground Time Delay (TDPU): (0 - 2000 cycles)	Z4GD	=	_____
Level 1 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL1D	=	_____
Level 2 Residual Long Time Delay (TDPU): (0 - 2000 cycles)	67NL2D	=	_____
Level 3 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL3D	=	_____
Level 4 Residual Time Delay (TDPU): (0 - 2000 cycles)	67NL4D	=	_____
Level 1 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL1D	=	_____
Level 2 Negative-Sequence Long Time Delay (TDPU): (0 - 2000 cycles)	67QL2D	=	_____
Level 3 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL3D	=	_____
Level 4 Negative-Sequence Time Delay (TDPU): (0 - 2000 cycles)	67QL4D	=	_____

Permissive Overreaching Scheme Settings

Enable Permissive Overreaching Transfer Trip Scheme: (Y/N)	EPOTT	=	_____
Zone 3 Reverse Block Time Delay (TDDO): (0 - 2000 cycles)	Z3RBD	=	_____
Echo Block Time Delay (TDDO): (0 - 2000 cycles)	EBLKD	=	_____
Echo Time Delay Pickup Time Delay (TDPU): (0 - 2000 cycles)	ETDPU	=	_____
Echo Duration Time Delay (TDDO): (0 - 2000 cycles)	EDURD	=	_____
Weak-Infeed Enable: (Y/N)	EWFC	=	_____

Directional Comparison Unblocking Scheme Settings

Enable DCUB: (Y/N)	EDCUB	=	_____
Guard Present Security Time Delay (TDDO): (0 - 2000 cycles)	GARD1D	=	_____
DCUB Disabling Time Delay (TDPU): (0.25 - 2000 cycles)	UBDURD	=	_____
DCUB Duration Time Delay (TDPU): (0 - 2000 cycles)	UBEND	=	_____

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Directional Comparison Blocking Scheme Settings

Enable DCB: (Y/N)	EDCB	=	_____
Zone 3 Dropout Extension Time Delay (TDDO): (0 - 2000 cycles)	Z3XD	=	_____
Block Trip Receive Extension Time Delay (TDDO): (0 - 2000 cycles)	BTXD	=	_____
Zone 2 Phase Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2PSD	=	_____
Zone 2 Ground Distance Short Delay Time Delay (TDPU): (0 - 60 cycles)	Z2GSD	=	_____
Level 2 Residual Short Delay Time Delay (TDPU): (0 - 60 cycles)	67N2SD	=	_____
Level 2 Neg.-Seq. Short Delay Time Delay (TDPU): (0 - 60 cycles)	67Q2SD	=	_____

Zone 1 Extension Settings

Enable Zone 1 Extension: (Y/N)	EZ1EXT	=	_____
Enable Time Delay (TDPU): (0 - 2000 cycles)	Z1EXTD	=	_____
Multiplier: (1 - 5 unitless)	Z1EXTM	=	_____

Remote-End-Just-Opened Settings

Enable: (Y/N)	EREJO	=	_____
Pickup Time Delay (TDPU): (0 - 2000 cycles)	REJOD	=	_____
Overcurrent Element Pickup: (0.1 - 20 amps sec.)	3P50R	=	_____

Switch-Onto-Fault Settings

Enable: (Y/N)	ESOTF	=	_____
Enable Close Logic: (Y/N)	ENCLO	=	_____
Close Enable Time Delay (TDPU): (0 - 8000 cycles)	CLOEND	=	_____
Enable 52A Logic: (Y/N)	EN52A	=	_____
52A Enable Time Delay (TDPU): (0 - 8000 cycles)	52AEND	=	_____
Time Duration (TDDO): (0.5 - 8000 cycles)	SOTFD	=	_____
High-Set Phase Overcurrent Pickup: (0.1 - 20 amps sec.)	50H	=	_____

Loss-of-Potential Settings

Enable Loss-Of-Potential: (Y, N, N1, Y1, Y2)	ELOP	=	_____
Loss-Of-Potential Time Delay (TDPU): (1 - 60 cycles)	LOPD	=	_____
Medium-Set Phase Overcurrent Pickup: (0.1 - 20 amps sec.)	50M	=	_____
Negative-Sequence Voltage LOP supervision: (0 - 150 V sec., V2)	59QL	=	_____
Positive-Sequence Voltage LOP supervision: (0 - 150 V sec., V1)	59PL	=	_____

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Miscellaneous Scheme Settings

Pole-Discordance Enable: (Y/N)	EPOLD	=	_____
Single-Pole Trip Pole-Discordance Time Delay (TDPU): (0 - 8000 cycles)	SPPDD	=	_____
Single-Pole Trip Enable: (Y/N/Y1/N1)	ESPT	=	_____
Single-Pole Open Enable: (Y/N)	ESPO	=	_____
Single-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	SPOD	=	_____
Three-Pole Open Time Delay (TDDO): (0 - 8000 cycles)	3POD	=	_____
Enable Stub Protection: (Y/N)	ESTUB	=	_____
Stub Protection Time Delay (TDPU): (0 - 2000 cycles)	50MFD	=	_____
Trip Unlatch Option: (N,1,2,3,4)	TULO	=	_____

Miscellaneous Timers

Minimum Trip Duration Time Delay (TDDO): (0 - 2000 cycles)	TDURD	=	_____
Trip During Open Pole Time Delay (TDDO): (0 - 8000 cycles)	TOPD	=	_____
Relay Element X Time Delay Pickup (TDPU): (0 - 8000 cycles)	TXPU	=	_____
Relay Element X Time Delay Dropout (TDDO): (0 - 8000 cycles)	TXDO	=	_____
Relay Element Y Time Delay Pickup (TDPU): (0 - 8000 cycles)	TYPU	=	_____
Relay Element Y Time Delay Dropout (TDDO): (0 - 8000 cycles)	TYDO	=	_____
Relay Element Z Time Delay Pickup (TDPU): (0 - 8000 cycles)	TZPU	=	_____
Relay Element Z Time Delay Dropout (TDDO): (0 - 8000 cycles)	TZDO	=	_____
Instantaneous Trip Time Declaration Delay (TDPU): (0 - 60 cycles)	ITTD	=	_____

Logic Variables

LOGIC V	=	_____
LOGIC W	=	_____
LOGIC X	=	_____
LOGIC Y	=	_____
LOGIC Z	=	_____

Tripping Logic

MTCS	=	_____
MTU	=	_____
MTO	=	_____

**SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(1A NOMINAL RELAY)**

Page 8 of 10
Date _____

Event Report Trigger Condition Logic

MER = _____

Output Contact Logic

OUT1 = _____
OUT2 = _____
OUT3 = _____
OUT4 = _____
OUT5 = _____
OUT6 = _____
OUT7 = _____
OUT8 = _____
OUT9 = _____
OUT10 = _____
OUT11 = _____
OUT12 = _____
OUT13 = _____
OUT14 = _____
OUT15 = _____
* OUT17 = _____
* OUT18 = _____
* OUT19 = _____

**SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(1A NOMINAL RELAY)**

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Date _____

* OUT20	=	_____
* OUT21	=	_____
* OUT22	=	_____
* OUT23	=	_____
* OUT24	=	_____
* OUT25	=	_____
* OUT26	=	_____
* OUT27	=	_____
* OUT28	=	_____
* OUT29	=	_____
* OUT30	=	_____
* OUT31	=	_____
* OUT32	=	_____
TMB1	=	_____
TMB2	=	_____
TMB3	=	_____
TMB4	=	_____
TMB5	=	_____
TMB6	=	_____
TMB7	=	_____
TMB8	=	_____

**SETTINGS SHEET
FOR THE SEL-321-3 RELAY
(1A NOMINAL RELAY)**

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Date _____

Global Contact Input Settings

Input Contact 1 Assignment:	IN1	=	_____
Input Contact 2 Assignment:	IN2	=	_____
Input Contact 3 Assignment:	IN3	=	_____
Input Contact 4 Assignment:	IN4	=	_____
Input Contact 5 Assignment:	IN5	=	_____
Input Contact 6 Assignment:	IN6	=	_____
Input Contact 7 Assignment:	IN7	=	_____
Input Contact 8 Assignment:	IN8	=	_____
* Input Contact 9 Assignment:	IN9	=	_____
* Input Contact 10 Assignment:	IN10	=	_____
* Input Contact 11 Assignment:	IN11	=	_____
* Input Contact 12 Assignment:	IN12	=	_____
* Input Contact 13 Assignment:	IN13	=	_____
* Input Contact 14 Assignment:	IN14	=	_____
* Input Contact 15 Assignment:	IN15	=	_____
* Input Contact 16 Assignment:	IN16	=	_____
Received MIRRORED BIT 1:	RMB1	=	_____
Received MIRRORED BIT 2:	RMB2	=	_____
Received MIRRORED BIT 3:	RMB3	=	_____
Received MIRRORED BIT 4:	RMB4	=	_____
Received MIRRORED BIT 5:	RMB5	=	_____
Received MIRRORED BIT 6:	RMB6	=	_____
Received MIRRORED BIT 7:	RMB7	=	_____
Received MIRRORED BIT 8:	RMB8	=	_____

Miscellaneous Global Settings

Front panel timeout: (0 - 30 minutes)	FP_TIMEOUT	=	_____
Group change delay: (0 - 900 seconds)	TGR	=	_____
CR RAM Diagnostics Action: Restart Enable (Y/N)	ERESTART	=	_____

* OUT17 - OUT32 available only on two I/O board relays.

* INPUT9 - INPUT16 available only on two I/O board relays.

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SECTION 6: INSTALLATION

INTRODUCTION

Planning should be the first step you take before installing any new device, and it is equally essential to ensure successful installation and operation of the SEL-321 Relay. This section of the SEL-321 instruction manual includes information and procedures you should be familiar with to install the SEL-321 Relay safely and effectively. Safe and effective installation of the SEL-321 Relay requires proper mounting, connection, communications, and setup.

INITIAL CHECKOUT

Perform the following steps to ensure that the SEL-321 Relay operates prior to installation:

1. Visually inspect the relay for loose or damaged parts.
2. Connect and apply power to the relay (see the “PWR SUP” field on the rear-panel nameplate for power requirements). If you do not have the proper voltage source available, use a power supply, such as the SEL-LPS, to power the unit.
3. Verify that the front-panel LEDs and LCD back-light come on when power is applied.
4. After a couple of seconds, the EN LED should light and “EN” should be visible in the LCD display. The ALARM contact should also operate (open). Momentarily press the TARGET RESET button and verify that all LEDs operate. (**Note:** If the LCD display is not readable, use a small slotted-tip screwdriver to adjust it via the hole near the EN LED.)
5. Connect a terminal (or computer equipped with terminal emulation software) to the front-panel connector Port 3 of the SEL-321 Relay using an SEL-C234A cable or equivalent (see *Communication Cables* in this section).
6. Set the computer terminal or emulation software to operate at:

2400 baud, 8 data bits, 1 stop bit, no parity
7. Press <ENTER> and verify that a “=” prompt is returned.
8. Type ACCESS<ENTER> to change to Access Level 1. If you enabled password protection, enter the factory-set password by typing OTTER<ENTER> at the password prompt. You should now have a “=>” (Level 1) prompt
9. Type STATUS<ENTER> and verify that a status report appears on your terminal. Refer to the STATUS command in *Section 3: Communications* for more detailed information. This step completes initial checkout of the SEL-321 Relay.

MOUNTING AND CONNECTIONS

This subsection provides details about the physical mounting and connection requirements for the SEL-321 Relay.

Mounting

The relay is designed to be permanently mounted in a dry, indoor location. The relay may be mounted either horizontally or vertically by its front flanges in a 19-inch relay rack. It may also be mounted semi-flush in a switchboard panel. Use four #10 screws for mounting. See Figure 6.2 through Figure 6.14 for front and rear panel drawings, mounting dimensions, and drilling details.

Rear-Panel Plug-In Connectors Option (Figure 6.10 through Figure 6.12)

Note: Important: Improvements in Connectorized[®] SEL-321 Relays (plug-in connectors) result in part number changes.

The current transformer shorting connector (for current channel inputs IA, IB, and IC) has been made more robust. This improvement makes the new connector design incompatible with the old design. Thus, presently constructed connectorized SEL-321 Relays with this improved connector have a new part number (partial part numbers shown):

Old	New
321xK	321xZ
321xJ	321xY

The respective wiring harness part numbers for these old and new connectorized SEL-321 Relays are (partial part numbers shown):

Old	New
W0321xK	WA0321xZ
W0321xJ	WA0321xY

The other connectors on the connectorized SEL-321 Relay rear panel (power input, voltage inputs, output contacts, etc.) are the same for the old or new models. Only the current transformer shorting connector has changed.

Figure 6.10, Figure 6.11, and Figure 6.12 show the rear panels for new models 321xZ and 321xY. These figures can also be used as a reference for old models 321xK and 321xJ, respectively. All terminal labeling/numbering remains the same.

Connector terminals 201-340 accept wire size AWG 24 to 12 (install wires with a small slotted-tip screwdriver).

Note: Output contacts OUT1-OUT28 and ALARM on relays equipped with interrupting-duty contacts are polarity dependent (note the “+” symbol on these contacts).

As an example, consider the connection of terminals 217 and 218 (output contact OUT1) in a circuit:

Terminal 218 (+) has to be at a higher voltage potential than terminal 217 in the circuit.

Standard output contacts are not polarity dependent (they do not have a “+” symbol).

Optoisolated inputs IN1 through IN16 are not polarity dependent.

Current input connector (terminals 101-108):

- Contains current transformer shorting mechanisms
- Accepts wire size AWG 16 to 10 (special tool required to attach wire to connector)
- Can be ordered prewired

Ground connection (terminal 124): tab size 0.250 inch x 0.032 inch, screw size #6-32.

Frame Ground Connection

You must connect the grounding terminal (#124) labeled “GND” on the rear panel to a frame ground for proper safety and performance. Use 12 AWG (or heavier) wire, less than 2m (6 feet) long for this. This terminal connects directly to the internal chassis ground of the instrument.

Power Connections

The terminals labeled “POWER” on the rear panel must be connected to a power source that matches the power supply (PWR SUP) characteristics specified on the rear-panel nameplate of your SEL-321 Relay. Control power passes through these terminals to the fuse(s) and a toggle switch, if installed. These terminals are isolated from the chassis ground. If you provide a dc power source, you must connect the source with the proper polarity as indicated by the “+” and “–” symbols on the power terminals. The SEL-321 Relay internal power supply has low power consumption and a wide input voltage tolerance. See *General Specifications* in **Section 2: Specifications** for complete power supply information.

Secondary Circuit Connections

The SEL-321 Relay presents a very low burden to the secondary potential and current circuits. It requires three phase, four-wire (wye) potentials (VA, VB, VC, and N) and three currents (IA, IB, IC) from the power system transformer secondaries. See Figure 6.17. Check the specified rotation and nominal voltage, current, and frequency on the rear-panel nameplate to ensure proper application prior to connection. To verify these connections, trigger an event report using the TRIGGER command (see **Section 3: Communications**). Analyze it using the SEL Direction and Polarity Check Form included at the end of this section.

Control Circuit Connections

Refer to Figure 6.18 and Figure 6.19.

Control Inputs

Relays come standard with control inputs that operate at the same voltage level as the relay power source. Check the control voltage, labeled “LOGIC INPUT” on the rear-panel nameplate, before making any connections. The control inputs are optically isolated “dry” circuits and are not polarity sensitive. To assert the IN1 input, for example, you must apply control voltage to the terminals assigned the IN1 input. Each input is individually isolated, and a terminal pair is brought out for each input. There are no internal connections between control inputs. To assign the functions of the control inputs, see *Contact Input Assignments* in **Section 2: Specifications** and the **SET G** command in **Section 3: Communications** for more details. To verify operation of the inputs, use the TARGET command (see **Section 3: Communications**). Several control (or contact) input configurations are available; contact your local representative or the factory for information.

Control Outputs

The standard control outputs are “dry” relay contacts rated for tripping duty. The optional interrupting-duty control outputs are polarity dependent and are capable of interrupting high-current, inductive loads. A metal-oxide varistor (MOV) protects each contact. Each output is individually isolated, and a terminal pair is brought out for each output (Note: some I/O boards share a common connection with adjacent contacts). There are no internal connections between control outputs (except as noted previously). To assign the functions of the control outputs, see *Trip Logic* in **Section 2: Specifications** and the **SET L** command in **Section 3: Communications** for more details. To verify operation of the outputs, use the PULSE command (see **Section 3: Communications**).

Alarm Contact Connection

The SEL-321 Relay includes an alarm output contact labeled “ALARM” on the rear panel. At the factory, the alarm contact is configured to be closed for an alarm condition, and open for normal operation. This is a “Form B” contact because it is closed when there is no power. To invert the alarm output to close under normal conditions (“Form-A”), change the soldered jumper associated with the alarm relay on the interface board where the alarm relay is located. See *Input/Output Connections* later in this section for details.

Note: If the ALARM contact has a “+” symbol, it is polarity dependent and must be connected accordingly.

The alarm contact asserts when power is disconnected from the SEL-321 Relay, the power supply fails, or self-test diagnostics detect a failure. Self-test diagnostic failures include memory failures, power supply failures, and invalid settings failures. See *Self-Tests* in **Section 2: Specifications** and the **STATUS** command in **Section 3: Communications** for a discussion on these failures and the alarm contact response to them. Also, the alarm contact is pulsed when Breaker or Level 2 access is established or when a setting change is accepted.

IRIG-B Input Connection

The SEL-321 Relay accepts a demodulated IRIG-B signal through a rear-panel 9-pin, subminiature "D" connector labeled "DEMODULATED IRIG-B". This allows synchronization with an external time source. See *Communications Ports Specifications* in **Section 2: Specifications** for connector pinout and additional details.

The IRIG-B signal includes code for time-of-day and day-of-year. It does not include a code to identify the year. To ensure the device calendar is set to the proper year, set the date using the DATE command (see **Section 3: Communications**). The relay stores the year for the set date with the relay settings in nonvolatile memory, so once the date is properly set, the relay will maintain the proper year even if relay power is cycled off and on. The relay does not maintain the time, month or day when power is off. If no external IRIG-B input signal is applied, the relay will start its clock/calendar at 0:00:00 and 1/1/YY at power up.

Where distance between the SEL-321 Relay and the IRIG-B sending device exceeds the cable length recommended for conventional EIA-232 metallic conductor cables, you can use modems to provide isolation and to establish communications to remote locations. Unfortunately, conventional short-haul, fiber optic, and telephone modems do not support IRIG-B signal transmission, so their use requires that you use some other method to synchronize the time in the SEL-321 Relay. Special fiber optic modems (like the SEL-2810) are available, however, that include a channel for the IRIG-B time code; these modems enable you to synchronize more precisely with devices (such as the SEL-2020) capable of sending IRIG-B time code, even with a fiber optic communication link.

The actual IRIG-B input circuit is a 330 Ω resistor in series with an optocoupler input diode. The input diode forward voltage drop is about 1.5 V. Driver circuits should put approximately 10 mA through the circuit when "on" (this would be accomplished by a 0 - 5 Vdc signal capable of supplying at least 10 mA when at 5 V). Ensure that the two connector pins are connected with proper polarity.

The IRIG-B serial data format consists of a one-second frame containing 100 pulses that are divided into fields. The relay decodes the second, minute, hour, and day fields and sets its internal time clock accordingly.

When IRIG-B data acquisition is activated, either manually (with the IRIG command), or automatically, two consecutive frames are taken. The first frame is updated by one second and then compared with the second frame. If they do not agree, the relay considers the data erroneous and discards it.

The relay reads the time-code automatically about once every minute. The relay stops IRIG-B data acquisition ten minutes before midnight on New Year's Eve every year so the relay clock may implement the year change without interference from the IRIG-B input. Ten minutes later, the relay restarts IRIG-B data acquisition.

Communication Circuit Connections

The SEL-321 Relay is equipped with two rear-panel serial communication ports, labeled "SERIAL PORT 1" and "SERIAL PORT 2", and one front-panel serial communication port, labeled "SERIAL PORT 3". The data connection for each SEL-321 serial communication port uses EIA-232 standard signal levels in a 9-pin, subminiature "D" connector (see Figure 6.1 for pin number convention and *Communications Ports Specifications* in **Section 2: Specifications**

for pin assignments). EIA-232 interfaces are supported by almost all modern relays, meters, computer, and communications devices. See Figure 6.15 and Figure 6.16.

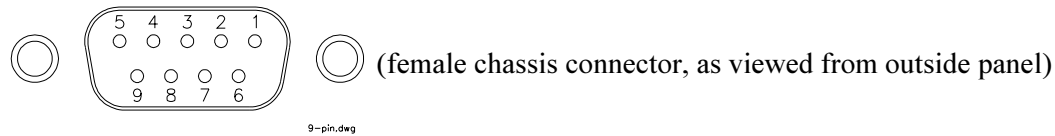


Figure 6.1: 9-Pin Connector Pin Number Convention



Do not rely upon pins 5 and 9 for safety grounding, because their current carrying capacity is less than control power short circuit and protection levels.

Pins 5 and 9 connect to frame (chassis) ground via the main board ground plane. The communication circuits are protected internally by low-energy, low-voltage MOVs and passive RC filters.

You should keep the length of the communication cables as short as possible to minimize communication circuit interference and also to minimize the magnitude of hazardous ground potential differences that can develop during abnormal power system conditions. See the next subsection, *Communication Cables*, for additional details and restrictions.

Communication Cables

Several standard SEL communication cables are available for use with the SEL-321 Relay. See below for some representative pinouts. Using an improper cable can cause numerous problems, so you must be sure to specify the proper cable for the application. To help in this regard, cable selector software is now available. Please contact SEL for more information or if you have any questions about cables and cable connections.

Never use standard null-modem cables with the SEL-321 Relay. Using any non-SEL cable can cause severe power and ground problems on the SEL-321 Relay communication ports.

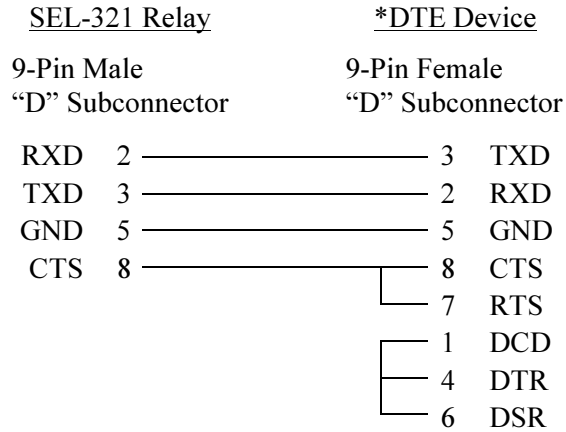
The following list provides additional rules and practices you should follow to ensure successful communication using EIA-232 serial communication devices and cables:

- You should keep the length of the communication cables as short as possible to minimize communication circuit interference and also to minimize the magnitude of hazardous ground potential differences that can develop during abnormal power system conditions.
- EIA-232 communication cable lengths should never exceed 50 feet, and you should always use shielded cables for communication circuit lengths greater than 10 feet.
- Modems are required for communications over long distances and to provide isolation from ground potential differences between device locations.
- Route communication cables well away from power and control circuits. Switching spikes and surges in power and control circuits can cause noise in the communications circuits if not adequately separated.

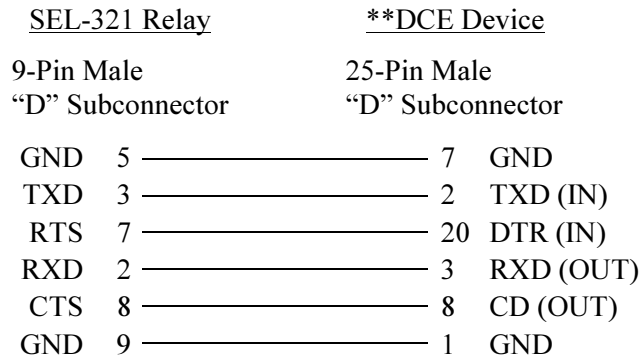
- Lower baud rate communication is less susceptible to interference and will transmit greater distances over the same medium than with higher baud rates. You should use the lowest baud rate that provides adequate data transfer speed.

EIA-232 Cables

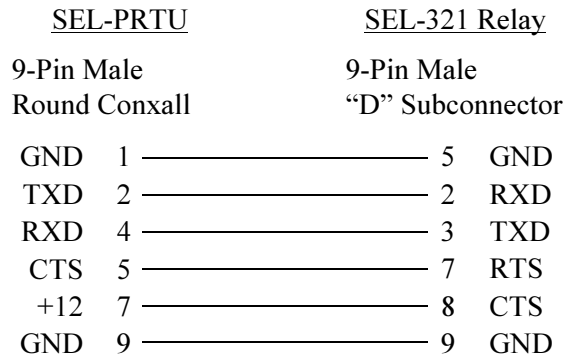
Cable C234A



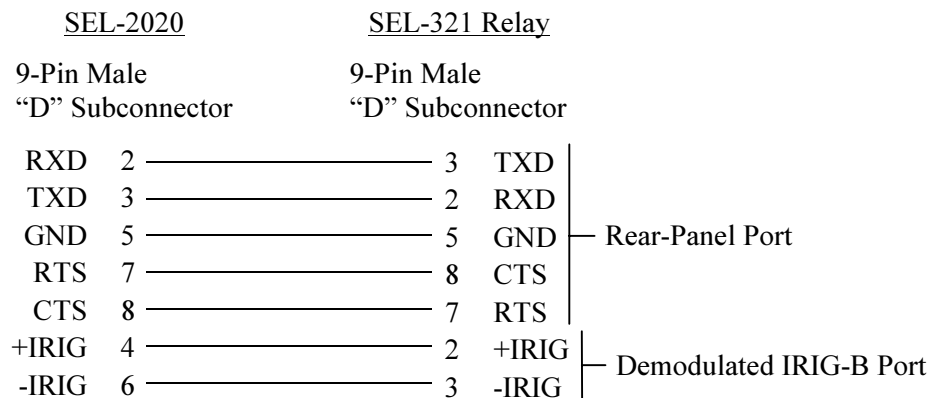
Cable C222



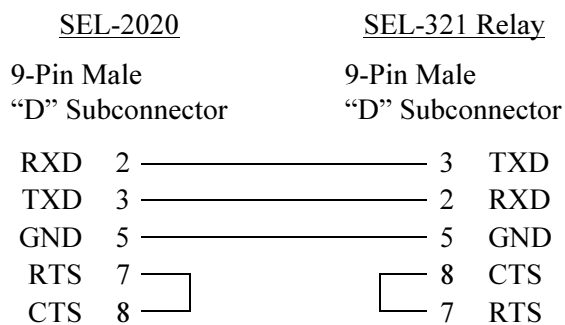
Cable 231



Cable 239
Data and IRIG-B



Cable 272A
Data Only



- * DTE = Data Terminal Equipment (Computer, Terminal, Printer, etc.)
- ** DCE = Data Communications Equipment (Modem, etc.)

COMMUNICATIONS

This subsection describes how you can optimize the communications interface between the SEL-321 Relay and other devices it will communicate with.

Modems

If electrical interference is a problem, consider using point-to-point fiber-optic modems to provide electrical isolation and noise immunity. We recommend the SEL-2800/2810 Fiber-Optic Transceivers for these applications. The connection between the SEL-321 Relay and the modem is EIA-232. The connection between the remote modem and the remote device is also EIA-232. Optical fibers connect the two modems.

For sites where the main issue is cable length, you can use short-haul modems connected by wire. This alternative is a compromise between the low cost and short cable for direct EIA-232 connections and the isolation and noise immunity of higher-cost fiber-optic links.

You must provide power to any modem that you install between the SEL-321 Relay and another device. You can use the SEL-321 Relay to power some types of modems connected to its rear-panel ports. The SEL-321 will support modems which accept +5 Vdc power. The total current drawn by all of the external modems powered by one SEL-321 should not exceed 0.5 A. Some modems power themselves from the control and data lines. These modems do not require connection to the +5 Vdc power.

Note: The three rear-panel ports provide +5 Vdc at Pin 1 of their 9-pin connectors. These are tied to the main board power supply. Use care when connecting to these pins. Misapplication may result in main board damage.

Telephone Line Communications

A telephone dial-up link is one option for off-site communications with an SEL-321 Relay. Use a modem to convert from the audio telephone line to an EIA-232 interface on the SEL-321 Relay.

You should use telephone line protection equipment where the line enters the building, to ensure personnel safety and reduce damage to equipment from ground-potential rise and other hazardous conditions. Connect the line protection equipment to the modem following standard commercial telephone wiring standards.

Data Flow Control

All SEL devices, including the SEL-321 Relay, support XON/XOFF software data flow control. Set RTS/CTS = N to connect an SEL-321 Relay to any SEL device. See the ***SET P*** command in ***Section 3: Communications*** for details.

The SEL-321 Relay also supports RTS/CTS hardware data flow control on Port 1 and Port 2. You should select the RTS/CTS option only if the connected device uses RTS/CTS, and does not use XON/XOFF flow control. Consult the instruction manual or contact the device vendor to determine the proper flow control technique for each non-SEL device. If you select RTS/CTS hardware data flow control, make sure that the cable you are using to connect the device to the SEL-321 Relay has conductors for RTS/CTS.

Baud Rate

The factory default baud rate for the SEL-321 Relay ports is 2400 baud. You can change the baud rate, and other port communication parameters, using the SET P command (see ***Section 3: Communications***). Available baud rates are 300, 1200, 2400, 4800, 9600 and 19200.

To change the communication baud rate, you should change the baud rate on the SEL-321 Relay first, then change the baud rate setting on the communicating device.

Passwords

Factory-set passwords are:

Level 1 = OTTER (all caps)

Level B = EDITH (all caps)

Level 2 = TAIL (all caps)

You can set your own passwords with the PASSWORD command (see *Section 3: Communications*), or you can disable the password protection with jumper selection (see *Main Board Jumpers* below).

JUMPER SETTINGS

This subsection describes the hardware jumper selections available on the SEL-321 Relay, and the recommended procedures for making the jumper setting changes.

Main Board Jumpers

Set the main board jumpers to meet your requirements. See Table 6.1 for jumper functions and positions. See *Appendix B* for jumper locations on the main board.

Table 6.1: Main Board Jumper Positions

Function	Install Jumpers At:
<u>Password Protection Disabled</u> Password Protection Enabled (default)	P7: J105 shorting block installed P7: J105 shorting block removed
OPEN/CLOSE Command Enable (default) OPEN/CLOSE Command Disable	P7: J106 shorting block installed P7: J106 shorting block removed
Note: Unused (spare) jumpers may be placed on P7 locations labeled “GND.” P7: J101 through P7: J204 do not provide any function.	

Input/Output Connections

Your SEL-321 Relay is equipped with one or two input/output (I/O) boards.

Configure the Output Contact Form

The SEL-321 Relay I/O boards are shipped from the factory with form A output contacts (except for the alarm contact). You may reconfigure the contacts by desoldering and then resoldering the 20 AWG jumper wire for each contact. See *Appendix H* for information on jumper locations and positions required to configure the contacts.

Open the SEL-321 Relay to Access Internal Jumpers

If you have decided that the SEL-321 Relay default configuration does not meet your needs, perform the following steps to gain access to internal jumpers:

1. De-energize the SEL-321 Relay.



Never work on the relay with the front or top cover removed, when the relay is energized.

2. Remove the screws attaching the front panel and top cover and remove the front panel and top cover. (Note: The top cover does not need to be removed to access the main board jumpers.) Be careful of the cables attaching the front-panel board to the main board.

**CAUTION**

The relay contains devices sensitive to Electrostatic Discharge (ESD). When working on the relay with front or top cover removed, work surfaces and personnel must be properly grounded or equipment damage may result.

3. If an I/O board requires changes, disconnect as many cables as necessary so that the I/O board can be removed. Release the I/O board by pulling out the white release clamps at the corners and then slide the board forward and out.

Set Jumpers

See *Appendix B* for main board jumper locations. Configure the following main board jumpers according to the selections you have made:

- OPEN/CLOSE Command Enable/Disable jumper.
- Password Enable/Disable jumper.

See *Appendix H* for I/O board jumper locations and positions. While the I/O board is removed, configure the following jumpers according to the selections you have made:

- Select output contact form: A or B (Note: most boards have a jumper for each output).

Reassemble the SEL-321 Relay

After configuring jumpers, reassemble the SEL-321 Relay as follows:

1. If you removed an I/O board, replace it.
2. Reconnect any cables that were disconnected between the I/O board and the other board(s).
3. Replace the top cover and top-cover screws and tighten them securely.
4. Replace the front panel and front-panel screws and tighten them securely. Once again, be careful of the cables attaching the front-panel board to the main board. Ensure that they are fully engaged and that they do not get pinched during reassembly.
5. Re-energize the relay and ensure that it powers up as expected.

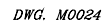
INSTALLATION

Before you install the SEL-321 Relay, you should perform the initial checkout procedure found earlier in this section, and set the configuration jumpers according to your installation requirements per the instructions outlined earlier in this section. Install the SEL-321 Relay according to the following step-by-step instructions:

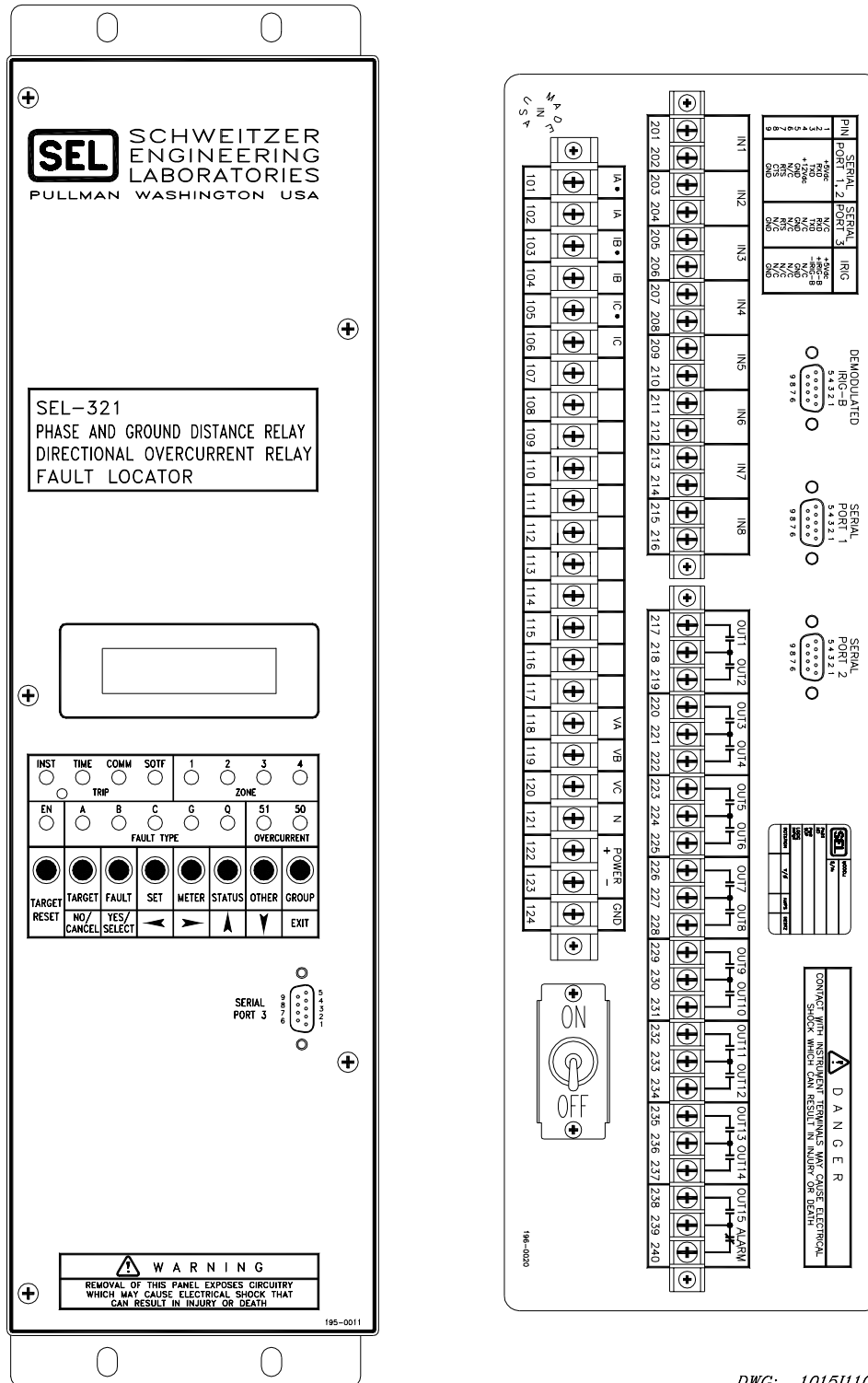
1. Mount the SEL-321 Relay in the desired panel location. Mounting information, including chassis, cutout and drilling dimensions are shown in Figure 6.13 through Figure 6.14.

2. Connect the devices you desire to the SEL-321 Relay rear-panel DB-9 communication ports using SEL cables, or their equivalents. Cable information is located earlier in this section.
3. Connect power and ground, alarm, IRIG-B, and other cabling on the rear panel.
4. Connect a terminal (or computer equipped with terminal emulation software) to the front-panel connector Port 3 of the SEL-321 Relay using an SEL-C234A cable or equivalent.
5. Set the computer terminal or emulation software to operate at:

2400 baud, 8 data bits, 1 stop bit, no parity
6. Press <ENTER> and verify that a “=” prompt is returned.
7. Type **ACCESS**<ENTER> to change to Access Level 1. If you enabled password protection, enter the factory-set password by typing **OTTER**<ENTER> at the password prompt. You should now have a “=>” (Level 1) prompt
8. Type **STATUS**<ENTER> and verify that a status report appears on your terminal. Confirm that IRIG-B, PORT, and I/O board connections/configurations match your expectations. Change the SEL-321 Relay settings as desired/required to suit the application (as outlined in other sections of this manual) and verify that their operation matches your expectations.
9. After you have installed the SEL-321 Relay, perform the checkout procedures in **Section 7: Maintenance and Testing**. You may follow the suggestions there, or combine them with your normal practice. Never implement recommendations prohibited by the rules of your normal practice.
10. When local checkout is complete, check communications with the SEL-321 Relay via the remote interface (if applicable). Make sure the automatic port is properly assigned and that the desired timeout intervals are selected for each port. Lastly, be sure to record password settings. This step completes installation of the SEL-321 Relay.



6-15



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Figure 6.6: SEL-321 Relay Vertical Front and Rear Panel Drawings
(One I/O Board Conventional Terminal Block Version; 16 outputs with shared return terminals shown – other options are available)

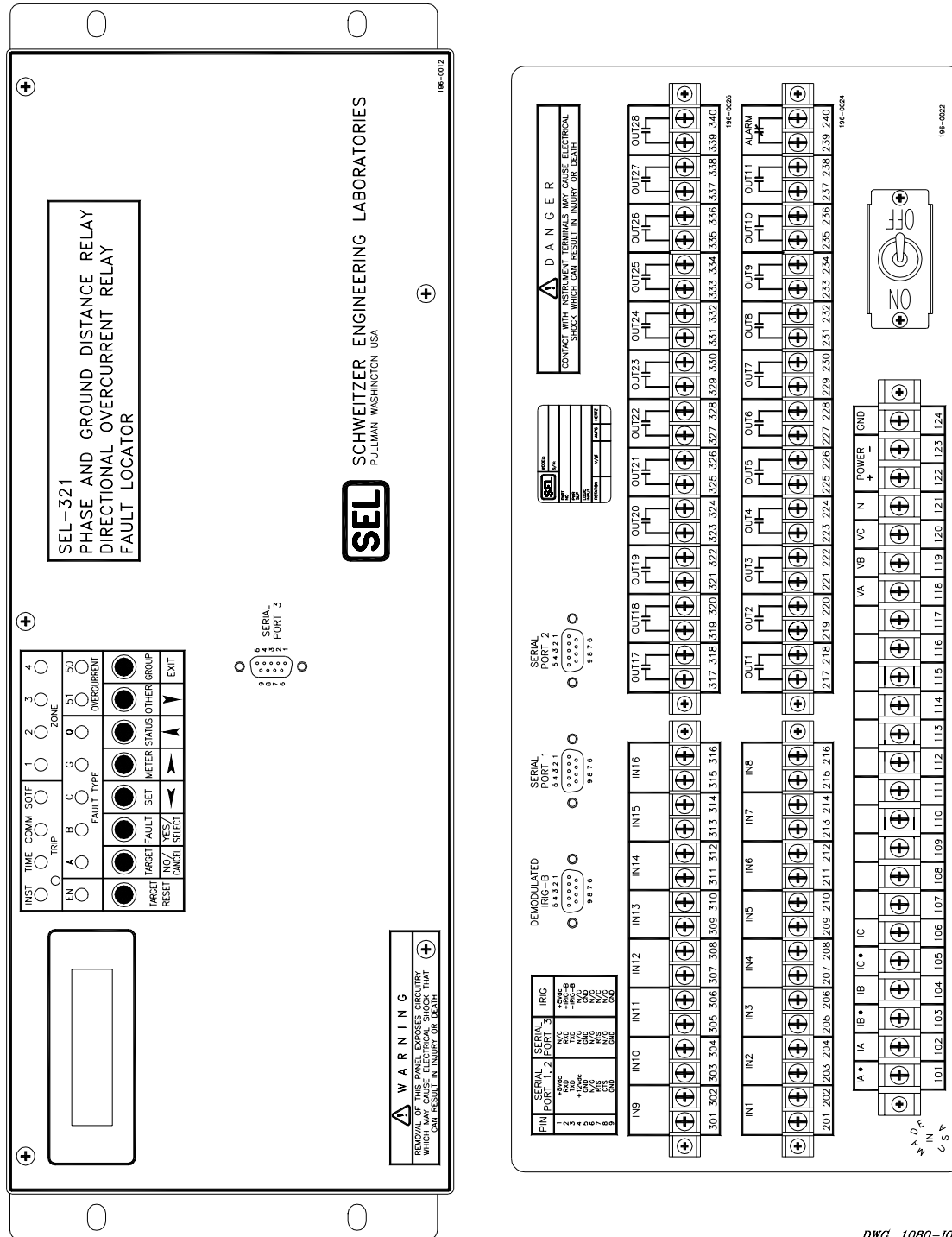


Figure 6.7: SEL-321 Relay Horizontal Front and Rear Panel Drawings
(Two I/O Board Conventional Terminal Block Version; 12 isolated outputs per board shown – other options are available)

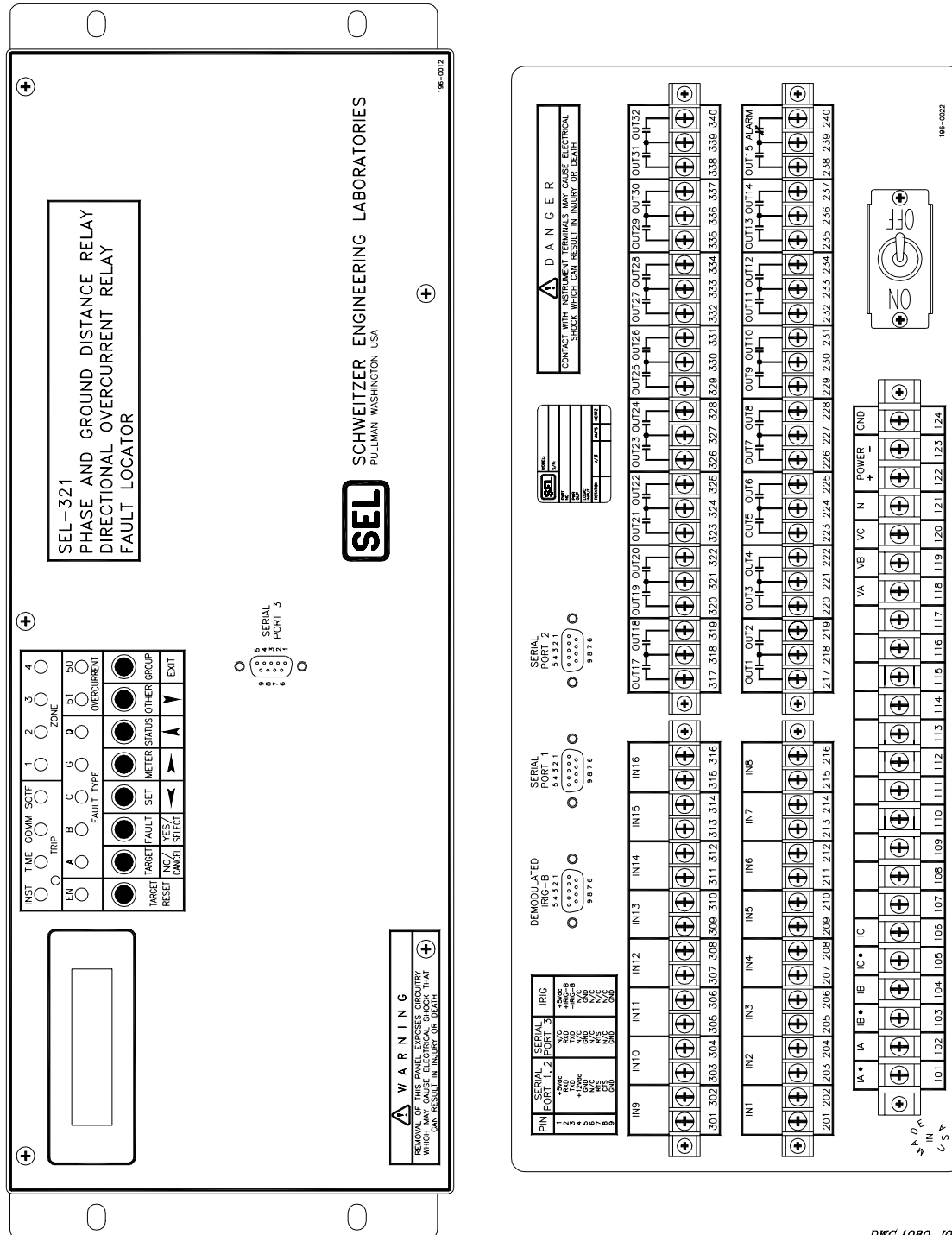
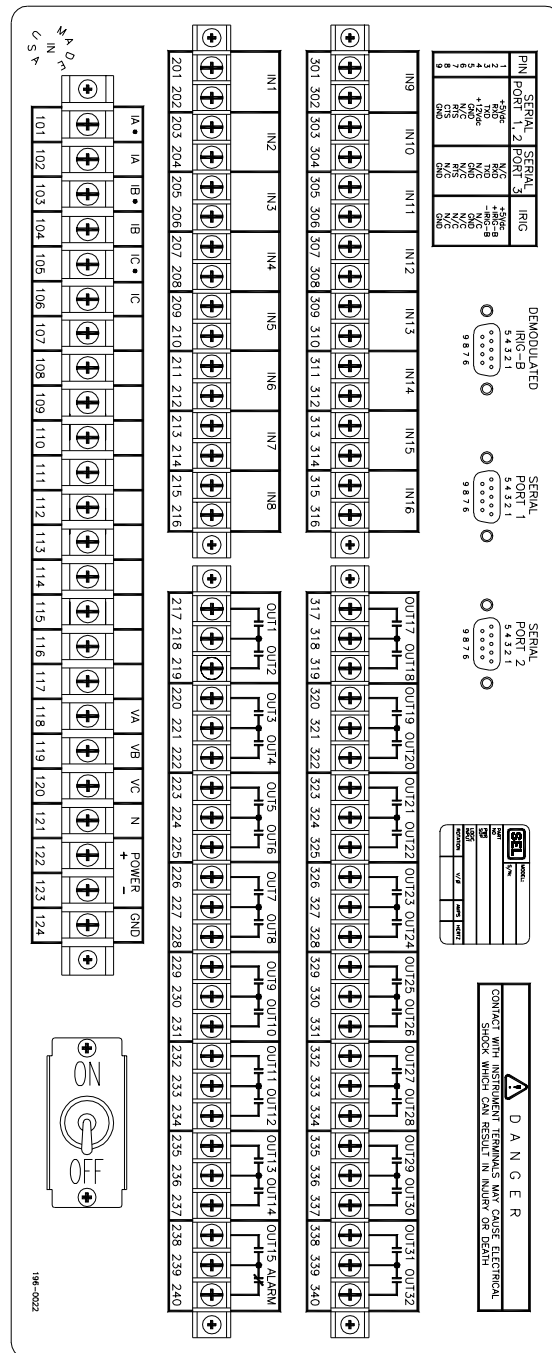
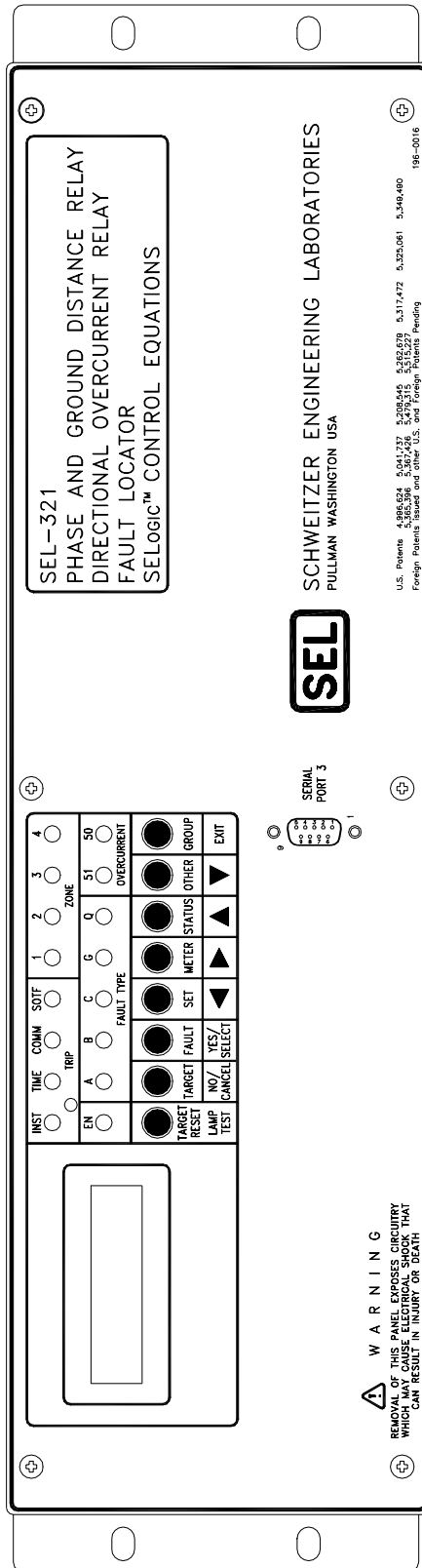


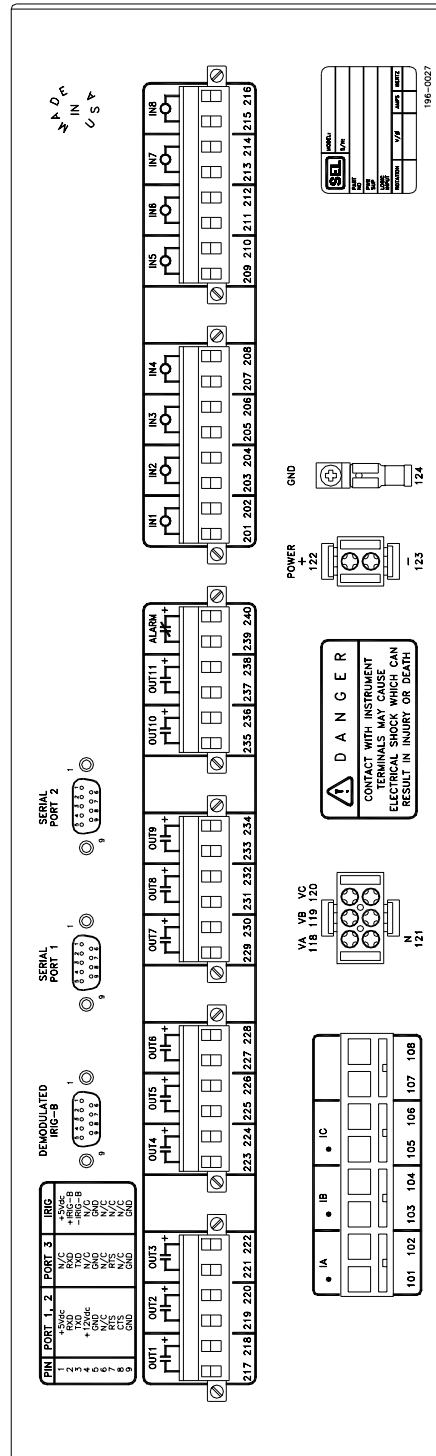
Figure 6.8: SEL-321 Relay Horizontal Front and Rear Panel Drawings (Two I/O Board Conventional Terminal Block Version; 16 outputs with shared return terminals per board shown – other options are available)



DWG. 1080-108



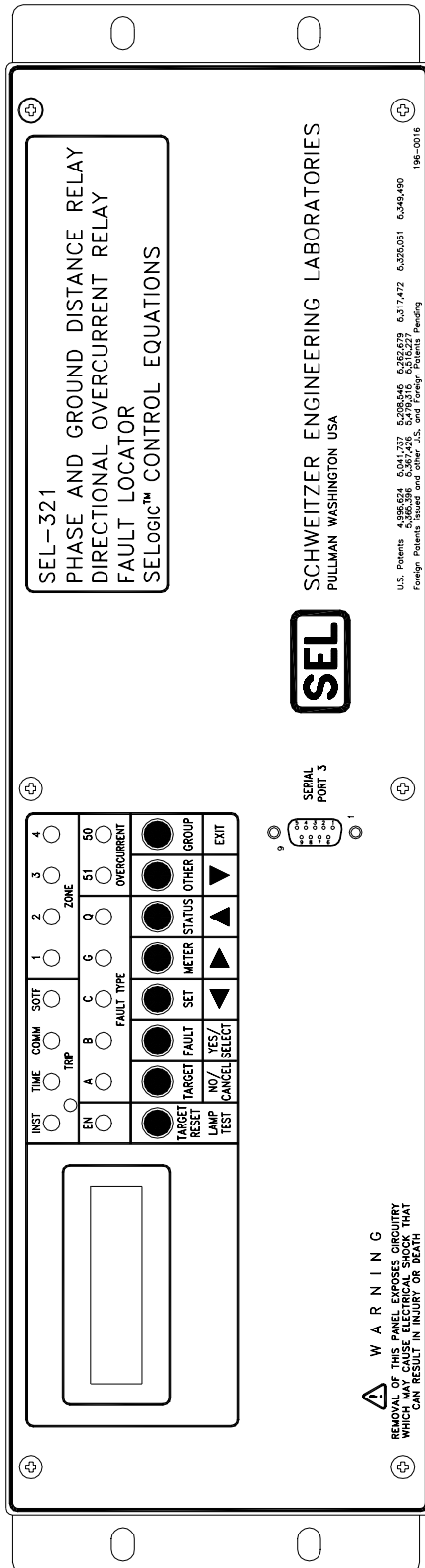
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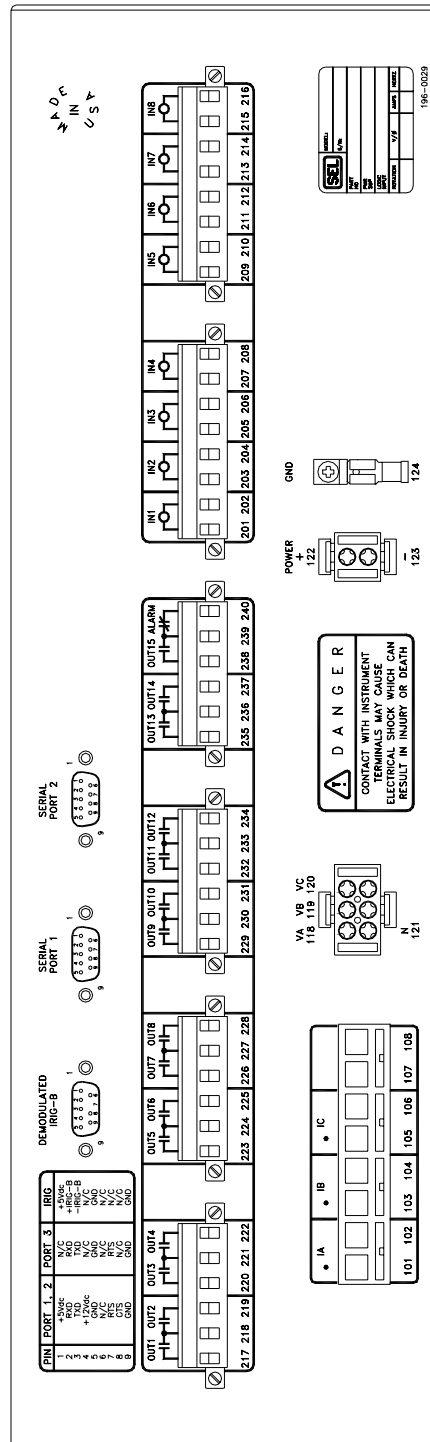
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Figure 6.10: SEL-321 Relay Horizontal Front and Rear Panel Drawings
(One I/O Board Plug-In Connector Version; 12 isolated high-current interrupting outputs shown – other options are available)

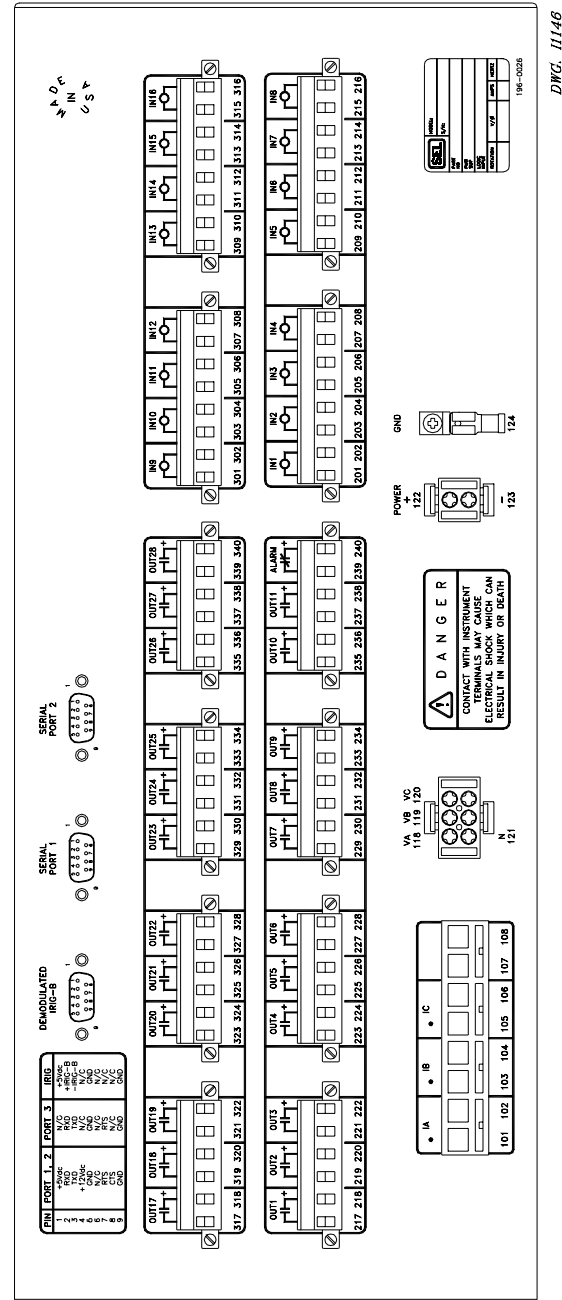
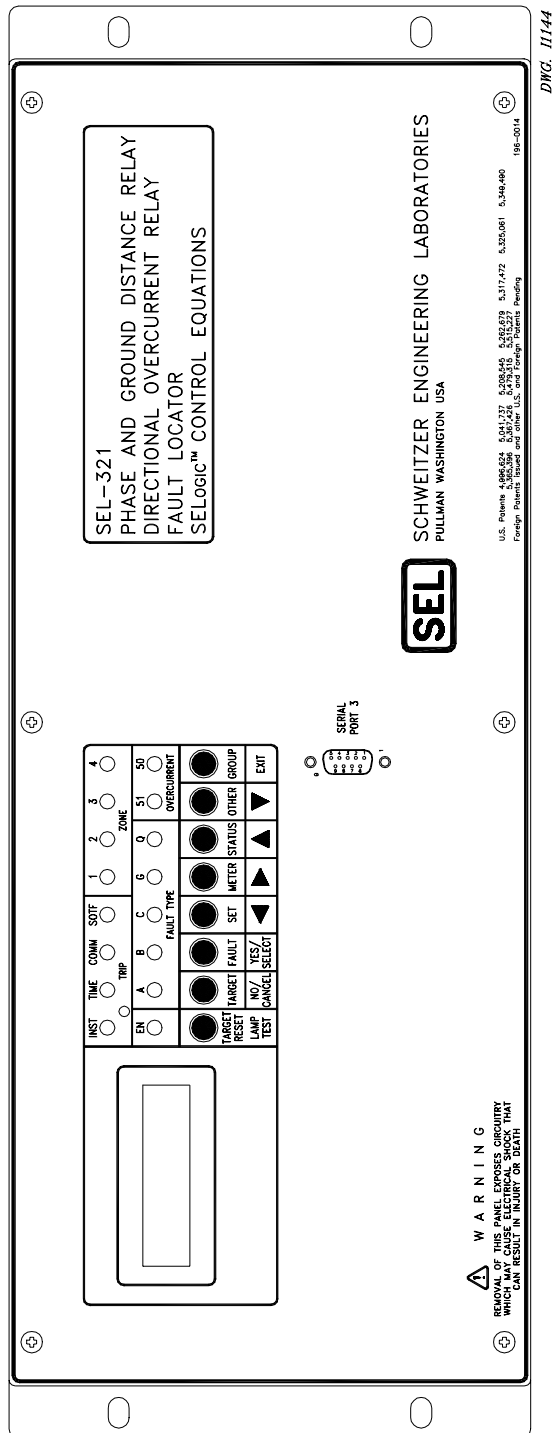


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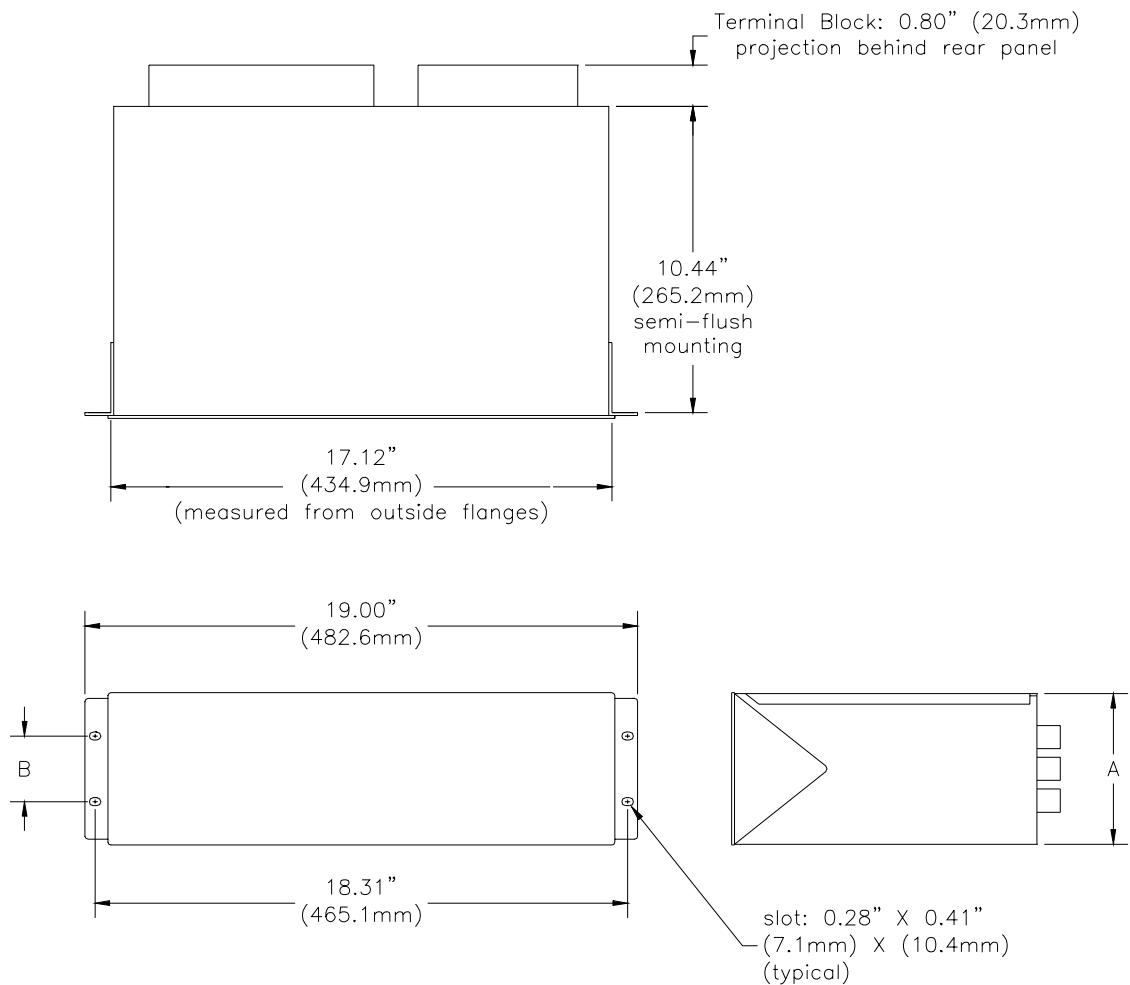


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**Figure 6.11: SEL-321 Relay Horizontal Front and Rear Panel Drawings
(One I/O Board Plug-In Connector Version; 16 outputs with shared return terminals shown – other options are available)**



**Figure 6.12: SEL-321 Relay Horizontal Front and Rear Panel Drawings
(Two I/O Board Plug-In Connector Version; 12 isolated high-current interrupting outputs per board shown – other options are available)**



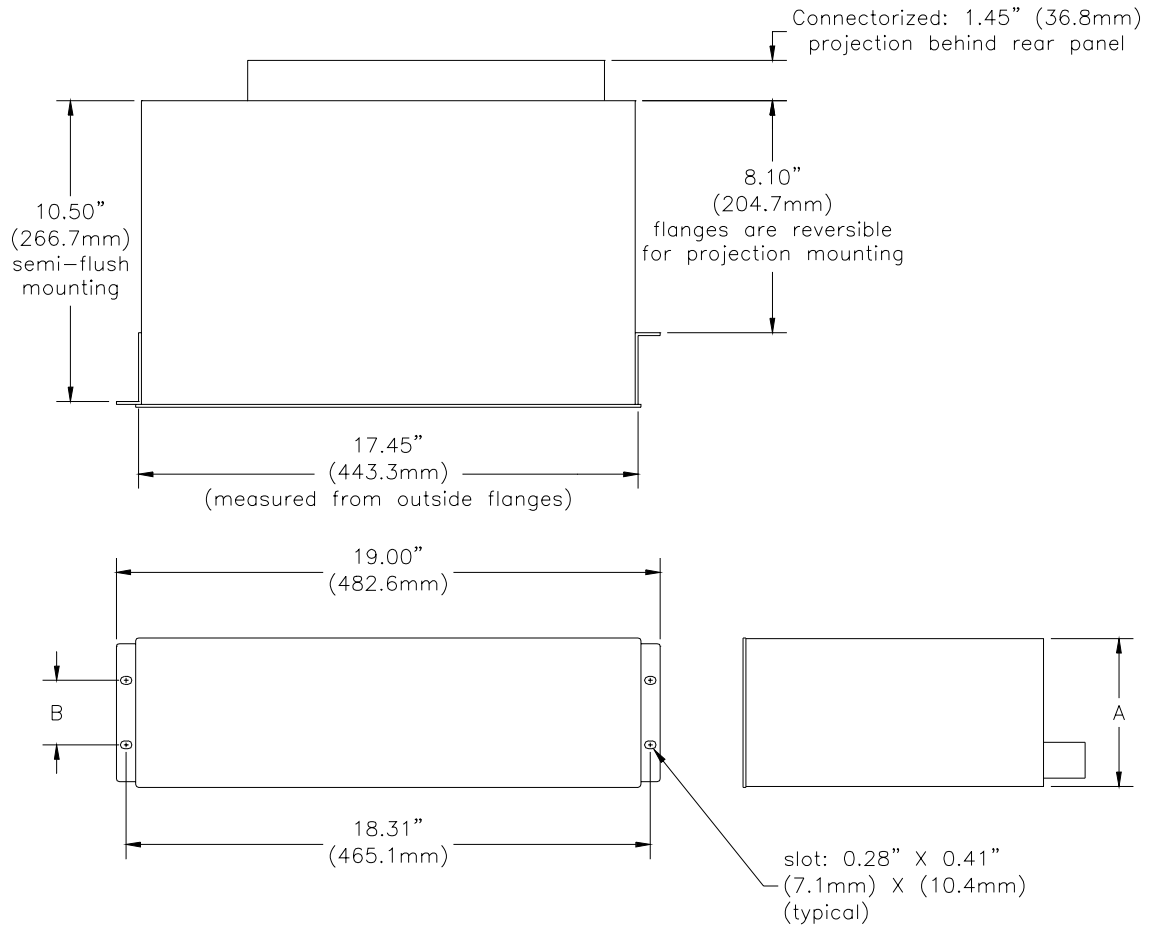
DIMENSION	ONE I/O BOARD (3U)	TWO I/O BOARDS (4U)
A	5.22" (132.6mm)	6.97" (177.0mm)
B	2.25" (57.2mm)	4.00" (101.6mm)

NOTE:

1. ALL TOLERANCES ARE $\pm 0.020"$ (0.51mm)
2. TO DETERMINE THE CUTOUT DIMENSIONS
CONSIDER BOTH SEL'S SPECIFIED TOLERANCE
AND THE CUSTOMER'S ALLOWED TOLERANCE.
3. DRAWING NOT TO SCALE

DWG. 11368
DATE: 12 AUG 98

Figure 6.13: Relay Dimensions and Drill Plan (One and Two I/O Board Versions – Conventional Terminal Blocks)



DIMENSION	ONE I/O BOARD (3U)	TWO I/O BOARDS (4U)
A	5.22" (132.6mm)	6.97" (177.0mm)
B	2.25" (57.2mm)	4.00" (101.6mm)

NOTE:

1. ALL TOLERANCES ARE $\pm 0.020"$ (0.51mm)
2. TO DETERMINE THE CUTOUT DIMENSIONS CONSIDER BOTH SEL'S SPECIFIED TOLERANCES AND THE CUSTOMER'S ALLOWED TOLERANCE.
3. DRAWING NOT TO SCALE

DWG. 11369
DATE: 12 AUG 98

Figure 6.14: Relay Dimensions and Drill Plan (One and Two I/O Board Versions – Plug-In Connectors Option)

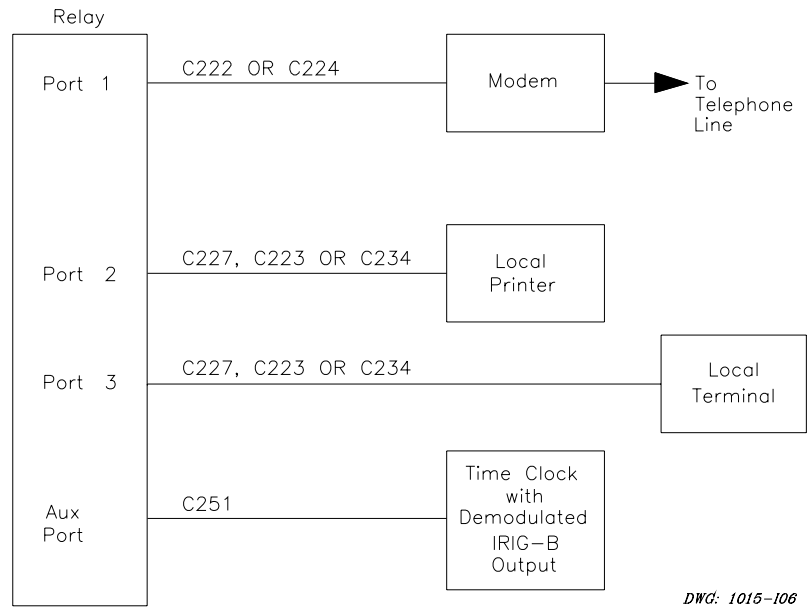


Figure 6.15: Communications and Clock Connections – One Unit at One Location

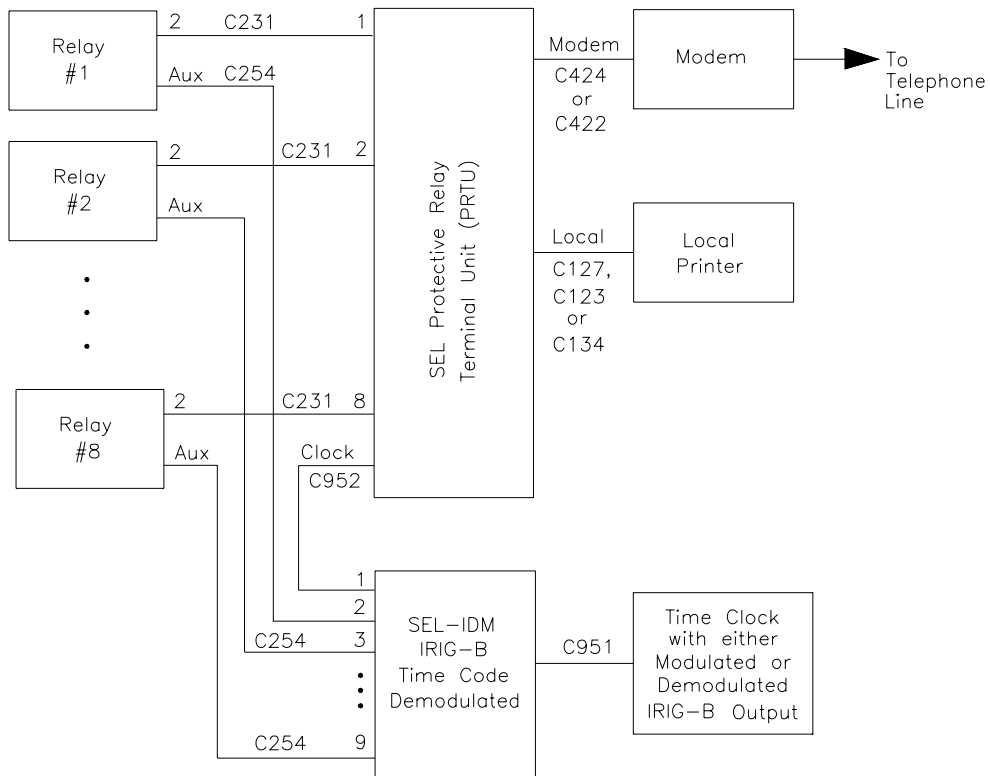


Figure 6.16: Communications and Clock Connections – Multiple Units at One Location

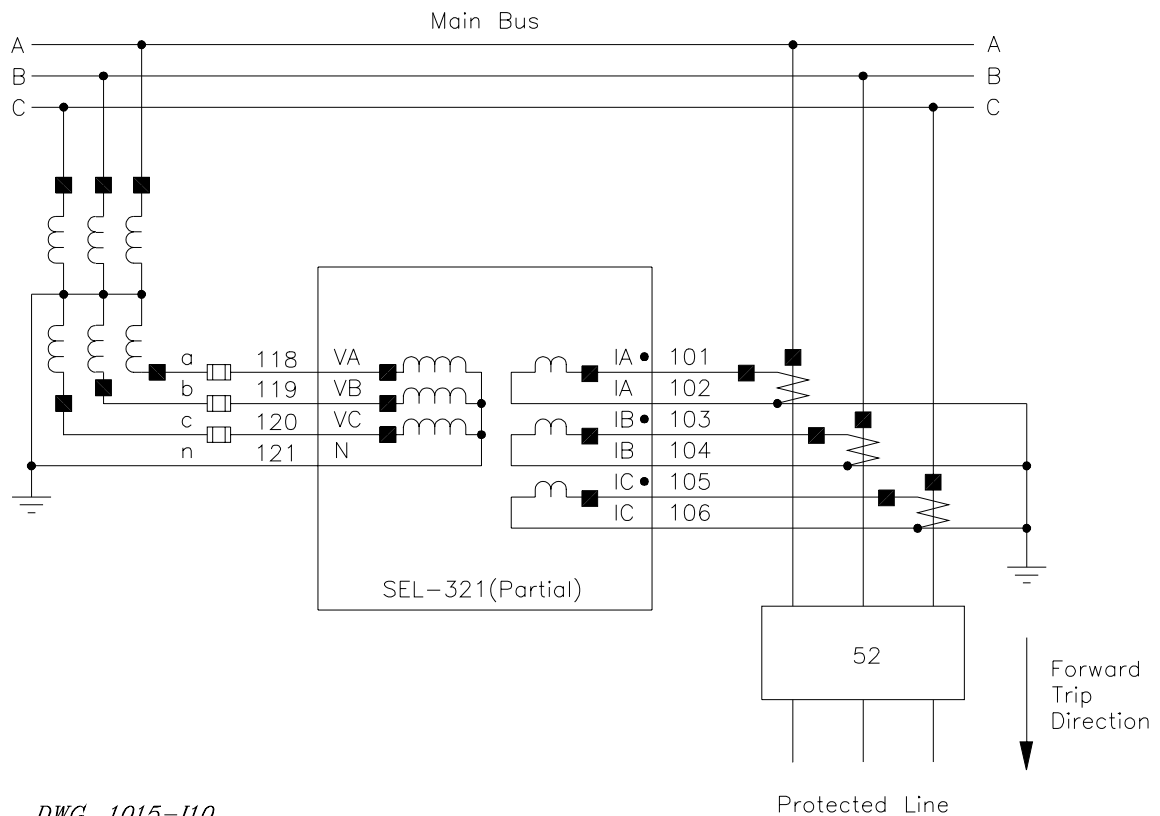


Figure 6.17: SEL-321 Relay External AC Current and Voltage Connections

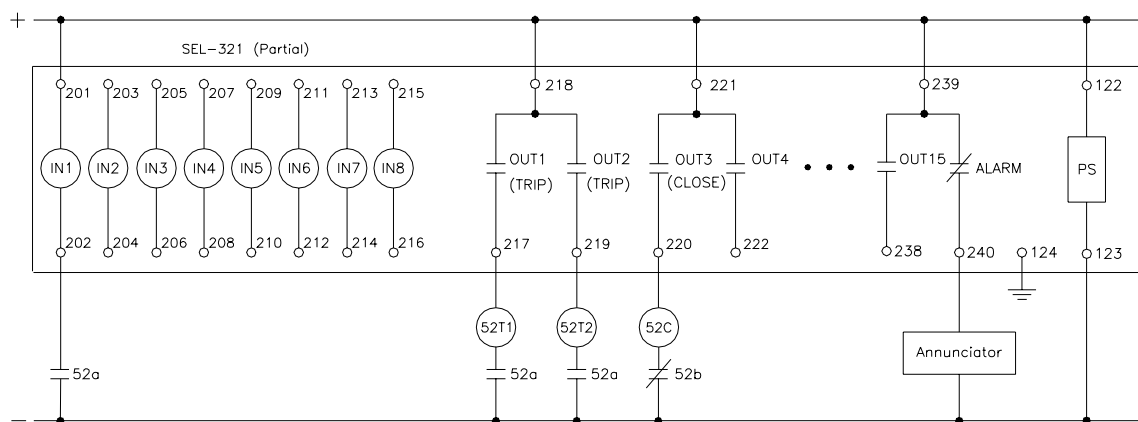
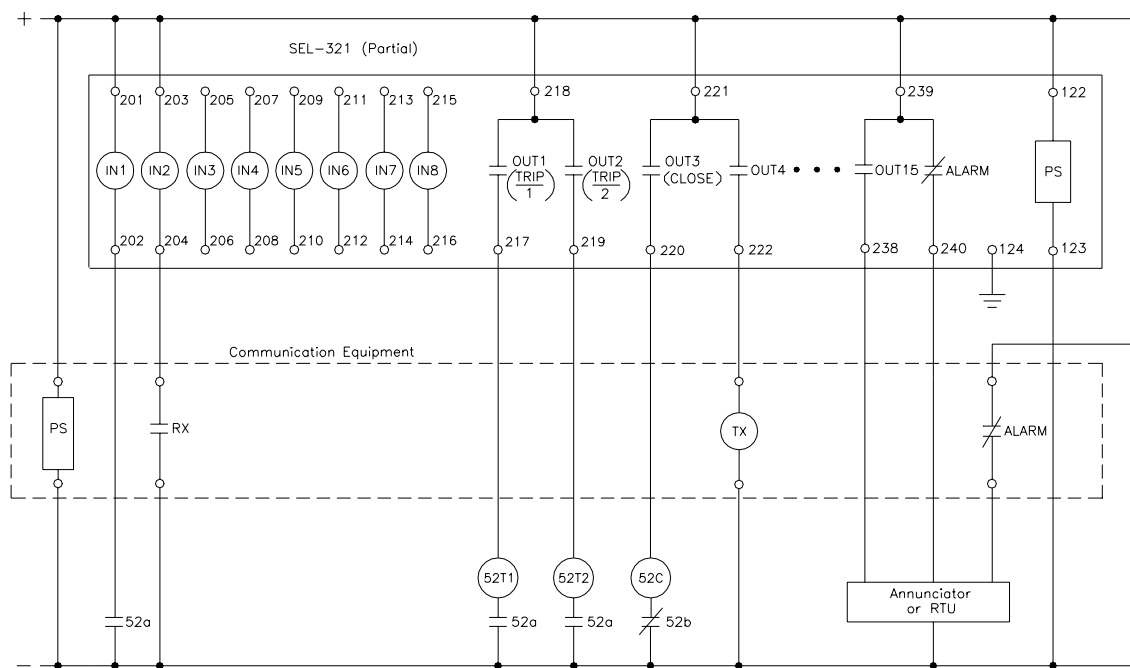


Figure 6.18: SEL-321 Relay Typical External DC Connection Diagram
(One I/O Board Version; 16 outputs with shared return terminals shown – other output options are available)



NOTE: All Inputs and Outputs are Assignable.

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Figure 6.19: SEL-321 Relay External DC Connections to Communications Equipment (One I/O Board Version; 16 outputs with shared return terminals shown – other options are available)

SEL DIRECTION AND POLARITY CHECK FORM

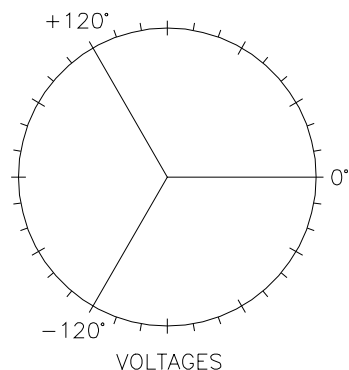
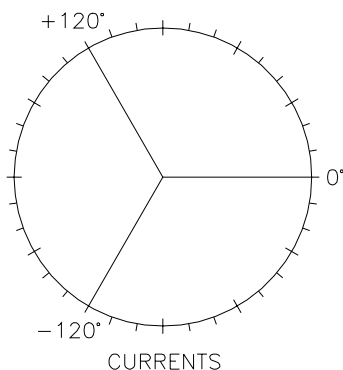
STATION _____ DATE: ____/____/____ TESTED BY _____
 SWITCH NO. _____ EQUIPMENT _____
 INSTALLATION _____ ROUTINE _____ OTHER _____

LOAD CONDITIONS:

STATION READINGS: _____ MW (OUT)(IN) _____ MVAR (OUT)(IN) _____ VOLTS _____ AMPS
 SEL READINGS: _____ MW (+)(-) _____ MVAR (+)(-)

AS SEEN ON SCREEN	I _a	I _b	I _c	V _a	V _b	V _c	
COMPANY NOTATION	I()	I()	I()	V()	V()	V()	
1st LINE CHOSEN (Y COMPONENT)							
2nd LINE CHOSEN (X COMPONENT)							
CALCULATED MAGNITUDE $\sqrt{X^2 + Y^2}$							ROW 1
ANGLE IN DEGREES ARCTAN Y/X							
VALUE OF V _a DEGREES TO SUBTRACT TO OBTAIN V _a DEGREES = 0							
@ V _a DEGREES = 0, ANGLE USED TO DRAW PHASOR DIAGRAM							ROW 2

USE THE VALUES IN ROWS 1 AND 2 ABOVE TO DRAW PHASOR DIAGRAMS BELOW



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SEL DIRECTION AND POLARITY CHECK FORM

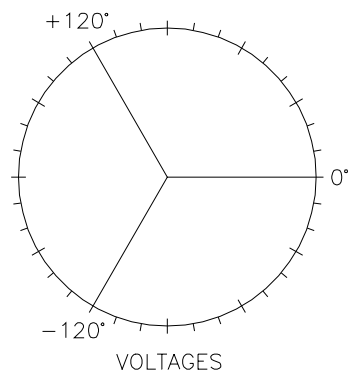
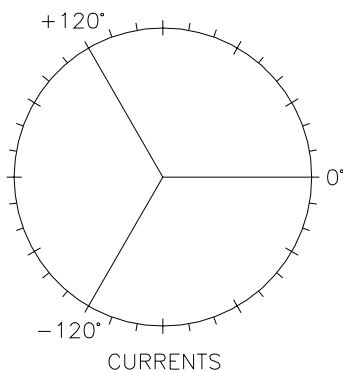
STATION _____ DATE: ____/____/____ TESTED BY _____
 SWITCH NO. _____ EQUIPMENT _____
 INSTALLATION _____ ROUTINE _____ OTHER _____

LOAD CONDITIONS:

STATION READINGS: _____ MW (OUT)(IN) _____ MVAR (OUT)(IN) _____ VOLTS _____ AMPS
 SEL READINGS: _____ MW (+)(-) _____ MVAR (+)(-)

AS SEEN ON SCREEN	I _a	I _b	I _c	V _a	V _b	V _c	
COMPANY NOTATION	I()	I()	I()	V()	V()	V()	
1st LINE CHOSEN (Y COMPONENT)							
2nd LINE CHOSEN (X COMPONENT)							
CALCULATED MAGNITUDE $\sqrt{X^2 + Y^2}$							ROW 1
ANGLE IN DEGREES ARCTAN Y/X							
VALUE OF V _a DEGREES TO SUBTRACT TO OBTAIN V _a DEGREES = 0							
@ V _a DEGREES = 0, ANGLE USED TO DRAW PHASOR DIAGRAM							ROW 2

USE THE VALUES IN ROWS 1 AND 2 ABOVE TO DRAW PHASOR DIAGRAMS BELOW



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SECTION 7: MAINTENANCE AND TESTING

INTRODUCTION

This section contains the following items:

- Initial Checkout Procedure
- SEL Relay Testing Philosophy
- Test Methods and Tools
- Test Procedures for overcurrent, directional, and distance elements
- Relay Test and Operation Troubleshooting Guides
- Firmware Upgrade Installation Procedures

INITIAL CHECKOUT

The initial checkout procedure should familiarize you with the relay. Study Functional Specifications and Descriptions in *Section 2: Specifications*, Command Descriptions in *Section 3: Communications*, *Section 4: Event Reporting*, and *Section 5: Applications* for a complete understanding of the relay capabilities.

Equipment Required

The following equipment is necessary for initial checkout.

1. Source of control power.
2. Source of three-phase voltages and at least two currents.
3. Ohmmeter or contact opening/closing sensing device.

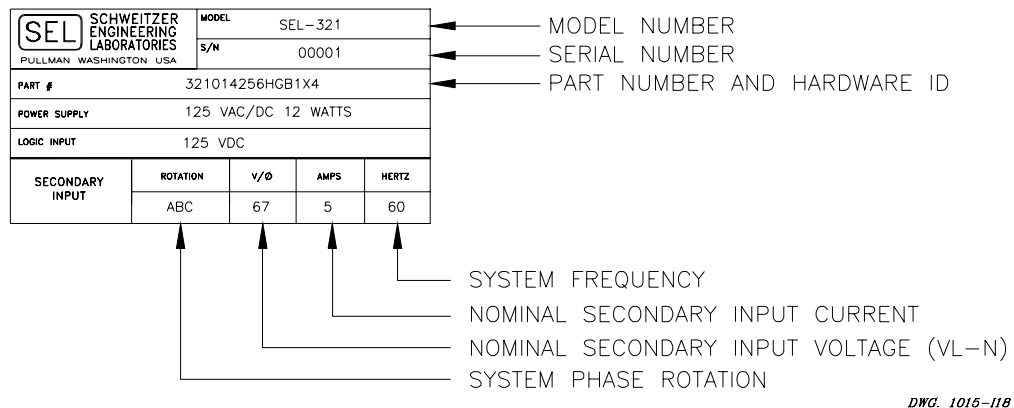
Checkout Procedure

Step 1. Purpose: Be sure you received the relay in satisfactory condition.

Method: Inspect the instrument for physical damage such as dents or rattles.

Step 2. Purpose: Refer to the Relay Part Number and Hardware Identification Sticker on the relay rear panel to verify the power supply voltage, dc control voltage, and nominal ac signal magnitudes appropriate for the relay under test.

Method: Refer to the information sticker on the rear panel of the relay. Figure 7.1 provides an example. Information on this sticker is important to note before applying power to the relay or starting tests.



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Figure 7.1: Relay Part Number and Hardware Identification Sticker

The relay described by the sticker shown in Figure 7.1 is an SEL-321 Relay, serial number 00001. The part number describes the relay configuration in a concise manner. Some critical aspects of this part number are called out under the Power Supply, Logic Input, and Secondary Input sections of the sticker.

The Power Supply specification shown in Figure 7.1 indicates that this relay is equipped with a power supply that accepts 125 volts ac or dc. Other power supply options include 24 volts dc, 48 volts dc, and 250 volts ac/dc. Refer to the sticker attached to your relay to determine the magnitude of voltage you should apply to the relay power supply input terminals. The voltage source should be capable of providing 12 watts continuously at the rated voltage.

The Logic Input specification indicates that the relay logic inputs are rated to accept 125 volts dc. Other options include 24 volts dc, 48 volts dc, and 250 volts dc. To assert a relay logic input, apply dc voltage to the relay input terminals. Refer to the sticker attached to your relay to determine the magnitude of voltage you should apply to the relay logic inputs. Approximately four milliamps of current flow when rated voltage is applied to a relay logic input.

The Rotation specification indicates the expected power system phase rotation. Figure 7.1 indicates that this relay is configured to accept ABC rotation. This is also referred to as 123 or positive phase rotation by some utilities. Under nominal conditions on a system with ABC rotation, B-phase voltage lags A-phase voltage by 120°, and C-phase voltage lags B-phase voltage by 120°.

The V/phase specification indicates the nominal ac voltage that the relay is designed to measure. This voltage is specified from line to neutral and assumes a standard 4-wire wye ac voltage connection. Figure 7.1 indicates that this relay is configured to accept 67 volts ac, line to neutral. The relay measures other ac voltage magnitudes accurately, as defined in **Section 2: Specifications**.

The Amps specification indicates the nominal ac current that the relay is designed to measure. Figure 7.1 indicates that this relay is configured to accept 5 amps ac, per phase. The relay measures other ac current magnitudes accurately, as defined in **Section 2: Specifications**.

The Hertz specification indicates the relay is designed to measure ac voltage and current signals at the nominal system frequency. The relay is designed to make accurate voltage and current measurements during frequency excursions, as defined in *Section 2: Specifications*.

Step 3. Purpose: Connect power supply voltage to the relay.

Method: If the relay is equipped with a rear panel power switch, move the switch to the 'OFF' position. Connect a frame ground to terminal marked GND on the rear panel and connect a voltage source to the terminals marked + and -. Polarity is unimportant. Relays equipped with 125 or 250 V power supplies may be powered from a 115 Vac wall receptacle for testing. In the final installation, we recommend that the relay receive control power from the station dc battery. This helps prevent loss of relay event reports stored in volatile memory if station ac service is lost.

Step 4. Purpose: Apply power supply voltage to the relay and access the relay via the LCD front panel.

Method: Turn on the voltage source connected to the relay power supply inputs. If the relay is equipped with a power switch, move the relay power switch to the 'ON' position. If you are using a battery simulator as the relay power supply voltage source, be sure the simulator voltage level is stabilized before turning the relay on.

The relay front panel Enable target (EN) should illuminate. **EN** should appear in the relay LCD screen.

The relay output labeled ALARM is typically configured as a normally closed (form "b") contact and closes to indicate loss of dc power to the relay, failure of a relay self-test, and several other functions. With power applied to the relay and the relay turned on, the ALARM contacts open.

If the Enable LED does not illuminate or **EN** does not appear on the relay LCD screen, turn off the power and refer to Relay Troubleshooting later in this section.

Step 5. Purpose: Perform a front panel LED test and check LCD screen contrast.

Method: Press the **TARGET RESET** button to perform an LED lamp test. During the lamp test, the relay illuminates all 16 front panel LEDs for about one second. The relay also turns on the LCD back lighting. If the LCD contrast is poor, refer to the Relay Troubleshooting Table in this section for steps to adjust it.

Step 6. Purpose: Verify the relay self-test status.

Method: Press the front panel **STATUS** button. The message **STATUS: OK** should appear on the relay LCD screen. Use the Up and Down arrow buttons to view the results of specific relay self-tests. Press the front panel **CANCEL** or **EXIT** button to exit the STATUS display.

Step 7. Purpose: Connect voltage and current sources to the relay.

Method: Turn relay power off. If three voltage sources and three current sources are available, connect the sources to the relay as shown in Figure 7.3. If three voltage sources and two current sources are available, connect them as shown in Figure 7.5. Apply 67 volts per phase (line-to-neutral) in positive-sequence rotation. Apply 2.0 amps per phase, in phase with the applied phase voltages.

Step 8. Purpose: Verify correct voltage and current connections and levels.

Method: Turn relay power on. Press the front panel **METER** button. Use the arrow keys to examine the METER data. The relay displays the measurements of the voltages and currents applied in Step 7. With applied voltages of 67 volts per phase and a potential transformer ratio of 2000:1, the displayed line-to-neutral voltages should be 134 kV. With applied currents of 2.0 A per phase and a current transformer ratio of 200:1, the displayed line-to-neutral currents should be 400 A. All line-to-line quantities should be balanced, differing from the line-to-neutral measurements by a factor of 1.73. Real power P should be approximately 160.1 MW; reactive power Q should be approximately 0 MVAR.

If you inadvertently switched a pair of voltages or currents, the MW reading should be approximately zero. It is important to remember this when commissioning the relay using system voltages and currents.

If you wish to verify the relay voltage and current connections in a more detailed manner, use the SEL Direction and Polarity Check Form provided in **Section 6: Installation**.

Step 9. Purpose: Use the front panel setting feature to adjust a relay setting.

Method: The following steps are required to change a relay setting from the SEL-321 Relay front panel:

1. Enter Access Level 2 using the appropriate password.
2. Execute the **SET** command.
3. Select the setting to change.
4. Make and accept the setting change.

With **EN** displayed on the relay LCD screen, press the front panel button labeled **OTHER**. With **2AC** shown on the screen, press **SELECT**. This instructs the relay to execute the 2ACCESS command.

In order to enter Access Level 2, you must enter the correct password. The relay is equipped with a Level 2 password of TAIL. The relay displays a list of characters to build the password from. Use the Up or Down arrow button to choose the list of characters containing T. Use the Left and Right arrow buttons to underline the T. Press **SELECT** to enter T as the first letter of the Level 2 password.

Next, use the Up or Down arrow button to choose the list of characters containing A, I, and L. Underline each character in turn and press the **SELECT** button to enter each character into the Level 2 password.

When the upper line of the display reads:

PASSWORD: TAIL

press the EXIT button to enter Access Level 2. The relay briefly displays the note **Level 2**, then resumes the **EN** display.

Press the button labeled **SET**. The display shows:

SET GROUP

Press **SELECT**. Use the Down arrow button to enter the number 1, then press **SELECT** again.

Note: The SEL-321 Relay includes six setting groups. While you are testing this relay, it is important to change settings in the group that is active. If you change settings in an inactive setting group, the relay performance will not change. The relay is shipped with Setting Group 1 active. You may change the active group by executing the GROUP command from the relay front panel or from a terminal connected to a relay serial port. You must enter the Breaker Access Level or Access Level 2 to change the active group.

Press the Down arrow button repeatedly, until the upper line of the display reads:

Misc Scheme Logic

Press **SELECT**. Press the Down arrow button repeatedly until the lower line of the display reads:

TULO = 3

Press **SELECT**. Press the Up arrow button until the lower line of the display reads:

TULO = 1 *

Press **SELECT**. Press **EXIT**. Press **YES** to save the new settings.

Step 10. Purpose: Test the fault locator.

Method: Test the fault locator using the voltages and currents in

. These voltages and currents were obtained for various locations and fault types assuming a radial line with a source impedance of 0.2 times the total 100 mile line impedance.

Note: To simplify this step, apply dc voltage to the IN1 input. The relay recognizes the asserted input when applied dc voltage is approximately equal to the Logic Input voltage rating shown on the relay identification sticker.

Input IN1 is programmed to monitor the breaker auxiliary contact, 52A. Energize the IN1 input for the duration of this step to block the Switch-Onto-Fault logic from operating. If dc voltage source is not available, set ESOTF = N in the relay settings.

Run ground fault tests using the test source connections shown in Figure 7.3, Figure 7.4, or Figure 7.6. Run phase-to-phase fault tests using the test source connections shown in Figure 7.2, Figure 7.4, or Figure 7.7.

Table 7.1: Fault Locator Test Values

Location	Type	VA	VB	VC	IA	IB	IC	Units
75 miles	AG	52.89 0.00	69.97 -124.30	70.34 124.10	5.24 -82.40	0.00 0.00	0.00 0.00	V or A Degrees
	BC	67.00 0.00	56.75 -126.20	56.75 126.20	0.00 0.00	7.83 -174.00	7.83 6.00	V or A Degrees
85 miles	AG	54.24 0.00	69.67 -123.90	70.00 123.70	4.74 -82.40	0.00 0.00	0.00 0.00	V or A Degrees
	BC	67.00 0.00	57.69 -125.50	57.69 125.50	0.00 0.00	7.08 -174.00	7.08 6.00	V or A Degrees

Faults at 75 miles are within Zone 1, since the Zone 1 reach setting is 80% of the 100-mile line positive-sequence impedance (see Z1P, Z1MG, and XG1 in the settings). Faults at 85 miles are beyond Zone 1, but within Zone 2.

Faults listed in

cause certain combinations of output contacts to close and front panel LEDs to illuminate. You may use the front panel LCD functions to examine the short form fault data following each test. Table 7.2 shows the expected results.

Table 7.2: Output Contact and Target LED Results

Location	Type	Output Relays	Target LEDs
75 miles	AG	OUT1, OUT2, OUT4	INST, Zone 1, A, G
75 miles	BC	OUT1, OUT2, OUT4	INST, Zone 1, B, C
85 miles	AG	OUT1, OUT2, OUT4	TIME, Zone 2, A, G
85 miles	BC	OUT1, OUT2, OUT4	TIME, Zone 2, B, C

Output Contact Explanation

The OUT1 and OUT2 are set to close for three-pole trips. The relay is set to trip instantaneously for Zone 1 faults, with a short time delay for Zone 2 faults, and by operation of the residual and negative-sequence time-overcurrent elements. OUT4 is set to close for assertion of the KEY element. The KEY element is used in Permissive Overreaching Transfer Tripping protection schemes to send the permissive signal to the remote end. The SEL-321 Relay asserts the KEY element when overreaching Zone 2 elements pick up, if other conditions permit.

Target LED Explanation

The INST target illuminates when the relay trips for a protection element that has been asserted for a time less than the relay ITTD setting.

The TIME target illuminates when the relay trips for a protection element that has been asserted for a time greater than the relay ITTD setting.

The Zone targets indicate the zone of the element that caused the trip. The A, B, C, and G targets indicate the phase involvement. The Q target indicates that a negative-sequence overcurrent element was asserted at the time of trip.

The 50 and 51 targets indicate trips based upon overcurrent element operation. The 50 indicates instantaneous and definite-time delayed overcurrent element operations. The 51 indicates time-overcurrent element operations.

The COMM and SOTF targets indicate when the trip occurred as part of a Communications-based operation or a Switch-Onto-Fault operation, respectively.

Section 2: Specifications includes detailed information regarding operation of the relay targets.

Front Panel LCD Explanation

The relay generates an event report for each fault. To see the summary event report for the last fault, press the **FAULT** button on the relay front panel and use the Up, Down, Left, and Right arrow buttons to review the information presented there.

If a new fault occurs while you are reviewing the fault data, press the **EXIT** button, then the **FAULT** button to review the new data.

You may review the long form event report for each fault using a terminal connected to one of the relay serial ports. Each event report is an eleven-cycle record of the currents, voltages, relay element states, and logic input and contact output states. The relay saves the twelve newest reports. See *Section 3: Communications* and *Section 4: Event Reporting* for further details on the retrieval and analysis of event reports saved by this relay.

TESTING PHILOSOPHY

Protective relay testing may be divided into three categories: acceptance, commissioning, and maintenance testing. The categories are differentiated by when they take place in the life cycle of the relay, as well as in the test complexity.

The paragraphs below describe when each type of test is performed, the goals of testing at that time, and the relay functions that you need to test at each point. While this information is intended as a guideline for testing SEL relays, each utility must determine its own testing practices.

Acceptance Testing

- When: When qualifying a relay model to be used on the utility system.
- Goal:
- a) Ensure relay meets published critical performance specifications such as operating speed and element accuracy.
 - b) Ensure that the relay meets the requirements of the intended application.
 - c) Gain familiarity with relay settings and capabilities.
- What to test: All protection elements and logic functions critical to the intended application.

SEL performs detailed acceptance testing on all new relay models and versions. We are certain the relays we ship meet their published specifications. It is important for you to perform acceptance testing on a relay if you are unfamiliar with its operating theory, protection scheme logic, or settings. This helps ensure the accuracy and correctness of the relay settings when you issue them.

Commissioning Testing

- When: When installing a new protection system.
- Goal:
- a) Ensure that all system ac and dc connections are correct.
 - b) Ensure that the relay functions as intended using your settings.
 - c) Ensure that all auxiliary equipment operates as intended.
- What to test: All connected or monitored inputs and outputs; polarity and phase rotation of ac current and voltage connections; simple check of protection elements.

SEL performs a complete functional check and calibration of each relay before it is shipped. This helps ensure that you receive a relay that operates correctly and accurately. Commissioning tests should verify that the relay is properly connected to the power system and all auxiliary equipment. Verify permissive trip or blocking signal inputs and outputs. Check breaker auxiliary inputs, SCADA control inputs and monitoring outputs. Use an ac connection check to verify that the relay voltage and current inputs are of the proper magnitude and phase rotation.

Brief fault tests ensure that the relay settings are correct. A Zone 1 AB fault, Zone 2 CG fault, and Zone 3 three-phase fault can verify distance and directional elements, time delays, and the relay trip and output functions. It is not necessary to test every relay element, timer, and function in these tests.

Maintenance Testing

When:	At regularly scheduled intervals, or when there is an indication of a problem with the relay or system.
Goal:	<ul style="list-style-type: none">a) Ensure that the relay is measuring ac quantities accurately.b) Ensure that scheme logic and protection elements are functioning correctly.c) Ensure that auxiliary equipment is functioning correctly.
What to test:	Anything not shown to have operated during an actual fault within the past maintenance interval.

SEL relays use extensive self-testing capabilities and feature detailed metering and event reporting functions that lower the utility dependence on routine maintenance testing.

Use the SEL relay reporting functions as maintenance tools. Periodically verify that the relay is making correct and accurate current and voltage measurements by comparing the relay METER output to other meter readings on that line. Review relay event reports in detail after each fault. Using the event report voltage, current, and relay element data you can determine that the relay protection elements are operating properly. Using the event report input and output data you can determine that the relay is asserting outputs at the correct instants and that auxiliary equipment is operating properly. At the end of your maintenance interval, the only items that need testing are those that have not operated during the maintenance interval.

The basis of this testing philosophy is simple: If the relay is correctly set and connected, is measuring properly, and no self-test has failed, there is no reason to test it further.

Each time a fault occurs, the protection system is tested. Use event report data to point out areas requiring attention. Slow breaker auxiliary contact operations, increasing or varying breaker operating time, fluctuations in total communications channel delay can all be detected through detailed analysis of relay event reports.

Because SEL relays are microprocessor-based, their operating characteristics do not change over time. Time-current operating times and distance element characteristics are affected only by the relay settings and applied signals. It is not necessary to verify operating characteristics as part of maintenance checks.

At SEL, we recommend that maintenance tests on SEL relays be limited under the guidelines provided above. The time saved may be spent analyzing event data and thoroughly testing those systems that require more attention.

TESTING METHODS AND TOOLS

Test Aids Provided by the Relay

The following features assist you during relay testing.

METER Command	The METER command shows the voltages and currents presented to the relay in primary values. The relay calculates Megawatts (MW) and Megavars (MVAR) from these voltages and currents. These quantities are useful for comparing relay calibration against other meters of known accuracy.
Event Reporting	<p>The relay generates an 11-cycle event report in response to faults or disturbances. Each event report contains voltage and current information, relay element states, and input/output contact information in quarter-cycle or sixteenth-cycle resolution. If you question the relay response or your test method, use the event report for more information.</p> <p>Each event report is date and time tagged relative to the triggering instant. If the timeout of a protective element results in a TRIP, the relay records a second event report. Thus, the relay may generate two event reports for a long duration fault: the first when the instantaneous element asserted, the second when the TRIP occurs.</p> <p>Where Time Delayed Pickup (TDPU) timers are concerned, the time tag in the event reports may be used to determine the validity of a TDPU timer setting. Simply subtract the latest event report time tag from the previous event report time tag. <i>Section 2: Specifications</i> has further details concerning event report generation.</p>
Programmable Logic	Programmable logic allows you to test individual relay elements. See the SET L command description in <i>Section 3: Communications</i> for further details.
TARGET 44 Command	The TARGET 44 command shows the state of the eight relay logic inputs in a relay with one I/O board. This allows you to monitor the input states while asserting the inputs to verify correct wiring and correct operation of the inputs.

For more information on these commands, see *Section 3: Communications*.

Test Methods

There are two means of determining the pickup and dropout of relay elements: front panel LCD indication and output contact closure.

Testing Via Front Panel LCD/LED Indication

To use the relay LCD/LED front panel to display the state of elements, press the front panel **TARGET** button. Use the Up or Down arrow button to select the TAR number, or row, that

contains the element under test. Press **SELECT**. The relay displays the elements that are presently asserted in that row. The LCD display updates about twice per second.

The relay also illuminates front panel LEDs corresponding to asserted elements in the selected row. The front panel LEDs are updated every eighth of a cycle. They may flicker to indicate an element that is on a pickup threshold.

For example, TAR row 7 indicates the state of several overcurrent elements. Press the front panel **TARGET** button, use the Up arrow button to select TAR 7, then press **SELECT**. The relay LCD screen displays the names of the elements that are asserted. With no current applied, the LCD display is blank and the lower row of LEDs is dark. As you apply current to the relay, the various elements assert and their names appear in the LCD display screen. LEDs corresponding to asserted elements illuminate. You may wish to use this function to assist in element pickup tests.

Testing Via Output Contact Assertion

To test via output contact assertion, use the **SET L** command to set one programmable output contact to assert when the element under test picks up.

As an example, you could set the OUT7 output to follow the state of the M3P element. When the relay is set in this manner, you can monitor Output 7 on the relay rear panel to determine when the Zone 3 phase distance element asserts.

For a normally open (form “a”) contact, when the condition asserts, the output contact closes. When the condition deasserts, the output contact opens.

For a normally closed (form “b”) contact, when the condition asserts, the output contact opens. When the condition deasserts, the output contact closes.

Programmable output contacts can be specified at the factory as either form “a” or “b.”

Using contact operation as an indicator, you can measure element operating characteristics, stop timers, etc.

Tests in this section use the output contact method and assume that a normally open (form “a”) output contact is used to indicate the functions under test.

Using a Breaker Simulator

If the relay setting EN52A = Y, the relay Switch-Onto-Fault (SOTF) logic operates based on the state of the relay 52A input. When EN52A = Y, we recommend testing the relay with a latching relay to simulate line breaker auxiliary contact action. This ensures proper assertion and deassertion of the 52A input on the back panel. If you do not have a means of simulating breaker status, disable 52A-based SOTF protection by:

- Setting EN52A = N,
- Setting the MTO logic equation to N/A,
- or disabling Switch-Onto-Fault protection by setting ESOTF = N.

Low-Level Test Interface

The SEL-321 Relay has a low-level test interface between the calibrated input module and the separately-calibrated processing module. You may test the relay in either of two ways: conventionally, by applying ac current signals to the relay inputs or by applying low magnitude ac voltage signals to the low-level test interface. Access the test interface by removing the relay front panel.

Figure 7.2 shows the low-level interface connections. This drawing also appears on the inside of the relay front panel. Remove the ribbon cable between the two modules to access the outputs of the input module and the inputs to the processing module (relay main board).

You can test the relay processing module using signals from the SEL-RTS Low-Level Relay Test System. Never apply voltage signals greater than 9 volts peak-peak to the low-level test interface. Figure 7.2 shows the signal scaling factors.



CAUTION

The relay contains devices sensitive to Electrostatic Discharge (ESD). When working on the relay with front or top cover removed, work surfaces and personnel must be properly grounded or equipment damage may result.

You can test the input module two different ways:

1. Measure the outputs from the input module with an accurate voltmeter (measure signal pin to GND pin), and compare the readings to accurate instruments in the relay input circuits, or
2. Replace the ribbon cable, press the front-panel <METER> button, and compare the relay readings to other accurate instruments in the relay input circuits.

LOW-LEVEL TEST INTERFACE

REMOVE RIBBON
CABLE FOR TESTING

VC	VB	VA	N/C	N/C	N/C	N/C	N/C	N/C	N/C	IC	IB	IA
○	○	○	○	○	○	○	○	○	○	○	○	■
GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND	GND

INPUT MODULE OUTPUT (J2) : 100 mV AT NOMINAL CURRENT (1 A OR 5 A)
1313.7 mV AT NOMINAL VOLTAGE (67 V_{LN})

PROCESSING MODULE INPUT (J13) : 9 V p-p MAXIMUM

U.S. Patent 5,479,315

SEL-321 157-0020

Figure 7.2: Low-Level Test Interface

TEST SETUP

Test Source Connections

Each relay element test requires that ac voltage and/or current signals be applied to the relay. The figures and text below describe the test source connections required for relay protection element tests.

Three Voltage Source and Three Current Source Connections

Figure 7.3 shows connections to use when three voltage sources and three current sources are available. Any protective element may be tested and any fault type simulated using these connections.

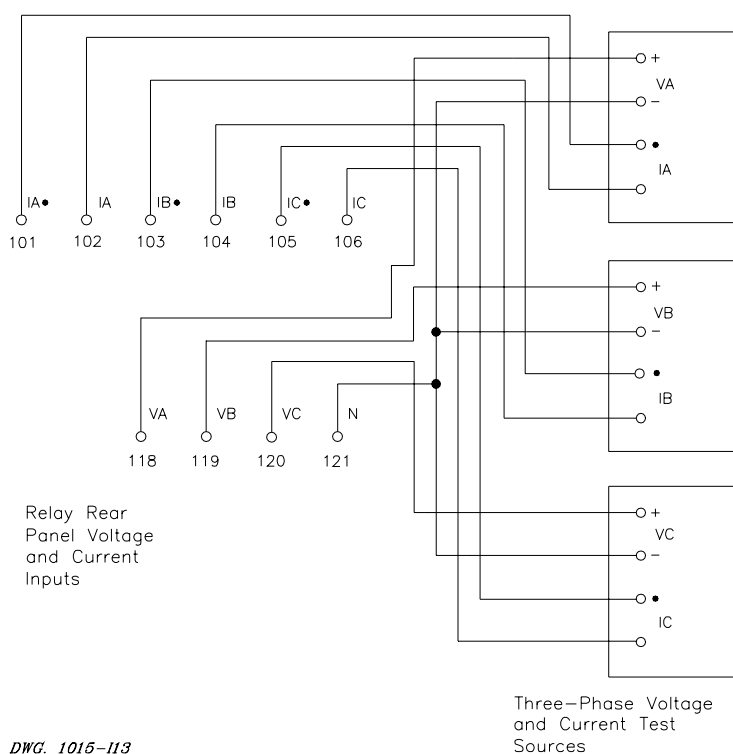


Figure 7.3: Three Voltage Source and Three Current Source Test Connections

Three Voltage Source and Two Current Source Connections

Figure 7.4 and Figure 7.5 show connections to use when three voltage sources and two current sources are available. Phase-to-phase, phase-ground, and two-phase-ground faults may be simulated using the connections shown in Figure 7.4. Three-phase faults may be simulated using the connections shown in Figure 7.5.

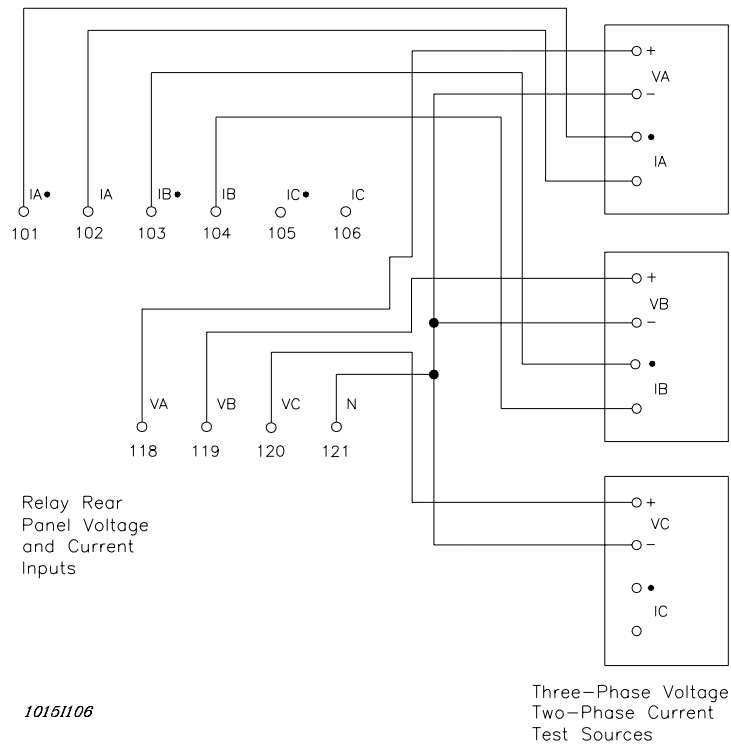


Figure 7.4: Phase-to-Phase, Phase-to-Ground, and Two-Phase-to-Ground Fault Test Connections Using Two Current Sources

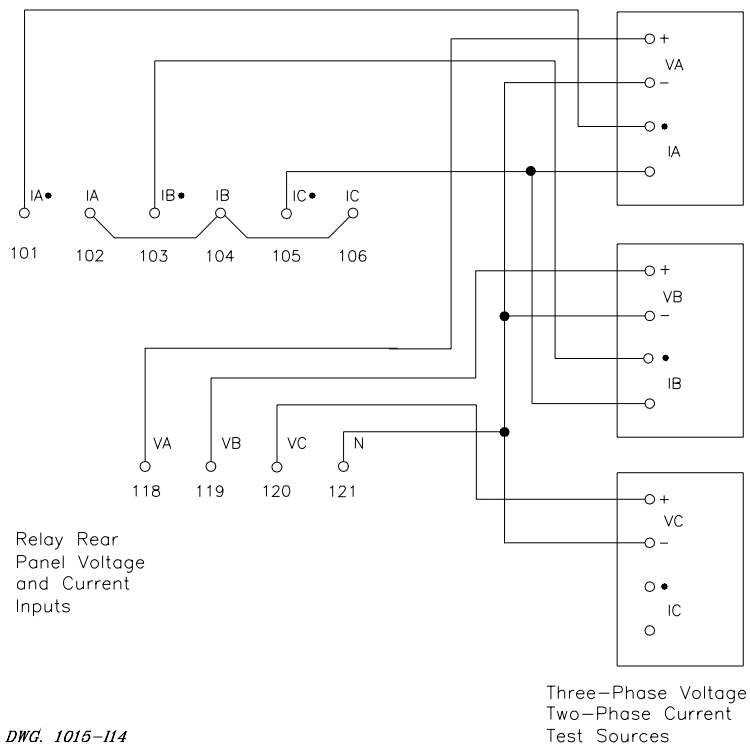


Figure 7.5: Three-Phase Fault and METER Test Connections Using Two Current Sources

Three Voltage Source and One Current Source Connections

Figure 7.6 and Figure 7.7 show connections to use when three voltage sources and a single current source are available. Phase-ground faults may be simulated using the connections shown in Figure 7.6. Phase-to-phase faults may be simulated using the connections shown in Figure 7.7.

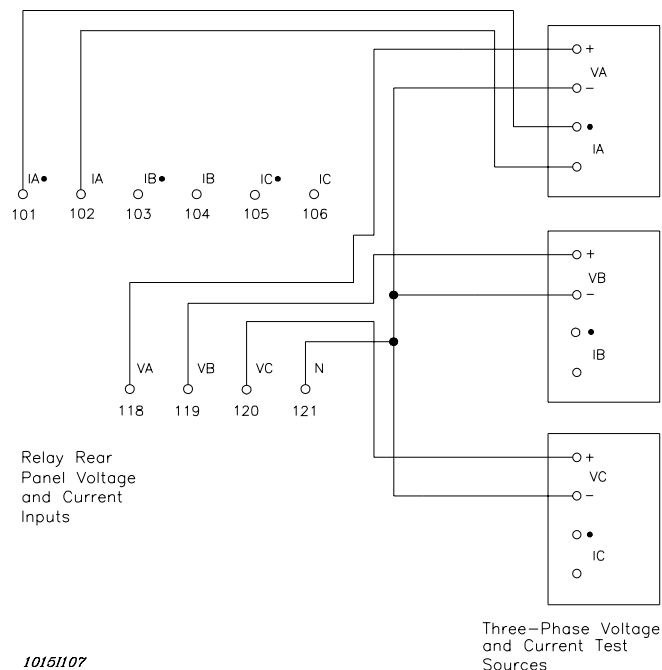


Figure 7.6: Phase-to-Ground Fault Test Connections Using a Single Current Source

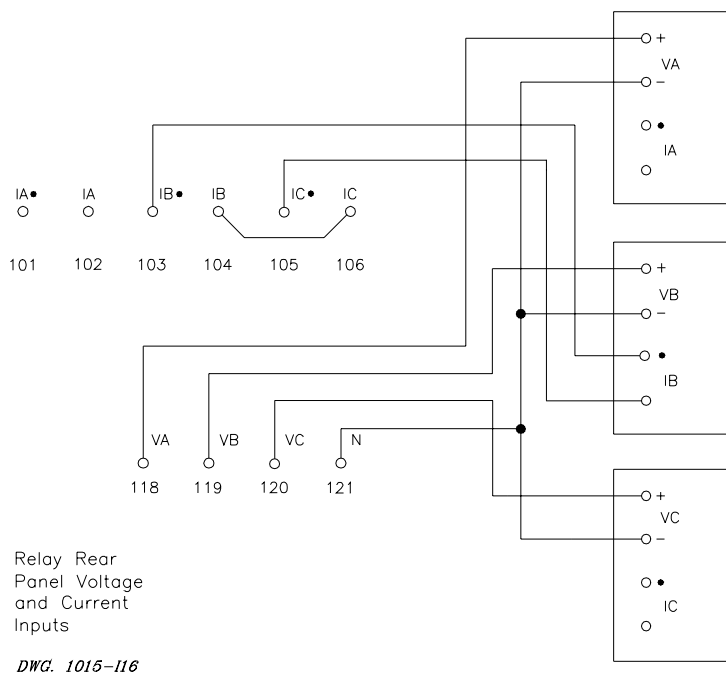


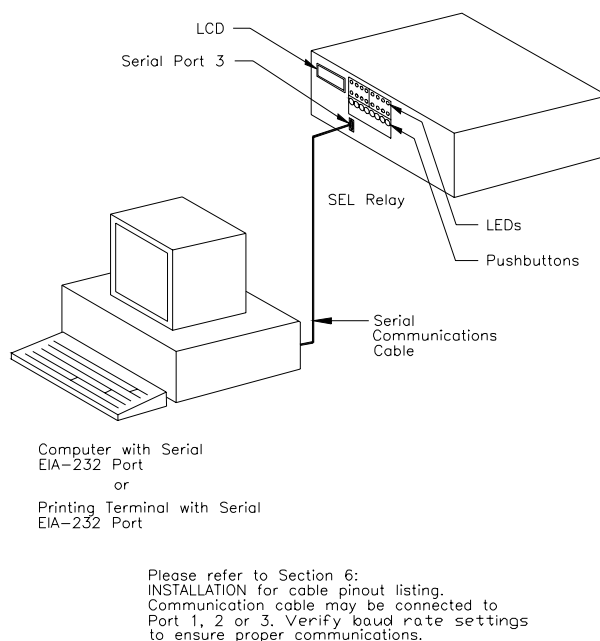
Figure 7.7: Phase-to-Phase Fault Test Connections Using a Single Current Source

Serial Communication Equipment Connections

A terminal or PC with communications software is necessary to make SELOGIC[®] control equations setting changes and examine relay event reports. We recommend using a terminal during relay testing. Figure 7.8 shows typical connections between a computer and the SEL-321 Relay Port 3. Complete details regarding serial communications with the relay may be found in *Section 3: Communications*.



Use only serial communications cables manufactured by SEL or built to SEL specifications with the SEL-321 Relay. Damage to the relay or your communication equipment may result from the use of incorrect communication connections.



DWG. 1015-119

Figure 7.8: Communications Connections Between the SEL-321 Relay and a Terminal

TEST PROCEDURES

This section includes outline test procedures for overcurrent, directional, phase distance, and ground distance elements included in the SEL-321 Relay. The procedures are general, so that they may be applied to any specific element or zone.

Overcurrent Elements

The SEL-321 Relay includes phase, residual, negative-sequence, and positive-sequence overcurrent elements. The type of overcurrent element under test determines the test connections required. Some elements are supervised by directional elements or distance elements.

The steps necessary to perform an overcurrent element test are shown below.

- Step 1.** Select element under test. Briefly review the specifications for the element under test. If the element under test is supervised by other conditions, be sure that you understand the inputs necessary to satisfy the supervisory conditions, and the over-current condition.
- Step 2.** Verify the element setting by executing the SHOWSET command via a terminal connected to a relay serial port, or by examining the relay settings via the front panel LCD display using the Access Level 2 SET command.
- Step 3.** Select the method used to indicate assertion of the element under test. Typically, this is accomplished by monitoring an output contact programmed to indicate only the condition under test.
- Step 4.** Make test source connections. If an unsupervised, single-phase overcurrent element, such as the 50H element, is being tested, a single current source is all that is required to perform the test. If a directionally supervised negative-sequence overcurrent element is to be tested, voltage-sources are also required to satisfy the directional supervision conditions.
- Make test source connections based upon the requirements of the test and the availability of sources. Figure 7.3 through Figure 7.7 illustrate the various source connections you may use.
- Step 5.** Determine the signals required to operate the element. For unsupervised elements, simply use the equations shown on the following page. Fulfilling the requirements of the supervisory conditions may be more complicated. Refer to the test procedures appropriate to the supervising element for details.
- Step 6.** Apply the test signals.
- Step 7.** Monitor the output contact assigned to indicate the state of the element under test to ensure that the element asserts. Review the event reports to ensure that supervisory conditions and the element under test asserted appropriately.

Calculating Overcurrent Element Test Quantities

The SEL-321 Relay is equipped with several different types of overcurrent elements. Each has a specific purpose and a slightly different method of testing. The types of overcurrent elements, the signals they operate from, and the elements of that type are listed below.

<u>Element Type</u>	<u>Operates based upon the magnitude of:</u>	<u>Relay Elements</u>
Phase	A-phase or B-phase or C-phase current. Test using single-phase current.	50H, 50M, 50L1, 50L2, 50L3, 50L4
Three-Phase	A-phase, B-phase, and C-phase current. Test using three-phase current.	3P50R
Phase-to-Phase	Vector difference between two phase currents. Test using one or two phase currents.	50PP1, 50PP2, 50PP3, 50PP4

<u>Element Type</u>	<u>Operates based upon the magnitude of:</u>	<u>Relay Elements</u>
Residual	Residual current: $I_R = I_A + I_B + I_C$. Test using single-phase current.	50G1, 50G2, 50G3, 50G4, 50N1, 50N2, 50N3, 50N4
Negative-Sequence	$3 \cdot I_2 = (I_A + a^2 \cdot I_B + a \cdot I_C)$ Test using single-phase current.	50Q1, 50Q2, 50Q3, 50Q4, 50QF, 50QR
Positive-Sequence	$I_1 = 1/3 (I_A + a \cdot I_B + a^2 \cdot I_C)$ Test using three-phase or single-phase current.	50ABC

Overcurrent Element Test Examples

Examples below illustrate the test methods used for several elements.

Single-Phase Overcurrent Element: 50H

Note: The steps taken in the example test for the 50H nondirectional phase overcurrent element may be applied to test the 50M, 50L1, 50L2, 50L3, and 50L4 nondirectional phase overcurrent element as well as the residual and negative-sequence overcurrent elements 50G1, 50G2, 50G3, 50G4, 50N1, 50N2, 50N3, 50N4, 50Q1, 50Q2, 50Q3, 50Q4, 50QF, and 50QR.

Step 1. Execute the SHOWSET command and verify the relay setting for the 50H overcurrent element. The example relay settings set the 50H element to pick up at 11.25 amps, secondary.

Step 2. Select an output contact to indicate operation of the 50H overcurrent element. In this example we use the OUT8 output.

From Access Level 2, execute the **SET L n** command to configure output OUT8 to close for assertion of the 50H overcurrent element.

```
=>>SET L 1 OUT8 <ENTER>
SELogic group 1

OUT8 =NA

? 50H <ENTER>
OUT9 =NA

? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. You must type **<ENTER>** a second time to review the full group of logic settings. At the prompt, type **Y <ENTER>** to accept those settings.

Connect output OUT8 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

- Step 3.** Connect a single current source to a phase current input of the relay. Refer to the current connections shown in Figure 7.6 as an example.
- Step 4.** Because the 50H overcurrent element operates based upon the magnitude of any single-phase current, the 50H element asserts when any phase current exceeds 11.25 amps.
- Step 5.** Turn on the current test source and slowly increase the magnitude of current applied until the 50H element asserts, causing OUT8 to close. This should occur when current applied is approximately 11.25 amps.
- Note:** As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Phase-to-Phase Overcurrent Element: 50PP2

- The SEL-321 Relay uses the 50PP overcurrent elements to supervise operation of the phase mho distance elements. If a phase distance element zone is not enabled by the PMHOZ setting, the 50PP element setting is not displayed and the element cannot pick up.
 - The steps taken in the example test for the 50PP2 overcurrent element may be applied to test the 50PP1, 50PP3, and 50PP4 phase-to-phase overcurrent elements.
- Step 1.** Execute the SHOWSET command and verify the relay setting for the 50PP2 overcurrent element. The example relay settings set the 50PP2 element to pick up at 2.22 amps, secondary.
- Step 2.** Select an output contact to indicate operation of the 50PP2 overcurrent element. In this example we use the OUT8 output.

From Access Level 2, execute the **SET L n** command to configure Output 8 to close for assertion of the 50PP2 overcurrent element.

```
=>>SET L 1 OUT8 <ENTER>
SELogic group 1

OUT8 =NA

? 50PP2 <ENTER>
OUT9 =NA

? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. Type **Y <ENTER>** to accept those settings.

Connect output OUT8 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

- Step 3.** Connect a single current source to two relay phase current inputs. Refer to the current connections shown in Figure 7.7 as an example.

You may wish to use the connections shown in Figure 7.3 or Figure 7.4 (modified to use I_B and I_C). If you use either of these alternative connections, set the magnitude of I_C equal to the magnitude of I_B and set the phase angle of I_C equal to the phase angle of ($I_B + 180^\circ$).

- Step 4.** The 50PP overcurrent elements operate based upon the magnitude of the vector difference between any two-phase currents. Using the current connections shown in Figure 7.7, the magnitude of I_{BC} is twice the magnitude of the applied current. This is illustrated by the following equations.

$$\begin{aligned} I_{TEST} &= I_B = -I_C \\ I_{BC} &= I_B - I_C \\ I_{BC} &= 2 \cdot I_B \\ I_{BC} &= 2 \cdot I_{TEST} \end{aligned} \quad \text{Equation 7.1}$$

With a 50PP2 setting of 2.22 amps, 50PP2 picks up when I_{TEST} is greater than 1.11 amps.

- Step 5.** Turn on the current test source and slowly increase the magnitude of current applied until the 50PP2 element asserts, causing OUT8 to close. This should occur when current applied is approximately 1.11 amps.

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Negative-Sequence Directional Element

The SEL-321 Relay includes a directional element that operates based upon the calculated magnitude and angle of negative-sequence impedance applied to the relay. There are two methods of testing the element. The first, using a single voltage and current, and the second using three voltages and one current. Examples of both methods are provided below following an explanation of the equations which define the element.

Negative-Sequence Directional Element Based Upon Negative-Sequence Impedance

The SEL-321 Relay calculates the magnitude and angle of negative-sequence voltage and current applied to the relay. From that information, the relay calculates the magnitude of negative-sequence impedance that lies collinear to the line positive-sequence impedance. The equation defining that function is shown below:

$$Z_{2c} = \frac{\text{Re}[V_2 \cdot (1 \angle Z1 \text{ANG}^\circ \cdot I_2)^*]}{|I_2|^2} \quad \text{Equation 7.2}$$

Where: Re indicates the real part of the term in brackets, for instance $\text{Re}[A + jB] = A$
 * indicates the complex conjugate of the expression in parentheses, $(A + jB)^* = (A - jB)$.

The result of Equation 7.2 is an impedance magnitude value that varies with the magnitude and angle of applied current. An example illustrates this operation.

Consider the result of applying the following voltage and current signals to Equation 7.2:

$$\angle Z_{\text{IANG}} = 90^\circ$$

$$V_2 = 10 \angle 180^\circ \text{volts, secondary}$$

$$I_2 = 2 \angle -90^\circ \text{amps, secondary}$$

$$Z_{2c} = \frac{\text{Re}[10 \angle 180^\circ \cdot (1 \angle 90^\circ \cdot 2 \angle -90^\circ)^*]}{|2|^2}$$

$$Z_{2c} = \frac{-20 \text{ ohms}}{4}$$

$$Z_{2c} = -5 \text{ ohms}$$

Coincidentally, these voltage and current signals could represent a forward single line-ground fault on a system with a 90° impedance angle. Normally, a forward fault results in a negative Z_{2c} value.

Here is an example for a reverse single line-ground fault.

$$\angle Z_{\text{IANG}} = 90^\circ$$

$$V_2 = 10 \angle 180^\circ \text{volts, secondary}$$

$$I_2 = 2 \angle 90^\circ \text{amps, secondary}$$

$$Z_{2c} = \frac{\text{Re}[10 \angle 180^\circ \cdot (1 \angle 90^\circ \cdot 2 \angle +90^\circ)^*]}{|2|^2}$$

$$Z_{2c} = \frac{20 \text{ ohms}}{4}$$

$$Z_{2c} = 5 \text{ ohms}$$

Notice that the result of Equation 7.2 is positive for a reverse fault and negative for a forward fault. This result is consistent with actual behavior on the power system.

The relay determines fault direction by comparing the result of Equation 7.2 to forward and reverse impedance thresholds that are dependent upon the Z_{2F} and Z_{2R} relay settings and the magnitude of negative-sequence voltage divided by the magnitude of negative-sequence current.

When Z_{2c} is less than the forward Z_2 threshold, Z_{2FT} , the fault is in the forward direction, so the relay sets the 32QF element, if other supervisory conditions permit. When Z_{2c} is greater than the reverse Z_2 threshold, Z_{2RT} , the fault is in the reverse direction, so the relay sets the 32QR element, if other supervisory conditions permit.

The forward directional threshold is calculated using Equation 7.3 when Z_{2F} is negative or Equation 7.4 when Z_{2F} is positive.

When $Z_{2F} \leq 0$:

$$Z_{2FT} = 0.75 \cdot Z_{2F} - 0.25 \cdot Z_{2m}$$

Equation 7.3

When $Z2F > 0$:

$$Z2FT = 1.25 \cdot Z2F - 0.25 \cdot Z2m \quad \text{Equation 7.4}$$

Where:

$$Z2m = \frac{|V_2|}{|I_2|}$$

The reverse directional threshold is calculated using Equation 7.5 when $Z2R$ is positive or Equation 7.6 when $Z2R$ is negative.

When $Z2R \geq 0$:

$$Z2RT = 0.75 \cdot Z2R + 0.25 \cdot Z2m \quad \text{Equation 7.5}$$

When $Z2R < 0$:

$$Z2RT = 1.25 \cdot Z2R + 0.25 \cdot Z2m \quad \text{Equation 7.6}$$

The threshold equations have a unique property. When $Z2m = |Z2R|$, $Z2RT = Z2R$ and when $Z2m = |Z2F|$, $Z2FT = Z2F$. This property is used to simplify the test procedures outlined on the following pages.

It is possible to create test conditions for a $Z2c$ that lies between the forward and reverse thresholds. In this case the relay does not set the 32QR or the 32QF element. While these conditions can be contrived in the lab, correct $Z2F$ and $Z2R$ settings prevent this from occurring for real power system faults.

Settings for both $Z2F$ and $Z2R$ may be either positive or negative, depending upon the constraints of the relay application. **Section 5: Applications** of this instruction manual provides guidelines for the selection of $Z2F$ and $Z2R$ settings.

Negative-Sequence Directional Element Supervisory Conditions

There are a number of supervisory conditions that must be fulfilled before the relay asserts the 32QF or 32QR elements. These supervisory conditions are described below:

Magnitude of $3I_2$

The SEL-321 Relay uses the 50QF and 50QR negative-sequence overcurrent elements to supervise operation of the directional element. If the magnitude of applied $3I_2$ is not greater than the 50QF setting, the 32QF element does not assert to indicate direction. If the magnitude of $3I_2$ applied is not greater than the 50QR setting, the 32QR element does not assert.

Magnitude Comparison of Positive-Sequence Current to Negative-Sequence Current

The relay multiplies the measured positive-sequence current (I_1) magnitude by the $a2$ setting, then compares the result to the measured magnitude of negative-sequence current (I_2). The magnitude of I_2 must be greater than the magnitude of I_1 multiplied by $a2$ for the directional element (32QF or 32QR) to operate.

Loss-of-Potential Supervision

If ELOP = Y, Y1, or Y2, the relay supervises the directional logic using the Internal Loss-of-Potential condition (ILOP). If ELOP = Y or Y2 the relay sets the 32QF element when a loss-of-potential is detected, regardless of other signals applied to the relay. If you test the directional logic using single voltage and current sources, set ELOP = N to simplify the test.

Single-Pole Open Supervision

The relay cannot issue an appropriate directional decision in single-pole trip applications if one or more breaker poles is open when line-side voltage transformers are applied. The relay asserts the 32QF element any time a Single-Pole Open condition is detected. To simplify directional element tests, apply dc voltage to any inputs assigned to perform the 52 auxiliary functions, or disable the Single-Pole Open logic by setting ESPO = N.

Negative-Sequence Directional Element Test Using Single Voltage and Current Sources

Step 1. Execute the SHOWSET command and verify the following relay settings: Z1MAG, Z1ANG, Z2F, 50QF, Z2R, 50QR, and a2. The example relay settings use the following settings: Z1MAG = 7.8 Ω , Z1ANG = 83.97°, Z2F = 0.77 Ω ; 50QF = 0.5 amps secondary; Z2R = 5.45 Ω ; 50QR = 0.5 amps secondary; a2 = 0.07.

Execute the **SET** command and change the example ELOP setting from Y to N.

Step 2. Select output contacts to indicate operation of the 32QF and 32QR elements. In this example we use the OUT7 and OUT8 outputs.

From Access Level 2, execute the **SET L n** command to configure Output 7 and Output 8 to close for assertion of the 32QF and 32QR elements, respectively.

```
=>>SET L 1 OUT7 <ENTER>
SELogic group 1
  OUT7 =NA

  ? 32QF <ENTER>
  OUT8 =50PP2
  ? 32QR <ENTER>
  OUT9 =NA
  ? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. At the prompt, type **Y <ENTER>** to accept those settings.

Connect outputs OUT7 and OUT8 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the voltage source to the A-phase to neutral relay voltage input. Connect the current source to the A-phase relay current input. Refer to the A-phase voltage and current connections shown in Figure 7.6 as an example. The B-phase and C-phase voltage connections are not required for this test.

Step 4. As described above, the relay 32Q element operates based upon the magnitude and angle of negative-sequence voltages and currents. You can calculate the magnitude and angle of V_2 and I_2 , given the magnitude and angle of each of the phase quantities using the equations below.

$$V_2 = \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C)$$

$$I_2 = \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C)$$

Using single-phase signals simplifies the V_2 and I_2 calculations.

$$V_B = V_C = 0 \text{ volts}$$

$$I_B = I_C = 0 \text{ amps}$$

$$V_2 = \frac{1}{3} \cdot (V_A)$$

$$I_2 = \frac{1}{3} \cdot (I_A)$$

Assume that you apply a test voltage $V_A = 18.0 \angle 180^\circ$ volts secondary.

$$V_2 = \frac{1}{3} \cdot (18.0 \angle 180^\circ) \text{ volts}$$

$$V_2 = 6.0 \angle 180^\circ \text{ volts}$$

Determine the test angle of A-phase current from the Z1ANG relay setting. Equation 7.2 yields a positive result when I_2 lags V_2 by the angle of Z1ANG°. Equation 7.2 yields a negative result when I_2 leads V_2 by $(180^\circ - \angle Z1ANG^\circ)$.

We are testing for positive values of Z2c, so I_2 should lag V_2 by Z1ANG.

Assuming that $V_A = 18.0 \angle 180^\circ$ volts, the angle of I_A for this test should be 96° .

Determine the magnitude of A-phase current where Z2 equals Z2R or Z2F using Equation 7.7:

$$|I_A| = 3 \cdot (|V_2| / |Z_2|) \quad \text{Equation 7.7}$$

For Z2R = 5.45 Ω :

$$|I_A| = 3 \cdot (6.0 \text{ volts} / 5.45 \text{ ohms})$$

$$|I_A| = 3.3 \text{ amps}$$

Calculate Z2m:

$$Z2m = \frac{|V_2|}{|I_2|}$$

$$Z2m = \frac{6.0V}{1.1A}$$

$$Z2m = 5.45 \text{ ohms}$$

Because Z2R is positive, use Equation 7.5 to calculate Z2RT.

$$Z2RT = 0.75 \cdot Z2R + 0.25 \cdot Z2m$$

$$Z2RT = 0.75 \cdot (5.45) + 0.25 \cdot (5.45)$$

$$Z2RT = 5.45 \text{ ohms}$$

The 32QR element asserts when Z2c applied is greater than Z2RT. As the magnitude of I_A is increased, the magnitudes of Z2c and Z2m decrease. For magnitudes of I_A less than 3.3 amps, 32QR asserts, given the other test quantities. For I_A magnitudes greater than 3.3 amps, Z2c is less than Z2RT, so 32QR deasserts.

For $Z2F = 0.77 \Omega$:

$$|I_A| = 3 \cdot (6.0 \text{ volts} / 0.77 \text{ ohms})$$

$$|I_A| = 23.4 \text{ amps}$$

Calculate Z2m:

$$Z2m = \frac{|V_2|}{|I_2|}$$

$$Z2m = \frac{6.0V}{7.8A}$$

$$Z2m = 0.77 \text{ ohms}$$

Because Z2F is positive, use Equation 7.4 to calculate Z2FT.

$$Z2FT = 1.25 \cdot Z2F - 0.25 \cdot Z2m$$

$$Z2FT = 1.25 \cdot (0.77) - 0.25 \cdot (0.77)$$

$$Z2FT = 0.77 \text{ ohms}$$

The 32QF element asserts when Z2c is less than Z2FT. As the magnitude of I_A is increased, the magnitudes of Z2c and Z2m decrease. For magnitudes of I_A less than 23.4 amps, 32QF should not assert, given the other test quantities. For I_A magnitudes greater than 23.4 amps, Z2c applied is less than Z2FT, so 32QF asserts.

Step 5. Turn on the voltage source.

Apply $V_A = 18.0 \text{ V } \angle 180^\circ$ $I_A = 0.0 \text{ A } \angle 96^\circ$.

Slowly increase the magnitude of I_A , without varying the phase angle.

The relay 32QR element asserts, closing OUT8 when $|I_A| = 0.5 \text{ amps}$. This indicates that Z2c applied is greater than Z2RT, $3I_2$ is greater than 50QR, and I_2 is greater than $a2 \cdot I_1$, where a2 is the relay setting.

Continue to increase the magnitude of I_A . 32QR deasserts when $|I_A| = 3.3 \text{ amps}$, indicating that Z2c is now less than Z2RT. 32QF asserts, closing OUT7 when $|I_A| = 23.4 \text{ amps}$, indicating that Z2c is less than Z2FT.

Verify the performance described above by calculating Z2c using Equation 7.2 and the test quantities listed above.

For $V_A = 18.0 \text{ V } \angle 180^\circ$, $I_A = 3.3 \text{ A } \angle 96^\circ$:

$$\begin{aligned}
 V_2 &= 6.0 \angle 180^\circ \\
 I_2 &= 1.10 \\
 1 \angle Z1 \text{ANG}^\circ &= 1 \angle 83.97^\circ \\
 Z2c &= \frac{\text{Re}[V_2 \cdot (1 \angle Z1 \text{ANG}^\circ \cdot I_2)^*]}{|I_2|^2} \\
 Z2c &= \frac{\text{Re}[6 \angle 180^\circ \cdot (1 \angle 83.97^\circ \cdot 1.10 \angle 96^\circ)^*]}{|1.10|^2} \\
 Z2c &= \frac{6.6 \text{ ohms}}{1.21} \\
 Z2c &= 5.45 \text{ ohms} = Z2RT \text{ when } Z2m = 5.45 \text{ ohms}
 \end{aligned}
 \tag{Equation 7.2}$$

For $V_A = 18.0 \text{ V } \angle 180^\circ$, $I_A = 23.4 \text{ A } \angle 96^\circ$, and using the equation above:

$$\begin{aligned}
 V_2 &= 6.0 \text{ V } \angle 180^\circ \\
 I_2 &= 7.80 \\
 1 \angle Z1 \text{ANG}^\circ &= 1 \angle 83.97^\circ \\
 Z2c &= \frac{\text{Re}[6 \angle 180^\circ \cdot (1 \angle 83.97^\circ \cdot 7.80 \angle 96^\circ)^*]}{|7.80|^2} \\
 Z2c &= \frac{46.8 \text{ ohms}}{60.84} \\
 Z2c &= 0.77 \text{ ohms} = Z2FT \text{ when } Z2m = 0.77 \text{ ohms}
 \end{aligned}$$

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Negative-Sequence Directional Element Test Using Three Voltage Sources and One Current Source

Step 1. Execute the **SHOWSET** command and verify the following relay settings: Z1MAG, Z1ANG, Z2F, 50QF, Z2R, 50QR, and a2. The example relay settings use the following settings: Z1MAG = 7.8 Ω ; Z1ANG = 83.97°; Z2F = 0.77 Ω ; 50QF = 0.5 amps secondary; Z2R = 5.45 Ω ; 50QR = 0.5 amps secondary; a2 = 0.07.

Execute the **SET** command and change the example ELOP setting from Y to N.

Step 2. Select output contacts to indicate operation of the 32QF and 32QR elements. In this example we use the OUT7 and OUT8 outputs.

From Access Level 2, execute the **SET Ln** command to configure Output 7 and Output 8 to close for assertion of the 32QF and 32QR elements, respectively.

```

=>>SET L 1 OUT7 <ENTER>
SELogic group 1
OUT7 =NA

? 32QF <ENTER>
OUT8 =50PP2

? 32QR <ENTER>
OUT9 =NA

? END <ENTER>

```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. Type **Y <ENTER>** to accept those settings.

Connect outputs OUT7 and OUT8 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the three voltage sources and one current source to the relay as shown in Figure 7.6.

Step 4. As described above, the relay 32Q element operates based upon the magnitude and angle of negative-sequence voltages and currents. You can calculate the magnitude and angle of V_2 and I_2 , given the magnitude and angle of each of the phase quantities using the equations below.

$$V_2 = \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C)$$

$$I_2 = \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C)$$

Using a single-phase current source simplifies the I_2 calculation.

$$I_B = I_C = 0 \text{ amps}$$

$$I_2 = \frac{1}{3} \cdot (I_A)$$

Assume that you apply the following test voltages:

$$V_A = 49.0V \angle 0^\circ$$

$$V_B = 67.0V \angle -120^\circ$$

$$V_C = 67.0V \angle 120^\circ$$

$$V_2 = \frac{1}{3} \cdot (49.0 \angle 0^\circ + 1 \angle 240^\circ \cdot 67 \angle -120^\circ + 1 \angle 120^\circ \cdot 67 \angle 120^\circ) \text{ volts}$$

$$V_2 = \frac{1}{3} \cdot (49.0 \angle 0^\circ + 67 \angle 120^\circ + 67 \angle -120^\circ) \text{ volts}$$

$$V_2 = 6.0 \angle 180^\circ \text{ volts}$$

Determine the test angle of A-phase current from the Z1ANG relay setting. For Equation 7.2 to yield a positive result, I_A , hence I_2 , should lag V_2 by the angle of Z1ANG. For Equation 7.2 to yield a negative result, I_A should lead V_2 by $(180^\circ - \angle Z1ANG^\circ)$.

When you apply the voltage signals shown above, V_2 is 180° out of phase from V_A . Take this into account, and calculate the angle of I_A with respect to the angle of V_A . Equation 7.2 yields a positive result when I_A leads V_A by $(180^\circ - \angle Z1ANG^\circ)$. Equation 7.2 yields a negative result when I_A lags V_A by $\angle Z1ANG^\circ$.

We are testing for positive values of $Z2c$, so I_A should lead V_A by $(180^\circ - \angle Z1ANG^\circ)$. Assuming that $V_A = 49.0 \angle 0^\circ$ volts, the angle of I_A for this test should be 96° .

Calculate the magnitude of A-phase current where $Z2c$ equals $Z2RT$ or $Z2FT$ using Equation 7.7:

$$|I_A| = 3 \cdot (|V_2| / |Z_2|) \quad \text{Equation 7.7}$$

For $Z2R = 5.45 \Omega$:

$$\begin{aligned} |I_A| &= 3 \cdot (6.0 \text{ volts} / 5.45 \text{ ohms}) \\ |I_A| &= 3.3 \text{ amps} \end{aligned}$$

Calculate $Z2m$:

$$\begin{aligned} Z2m &= \frac{|V_2|}{|I_2|} \\ Z2m &= \frac{6.0V}{1.1A} \\ Z2m &= 5.45 \text{ ohms} \end{aligned}$$

Because $Z2R$ is positive, use Equation 7.5 to calculate $Z2RT$.

$$\begin{aligned} Z2RT &= 0.75 \cdot Z2R + 0.25 \cdot Z2m \\ Z2RT &= 0.75 \cdot (5.45) + 0.25 \cdot (5.45) \\ Z2RT &= 5.45 \text{ ohms} \end{aligned}$$

The 32QR element asserts when $Z2c$ applied is greater than $Z2RT$. As the magnitude of I_A is increased, the magnitudes of $Z2c$ and $Z2m$ decrease. For magnitudes of I_A less than 3.3 amps, 32QR asserts, given the other test quantities. For I_A magnitudes greater than 3.3 amps, $Z2c$ is less than $Z2RT$, so 32QR deasserts.

For $Z2F = 0.77 \Omega$:

$$\begin{aligned} |I_A| &= 3 \cdot (6.0 \text{ volts} / 0.77 \text{ ohms}) \\ |I_A| &= 23.4 \text{ amps} \end{aligned}$$

Calculate $Z2m$:

$$\begin{aligned} Z2m &= \frac{|V_2|}{|I_2|} \\ Z2m &= \frac{6.0V}{7.8A} \\ Z2m &= 0.77 \text{ ohms} \end{aligned}$$

Because Z2F is positive, use Equation 7.4 to calculate Z2FT.

$$\begin{aligned}Z2FT &= 1.25 \cdot Z2F - 0.25 \cdot Z2m \\Z2FT &= 1.25 \cdot (0.77) - 0.25 \cdot (0.77) \\Z2FT &= 0.77 \text{ ohms}\end{aligned}$$

The 32QF element asserts when Z2c is less than Z2FT. As the magnitude of I_A is increased, the magnitudes of Z2c and Z2m decrease. For magnitudes of I_A less than 23.4 amps, 32QF should not assert, given the other test quantities. For I_A magnitudes greater than 23.4 amps, Z2c applied is less than Z2FT, so 32QF asserts.

Step 5. Turn on the voltage sources.

Apply:

$$\begin{aligned}V_A &= 49.0V\angle 0^\circ \\V_B &= 67.0V\angle -120^\circ \\V_C &= 67.0V\angle 120^\circ \\I_A &= 0.0A\angle 96^\circ\end{aligned}$$

Slowly increase the magnitude of I_A , without varying the phase angle.

The relay 32QR element asserts, closing OUT8 when $|I_A| = 0.5$ amps. This indicates that Z2c applied is greater than Z2RT, $3I_2$ is greater than 50QR, and I_2 is greater than $a2 \cdot I_1$, where a2 is the relay setting.

Continue to increase the magnitude of I_A . 32QR deasserts when $|I_A| = 3.3$ amps, indicating that Z2c is now less than Z2RT. 32QF asserts, closing OUT7 when $|I_A| = 23.4$ amps, indicating that Z2c is less than Z2FT.

Verify that the relay operated properly by calculating Z2c using Equation 7.2 and the test quantities listed below.

For:

$$\begin{aligned}I_A &= 3.30A\angle 96^\circ \\V_A &= 49.0V\angle 0^\circ \\V_B &= 67.0V\angle -120^\circ \\V_C &= 67.0V\angle 120^\circ\end{aligned}$$

$$\begin{aligned}V_2 &= 6.0V\angle 180^\circ \\I_2 &= 1.10 \\1\angle Z1ANG^\circ &= 1\angle 83.97^\circ\end{aligned}$$

$$Z2c = \frac{\text{Re}[V_2 \cdot (1\angle Z1ANG^\circ \cdot I_2)^*]}{|I_2|^2}$$

$$Z2c = \frac{\text{Re}[6\angle 180^\circ \cdot (1\angle 83.97^\circ \cdot 1.10\angle 96^\circ)^*]}{|1.10|^2}$$

Equation 7.2

$$Z2c = \frac{6.6 \text{ ohms}}{1.21}$$

$$Z2c = 5.45 \text{ ohms} = Z2RT \text{ when } Z2m = 5.45 \text{ ohms}$$

For:

$$\begin{aligned}I_A &= 23.4A\angle 96^\circ \\V_A &= 49.0V\angle 0^\circ \\V_B &= 67.0V\angle -120^\circ \\V_C &= 67.0V\angle 120^\circ\end{aligned}$$

$$\begin{aligned}V_2 &= 6.0V\angle 180^\circ \\I_2 &= 7.80 \\1\angle Z1ANG^\circ &= 1\angle 83.97^\circ\end{aligned}$$

$$Z2c = \frac{\text{Re}[6\angle 180^\circ \cdot (1\angle 83.97^\circ \cdot 7.80\angle 96^\circ)^*]}{|7.80|^2}$$

$$Z2c = \frac{46.8 \text{ ohms}}{60.84}$$

$$Z2c = 0.77 \text{ ohms} = Z2F \text{ when } Z2m = 0.77 \text{ ohms}$$

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Phase Mho Distance Elements

The SEL-321 Relay includes up to four zones of mho phase distance protection. Enable the number of phase distance zones you would like to apply using the PMHOZ setting. You may set the phase distance elements to reach in the forward or reverse direction. The reach and direction of each zone is independent from the other zones. When a zone of phase distance protection is set to reach in one direction, the ground distance elements associated with that zone must be set to reach in the same direction. Reach is set in secondary ohms. The phase distance element maximum reach angle is always equal to the angle of Z1ANG.

Each zone has an instantaneous indication. For example, the M3P element asserts without intentional time delay for A-B, B-C, or C-A faults within the Zone 3 characteristic. Zones 2, 3, and 4 also include time delayed indication through elements M2PT, M3PT, and M4PT. In addition, the relay provides an instantaneous indication for each individual phase-to-phase distance element. For example, the MAB1, MAB2, MAB3, and MAB4 elements provide instantaneous indication of A-B phase faults in each zone.

For general testing, use the instantaneous and time delayed elements that respond to any phase-to-phase fault within a given zone such as M1P, M2P, etc. You can record more detailed and specific test results using the instantaneous element associated with the faulted phase pair and zone under test.

Phase Distance Element Supervisory Conditions

There are a number of supervisory conditions that must be fulfilled before the relay allows a phase distance element to pick up. These supervisory conditions are described below.

Phase-to-Phase Nondirectional Overcurrent Element, 50PPn

Each phase-to-phase distance element is supervised by a nondirectional phase-to-phase overcurrent element. For example, the relay can not assert the Zone 3 A-B phase-to-phase distance element if the vector difference between A-phase current and B-phase current is less than the 50PP3 setting.

Negative-Sequence Directional Element

The phase distance protection function is supervised by the negative-sequence directional element to provide improved directional security. Forward-reaching phase distance elements may not assert unless the 32QF element is asserted. Reverse-reaching phase distance elements may not assert unless the 32QR element is asserted. The relay operates properly for three-phase faults where no negative-sequence current is present using alternative logic to detect three-phase faults.

Loss-of-Potential Logic

If ELOP = Y, Y1, or Y2 the relay supervises the phase distance element logic using the Internal Loss-of-Potential condition (ILOP). When ELOP = Y, Y1, or Y2 the relay disables the phase distance elements when a loss-of-potential is detected, regardless of other signals applied to the relay. If you test the phase distance elements using low voltage signals, set ELOP = N to simplify the test.

Single-Pole Open Logic

In single-pole trip applications, the relay cannot properly polarize or operate the phase distance elements associated with an open breaker pole. The relay Single-Pole Open logic disables the two phase-to-phase distance elements associated with an open breaker pole. For instance, if Pole A is open, the relay may not operate the A-B or C-A phase-to-phase distance elements. To simplify distance element tests, apply control voltage to any inputs assigned to perform the 52 auxiliary functions, or disable the Single-Pole Open logic by setting ESPO = N.

Load-Encroachment Logic

The relay includes Load-Encroachment logic to help prevent the relay phase distance elements from operating improperly under heavy load conditions. Forward and reverse load regions are defined using impedance and angle settings. The relay calculates the positive-sequence impedance. If the calculated impedance falls within the set load area, the phase distance elements are blocked from operating. This may result in a phase distance element characteristic that appears to have a bow-tie shaped section missing near the area of the resistive axis. Double-check the relay Load-Encroachment logic settings if your test results appear incorrect near the resistive axis.

Out-of-Step Blocking Logic

The relay includes Out-of-Step Tripping and Blocking logic that operates based on the Zone 5 and Zone 6 positive-sequence impedance zones and several timers. If you suspect that the Out-of-Step logic is blocking operation of a phase distance element under test, check the relay settings associated with the Out-of-Step function and review the relay event report.

Phase Distance Element Test Using Three Voltage Sources and One Current Source

Note: This test refers directly to the Zone 2 phase distance element, but may be applied to any other forward-reaching phase-to-phase distance element zone. To test reverse-reaching zones, simply add 180° to the calculated test current phase angle. Verify correct operation of the 32QR element for the test voltage and current signals using Equation 7.2 in the Negative-Sequence Directional Element Test Procedure.

Step 1. Execute the SHOWSET command and verify the following relay settings: Z1MAG, Z1ANG, PMHOZ, DIR2, Z2P, 50PP2, Z2F, and 50QF. The example relay settings use the following settings: Z1MAG = 7.8; Z1ANG = 83.97° ; PMHOZ = 3; DIR2 = F; Z2P = 9.36 Ω ; 50PP2 = 2.22; Z2F = 0.77 Ω ; 50QF = 0.5 amps secondary.

Execute the SET command and change the example ELOP setting from Y to N. This prevents the relay Loss-of-Potential logic from blocking operation of the relay distance elements.

Step 2. Select an output contact to indicate operation of the M2P element. In this example we use the OUT7 output.

From Access Level 2, execute the SET L n command to configure Output 7 to close for assertion of the M2P element.

```
=>>SET L 1 OUT7 <ENTER>
SELogic group 1
OUT7 =NA
? M2P <ENTER>
OUT8 =32QR
? END <ENTER>
```

After you type **END** <ENTER> to end the set procedure, the relay displays the current logic settings. Type **Y** <ENTER> to accept those settings.

Connect output OUT7 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the voltage sources to the relay A-phase, B-phase, and C-phase voltage inputs. Connect the current source to the relay B-phase and C-phase current inputs. Refer to the voltage and current connections shown in Figure 7.7 as an example.

Step 4. Select the magnitude of the test signals, I_{BC} , V_B , and V_C .

Table 7.3 summarizes the test quantities for the Zone 2 B-C phase distance element based upon the example relay settings.

Table 7.3: Test Quantities for Zone 2 Phase Distance Element

Test Voltages	Test Current
$V_A = 67 \angle 0^\circ$ volts	$I_{TEST} = 2.5 \angle -173.97^\circ$ amps
$V_B = 46.8 \angle -150^\circ$ volts	
$V_C = 46.8 \angle 150^\circ$ volts	

The following text describes a hand calculation method you may use to calculate relay distance element voltage and current test signals. If you do not wish to review this information, go to Step 5.

You may want to use the Basic program ONEBUS to calculate distance element test quantities. A listing of this program is provided in *Appendix D*.

The relay phase distance elements operate based upon the magnitude of applied phase-to-phase impedance. The impedance calculation is also supervised by the functions described. To effectively test the distance elements, select voltage and current test signals that fulfill the impedance and supervisory requirements of the relay settings, but are within the ability of the voltage and current test sources to produce accurately.

The Zone 2 phase distance element is forward-reaching in the example relay settings. Thus, it is supervised by the forward directional element 32QF, as well as the 50PP2 phase-to-phase overcurrent elements. For the distance element to assert, the applied phase-to-phase current must exceed the 50PP2 setting and applied $3I_2$ must exceed the 50QF setting.

The 50PP overcurrent elements operate based upon the magnitude of the vector difference between any two phase currents. Using the current connections shown in Figure 7.7, the magnitude of I_{BC} is twice the magnitude of the applied current. This is illustrated by the following equations.

$$\begin{aligned} I_{TEST} &= I_B = -I_C \\ I_{BC} &= I_B - I_C \\ I_{BC} &= 2 \cdot I_B \\ I_{BC} &= 2 \cdot I_{TEST} \end{aligned}$$

With a 50PP2 setting of 2.22 amps, 50PP2 picks up when I_{TEST} is greater than 1.11 amps.

The 50QF negative-sequence overcurrent element operates based upon the magnitude of $3I_2$ applied. Using the current connections shown in Figure 7.7, we can calculate the magnitude of $3I_2$ applied based upon the magnitude of I_{TEST} .

$$\begin{aligned} I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\ 3 \cdot I_2 &= (I_A + a^2 \cdot I_B + a \cdot I_C) \\ I_A &= 0 \text{ and } I_C = -I_B, \text{ so:} \\ 3 \cdot I_2 &= (a^2 \cdot I_B - a \cdot I_B) \\ 3 \cdot I_2 &= I_B \cdot (a^2 - a) \\ 3 \cdot I_2 &= I_B \cdot (1.732 \angle -90^\circ) \end{aligned}$$

Because the 50QF element operates based upon magnitude only, the equation above is simplified.

$$|3 \cdot I_2| = |I_{TEST}| \cdot 1.732$$

With a 50QF setting of 0.5 amps, 50QF picks up when I_{TEST} is greater than 0.288 amps.

In this example, select $|I_{TEST}| = 2.5$ amps, thus $I_{BC} = 5.0$ amps and $3I_2 = 4.33$ amps. This selection fulfills the supervisory overcurrent conditions described above.

The reach of the distance element under test is defined by the element setting. In this case $Z2P = 9.36$ secondary ohms.

Calculate the magnitude of V_{BC} using Equation 7.8.

$$\begin{aligned} |V_{BC}| &= |I_{BC}| \cdot |Z_{BC}| \\ |V_{BC}| &= |5.0| \cdot |9.36| \\ |V_{BC}| &= 46.8 \text{ volts secondary} \end{aligned} \quad \text{Equation 7.8}$$

Refer to Figure 7.9 and use the equations below to calculate the magnitude and angle of V_B and V_C based upon the magnitude of V_{BC} calculated above.

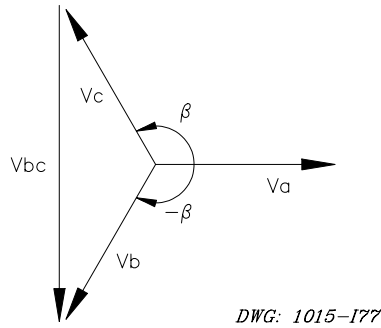


Figure 7.9: Phase Distance Element Test Voltage Signals

When the magnitude of V_{BC} calculated above lies between 67 and 35 volts, use $\beta = 150^\circ$ and $|V_B| = |V_C| = |V_{BC}|$.

When the magnitude of V_{BC} calculated above is greater than 67 volts, use $|V_B| = |V_C| = 67$ V. Calculate the angle β using Equation 7.9.

When the magnitude of V_{BC} calculated above is less than 35 volts, use $|V_B| = |V_C| = 35$ V. Calculate the angle β using Equation 7.9.

$$\beta = 180^\circ - \arcsin[|V_{BC}| / (2 \cdot |V_C|)] \text{ deg} \quad \text{Equation 7.9}$$

Select $V_A = 67 \angle 0^\circ$ volts. For the Zone 2 B-C element test, based upon the example settings, the magnitude of V_{BC} equals 46.8 volts. From the equations above, select the following test voltage magnitudes and angles.

$$\begin{aligned} V_A &= 67.0 \angle 0^\circ \text{ volts} \\ V_B &= 46.8 \angle -150^\circ \text{ volts} \\ V_C &= 46.8 \angle 150^\circ \text{ volts} \end{aligned}$$

The phase distance element maximum reach is measured when faulted phase-to-phase current lags faulted phase-to-phase voltage by the distance element maximum

torque angle. In the SEL-321 Relay, the phase distance element maximum torque angle is defined by the angle of the relay Z1ANG setting.

For the example relay settings, I_{BC} should lag V_{BC} by 83.97° . Based upon the test voltages selected above, V_{BC} lags V_A by 90° , so I_{BC} should lag V_A by 173.97° .

As stated above, the phase distance elements are supervised by the negative-sequence directional element. It is important to check the negative-sequence quantities applied and verify that the 32QF element should assert allowing the forward-reaching distance element to operate. We can calculate the magnitude and angle of negative-sequence voltage and current applied for the test quantities listed above. We can then calculate the negative-sequence impedance, $Z2c$, applied using Equation 7.2 and compare $Z2c$ to the $Z2FT$ threshold which is a function of the $Z2F$ setting and $Z2m$.

$$\begin{aligned} V_2 &= \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C) \\ I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\ Z2c &= \frac{\text{Re}[V_2 \cdot (1 \angle Z1ANG^\circ \cdot I_2)^*]}{|I_2|^2} \end{aligned} \quad \text{Equation 7.2}$$

$$\begin{aligned} Z2m &= \frac{|V_2|}{|I_2|} \\ Z2FT &= 1.25 \cdot Z2F - 0.25 \cdot Z2m \end{aligned} \quad \text{Equation 7.4}$$

Taking the test signals from Table 7.3.

$$V_A = 67.0V \angle 0^\circ \text{ volts}$$

$$V_B = 46.8V \angle -150^\circ \text{ volts}$$

$$V_C = 46.8V \angle 150^\circ \text{ volts}$$

$$V_2 = \frac{1}{3} \cdot (67.0 \angle 0^\circ + 1 \angle 240^\circ \cdot 46.8 \angle -150^\circ + 1 \angle 120^\circ \cdot 46.8 \angle 150^\circ) \text{ volts}$$

$$V_2 = 22.3 \angle 0^\circ \text{ volts}$$

Due to the test connections used, $I_B = -I_C = I_{TEST}$.

$$I_A = 0.0A \angle 0^\circ$$

$$I_B = 2.5A \angle -173.97^\circ$$

$$I_C = 2.5A \angle 6.03^\circ$$

$$I_2 = \frac{1}{3} \cdot (0.0 \angle 0^\circ + 1 \angle 240^\circ \cdot 2.5 \angle -173.97^\circ + 1 \angle 120^\circ \cdot 2.5 \angle 6.03^\circ) \text{ amps}$$

$$I_2 = 1.44 \angle 96.03^\circ \text{ amps}$$

Using Equation 7.2 to calculate $Z2c$, the result is:

$$Z2c = -15.47 \text{ ohms}$$

$$\begin{aligned}
Z_{2m} &= 15.47 \text{ ohms} \\
Z_{2FT} &= 1.25 \cdot (0.77) - 0.25 \cdot (15.47) \\
Z_{2FT} &= -2.91 \text{ ohms}
\end{aligned}$$

The Z_{2FT} threshold is -2.91 Ω. Z_{2c} applied (-15.47 Ω) is less than the Z_{2FT} threshold based upon the Z_{2F} setting (0.77 Ω) and Z_{2m} (15.47 Ω), therefore, the 32QF element asserts when these signals are applied. If Z_{2c} applied is greater than the Z_{2FT} threshold, select new test current and voltages using the steps outlined above.

Step 5. Turn on the voltage sources. Apply V_A, V_B, and V_C at the magnitudes and angles listed in Table 7.3. Turn on the current test source. Set the current angle to -174°. Slowly increase the magnitude of current applied until the M2P element asserts, causing OUT7 to close. This should occur when current applied is approximately 2.5 amps.

With these signals applied, the relay measures B-C phase impedance defined by the equation:

$$Z_{BC} = \frac{V_{BC}}{2 \cdot I_{TEST}} \text{ ohms, sec} \quad \text{Equation 7.10}$$

You may wish to test the distance element characteristic at impedance angles other than the line positive-sequence impedance angle. To do this, you must adjust the magnitude and angle of I_{TEST} from the values shown in Table 7.3. As an example, calculate the current signal necessary to test the distance element at an angle of 38.97°.

First, the new desired impedance angle (38.97°) is 45° less than the original test impedance angle (83.97°). Add 45° to the angle of I_{TEST1}.

$$\begin{aligned}
\angle I_{TEST2} &= \angle I_{TEST1} + 45^\circ \\
\angle I_{TEST2} &= -173.97^\circ + 45^\circ \\
\angle I_{TEST2} &= -128.97^\circ
\end{aligned}$$

Calculate the magnitude of I_{TEST2} using Equation 7.11.

$$\begin{aligned}
|I_{TEST2}| &= \frac{|I_{TEST1}|}{\cos(\text{Line Impedance Angle} - \text{New Test Impedance Angle})} \text{ amps, sec} \\
|I_{TEST2}| &= \frac{2.5}{\cos(83.97^\circ - 38.97^\circ)} \text{ amps} \\
|I_{TEST2}| &= \frac{2.5}{\cos(45^\circ)} \text{ amps} \\
|I_{TEST2}| &= 3.54 \text{ amps}
\end{aligned} \quad \text{Equation 7.11}$$

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern

Ground Mho Distance Elements

The SEL-321 Relay includes up to four zones of mho ground distance protection. Enable the number of ground distance zones you would like to apply using the GMHOZ setting. You may set the ground distance elements to reach in the forward or reverse direction. The reach and direction of each zone is independent from the other zones. When a zone of phase distance protection is set to reach in one direction, the ground distance elements associated with that zone must be set to reach in the same direction. Reach is set in secondary ohms. The angle of maximum reach of the ground distance elements is defined by the Z1ANG setting and the zero-sequence current compensation factor for the zone under test.

Each zone has an instantaneous indication. For example, the Z3G element asserts without intentional time delay for A-G, B-G, and C-G faults within the Zone 3 mho or quadrilateral characteristic. Zones 2, 3, and 4 also include time delayed indication through elements Z2GT, Z3GT, and Z4GT. In addition, each individual phase-ground distance element provides an instantaneous indication for each zone. For example, the MAG1, MAG2, MAG3, and MAG4 elements provide instantaneous indication of A-G ground faults in each zone.

For general testing, use the instantaneous and time delayed elements that respond to any phase-ground fault within a given zone such as Z1G, Z2G, etc. You can record more detailed and specific test results using the instantaneous element associated with the faulted phase and zone under test.

There are a number of supervisory conditions that must be fulfilled before the relay allows a ground distance element to pick up. These supervisory conditions are described below.

Ground Distance Element Supervisory Conditions

Note: Unless otherwise indicated, all of the supervisory conditions listed below apply to the ground mho and ground quadrilateral distance elements.

Phase and Ground Nondirectional Overcurrent Elements, 50Ln and 50Gn

Each zone ground distance element is supervised by two nondirectional overcurrent elements, 50Gn and 50Ln, where n indicates the zone associated with the overcurrent element. For example, the relay may assert the Zone 3 A-ground distance element only if the A-phase current is greater than the 50L3 setting and the residual current is greater than the 50G3 setting.

Negative-Sequence Directional Element

The ground distance protection function is supervised by the negative-sequence directional element to provide improved directional security. Forward-reaching distance elements may not assert unless the 32QF element is asserted. Reverse-reaching distance elements may not assert unless the 32QR element is asserted.

Loss-of-Potential Logic

If ELOP = Y, Y1, or Y2 the relay supervises the ground distance element logic using the Internal Loss-of-Potential condition (ILOP). When ELOP = Y, Y1, or Y2 the relay disables the ground distance elements when a loss-of-potential is detected, regardless of other signals applied to the

relay. If you test the ground distance elements using low voltage signals, set ELOP = N to simplify the test.

Single-Pole Open Logic

In single-pole trip applications, the relay cannot properly polarize or operate the ground distance elements associated with an open breaker pole. The relay Single-Pole Open logic disables the ground distance element associated with an open breaker pole. For instance, if Pole A is open, the relay cannot operate the A-G ground mho distance elements. If any single-pole is open, the relay disables all ground quadrilateral distance elements. To simplify distance element tests, apply control voltage to any inputs assigned to perform the 52 auxiliary functions, or disable the Single-Pole Open logic by setting ESPO = N.

Three-Pole Open Logic

If significant pole-scatter occurs when a circuit breaker closes, sensitive ground distance elements may operate undesirably due to the unbalanced signals applied. The SEL-321 Relay disables the ground distance elements during Three-Pole Open conditions and for a short, settable time after the breaker closes. The time is set by the 3POD time delay settings. To simplify distance element tests, apply control voltage to any inputs assigned to perform the 52 auxiliary functions.

Ground Distance Element Disable Inputs

The SEL-321 Relay is equipped with ground distance element disabling inputs, PARA, PARB, and PARC. When a relay input assigned to one of these functions is asserted, the relay disables the ground distance elements associated with that phase. For instance, if Input 4 is assigned to PARA, each time Input 4 is asserted, all of the A-ground distance elements are disabled.

Ground Mho Distance Element Test Using Three Voltage Sources and One Current Source

Note: This test refers directly to the Zone 2 ground mho distance element, but may be applied to any other forward-reaching ground mho distance element zone. To test reverse-reaching zones, simply add 180° to the calculated test current phase angle. Verify correct operation of the 32QR element for the test voltage and current signals using Equation 7.2 in the Negative-Sequence Directional Element Test Procedure.

Step 1. Execute the SHOWSET command and verify the following relay settings: Z1MAG, Z1ANG, GMHOZ, DIR2, Z2MG, 50L2, 50G2, k0M, k0A, Z2F, and 50QF. The example relay settings use the following settings: Z1MAG = 7.8; Z1ANG = 83.97°; GMHOZ = 3; DIR2 = F; Z2MG = 9.36 Ω; 50L2 = 0.90; 50G2 = 0.60; k0M = 0.726; k0A = -3.69; Z2F = 0.77 Ω; 50QF = 0.5 amps secondary.

Execute the SET command and change the following settings. Change QUADZ to N and ELOP from Y to N. Changing the QUADZ setting prevents the relay ground quadrilateral distance elements from interfering with the test. Changing the ELOP setting prevents the Loss-of-Potential logic from blocking operation of the relay distance elements if the test signals fulfill Loss-of-Potential conditions.

Step 2. Select an output contact to indicate operation of the Z2G element. In this example we use the OUT7 output.

From Access Level 2, execute the **SET L n** command to configure Output 7 to close for assertion of the Z2G element.

```
=>>SET L 1 OUT7 <ENTER>
SELogic group 1

OUT7 =NA

? Z2G <ENTER>
OUT8 =32QR

? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. Type **Y <ENTER>** to accept those settings.

Connect output OUT7 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the voltage sources to the A-phase, B-phase, and C-phase to neutral relay voltage inputs. Connect the current source to the A-phase relay current input. Refer to the voltage and current connections shown in Figure 7.6 as an example.

Step 4. Select the magnitude of the test signals, I_A and V_A .

Table 7.4 summarizes the test quantities for the Zone 2 A-G ground distance element based upon the example relay settings.

Table 7.4: Test Quantities for Zone 2 Ground Mho Distance Element

Test Voltages	Test Current
$V_A = 40.4 \angle 0^\circ$ volts	$I_{TEST} = 2.5 \angle -82.42^\circ$ amps
$V_B = 67.0 \angle -120^\circ$ volts	
$V_C = 67.0 \angle 120^\circ$ volts	

The following text describes a hand calculation method you may use to calculate relay distance element voltage and current test signals. If you do not wish to review this information, go to Step 5.

You may want to use the Basic program ONEBUS to calculate distance element test quantities. A listing of this program is provided in *Appendix D*.

The relay ground distance elements operate based upon the magnitude of applied phase-ground impedance. The impedance calculation is supervised by the functions described. To effectively test the distance elements, select test signals that fulfill the impedance and supervisory requirements of the relay, but are within the ability of the test sources to produce accurately.

The Zone 2 ground distance element is forward-reaching in the example relay settings. Thus, it is supervised by the forward directional element 32QF, as well as the 50L2 and 50G2 phase and residual overcurrent elements. Applied phase current must exceed the 50L2 setting, applied residual current must exceed the 50G2 setting, and applied $3I_2$ must exceed the 50QF setting.

The 50L overcurrent elements operate based upon the magnitude of the phase current. Using the current connections shown in Figure 7.6, the magnitude of I_A is equal to the magnitude of the applied test current. With a 50L2 setting of 0.90 amps, 50L2 picks up when I_{TEST} is greater than 0.90 amps.

The 50G overcurrent elements operate based upon the magnitude of the residual current. Using the current connections shown in Figure 7.6, the magnitude of I_R is equal to the magnitude of the applied test current, I_A . With a 50G2 setting of 0.60 amps, 50G2 picks up when I_{TEST} is greater than 0.60 amps.

The 50QF negative-sequence overcurrent element operates based upon the magnitude of $3I_2$ applied. Using the current connections shown in Figure 7.6, we can calculate the magnitude of $3I_2$ applied based upon the magnitude of I_{TEST} .

$$\begin{aligned} I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\ 3 \cdot I_2 &= (I_A + a^2 \cdot I_B + a \cdot I_C) \\ I_A &= I_{TEST} \text{ and } I_B = I_C = 0, \text{ so:} \\ 3 \cdot I_2 &= I_{TEST} \end{aligned}$$

With a 50QF setting of 0.5 amps, 50QF picks up when I_{TEST} is greater than 0.5 amps.

Select the magnitude of I_A greater than the 50L2, 50G2, and 50QF settings, but less than the maximum current output capability of the current test source.

In this example, select $|I_{TEST}| = 2.5$ amps. This selection fulfills the supervisory overcurrent conditions described above.

The reach of the distance element under test in secondary ohms is defined by the element setting. In this case $Z2MG = 9.36 \Omega$. The impedance measured by the relay for a ground fault is determined by the faulted phase voltage, faulted phase current, and the residual current multiplied by the zero-sequence current compensation factor, $k0$. The SEL-321 Relay uses $k01M$ and $k01A$ settings to define the zero-sequence current compensation factor for Zone 1 ground distance elements. The $k0M$ and $k0A$ settings to define $k0$ for the remaining zones. The impedance measured by the relay ground mho distance element for a Zone 2 fault is defined by the following equation:

$$Z_{AG} = \frac{V_A}{I_A + k0 \cdot I_R} \quad \text{Equation 7.12}$$

Where: $k0 = k0M \angle k0A^\circ$

For a fault on a radial system and when testing a ground distance element using a single current source, $I_A = I_R$. In this case, Equation 7.12 can be simplified:

$$Z_{AG} = \frac{V_A}{I_A \cdot (1 + k_0)} \quad \text{Equation 7.13}$$

If we multiply both sides of Equation 7.13 by the quantity $(1 + k_0)$, the result is the impedance applied by the A-phase test signals, V_A and I_A .

$$Z_{AG} \cdot (1 + k_0) = \frac{V_A}{I_A} \quad \text{Equation 7.14}$$

Since we are testing the Zone 2 mho ground distance element, the intended value of $Z_{AG} = Z2MG = 9.36 \angle 0^\circ$. The angle of $Z2MG$ is equal to the angle of positive-sequence impedance, $Z1ANG$.

Because the element under test is not a Zone 1 element, the k_0 value is defined by the relay settings $k0M$ and $k0A$. When you test the relay Zone 1 ground elements, use $k01M$ and $k01A$ to define the magnitude and angle of k_0 .

Calculate the value of $Z_{AG} \cdot (1 + k_0)$ based upon the information above.

$$Z_{AG} \cdot (1 + k_0) = Z_{TEST} = Z2MG \cdot (1 + k0M \angle k0A) \quad \text{Equation 7.15}$$

$$\begin{aligned} Z_{TEST} &= 9.36 \angle 83.97^\circ (1 + 0.726 \angle -3.69^\circ) \\ Z_{TEST} &= 9.36 \angle 83.97^\circ (1.725 \angle -1.55^\circ) \\ Z_{TEST} &= 16.15 \angle 82.42^\circ \end{aligned}$$

I_A must lag V_A by the angle of Z_{TEST} to check the maximum reach of the element under test. With V_A applied at an angle of 0° , the angle of I_A is:

$$I_A = 2.5 \angle -82.42^\circ$$

Calculate the magnitude of V_A using Equation 7.16

$$\begin{aligned} V_A &= I_A \cdot Z_{TEST} \\ V_A &= 2.5 \angle -82.42^\circ \cdot 16.15 \angle 82.42^\circ \\ V_A &= 40.4 \angle 0.0^\circ \text{ volts secondary} \end{aligned} \quad \text{Equation 7.16}$$

Select $V_B = 67 \angle -120^\circ$ volts and $V_C = 67 \angle 120^\circ$ volts.

The ground distance elements are supervised by the negative-sequence directional element. It is important to check the negative-sequence quantities applied and verify that the 32QF element should assert allowing the forward-reaching distance element to operate. Calculate the magnitude and angle of negative-sequence voltage and current applied for the test quantities listed above. Then calculate the negative-sequence impedance, $Z2c$, applied using Equation 7.2 and compare $Z2c$ to the $Z2FT$ threshold which is a function of the $Z2F$ setting and $Z2m$.

$$V_2 = \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C)$$

$$I_2 = \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C)$$

$$Z2c = \frac{\text{Re}[V_2 \cdot (1 \angle Z1 \text{ANG}^\circ \cdot I_2)^*]}{|I_2|^2} \quad \text{Equation 7.2}$$

$$Z2m = \frac{|V_2|}{|I_2|}$$

$$Z2FT = 1.25 \cdot Z2F - 0.25 \cdot Z2m$$

Taking the test signals from Table 7.4.

$$V_A = 40.4V \angle 0^\circ$$

$$V_B = 67.0V \angle -120^\circ$$

$$V_C = 67.0V \angle 120^\circ$$

$$V_2 = \frac{1}{3} \cdot (40.4 \angle 0^\circ + 1 \angle 240^\circ \cdot 67.0 \angle -120^\circ + 1 \angle 120^\circ \cdot 67.0 \angle 120^\circ) \text{ volts}$$

$$V_2 = 8.88 \angle 180^\circ \text{ volts}$$

$$I_A = 2.5 \angle -82.42^\circ$$

$$I_B = 0.0 \angle 0.0^\circ$$

$$I_C = 0.0 \angle 0.0^\circ$$

$$I_2 = \frac{1}{3} \cdot (2.5 \angle -82.42^\circ) \text{ amps}$$

$$I_2 = 0.83 \angle -82.42^\circ \text{ amps}$$

Using Equation 7.2 to calculate Z2, the result is:

$$Z2c = -10.66 \text{ ohms}$$

$$Z2m = 15.47 \text{ ohms}$$

$$Z2FT = 1.25 \cdot (0.77) - 0.25 \cdot (15.47)$$

$$Z2FT = -2.91 \text{ ohms}$$

The relay example Z2F setting is 0.77 Ω . Z2c applied (-10.66 Ω) is less than the Z2FT threshold (-2.91 Ω), therefore, the 32QF element asserts when these signals are applied. If Z2c applied is greater than the Z2FT threshold, select new test current and voltages using the steps outlined above.

Step 5. Turn on the voltage sources. Apply V_A , V_B , and V_C at the magnitudes and angles listed in Table 7.4. Turn on the current test source. Set the current angle to -82° . Slowly increase the magnitude of current applied until the Z2G element asserts, causing OUT7 to close. This occurs when current applied is approximately 2.5 amps.

You may wish to test the distance element characteristic at impedance angles other than the line positive-sequence impedance angle. To do this, you must adjust the magnitude and angle of I_{TEST} from the values shown in Table 7.4. As an example,

calculate the current signal necessary to test the distance element at an angle of 38.97°.

First, the new desired impedance angle (38.97°) is 45° less than the original test impedance angle (83.97°). Add 45° to the angle of I_{TEST1} .

$$\begin{aligned}\angle I_{TEST2} &= \angle I_{TEST1} + 45^\circ \\ \angle I_{TEST2} &= -173.97^\circ + 45^\circ \\ \angle I_{TEST2} &= -128.97^\circ\end{aligned}$$

Calculate the magnitude of I_{TEST2} using Equation 7.11.

$$\begin{aligned}|I_{TEST2}| &= \frac{|I_{TEST1}|}{\cos(\text{Line Impedance Angle} - \text{New Test Impedance Angle})} \text{ amps, sec} \\ |I_{TEST2}| &= \frac{2.5}{\cos(83.97^\circ - 38.97^\circ)} \text{ amps} \\ |I_{TEST2}| &= \frac{2.5}{\cos(45^\circ)} \text{ amps} \\ |I_{TEST2}| &= 3.54 \text{ amps}\end{aligned} \quad \text{Equation 7.11}$$

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Ground Quadrilateral Distance Element Reactive Reach Test Using Three Voltage Sources and One Current Source

Note: This test refers directly to the Zone 2 ground quadrilateral distance element, but may be applied to any other forward-reaching ground quadrilateral distance element zone. To test reverse-reaching zones, simply add 180° to the calculated test current phase angle. Verify correct operation of the 32QR element for the test voltage and current signals using Equation 7.2 in the Negative-Sequence Directional Element Test Procedure of this section.

Step 1. Execute the SHOWSET command and verify the following relay settings: Z1MAG, Z1ANG, QUADZ, DIR2, XG2, RG2, 50L2, 50G2, k0M, k0A, T, Z2F, and 50QF. The example relay settings use the following settings: Z1MAG = 7.8 Ω; Z1ANG = 83.97°; QUADZ = 3; DIR2 = F; XG2 = 9.36 Ω; RG2 = 5.00 Ω; 50L2 = 0.90; 50G2 = 0.60; k0M = 0.726; k0A = -3.69; T = 0.00; Z2F = 0.77; 50QF = 0.5 amps secondary.

Execute the SET command and change the following settings. Change GMHOZ to N, QUADZ to 3, XG1 = 6.24, XG2 = 9.36, XG3 = 1.87, RG1 = 2.5, RG2 = 5.0, and RG3 = 6.0. Changing the GMHOZ setting prevents the relay ground mho distance elements from interfering with the test.

Step 2. Select output contacts to indicate operation of the Z2G element. In this example we use the OUT7 output.

From Access Level 2, execute the SET L n command to configure Output 7 to close for assertion of the Z2G element.

```
=>>SET L 1 OUT7 <ENTER>
SELogic group 1

OUT7 =NA

? Z2G <ENTER>
OUT8 =32QR

? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. Type **Y <ENTER>** to accept those settings.

Connect output OUT7 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the voltage sources to the A-phase, B-phase, and C-phase to neutral relay voltage inputs. Connect the current source to the A-phase relay current input. Refer to the voltage and current connections shown in Figure 7.6 as an example.

Step 4. Select the magnitude of the test signals, I_A and V_A .

Table 7.5 summarizes the test quantities for the Zone 2 A-G ground quadrilateral distance element based upon the example relay settings.

Table 7.5: Test Quantities for Zone 2 Ground Quadrilateral Distance Element: Reactive Reach

Test Voltages	Test Current
$V_A = 40.4 \angle 0^\circ$ volts	$I_{TEST} = 2.49 \angle -90.0^\circ$ amps
$V_B = 67.0 \angle -120^\circ$ volts	
$V_C = 67.0 \angle 120^\circ$ volts	

The following text describes a hand calculation method you may use to calculate relay distance element voltage and current test signals. If you do not wish to review this information, go to Step 5.

The relay ground distance elements operate based upon the magnitude of applied phase-ground impedance. The impedance calculation is supervised by the functions described. To effectively test the distance elements, select test signals that fulfill the impedance and supervisory requirements of the relay, but are within the ability of the test sources to produce accurately.

The reactive reach of the quadrilateral distance element under test is defined by the XG2 element setting. In this case $XG2 = 9.36$ secondary ohms. The impedance measured by the relay for a ground fault is determined by the faulted phase voltage, faulted phase current, and the residual current multiplied by the zero-sequence current compensation factor, k_0 . The SEL-321 Relay uses k_{01M} and k_{01A} settings to define the zero-sequence current compensation factor for Zone 1 ground distance elements and the k_{0M} and k_{0A} settings to define that factor for the remaining zones.

The reactance measured by the relay ground quadrilateral distance element for a Zone 2 fault is defined by the following equation:

$$X_{AG} = \frac{\text{Im}(V_A (I_R \cdot 1 \angle T^\circ)^*)}{\text{Im}(1 \angle Z1 \text{ANG} (I_A + k0 \cdot I_R) (I_R \cdot 1 \angle T^\circ)^*)} \quad \text{Equation 7.17}$$

Where:

$$k0 = k0M \angle k0A^\circ$$

T = Non-homogenous system compensation setting

For a fault on a radial system and when testing a ground distance element using a single current source, $I_A = I_R$. Equation 7.17 can be simplified:

$$X_{AG} = \frac{\text{Im}(V_A (I_A \cdot 1 \angle T^\circ)^*)}{\text{Im}(1 \angle Z1 \text{ANG} \cdot (1 + k0) \cdot I_A \cdot (I_A \cdot 1 \angle T^\circ)^*)} \quad \text{Equation 7.18}$$

When $T = 0^\circ$, as it does in the example relay settings, Equation 7.18 can be further Simplified using the following identity:

$$\begin{aligned} |I_A|^2 &= (I_A) \cdot (I_A)^* \\ X_{AG} &= \frac{\text{Im}(V_A (I_A)^*)}{\text{Im}(1 \angle Z1 \text{ANG} |I_A|^2 (1 + k0))} \end{aligned} \quad \text{Equation 7.19}$$

If we select a value for V_A , it then becomes possible to use Equation 7.19 to calculate the magnitude and angle of I_A required to test the Zone 2 ground quadrilateral distance element reactive reach.

For the example, select $V_A = 40.0 \angle 0^\circ$. To simplify the reactance calculation, select the angle of $I_A = -90^\circ$ with respect to V_A . For the Zone 2 element, $XG2 = 9.36 \Omega$, $Z1 \text{ANG} = 83.97^\circ$, and $k0 = 0.726 \angle -3.69^\circ$.

$$9.36 = \frac{\text{Im}(40.0 \angle 0^\circ |I_A| \angle 90^\circ)}{|I_A|^2 \cdot \text{Im}(1 \angle 83.97^\circ (1 + 0.726 \angle -3.69^\circ))}$$

The result of computing the imaginary portion of $V_A \cdot I_A^*$ when I_A lags V_A by 90° is:

$$\text{Im}(V_A \angle 0^\circ \cdot I_A \angle 90^\circ) = |V_A| \cdot |I_A|$$

Substituting this into the equation above yields:

$$9.36 = \frac{40.0 \cdot |I_A|}{|I_A|^2 \cdot (1.71)}$$

Solving for the magnitude of I_A yields:

$$\begin{aligned} |I_A| &= \frac{40.0}{(9.39) \cdot (1.71)} \\ |I_A| &= 2.49 \text{ amps} \end{aligned}$$

The Zone 2 ground distance element is forward-reaching in the example relay settings. Thus, it is supervised by the forward directional element 32QF, as well as the 50L2 and 50G2 phase and residual overcurrent elements. Applied phase current must exceed the 50L2 setting, applied residual current must exceed the 50G2 setting, and applied 3I₂ must exceed the 50QF setting.

The 50L overcurrent elements operate based upon the magnitude of the phase current. Using the current connections shown in Figure 7.6, the magnitude of I_A is equal to the magnitude of the applied test current.

With a 50L2 setting of 0.90 amps, 50L2 picks up when I_{TEST} is greater than 0.90 amps.

The 50G overcurrent elements operate based upon the magnitude of the residual current. Using the current connections shown in Figure 7.6, the magnitude of I_R is equal to the magnitude of the applied test current.

With a 50G2 setting of 0.60 amps, 50G2 picks up when I_{TEST} is greater than 0.60 amps.

The 50QF negative-sequence overcurrent element operates based upon the magnitude of 3I₂ applied. Using the current connections shown in Figure 7.6, calculate the magnitude of 3I₂ applied based upon the magnitude of I_{TEST}.

$$\begin{aligned} I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\ 3 \cdot I_2 &= (I_A + a^2 \cdot I_B + a \cdot I_C) \\ I_A &= I_{TEST} \text{ and } I_B = I_C = 0, \text{ so:} \\ 3 \cdot I_2 &= I_{TEST} \end{aligned}$$

With a 50QF setting of 0.5 amps, 50QF picks up when I_{TEST} is greater than 0.5 amps.

We calculated $|I_A| = |I_{TEST}| = 2.49$ amps which satisfies the supervisory overcurrent conditions described above.

Select $V_B = 67 \angle -120^\circ$ volts and $V_C = 67 \angle 120^\circ$ volts.

The ground distance elements are supervised by the negative-sequence directional element. Check the negative-sequence quantities applied and verify that the 32QF element should assert. Calculate the magnitude and angle of negative-sequence voltage and current applied for the test quantities listed above. Then calculate the negative-sequence impedance, Z_{2c}, applied using Equation 7.2.

$$\begin{aligned} V_2 &= \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C) \\ I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\ Z_2 &= \frac{\text{Re}[V_2 \cdot (1 \angle ZIANG^\circ \cdot I_2)^*]}{|I_2|^2} \\ Z_{2m} &= \frac{|V_2|}{|I_2|} \end{aligned} \quad \text{Equation 7.2}$$

$$Z2FT = 1.25 \cdot Z2F - 0.25 \cdot Z2m$$

Equation 7.4

Taking the test signals from Table 7.5.

$$\begin{aligned} V_A &= 40.4V \angle 0^\circ \\ V_B &= 67.0V \angle -120^\circ \\ V_C &= 67.0V \angle 120^\circ \end{aligned}$$

$$\begin{aligned} V_2 &= \frac{1}{3} \cdot (40.4 \angle 0^\circ + 1 \angle 240^\circ \cdot 67.0 \angle -120^\circ + 1 \angle 120^\circ \cdot 67.0 \angle 120^\circ) \text{ volts} \\ V_2 &= 9.0 \angle 180^\circ \text{ volts} \end{aligned}$$

$$\begin{aligned} I_A &= 2.49A \angle -90.0^\circ \\ I_B &= 0.0A \angle 0.0^\circ \\ I_C &= 0.0A \angle 0.0^\circ \end{aligned}$$

$$\begin{aligned} I_2 &= \frac{1}{3} \cdot (2.49 \angle -90.0^\circ) \text{ amps} \\ I_2 &= 0.83 \angle -90.0^\circ \text{ amps} \end{aligned}$$

Using Equation 7.2 to calculate Z2c, the result is:

$$\begin{aligned} Z2c &= -10.84 \text{ ohms} \\ Z2m &= 10.84 \text{ ohms} \\ Z2FT &= 1.25 \cdot (0.77) - 0.25 \cdot (10.84) \\ Z2FT &= -4.46 \text{ ohms} \end{aligned}$$

The relay example Z2F setting is 0.77 Ω . Z2c applied (-10.84 Ω) is less than the Z2FT threshold (-4.46 Ω), therefore, the 32QF element asserts when these signals are applied. If Z2c applied is greater than the Z2FT setting, select new test current and voltages using the steps outlined above.

Step 5. Turn on the voltage sources. Apply V_A , V_B , and V_C at the magnitudes and angles listed in Table 7.5. Turn on the current test source. Set the current angle to -90.0°. Slowly increase the magnitude of current applied until the Z2G element asserts, causing OUT7 to close. This occurs when current applied is approximately 2.49 amps.

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

Ground Quadrilateral Distance Element Resistive Reach Test Using Three Voltage Sources and One Current Source

Note: This test refers directly to the Zone 2 ground quadrilateral distance element, but may be applied to any other forward-reaching ground quadrilateral distance element zone. To test reverse-reaching zones, simply add 180° to the calculated test current phase angle. Verify correct operation of the 32QR element for the test voltage and current signals using Equation 7.2 in the Negative-Sequence Directional Element Test Procedure.

Step 1. Execute the SHOWSET command and verify the following relay settings: Z1MAG, Z1ANG, QUADZ, DIR2, XG2, RG2, 50L2, 50G2, k0M, k0A, T, Z2F, and 50QF. The example relay settings use the following settings: Z1MAG = 7.8 Ω; Z1ANG = 83.97°; QUADZ = 3; DIR2 = F; XG2 = 9.36 Ω; RG2 = 5.00 Ω; 50L2 = 0.90; 50G2 = 0.60; k01M = 0.726; k01A = -3.69; T = 0.00; Z2F = 0.77 Ω; 50QF = 0.5 amps secondary.

Execute the **SET** command and change the following settings. Change GMHOZ to N, QUADZ to 3, and ELOP from Y to N. Changing the GMHOZ setting prevents the relay ground mho distance elements from interfering with the test. Changing the ELOP setting prevents the Loss-of-Potential logic from blocking operation of the relay distance elements if the test signals fulfill Loss-of-Potential conditions.

Step 2. Select an output contact to indicate operation of the Z2G element. In this example use the OUT7 output.

From Access Level 2, execute the **SET L n** command to configure Output 7 to close for assertion of the Z2G element.

```
=>>SET L 1 OUT7 <ENTER>
SELogic group 1

OUT7 =NA

? Z2G <ENTER>
OUT8 =32QR

? END <ENTER>
```

After you type **END <ENTER>** to end the set procedure, the relay displays the current logic settings. Type **Y <ENTER>** to accept those settings.

Connect output OUT7 to the sense input of your test set, an ohmmeter, or some other contact sensing device.

Step 3. Connect the voltage sources to the A-phase, B-phase, and C-phase to neutral relay voltage inputs. Connect the current source to the A-phase relay current input. Refer to the voltage and current connections shown in Figure 7.6 as an example.

Step 4. Select the magnitude of the test signals, I_A and V_A .

Table 7.6 summarizes the test quantities for the Zone 2 A-G ground quadrilateral distance element based upon the example relay settings.

Table 7.6: Test Quantities for Zone 2 Ground Quadrilateral Distance Element: Resistive Reach

Test Voltages	Test Current
$V_A = 40.0 \angle 0^\circ$ volts	$I_{TEST} = 8.0 \angle 0.0^\circ$ amps
$V_B = 67.0 \angle -120^\circ$ volts	
$V_C = 67.0 \angle 120^\circ$ volts	

The following text describes a hand calculation method you may use to calculate relay distance element voltage and current test signals. If you do not wish to review this information, go to Step 5.

The relay ground distance elements operate based upon the magnitude of applied phase-ground impedance. The impedance calculation is supervised by the functions described. To effectively test the distance elements, select test signals that fulfill the impedance and supervisory requirements of the relay, but are within the ability of the test sources to produce accurately.

The resistive reach of the quadrilateral distance element under test is defined by the RG2 element setting. In this case $RG2 = 5.00$ secondary ohms. The impedance measured by the relay for a ground fault is determined by the faulted phase voltage, faulted phase current, and the residual current multiplied by the zero-sequence current compensation factor, $k0$. The SEL-321 Relay uses $k01M$ and $k01A$ settings to define the zero-sequence current compensation factor for all zones.

The reactance measured by the relay ground quadrilateral distance element for a Zone 2 fault is defined by the following equation:

$$R_{AG} = \frac{\text{Im}(V_A ((I_A + k0 \cdot I_R) \cdot 1 \angle Z1 \text{ANG})^*)}{\text{Im}[(\frac{3}{2} \cdot (I_{A2} + I_{A0})) (I_A + k0 \cdot I_R) \cdot 1 \angle Z1 \text{ANG})^*]} \quad \text{Equation 7.20}$$

Where:

$k0 = k01M \angle k01A^\circ$ for Zone 1, 2, 3, and 4

I_{A2} = negative-sequence current flowing in A-phase for the fault

I_{A0} = zero-sequence current flowing in A-phase for the fault

For a fault on a radial system with no load and when testing a ground distance element using a single current source, $I_A = I_R$, $I_{A2} = I_A/3$, and $I_{A0} = I_A/3$. Equation 7.20 can be simplified:

$$R_{AG} = \frac{\text{Im}(V_A \cdot (I_A \cdot (1 + k0) \cdot 1 \angle Z1 \text{ANG})^*)}{\text{Im}(I_A \cdot (I_A \cdot (1 + k0) \cdot 1 \angle Z1 \text{ANG})^*)} \quad \text{Equation 7.21}$$

Select a value for V_A . Then it is possible to use Equation 7.21 to calculate the magnitude and angle of I_A required to test the Zone 2 ground quadrilateral distance element resistive reach.

For the example, select $V_A = 40.0 \angle 0^\circ$. To simplify the resistance calculation, select the angle of $I_A = 0^\circ$. For the Zone 2 element, $RG2 = 5.00 \Omega$, $\angle Z1ANG = 83.97^\circ$, and $k01 = 0.726 \angle -3.69^\circ$.

$$\begin{aligned}
 5.00 &= \frac{\text{Im}(40.0 \angle 0^\circ (I_A \cdot (1 + 0.726 \angle -3.69^\circ) \cdot 1 \angle 83.97^\circ)*)}{\text{Im}(I_A \cdot (I_A \cdot (1 + 0.726 \angle -3.69^\circ) \cdot 1 \angle 83.97^\circ)*)} \\
 5.00 &= \frac{\text{Im}(40.0 \angle 0^\circ (I_A \cdot (1.725 \angle -1.55^\circ) \cdot 1 \angle 83.97^\circ)*)}{\text{Im}(I_A \cdot (I_A \cdot (1.725 \angle -1.55^\circ) \cdot 1 \angle 83.97^\circ)*)} \\
 5.00 &= \frac{\text{Im}(40.0 \angle 0^\circ (I_A \cdot (1.725 \angle 82.42^\circ)*)}{\text{Im}(I_A \cdot (I_A \cdot (1.725 \angle 82.42^\circ)*)}
 \end{aligned}
 \tag{Equation 7.22}$$

Because the angle of I_A equals 0° , simplify the equation above:

$$5.00 = \frac{40.0 \cdot |I_A| \cdot \text{Im}(1.725 \angle -82.42^\circ)}{|I_A|^2 \cdot \text{Im}(1.725 \angle -82.42^\circ)}$$

Canceling the imaginary terms, and rearranging the equation to calculate $|I_A|$ yields:

$$\begin{aligned}
 |I_A| &= \frac{40.0}{5.0} \\
 |I_A| &= 8.0 \text{ amps}
 \end{aligned}$$

The Zone 2 ground distance element is forward-reaching in the example relay settings. Thus, it is supervised by the forward directional element 32QF, as well as the 50L2 and 50G2 phase and residual overcurrent elements. Applied phase current must exceed the 50L2 setting, applied residual current must exceed the 50G2 setting, and applied 3I2 must exceed the 50QF setting.

The 50L overcurrent elements operate based upon the magnitude of the phase current. Using the current connections shown in Figure 7.6, the magnitude of I_A is equal to the magnitude of the applied test current.

With a 50L2 setting of 0.90 amps, 50L2 picks up when I_{TEST} is greater than 0.90 amps.

The 50G overcurrent elements operate based upon the magnitude of the residual current. Using the current connections shown in Figure 7.6, the magnitude of I_R is equal to the magnitude of the applied test current.

With a 50G2 setting of 0.60 amps, 50G2 picks up when I_{TEST} is greater than 0.60 amps.

The 50QF negative-sequence overcurrent element operates based upon the magnitude of $3I_2$ applied. Using the current connections shown in Figure 7.6, calculate the magnitude of $3I_2$ applied based upon the magnitude of I_{TEST} .

$$\begin{aligned}
I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\
3 \cdot I_2 &= (I_A + a^2 \cdot I_B + a \cdot I_C) \\
I_A &= I_{\text{TEST}} \text{ and } I_B = I_C = 0, \text{ so:} \\
3 \cdot I_2 &= I_{\text{TEST}}
\end{aligned}$$

With a 50QF setting of 0.5 amps, 50QF picks up when I_{TEST} is greater than 0.5 amps.

We calculated $|I_A| = |I_{\text{TEST}}| = 8.0$ amps which satisfies the supervisory overcurrent conditions described above.

Select $V_B = 67\angle -120^\circ$ volts and $V_C = 67\angle 120^\circ$ volts.

The ground distance elements are supervised by the negative-sequence directional element. Check the negative-sequence quantities applied and verify that the 32QF element should assert. Calculate the magnitude and angle of negative-sequence voltage and current applied for the test quantities listed above. Then calculate the negative-sequence impedance, Z2c, applied using Equation 7.2.

$$\begin{aligned}
V_2 &= \frac{1}{3} \cdot (V_A + a^2 \cdot V_B + a \cdot V_C) \\
I_2 &= \frac{1}{3} \cdot (I_A + a^2 \cdot I_B + a \cdot I_C) \\
Z2c &= \frac{\text{Re}[V_2 \cdot (1\angle Z1\text{ANG}^\circ \cdot I_2)^*]}{|I_2|^2}
\end{aligned}
\tag{Equation 7.2}$$

$$Z2m = \frac{|V_2|}{|I_2|}$$

$$Z2FT = 1.25 \cdot Z2F - 0.25 \cdot Z2m \tag{Equation 7.4}$$

Taking the test signals from Table 7.6.

$$\begin{aligned}
V_A &= 40.0V\angle 0^\circ \\
V_B &= 67.0V\angle -120^\circ \\
V_C &= 67.0V\angle 120^\circ
\end{aligned}$$

$$\begin{aligned}
V_2 &= \frac{1}{3} \cdot (40.0\angle 0^\circ + 1\angle 240^\circ \cdot 67.0\angle -120^\circ + 1\angle 120^\circ \cdot 67.0\angle 120^\circ) \text{ volts} \\
V_2 &= 9.0\angle 180^\circ \text{ volts}
\end{aligned}$$

$$\begin{aligned}
I_A &= 8.0\angle 0.0^\circ \\
I_B &= 0.0\angle 0.0^\circ \\
I_C &= 0.0\angle 0.0^\circ
\end{aligned}$$

$$\begin{aligned}
I_2 &= \frac{1}{3} \cdot (8.0\angle 0.0^\circ) \text{ amps} \\
I_2 &= 2.67\angle 0.0^\circ \text{ amps}
\end{aligned}$$

Using Equation 7.2 to calculate Z2c, the result is:

$$Z2c = -3.37 \text{ ohms}$$

$$Z2m = 3.37 \text{ ohms}$$

$$Z2FT = 1.25 \cdot (0.77) - 0.25 \cdot (3.37)$$

$$Z2FT = 0.12 \text{ ohms}$$

The relay example Z2F setting is 0.77 Ω . Z2c applied (-3.37 Ω) is less than the Z2FT threshold (0.12 Ω), therefore, the 32QF element should assert when these signals are applied. If Z2c applied is greater than the Z2FT threshold, select new test current and voltages using the steps outlined above.

Step 5. Turn on the voltage sources. Apply V_A , V_B , and V_C at the magnitudes and angles listed in Table 7.6. Turn on the current test source. Set the current angle to 0.0°. Slowly increase the magnitude of current applied until the Z2G element asserts, causing OUT7 to close. This occurs when current applied is approximately 8.0 amps.

Note: As you perform this test, other protection elements may assert, causing the relay to close other output contacts and assert relay targets. This is normal and is not a cause for concern.

TROUBLESHOOTING TEST RESULTS

The following information is intended to help you troubleshoot relay tests if the relay does not perform as you expected.

<u>Symptom:</u>	<u>What to check:</u>
Incorrect Targets	<ul style="list-style-type: none">• Check the relay event report. Determine the asserted elements at the instant the TRIP output was asserted.• Verify the ac connections by plotting currents and voltages from event report data.• Verify the MTU, MTCS, and MTO settings to ensure the appropriate elements are enabled to trip.• Verify the TULO setting. If a trip occurs and does not unlatch following clearance of the fault, new faults do not generate new targets. You may need to turn off ac current applied to the relay, deassert 52A inputs, assert the External Trip Unlatch Input, (EXTUL), or press the Target Reset button.

Symptom:

What to check:

Incorrect Tripping

- Check the current and voltage connections by applying small signals to the connected current and voltage inputs. Trigger an event report using the TRIGGER command. Plot the magnitude and angle of measured currents and voltages.
- Check the MTU, MTCS, and MTO settings to determine which elements are enabled to trip.
- Check the output logic equation settings to determine which outputs are enabled to trip.
- Check the settings of elements that are enabled to trip.
- Check the settings of elements that supervise elements that are enabled to trip.

Incorrect Distance
Element Characteristic
Shape

- Check the voltage and current connections by applying small signals to the connected current and voltage inputs. Trigger an event report using the TRIGGER command. Plot the magnitude and angle of measured currents and voltages.
- Verify the distance element settings, including Zone 1 Extension logic settings.
- Verify the supervisory overcurrent element settings which apply to the element under test: 50PP overcurrent elements supervise the phase distance elements; 50G and 50L overcurrent elements supervise the ground mho and quadrilateral distance elements.
- Verify the negative-sequence directional element settings. 32QF supervises forward-reaching phase and ground distance elements. 32QR supervises reverse-reaching phase and ground distance elements.
- Verify the Loss-of-Potential (LOP) logic and element settings. If ELOP = Y, Y1, or Y2, the relay blocks operation of the distance elements when LOP conditions are detected. If ELOP = Y, LOP conditions are defined by the 50M, 59QL, 59PL, 50QF, and 50QR settings. If ELOP = Y1 or Y2, LOP conditions are determined automatically by advanced LOP logic.
- The relay Single- and Three-Pole Open logic functions block certain phase and ground distance elements when those conditions are detected. Verify the 3POD and SPOD time delay settings and review event report data to determine if these functions are interfering with your test.
- The Load-Encroachment function blocks operation of the relay phase distance elements if measured positive-sequence impedance is within a defined load characteristic. Verify your Load-Encroachment logic settings and review event report data to determine if this function is interfering with your phase distance element test.

Symptom:

Incorrect Contact
Operation

What to check:

- Check the logic equation settings to determine which elements are enabled to operate the contact.
- Check the event report to determine which elements asserted during the event.
- Check the connections and test signals to ensure that the appropriate signals were applied to cause the element under test to assert.

RELAY TROUBLESHOOTING

Inspection Procedure

Complete the following procedure before disturbing the system. After you finish the inspection, proceed to the Troubleshooting Procedure.

Step 1. Measure and record the power supply voltage at the power input terminals.

Step 2. Check to see that the power is on. Do not turn the relay off.

Step 3. Measure and record the voltage at all control inputs.

Step 4. Measure and record the state of all output relays.

Troubleshooting Procedure

All Front Panel LEDs Dark

1. Relay power switch is in “OFF” position.
2. Input power not present.
3. Blown fuse.
4. Self-test failure.

Cannot See Characters on Relay LCD Screen

1. Front panel connector cable is unhooked.
2. Relay is de-energized or turned off.
3. LCD contrast is out of adjustment. Use the steps below to adjust the contrast.

Press the **TARGET RESET** button to perform an LED lamp test. During the lamp test, the relay illuminates all 16 front panel LEDs for about one second. The relay also turns on the LCD back lighting.

Locate the contrast adjust hole in the front panel below the **INST LED**.

Insert a small screwdriver in this hole to adjust the contrast. Turn clockwise to decrease contrast and counter-clockwise to increase contrast.

Relay Does Not Respond to Commands From Device Connected to Serial Port

1. Communications device not connected to system.
2. Relay or communications device at incorrect baud rate or other communication parameter incompatibility, including cabling error.
3. System is processing event record. Wait several seconds.
4. System is attempting to transmit information, but cannot due to handshake line conflict. Check communications cabling.
5. System is in the XOFF state, halting communications. Type <CTRL>Q to put system in XON state.

Tripping Output Relay Remains Closed Following Fault

1. Auxiliary breaker contact inputs improperly wired.
2. Improper Trip Unlatch Logic Setting.
3. Output relay contacts welded closed.

No Prompting Message Issued to Terminal upon Power-Up

1. Terminal not connected to relay.
2. Terminal improperly connected to relay.
3. Incorrect terminal serial communications protocol (baud rate, parity, stop elements).
4. Main board failure.

System Does Not Respond to Faults

1. Relay improperly set.
2. Improper test source settings.
3. PT or CT input cable wiring error.
4. Analog input cable between transformer secondary and main board loose or defective.
5. Failed relay self-test.

Terminal Displays Meaningless Characters

1. Serial communications protocol (baud rate, parity, stop elements) set incorrectly.

RELAY CALIBRATION

The SEL-321 Relay is factory calibrated to a very high degree of accuracy. If you suspect that the relay is out of calibration, please contact the factory. We can provide instructions for returning the relay for factory recalibration.

FIRMWARE UPGRADES

SEL may occasionally offer firmware upgrades to improve the performance of your relay. These instructions explain how to install new firmware.

The modifications require that you power down the relay, remove its front panel, pull out the drawout unit, exchange one or more integrated circuit (IC) chips, and reassemble the relay. If you do not wish to perform the modifications yourself, we can assist you. Simply return the relay and integrated circuit chips to us. We will install the new chips and return the unit to you within a few days.



CAUTION

This procedure requires that you handle electrostatic discharge sensitive components. If your facility is not equipped to work with these components, we recommend that you return the relay to SEL for firmware installation.

Firmware Upgrade Instructions

- Step 1.** Connect a computer or terminal to the relay serial communications port and enter Access Level 2. Execute the **SHOWSET C** and **SHOWSET F** commands, and record all displayed data for possible future recalibration. Execute the **QUIT** command to leave Access Level 2 and return to Access Level 0.
- Step 2.** If the relay is in service, disable its breaker control functions. Turn off control power to the relay. Remove all communications cables from the front- and rear-panel communications ports. Remove the cable from the IRIG-B input, if one is installed.
- Step 3.** Remove the relay front panel by unscrewing the five front-panel screws. Carefully lift the front panel up and out and then disconnect the front-panel communications cables (P8 FP and P9 INTERFACE BUS) from the relay main board. With the front panel removed, you can see the aluminum drawout trays. The main board is attached to the top drawout tray. The power supply and transformer assembly are attached to the bottom of the relay chassis. The relay interface circuit board trays lie between the main board drawout assembly (above), and the power supply and input transformers (below).
- Step 4.** Disconnect P12 PWR SUPPLY and P13 SIGNAL INPUTS from the front of the main board drawout assembly.
- Step 5.** Remove the main board drawout assembly (upper tray) by pulling the nylon extractors on the front corners of the drawout tray. (Be careful not to subject cable assemblies to unusual mechanical stress or strain as the drawout assembly may snag the cable assemblies upon drawout removal or replacement.) You should be able to

remove the assembly with your fingers. Because Steps 6 and 7 involve handling devices and assemblies sensitive to ESD, perform these steps at an ESD-safe workstation. This will help prevent possible damage by ESD.

- Step 6.** Note the orientation of the ICs to be replaced. (The orientation mark is typically a half-circle indentation in one end of the IC.) Use an IC removal tool or a small screwdriver to pry the indicated ICs from their sockets, being careful not to bend the IC pins or damage adjacent components.
- Step 7.** Carefully place the new ICs in the appropriate sockets. Check the orientation of the ICs. Be sure that each IC is in its corresponding socket. Look for IC pins that are bent under or did not enter a socket hole.



CAUTION

Verify proper orientation of the replaced ICs before reassembling the relay. Energizing the relay with an IC reversed irrecoverably damages the IC. If you mistakenly reenergize the relay with an IC reversed, do not place the relay in service using those ICs, even if you correct the orientation.

- Step 8.** Slide the drawout assembly into the relay chassis. Using your fingers, push the assembly in until it seats properly and the extractor levers are at their home positions. Reconnect P12 PWR SUPPLY and P13 SIGNAL INPUTS cables to the receivers on the front of the drawout assembly. Reconnect the P8 FP and P9 INTERFACE BUS cables leading from the front panel to the relay main board. Replace the relay front panel.

- Step 9.** With breaker control disabled, turn relay power on. If the relay front panel displays an INVALID message (i.e., GRP SET INVALID), Group logic and Global settings will need to be validated. Connect a computer or terminal set to 2400 baud, 8 data bits, 1 stop bit to a relay serial communications port and enter Access Level 2. Execute the **SHOWSET** for all groups and the **SHOWSET G** commands.

If a setting named VALID or LOGVAL is displayed, it will have a value of N. This signifies that default settings have been loaded. Execute the **SET G** command to enter the correct global settings for your application, and set VALID to Y. Note that if VALID is Y, it is no longer displayed. Execute the **SET 1** command to enter the correct group settings for your application, and set VALID and LOGVAL to Y.

- Step 10.** Execute the **SHO F** command and review displayed data. Confirm that the I/O board settings match those displayed in Step 1. If any I/O board settings do not match, you must enter the correct settings. Note that some default settings may have changed.

For example, if the output board configuration settings (IOBRD1 and/or IOBRD2) do not match the number of output contacts on your relay, you must change the output board configuration setting. To change the output board configuration setting, you must enter the Calibration access level by executing the **CAL** command. The password for Calibration access level is **CLARKE**.

Execute the **SET F** command to change the board configuration settings. Change the IOBRD1 and/or the IOBRD2 (if equipped with a second output board) settings to match the output board configuration. Set IOBRD1 = 8 for an 8 contact output board

configuration, IOBRD1 = 12 for a 12 contact output board configuration, and IOBRD1 = 16 for a 16 contact output board configuration. Enter the output board configuration setting for IOBRD2 if the relay is equipped with a second output board.

Note that IOBRD1 refers to the interface board terminating on relay terminals 201 through 240. IOBRD2 refers to the interface board terminating on relay terminals 301 through 340.

Execute the **SET L 1** command to enter the correct SELOGIC control equations for your application. Execute the **COPY** command or the **SET** and **SET L** commands to enter settings for each of the remaining groups (six total).

Execute the **STATUS**, **METER**, and **TRIGGER** commands to ensure that all functions are operational. Set and record your Access Level 1, Breaker Access Level, and Access Level 2 passwords and the date and time.

- Step 11.** With relay communications still established and at Access Level 2, execute the **SHOWSET C** command and review displayed data. If data is identical to previously recorded data of Step 1, you may execute the **QUIT** command, and the relay is ready for your commissioning procedure. If, however, any channel gains are different, you must reenter the previously recorded values by executing the **SET C** command (similar to group settings procedure). Make sure **VALID = Y** (Note: **VALID** will only be present in the settings if defaults have been reloaded). After this procedure is completed and changes have been saved, execute the **QUIT** command. The relay is now ready for your commissioning procedure.
- Step 12.** If a new serial number label is included with the upgrade, attach the serial number label so the old label is covered.
- Step 13.** If you have any questions, please do not hesitate to telephone us for assistance.

FACTORY ASSISTANCE

The employee-owners of Schweitzer Engineering Laboratories are dedicated to making electric power safer, more reliable, and more economical.

We appreciate your interest in SEL products, and we are committed to making sure you are satisfied. If you have any questions, please contact us at:

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2350 NE Hopkins Court
Pullman, WA USA 99163-5603
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We provide prompt, courteous, and professional service.

We appreciate receiving any comments and suggestions about new products or product improvements that would help us make your job easier.

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APPENDIX A: FIRMWARE VERSIONS IN THIS MANUAL

This manual covers SEL relays that contain firmware bearing the part numbers and revision numbers shown in the following three tables (most recent firmware listed at top of each table). The first table covers the SEL-321-3 Relay. The subsequent tables cover the SEL-321-1 Relay.

For a detailed explanation of the FID refer to *Section 4: Event Reporting*.

DETERMINING THE FIRMWARE VERSION IN YOUR RELAY

To find the firmware revision number in your relay, obtain an event report (which identifies the firmware) using the **EVENT** command. For firmware versions prior to July 21, 2000, the status report displays the Firmware Identification (FID) label:

FID=SEL-321-1-Rxxx-Dxxxxxx

For firmware versions with the date code of July 21, 2000, or later, the FID label will appear as follows with the Part/Revision number in bold:

FID=SEL-321-3-Rxxx-Z000000-Dxxxxxxxx

The firmware revision number is after the “R” and the release date is after the “D”.

For example:

FID=SEL-321-3-R**400**-Z000000-D**20010213**

is firmware revision number 400 and a release date of February 13, 2001.

This manual covers SEL-321 Relays that contain firmware bearing the following part numbers and revision numbers (most recent firmware listed at top):

Firmware Part/Revision No.	SEL-321-3 Relay Base Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-3-R400-Z000000-D20010213 SEL-321-3-R450-Z000000-D20010213 SEL-321-3-R500-Z000000-D20010213 SEL-321-3-R550-Z000000-D20010213 SEL-321-3-R600-Z000000-D20010213 SEL-321-3-R650-Z000000-D20010213 SEL-321-3-R700-Z000000-D20010213 SEL-321-3-R750-Z000000-D20010213 SEL-321-3-R800-Z000000-D20010213 SEL-321-3-R850-Z000000-D20010213 SEL-321-3-R900-Z000000-D20010213 SEL-321-3-R950-Z000000-D20010213	<p>SEL-321-3 Relay is based on SEL-321-1 firmware version dated D20000721. The differences are as follows:</p> <ul style="list-style-type: none"> – Added SER feature. – Added Distributed Network Protocol (DNP). – Limit SELOGIC control equation terms to 100 for 60 Hz version. – Limit frequency tracking to 63 Hz for 60 Hz version. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Board 50 Hz, 5 Amp, 2 I/O Board 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Board, ACB rotation 60 Hz, 1 Amp, 2 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Board 50 Hz, 1 Amp, 2 I/O Board</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R424-Z001001-D20000721 SEL-321-1-R474-Z001001-D20000721 SEL-321-1-R525-Z001001-D20000721 SEL-321-1-R574-Z001001-D20000721 SEL-321-1-R625-Z001001-D20000721 SEL-321-1-R655-Z001001-D20000721 SEL-321-1-R725-Z001001-D20000721 SEL-321-1-R755-Z001001-D20000721 SEL-321-1-R824-Z001001-D20000721 SEL-321-1-R874-Z001001-D20000721 SEL-321-1-R924-Z001001-D20000721 SEL-321-1-R975-Z001001-D20000721	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Increased Z1ANG, Z0ANG, k01A, and k0A setting ranges. – New LOP logic and IEC 1000-4-5 compliance. – Improved MIRRORED BITS™ communications. – Improved <i>Fast Meter</i> communications. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R423-D991020 SEL-321-1-R473-D991020 SEL-321-1-R523-D991020 SEL-321-1-R573-D991020 SEL-321-1-R624-D991020 SEL-321-1-R654-D991020 SEL-321-1-R724-D991020 SEL-321-1-R754-D991020 SEL-321-1-R823-D991020 SEL-321-1-R873-D991020 SEL-321-1-R923-D991020 SEL-321-1-R974-D991020	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Improved <i>Fast Meter</i> communications. – Improved MIRRORED BITS communications. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R422-990415 SEL-321-1-R472-990415 SEL-321-1-R522-990415 SEL-321-1-R572-990415 SEL-321-1-R623-990415 SEL-321-1-R653-990415 SEL-321-1-R723-990415 SEL-321-1-R753-990415 SEL-321-1-R822-990415 SEL-321-1-R872-990415 SEL-321-1-R922-990415 SEL-321-1-R973-990415	This firmware differs from previous versions as follows: <ul style="list-style-type: none"> – Added MIRRORED BITS protocol MB8. MB8 has two stop bits. – Prevent inadvertent cancellation of <i>Fast Operate</i> by a <i>Fast Meter</i> response. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R420-980806 SEL-321-1-R470-980806 SEL-321-1-R520-980806 SEL-321-1-R570-980806 SEL-321-1-R621-980806 SEL-321-1-R651-980806 SEL-321-1-R721-980806 SEL-321-1-R751-980806 SEL-321-1-R820-980806 SEL-321-1-R870-980806 SEL-321-1-R920-980806 SEL-321-1-R971-980806	This firmware differs from previous versions as follows: <ul style="list-style-type: none"> – Improved diagnostics. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R650-980709 SEL-321-1-R750-980709	This firmware differs from previous versions as follows: <ul style="list-style-type: none"> – Added new configurations 60 Hz, 1 Amp, 1 I/O Board, ACB rotation 60 Hz, 1 Amp, 2 I/O Boards, ACB rotation

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R419-980709 SEL-321-1-R469-980709 SEL-321-1-R519-980709 SEL-321-1-R569-980709 SEL-321-1-R620-980709 SEL-321-1-R720-980709 SEL-321-1-R819-980709 SEL-321-1-R869-980709 SEL-321-1-R919-980709 SEL-321-1-R970-980709	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Correct problem where relay incorrectly processed SELOGIC® Control Equations <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>
SEL-321-1-R418-980601 SEL-321-1-R468-980601 SEL-321-1-R518-980601 SEL-321-1-R568-980601 SEL-321-1-R619-980601 SEL-321-1-R719-980601 SEL-321-1-R818-980601 SEL-321-1-R868-980601 SEL-321-1-R918-980601 SEL-321-1-R969-980601	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Changed series compensation logic – Changed long memory constant time to 31.75 cycles <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R417 SEL-321-1-R467 SEL-321-1-R517 SEL-321-1-R567 SEL-321-1-R618 SEL-321-1-R718 SEL-321-1-R817 SEL-321-1-R867 SEL-321-1-R917 SEL-321-1-R968	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Include support of 8 output I/O board – Does not check validity of hidden settings – Adequately checks for event reports being overwritten – STFAIL bit cleared if no alarm conditions – <i>Fast Operate</i> requests have a higher priority than ASCII and do not affect timeout – Load encroachment logic works as intended if PLAF and NLAF are set in same quadrant <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>
SEL-321-1-R416 SEL-321-1-R466 SEL-321-1-R516 SEL-321-1-R566 SEL-321-1-R617 SEL-321-1-R717 SEL-321-1-R816 SEL-321-1-R866 SEL-321-1-R916 SEL-321-1-R967	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – New MIRRORED BITS Protocol <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R415 SEL-321-1-R465 SEL-321-1-R515 SEL-321-1-R565 SEL-321-1-R616 SEL-321-1-R716 SEL-321-1-R815 SEL-321-1-R865 SEL-321-1-R915 SEL-321-1-R966	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Corrected serial port timeout that could result in a vector halt. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>
SEL-321-1-R414 SEL-321-1-R464 SEL-321-1-R514 SEL-321-1-R564 SEL-321-1-R615 SEL-321-1-R715 SEL-321-1-R814 SEL-321-1-R864 SEL-321-1-R914 SEL-321-1-R965	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Removed problem where entering an invalid command with several parameters (i.e., EVE 1 U M BAD), followed by SHOW L OUTn, where n is 12 - 15 or 29 - 32 could result in a vector halt. – Removed problem where powering up the relay with a port PROTOCOL setting set to R6 causes the default settings to be loaded. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R413 SEL-321-1-R463 SEL-321-1-R513 SEL-321-1-R563 SEL-321-1-R614 SEL-321-1-R714 SEL-321-1-R813 SEL-321-1-R863 SEL-321-1-R913 SEL-321-1-R964	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Added global setting ERESTART – Added RDMEM command 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R412 SEL-321-1-R462 SEL-321-1-R512 SEL-321-1-R562 SEL-321-1-R613 SEL-321-1-R713 SEL-321-1-R812 SEL-321-1-R862 SEL-321-1-R912 SEL-321-1-R963	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Relay-to-relay integral communications-assisted protection security enhancement. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Board

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Block the OSTD timer output latch if EOOST=N. – New factory setting for pickup delay in the DCB Zone 3 extension logic. – Hide PASSWORD when entering new access level. – Targets are retained after loss of power.
SEL-321-1-R411 SEL-321-1-R461 SEL-321-1-R511 SEL-321-1-R561 SEL-321-1-R612 SEL-321-1-R712 SEL-321-1-R811 SEL-321-1-R861 SEL-321-1-R911 SEL-321-1-R962	60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R410 SEL-321-1-R460 SEL-321-1-R510 SEL-321-1-R560 SEL-321-1-R611 SEL-321-1-R711 SEL-321-1-R810 SEL-321-1-R860 SEL-321-1-R910 SEL-321-1-R961	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Used PT input instead of PTRX in POTT logic. – Targeting modification to target on all rising edges of trip. – Direct transfer tripping allowed with supervision of pole open. – Hide FAST_OP port setting when PROTOCOL=R. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R409 SEL-321-1-R459 SEL-321-1-R509 SEL-321-1-R559 SEL-321-1-R610 SEL-321-1-R710 SEL-321-1-R809 SEL-321-1-R859 SEL-321-1-R909 SEL-321-1-R960	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Added relay-to-relay integral communications-assisted protection. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>
SEL-321-1-R408 SEL-321-1-R458 SEL-321-1-R508 SEL-321-1-R558 SEL-321-1-R609 SEL-321-1-R709 SEL-321-1-R808 SEL-321-1-R858 SEL-321-1-R908 SEL-321-1-R959	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Corrected compressed ASCII configuration message. – Added CEV L and CEV C to compressed ASCII configuration message. – Display fault location, LOC, in CHI compressed ASCII command as a floating point number instead of a string. – Add device identification number to ID command transmission. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R407 SEL-321-1-R457 SEL-321-1-R507 SEL-321-1-R557 SEL-321-1-R608 SEL-321-1-R708 SEL-321-1-R807 SEL-321-1-R857 SEL-321-1-R907 SEL-321-1-R958	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Made CEVENT command more robust. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards
SEL-321-1-R406 SEL-321-1-R456 SEL-321-1-R506 SEL-321-1-R556 SEL-321-1-R607 SEL-321-1-R707 SEL-321-1-R806 SEL-321-1-R856 SEL-321-1-R906 SEL-321-1-R957	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Improved operating frequency bandwidth. – Corrected error in POTT Logic when ETDPU set to OFF. – Changed default setting for OSTD to 0.5 cycles. – Corrected minor front-panel display problem. 60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R405 SEL-321-1-R455 SEL-321-1-R505 SEL-321-1-R555 SEL-321-1-R606 SEL-321-1-R706 SEL-321-1-R805 SEL-321-1-R855 SEL-321-1-R905 SEL-321-1-R956	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Correctly report inputs in configured fast meter message. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>
SEL-321-1-R404 SEL-321-1-R454 SEL-321-1-R504 SEL-321-1-R554 SEL-321-1-R605 SEL-321-1-R705 SEL-321-1-R804 SEL-321-1-R854 SEL-321-1-R904 SEL-321-1-R955	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Remove problem where changing settings of ports with RTS/CTS enabled, CTS deasserted while messages pending could lead to communications lockup or vector halt. – Add check of 51XTC to warn if torque control specified by bits that will never be set. – Add fast operate function. – Add compressed ASCII configuration message. – Add FAST_OP port setting. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision B or C Main Board and Low-Level Test Capability (ET3 or TT3):
SEL-321-1-R402 SEL-321-1-R452 SEL-321-1-R502 SEL-321-1-R552 SEL-321-1-R603 SEL-321-1-R703 SEL-321-1-R802 SEL-321-1-R852 SEL-321-1-R902 SEL-321-1-R953	<p>SEL-321-1 Relay includes SEL-321 Relay base version plus:</p> <ul style="list-style-type: none"> – 51PTC setting which allow torque control of phase time-overcurrent element by load encroachment element. – PULSE command to independently close output contacts. – Limited-Multidrop (LMD) protocol. – Fast Meter messages. – Compressed ASCII commands. – The CONTROL command which allows the user to set, clear or pulse the new relay elements RB1 - RB16. <p>60 Hz, 5 Amp, 1 I/O Board 50 Hz, 5 Amp, 1 I/O Board 60 Hz, 5 Amp, 2 I/O Boards 50 Hz, 5 Amp, 2 I/O Boards 60 Hz, 5 Amp, 1 I/O Board, ACB rotation 60 Hz, 5 Amp, 2 I/O Boards, ACB rotation 60 Hz, 1 Amp, 1 I/O Board 50 Hz, 1 Amp, 1 I/O Board 60 Hz, 1 Amp, 2 I/O Boards 50 Hz, 1 Amp, 2 I/O Boards</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R124-Z001001-D20000721 SEL-321-1-R174-Z001001-D20000721 SEL-321-1-R224-Z001001-D20000721	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Increased Z1ANG, Z0ANG, k01A, and k0A setting ranges. – New LOP logic and IEC 1000-4-5 compliance. – Improved MIRRORED BITS communications. – Improved <i>Fast Meter</i> communications. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R123-D991020 SEL-321-1-R173-D991020 SEL-321-1-R223-D991020	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Improved <i>Fast Meter</i> communications. – Improved MIRRORED BITS communications. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R122-990415 SEL-321-1-R172-990415 SEL-321-1-R222-990415	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Added MIRRORED BITS protocol MB8. MB8 has two stop bits. – Prevent inadvertent cancellation of <i>Fast Operate</i> by a <i>Fast Meter</i> response. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R120-980806 SEL-321-1-R170-980806 SEL-321-1-R220-980806	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Improved diagnostics. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R119-980709 SEL-321-1-R169-980709 SEL-321-1-R219-980709	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Correct problem where relay incorrectly processed SELOGIC Control Equations <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R118-980601 SEL-321-1-R168-980601 SEL-321-1-R218-980601	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Changed series compensation logic – Changed long memory constant time to 31.75 cycles <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R117 SEL-321-1-R167 SEL-321-1-R217	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Include support of 8 output I/O board – Does not check validity of hidden settings – Adequately checks for event reported being overwritten – STFAIL bit cleared if no alarm conditions – <i>Fast Operate</i> requests have a higher priority than ASCII and do not affect timeout – Load encroachment logic works as intended if PLAF and NLAF are set in same quadrant <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R116 SEL-321-1-R166 SEL-321-1-R216	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – New MIRRORED BITS Protocol <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R115 SEL-321-1-R165 SEL-321-1-R215	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Corrected serial port timeout that could result in a vector halt. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R114 SEL-321-1-R164 SEL-321-1-R214	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Removed problem where entering an invalid command with several parameters (i.e., EVE 1 U M BAD), followed by SHOW L OUTn, where n is 12 - 15 or 29 - 32 could result in a vector halt. – Removed problem where powering up the relay with a port PROTOCOL setting set to R6 causes the default settings to be loaded. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R113 SEL-321-1-R163 SEL-321-1-R213	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Added global setting ERESTART – Added RDMEM command <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R112 SEL-321-1-R162 SEL-321-1-R212	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Relay-to-relay integral communications-assisted protection security enhancement. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R111 SEL-321-1-R161 SEL-321-1-R211	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Block the OSTD timer output latch if EOOST=N. – New factory setting for pickup delay in the DCB Zone 3 extension logic. – Hide PASSWORD when entering new access level. – Targets are retained after loss of power. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R110 SEL-321-1-R160 SEL-321-1-R210	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Used PT input instead of PTRX in POTT logic. – Targeting modification to target on all rising edges of trip. – Direct transfer tripping allowed with supervision of pole open. – Hide FAST_OP port setting when PROTOCOL=R. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R109 SEL-321-1-R159 SEL-321-1-R209	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Added relay-to-relay integral communications-assisted protection. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R108 SEL-321-1-R158 SEL-321-1-R208	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Corrected compressed ASCII configuration message. – Added CEV L and CEV C to compressed ASCII configuration message. – Display fault location, LOC, in CHI compressed ASCII command as a floating point number instead of a string. – Add device identification number to ID command transmission. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R107 SEL-321-1-R157 SEL-321-1-R207	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Improved operating frequency bandwidth. – Corrected error in POTT Logic when ETDPU set to OFF. – Changed default setting for OSTD to 0.5 cycles. – Corrected minor front-panel display problem. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R106 SEL-321-1-R156 SEL-321-1-R206	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Made CEVENT command more robust. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R105 SEL-321-1-R155 SEL-321-1-R205	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Correctly report inputs in configured fast meter message. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

Firmware Part/Revision No.	SEL-321-1 Relay Version Description of Firmware
	Revision A Main Board:
SEL-321-1-R104 SEL-321-1-R154 SEL-321-1-R204	<p>This firmware differs from previous versions as follows:</p> <ul style="list-style-type: none"> – Remove problem where changing settings of ports with RTS/CTS enabled, CTS deasserted while messages pending could lead to communications lockup or vector halt. – Add check of 51XTC to warn if torque control specified by bits that will never be set. – Add fast operate function. – Add compressed ASCII configuration message. – Add FAST_OP port setting. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>
SEL-321-1-R102 SEL-321-1-R152 SEL-321-1-R202	<p>SEL-321-1 Relay includes SEL-321 Relay base version plus:</p> <ul style="list-style-type: none"> – 51PTC setting which allow torque control of phase time-overcurrent element by load encroachment element. – PULSE command to independently close output contacts. – Limited Multidrop (LMD) protocol. – Fast Meter messages. – Compressed ASCII commands. – The CONTROL command which allows the user to set, clear or pulse the new relay elements RB1 - RB16. <p>60 Hz, 5 Amp, 1 I/O Board, Rev. A 50 Hz, 5 Amp, 1 I/O Board, Rev. A 60 Hz, 5 Amp, 2 I/O Boards, Rev. A</p>

APPENDIX B: SEL-321 MAIN BOARD JUMPER, CONNECTOR, AND SOCKET LOCATIONS

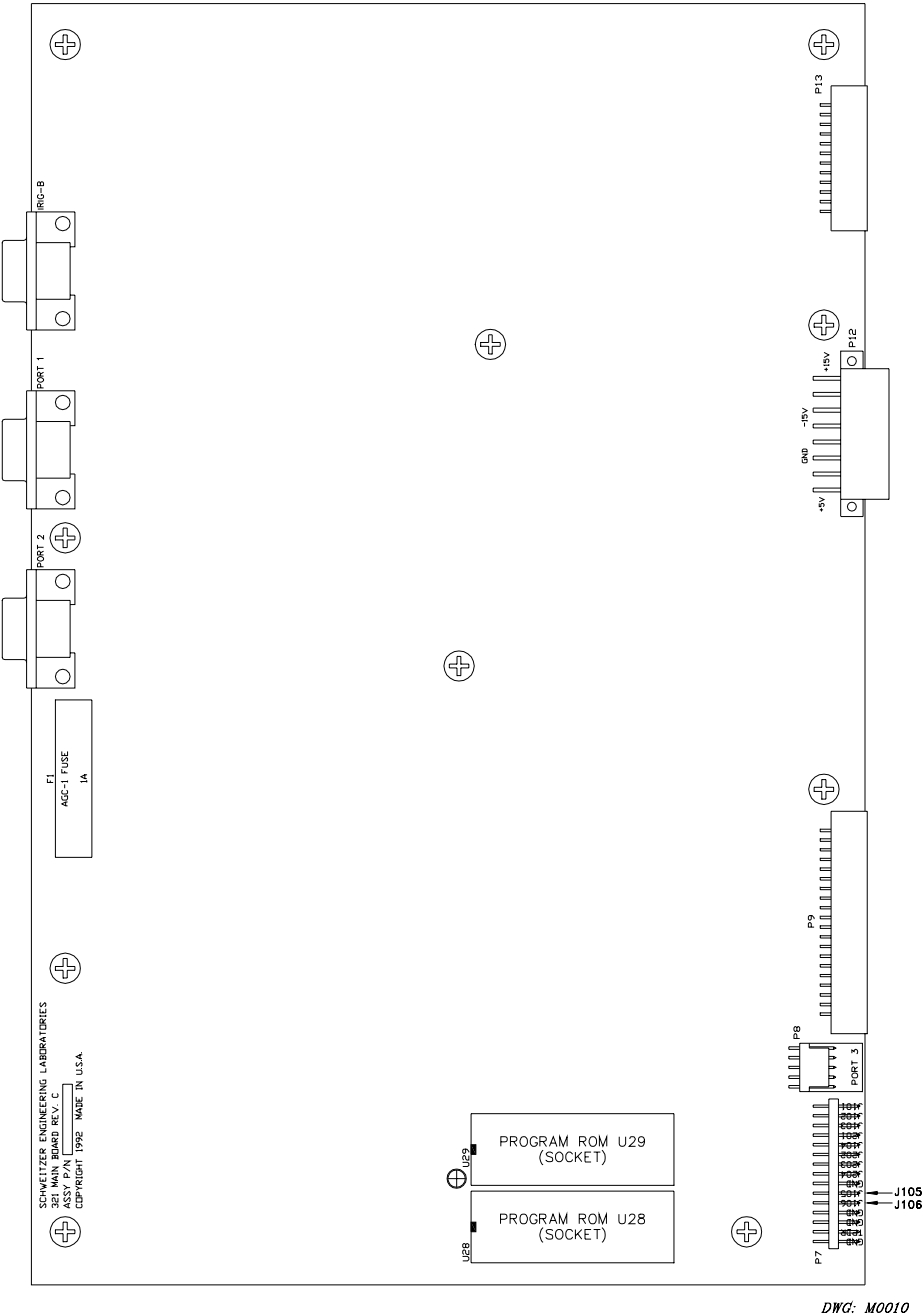


Figure B.1: SEL-321 Main Board Jumper, Connector, and Socket Locations

APPENDIX C: APPLICATION GUIDELINES

This section contains the following Application Guides:



AG93-03 REJO Application Guidelines

APPENDIX D: ONEBUS: PROGRAM TO COMPUTE TEST SET SETTINGS FOR TESTING DISTANCE RELAYS

The BASIC program in this note determines voltages and currents which would appear on distance relay terminals for ground and phase faults on a radial system with source impedance at the same angle as line impedance. It is useful in determining test voltage and current settings for SEL distance relays and fault locating equipment.

The program was initially designed to run on a TRS-80 Model 100 briefcase computer but may be installed on virtually any personal computer or laptop.

The program first prompts you for the positive- and zero-sequence impedances of the transmission line. Enter the data in secondary ohms for the entire length of the protected line.

Next, you may enter fault resistance, which is used in the ground-fault computations.

Enter source impedance as a per-unit value with a base of the previously-entered transmission line data. For example, if the radial system has a source impedance of about ten percent of the entered line impedance, enter 0.1 for the per-unit distance from the source to the bus.

Specify the distance from the bus to the fault as a fraction of the total line length. To obtain the voltages and currents for a fault one-half the way down the line from the bus, enter 0.5 for the distance from the bus to the fault.

After you enter this data, the program begins computations. The display then shows voltages and currents for both an AG and BC fault. These data can be entered into any active test source.

The bottom line of the display offers you a choice of entering new impedance data (I), changing the distance from the source to the bus (B), specifying a new fault location (F), or quitting (Q).

```

1  REM SCHWEITZER ENGINEERING LABORATORIES, INC.
2  REM 2350 NE Hopkins Court
3  REM Pullman, WA 99163-5603
4  REM
10 REM COMPUTE DOBLE SETTINGS FOR A ONE-BUS SYSTEM
20 REM HOMOGENEOUS SYSTEM
30 REM SOURCE VOLTS= 67 L-N
40 REM
50 REM ENTER IMPEDANCES FOR 100% OF LINE
60 INPUT "ENTER Z1: R,X";R1,S1
70 INPUT "ENTER Z0: R,X";R0,S0
75 INPUT "ENTER RF FOR GND FLTS";RF
80 REM
90 REM ENTER BUS LOC. FROM SOURCE
100 INPUT "DIST SOURCE TO BUS (PU OF LINE)";S
120 INPUT "DIST BUS TO FAULT (PU OF LINE)";F
130 REM
140 REM PHASE A TO GROUND
150 REM COMPUTE POS SEQ CURRENT
160 X = R0+2*R1: Y = S0+2*S1
170 R3 = R1-R0: S3 = S1-S0
180 AR=1/(S+F): AI=0
190 BR=X : BI=Y
195 BR=BR+3*RF/(S+F)
200 GOSUB 2000
210 I = RR : J = RI
220 IA = 3*67*I: JA=3*67*J
225 IB=0:JB=0:IC=0:JC=0
230 AR=X:AI=Y:BR=I:BI=J
232 GOSUB 1000
234 UA=67*(1-S*RR):VA=67*(-S*RI)
240 AR=R3 :AI=S3
250 BR=I :BI=J
260 GOSUB 1000
270 TR=S*RR :TS=S*RI
280 UB=67*(-0.5+TR)
290 VB=67*(-SQR(3)/2+TS)
300 UC=67*(-0.5+TR)
310 VC=67*(SQR(3)/2+TS)
315 FF$="A-G"
320 GOSUB 4041
500 REM B-C FAULT
510 AR=1: AI=0
520 BR=2*R1*(S+F):BI=2*S1*(S+F)
530 GOSUB 2000
540 I=RR:J=RI
550 IA=0:JA=0
560 AR=I:AI=J:BR=0:BI=-67*SQR(3)
570 GOSUB 1000
580 IB=RR:JB=RI:IC=-IB:JC=-JB
590 UA=67:VA=0
600 AR=I:AI=J:BR=S*R1:BI=S*S1
610 GOSUB 1000
620 AR=RR:AI=RI:BR=0:BI=SQR(3)
630 GOSUB 1000
635 TR=RR:TS=RI
640 UB=67*(-0.5+TR)
650 VB=67*(-SQR(3)/2+TS)
660 UC=67*(-0.5+TR)
670 VC=67*(0.5*SQR(3)-TS)
675 FF$="B-C"
680 GOSUB 4041
900 INPUT "IMP BUS FAULT OR QUIT (I,B,F,Q)";A$
910 IF A$ = "I" THEN GOTO 50
920 IF A$ = "B" THEN GOTO 75
930 IF A$ = "F" THEN GOTO 120 ELSE GOTO 999
999 END
1000 REM MULT SUBROUTINE
1010 REM AR,AI * BR,BI = RR,RI
1020 RR=AR*BR-AI*BI
1030 RI=AI*BR+AR*BI
1040 RETURN
2000 REM DIVISION SUBROUTINE
2010 REM AR,AI / BR,BI = RR,RI
2020 D = BR*BR + BI*BI
2030 RR = AR*BR + AI*BI
2040 RR = RR/D
2050 RI = BR*AI - AR*BI
2060 RI = RI/D
2070 RETURN
3000 REM RECT TO POLAR CONV
3010 REM AR,AI, TO RH, TH
3020 PI = 3.14159265358
3030 IF (AR=0 AND AI=0) THEN RH=0: TH=0: RETURN
3040 IF (AR=0 AND AI>0) THEN RH=AI: TH=90: RETURN
3050 IF (AR=0 AND AI<0) THEN RH=-AI: TH=-90: RETURN
3060 IF (AR>0) THEN TH=(180/PI)*ATN(AI/AR)
3070 IF (AR<0) THEN TH=(180/PI)*ATN(AI/AR)+180
3080 IF TH>180 THEN TH = TH-360
3090 RH=SQR(AR*AR+AI*AI)
3100 RETURN
4041 AR=UA:AI=VA:GOSUB 3000
4042 UA=RH:VA=TH
4043 AR=UB:AI=VB:GOSUB 3000
4044 UB=RH:VB=TH-VA
4045 AR=UC:AI=VC:GOSUB 3000
4046 UC=RH:VC=TH-VA
4047 AR=IA:AI=JA:GOSUB 3000
4048 IA=RH:JA=TH-VA
4049 AR=IB:AI=JB:GOSUB 3000
4050 IB=RH:JB=TH-VA
4055 AR=IC:AI=JC:GOSUB 3000
4060 IC=RH:JC=TH-VA
4061 VA=0
4100 PRINT " VA VB VC IA IB IC"
4130 PRINT USING"###. # ";UA;UB;UC;IA;IB;IC,
4132 PRINT FF$
4140 PRINT USING"#### ";VA;VB;VC;JA;JB;JC
4150 RETURN

```

APPENDIX E: SPECIAL APPLICATION SETTINGS

Some settings have special values to actuate line specific features. These are documented in this appendix.

VALUE OF "S" FOR E51N, E51Q

With typical settings of "Y" or "N", the time overcurrent accumulation is blocked for a single-pole open (SPO) condition. When E51N is set to "S", SPO does not block the 51N elements. When E51Q is set to "S", SPO does not block the 51Q elements.

VALUE OF "N1" OR "Y1" FOR ESPT SETTING

N1 activates special Scheme 1 Trip Logic if the SPTE contact enables single-pole tripping.

Y1 activates special Scheme 1 Trip Logic equations:

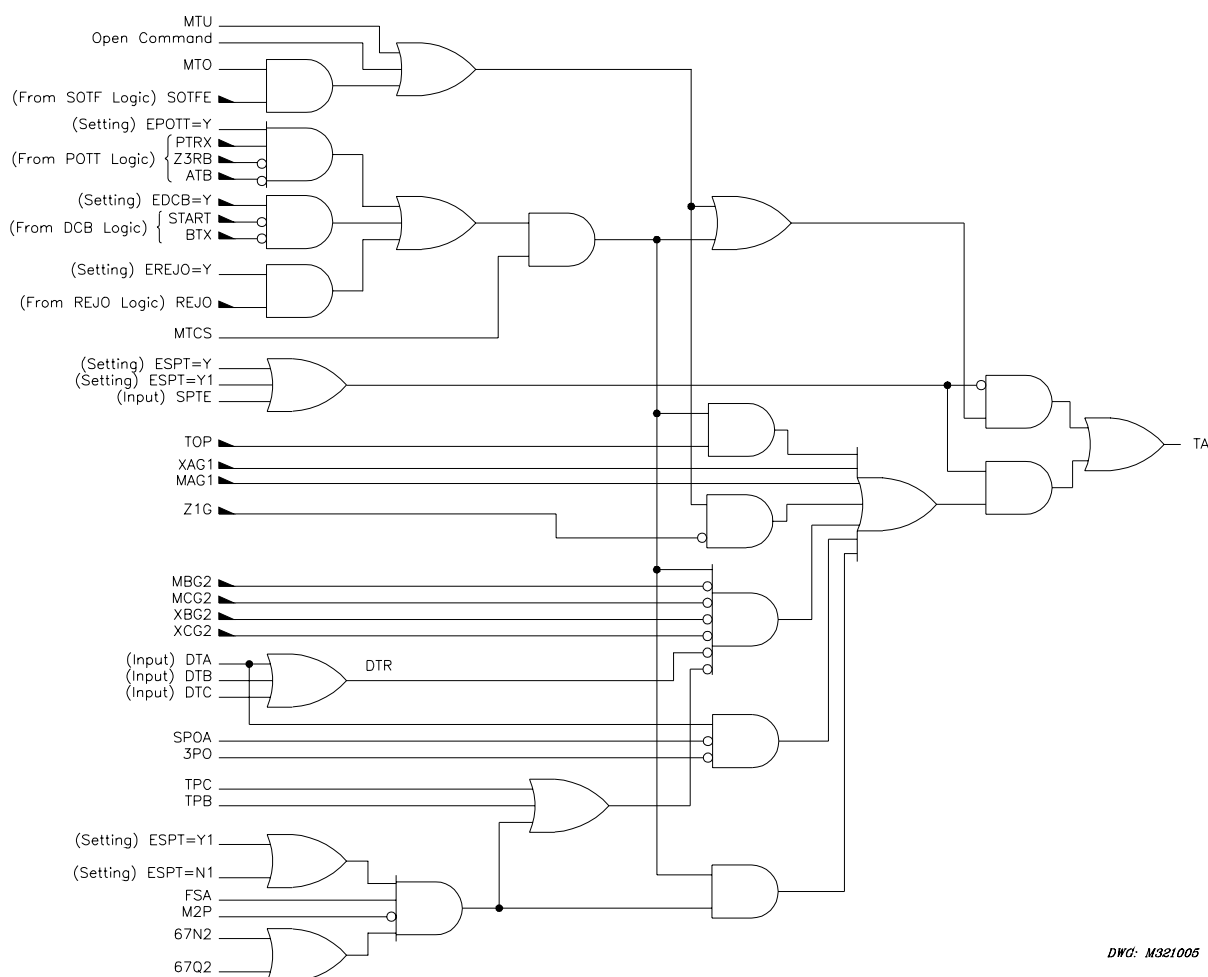


Figure E.1: Scheme 1 Trip Decision Logic for Phase A

VALUE OF FACTORY SETTINGS LPVNOM AND FQVPU

Factory settings are not normally adjusted by the user and are not all described in the instruction manual. Access factory settings at security level CAL (the password is CLARKE) with the **SET F** command.

Setting LPVNOM adjusts the magnitude of positive-sequence voltage required to reset loss-of-potential (LOP) upon the restoration of voltage. The default setting of 57 volts will provide correct operation for systems down to a nominal secondary voltage of 100 V line-to-line.

Setting FQVPU sets the magnitude of A-phase voltage at which the relay enables frequency tracking. Certain system configurations, such as series compensated lines, may require a higher value than the default settings of 10 volts. To prevent frequency tracking errors during a fault, this setting should not be changed without system studies.

APPENDIX F: ADDITIONAL SEL-321-3 RELAY COMMUNICATIONS PROTOCOL

This section contains the following Application Guides:



AG94-03 SEL Distributed Port Switch Protocol (LMD)

AG95-10 Configuration and Fast Meter Messages

AG95-11 SEL-321-1/SEL-321-2 Configuration and Fast Meter Messages

AG95-03 SEL-321-1 Compressed ASCII Commands

APPENDIX G: MIRRORED BITS™ COMMUNICATIONS

OVERVIEW

MIRRORED BITS is a direct relay-to-relay digital communications protocol which allows protective relays to exchange information quickly and securely, and with minimal expense. The information exchanged can facilitate remote control, remote sensing, or communications-assisted protection schemes such as POTT, DCB, etc. In this document the bits received are called RMB1 through RMB8. Bits transmitted are called TMB1 through TMB8.

SETTINGS

```
protocol (SEL,LMD,DNP,MB,MB8)          PROTOCOL= MB    ?
baud rate (300-9600)                     SPEED = 9600    ?
enable hardware handshaking (Y,N,MBT)    RTS_CTS= N      ?
Mirrored Bits Receive bad pickup (1- 10000 sec) RBADPU= 60    ?
Mirrored Bits Channel bad pickup (1- 10000 10E-6) CBADPU= 1000 ?
Mirrored Bits transmit identifier(1 - 4)   TX_ID = 1       ?
Mirrored Bits receive identifier(1 - 4)    RX_ID = 2       ?
Mirrored Bits receive default state (string of 1s, 0s or Xs)
87654321
RXDFLT=00000X11
?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB1PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB1DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB2PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB2DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB3PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB3DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB4PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB4DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB5PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB5DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB6PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB6DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB7PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB7DO= 1     ?
Mirrored Bits RMB_ Debounce PU time (1-8 msgs) RMB8PU= 1     ?
Mirrored Bits RMB_ Debounce DO time (1-8 msgs) RMB8DO= 1     ?
```

```
protocol (SEL,LMD,DNP,MB,MB8)          PROTOCOL= MB    ?
```

Set PROTOCOL = MB or MB8 to enable the MIRRORED BITS protocol.

Use MB protocol with dedicated fiber-optic modems such as the SEL-2800. Set PROTOCOL = MB8 for use with communications devices that have higher latency times, such as spread spectrum radios. MB8 is also required for communications devices that require eight data bits, no parity, and one stop bit.

```
baud rate (300-9600)                     SPEED = 9600    ?
```

Use the SPEED setting to control the rate at which the MIRRORED BITS messages are transmitted, in power system cycles.

```
enable hardware handshaking (Y,N,MBT)      RTS_CTS= N      ?
```

Use the MBT option if you are using a Pulsar MBT 9600 baud modem. With this option set, the relay will transmit a message every 3/8 power system cycle and the relay will deassert the RTS signal on the EIA-232 connector. Also, the relay will monitor the CTS signal on the EIA-232 connector, which the modem will deassert if the channel has too many errors. The modem uses the relay's RTS signal to determine whether the new or old MIRRORED BITS protocol is in use.

```
Mirrored Bits Receive bad pickup (1- 10000 sec)  RBADPU= 60      ?
```

Use the RBADPU setting to determine how long a channel error must last before the relay element RBAD is asserted. RBAD is instantaneously deasserted when the channel error is corrected.

```
Mirrored Bits Channel bad pickup (1- 10000 10E-6)  CBADPU= 1000 ?
```

Use the CBADPU setting to determine the ratio of channel down time to the total channel time before the relay element CBAD is asserted. The time used in the calculation are those that are available in the COMM records. See the **COMM** command in the SEL-321 or SEL-351 manuals for a description of the COMM records.

```
Mirrored Bits transmit identifier(1 - 4)      TX_ID = 1      ?
Mirrored Bits receive identifier(1 - 4)      RX_ID = 2      ?
```

Set the RX_ID of the local relay to match the TX_ID of the remote relay. For example, in the three-terminal case, where Relay A transmits to Relay B, Relay B transmits to Relay C, and Relay C transmits to Relay A:

Relay	TX_ID	RX_ID
A	1	3
B	2	1
C	3	2

```
Mirrored Bits receive default state (string of 1s, 0s or Xs)
      87654321
RXDFLT=00000X11
      ?
```

Use the RXDFLT setting to determine the default state the MIRRORED BITS should use in place of received data if an error condition is detected. The setting is a mask of 1s, 0s and/or Xs, for RMB1 - RMB8, where X represents the most recently received valid value.

Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB1PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB1DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB2PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB2DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB3PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB3DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB4PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB4DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB5PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB5DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB6PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB6DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB7PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB7DO= 1	?
Mirrored Bits RMB_	Debounce PU time (1-8 msgs)	RMB8PU= 1	?
Mirrored Bits RMB_	Debounce DO time (1-8 msgs)	RMB8DO= 1	?

Supervise the transfer of received data (or default data) to RMB1 - RMB8 with the MIRRORRED BITS pickup and dropout security counters. Set the pickup and dropout counters individually for each bit.

For example, any received mirrored bit that is used for direct transfer tripping should have at least a two received message pickup delay.

OPERATION

Message Transmission

All messages are transmitted without idle bits between characters. Idle bits are allowed between messages.

- At 4800 baud, one message is transmitted each power system cycle.
- At 9600 baud, one message is transmitted each 1/2 power system cycle.

Message Decoding and Integrity Checks

The relay will deassert a relay element bit, ROK for any of the following reasons:

- Relay disabled.
- MIRRORRED BITS not enabled.
- Received data parity, framing, or overrun errors.
- Receive data redundancy error.
- Receive message identification error.
- No message received in the time three messages have been sent for MB protocol. No message received in the time six messages have been sent for MB8 protocol.

While ROK is not asserted, the relay will:

- Enter the synchronization process described below.
- Prevent new data from being transferred to the pickup/dropout security counters. Instead, the relay will send the default values (RXDFLT) to the security counter inputs:

1
0
The last valid value

The relay will assert ROK only after successful synchronization as described below and 2 consecutive messages pass all of the checks described above.

The user can combine ROK with other relay bits in SELOGIC[®] Control Equations.

After ROK is reasserted, received data may be delayed while passing through the security counters described below.

Transfer of received data to RMB1 - RMB8 is supervised by the 8 user-programmable pickup/dropout security counters (RMB1PU - RMB8DO) settable from 1 (allow every occurrence to pass) to 8 (require 8 consecutive occurrences to pass). The pickup and dropout security count settings are separate.

Note: Pickup/dropout security counters operate identically to pickup/dropout timers, except they are set in counts of received messages instead of time.

Synchronization

When a node detects a communications error, it deasserts ROK and transmits an attention message, which includes its TX_ID setting.

When a node receives an attention message, it checks to see if its own TX_ID is included.

If its own TX_ID is included and at least one other TX_ID is included, the node discards the attention message and transmits data.

If its own TX_ID is not included, the node deasserts ROK, includes its TX_ID in the attention message, and transmits the new attention message.

If its own TX_ID is the only TX_ID included, the node assumes the message is corrupted unless the loop back mode has been enabled. If loop back is not enabled, the node deasserts ROK and transmits the attention message with its TX_ID included. If loop back is enabled, the node discards the attention message and transmits data.

Note: In summary, when a node detects an error, it transmits attention until it receives an attention with its own TX_ID included. If three or four relays are connected in a ring topology, then the attention message will go all the way around the loop, and will eventually be received by the originating node. It will then be discarded, and data transmission will resume. This method of synchronization allows the nodes to reliably determine which character is the first character of the message. It also forces a mis-synchronized relay to become re-synchronized. This method takes down the entire loop for a receive error at any node in the loop, an exchange of availability for security.

Loopback Testing

Physically loopback the MIRRORED BITS communication channel external to the relay. Then use the **LOOP** command to enable loopback testing.

While in loopback mode, ROK is deasserted, and the relay element LBOK will assert and deassert based on the ROK checks listed above.

The **TAR** command, front panel targets, and/or the **COMM** command may be used to monitor the loopback test.

Refer to the SEL-321 or SEL-351 manuals for additional information on these commands.

Channel Monitoring

Based on the results of data checks described above, the relay will collect information regarding the 255 most recent communications errors. Each record will contain at least the following fields:

- Dropout Time/Date
- Pickup Time/Date
- Time elapsed during dropout
- Reason for dropout (See Message Decoding and Integrity Checks)

Use the **COMM** command to generate a long or summary report of the communications errors.

Note: There is only a single record for each outage, but an outage can evolve. For example the initial cause could be a data disagreement, but the outage can be perpetuated by framing errors. If the channel is presently down, the COMM record will only show the initial cause, but the COMM summary will display the present cause of failure.

When the duration of an outage exceeds the setting RBADPU, the relay will assert the relay element, RBAD.

Note: RBAD is typically combined with other alarm conditions using SELOGIC Control Equations.

When channel unavailability exceeds the setting CBADPU, the relay will assert the relay element, CBAD.

Note: CBAD is typically combined with other alarm conditions using SELOGIC Control Equations.

APPENDIX H: INTERFACE BOARD SPECIFICATIONS

INTRODUCTION

The SEL-321 Relay is available with one or two interface boards for application flexibility. The number of inputs, number of outputs, operating speeds, interrupt capabilities, and operation configuration vary depending on the interface boards. This appendix describes the interface boards and shows partial rear-panel diagrams for each.

Note: The interface boards are not interchangeable with each other on a two I/O board relay.

Table H.1: Interface Board Types

Screw Terminal			
I/O Board	Inputs	Outputs	
Interface 1	8	16	Standard Shared-Terminal
Interface 2*	8	12	Standard Independent
Interface 5	8	8	Fast High Current Interrupting
Plug-In Connections			
I/O Board	Inputs	Outputs	
Interface 1	8	16	Standard Shared-Terminal
Interface 2	8	12	Standard Independent
Interface 6	8	12	High Current Interrupting

* Interface board 2 is listed as option 3 on the screw terminal ordering information sheet.

INTERFACE BOARD 1 (16 OUTPUTS, 8 INPUTS) - SCREW TERMINAL OR PLUG-IN CONNECTIONS

Optoisolated Inputs

All eight control inputs are dry optoisolated inputs and are not polarity dependent. The screw terminal version comes with standard fixed inputs while the plug-in version has fixed level-sensitive inputs. The nominal rated control voltage of 24, 48, 125, or 250 Vdc must be specified when ordering. To assert an input, apply control voltage to the terminals assigned to that input. Each input is individually isolated, and a terminal pair is brought out for each input. There are no internal connections between inputs. The inputs will assert within 2 ms and draw approximately 4 mA of current at nominal voltage. For further information, see *General Specifications* in *Section 2*.

Output Contacts

30 A make

6 A carry

Not rated for interrupting duty

Closing (pickup for “a” contacts, dropout for “b” contacts): 1/4-cycle or less

Opening (dropout for “a” contacts, pickup for “b” contacts): 1/2-cycle or less (typical is 1/4-cycle)

Interface board 1 provides 16 contact outputs. These 16 **standard** dry output contacts **share** a common terminal for each pair of contacts, but are not polarity dependent. The rear of the relay will be similar to the following figures:

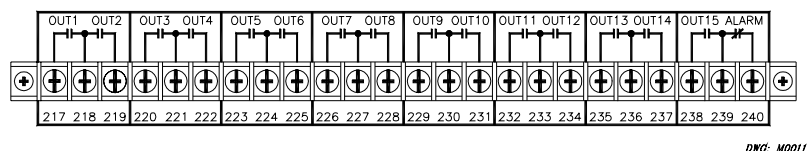


Figure H.1: Interface Board 1 Output Contacts (Board Position 1)

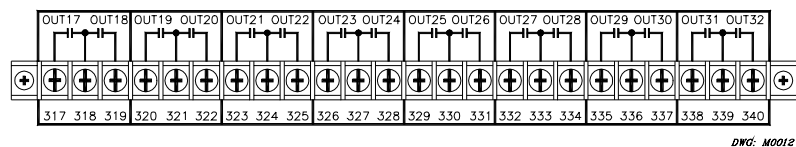


Figure H.2: Interface Board 1 Output Contacts (Board Position 2)

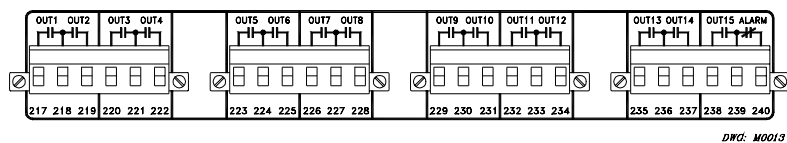


Figure H.3: Interface Board 1 Output Contacts (Board Position 1) (Plug-In Connections)

Configure the output contacts as “a” contacts or “b” contacts with solder jumpers. Figure H.4 and Figure H.5 show the locations of the jumpers and explain the jumper positions. Contacts are factory-configured as “a” contacts (except the alarm contact which is “b”).

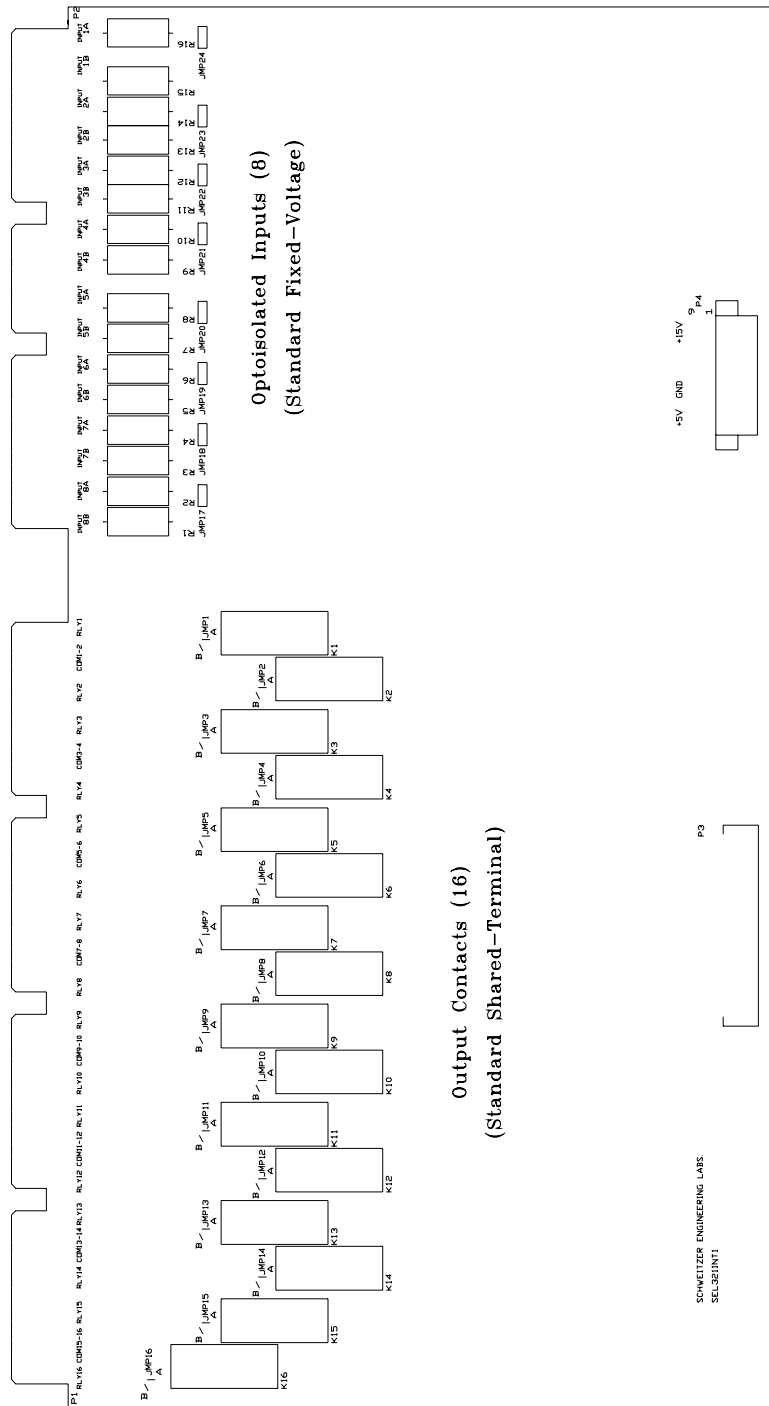


Figure H.4: Interface Board 1 Component Layout (Screw Terminal)

Output Contacts K1 - K16	
Solder Jumper Position	Operation
A	Contact closes when asserted
B	Contact opens when asserted



INTERFACE BOARD 2 (12 OUTPUTS, 8 INPUTS) - SCREW-TERMINAL OR PLUG-IN CONNECTIONS

Optoisolated Inputs

All eight control inputs are dry optoisolated inputs, and are not polarity dependent. The screw terminal version comes with standard fixed inputs while the plug-in version has fixed level-sensitive inputs. The nominal rated control voltage of 24, 48, 125, or 250 Vdc must be specified when ordering. To assert an input, apply control voltage to the terminals assigned to that input. Each input is individually isolated, and a terminal pair is brought out for each input. There are no internal connections between inputs. The inputs will assert within 2 ms and draw approximately 4 mA of current at nominal voltage. For further information, see *General Specifications* in *Section 2*.

Output Contacts

30 A make

6 A carry

Not rated for interrupting duty

Closing (pickup for “a” contacts, dropout for “b” contacts): 1/4-cycle or less

Opening (dropout for “a” contacts, pickup for “b” contacts): 1/2-cycle or less (typical is 1/4-cycle)

Interface board 2 provides 12 output contacts. These 12 **standard** dry output contacts have **independent** terminals for each pair of contacts and are not polarity dependent. The rear of the relay will be similar to the following figures:

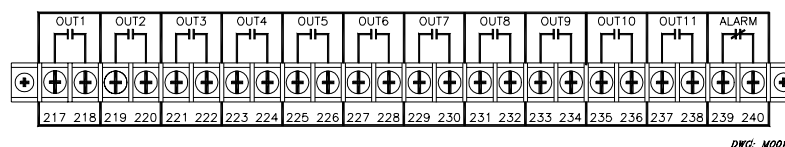


Figure H.6: Interface Board 2 Output Contacts (Board Position 1)

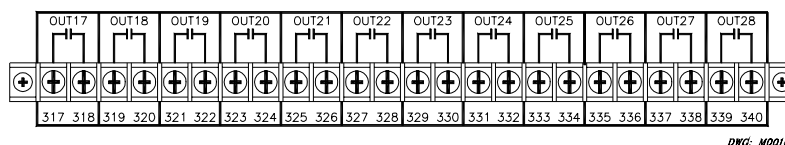


Figure H.7: Interface Board 2 Output Contacts (Board Position 2)

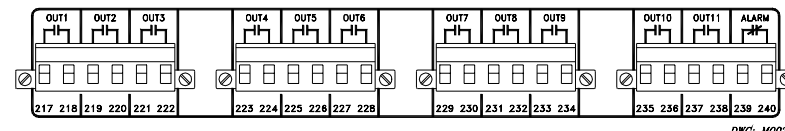


Figure H.8: Interface Board 2 Output Contacts (Board Position 1) (Plug-In Connections)

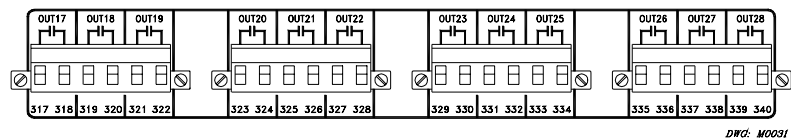


Figure H.9: Interface Board 2 Output Contacts (Board Position 2) (Plug-In Connections)

Configure the output contacts as “a” contacts or “b” contacts with solder jumpers. Figure H.10 and Figure H.11 show the locations of the jumpers and explain the jumper positions. Contacts are factory-configured as “a” contacts (except the alarm contact which is “b”).

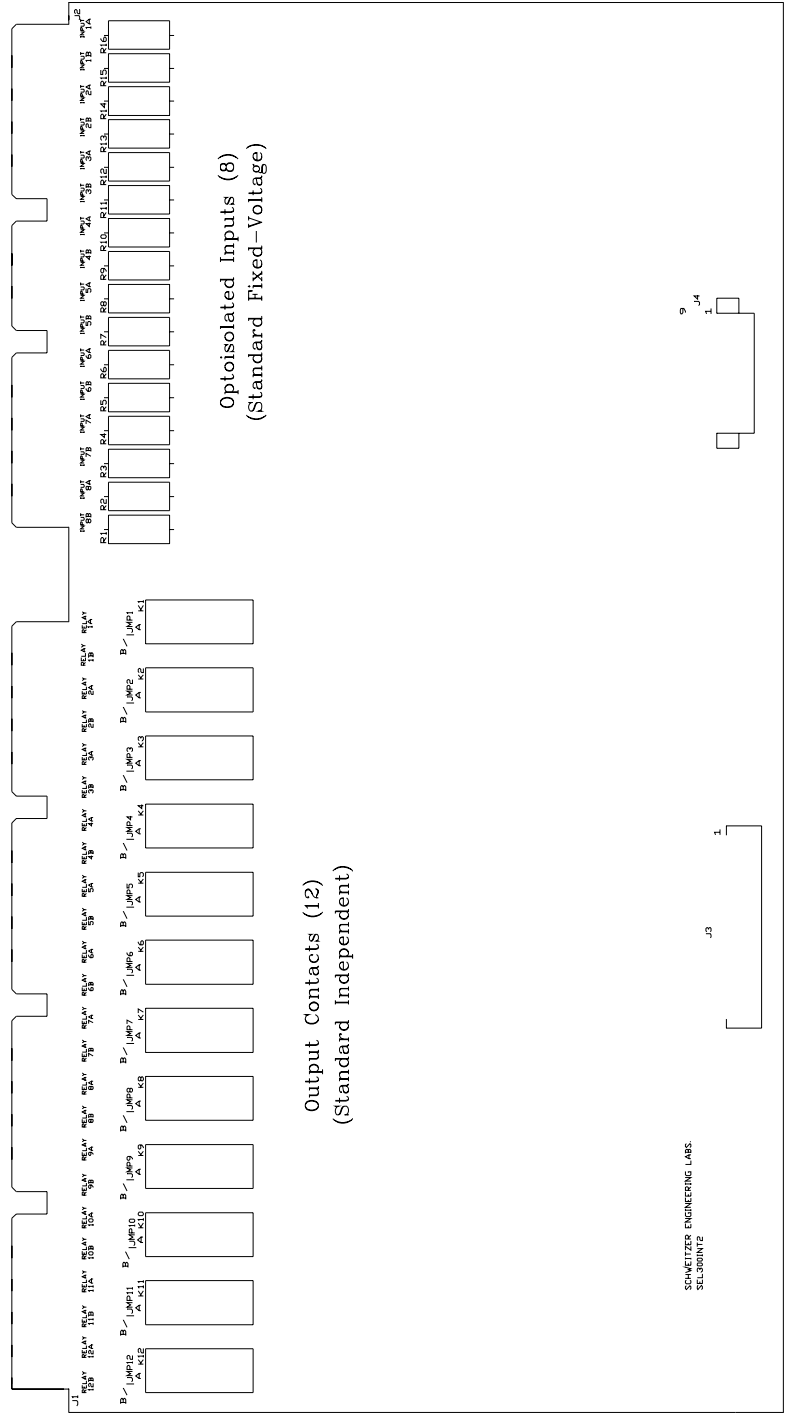
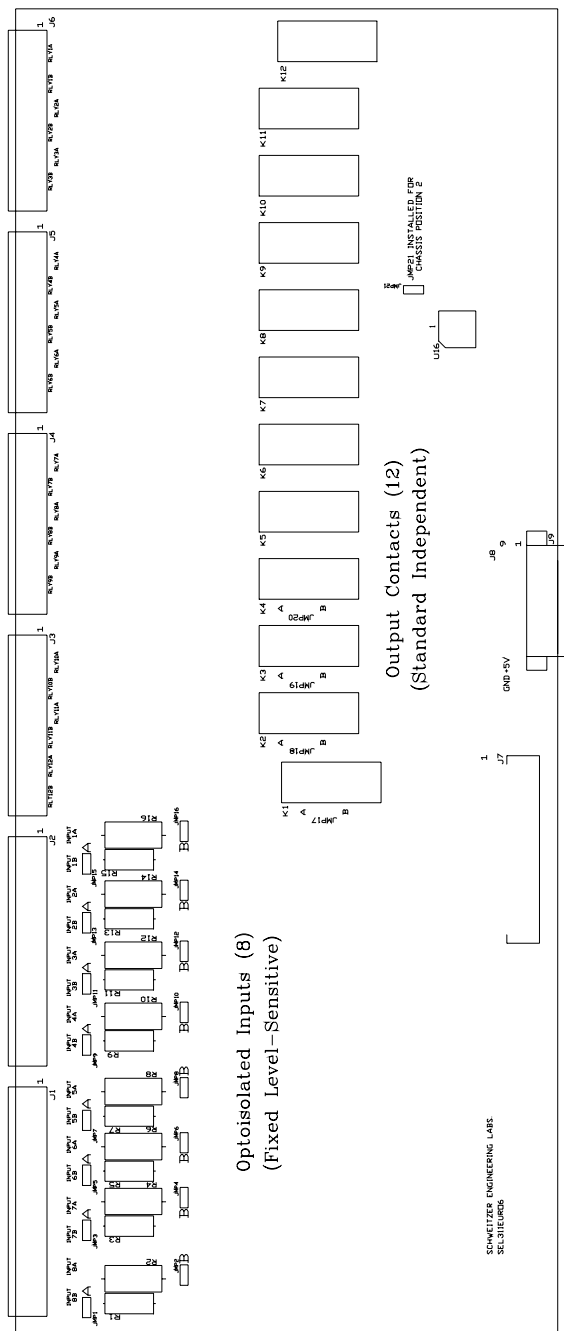


Figure H.10: Interface Board 2 Component Layout (Screw Terminal)

Output Contacts K1 – K12

Solder Jumper Position	Operation
A	Contact closes when asserted
B	Contact opens when asserted

DWG: M0025



Output Contacts K1 - K4	
Solder Jumper Position	Operation
A	Contact closes when asserted
B	Contact opens when asserted

I/O Board Position Selection	
First I/O board position selected	JMP21 shorting block removed
Second I/O board position selected	JMP21 shorting block installed

DWG: M0028

Figure H.11: Interface Board 2 Component Layout (Plug-In Connectors)

INTERFACE BOARD 5 (8 OUTPUTS, 8 INPUTS) - SCREW-TERMINAL

Optoisolated Inputs

All eight control inputs are standard, fixed-voltage, dry optoisolated inputs, and are not polarity dependent. The nominal rated control voltage of 24, 48, 125, or 250 Vdc must be specified when ordering. To assert an input, apply control voltage to the terminals assigned to that input. Each input is individually isolated, and a terminal pair is brought out for each input. There are no internal connections between inputs. The inputs will assert within 2 ms and draw approximately 4 mA of current at nominal voltage. For further information, see *General Specifications* in *Section 2*.

Output Contacts

30 A make

6 A carry

10 A interrupt for $L/R < 0.04$ seconds at 125 Vdc

10 A interrupt for $L/R < 0.02$ seconds at 250 Vdc

Closing (open-to-close for both “a” or “b” contacts): 200 μ s

Opening (close-to-open for both “a” or “b” contacts): typically 1/2-cycle

Interface board 5 provides eight output contacts. These eight **Fast High Current Interrupting** dry output contacts can interrupt 10 A of inductive current with an $L/R < 0.04$ seconds. At 250 Vdc, they will interrupt 10 A of inductive current for an $L/R < 0.02$ seconds. They operate (close for “a” contacts and open for “b” contacts) in less than 10 μ s (.00001 seconds). Due to relay capabilities the outputs of the SEL-321 Relay are specified at 200 μ s (.0002 seconds).

The output contacts may be configured as either “a” or “b” contacts with solder jumpers. Figure H.15 show the locations of the jumpers and explain the jumper positions. Contacts are factory-configured as “a” contacts (except the alarm contact which is “b”).

Short transient inrush current may flow when a switch that is in series with the contact is closed, and the Interface 5 contact is open. This transient will not energize the circuit used in typical applications. Trip and Close coils and standard auxiliary relays will not pick up; however, an extremely sensitive digital input or light-duty, high-speed auxiliary may pick up for this condition. The transient occurs when the capacitance of the output contact circuitry is charged. A third terminal for each contact provides a path for charging the capacitance when the circuit is open. See Figure H.12 and Figure H.13.

Figure H.14 shows some possible connections for this third terminal that will eliminate the possibility of transients when closing a switch. Circuit load is not shown. In general, the third terminal must be connected to the dc rail that is on the same side as the open switch condition. If an open switch may exist on either side of the output contact, only one condition may be considered. Two open switches (one on each side of the contact) defeat the charge circuit.

The Interface 5 contact outputs are **not** polarity dependent.

The rear of the relay will be similar to the following drawings:

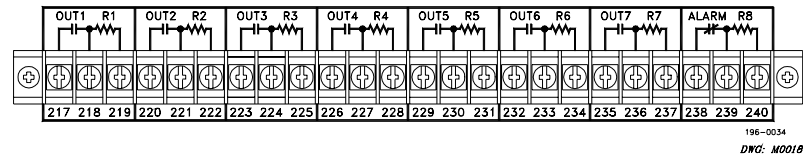


Figure H.12: Interface Board 5 Output Contacts (Board Position 1)

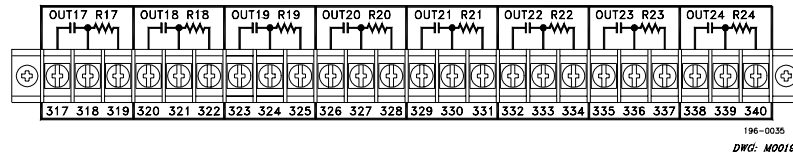


Figure H.13: Interface Board 5 Output Contacts (Board Position 2)

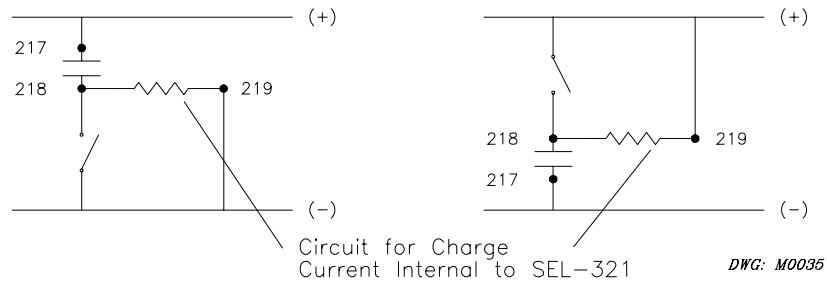
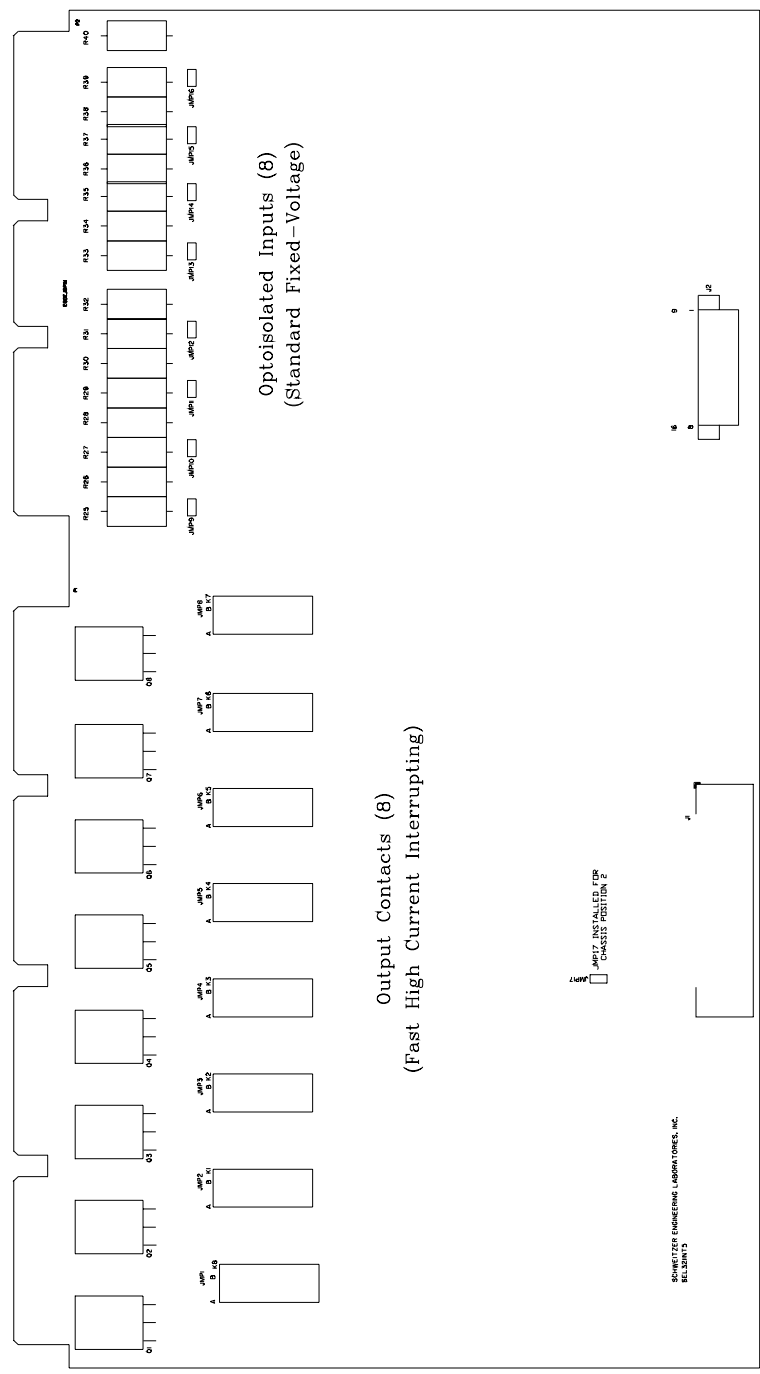


Figure H.14: Possible Connections for Fast High Current Interrupting Output Contacts (Circuit Load Not Shown, Third Terminal Connection is Optional)



Output Contacts K1 - K8	
Solder Jumper Position	Operation
A	Contact closes when asserted
B	Contact opens when asserted

I/O Board Position Selection	
First I/O board position selected	JMP17 shorting block removed
Second I/O board position selected	JMP17 shorting block installed

DWG: M0029

* Note: Revision A is jumper configurable for K8 only (alarm).
The other output contacts are type "a" only.

INTERFACE BOARD 6 (12 OUTPUTS, 8 INPUTS) - PLUG-IN CONNECTIONS

Optoisolated Inputs

All eight control inputs are fixed level-sensitive, dry optoisolated inputs, and are not polarity dependent. The nominal rated control voltage of 48, 125, or 250 Vdc must be specified when ordering. To assert an input, apply control voltage to the terminals assigned to that input. Each input is individually isolated, and a terminal pair is brought out for each input. There are no internal connections between inputs. The inputs will assert within 2 ms and draw approximately 4 mA of current at nominal voltage. For further information, see *General Specifications* in *Section 2*.

Output Contacts

30 A make

6 A carry

10 A interrupt for L/R <0.04 seconds at 125 Vdc

10 A interrupt for L/R <0.02 seconds at 250 Vdc

Closing (pickup for “a” contacts, dropout for “b” contacts): 1/4-cycle or less

Opening (dropout for “a” contacts, pickup for “b” contacts): 1/2-cycle or less (typical is 1/4-cycle)

Interface board 6 provides 12 output contacts. These 12 **High Current Interrupting** dry output contacts can interrupt 10 A of inductive current with an L/R <0.04 seconds at 125 Vdc. At 250 Vdc, they will interrupt 10 A of inductive current for an L/R <0.02 seconds. These outputs **are polarity dependent**. Notice the “+” polarity mark above terminals 218 and 318 in the following figures that are similar to the rear of the relay:

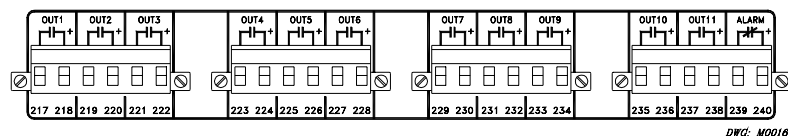


Figure H.16: Interface Board 6 Output Contacts (Board Position 1) (Plug-In Connections)

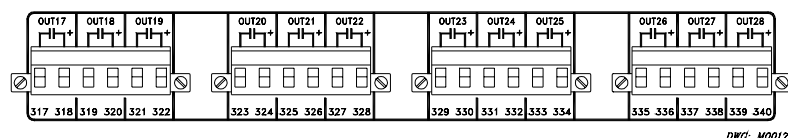


Figure H.17: Interface Board 6 Output Contacts (Board Position 2) (Plug-In Connections)

Configure the output contacts as “a” contacts or “b” contacts with solder jumpers. Figure H.18 shows the locations of the jumpers and explains the jumper positions. Contacts are factory-configured as “a” contacts (except the alarm contact which is “b”).

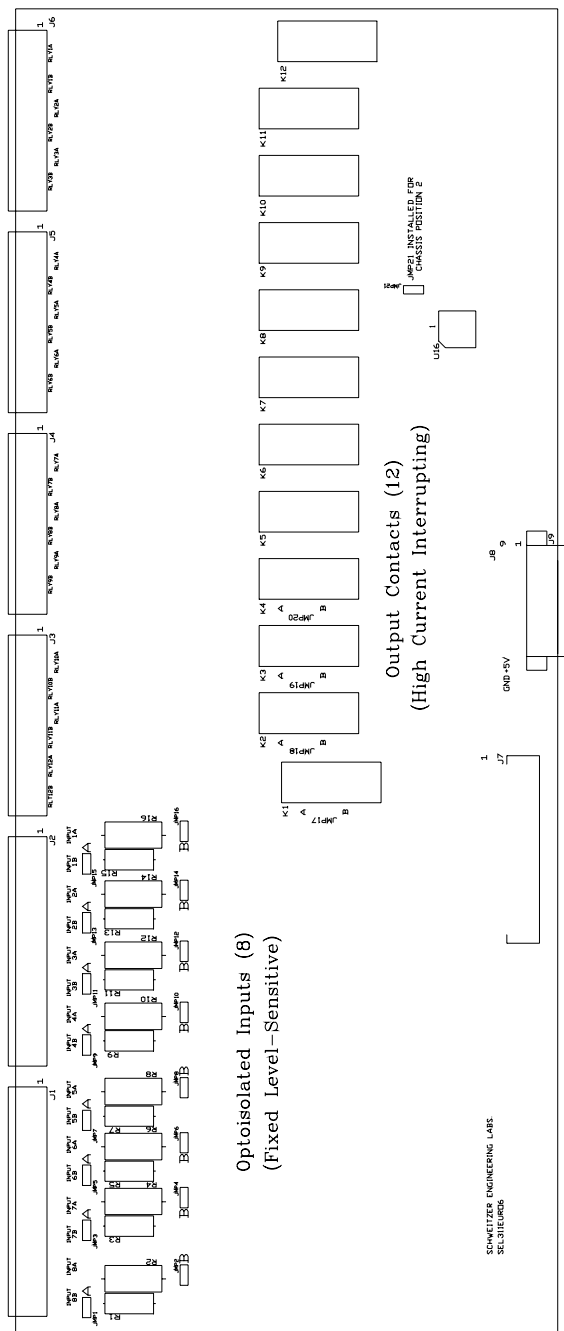


Figure H.18: Interface Board 6 Component Layout (Plug-In Connectors)

Output Contacts K1 - K4	
Solder Jumper Position	Operation
A	Contact closes when asserted
B	Contact opens when asserted

I/O Board Position Selection	
First I/O board position selected	JMP21 shorting block removed
Second I/O board position selected	JMP21 shorting block installed

DWG: M0033

APPENDIX I: DISTRIBUTED NETWORK PROTOCOL (DNP) 3.00

OVERVIEW

SEL-321-3 Relay supports Distributed Network Protocol (DNP) 3.00 Level 2 Slave protocol. This includes access to metering data, protection elements (Relay Word), contact I/O, targets, sequential events recorder, relay summary event reports, settings groups, time synchronization, and open/trip breaker. The SEL-321-3 supports DNP point remapping and virtual terminal object.

PORT CONFIGURATION

Configure a port for DNP by setting PROTO setting to DNP. You can select DNP on any of the available ports, however, you cannot select DNP on more than one port at a time. Use the following information to configure a port for DNP operation:

Label	Description	Default
SPEED	Port baud rate (300 - 19200) ¹	2400
DNPADR	DNP Address (0 - 65534)	0
TIMEOUT	Port time-out (0 - 30 minutes)	5
MODEM	Modem connected to port (Y, N) ²	N
MSTR	Modem startup string (up to 30 characters)	E0X0&D0S0=2
PH_NUM	Phone number to dial-out to (up to 30 characters)	18888888888
MDTIME	Time to attempt dial (5 - 300 seconds)	60
MDRETI	Time between dial-out attempts (5 - 3600 sec.)	120
MDRETN	Number of dial-out attempts (0 - 5)	3
ECLASSA	Class for analog event data (0 - 3, 0 for no event)	2
ECLASSB	Class for binary event data (0 - 3, 0 for no event)	2
ECLASSC	Class for counter event data (0 - 3, 0 for no event)	2
DECLPA	Current scaling (0 - 3 decimal places)	1
DECPLV	Voltage scaling (0 - 3 decimal places)	1
DECPLM	3-Phase power scaling (0 - 3 decimal places)	1
TIMERQ	Time of request interval (0 - 32767 min.)	0
STIMEO	Select/Operate time-out (0.0 - 30.0 sec.)	1.0
DRETRY	Data link retries (0 - 15)	3
DTIMEO	Data link time-out (0 - 5 sec.)	1
MINDLY	Minimum time from DCD to TX (0.00 - 1.00 sec.) ²	0.05
MAXDLY	Maximum time from DCD to TX (0.00 - 1.00 sec.) ²	0.10
PREDLY	Settle time from RTS on to TX (OFF, 0.00 - 30.00 sec.) ²	0
PSTDLY	Settle time after TX to RTS off (0.00 - 30.00 sec.) ²	0
ANADBA	Analog deadband for currents (0 - 32767 counts)	100

Label	Description	Default
ANADBV	Analog deadband for voltage (0 - 32767 counts)	100
ANADBM	Analog deadband for Three-Phase power (0 - 32767 counts)	100
ETIMEO	Event data confirmation time-out (0.1 - 50.0 sec.)	2.0
UNSOL	Enable unsolicited reporting (Y, N)	N
PUNSOL	Enable unsolicited reporting at power-up (Y, N)	N
REPADR	DNP Address to report to (0 – 65534)	0
NUMEVE	Number of events to transmit on (1 - 200)	10
AGEEVE	Age of oldest event to transmit on (0 - 60 sec.)	2.0

¹ **Note:** 2400 for Port 3

² **Note:** only for Port 1 and Port 2

The DNP function will restart and initialize if the DNP port settings are changed.

If desired, use the RTS signal to control an external transceiver and use the CTS as a DCD input to indicate whether the medium is in use. The DNP protocol will initiate transmission only if DCD is deasserted. The SEL-321-3 will send the next impending message when the DCD drops and the idle time expires. The relay selects the idle time randomly between the minimum and maximum allowed idle times (i.e., MAXDLY and MINDLY). In addition, the SEL-321-3 monitors received data and treats receipt of data as a DCD indication. If you are not providing the DCD, connect RTS to the CTS. When the SEL-321-3 transmits a DNP message, it delays transmitting after asserting RTS by at least the time in the PREDLY setting. After transmitting the last byte of the message, the SEL-321-3 delays for at least PSTDLY milliseconds before deasserting RTS. If the PSTDLY time delay is in progress (RTS still high) following a transmission, and another transmission is initiated, the SEL-321-3 transmits the message without completing the PSTDLY delay and without any preceding PREDLY delay. You can disable the RTS/CTS handshaking by setting PREDLY to OFF. In this case, RTS is forced high and CTS is ignored, with only received characters acting as a DCD indication. The timing is the same as above, except that the PREDLY functions as if it were set to 0, and RTS does not deassert after the PSTDLY time delay expires.

DATA-LINK OPERATION

Two important aspects of the data-link layer operation are the handling of the data-link confirmation and media access control. If a highly reliable communications link exists, you can disable the data-link access to significantly reduce the communications overhead. Otherwise, you should enable confirmation, and determine the number of allowable retries and the data-link time-out. The likelihood of the message getting corrupted is directly proportional to the communications channel noise. Thus, set the number of retries higher on noisy channels. Similarly, set the data-link time-out long enough to allow for the worst-case response of the master plus transmission time.

When planning the network you should consider methods to control the access to the media by various devices. The main concern in dealing with media access is the potential for collisions. If you do not plan on using unsolicited reporting from any of the devices on the network, there is no risk of collisions and you can simply set PREDLY to OFF. If you plan on using unsolicited reporting, you have to find a way to detect network usage to help avoid collisions. In a half-

duplex network, you can use the CTS input as a DCD to indicate network usage. The SEL-321-3 will also treat the receipt of character as network in-use indication. You can prevent collisions by using these indications in combination with the MINDLY and MAXDLY settings (as described above). There is still some risk of collisions, but the automatic use of application-layer confirmation with unsolicited messages is normally sufficient to detect these cases and handle the data re-transmission. In a full duplex network, there is no direct method to determine whether the network is in-use, hence there is no way to avoid collisions. Therefore, you should use data-link confirmation to confirm that messages get through successfully.

DATA ACCESS METHOD

Based on the capabilities of the system, you must choose a method for retrieving data on the DNP connection. The following table summarizes the main options, listed from least to most efficient, and indicates corresponding key related settings.

Table I.1: Data Access Methods

Data Retrieval Method	Description	Relevant SEL-321-3 Settings
Polled Static	The master polls for static (Class 0) data only.	Set CLASS = 0 Set UNSOL = N.
Polled Report-by-Exception	The master polls frequently for event data and occasionally for static data.	Set CLASS to a non-zero value, Set UNSOL = N.
Unsolicited Report-by-Exception	The slave devices send unsolicited event data to the master and the master occasionally sends integrity polls for static data.	Set CLASS to a non-zero value, Set UNSOL = Y, Set NUMEVE and AGEEVE according to how often messages are desired to be sent.
Quiescent	The master never polls and relies on unsolicited reports only.	Set CLASS to a non-zero value, Set UNSOL = Y, Set NUMEVE and AGEEVE according to how often messages are desired to be sent.

DEVICE PROFILE

The following is the device profile as specified in the *DNP 3.00 Subset Definitions* document:

DNP 3.00 DEVICE PROFILE DOCUMENT This document must be accompanied by a table having the following headings: Object Group Request Function Codes Response Function Codes Object Variation Request Qualifiers Response Qualifiers Object Name (optional)	
Vendor Name: Schweitzer Engineering Laboratories, Inc.	
Device Name: SEL-321-3	
Highest DNP Level Supported: For Requests Level 2 For Responses Level 2	Device Function: <input type="checkbox"/> Master <input checked="" type="checkbox"/> Slave
Notable objects, functions, and/or qualifiers supported in addition to the Highest DNP Levels Supported (the complete list is described in the attached table): <u>Supports enabling and disabling of unsolicited reports on a class basis.</u> <u>Supports virtual terminal object.</u>	
Maximum Data Link Frame Size (octets): Transmitted <u> 292 </u> Received (must be 292)	Maximum Application Fragment Size (octets): Transmitted <u> 2048 </u> (if > 2048, must be configurable) Received <u> 2048 </u> (must be > 249)
Maximum Data Link Re-tries: <input type="checkbox"/> None <input type="checkbox"/> Fixed at _____ <input checked="" type="checkbox"/> Configurable, range <u> 0 </u> to <u> 15 </u>	Maximum Application Layer Re-tries: <input checked="" type="checkbox"/> None <input type="checkbox"/> Configurable, range _____ to _____ (Fixed is not permitted)
Requires Data Link Layer Confirmation: <input type="checkbox"/> Never <input type="checkbox"/> Always <input type="checkbox"/> Sometimes If 'Sometimes', when? _____ <input checked="" type="checkbox"/> Configurable If 'Configurable', how? <u> by settings </u>	

Requires Application Layer Confirmation: <input type="checkbox"/> Never <input type="checkbox"/> Always (not recommended) <input checked="" type="checkbox"/> When reporting Event Data (Slave devices only) <input type="checkbox"/> When sending multi-fragment responses (Slave devices only) <input type="checkbox"/> Sometimes If 'Sometimes', when? _____ <input type="checkbox"/> Configurable If 'Configurable', how? _____																																																								
Timeouts while waiting for: <table style="width: 100%; border: none;"> <tr> <td style="width: 35%;">Data Link Confirm</td> <td style="width: 15%;"><input type="checkbox"/> None</td> <td style="width: 15%;"><input type="checkbox"/> Fixed at _____</td> <td style="width: 15%;"><input type="checkbox"/> Variable</td> <td style="width: 20%;"><input checked="" type="checkbox"/> Configurable</td> </tr> <tr> <td>Complete Appl. Fragment</td> <td><input checked="" type="checkbox"/> None</td> <td><input type="checkbox"/> Fixed at _____</td> <td><input type="checkbox"/> Variable</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Application Confirm</td> <td><input type="checkbox"/> None</td> <td><input type="checkbox"/> Fixed at _____</td> <td><input type="checkbox"/> Variable</td> <td><input checked="" type="checkbox"/> Configurable</td> </tr> <tr> <td>Complete Appl. Response</td> <td><input checked="" type="checkbox"/> None</td> <td><input type="checkbox"/> Fixed at _____</td> <td><input type="checkbox"/> Variable</td> <td><input type="checkbox"/> Configurable</td> </tr> </table> Others _____ Attach explanation if 'Variable' or 'Configurable' was checked for any timeout.		Data Link Confirm	<input type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input checked="" type="checkbox"/> Configurable	Complete Appl. Fragment	<input checked="" type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input type="checkbox"/> Configurable	Application Confirm	<input type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input checked="" type="checkbox"/> Configurable	Complete Appl. Response	<input checked="" type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input type="checkbox"/> Configurable																																			
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Complete Appl. Fragment	<input checked="" type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input type="checkbox"/> Configurable																																																				
Application Confirm	<input type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input checked="" type="checkbox"/> Configurable																																																				
Complete Appl. Response	<input checked="" type="checkbox"/> None	<input type="checkbox"/> Fixed at _____	<input type="checkbox"/> Variable	<input type="checkbox"/> Configurable																																																				
Sends/Executes Control Operations: <table style="width: 100%; border: none;"> <tr> <td style="width: 35%;">WRITE Binary Outputs</td> <td style="width: 15%;"><input type="checkbox"/> Never</td> <td style="width: 15%;"><input checked="" type="checkbox"/> Always</td> <td style="width: 15%;"><input type="checkbox"/> Sometimes</td> <td style="width: 20%;"><input type="checkbox"/> Configurable</td> </tr> <tr> <td>SELECT/OPERATE</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>DIRECT OPERATE</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>DIRECT OPERATE – NO ACK</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Count > 1</td> <td><input checked="" type="checkbox"/> Never</td> <td><input type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Pulse On</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Pulse Off</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Latch On</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Latch Off</td> <td><input type="checkbox"/> Never</td> <td><input checked="" type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Queue</td> <td><input checked="" type="checkbox"/> Never</td> <td><input type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> <tr> <td>Clear Queue</td> <td><input checked="" type="checkbox"/> Never</td> <td><input type="checkbox"/> Always</td> <td><input type="checkbox"/> Sometimes</td> <td><input type="checkbox"/> Configurable</td> </tr> </table> Attach explanation if 'Sometimes' or 'Configurable' was checked for any operation.		WRITE Binary Outputs	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	SELECT/OPERATE	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	DIRECT OPERATE	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	DIRECT OPERATE – NO ACK	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Count > 1	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Pulse On	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Pulse Off	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Latch On	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Latch Off	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Queue	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable	Clear Queue	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable
WRITE Binary Outputs	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
SELECT/OPERATE	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
DIRECT OPERATE	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
DIRECT OPERATE – NO ACK	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Count > 1	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Pulse On	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Pulse Off	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Latch On	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Latch Off	<input type="checkbox"/> Never	<input checked="" type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Queue	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
Clear Queue	<input checked="" type="checkbox"/> Never	<input type="checkbox"/> Always	<input type="checkbox"/> Sometimes	<input type="checkbox"/> Configurable																																																				
FILL OUT THE FOLLOWING ITEM FOR MASTER DEVICES ONLY:																																																								
Expects Binary Input Change Events: <input type="checkbox"/> Either time-tagged or non-time-tagged for a single event <input type="checkbox"/> Both time-tagged and non-time-tagged for a single event <input type="checkbox"/> Configurable (attach explanation)																																																								
FILL OUT THE FOLLOWING ITEMS FOR SLAVE DEVICES ONLY																																																								
Reports Binary Input Change Events when no specific variation requested: <input type="checkbox"/> Never <input checked="" type="checkbox"/> Only time-tagged <input type="checkbox"/> Only non-time-tagged <input type="checkbox"/> Configurable to send both, one or the other (attach explanation)	Reports time-tagged Binary Input Change Events when no specific variation requested: <input type="checkbox"/> Never <input checked="" type="checkbox"/> Binary Input Change With Time <input type="checkbox"/> Binary Input Change With Relative Time <input type="checkbox"/> Configurable (attach explanation)																																																							

Sends Unsolicited Responses: <input type="checkbox"/> Never <input checked="" type="checkbox"/> Configurable (attach explanation) <input type="checkbox"/> Only certain objects <input type="checkbox"/> Sometimes (attach explanation) <input checked="" type="checkbox"/> ENABLE/DISABLE UNSOLICITED Function codes supported	Sends Static Data in Unsolicited Responses: <input checked="" type="checkbox"/> Never <input type="checkbox"/> When Device Restarts <input type="checkbox"/> When Status Flags Change No other options are permitted.
Default Counter Object/Variation: <input type="checkbox"/> No Counters Reported <input type="checkbox"/> Configurable (attach explanation) <input checked="" type="checkbox"/> Default object <u>20</u> <input type="checkbox"/> Default variation <u>6</u> <input type="checkbox"/> Point-by-point list attached	Counters Roll Over at: <input type="checkbox"/> No Counters Reported <input type="checkbox"/> Configurable (attach explanation) <input checked="" type="checkbox"/> 16 Bits <input type="checkbox"/> 32 Bits <input type="checkbox"/> Other Value _____ <input type="checkbox"/> Point-by-point list attached
Sends Multi-Fragment Responses: <input checked="" type="checkbox"/> Yes <input type="checkbox"/> No	

In all cases of a configurable item within the device profile, the item is controlled by SEL-321-3 settings.

OBJECT TABLE

The following object table lists supported objects, functions, and qualifier code combinations.

Table I.2: SEL-321-3 DNP Object Table

Object			Request (supported)		Response (may generate)	
Obj.	Var. *default	Description	Function Codes (decimal)	Qualifier Codes (hex)	Function Codes (decimal)	Qualifier Codes (hex)
1	0	Binary Input - All Variations	1	0,1,6,7,8		
1	1	Binary Input	1	0,1,6,7,8	129	0,1,7,8
1	2*	Binary Input with Status	1	0,1,6,7,8	129	0,1,7,8
2	0	Binary Input Change - All Variations	1	6,7,8		
2	1	Binary Input Change without Time	1	6,7,8	129	17,28
2	2*	Binary Input Change with Time	1	6,7,8	129,130	17,28
2	3	Binary Input Change with Relative Time	1	6,7,8	129	17,28
10	0	Binary Output - All Variations	1	0,1,6,7,8		
10	1	Binary Output				
10	2*	Binary Output Status	1	0,1,6,7,8	129	0,1

Object			Request (supported)		Response (may generate)	
Obj.	Var. *default	Description	Function Codes (decimal)	Qualifier Codes (hex)	Function Codes (decimal)	Qualifier Codes (hex)
12	0	Control Block - All Variations				
12	1	Control Relay Output Block	3,4,5,6	17,28	129	echo of request
12	2	Pattern Control Block				
12	3	Pattern Mask				
20	0	Binary Counter - All Variations	1,7,8,9,10	0,1,6,7,8		
20	1	32-Bit Binary Counter	1,7,8,9,10	0,1,6,7,8	129	0,1
20	2	16-Bit Binary Counter	1,7,8,9,10	0,1,6,7,8	129	0,1
20	3	32-Bit Delta Counter				
20	4	16-Bit Delta Counter				
20	5	32-Bit Binary Counter without Flag	1,7,8,9,10	0,1,6,7,8	129	0,1,7,8
20	6*	16-Bit Binary Counter without Flag	1,7,8,9,10	0,1,6,7,8	129	0,1,7,8
20	7	32-Bit Delta Counter without Flag				
20	8	16-Bit Delta Counter without Flag				
21	0	Frozen Counter - All Variations	1	0,1,6,7,8	129	0,1
21	1	32-Bit Frozen Counter	1	0,1,6,7,8	129	0,1
21	2	16-Bit Frozen Counter	1	0,1,6,7,8	129	0,1
21	3	32-Bit Frozen Delta Counter				
21	4	16-Bit Frozen Delta Counter				
21	5	32-Bit Frozen Counter with Time of Freeze				
21	6	16-Bit Frozen Counter with Time of Freeze				
21	7	32-Bit Frozen Delta Counter with Time of Freeze				
21	8	16-Bit Frozen Delta Counter with Time of Freeze				
21	9	32-Bit Frozen Counter without Flag	1	0,1,6,7,8	129	0,1
21	10*	16-Bit Frozen Counter without Flag	1	0,1,6,7,8	129	0,1
21	11	32-Bit Frozen Delta Counter without Flag				
21	12	16-Bit Frozen Delta Counter without Flag				
22	0	Counter Change Event – All Variations	1	6,7,8		
22	1	32-Bit Counter Change Event without Time	1	6,7,8	129	17,28
22	2*	16-Bit Counter Change Event without Time	1	6,7,8	129,130	17,28
22	3	32-Bit Delta Counter Change Event without Time				
22	4	16-Bit Delta Counter Change Event without Time				
22	5	32-Bit Counter Change Event with Time	1	6,7,8	129	17,28
22	6	16-Bit Counter Change Event with Time	1	6,7,8	129	17,28

Object			Request (supported)		Response (may generate)	
Obj.	Var. *default	Description	Function Codes (decimal)	Qualifier Codes (hex)	Function Codes (decimal)	Qualifier Codes (hex)
22	7	32-Bit Delta Counter Change Event with Time				
22	8	16-Bit Delta Counter Change Event with Time				
23	0	Frozen Counter Event – All Variations				
23	1	32-Bit Frozen Counter Event without Time				
23	2	16-Bit Frozen Counter Event without Time				
23	3	32-Bit Frozen Delta Counter Event without Time				
23	4	16-Bit Frozen Delta Counter Event without Time				
23	5	32-Bit Frozen Counter Event with Time				
23	6	16-Bit Frozen Counter Event with Time				
23	7	32-Bit Frozen Delta Counter Event with Time				
23	8	16-Bit Frozen Delta Counter Event with Time				
30	0	Analog Input – All Variations	1	0,1,6,7,8		
30	1	32-Bit Analog Input	1	0,1,6,7,8	129	0,1,7,8
30	2	16-Bit Analog Input	1	0,1,6,7,8	129	0,1,7,8
30	3	32-Bit Analog Input without Flag	1	0,1,6,7,8	129	0,1,7,8
30	4*	16-Bit Analog Input without Flag	1	0,1,6,7,8	129	0,1,7,8
31	0	Frozen Analog Input – All Variations				
31	1	32-Bit Frozen Analog Input				
31	2	16-Bit Frozen Analog Input				
31	3	32-Bit Frozen Analog Input with Time of Freeze				
31	4	16-Bit Frozen Analog Input with Time of Freeze				
31	5	32-Bit Frozen Analog Input without Flag				
31	6	16-Bit Frozen Analog Input without Flag				
32	0	Analog Change Event – All Variations	1	6,7,8		
32	1	32-Bit Analog Change Event without Time	1	6,7,8	129	17,28
32	2*	16-Bit Analog Change Event without Time	1	6,7,8	129,130	17,28
32	3	32-Bit Analog Change Event with Time	1	6,7,8	129	17,28
32	4	16-Bit Analog Change Event with Time	1	6,7,8	129	17,28
33	0	Frozen Analog Event – All Variations				
33	1	32-Bit Frozen Analog Event without Time				
33	2	16-Bit Frozen Analog Event without Time				
33	3	32-Bit Frozen Analog Event with Time				
33	4	16-Bit Frozen Analog Event with Time				

Object			Request (supported)		Response (may generate)	
Obj.	Var. *default	Description	Function Codes (decimal)	Qualifier Codes (hex)	Function Codes (decimal)	Qualifier Codes (hex)
40	0	Analog Output Status – All Variations	1	0,1,6,7,8		
40	1	32-Bit Analog Output Status	1	0,1,6,7,8	129	0,1,7,8
40	2*	16-Bit Analog Output Status	1	0,1,6,7,8	129	0,1,7,8
41	0	Analog Output Block – All Variations				
41	1	32-Bit Analog Output Block	3,4,5,6	17,28	129	echo of request
41	2	16-Bit Analog Output Block	3,4,5,6	17,28	129	echo of request
50	0	Time and Date – All Variations				
50	1	Time and Date	1,2	7,8 index = 0	129	07, quantity=1
50	2	Time and Date with Interval				
51	0	Time and Date CTO – All Variations				
51	1	Time and Date CTO				
51	2	Unsynchronized Time and Date CTO				07, quantity=1
52	0	Time Delay – All Variations				
52	1	Time Delay Coarse				
52	2	Time Delay Fine			129	07, quantity=1
60	0	All Classes of Data	1,20,21	6		
60	1	Class 0 Data	1	6,7,8	129	
60	2	Class 1 Data	1,20,21	6,7,8	129,130	
60	3	Class 2 Data	1,20,21	6,7,8	129,130	
60	4	Class 3 Data	1,20,21	6,7,8	129,130	
70	1	File Identifier				
80	1	Internal Indications	2	0,1 index = 7		
81	1	Storage Object				
82	1	Device Profile				
83	1	Private Registration Object				
83	2	Private Registration Object Descriptor				
90	1	Application Identifier				
100	1	Short Floating Point				
100	2	Long Floating Point				
100	3	Extended Floating Point				

Object			Request (supported)	Response (may generate)		
Obj.	Var. *default	Description	Function Codes (decimal)	Qualifier Codes (hex)	Function Codes (decimal)	Qualifier Codes (hex)
101	1	Small Packed Binary-Coded Decimal				
101	2	Medium Packed Binary-Coded Decimal				
101	3	Large Packed Binary-Coded Decimal				
112	All	Virtual Terminal Output Block	2	6		
113	All	Virtual Terminal Event Data	1	6	129,130	17,28
No object						

DATA MAP

The following is the default object map supported by the SEL-321-3.

Table I.3: SEL-321-3 DNP Data Map

DNP Object Type	Index	Description
01,02	000 – 799	Relay Word, where index is divided by 8 to get the row, and the remainder is used as a bit index. Check Table I.4 for detail.
01,02	800 – 1599	Relay Word from the SER, encoded same as inputs 000 – 799 with 800 added.
01,02	1600 – 1615	Relay front panel targets, where 1615 is EN, 1608 is 50,1607 is INST and 1600 is ZONE4.
01,02	1616	Relay Disabled.
01,02	1617	Relay diagnostic failure.
01,02	1618	Relay diagnostic warning.
01,02	1619	New relay event available.
01,02	1620	Relay restart.
01,02	1621	Settings change.
10,12	00 – 15	Remote bits RB1 – RB16.
10,12	16	Open breaker command.
10,12	17	Close breaker command.
10,12	18 – 25	Remote bit pairs RB1 – RB15.
10,12	26	Open/Close pair for breaker.
10,12	27	Reset front-panel targets.
10,12	28	Read next relay event.

DNP Object Type	Index	Description
20,21,22	00	Active settings group.
20,21,22	01	Number of unread event reports.
30,32	00	IA magnitude (A).
30,32	01	IB magnitude (A).
30,32	02	IC magnitude (A).
30,32	03	IAB magnitude (A).
30,32	04	IBC magnitude (A).
30,32	05	ICA magnitude (A).
30,32	06	VA magnitude (kV).
30,32	07	VB magnitude (kV).
30,32	08	VC magnitude (kV).
30,32	09	VAB magnitude (kV).
30,32	10	VBC magnitude (kV).
30,32	11	VCA magnitude (kV).
30,32	12	3 phase in MW.
30,32	13	3 phase in MVAR.
30,32	14	Fault type (see tables on page I-13 for definition).
30,32	15	Fault location.
30,32	16	Fault frequency.
30,32	17	Fault targets.
30,32	18	Magnitude of memorized V1 (kV).
30,32	19	Angle of memorized V1.
30,32	20	Fault settings group.
30,32	21-23	Fault time in DNP format (high, middle, and low 16 bits).
40,41	00	Active settings group.

Binary inputs (objects 1 and 2) are supported as defined by the previous table. Binary inputs 0 – 799 and 1600 – 1619 are scanned approximately once every 500 ms to generate events. When time is reported with these event objects, it is the time at which the scanner observed the bit change. This may be significantly delayed from when the original source change and should not be used for sequence-of-events determination. In order to determine an element's point index, see Table I.4. It is derived from the Relay Word Bits tables in **Section 2: Specifications**. Locate the element in question in the table and note the Relay Word row number. From that row number, multiply that row number by 8. This is the index of the right-most element of the Relay Word row of the element in question. Count over to the original element and add that to get the point index. Binary Inputs 800 – 1599 are derived from the Sequential Events Recorder (SER) and carry the time stamp of actual occurrence. Add 800 to the Binary Input Point column to get

the point mapping for points 800 – 1599. Static reads from these inputs will show the same data as a read from the corresponding index in the 0 – 799 group. Only points that are actually in the SER list (**SET R**) will generate events in the 800 – 1599 group.

Control Relay Output Block objects (object 12, variation 1) are supported. The Close/Trip bits take precedence over the control field. If either the Trip or Close bit is set, one of the other control field bits must be set as well. The control field is interpreted as follows:

Index	Close(0x4X)	Trip(0x8X)	Latch On (3)	Latch Off (4)	Pulse On (1)	Pulse Off(2)
0-15	Set	Clear	Set	Clear	Pulse	Clear
16	Open breaker	Do nothing	Open breaker	Do nothing	Open breaker	Do nothing
17	Close breaker	Do nothing	Close breaker	Do nothing	Close breaker	Do nothing
18	Pulse RB2	Pulse RB1	Pulse RB2	Pulse RB1	Pulse RB2	Pulse RB1
19	Pulse RB4	Pulse RB3	Pulse RB4	Pulse RB3	Pulse RB4	Pulse RB3
20	Pulse RB6	Pulse RB5	Pulse RB6	Pulse RB5	Pulse RB6	Pulse RB5
21	Pulse RB8	Pulse RB7	Pulse RB8	Pulse RB7	Pulse RB8	Pulse RB7
22	Pulse RB10	Pulse RB9	Pulse RB10	Pulse RB9	Pulse RB10	Pulse RB9
23	Pulse RB12	Pulse RB11	Pulse RB12	Pulse RB11	Pulse RB12	Pulse RB11
24	Pulse RB14	Pulse RB13	Pulse RB14	Pulse RB13	Pulse RB14	Pulse RB13
25	Pulse RB16	Pulse RB15	Pulse RB16	Pulse RB15	Pulse RB16	Pulse RB15
26	Close breaker	Open breaker	Close breaker	Open breaker	Close breaker	Open breaker
27-28	Pulse	Do nothing	Pulse	Do nothing	Pulse	Do nothing

Note: The pulse interval (in millisecond unit) can be decided by the master station by setting On-Time and Off-Time when Pulse On or Pulse Off function is used, the default time interval is 1/8 cycle. If On-Time and Off-Time are set, the RBx will be set in On-Time and clear in Off-Time.

The Open and Close breaker functions will behave in the same manner as the **OPEN/CLOSE** command listed in *Section 3: Communications*.

For the paired operation for remote bit with the combination of Close/Trip and Pulse On/Off functions, the master station can determine the pulse interval in millisecond by using Time On/Off in the Pulse On/Off function. Without providing time interval (Time On/Off are equal to zero), the Pulse will use default time, i.e., 1/8 cycle, for the operation. The paired operation with the combination of Close/Trip and Latch On/Off functions will only use the default time for the operation. Qualifier codes of 17h and 28h are supported in both the request and response messages. Only Select (3), Operate (4), Direct Operate (5), and Direct Operate, No Ack (6) function codes are allowed with these objects. The Select/Operate time-out is given by setting STIMEO.

Binary Output status (Object 10 variation 2) is supported. Only the read function code (1) is allowed on the object. The response from reading point 0 – 15 will show the on-line bit set and the state of the requested remote bit, and the response from reading point 16 – 28 will show the on-line bit set and a state of 0.

The SEL-321-3 supports Binary Counters (object 20) and Frozen Counters (object 21). The application of Freeze Clear (function code 9 and 10) to index 1 of the Binary Counter will clear the number of unread event reports in the Binary Counter. Event Counters (object 22) are supported with variations 0, 1, 2, 5, and 6. Counters are scanned approximately once every 500 ms and the event time stamp is based on this scan.

Analog Input objects (objects of 30 and 32) are supported, as defined by the preceding table. The values are reported in primary units. Analog inputs 0 - 5 are scaled according to the DECPLA setting (e.g., if DECPLA is 2, then the value is multiplied by 100) unless scaled in the map command. Analog inputs 6 - 11 are scaled according to the DECPLV setting, and 12 - 13 are scaled according to the DECPLM setting. The remaining analogs are not scaled. A dead-band check is done after any scaling is applied. Event class messages are generated whenever an input current changes beyond the value given by the ANADBA setting, or input voltage changes beyond the ANADBV setting, or input power changes beyond the ANADBM setting. Analog inputs are scanned at approximately a 1 second rate, except for analogs 14 - 23. During a scan, all events generated will use the time at which the scan was initiated. Analogs 14 - 23 are derived from the history queue data for the most recently read fault. Analog 14 is a 16 bit composite value, where the upper byte is defined as follows:

Value	Event Cause
1	Triggered by TRIGGER command
2	Triggered by EXT(external trigger)
3	Triggered by TPA,TPB,TPC, or 3PT, no fault
4	Triggered by MER SELOGIC control equations
5	Triggered by TPA,TPB,TPC, or 3PT, with fault

And the lower byte is defined as follows:

Value	Fault Type
0	Indeterminate
1	A Phase
2	B Phase
4	C Phase
8	Ground

The lower byte may contain any combination of the above bits (e.g., 6 means B to C fault and 9 is A to ground fault). If Analog index 14 is 0, it means that there is no more new event report available.

Analog 17 is a 16 bit composite value for fault targets. The upper byte reflects the upper row of LED and the lower byte reflects the lower row of LED on the front panel.

Analog Outputs (objects 40 and 41) are supported as defined by the preceding table. Flags returned with object 40 responses are always set to 0. The Control Status field of object 41 requests is ignored. If the value written to index 0 is outside of the range 1 through 6, the relay will not accept the value and will return a hardware error status.

Table I.4: SEL-321-3 Relay Binary Input Lookup Table

Row	SEL-321-3 Relay Word Bits								Binary Input Point
0	INST	TIME	COMM	SOTF	ZONE1	ZONE2	ZONE3	ZONE4	7–0
1	EN	A	B	C	G	Q	51	50	15–8
2	Z4G	Z3G	Z2G	Z1G	M4P	M3P	M2P	M1P	23–16
3	Z4GT	Z3GT	Z2GT	LOP	M4PT	M3PT	M2PT	OPA	31–24
4	67Q4	67Q3	67Q2	67Q1	67N4	67N3	67N2	67N1	39–32
5	67Q4T	67Q3T	67Q2T	OST	67N4T	67N3T	67N2T	OSB	47–40
6	PD1	3P27	27L	50H	50MF	51NT	51QT	51PT	55–48
7	ZLOAD	SOTFE	TCM	ANYTRP	3PO	SPO	REJO	PD2	63–56
8	3P50R	51NP	51QP	51PP	50G	50PP	50M	50L	71–64
9	50Q4	50Q3	50Q2	50Q1	50N4	50N3	50N2	50N1	79–72
10	50ABC	X6ABC	X5ABC	3PT	TPC	TPB	TPA	32QF	87–80
11	3P59	59L	59N	59PR	59PB	59QL	59PL	50Q	95–88
12	BTX	SPTI	STOP	START	FIDEN	FSC	FSB	FSA	103–96
13	32QR	Z1X	CC	EKEY	Z3RB	ATB	ECTT	KEY	111–104
14	XAG4	XAG3	XAG2	XAG1	MAG4	MAG3	MAG2	MAG1	119–112
15	XBG4	XBG3	XBG2	XBG1	MBG4	MBG3	MBG2	MBG1	127–120
16	XCG4	XCG3	XCG2	XCG1	MCG4	MCG3	MCG2	MCG1	135–128
17	MBC4	MBC3	MBC2	MBC1	MAB4	MAB3	MAB2	MAB1	143–136
18	SPOC	SPOB	SPOA	Z1	MCA4	MCA3	MCA2	MCA1	151–144
19	50HH	OSTI	50CA	50BC	50AB	Z4	Z3	Z2	159–152
20	RBAD	CBAD	LBOK	ROK	3PTC	3PTB	3PTA	TOP	167–160
21	LP1	SS3	SS2	SS1	EXT	DT	BT	PT	175–168
22	EXTUL	PARC	PARB	PARA	SPTE	PTXFR	LP2	LOG	183–176
23	LP3	CLOSE	52AC2	52AC1	52AB2	52AB1	52AA2	52AA1	191–184
24	LP5	LP4	TCMC2	TCMC1	TCMB2	TCMB1	TCMA2	TCMA1	199–192
25	DTA	DTB	DTC	LP6	LP7	LP8	LP9	LP10	207–200
26	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	215–208
27	RB16	RB15	RB14	RB13	RB12	RB11	RB10	RB9	223–216
28	ZT	Z	YT	Y	XT	X	W	V	231–224
29	RAG4	RAG3	RAG2	RAG1	MER	MTO	MTU	MTCS	239–232
30	RCG4	RCG3	RCG2	RCG1	RBG4	RBG3	RBG2	RBG1	247–240
31	50AL4	50AL3	50AL2	50AL1	VPOLV	N3PT	L3PT	PTRX	255–248
32	50CL4	50CL3	50CL2	50CL1	50BL4	50BL3	50BL2	50BL1	263–256
33	50G4	50G3	50G2	50G1	50CL	50BL	50AL	*	271–264
34	OSB4	OSB3	OSB2	OSB1	50PP4	50PP3	50PP2	50PP1	279–272
35	TS	TC	TB	TA	ZLOUT	ZLIN	ILOP	50P	287–280
36	SPT_EN	*	*	*	*	52AC	52AB	52AA	295–288
37	50AB4	50AB3	50AB2	50AB1	ATPC	ATPB	ATPA	50PPL	303–296
38	50CA4	50CA3	50CA2	50CA1	50BC4	50BC3	50BC2	50BC1	311–304
39	*	51NR	51QR	51PR	*	*	*	*	319–312

Row	SEL-321-3 Relay Word Bits (One I/O Board Version)								Binary Input Point
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8	327–320
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM	335–328
42	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1	343–336
43	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS	351–344
44	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1	359–352
45	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1	367–360

Row	SEL-321-3 Relay Word Bits (Two I/O Board Version)								Binary Input Point
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8	327–320
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM	335–328
42	OUT17	OUT18	OUT19	OUT20	OUT21	OUT22	OUT23	OUT24	343–336
43	OUT25	OUT26	OUT27	OUT28	OUT29	OUT30	OUT31	OUT32	351–344
44	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1	359–352
45	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS	367–360
46	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1	375–368
47	IN16	IN15	IN14	IN13	IN12	IN11	IN10	IN9	383–376
48	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1	391–384

Relay Summary Event Data

The counter index 1 will tell how many unread relay summary event report available. The event queue for DNP can only store a maximum of 15 events. Loading the oldest event will leave room for a new event to be stored in the event queue. In order to load the next available relay event summary, the master should pulse binary output point 28. This will cause the event summary analogs (points 14 – 23) to be loaded with information from the next oldest relay event summary and the corresponding event is generated (object 32). Since the summary data is stored in a first-in, first-out manner, loading the next event will cause the data from the previous load to be discarded. The event summary analogs will retain this information until the next event is loaded. If no further event summaries are available, attempting to load the next event will cause the event type analog (point 14) to be set to 0.

POINT REMAPPING

The **DNP** command is available to view and re-map the DNP data. This command is available at level 1 for viewing data, but only from level 2 can it be used to re-map the DNP map.

Command Syntax: DNP [A|B|S|T]

 DNP [AI|AO|BI|BO|C|D] [VIEW]

The DNP analog input, analog output, counter, binary output, and binary input points may be remapped via the **DNP** command. The map is composed of five lists of indices: one for the analog inputs (30 and 32), one for the binary inputs (1 and 2), one for the binary outputs (10 and 12), one for the analog outputs (40 and 41), and the other for the counters (20 and 22). The indices correspond to those given by the relay's DNP data map. The order in which they occur in the list determines the index that the corresponding value is reported to the DNP master. If a value is not in the list, it is not available to the DNP master. All points of the corresponding type may be included in the list, but must only occur once. The maps are stored in nonvolatile memory and are protected with a checksum. The **DNP** command is only available if DNP has been selected on one of the ports.

If the **DNP** command is issued without parameters, the relay displays all of the maps with the following format:

```
=>DNP <ENTER>

Binary Inputs  = 112 28 17 35 1 56 57 58 59 60 61 62 63 64 65 \
                66 67 100 101 102 103
Binary Outputs = Default Map
Counters       = Default Map
Analog Inputs  = 12 2 7 3 1 6
Analog Outputs = Off

=>
```

If the **DNP** command is issued with an object type specified (AI, AO, BI, BO, and C) and the VIEW parameter, the relay displays only the corresponding map. The S parameter is equivalent to AI VIEW and the T parameter is equivalent to BI VIEW; they are available for consistency with the older products. If the map checksum is determined to be invalid, the map will be reported as corrupted during a display command, as follows:

```
=>DNP BI VIEW <ENTER>

Binary Inputs  = Map Corrupted

=>
```

The **D** parameter is available in the **DNP** command to allow user to reset the DNP map to default value:

```
=>DNP D <ENTER>
Change DNP to default map (Y/N) ?Y <ENTER>
Default DNP map is installed

=>DNP <ENTER>
Analog Inputs = Default Map
Binary Inputs = Default Map
Analog Outputs = Default Map
Binary Outputs = Default Map
Counters = Default Map
```

If the **DNP** command is issued with just an object type specifier (AI, AO, BI, BO, C) at level 2 or greater, the relay asks the user to enter indices for the corresponding list. (The A parameter is the same as AI and B is the same as BI; these parameters are available for consistency with older products.) The relay accepts lines of indices until a line without a final continuation character (\) is entered. Each line of input is constrained to 80 characters, but all the points may be remapped, using multiple lines with continuation characters (\) at the end of the intermediate lines. If a single blank line is entered as the first line, the remapping is disabled for that type (i.e., the relay uses the default map). If a single entry of OFF or NA is entered, all objects of that type will be disabled. For example, the first example remap could be produced with the followings:

```
==>DNP BI <ENTER>

Enter the new DNP Binary Input map = 112 28 17 \<ENTER>
35 1 56 57 58 59 60 61 62 63 64 65 66 67 100 101 102 \<ENTER>
103<ENTER>

Save Settings (Y/N)? Y <ENTER>

==>DNP AI <ENTER>

Enter the new DNP Analog Input map = <ENTER>

Save Settings (Y/N)? Y <ENTER>

==>DNP AO <ENTER>

Enter the new DNP Analog Output map = OFF <ENTER>

Save Settings (Y/N)? Y <ENTER>

==>
```

The **DNP** command will report an error if an index is used twice, an invalid index is used, or nonnumeric data is entered:

```
xx is referenced more than once, changes not saved

xx is not a valid index, changes not saved

Invalid format, changes not saved
```

In addition to remapping, these commands can be used on analog inputs to create custom scaling and dead-bands per point (applicable only to Object 30, indexes 0 - 13). Scaling is done by adding a semicolon and scaling factor to a point reference. This scaling factor will be multiplied to the base value before reporting it and it will override the appropriate DECPLx setting. Dead-bands are added using a colon and dead-band count. This dead-band will override the appropriate ANADBx setting. For example:

```
==>DNP AI <ENTER>

Enter the new DNP Analog Input map
12;5 2;0.2 7:10 1;1:15<ENTER>

==>
```

These settings will cause the value at index 12 (now at index 0) to be multiplied by five before it is reported. Similarly, the value at index 2 (now at index 1) will be multiplied by 0.2 before it is reported. Both of these values will use the default dead-band. The value at index 7 (now at index 2) is left for default scaling, but uses a dead-band of +/- 10 counts. Similarly, the value that was at index 1 (now at index 3) is now not scaled (multiplied by 1) and uses a dead-band of +/- 15 counts.

The scaling range is from 0.001 to 1000. The dead-band setting is less than 32768.

MODEM SUPPORT

The modem handling will only be applied when the port settings include the following:

PROTOCOL = DNP

MODEM = Y

On power-up and settings change, the relay shall initialize the modem by issuing the string "+++AT" followed by the MSTR string and <CR>. This will initialize the modem. The MSTR (modem string) is a port setting visible only when the protocol setting is DNP. The MSTR setting is a series of ASCII characters that initialize the modem by sending the modem a series of commands.

If someone calls in, the modem will send "RING" and "CONNECT" messages to the relay. These messages, as well as all messages received while DCD is low, shall be ignored. All DNP messages received while connected shall be treated normally.

If the relay needs to send an unsolicited message and it is not currently connected, it must attempt to make a connection by sending the string "+++ATDT" followed by the phone number and <CR>. It shall then wait for a "CONNECT" message. Once "CONNECT" is received and CTS is asserted, the relay can consider itself connected and continue its transaction. If connection is not achieved within MDTIME seconds of initiating the phone call, the relay shall issue the command "+++ATH<CR>" and wait at least MDRETI seconds before trying again and try MDRETN times before giving up. If it fails to connect in the first try, it will try again at a later time every six hours.

If the relay initiates a connection, it shall disconnect once there have been no transactions for TIMEOUT time, using the disconnect command "+++ATH<CR>". Also, if an outside caller connects to the modem in the SEL-321-3, the SEL-321-3 will disconnect the modem if there have been no transactions for the TIMEOUT time.

Note 1: Because of the connection requirements described here, it will not be possible to use hardware flow control (RTS/CTS) with the modem. This means that it is important to select a port baud rate low enough that the modem connection will not end up slower, or there will be a high likelihood of losing characters.

Note 2: The CTS signal shall be treated as a data carrier detect (DCD). This means that the message may only be transmitted while DCD is asserted. (Normally, a modem will be connected with a C220 or C222 cable that ties the DCD of the modem to the CTS.)

VIRTUAL TERMINAL

The purpose of this Virtual Terminal (VT) Protocol is to allow ASCII data transfers between a master and a SEL relay over a DNP port. DNP 3.00 objects 112 and 113 are used for embedding the ASCII communications over the DNP port. At the master each slave channel is assigned a Virtual Port number. Only one channel, with a Virtual Port number of "0" (for ASCII), is supported in the relay.

Object 112 is used with the Function code Write (FC=2) to send data from the Master side to the Slave side (IED) of the link.

Object 113 is used to send data from the relay side to the Master side of the link. Master devices may use only Function codes Read (FC=1). The relay uses only Function codes Response (FC=129).

The procedure for accessing these objects is as follows. Master devices transmit data to relay devices by writing one or more of object 112 to a relay using the Virtual Port number as the DNP point number. Relays send information to the Master using the Virtual Port number by responding to a Master READ (FC=1) request of object 113. Messages can flow in either direction at any time, however the relay sends messages only at the request of the Master. There are no explicit procedures for the initiation or conclusion of a VT session (i.e., implicit connections exist by the mere presence of a VT-compatible Slave IED).

Virtual terminal supports all ASCII commands listed in the *Command Summary* at the end of **Section 3: Communications**. You do not need a password to login to a virtual terminal session through a DNP port, but you will need the appropriate password to access different levels for setting changes and breaker operations. A virtual terminal session times out in the same way as an ASCII session.

SEL-321-3 RELAY DNP PORT - SET P SETTINGS SHEET

Protocol (SEL, LMD, DNP, MB, MB8)	PROTO	=	DNP
Port baud rate (300, 1200, 2400, 4800, 9600, 19200)	SPEED	=	
DNP Address (0 – 65534)	DNPADR	=	
Port time-out (0 – 30 minutes)	TIMEOUT	=	
Modem connected to port (Y, N)	MODEM	=	
Modem startup string (up to 30 characters)	MSTR	=	
Phone number to dial-out to (up to 30 characters)	PH_NUM	=	
Time to attempt dial (5 – 300 seconds)	MDTIME	=	
Time between dial-out attempts (5 – 3600 seconds)	MDRETI	=	
Number of dial-out attempts (0 – 5)	MDRETN	=	
Class for analog event data (0 – 3, 0 for no event)	ECLASSA	=	
Class for binary event data (0 – 3, 0 for no event)	ECLASSB	=	
Class for counter event data (0 – 3, 0 for no event)	ECLASSC	=	
Current scaling (0 – 3 decimal places)	DECLPA	=	
Voltage scaling (0 – 3 decimal places)	DECLPV	=	
3-Phase power scaling (0 – 3 decimal places)	DECLPM	=	
Time of request interval (0 – 32767 min, 0 for never)	TIMERQ	=	
Select/Operate time-out interval (0.0 – 30.0 sec)	STIMEO	=	
Data-link retries (0 – 15)	DRETRY	=	
Data link time-out interval (0 – 5 sec)	DTIMEO	=	
Minimum time from DCD to TX (0.00 – 1.00 sec)	MINDLY	=	
Maximum time from DCD to TX (0.00 – 1.00 sec)	MAXDLY	=	
Settle time from RTS on to TX (OFF, 0.00 – 30.00 sec)	PREDLY	=	
Settle time from TX to RTS off (0.00 – 30.00 sec)	PSTDLY	=	
Analog deadband for current (0 – 32767 counts)	ANADBA	=	
Analog deadband for voltage (0 – 32767 counts)	ANADBV	=	
Analog deadband for 3-Phase power (0 – 32767 counts)	ANADBM	=	
Event data confirmation time-out (0.1 – 50.0 sec)	ETIMEO	=	
Enable unsolicited reporting (Y, N)	UNSOL	=	
Enable unsolicited messages at power-up (Y, N)	PUNSOL	=	
DNP Address to report to (0 – 65534)	REPADR	=	
Number of events to transmit on (1 – 200)	NUMEVE	=	
Age of oldest event to transmit on (0.0 – 60.0 sec)	AGEEVE	=	

SEL-321-3 TARGET INFORMATION

SEL-321-3 Relay

TAR	Status Indicators							
0	INST	TIME	COMM	SOTF	ZONE1	ZONE2	ZONE3	ZONE4
1	EN	A	B	C	G	Q	51	50
2	Z4G	Z3G	Z2G	Z1G	M4P	M3P	M2P	M1P
3	Z4GT	Z3GT	Z2GT	LOP	M4PT	M3PT	M2PT	OPA
4	67Q4	67Q3	67Q2	67Q1	67N4	67N3	67N2	67N1
5	67Q4T	67Q3T	67Q2T	OST	67N4T	67N3T	67N2T	OSB
6	PD1	3P27	27L	50H	50MF	51NT	51QT	51PT
7	ZLOAD	SOTFE	TCM	ANYTRP	3PO	SPO	REJO	PD2
8	3P50R	51NP	51QP	51PP	50G	50PP	50M	50L
9	50Q4	50Q3	50Q2	50Q1	50N4	50N3	50N2	50N1
10	50ABC	X6ABC	X5ABC	3PT	TPC	TPB	TPA	32QF
11	3P59	59L	59N	59PR	59PB	59QL	59PL	50Q
12	BTX	SPTI	STOP	START	FIDEN	FSC	FSB	FSA
13	32QR	Z1X	CC	EKEY	Z3RB	ATB	ECTT	KEY
14	XAG4	XAG3	XAG2	XAG1	MAG4	MAG3	MAG2	MAG1
15	XBG4	XBG3	XBG2	XBG1	MBG4	MBG3	MBG2	MBG1
16	XCG4	XCG3	XCG2	XCG1	MCG4	MCG3	MCG2	MCG1
17	MBC4	MBC3	MBC2	MBC1	MAB4	MAB3	MAB2	MAB1
18	SPOC	SPOB	SPOA	Z1	MCA4	MCA3	MCA2	MCA1
19	50HH	OSTI	50CA	50BC	50AB	Z4	Z3	Z2
20	RBAD	CBAD	LBOK	ROK	3PTC	3PTB	3PTA	TOP
21	LP1	SS3	SS2	SS1	EXT	DT	BT	PT
22	EXTUL	PARC	PARB	PARA	SPTE	PTXFR	LP2	LOG
23	LP3	CLOSE	52AC2	52AC1	52AB2	52AB1	52AA2	52AA1
24	LP5	LP4	TCMC2	TCMC1	TCMB2	TCMB1	TCMA2	TCMA1
25	DTA	DTB	DTC	LP6	LP7	LP8	LP9	LP10
26	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1
27	RB16	RB15	RB14	RB13	RB12	RB11	RB10	RB9
28	ZT	Z	YT	Y	XT	X	W	V
29	RAG4	RAG3	RAG2	RAG1	MER	MTO	MTU	MTCS
30	RCG4	RCG3	RCG2	RCG1	RBG4	RBG3	RBG2	RBG1
31	50AL4	50AL3	50AL2	50AL1	VPOLV	N3PT	L3PT	PTRX
32	50CL4	50CL3	50CL2	50CL1	50BL4	50BL3	50BL2	50BL1
33	50G4	50G3	50G2	50G1	50CL	50BL	50AL	*
34	OSB4	OSB3	OSB2	OSB1	50PP4	50PP3	50PP2	50PP1
35	TS	TC	TB	TA	ZLOUT	ZLIN	ILOP	50P
36	SPT_EN	*	*	*	*	52AC	52AB	52AA
37	50AB4	50AB3	50AB2	50AB1	ATPC	ATPB	ATPA	50PPL
38	50CA4	50CA3	50CA2	50CA1	50BC4	50BC3	50BC2	50BC1
39	*	51NR	51QR	51PR	*	*	*	*

SEL-321-3 TARGET INFORMATION

SEL-321-3 Relay – One I/O Board Version

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
43	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
44	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
45	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

SEL-321-3 Relay – Two I/O Board Version

TAR	Status Indicators							
40	OUT1	OUT2	OUT3	OUT4	OUT5	OUT6	OUT7	OUT8
41	OUT9	OUT10	OUT11	OUT12	OUT13	OUT14	OUT15	!ALARM
42	OUT17	OUT18	OUT19	OUT20	OUT21	OUT22	OUT23	OUT24
43	OUT25	OUT26	OUT27	OUT28	OUT29	OUT30	OUT31	OUT32
44	TMB8	TMB7	TMB6	TMB5	TMB4	TMB3	TMB2	TMB1
45	MIRBRK	MIRFRA	MIRPAR	MIROVR	MIRIN	MIRSYC	MIRDAT	MIRDIS
46	IN8	IN7	IN6	IN5	IN4	IN3	IN2	IN1
47	IN16	IN15	IN14	IN13	IN12	IN11	IN10	IN9
48	RMB8	RMB7	RMB6	RMB5	RMB4	RMB3	RMB2	RMB1

Note: The ANYTRIP, SPTI, Z1, Z2, Z3, Z4, 3PTC, 3PTB, and 3PTA elements (highlighted in the first table) are to be used for annunciation or auxiliary functions (for example, recloser control, SCADA, and indication). These elements should not be used in any trip logic equations (MTU, MTCS or MTO).

SEL-321-3 RELAY COMMAND SUMMARY

Access Level 0

ACCESS Answer password prompt (if password protection is enabled) to enter Access Level 1. Three unsuccessful attempts pulse ALARM contacts closed for one second.

Access Level 1

2ACCESS Answer password prompt (if password protection is enabled) to enter Access Level 2. This command always pulses the ALARM contacts closed for one second.

BREAKER Answer password prompt (if password protection is enabled) to enter breaker control Access Level B. Allows execution of OPEN, CLOSE, GROUP N, and Access Level 1 commands.

COMM Displays MIRRORED BITS™ communications summary data.

COMM C Clears MIRRORED BITS communications data.

COMM L Displays MIRRORED BITS communications data.

DATE Shows or sets date. DAT 2/3/92 sets date to Feb. 3, 1992. IRIG-B time code input overrides existing month and day settings. DATE pulses ALARM contacts when year entered differs from year stored.

EVENT Shows event record. EVE 1 shows newest event; EVE 12 shows oldest. Default report is 1/4-cycle standard, EVE n L=1/16-cycle standard, EVE n R=1/16-cycle unfiltered, EVE n C=1/16-cycle SEL-5601 Event Report, EVE n U=1/16-cycle unfiltered.

GROUP Shows setting group to use in lieu of active group.

HISTORY Shows DATE, TIME, ZONE/TYPE, LOCATION (distance), GROUP, and front panel targets for the last 40 events.

IRIG Force immediate attempt to synchronize internal relay clock to time code input. Reports ID, Date, Time, or Error Message.

METER Displays meter data.

QUIT Returns control to Access Level 0; returns target display to Relay Targets TAR O. Displays ID, Date, and Time.

SHOWSET n Shows active group settings for Group n. Shows active relay group settings if n omitted.

SHOWSET C Shows calibration settings.

SHOWSET G Shows global settings.

SHOWSET L Displays active logic settings. Append group number (1-6) to display that group's logic settings.

SHOWSET P Shows active port's settings. Append port number (1-3) to display that port's settings.

SHOWSET R Shows SER settings.

STATUS	Shows self-test status.
TIME	Shows or sets time. TIM 13/32/00 sets clock to 1:32:00 PM. IRIG-B synchronization overrides this setting.
TRIGGER	Triggers an event report.

Access Level B

CLOSE	Asserts the CLOSE condition.
GROUP	Specifies currently selected group. Use GROUP n to change selected group to n.
OPEN	Asserts trip condition.

Access Level 2

CONTROL n	Allows you to control Relay Word bits RB1 through RB16.
COPY m n	Copies settings and logic from setting Group m to Group n.
LOOP	Enables MIRRORED BITS loop back mode for testing communications
LOOP R	Disables MIRRORED BITS loop back mode.
PASSWORD	Shows or sets passwords. Command pulses ALARM contacts closed momentarily after password entry. PAS 1 OTTER sets Level 1 password to OTTER. PAS 2 TAIL sets Level 2 password to TAIL.
PULSE n t	Closes an output contact for testing and control purposes.
RDMEM m	Use to download contents of selected memory areas. m = RAM, EEPROM, or ALL.
SET n	Use to enter group settings. If n argument omitted, edits active group.
SET G	Use to enter new global settings.
SET L	Use SET L n to edit Group n's logic settings. Selects active logic group to edit.
SET P	Use SET P n to edit Port n's settings. Changes active port's settings.
SET R	Use to enter new SER settings.
TARGET	Shows target values, and defines target group for display. TAR n displays target row n. TAR R command resets front panel targets to TAR 1.